

Variable Demand Equilibrium Problems

A Comparison of Automated Methods

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Mathematics in Transport, 2005

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Outline

- 1 Motivation
 - The Basic Problem That We Studied
 - How To Find Variable Demand Equilibria
 - Previous Ways of Fixing The Flaw
- 2 A Different Way To Fix The Flaw
 - A New Search Direction
 - Experimental Results

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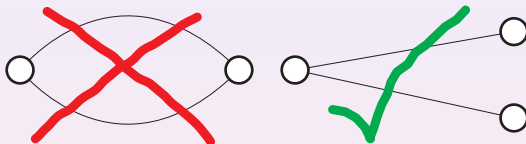
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 - The Universities of York, Leeds and Napier.

Simplifying Our Model.

We have just one route joining each OD pair.

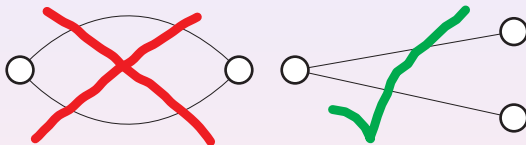
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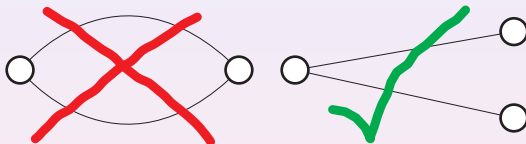
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Main variables are as follows:

Simplifying Our Model.

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X_i = “the flow along the route between OD-pair i ”;

Y_i = “the cost of travel along the route between OD-pair i ”.

Cost and Demand Functions.

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Definition (Cost and demand functions)

- Cost function, $\mathbf{C} : [0^N, +\infty^N) \rightarrow [0^K, +\infty^K)$;
- and demand function, $\mathbf{D} : [0^K, +\infty^K) \rightarrow [0^N, +\infty^N)$.

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- Cost function $\mathbf{C}(\mathbf{X})$ gives us the cost of traversing each route with flows \mathbf{X} ;
 - Demand function $\mathbf{D}(\mathbf{Y})$ gives us the demand on each route with costs \mathbf{Y} .

Variable Demand Equilibrium.

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Definition (Variable Demand Equilibrium)

$$\begin{pmatrix} \mathbf{D}(\mathbf{Y}) - \mathbf{X} \\ \mathbf{Y} - \mathbf{C}(\mathbf{X}) \end{pmatrix} = 0,$$

or equivalently

$$\mathbf{D}(\mathbf{C}(\mathbf{X})) - \mathbf{X} = 0.$$

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- But how do we find the solutions to variable demand equilibrium?

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A Basic Algorithm.

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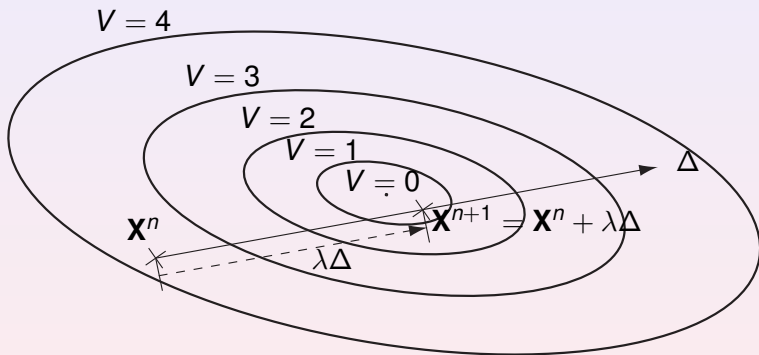
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For our basic algorithm we:

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- Follow a search direction Δ each step;
- Move a distance λ .

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Our First Algorithm – Algorithm 1.

