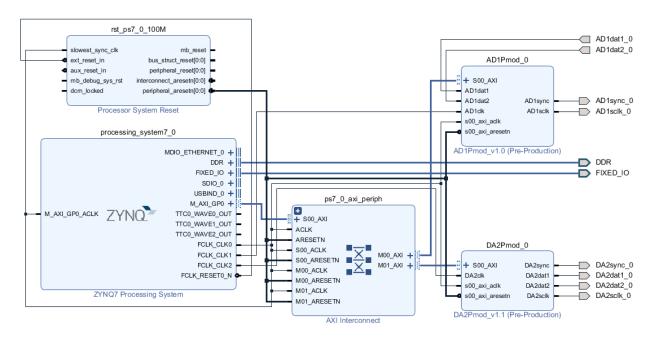


ECE3623 Embedded System Design Laboratory



AD1Pmod and DA2Pmod in FreeRTOS

In this Laboratory you will investigate utilizing a *queue* to send data between tasks in the FreeRTOS environment on the Zybo board. A Vivado hardware project that uses the PmodAD1 ADC and the PmodDA2 DAC which you are to configure is shown below.



These AD1Pmod and the DA2Pmod IPs are *not* that provided by Digilent (note the reversed names) but use the controller-data path formulation for increased performance in their data throughput. The PmodAD1 ADC uses the FCLK_CLK1 external clock signal at nominally 30 MHz (actually 30.303 MHz) for a SPI clock frequency of approximately 15 MHz where the maximum is 20 MHz. The PmodDA2 DAC uses the FCLK_CLK2 external clock signal at 50 MHz for a SPI clock frequency of 25 MHz where the maximum is 30 MHz.



The constraint file *AD1DA2JE.xdc* on *Canvas* uses the JE Pmod connector on the Zybo board with the PmodAD1 on the upper 6 pins and the PmodDA2 on the lower 6 pins. The constraint file *AD1DA2JE.xdc* must be added to the laboratory project.



AD1DA2JE.xdc

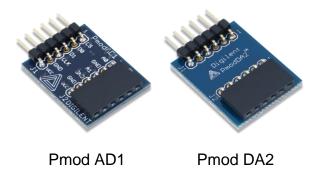
The *main.c* program in SDK is given below. This is a single task, standalone operating system application and *not* FreeRTOS. The application is a *straight-through* ADC to DAC system using the control and status signals for the ADC and DAC. The Address Editor for Vivado provides that start address for the PmodAD1 and PmodDA2 IP blocks.



The ADC input and DAC output signals are shown in the Digilent *Waveforms* display. The *straight-through* ADC to DAC application has a nominal gain of 1 but there is a difference in the fixed offsets between the ADC and DAC. You should verify the performance of the template program. The ADC and DAC are evoked by asserting an I/O port acquisition signals *AD1acq* and *DA2acq* and waiting for conversion to complete by testing the data available status commands *AD1dav* and *DA2dav*.

This is a two channel application but the ADC and DAC SPI interface can convert two channels simultaneously and thus provide no additional burden if two channels are required.

Task 1. Describe in detail the single task, standalone operating system template application. What are the various control and status signals? Using the Waveforms oscilloscope, measure the sampled data throughput rate beginning at an initial ADC data conversion (ADC SS high to active low) to the beginning of the next ADC data conversion (ADC SS high to active low). The Pmod AD1 is marked CS for chip select (or slave select SS) at pin 1. The Pmod DA2 is marked 1 for pin 1 as slave select SS.



Measure the time for each of the components of this data acquisition sequence. That is, the measured time for ADC conversion (ADC SS active low to high), DAC conversion (DAC SS active low to high) and the remaining time as overhead of the single task application. Show the input and output for a sinusoidal input signal. Note that the ADC is unipolar and the input signal must be biased to greater than 0 V as shown below in the upper panel at 2 V.



