Quantum Systems

(Lecture 3: Quantum states and computation)

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The principles

Quantum computation explores the laws of quantum theory as computational resources.

Thus, the principles of the former are directly derived from the postulates of the latter.

- The state **space** postulate
- The state evolution postulate
- The state composition postulate
- The state **measurement** postulate

The underlying maths is that of Hilbert spaces.

The underlying maths: Hilbert spaces

Complex, inner-product vector space

A complex vector space with inner product which measures how much two vectors overlap:

$$\langle -|-\rangle: H \times H \longrightarrow \mathbb{C}$$

such that

$$(1) \quad \langle v | \sum_{i} \lambda_{i} \cdot |w_{i} \rangle \rangle = \sum_{i} \lambda_{i} \langle v | w_{i} \rangle$$

$$(2) \quad \langle v|w\rangle = \overline{\langle w|v\rangle}$$

(3)
$$\langle v|v\rangle \geq 0$$
 (with equality iff $|v\rangle = 0$)

Note: $\langle -|-\rangle$ is conjugate linear in the first argument:

$$\langle \sum_{i} \lambda_{i} \cdot |w_{i}\rangle |v\rangle = \sum_{i} \overline{\lambda_{i}} \langle w_{i}|v\rangle$$

Dirac's notation

Dirac's bra/ket notation is a handy way to represent elements and constructions on an Hilbert space

- $|u\rangle$ A ket stands for a vector in an Hilbert space H. In \mathbb{C}^n , it is a column vector of complex entries. Note that the identity for + (the zero vector) is just written 0.
- $\langle u|$ A bra is a vector in the dual space H^* , i.e. scalar-valued linear maps in H. In $(\mathbb{C}^n)^*$ it is the adjoint, i.e. the conjugate transpose, of the corresponding ket, therefore a row vector.

There is a bijective correspondence between $|u\rangle$ and $\langle u|$

$$|u\rangle = \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix} \Leftrightarrow [\overline{u}_1 \cdots \overline{u}_n] = \langle u|$$

Inner product: examples

In C

$$\langle a+bi|c+di\rangle = (a-bi)(c+di) = ac+adi-bci+bd$$

In \mathbb{C}^n : The dot product

Amost useful example of a inner product is the dot product

$$\langle u|v\rangle = \underbrace{\begin{bmatrix} \overline{u_1} & \overline{u_2} & \cdots & \overline{u_n} \end{bmatrix}}_{\langle u|} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = \sum_{i=1}^n \overline{u_i} v_i$$

where $\overline{c} = a - ib$ is the complex conjugate of c = a + ib

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Old friends: The dual space

 H^*

If H is a Hilbert space, H^* is the space of linear maps from H to \mathfrak{C} .

Elements of H^* are denoted by

$$\langle u|: H \longrightarrow \mathcal{C}$$
 and defined as $\langle u|(|v\rangle) = \langle u|v\rangle$

In a matricial representation $\langle u|$ is obtained as the Hermitian conjugate (i.e. the transpose of the vector composed by the complex conjugate of each element) of $|u\rangle$, therefore the dot product of $|u\rangle$ and $|v\rangle$.

Old friends: Norms and orthogonality

- The inner product measures the degree of overlapping: $|v\rangle$ and $|w\rangle$ are orthogonal if $\langle v|w\rangle=0$
- The "length" of a vector uses the measure of its overlap with itself to yield the (Euclidean) norm:

$$\||v\rangle\| = \sqrt{\langle v|v\rangle}$$

(generalizing the distance between two points)

- $|v\rangle$ is a unit vector if $||v\rangle||=1$
- normalization: $\frac{|v\rangle}{\||v\rangle\|}$
- A set of vectors $\{|i\rangle,|j\rangle,\cdots,\}$ is orthonormal if each $|i\rangle$ is a unit vector and

$$\langle i|j\rangle = \delta_{i,j} = \begin{cases} i=j & \Rightarrow 1 \\ \text{otherwise} & \Rightarrow 0 \end{cases}$$

Old friends: Bases

Orthonormal basis

A orthonormal basis for a Hilbert space H of dimension n is a set $B = \{|i\rangle \mid i \in n-1\}$ of n linearly independent elements of H st

- $\langle i|j\rangle = \delta_{i,j}$ for all $|i\rangle, |j\rangle \in B$
- and B spans H, i.e. every $|v\rangle$ in H can be written as

Note that the amplitude or coefficient of $|v\rangle$ wrt $|i\rangle$ satisfies

$$\alpha_i = \langle i | v \rangle$$

Why?

Bases

$$\alpha_i = \langle i | v \rangle$$
 because

$$\langle i|v\rangle = \langle i|\sum_{j} \alpha_{j}j\rangle$$

$$= \sum_{j} \alpha_{j}\langle i|j\rangle$$

$$= \sum_{j} \alpha_{j}\delta_{i,j}$$

$$= \alpha_{j}$$

Note

If $|v\rangle$ is expressed wrt an orthonormal basis $\{|i\rangle \mid i \in n\}$, i.e.

$$|v\rangle = \sum_{i} \alpha_{i} |i\rangle$$
, then

$$\||v\rangle\| = \sum_{i} \|\alpha_{i}\|^{2}$$

Example: The Hadamard basis

One of the infinitely many orthonormal bases for a space of dimension 2:

$$\begin{split} |+\rangle &= \frac{1}{\sqrt{2}}|0\rangle + \frac{1}{\sqrt{2}}|1\rangle \\ |-\rangle &= \frac{1}{\sqrt{2}}|0\rangle - \frac{1}{\sqrt{2}}|1\rangle \end{split}$$

