TML Equivalence Proof

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Abstract

This document proves the equivalence of the TML with TMs. We do this by constructing an equivalent TML program for a TM, and vice versa. In the first section, we define complete TML programs, which are very close to TMs, and describe how they can be mapped into TMs. In the second section, we define formally how complete TML programs can be transformed into TMs, and vice versa. Finally, the third section describes how we can transform a valid TML program into a complete TML program.

1 Complete TML programs

Complete programs in the TML are a specific type of TML programs that are very detailed and obey different properties. As such, it is very easy to construct the TM corresponding to a complete program. In this section, we will build to the definition complete programs from complete blocks and modules.

Definition 1.1. Let P be a valid TML program, and let B be a basic block in P. We say that B is a *complete block* if it is composed of all the 3 commands: a *changeto* command, a *move* command, and a *flow* command. If the *flow* command is missing, we say that B is a *partially complete block*.

Complete blocks contain all the information required to transition from one state to another. This is because of the following:

- A complete block lists the next value of the tapehead; we assume the original value of the tapehead to be known outwith the block.
- A complete block states which direction the tapehead is moving- left or right.
- A complete block determines precisely what the next state is for the blockit is either a terminating state or we are going to the initial block of another module.

We can convert any basic block with a *flow* command to a complete block by adding the default commands (i.e. moving left and changing the tapehead value

to the current value). Equally, it is quite straightforward to convert a complete block into a subpart of a Turing Machine.

Example 1.2. Consider the following complete block.

```
changeto a move right goto s2
```

If we are at the state s_1 , and the block applies when the tapehead value is b, then the following is the corresponding subpart of the Turing Machine:

$$\underbrace{(s_1)} \quad \stackrel{b \to a,R}{\longrightarrow} \underbrace{(s_2)}$$

Figure 1: The TM subpart of the given Turing Machine complete block.

Using complete and partially complete blocks, we can define complete modules.

Definition 1.3. Let P be a valid TML program, and let M be a module in P. We say that M is a *complete module* if all of the following hold:

- it is composed of a single switch block;
- the body of each if command is a complete block; and
- the body of each while command is a partially complete block.

Remark 1.4. For a *while* command, the body must be partially complete because the corresponding edge in the TM is always a loop.

It is quite easy to map a single module to a sub-Turing machine. It precisely corresponds to having an initial state and edges going to other states as dictated by each case. Because the program is valid, we know that there is a case for each letter in the alphabet, including the blank letter.

Example 1.5. Consider the following complete module.

```
module basic {
    switch tapehead {
        while b {
            changeto b
            move right
        } if a, blank {
            changeto blank
            move left
            reject
        }
    }
}
```

If the alphabet is composed only of a and b, then the corresponding sub-TM is the following:

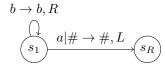


Figure 2: The sub-TM of the given Turing Machine complete module.

Remark 1.6. In the example above, we consider the state s_1 to be the *corresponding state* of the module. For every complete module, there is precisely one corresponding state.

Now, we can define complete programs.

Definition 1.7. Let P be a TML program. We say that P is *complete* if it is composed of one or more complete modules. We also require every *goto* command in a complete block to refer to an existing module.

Remark 1.8. The second condition (called *valid reference*) is required for any TML program.

Remark 1.9. In general, a complete program is not composed of a single complete module. We will see later that a relatively simple module can be broken down into a couple of complete modules, each of which refer to each other.

Every module in the program can be converted to a state, along with directed edges to other states. If the program is complete, then we ensure that the states connect to form a valid TM.

Example 1.10. Consider the following complete program.

```
1 alphabet = {"a", "b"}
2 module isDivTwo {
     switch tapehead {
         while 0 {
              changeto 0
              move right
         } while 1 {
              changeto 1
              move right
         } if blank {
10
11
              changeto blank
12
              move left
              goto isDivTwoCheck
13
14
15
16 }
17 module isDivTwoCheck {
switch tapehead {
    if 0 {
```

```
changeto 0
20
21
                move left
                accept
22
             if 1, blank {
23
                changeto blank
24
                move left
25
26
                reject
27
28
29 }
```

Then, the corresponding TM is the following:

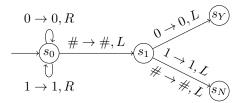


Figure 3: The TM of the given TML program. The state s_0 corresponds to the module isDivTwo and the state s_1 corresponds to the module isDivTwoCheck.

Remark 1.11. In the example above, we converted a complete TML program into a TM. It is equally possible to convert a TM into a complete TML program.