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Definition

Our search direction is

$$\Delta^{A1}(\mathbf{X}) = \mathbf{D}(\mathbf{C}(\mathbf{X})) - \mathbf{X}.$$

Our objective function is

$$V^{A1}(\mathbf{X}) = \frac{1}{2} \Delta^{A1}(\mathbf{X}) \cdot \Delta^{A1}(\mathbf{X}).$$

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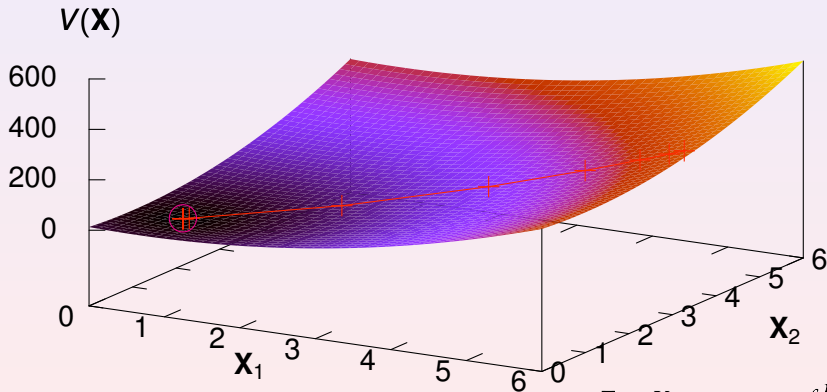
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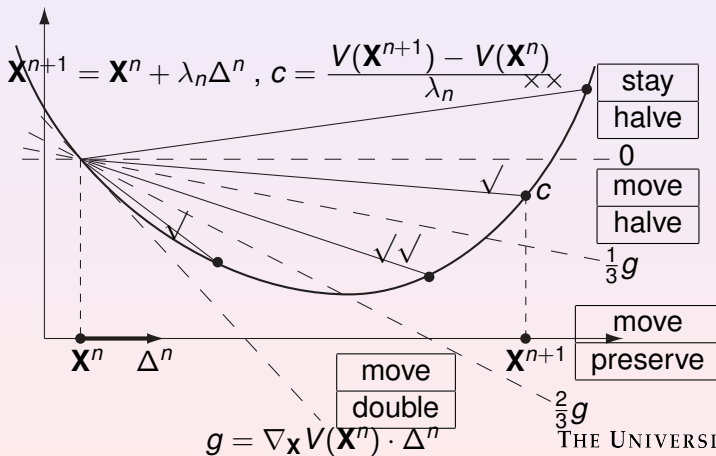
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Choose step-lengths via Armijo-like method.

Algorithm 1 In Practise.

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Armijo-Like Step-Lengths.



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$$\mathbf{C}(\mathbf{X}) = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \mathbf{X}, \quad \mathbf{D}(\mathbf{Y}) = \begin{pmatrix} 4 \\ 94 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 31 \end{pmatrix} \mathbf{Y}$$

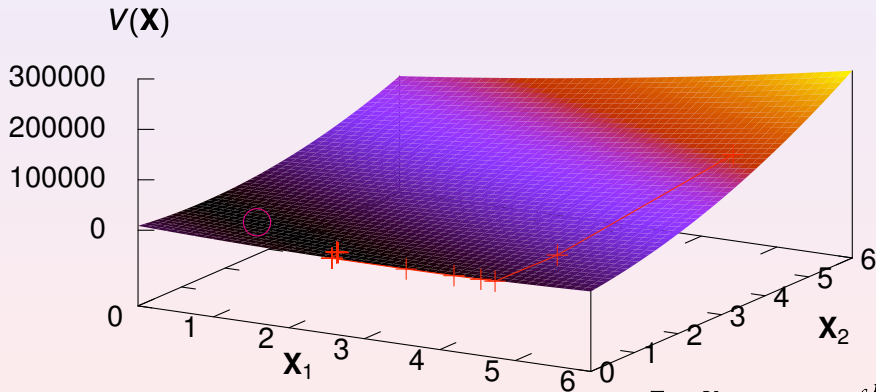
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- Along the line $\mathbf{X} = (3 - 2t, t)^\top$, $t \in [0, 1.5]$ the search direction is uphill.

Algorithm 1 Failing In Practise.

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Avoid The Flaw By Searching Both Flows And Costs.