Check, e. g.

$$\langle +|-\rangle \;=\; \frac{1}{2}(|0\rangle + |1\rangle, |0\rangle - |1\rangle) \;=\; \frac{1}{2}\left(\begin{bmatrix}1\\1\end{bmatrix}, \begin{bmatrix}1\\-1\end{bmatrix}\right) \;=\; \frac{1}{2}\begin{bmatrix}1&1\end{bmatrix}\begin{bmatrix}1\\-1\end{bmatrix} \;=\; 0$$

$$\| \left| + \right\rangle \| \ = \ \sqrt{\left\langle + \right| + \right\rangle} \ = \ \sqrt{\frac{1}{2}(\left| 0 \right\rangle + \left| 1 \right\rangle, \left| 0 \right\rangle + \left| 1 \right\rangle)} \ = \ \sqrt{\frac{1}{2}\left(\left[\frac{1}{1} \right], \left[\frac{1}{1} \right] \right)} \ = \ 1$$

Bases

A basis for H^* If $\{|i\rangle \mid i \in n\}$ is an orthonormal basis for H, then

$$\{\langle i | \mid i \in n\}$$

is an orthonormal basis for H^* .

Hilbert spaces

The complete picture

An Hilbert space is an inner-product space H st the metric defined by its norm turns H into a complete metric space, i.e.any Cauchy sequence

$$|v_1\rangle, |v_2\rangle, \cdots$$

$$\forall_{\epsilon>0} \exists_N \forall_{m,n>N} \||v_m-v_n\rangle\| \leq \epsilon$$

converges

(i.e. there exists an element $|s\rangle$ in H st $\forall_{\epsilon>0}\ \exists_N\ \forall_{n>N}\quad \||s-v_n\rangle\|\leq \epsilon$)

The completeness condition is trivial in finite dimensional vector spaces

The state space postulate

Postulate 1

The state space of a quantum system is described by a unit vector in a Hilbert space

- In practice, with finite resources, one cannot distinguish between a continuous state space from a discrete one with arbitrarily small minimum spacing between adjacente locations.
- One may, then, restrict to finite-dimensional (complex) Hilbert spaces.

The state space postulate

A quantum (binary) state is represented as a superposition, i.e. a linear combination of vectors $|0\rangle$ and $|1\rangle$ with complex coeficients:

$$|\phi\rangle = \alpha|0\rangle + \beta|1\rangle = \begin{bmatrix} \alpha \\ \beta \end{bmatrix}$$

When state $|\varphi\rangle$ is measured (i.e. observed) one of the two basic states $|0\rangle,|1\rangle$ is returned with probability

$$\|\alpha\|^2$$
 and $\|\beta\|^2$

respectively.

Being probabilities, the norm squared of coefficients must satisfy

$$\|\alpha\|^2 + \|\beta\|^2 = 1$$

which enforces quantum states to be represented by unit vectors.

The state space of a qubit

Global phase

Unit vectors equivalent up to multiplication by a complex number of modulus one, i.e. a phase factor $e^{i\theta}$, represent the same state.

Let

$$|v\rangle = \alpha |u\rangle + \beta |u'\rangle$$

$$\| e^{i\theta} \alpha \|^2 = (\overline{e^{i\theta} \alpha})(e^{i\theta} \alpha) = (e^{-i\theta} \overline{\alpha})(e^{i\theta} \alpha) = \overline{\alpha} \alpha = \| \alpha \|^2$$

and similarly for β .

As the probabilities $\|\alpha\|^2$ and $\|\beta\|^2$ are the only measurable quantities, global phase has no physical meaning.

Representation redundancy

qubit state space ≠ complex vector space used for representation

The state space of a qubit

Relative phase

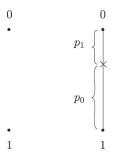
It is a measure of the angle between the two complex numbers. Thus, it cannot be discarded!

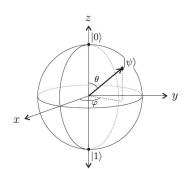
Those are different states

$$\frac{1}{\sqrt{2}}(|u\rangle+|u'\rangle) \quad \frac{1}{\sqrt{2}}(|u\rangle-|u'\rangle) \quad \frac{1}{\sqrt{2}}(e^{i\theta}|u\rangle+|u'\rangle)$$

...

Deterministic, probabilistic and quantum bits





(from [Kaeys et al, 2007])

The Bloch sphere: Representing $|\psi\rangle = \alpha |0\rangle + \beta |1\rangle$

• Express $|\psi\rangle$ in polar form

$$|\psi
angle =
ho_1 e^{i\, arphi_1} |0
angle +
ho_2 e^{i\, arphi_2} |1
angle$$

• Eliminate one of the four real parameters multiplying by $e^{-i\varphi_1}$

$$|\psi\rangle = \rho_1 |0\rangle + \rho_2 e^{i(\phi_2 - \phi_1)} |1\rangle = \rho_1 |0\rangle + \rho_2 e^{i\phi} |1\rangle$$

making $\phi = \phi_2 - \phi_1$,

which is possible because global phase factors are physically meaningless.

The Bloch sphere: Representing $|\psi\rangle = \alpha |0\rangle + \beta |1\rangle$

• Switching back the coefficient of $|1\rangle$ to Cartesian coordinates

$$|\psi\rangle = \rho_1 |0\rangle + (a+bi)|1\rangle$$

the normalization constraint

$$\| \rho_1 \|^2 + \| a + ib \|^2 = \| \rho_1 \|^2 + (a - ib)(a + ib) = \| \| \rho_1 \|^2 + a^2 + b^2 = 1$$

yields the equation of a unit sphere in the real tridimensional space with Cartesian coordinates: (a, b, ρ_1) .