Example 1.12. Consider the following TM:

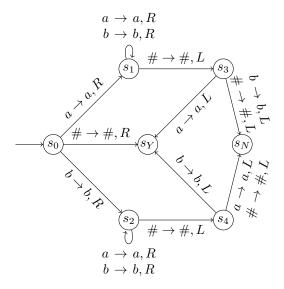


Figure 4: A Turing machine

Then, its corresponding TML program is:

```
1 alphabet = {"a", "b"}
2 module startsAndEndsSame {
      switch tapehead {
          if blank {
               accept
5
          } if a {
6
              changeto a
               move right
               goto startsAndEndsSameMoveA
          } if b {
10
11
               changeto b
               move right
12
13
               goto startsAndEndsSameMoveB
          }
14
      }
15
16 }
17 module startsAndEndsSameMoveA {
      switch tapehead {
18
          while a {
19
              changeto a
20
               move right
21
          } while b {
22
23
              changeto b
               move right
24
25
          } if blank {
               changeto blank
26
               move left
27
               goto startsAndEndsSameCheckA
28
          }
29
30
31 }
32 module startsAndEndsSameCheckA {
33
      switch tapehead {
34
          if a {
35
               changeto a
              move left
36
               accept
37
          } if b {
38
              changeto b
39
40
               move left
               reject
41
42
          } if blank {
               changeto blank
43
44
               move left
45
               reject
          }
46
47
48 }
49 module startsAndEndsSameMoveB {
      switch tapehead {
50
          while a {
51
52
               changeto a
               move right
53
54
          } while b {
55
               changeto b
               move right
56
```

```
} if blank {
57
58
                changeto blank
                move left
59
                {\tt goto} \quad {\tt startsAndEndsSameCheckB}
60
           }
61
      }
62
63 }
64 module startsAndEndsSameCheckB {
       switch tapehead {
66
           if a {
                changeto a
67
                move left
68
                reject
69
           } if b {
                changeto b
71
72
73
                accept
           } if blank {
74
75
                changeto blank
                move left
76
77
                reject
           }
78
      }
79
```

This is a complete program since TMs always include the required commands corresponding to *if* and *while* commands.

Remark 1.13. Although a TML program need not be complete, any valid TML program is equivalent to a complete one. So, a TML program that is not be complete is just a compact representation of its complete version.

2 Complete TML programs to TM

In this section, we will convert TML programs into TM. To do this, we first need to define TMs.

Definition 2.1. A Turing Machine is a collection (Q, Σ, δ, q_0) , where:

- Q is a set of states, including the accept state q_Y and reject state q_N ;
- Σ is the set of letters, excluding the blank symbol;
- $\delta: Q \setminus \{\text{accept}, \text{reject}\} \times \Sigma^+ \to Q \times \Sigma^+ \times \{\text{left}, \text{right}\}, \text{ where } \Sigma^+ = \Sigma \cup \{\text{blank}\}, \text{ is the transition function; and}$
- $q_0 \in Q$ is the starting state.

Remark 2.2. The definition of a valid tape only depends on the alphabet. So, for a TM program with language set equal to Σ and a TM with alphabet Σ , the set of valid tapeheads is equivalent.

Like with TML programs, we can execute a TM on a valid tape.

Definition 2.3. Let M be a TM, and let T be a valid tape for the program, with i the smallest integer such that T(i) is not blank. We execute M on T by constructing (countable) different tapes until execution is terminated. We first take the given tape T and the tapehead index i, and execute it using the initial state q_0 . This is done by computing $\delta(q_0, t) = (q_1, t', \text{dir})$. Then,

• the next tape T' is given by

$$T'(x) = \begin{cases} t' & x = i \\ T(x) & \text{otherwise;} \end{cases}$$

- the next state is q_1 ; and
- the next tapehead index is given by:

$$i' = egin{cases} i+1 & ext{dir} = ext{right} \ i-1 & ext{dir} = ext{left}. \end{cases}$$

If the next state q_1 is not a terminating state (accept or reject), then we execute the tape T' with the next state q_1 and the next tapehead index i'.

Definition 2.4. Let M be a TM. For each state q in M, we define the *corresponding module for* q, m, as follows:

- the module contains a single *switch* command;
- for each letter σ in the alphabet Σ^+ , we find $\delta(q,\sigma) = (q',\sigma',\text{dir})$. Then, we add a case in the *switch* command corresponding to letter σ (an *if* case if $q' \neq q$, otherwise a *while* case) with:
 - changeto σ'
 - move dir
 - in the case of an *if* block, if q' is accept, then the command accept; if q' is reject, then the command reject; otherwise, goto q'.

Let P be the program with

- alphabet Σ ;
- modules corresponding to every state q;
- the module corresponding to the initial state q_0 placed at the top.

We say that P is the corresponding program for M.

Remark 2.5. For any TM M, its corresponding program P will be complete. By definition, every module in P is complete.