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- New objective function:

$$V^{\text{MO}}(\mathbf{X}, \mathbf{Y}) = \Delta_{\mathbf{X}}^{\text{MO}} \cdot \Delta_{\mathbf{X}}^{\text{MO}} + \Delta_{\mathbf{Y}}^{\text{MO}} \cdot \Delta_{\mathbf{Y}}^{\text{MO}}.$$

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- Two new search directions:

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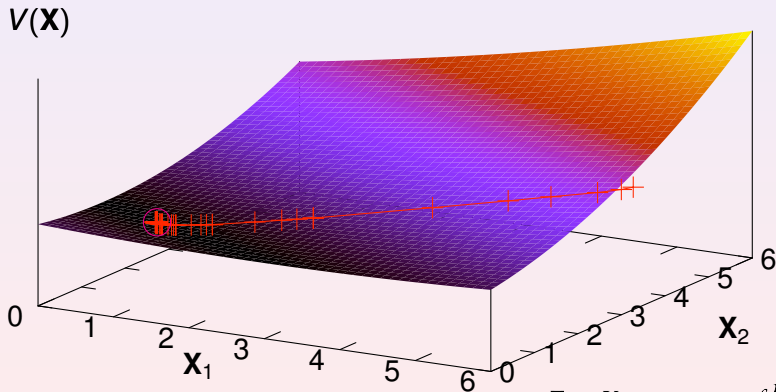
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- $$\Delta^{\text{AD}}(\mathbf{X}, \mathbf{Y}) = \begin{pmatrix} \Delta_{\mathbf{X}}^{\text{AD}}(\mathbf{X}, \mathbf{Y}) \\ \Delta_{\mathbf{Y}}^{\text{AD}}(\mathbf{X}, \mathbf{Y}) \end{pmatrix} = \begin{pmatrix} \mathbf{D}(\mathbf{Y}) - \mathbf{X} \\ \mathbf{C}(\mathbf{X}) - \mathbf{Y} \end{pmatrix}.$$

'Most Obvious' Direction Fixing The Flaw.

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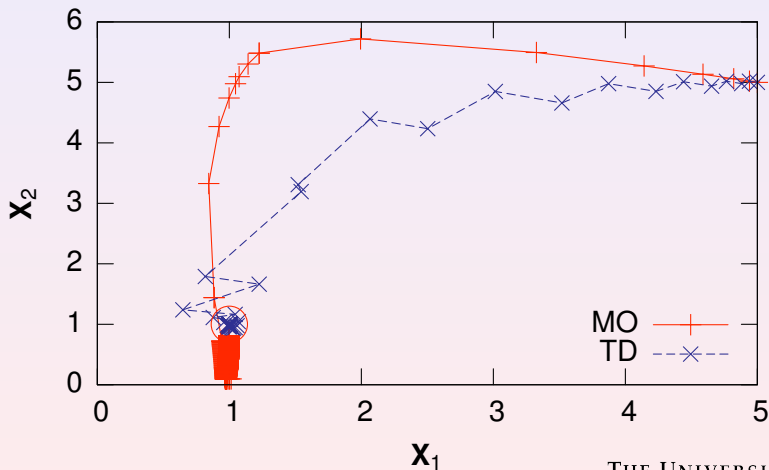
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 - 'Alternating Search' algorithm.

'Alternating Search' Fixing The Further Flaw.



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$$\Delta^{\text{ND}}(\mathbf{X}) = P(\mathbf{X})\Delta^{\text{A1}}(\mathbf{X}).$$

- Can we find a good definition for $P(\mathbf{X})$?

Can We Make Our Directional Derivative Negative?

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- Our directional derivative is

$$\begin{aligned} \nabla_{\mathbf{X}} V^{A1} \cdot \Delta^{\text{ND}} = & \left(P(\mathbf{X}) \Delta^{A1} \right)^{\top} \mathbf{C}'(\mathbf{X})^{\top} \left(\mathbf{D}'(\mathbf{C}(\mathbf{X}))^{\top} \Delta^{A1} \right) \\ & - \left(\Delta^{A1} \right)^{\top} P(\mathbf{X})^{\top} \left(\Delta^{A1} \right). \end{aligned}$$

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- We need $P(\mathbf{X})$ such that $\nabla_{\mathbf{X}} V^{A1} \cdot \Delta^{\text{ND}} < 0$.