The Bloch sphere: Representing $|\psi\rangle=\alpha|0\rangle+\beta|1\rangle$

• The polar coordinates (ρ, θ, ϕ) of a point in the surface of a sphere relate to Cartesian ones through the correspondence

$$x = \rho \sin \theta \cos \varphi$$
$$y = \rho \sin \theta \sin \varphi$$
$$z = \rho \cos \theta$$

• Recalling $\rho = 1$ (cf unit vector),

$$\begin{aligned} |\psi\rangle &= \rho_1 |0\rangle + (a+ib)|1\rangle \\ &= \cos \theta |0\rangle + \sin \theta (\cos \varphi + i \sin \varphi)|1\rangle \\ &= \cos \theta |0\rangle + e^{i\varphi} \sin \theta |1\rangle \end{aligned}$$

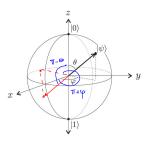
which, with two parameters, defines a point in the sphere's surface.

Actually, one may just focus on the upper hemisphere $(0 \le \theta' \le \frac{\pi}{2})$ as opposite points in the lower one differ only by a phase factor of -1, as suggested by

$$\begin{array}{lll} \theta'=0 & \Rightarrow & |\psi\rangle \; = \; \cos 0|0\rangle + e^{i\phi} \sin 0|1\rangle \; = \; |0\rangle \\ \theta'=\frac{\pi}{2} & \Rightarrow & |\psi\rangle \; = \; \cos\frac{\pi}{2}|0\rangle + e^{i\phi} \sin\frac{\pi}{2}|1\rangle \; = \; e^{i\phi}|1\rangle \; = \; |1\rangle \end{array}$$

Note that longitude (ϕ) is irrelevant in a pole!

Indeed, let $|\psi'\rangle$ be the opposite point on the sphere with polar coordinates $(1, \pi - \theta, \varphi + \pi)$:

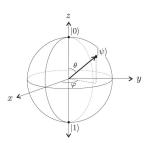


$$\begin{split} |\psi'\rangle &= \cos{(\pi-\theta)}|0\rangle + e^{i(\phi+\pi)}\sin{(\pi-\theta)}|1\rangle \\ &= -\cos{\theta}|0\rangle + e^{i\phi}e^{i\pi}\sin{\theta}|1\rangle \\ &= -\cos{\theta}|0\rangle + e^{i\phi}\sin{\theta}|1\rangle \\ &= -|\psi\rangle \end{split}$$

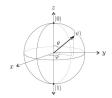
which leads to

$$|\psi\rangle=\cos\frac{\theta}{2}|0\rangle+e^{i\phi}\sin\frac{\theta}{2}|1\rangle$$

where $0 \le \theta \le \pi$, $0 \le \phi \le 2\pi$



The map $\frac{\theta}{2} \mapsto \theta$ is one-to-one at any point but at $\frac{\theta}{2}$: all points on the equator are mapped into a single point: the south pole.



- The poles represent the classical bits. In general, orthogonal states correspond to antipodal points and every diameter to a basis for the single-qubit state space.
- Once measured a qubit collapses to one of the two poles. Which pole depends exactly on the arrow direction: The angle θ measures that probability: If the arrow points at the equator, there is 50-50 chance to collapse to any of the two poles.
- Rotating a vector wrt the z-axis results into a phase change (ϕ) , and does not affect which state the arrow will collapse to, when measured.

The state evolution postulate

If a quantum state is a ray (i.e. a unit vector in a Hilbert space H up to a global phase), its evolution is specified a certain kind of linear maps $U: H \longrightarrow H$.

Linearity

$$U\left(\sum_{j} \alpha_{j} |v_{j}\rangle\right) = \sum_{j} \alpha_{j} U(|v_{j}\rangle)$$

just by itself has an important consequence: quantum states cannot be cloned

The no-cloning theorem

Linearity implies that quantum states cannot be cloned

Let $U(|a\rangle|0\rangle) = |a\rangle|a\rangle$ be a 2-qubit operator and $|c\rangle = \frac{1}{\sqrt{2}}(|a\rangle + |b\rangle)$ for $|a\rangle$, $|b\rangle$ orthogonal. Then,

$$U(|c\rangle|0\rangle) = \frac{1}{\sqrt{2}}(U(|a\rangle|0\rangle) + U(|b\rangle|0\rangle))$$

$$= \frac{1}{\sqrt{2}}(|a\rangle|a\rangle + |b\rangle|b\rangle)$$

$$\neq \frac{1}{\sqrt{2}}(|a\rangle|a\rangle + |a\rangle|b\rangle + |b\rangle|a\rangle + |b\rangle|b\rangle)$$

$$= |c\rangle|c\rangle$$

$$= U(|c\rangle|0\rangle)$$

As already seen, $|x\rangle|y\rangle = |xy\rangle = |x\rangle \otimes |y\rangle$

But, linearity is not enough ...

... we need to enforce that the norm squared of the new amplitudes still represent a probability distribution

If
$$\sum_{j} \alpha_{j} U(|v_{j}\rangle) = \sum_{j} \alpha'_{j} |v_{j}\rangle$$
 then $\sum_{j} \|\alpha'_{j}\|^{2} = 1$

This is achieved by making U unitary, i.e. such that $U^{-1} = U^{\dagger}$.