Task 2. Next reconfigure this single task, standalone operating system application as two tasks, *AD1task* and *DA2task*, within FreeRTOS. You are to use a *queue* function to transfer data for *straight-through* operation between the two tasks in sequence AD1task > DACtask.

Describe in detail the application. Repeat the measurements of the sampled data throughput rate in samples/second *fs* as given in Task 1. Comment on the performance difference between Task 1 and Task 2 for the measured the sampled data throughput rate.

Task 3. Finally, insert another FreeRTOS task *SquareRootTask* which processes the ADC data from *AD1task* as a low frequency sinusoid (<100 Hz) computes the square root of the sampled analog data and outputs the result to the DAC as *DA2task*. You are to use a *queue* function to transfer data between the three tasks in sequence *AD1task* > *SquaredTask* > *DACtask*.

Note that the amplitude of the square root of the sinusoidal signal may be smaller than the full-scale range of the DAC and should be appropriately scaled.

Describe your choice of the scaling factor. Describe in detail the application. Repeat the measurements of the sampled data throughput rate in samples/second *fs* as given in Task 1. Comment on the performance difference between Task 1, Task 2 and Task 3.

The completed Laboratories should be archived on your laptop and will form the basis of SNAP Quizzes and Exams.

You are to use the *Project Report Format* posted on *Canvas*. You are to upload your *Report* to Canvas for time and date stamping to avoid a late penalty. This Laboratory is for the weeks of March 9th and March 16th and due no later than 11:59 PM Sunday march 22nd.

AD1DA2standalone.c

```
#define DA2aca
                   0x43C10000
                                 //DA2 acquisition
                                                      - output
#define DA2dav
                    0x43C10004
                                 //DA2 data available - input
#define DA2dat1
                   0x43C10008
                               //DA2 channel 1 data - output
#define DA2dat2
                   0x43C1000C
                               //DA2 channel 2 data - output
int main(void)
{
      int adcdav;
                          //ADC data available
      int adcdata1;
                          //ADC channel 1 data
      int adcdata2;
                          //ADC channel 2 data
      int dacdata1;
                          //DAC channel 1 data
      int dacdata2;
                          //DAC channel 2 data
      int dacdav;
                          //DAC data available
      xil_printf("\n\rStarting AD1-DA2 Pmod demo test...\n");
      Xil Out32(AD1acq,0);
                                        //ADC stop acquire
      adcdav=Xil_In32(AD1dav);
                                        //ADC available?
      while(adcdav==1)
             adcdav=Xil_In32(AD1dav);
                                        //DAC stop acquire
      Xil_Out32(DA2acq,0);
      dacdav=Xil_In32(DA2dav);
                                       //DAC available?
      while(dacdav==1)
             dacdav=Xil In32(DA2dav);
      while (1)
             //ADC
             Xil_Out32(AD1acq,1);
                                        //ADC acquire
                                        //ADC data available?
             while (adcdav==0)
                    adcdav=Xil_In32(AD1dav);
             Xil_Out32(AD1acq,0);
                                                     //ADC stop acquire
             adcdata1=Xil_In32(AD1dat1);
                                                     //input ADC data
             adcdata2=Xil_In32(AD1dat2);
             while (adcdav==1)
                                                     //wait for reset
                    adcdav=Xil_In32(AD1dav);
                                                     //ADC -> DAC pass through
             dacdata1=adcdata1;
             dacdata2=adcdata2;
             //DAC
             Xil_Out32(DA2dat1, dacdata1);
                                                     //output DAC data
             Xil_Out32(DA2dat2, dacdata2);
             Xil Out32(DA2acq,1);
                                                     //DAC acquire
             while (dacdav==0)
                                                     //DAC data output?
                    dacdav=Xil In32(DA2dav);
             Xil_Out32(DA2acq,0);
                                                     //stop DAC acquire
                                                     //wait for reset
             while(dacdav==1)
                    dacdav=Xil In32(DA2dav);
      }
}
```

//DAC2Pmod from Address Editor in Vivado, second IP