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 - $P(\mathbf{X}) \equiv -\mathbf{D}'(\mathbf{C}(\mathbf{X}))$;
 - $P(\mathbf{X}) \equiv -\mathbf{D}'(\mathbf{C}(\mathbf{X}))^{\top}$.

First Choice — $P(\mathbf{X}) \equiv \mathbf{C}'(\mathbf{X})$.

Using this our directional derivative is now equal

$$\underbrace{\left(\Delta^{A1}\right)^{\top} \left[\mathbf{C}'(\mathbf{X})^{\top} \mathbf{C}'(\mathbf{X})^{\top} \mathbf{D}'(\mathbf{C}(\mathbf{X}))^{\top} \right] \left(\Delta^{A1}\right)}_{\text{unsure of sign}}$$

$$- \underbrace{\left(\Delta^{A1}\right)^{\top} \mathbf{C}'(\mathbf{X}) \left(\Delta^{A1}\right)}_{< 0 \text{ as } \mathbf{C}'(\mathbf{X}) \text{ strictly positive definite}}.$$

Second Choice — $P(\mathbf{X}) \equiv -\mathbf{D}'(\mathbf{C}(\mathbf{X}))$.

Using this our directional derivative is now equal

$$\underbrace{- \left(\mathbf{D}'(\mathbf{C}(\mathbf{X})) \Delta^{A1} \right)^{\top} \mathbf{C}'(\mathbf{X})^{\top} \left(\mathbf{D}'(\mathbf{C}(\mathbf{X}))^{\top} \Delta^{A1} \right)}_{\text{unsure of sign because } \mathbf{D}'(\mathbf{C}(\mathbf{X})) \text{ doesn't match } \mathbf{D}'(\mathbf{C}(\mathbf{X}))^{\top}} + \underbrace{\left(\Delta^{A1} \right)^{\top} \mathbf{D}'(\mathbf{C}(\mathbf{X})) \left(\Delta^{A1} \right)}_{< 0 \text{ as strictly negative definite}}.$$

Third Choice — $P(\mathbf{X}) \equiv -\mathbf{D}'(\mathbf{C}(\mathbf{X}))^\top$.

Using this our directional derivative is now equal

$$\underbrace{-\left(\mathbf{D}'(\mathbf{C}(\mathbf{X}))^\top \Delta^{A1}\right)^\top \mathbf{C}'(\mathbf{X})^\top \left(\mathbf{D}'(\mathbf{C}(\mathbf{X}))^\top \Delta^{A1}\right)}_{< 0 \text{ as } \mathbf{C}'(\mathbf{X}) \text{ strictly positive definite}} + \underbrace{\left(\Delta^{A1}\right)^\top \mathbf{D}'(\mathbf{C}(\mathbf{X})) \left(\Delta^{A1}\right)}_{< 0 \text{ as strictly negative definite}}.$$

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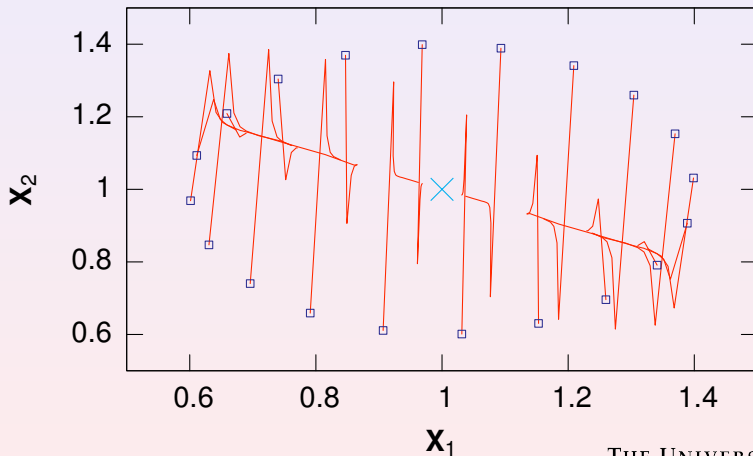
$$\underbrace{-\left(\mathbf{D}'(\mathbf{C}(\mathbf{X}))^\top \Delta^{A1}\right)^\top \mathbf{C}'(\mathbf{X})^\top \left(\mathbf{D}'(\mathbf{C}(\mathbf{X}))^\top \Delta^{A1}\right)}_{< 0 \text{ as } \mathbf{C}'(\mathbf{X}) \text{ strictly positive definite}} + \underbrace{\left(\Delta^{A1}\right)^\top \mathbf{D}'(\mathbf{C}(\mathbf{X})) \Delta^{A1}}_{< 0 \text{ as strictly negative definite}}.$$