What is U^{\dagger} ? The adjoint map

Given a linear map $U: H \longrightarrow H'$, its adjoint $U^{\dagger}: H' \longrightarrow H$ is the unique linear map such that

$$\langle U^{\dagger} a | b \rangle = \langle a | U b \rangle$$

or, in the more 'verbose' notation for the inner product

$$(U^{\dagger}|a\rangle,|b\rangle) = (|a\rangle,U|b\rangle)$$

Note that $(UV)^{\dagger} = V^{\dagger}U^{\dagger}$ and $U^{\dagger} = U$ because

$$\langle V^{\dagger} U^{\dagger} a | b \rangle = \langle U^{\dagger} a | V b \rangle = \langle a | U V b \rangle$$

and

$$\langle U^{\dagger^{\dagger}} a | b \rangle = \langle a | U^{\dagger} b \rangle$$

The state evolution postulate

Postulate 2

The evolution over time of the state of a closed quantum system is described by a unitary map.

The evolution is linear

$$U\left(\sum_{j} \alpha_{j} |v_{j}\rangle\right) = \sum_{j} \alpha_{j} U(|v_{j}\rangle)$$

and preserves the normalization constraint

If
$$\sum_{j} \alpha_{j} U(|v_{j}\rangle) = \sum_{j} \alpha'_{j} |v_{j}\rangle$$
 then $\sum_{j} \|\alpha'_{j}\|^{2} = 1$

The state evolution postulate

Preservation of the normalization constraint means that unit length vectors (and thus orthogonal subspaces) are mapped by U to unit length vectors (and thus to orthogonal subspaces).

It also means that applying a transformation followed by a measurement in the transformed basis is equivalent to a measurement followed by a transformation.

This entails a condition on valid quantum operators: they must preserve the inner product, i.e.

$$\langle Ua|Ub\rangle = \langle a|U^{\dagger}Ub\rangle = \langle v|w\rangle$$

which is only the case iff U is unitary, i.e. U^{\dagger} is the inverse of U:

$$U^{\dagger}U = UU^{\dagger} = I$$

Unitary maps

- Preserving the inner product means that a unitary operator maps orthonormal bases to orthonormal bases.
- Conversely, any operator with this property is unitary.
- If given in matrix form, being unitary means that the set of columns of its matrix representation are orthonormal (because the *j*th column is the image of $U|j\rangle$). Equivalently, rows are orthonormal (why?)

Unitary maps

Unitarity is the only constraint on quantum operators: Any unitary matrix specifies a valid quantum operator.

This means that there are many non-trivial operators on a single qubit (in contrast with the classical case where the only non-trivial operation on a bit is complement).

Finally, because the inverse of a unitary matrix is also a unitary matrix, a quantum operator can always be inverted by another quantum operator

Unitary transformations are reversible

A linear map $U: H \longrightarrow H'$ is fully characterized by specifying how it acts on a basis of H. If H is finite this leads to a natural representation of U as matrix.

Let $\{|j\rangle \mid j \in n-1\}$ be a basis for a *n*-dimensional Hilbert space H, and similarly $\{|i\rangle \mid i \in m-1\}$ for a *m*-dimensional H'. Then the $m \times n$ matrix corresponding to U is defined as

$$\begin{bmatrix} U|0\rangle & U|1\rangle & \cdots & U|n-1\rangle \end{bmatrix}$$

i.e. its j^{th} -column corresponds to m-dimensional vector $U|j\rangle$.

The Dirac notations provides a handy, alternative description of matrices via outer products.

Representing linear maps

Outer product

... is computed straightforwardly by matrix multiplication, e.g.

$$|0\rangle\langle 0| = \begin{bmatrix} 1\\0 \end{bmatrix} \begin{bmatrix} 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0\\0 & 0 \end{bmatrix}$$
$$|1\rangle\langle 0| = \begin{bmatrix} 0\\1 \end{bmatrix} \begin{bmatrix} 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0\\1 & 0 \end{bmatrix}$$

In general, for vectors $|i\rangle,|j\rangle$ in an orthonormal basis, $|i\rangle\langle j|$ is a square matrix with 1 in position (i,j) and 0 elsewhere. As an operator, $|i\rangle\langle j|$ maps $|j\rangle$ into $|i\rangle$ because

$$|i\rangle\langle j||j\rangle = |i\rangle\langle j|j\rangle = |i\rangle$$

A linear map $U: H \longrightarrow H'$ can be represented as a matrix

$$\sum_{i \in m-1, i \in n-1} U_{i,j} |i\rangle\langle j|$$

Representing linear maps

Decomposition of the identity (for an orthonormal basis)

$$I_H = \sum_{i \in n-1} |i\rangle\langle i|$$

Thus,

$$U = I_{H'}UI_{H} = \sum_{i \in m-1} |i\rangle\langle i| \ U \sum_{j \in n-1} |j\rangle\langle j|$$
$$= \sum_{i \in m-1, j \in n-1} |i\rangle\langle i| \ U |j\rangle\langle j|$$
$$= \sum_{i \in m-1, j \in n-1} \langle i| U|j\rangle |i\rangle\langle j|$$

Clearly,

$$U_{i,j} = \langle i|U|j\rangle$$

Representing linear maps

because

$$\langle i|U|j\rangle = \langle i|\left(\sum_{i'\in m-1,j'\in n-1} U_{i',j'}|i'\rangle\langle j'|\right)|j\rangle$$

$$= \sum_{i'\in m-1,j'\in n-1} U_{i',j'}\langle i|i'\rangle\langle j|j'\rangle$$

$$= \sum_{i'\in m-1,j'\in n-1} U_{i',j'}\delta_{ii'}\delta_{jj'} = U_{i,j}$$

Representing linear maps

Any orthonormal provides a decomposition of the identity.

