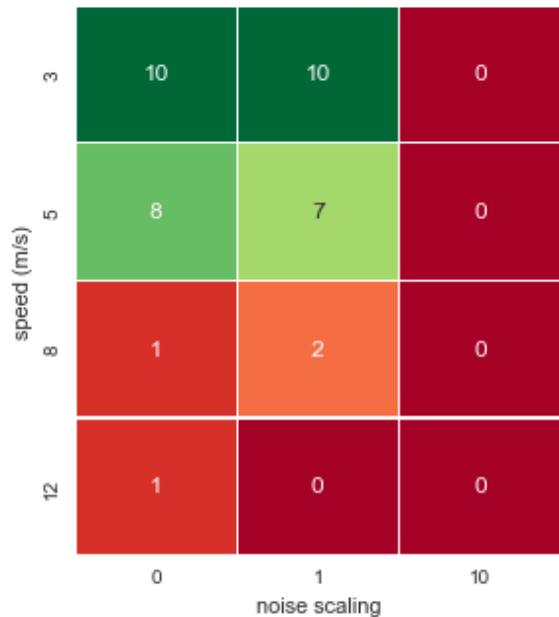
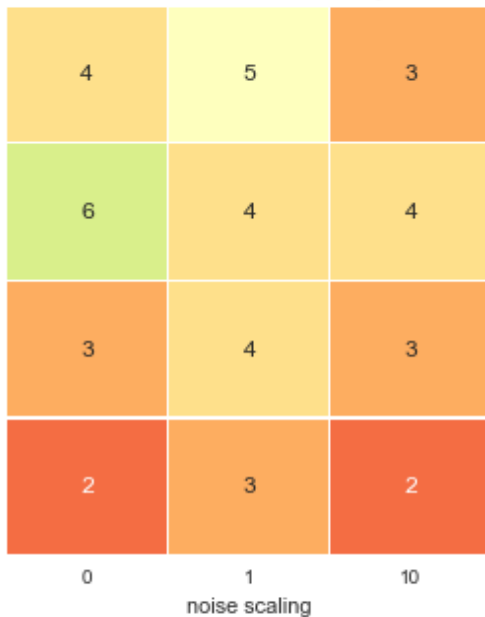


success
(out of 10)

Global Path Planning & Following



Deterministic MPC-Library



Probabilistic MPC-Library