Theorem 2.6. Let M be a TM, and let P be the corresponding program for M. Then, M and P execute on every valid tape T in the same way. That is,

- for every valid index n, if we have tape T_n , tapehead index i_n and module m_n for the TM program P, and we have tape S_n , tapehead index j_n and state q_n for the TM M, then $T_n = S_n$, $i_n = j_n$ and m_n is the corresponding module for q_n ;
- M terminates execution on T if and only if P terminates execution on T, with the same final status (accept or reject).

Proof. We prove this by induction. At the start, we have the same tape T for both M and P, with tapehead index 0. Moreover, the first module in P corresponds to the initial state q_0 . So, the result is true if n=0. Now, assume that the result is true for some integer n, where the TM state q_n is not accept or reject. In that case, $T_n = S_n$, $i_n = j_n$ and m_n is the corresponding module for q_n . Now, let σ_n be the letter at index $i_n = j_n$ on the tape $T_n = S_n$. Compute $q(q_n, \sigma_n) = (q_{n+1}, \sigma_{n+1}, \operatorname{dir})$. In that case,

$$T_{n+1}(x) = \begin{cases} T_n(x) & x \neq i_n \\ \sigma_{n+1} & \text{otherwise} \end{cases}, \qquad i_{n+1} = \begin{cases} i_n - 1 & \text{dir} = \texttt{left} \\ i_n + 1 & \text{dir} = \texttt{right}, \end{cases}$$

and the next state is q_{n+1} . We know that the module m_n in TM program P corresponds to the state q_n , so it has a changeto σ_{n+1} command for the case σ_n . In the case, the next tape for P is:

$$S_{n+1}(x) = \begin{cases} S_n(x) & x \neq i_n \\ \sigma_{n+1} & \text{otherwise.} \end{cases}$$

So, $T_{n+1} = S_{n+1}$. Similarly, the case also contains a move dir command. This implies that the next tapehead index for P is:

$$j_{n+1} = egin{cases} j_n - 1 & \mathtt{dir} = \mathtt{left} \ j_n + 1 & \mathtt{dir} = \mathtt{right}. \end{cases}$$

So, $i_{n+1} = j_{n+1}$. Now, if $q_{n+1} = q_n$, then the case block is a while block, and vice versa. So, the next module to be executed is m_n . In that case, m_{n+1} still corresponds to q_{n+1} . Otherwise, we have an if block. In particular, if q_{n+1} is the accept state, then the case for σ_n contains the flow command accept, and vice versa. In that case, execution terminates with the same final status of accept. The same is true for reject. Otherwise, the module contains the command goto m_{n+1} , where m_{n+1} is the corresponding module for q_{n+1} . Therefore, if the result holds for n, it holds for n+1. Then, the result follows from induction.

Definition 2.7. Let P be a complete TM program, and let Σ be its alphabet. For each module m in P, we define the *corresponding state for* m, q as followsfor each letter σ in Σ^+ , we define $\delta(q, \sigma) = (q', \sigma', \operatorname{dir})$, where:

- the value σ' is the letter given in the *changeto* command within m;
- the value dir is the direction given in the move command within m;
- if the flow command in m is accept, then q' is the accept state; if it is reject, then q' is the reject state; otherwise, q' is the state corresponding to the module given in the goto command within m.

Then, the TM with all the states q, alphabet Σ , the transition function δ and initial state q_0 corresponding to the first module in P is called the *corresponding TM for P*.

Theorem 2.8. Let P be a complete TM program, and let M be the corresponding TM for P. Then, P and M execute on every valid tape T in the same way. That is.

- for every valid index n, if we have tape T_n , tapehead index i_n and module m_n for TM program P, and we have tape S_n , tapehead index j_n and state q_n for the TM M, then $T_n = S_n$, $i_n = j_n$ and q_n is the corresponding state for m_n ;
- P terminates execution on T if and only if M terminates execution on T, with the same final status (accept or reject).

Proof. We prove this by induction as well. At the start, we have the same tape T for both P and M, with tapehead index 0. Moreover, the initial state q_0 in M corresponds to the first module in P. So, the result is true if n=0. Now, assume that the result is true for some integer n, which is not the terminating step in execution. In that case, $S_n = T_n$, $j_n = i_n$ and q_n is the corresponding state for m_n . Now, let σ_n be the letter at index $j_n = i_n$ on the tape $S_n = T_n$. If the block in m_n corresponding to σ_n is a while block, then we know that its body is partially complete, and so is composed of the following commands:

- changeto σ_{n+1}
- move dir

So, we have $\delta(q_n, \sigma_n) = (q_n, \sigma_{n+1}, \text{dir})$. Using the same argument as in **2.6**, we find that $T_{n+1} = S_{n+1}$ and $i_{n+1} = j_{n+1}$. Also, $q_{n+1} = q_n$ is the corresponding state for $m_{n+1} = m_n$. Otherwise, we have an *if* command. In this case, the case body is complete, and so composed of the following commands:

- changeto σ_{n+1}
- move dir
- accept, reject or goto m_{n+1} .