Is there a standard way to provide a decomposition for an arbitrary operator U over a Hilbert H?

Yes, if *U* is normal operator, i.e. $UU^{\dagger} = U^{\dagger}U$, because of the

Spectral theorem

Any normal operator on a finite, n-dimensional Hilbert space H provides a basis for H consisting of its eigenvectors. Thus,

$$U = \sum_{i \in n-1} \lambda_i |\lambda_i\rangle \langle \lambda_i|$$

where each $(\lambda_i, |\lambda_i\rangle)$ is a eigenvalue / eigenvector pair.

The
$$X=\begin{bmatrix}0&1\\1&0\end{bmatrix}=|0\rangle\langle 1|+|1\rangle\langle 0|$$
 gate



$$X|0\rangle = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = |1\rangle$$

As $X|+\rangle=|+\rangle$ and $X|-\rangle=-|-\rangle$, its spectral decomposition yields

$$X = |+\rangle\langle +|-|-\rangle\langle -|$$

The
$$Z=\begin{bmatrix}1&0\\0&-1\end{bmatrix}=|0\rangle\langle 1|+|1\rangle\langle 0|$$
 gate

Acts as

$$Z|0\rangle = |0\rangle$$
 and $Z|1\rangle = -|1\rangle$

i.e. leaves $|0\rangle$ invariant, but injects a phase $e^{i\pi}=-1$ to $|0\rangle$, corresponding to a rotation of π radians around the Z axis.

Clearly, its spectral decomposition yields:

$$Z = |0\rangle\langle 0| - |1\rangle\langle 1|$$

The phase shift gate

$$P_{\Phi} = \begin{bmatrix} 1 & 0 \\ 0 & e^{i\Phi} \end{bmatrix}$$

i.e.
$$P_{\Phi} |0\rangle = |0\rangle$$
 and $P_{\Phi} |1\rangle = e^{i\Phi} |1\rangle$.

The probability of measuring a $|0\rangle$ or $|1\rangle$ remains unchanged, but it modifies the phase of the quantum state.

This corresponds to a rotation of ϕ radians around the Z axis (i.e. along a line of latitude on the Bloch sphere) by ϕ radians.

Examples

- $Z = P_{\pi}$
- $S = P_{\frac{\pi}{2}} = \sqrt{Z} = \begin{bmatrix} 1 & 0 \\ 0 & e^{i\frac{\pi}{2}} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & i \end{bmatrix}$
- $T = P_{\frac{\pi}{4}} = \sqrt{S}$ (also called the $\frac{\pi}{8}$ gate)

$$T = R_{\frac{\pi}{4}} = \begin{bmatrix} 1 & 0 \\ 0 & e^{i\frac{\pi}{4}} \end{bmatrix}$$

which, up to a global phase factor $e^{i\frac{\pi}{8}}$, is equivalent to

$$\begin{bmatrix} e^{-i\frac{\pi}{8}} & 0 \\ 0 & e^{i\frac{\pi}{8}} \end{bmatrix}$$

Pauli gates

X,Y,Z specify a rotation by π radians around the corresponding axes on the Bloch sphere.

$$I = |0\rangle\langle 0| + |1\rangle\langle 1| = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$X = |1\rangle\langle 0| + |0\rangle\langle 1| = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$Z = |0\rangle\langle 0| - |1\rangle\langle 1| = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$Y = i(-|1\rangle\langle 0| + |0\rangle\langle 1|) = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$$

Rotation gates

Correspond to arbitrary rotations around the three axes of the Bloch sphere

$$R_e(\theta) \stackrel{=}{=} e^{\frac{-i\theta E}{2}} = \cos\left(\frac{\theta}{2}\right)I - i\sin\frac{\theta}{2}E$$

where e = x, y, z and E = X, Y, Z.

because, for any real number θ and matrix R st $R^2 = I$, which is the case for X, Y, and Z.

$$e^{i\theta R} = cos(\theta)I + i\sin(\theta)R$$

Rotation gates as matrices in the computational basis

$$R_{x}(\theta) \ = \ \begin{bmatrix} \cos\left(\frac{\theta}{2}\right) & -i\sin\left(\frac{\theta}{2}\right) \\ -i\sin\left(\frac{\theta}{2}\right) & \cos\left(\frac{\theta}{2}\right) \end{bmatrix}$$

$$R_{y}(\theta) = \begin{bmatrix} \cos\left(\frac{\theta}{2}\right) & -\sin\left(\frac{\theta}{2}\right) \\ \sin\left(\frac{\theta}{2}\right) & \cos\left(\frac{\theta}{2}\right) \end{bmatrix}$$

$$R_{z}(\theta) = \begin{bmatrix} e^{-i\frac{\theta}{2}} & 0\\ 0 & e^{i\frac{\theta}{2}} \end{bmatrix}$$

