



Computational Learning Theory

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Outline



- Sample Complexity
- Errors of a Hypothesis
- PAC Learnability
- Exhausting the Version Space
- Mistake Bounds

Computational Learning Theory



- What general laws constrain inductive learning?
- We seek theory to relate:
 - Complexity of hypothesis space considered by the learner
 - Accuracy to which target concept is approximated
 - Probability that the learner outputs a successful hypothesis
 - Manner in which training examples presented to the learner
- Goals:
 - **Sample complexity**: How many training examples are needed for successful learning?
 - **Computational complexity**: How much computational effort is needed for a learner to converge to a successful hypothesis?
 - **Mistake bound**: How many examples will the learner misclassify before the convergence?

Q1:

- Which of the following statements below is not the goal that computational learning theory want to achieve?
- (A) Learning successfully in polynomial time.
- (B) Finding out the upper and lower bound of error.
- (C) Deriving sample complexity.
- (D) All of the above.

Sample Complexity

- How many training examples are sufficient to learn the target concept?
- 3 settings:
 - ① Learner proposes instances, as queries to teacher:
Learner proposes instance x , teacher provides $c(x)$.
 - ② Teacher provides training examples:
Teacher provides sequence of examples of form $\langle x, c(x) \rangle$.
 - ③ Some random process (e.g., nature) proposes instances:
Instance x generated randomly, teacher provides $c(x)$.

Cross-validation

Sample Complexity: Setting 1

- Learner proposes instance x , teacher provides $c(x)$ (assume c is in learner's hypothesis space H)
- Optimal query strategy: play 20 questions
 - Pick instance x such that half of hypotheses in VS classify x positive, half classify x negative.
 - When this is possible, need $\lceil \log_2 |H| \rceil$ queries to learn c . \Rightarrow Best case
 - When not possible, need even more.

Sample Complexity: Setting 2

- Teacher (who knows c) provides training examples (assume c is in learner's hypothesis space H)
- Optimal teaching strategy: depends on H used by learner.
- Consider the case where H is conjunctions of up to n boolean literals (positive or negative).
 - e.g., $(AirTemp = Warm) \wedge (Wind = Strong)$, where $AirTemp, Wind, \dots$ each has 2 possible values.
 - if n possible boolean attributes in H , $(n + 1)$ examples suffice.
 - Why?

The size of hypothesis space ($|H|$) : 3^n (Attribute is +, -, or ?)

The number of examples: $\log(|H|) \Rightarrow$ Worst case

如果concept有don 't care? (1/2)

	A ₁	A ₂	A ₃	A _n
Concept:	+	-	?	?...	?

要學會這樣的concept，需要提供幾個example??

Step1: 學don' t care

A ₁	A ₂	A ₃	A _n	Class
+	-	+	+...	+	=> +
+	-	-	-...	-	=> +

需要兩個
example
來學所有的
don't
care

同時包含+ & -，在conjunction做不到
=> 所以就會是don 't care

Step2: 學A₁只能是+ & A₂只能是-

+	+	+	+...	+	=> -
-	-	+	+...	+	=> -

如果concept有don't care? (2/2)

A_1	A_2	A_3	A_n
+	-	?	?...	?

要學會這樣的concept，需要提供幾個example??

Step1: 學don't care

A_1	A_2	A_3	A_n	Class
-------	-------	-------	-------	-------	-------

$\begin{matrix} + & - & + & +\dots & + & \Rightarrow + \end{matrix}$

$\begin{matrix} + & - & - & -\dots & - & \Rightarrow + \end{matrix}$

$n-k$

花兩個example來學k個don't care

Step2: 學 A_1 只能是+ & A_2 只能是-

$\begin{matrix} + & + & + & +\dots & + & \Rightarrow - \end{matrix}$

$\begin{matrix} - & - & + & +\dots & + & \Rightarrow - \end{matrix}$

$n-k$ 個
example

Total example: $n-k+2$. If there is don't care, $k \geq 1 \Rightarrow n-k+2 \leq n+1$

如果concept都沒有don 't care?