So, we have $\delta(q_n, \sigma_n) = (q_n, \sigma_{n+1}, \operatorname{dir})$, where σ_{n+1} is the corresponding state to the flow command present. Here too, we have $T_{n+1} = S_{n+1}$, $i_{n+1} = j_{n+1}$. If we have an accept command in the body, then q_{n+1} is the accepting state, and vice versa. So, we terminate execution with the final status of accept. The same is true for reject. Otherwise, the state q_{n+1} is the corresponding state to the module m_{n+1} . So, the result follows from induction.

3 Valid to complete programs

Definition 3.1. Let P be a TM program. We define the TM program P_1 to be the *first completion of* P as follows:

- the alphabet of P_1 is the same as the alphabet of P;
- for every block b in every module m of P, P_1 has a module with body the block b. If the block is not the final block in m, it has an additional flow command to the next block in the module. The order of the modules is the same as the order of the original blocks.

We define the TM program P_2 to be the second completion of P as follows:

- the alphabet of P_2 is the same as the alphabet of P;
- for every module m of P with a basic block, replace it with a switch block where every case is an if command with body the original basic block.

Finally, we define the TM program P^+ to be the *(third) completion of* P as follows:

- the alphabet of P^+ is the same as the alphabet of P;
- ullet for every non-complete module m of P, replace it with a complete block by adding the default commands:
 - if the changeto command is missing, add the changeto command corresponding to the case value;
 - if the *move* command is missing, add the command move left;
 - if the *flow* command is missing, add the command reject.

Remark 3.2. For any TM program P, its completion P^+ is complete by construction.

Remark 3.3. Let P be a TM program. For every block b in P, there is a complete module m in the completion program P^+ . We say that m is the corresponding complete module of b.

Theorem 3.4. Let P be a valid TM program. Then, P and its completion P^+ execute on every valid tape T in the same way. That is,

- for every valid index n, if we have tape T_n , tapehead index i_n and module m_n with executing block b_n for the TM program P, and we have tape S_n , tapehead index j_n and module t_n , then $T_n = S_n$, $i_n = j_n$, and t_n is the corresponding complete module block of b_n ;
- P terminates execution on T if and only if P⁺ terminates execution on T, with the same final status (accept or reject).

Proof. We prove this by induction. At the start, we have the same tape T for both P and P^+ , with tapehead index 0. Moreover, the corresponding (complete) module of the first block in the first module of P is the first module of P. So, the result is true if n=0. Now, assume that the result is true for some integer n, where the block b_n in the TM program P does not end with a terminating flow command. Let σ_n be the letter at index $i_n=j_n$ on the tape $S_n=T_n$.

If the *changeto* command is missing in b_n for σ_n , then the next tape $T_{n+1} = T_n$. In the complete module m_n , the case for σ_n will have change to σ_n . So, the next tape is given by:

$$S_{n+1}(x) = \begin{cases} S_n(x) & x \neq j \\ \sigma_n & \text{otherwise} \end{cases}$$
.

Therefore, we have $S_{n+1} = S_n$ as well. So, $T_{n+1} = S_{n+1}$. Otherwise, we have the same *changeto* command, in which case $T_{n+1} = S_{n+1}$ as well.

If the *move* command is missing in b_n for σ_n , then the next tapehead index $i_{n+1} = i_n - 1$. In the complete module m_n , the case for σ_n will have move left, so we also have $j_{n+1} = j_n - 1$. So, we have $i_{n+1} = j_{n+1}$. Otherwise, we have the same *move* command, meaning that $i_{n+1} = j_{n+1}$.

If the block b_n is a *switch* block with a *while* case for σ_n , then this is still true in the module m_n . So, the next block to be executed in P is b_n , and the next module to be executed in P^+ is m_n . In that case, the corresponding module of the block $b_{n+1} = b_n$ is still $m_{n+1} = m_n$. Instead, if the block b_n has no *flow* command for σ_n , and is not the last block, then the next block to execute is the block just below b_n , referred as b_{n+1} . By the definition of P^+ , we find that the case block in the module m_n has a *goto* command, going to the module m_{n+1} which corresponds to the block b_{n+1} . Also, if the *flow* command is missing for σ_n and this is the last block, then execution is terminated with the status reject for the program P. In that case, the case for σ_n in the module m_n has the reject command present, so the same happens for P^+ as well. Otherwise, both P and P^+ have the same flow command, meaning that there is either correspondence between the next block and the next module, or both the program terminate with the same status.