Compute
$$R_z(\theta)|\psi
angle$$
 for $|\psi
angle=\cos\left(rac{\sigma}{2}
ight)|0
angle+e^{i\gamma}\sin\left(rac{\sigma}{2}
ight)|1
angle$

$$\begin{bmatrix} e^{-i\frac{\theta}{2}} & 0 \\ 0 & e^{i\frac{\theta}{2}} \end{bmatrix} \begin{bmatrix} \cos\left(\frac{\sigma}{2}\right) \\ e^{i\gamma}\sin\left(\frac{\sigma}{2}\right) \end{bmatrix} = \begin{bmatrix} e^{-i\frac{\theta}{2}}\cos\left(\frac{\sigma}{2}\right) \\ e^{i\frac{\theta}{2}}e^{i\gamma}\sin\left(\frac{\sigma}{2}\right) \end{bmatrix}$$
$$= e^{-i\frac{\theta}{2}} \begin{bmatrix} \cos\left(\frac{\sigma}{2}\right) \\ e^{i\theta}e^{i\gamma}\sin\left(\frac{\sigma}{2}\right) \end{bmatrix}$$
$$= e^{-i\frac{\theta}{2}} \left(\cos\left(\frac{\sigma}{2}\right)|0\rangle + e^{i(\gamma+\theta)}\sin\left(\frac{\sigma}{2}\right)|1\rangle \right)$$

As global phase is insignificant, the angle mapping $\gamma \mapsto \gamma + \theta$ is a rotation of θ around the z-axis of the Bloch sphere.

Theorem

Let U be a 1-gate, and v, w any two non-parallel axes of the Bloch sphere. Then there exist real numbers $\alpha, \beta \gamma, \delta$ st

$$U = e^{i\alpha}R_{\nu}(\beta)R_{\nu}(\gamma)R_{\nu}(\delta)$$

which means that any 1-gate can be expressed as a sequence of two rotations about an axis and one rotation about another non parallel axis, multiplied by a suitable phase factor.

proof hint: Recall U is unitary and unfold the definition of rotation gate.

The Hadamard gate creates superpositions

$$H = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$



$$H |0\rangle = |+\rangle = \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle)$$
 $H |1\rangle = |-\rangle = \frac{1}{\sqrt{2}}(|0\rangle - |1\rangle)$

Building larger states from smaller

Operator U in the no-cloning theorem acts on a 2-dimensional state, i.e. over the composition of two gubits.

What does composition mean?

Postulate 3

The state space of a combined quantum system is the tensor product $V \otimes W$ of the state spaces V and W of its components.

Composing quantum states

State spaces in a quantum system combine through tensor: \otimes

n m-dimensional vectors \rightsquigarrow a vector in m^n -dimensional space

i.e. the state space of a quantum system grows exponentially with the number of particles: cf, Feyman's original motivation

Example

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} \otimes \begin{bmatrix} d \\ e \\ f \end{bmatrix} = \begin{bmatrix} ad \\ e \\ f \end{bmatrix} \begin{bmatrix} ad \\ ae \\ af \\ bd \\ e \\ f \end{bmatrix} = \begin{bmatrix} ad \\ ae \\ af \\ bd \\ e \\ f \end{bmatrix}$$

Composing quantum states

Tensor $V \otimes W$

- $B_{V \otimes W}$ is a set of elements of the form $|v_i\rangle \otimes |w_i\rangle$, for each $|v_i\rangle \in B_V$, $|w_i\rangle \in B_W$ and $\dim(V \otimes W) = \dim(V) \times \dim(W)$
- $(|u_1\rangle + |u_2\rangle) \otimes |z\rangle = |u_1\rangle \otimes |z\rangle + |u_2\rangle \otimes |z\rangle$
- $|z\rangle \otimes (|u_1\rangle + |u_2\rangle) = |z\rangle \otimes |u_1\rangle + |z\rangle \otimes |u_2\rangle$
- $(\alpha|u\rangle)\otimes|z\rangle = |u\rangle\otimes(\alpha|z\rangle) = \alpha(|u\rangle\otimes|z\rangle)$
- $\langle (|u_2\rangle \otimes |z_2\rangle)|(|u_1\rangle \otimes |z_1\rangle)\rangle = \langle u_2|u_1\rangle \langle z_2|z_1\rangle$

Composing quantum states

Clearly, every element of $V \otimes W$ can be written as

$$\alpha_1(|v_1\rangle\otimes|w_1\rangle)+\alpha_2(|v_2\rangle\otimes|w_1\rangle)+\cdots+\alpha_{nm}(|v_n\rangle\otimes|w_m\rangle)$$

Example

The basis of $V \otimes W$, for V, W qubits with the computational basis is

$$\{|0\rangle\otimes|0\rangle,|0\rangle\otimes|1\rangle,|1\rangle\otimes|0\rangle,|1\rangle\otimes|1\rangle\}$$

Thus, the tensor of $\alpha_1|0\rangle+\alpha_2|1\rangle$ and $\beta_1|0\rangle+\beta_2|1\rangle$ is

$$\alpha_1\beta_1|0\rangle\otimes|0\rangle \ + \ \alpha_1\beta_2|0\rangle\otimes|1\rangle \ + \ \alpha_2\beta_1|1\rangle\otimes|0\rangle \ + \ \alpha_2\beta_2|1\rangle\otimes|1\rangle$$

i.e., in a simplified notation,

$$\alpha_1\beta_1|00\rangle + \alpha_1\beta_2|01\rangle + \alpha_2\beta_1|10\rangle + \alpha_2\beta_2|11\rangle$$