So we have a definition of $P(\mathbf{X})$ that looks good under standard constraints.

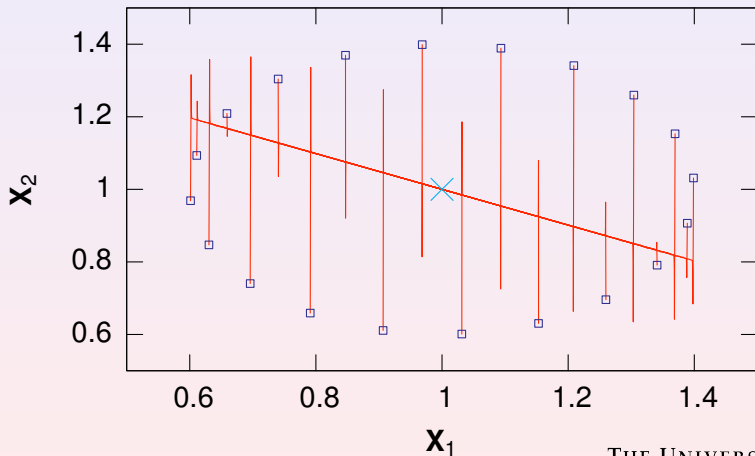
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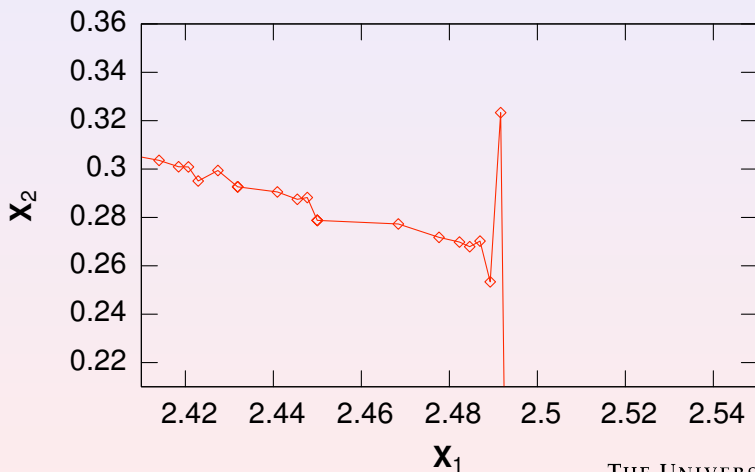
Demonstration of The Failure of Algorithm 1.



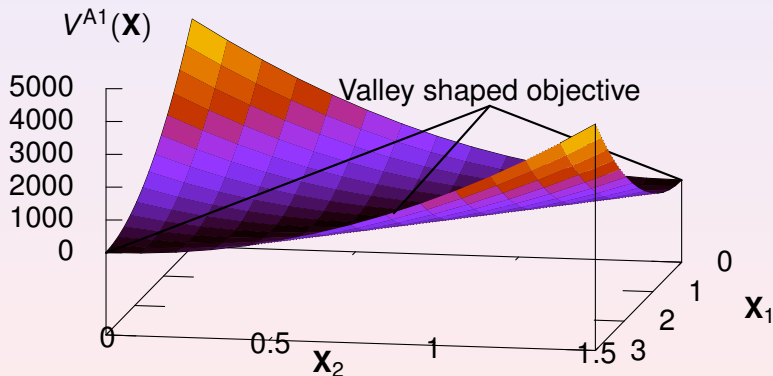
New Search Direction Succeeding Where A1 Fails.