Bases

The computational basis for a vector space

$$\underbrace{V\otimes V\otimes \cdots \otimes V}_{n}$$

corresponding to the composition of n qubits (each living in V) is the set

$$\underbrace{\{\underbrace{|0\rangle\cdots|0\rangle|0\rangle}_{n},\,\,\underbrace{|0\rangle\cdots|0\rangle|1\rangle}_{n},\,\,\underbrace{|0\rangle\cdots|1\rangle|0\rangle}_{n},\,\,\cdots\,\,\underbrace{|1\rangle\cdots|1\rangle|1\rangle}_{n}\}}_{abv}$$

$$\underbrace{\{\underbrace{|0\cdots00\rangle}_{n},\,\,\underbrace{|0\cdots01\rangle}_{n},\,\,\underbrace{|0\cdots10\rangle}_{n},\,\,\cdots\,\,\underbrace{|1\cdots11\rangle}_{n}\}}_{n}$$

which may be written in a compressed (decimal) way as

$$\{|0\rangle, |1\rangle, |2\rangle, |3\rangle, \cdots |2^n - 1\rangle\}$$

Bases

The computational basis for a two qubit system would be

$$\{|0\rangle, |1\rangle, |2\rangle, |3\rangle\}$$

with

$$|0\rangle = |00\rangle = \begin{bmatrix} 1\\0\\0\\0 \end{bmatrix} \quad |1\rangle = |01\rangle = \begin{bmatrix} 0\\1\\0\\0 \end{bmatrix} \quad |2\rangle = |10\rangle = \begin{bmatrix} 0\\0\\1\\0 \end{bmatrix} \quad |3\rangle = |11\rangle = \begin{bmatrix} 0\\0\\0\\1 \end{bmatrix}$$

Bases

There are of course other bases ... besides the standard one, e.g.

The Bell basis

$$\begin{split} |\Phi^{+}\rangle &= \frac{1}{\sqrt{2}}(|00\rangle + |11\rangle) \\ |\Phi^{-}\rangle &= \frac{1}{\sqrt{2}}(|00\rangle - |11\rangle) \\ |\Psi^{+}\rangle &= \frac{1}{\sqrt{2}}(|01\rangle + |10\rangle) \\ |\Psi^{-}\rangle &= \frac{1}{\sqrt{2}}(|01\rangle - |10\rangle) \end{split}$$

Compare with the Hadamard basis for the single qubit systems

Representing multi-qubit states

Any unit vector in a 2^n Hilbert space represents a possible n-qubit state, but for

... a certain level of redundancy

- As before, vectors that differ only in a global phase represent the same quantum state
- but also the same phase factor in different qubits of a tensor product represent the same state:

$$|u\rangle\otimes(e^{i\varphi}|z\rangle) = e^{i\varphi}(|u\rangle\otimes|z\rangle) = (e^{i\varphi}|u\rangle)\otimes|z\rangle$$

Actually, phase factors in qubits of a single term of a superposition can always be factored out into a coefficient for that term, i.e. phase factors distribute over tensors

Representing multi-qubit states

Representation

Relative phases still matter (of course!)

$$\frac{1}{\sqrt{2}}(|00\rangle+|11\rangle) \ \ \text{differs from} \ \ \frac{1}{\sqrt{2}}(e^{i\Phi}|00\rangle+|11\rangle)$$

even if

$$\frac{1}{\sqrt{2}}(|00\rangle+|11\rangle) = \frac{1}{\sqrt{2}}(e^{i\phi}|00\rangle+e^{i\phi}|11\rangle) = \frac{e^{i\phi}}{\sqrt{2}}(|00\rangle+|11\rangle$$

 The complex projective space of dimension 1 (depicted in the Block sphere) generalises to higher dimensions, although in practice linearity makes Hilbert spaces easier to use.

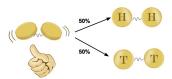
Entanglement

Most states in $V \otimes W$ cannot be written as $|u\rangle \otimes |z\rangle$

For example, the Bell state

$$|\Phi^{+}\rangle = \frac{1}{\sqrt{2}}(|00\rangle + |11\rangle) = \frac{1}{\sqrt{2}}|00\rangle + \frac{1}{\sqrt{2}}|11\rangle$$

is entangled



Entanglement

Actually, to make $|\Phi^+\rangle$ equal to

$$(\alpha_1|0\rangle+\beta_1|1\rangle)\otimes(\alpha_2|0\rangle+\beta_2|1\rangle)\ =\ \alpha_1\alpha_2|00\rangle+\alpha_1\beta_2|01\rangle+\beta_1\alpha_2|10\rangle+\beta_1\beta_2|11\rangle$$

would require that $\alpha_1\beta_2=\beta_1\alpha_2=0$ which implies that either

$$\alpha_1\alpha_2=0 \ \ \text{or} \ \ \beta_1\beta_2=0$$

Note

Entanglement can also be observed in simpler structures, e.g. relations:

$$\{(a,a),(b,b)\}\subseteq A\times A$$

cannot be separated, i.e. written as a Cartesian product of subsets of A.

Acts on the standard basis for a 2-qubit system, flipping the second bit if the first bit is 1 and leaving it unchanged otherwise.

$$\begin{array}{lll} \textit{CNOT} &=& |0\rangle\langle 0| \otimes \textit{I} + |1\rangle\langle 1| \otimes \textit{X} \\ &=& |0\rangle\langle 0| \otimes (|0\rangle\langle 0| + |1\rangle\langle 1|) + |1\rangle\langle 1| \otimes (|1\rangle\langle 0| + |0\rangle\langle 1|) \\ &=& |00\rangle\langle 00| + |01\rangle\langle 01| + |11\rangle\langle 10| + |10\rangle\langle 11| \\ &=& \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \\ \end{array}$$

CNOT is unitary and is its own inverse, and cannot be decomposed into a tensor product of two 1-qubit transformations

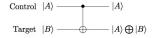
The importance of *CNOT* is its ability to change the entanglement between two qubits, e.g.

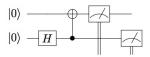
$$\begin{array}{ll} \textit{CNOT} \, \left(\frac{1}{\sqrt{2}} (|0\rangle + |1\rangle) \otimes |0\rangle \right) \; = \; \textit{CNOT} \, \left(\frac{1}{\sqrt{2}} (|00\rangle + |10\rangle) \right) \\ & = \; \frac{1}{\sqrt{2}} (|00\rangle + |11\rangle) \end{array}$$

Being its own inverse, also takes an entangled state to an unentangled one.

Note that entanglement is not a local property in the sense that transformations that act separately on two or more subsystems cannot affect the entanglement between those subsystems:

$$(U \otimes V) |v\rangle$$
 is entangled iff $|v\rangle$ is



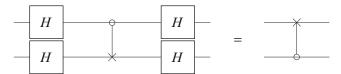




The notions of control/target bit in *CNOT* are arbitrary: they depend on what basis is considered. The standard behaviour is obtained in the computational basis. However, roles are interchanged in the Hadamard basis in which the effect of *CNOT* is

$$|++\rangle \mapsto |++\rangle \ |+-\rangle \mapsto |--\rangle \ |-+\rangle \mapsto |-+\rangle \ |--\rangle \mapsto |+-\rangle$$

Exercise



The proof

$$LHS = \frac{1}{2} \begin{bmatrix} H & H \\ H & -H \end{bmatrix} \begin{bmatrix} I & 0 \\ 0 & X \end{bmatrix} \begin{bmatrix} H & H \\ H & -H \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} H & HX \\ H & -HX \end{bmatrix} \begin{bmatrix} H & H \\ H & -H \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} I + HXH & I - HXH \\ I - HXH & I + HXH \end{bmatrix} = \frac{1}{2} \begin{bmatrix} I + Z & I - Z \\ I - Z & I + Z \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

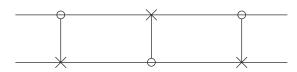
$$= I \otimes |0\rangle\langle 0| + X \otimes |1\rangle\langle 1| = RHS$$

noting that

$$H \otimes H = (I \otimes H)(H \otimes I) = \frac{1}{\sqrt{2}} \begin{bmatrix} H & 0 \\ 0 & H \end{bmatrix} \begin{bmatrix} I & I \\ I & -I \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} H & H \\ H & -H \end{bmatrix}$$

Exercise

Discuss



Controlled Q-gates

From



to



$$C_Q|0\rangle|\phi\rangle = |0\rangle|\phi\rangle$$

 $C_Q|1\rangle|\phi\rangle = |1\rangle Q|\phi\rangle$

$$C_Q = |0\rangle\langle 0| \otimes I + |1\rangle\langle 1| \otimes Q$$

corresponding to the following matrix in the standard basis:

$$C_Q = \begin{bmatrix} 1 & 0 \\ 0 & Q \end{bmatrix}$$

Controlled phase shift gate

$$C_{e^{i\theta}} = |00\rangle\langle00| + |01\rangle\langle01| + e^{i\theta}|10\rangle\langle10| + e^{i\theta}|11\rangle\langle11|$$

$$C_{e^{i\theta}} = egin{bmatrix} 1 & 0 & 0 & 0 \ 0 & 1 & 0 & 0 \ 0 & 0 & e^{i\theta} & 0 \ 0 & 0 & 0 & e^{i\theta} \end{bmatrix}$$

Transforming a global into a local phase

$$\frac{1}{\sqrt{2}}(|00\rangle + |11\rangle) \longrightarrow \frac{1}{\sqrt{2}}(|00\rangle + e^{i\theta}|11\rangle)$$

Actually, a unitary transformation is completely determined by its action on a basis, but not by specifying what states the states corresponding to basis states are sent to.

Example: $e^{i\theta}$ takes the four quantum states to themselves (because e.g. $|10\rangle$ and $e^{i\theta}|10\rangle$ represent the same state), but a global phase can be transformed into a local one, as above

CCNOT or Toffoli gate

A 3-bit gate corresponding to controlled *CNOT*. If the first two bits are in the state $|1\rangle$ applies X the third bit, else it does nothing:

$$|q_1q_2q_3\rangle \mapsto |q_1q_2,q_3 \oplus (q_1 \wedge q_2)\rangle$$

In matrix form,

Universal set of gates?

Is there a universal set of quantum gates?

In general no: there are uncountably many quantum transformations, and a finite set of generators can only generate countably many elements. However, it is possible for finite sets of gates to generate arbitrarily close approximations to all unitary transformations.

Definitions

• The error in approximating U by V is

$$Er(U, V) = \max_{|\phi\rangle} \|(U - V)|\phi\rangle\|$$

- An operator U can be approximated to arbitrary accuracy if for any positive ϵ there exists another unitary transformation V st $Er(U,V) \leq \epsilon$.
- A set of gates is universal if for any integer n ≥ 1, any n-qubit unitary operator can be approximated to arbitrary accuracy by a quantum circuit using only gates from that set.

Universal set of gates?

Some examples

- The set {H, T} is universal for 1-gates.
- The set {*H*, *T*, *CNOT*} is a universal set of gates.

How efficient is an approximation?

To approximate an unitary transformation encoding some specific computation, one would expect to use a number of gates from the universal set which is polynomial in the number of qubits and the inverse of the quality factor ϵ .

Main result: theorem of Solovay-Kitaev