Why The New Direction Is Slow.



Maybe The Cost Function Is The Cause.



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Two Example Problems.

Definition (First Problem)

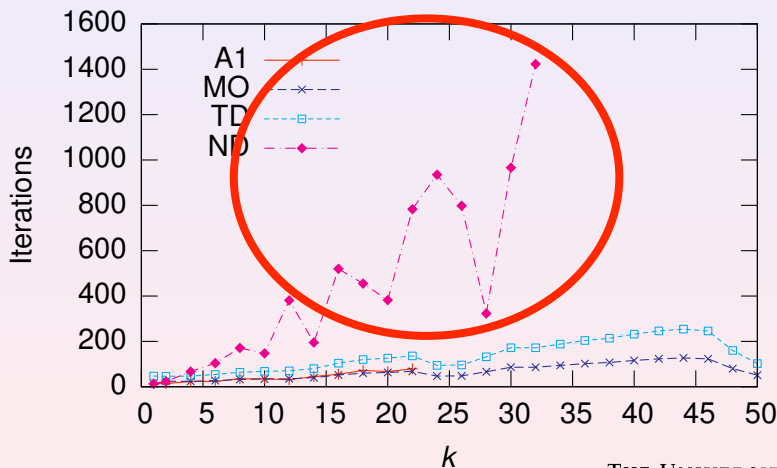
$$\mathbf{C}(\mathbf{X}) = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \mathbf{X}, \quad \mathbf{D}(\mathbf{Y}) = \begin{pmatrix} 4 \\ 3k + 1 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & k \end{pmatrix} \mathbf{Y}$$

Definition (Second Problem)

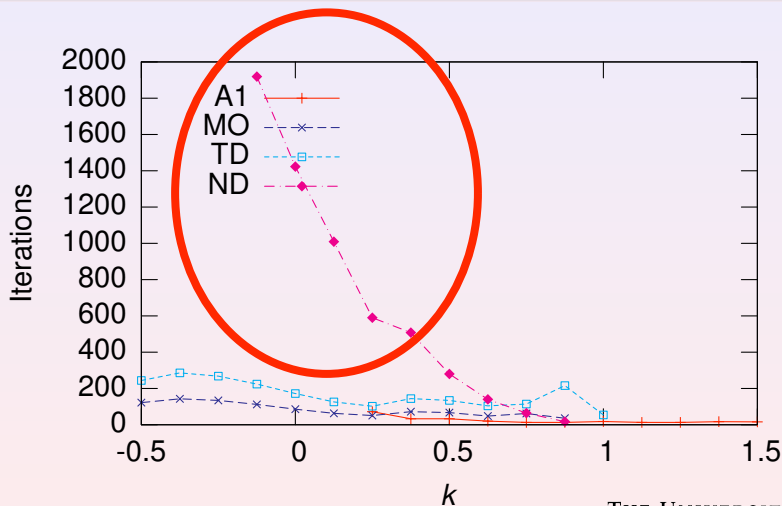
$$\mathbf{C}(\mathbf{X}) = \begin{pmatrix} k \\ 3k \end{pmatrix} + \begin{pmatrix} 2 & 1 - k \\ 1 - k & 2(1 - k) \end{pmatrix} \mathbf{X},$$

$$\mathbf{D}(\mathbf{Y}) = \begin{pmatrix} 4 \\ 1 + 96(1 - k) \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 32(1 - k) \end{pmatrix} \mathbf{Y}$$

Armijo-Like Step-Lengths And Problem 1.



Armijo-Like Step-Lengths And Problem 2.



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- Outlook
 - Find a way to improve the performance of the new direction.

For Further Reading I



M. J. Smith

Two-direction methods of calculating variable demand equilibria.

DIADEM research note, 2004.



J. Springham

On solving variable demand equilibrium problems.

Thesis submitted for the degree of MSc at the University of York, 2004.



A. Woods

A Comparison Of Automated Methods For Solving Variable Demand Equilibrium Problems.

Thesis submitted for the degree of MSc at the University of York, 2005.

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