	A_1	A_2	A_3	A_n
Concept:	+	+	+	+...	+

要學會這樣的concept，需要提供幾個example??

A_1	A_2	A_3	A_n	Class
+	+	+	+...	+	$\Rightarrow +$
-	+	+	+...	+	$\Rightarrow -$
+	-	+	+...	+	$\Rightarrow -$
+	+	-	+...	+	$\Rightarrow -$
\vdots					

1 example

n example

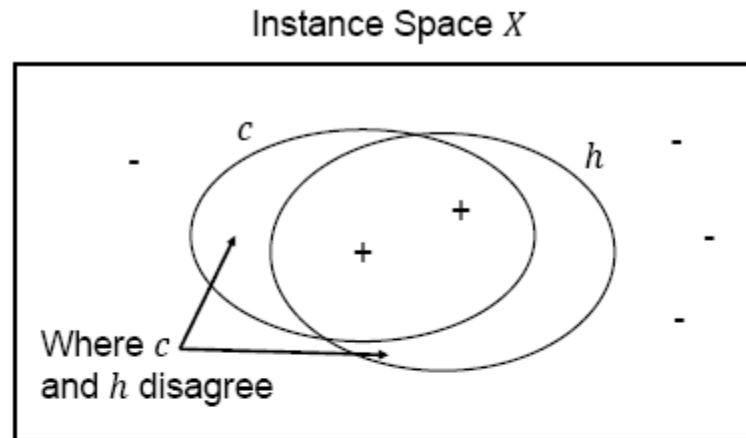
Total example: $n+1$

Sample Complexity: Setting 3

- **Given:**

- Set of instances X .
 - Set of hypotheses H .
 - Set of possible target concepts C .
 - Training instances generated by a fixed, unknown probability distribution \mathbb{D} over X .
- Learner observes a sequence D of training examples of form $\langle x, c(x) \rangle$, for some target concept $c \in C$.
 - Instances x are drawn from distribution \mathbb{D} .
 - Teacher provides target value $c(x)$ for each x .
 - Learner must output a hypothesis h estimating c
 - h is evaluated by its performance on subsequent instances drawn according to \mathbb{D}
 - **Note:** randomly drawn instances, noise-free classifications.

True Error of a Hypothesis



Definition

The **true error** (denoted $\text{error}_{\mathbb{D}}(h)$) of hypothesis h with respect to target concept c and distribution \mathbb{D} is the probability that h misclassifies an instance drawn at random according to \mathbb{D} .

$$\text{error}_{\mathbb{D}}(h) \equiv \Pr_{x \in \mathbb{D}} (c(x) \neq h(x))$$

Two Notations of Error

多常錯? => 100個training example 錯2個 => 2%

- **Training error**, denoted $\text{error}_D(h)$, of hypothesis h with respect to c :
How often $h(x) \neq c(x)$ over training instances.
- **True error**, denoted $\text{error}_{\mathbb{D}}(h)$, of hypothesis h with respect to c :
How often $h(x) \neq c(x)$ over future random instances.
- Our concerns: Training error: 2% => True error不高於3%的機率是多少?
 - Can we bound the **true** error of h given its **training** error?
 - First consider when **training** error of h is zero (i.e., $h \in VS_{H,D}$)

PAC Learning

- Consider a class C of possible target concepts defined over a set of instances X of length n , and a learner L using hypothesis space H .
- We desire that the learner **probably** learns a hypothesis that is **approximately correct**.

Definition

C is **PAC-learnable** by L using H if for all $c \in C$, distributions \mathbb{D} over X , ϵ such that $0 < \epsilon < 1/2$, and δ such that $0 < \delta < 1/2$, learner L will with probability at least $(1 - \delta)$ output a hypothesis $h \in H$ such that $\text{error}_{\mathbb{D}}(h) \leq \epsilon$, in time that is polynomial in $1/\epsilon$, $1/\delta$, n and $\text{size}(c)$.

- To prove any concept is PAC-learnable or not, we need to derive the sample complexity needed for setting 3.

如果一個concept是PAC-learnable，代表此concept沒有很難，可以在夠短的時間內，夠高的機率輸出一個夠準確的hypothesis

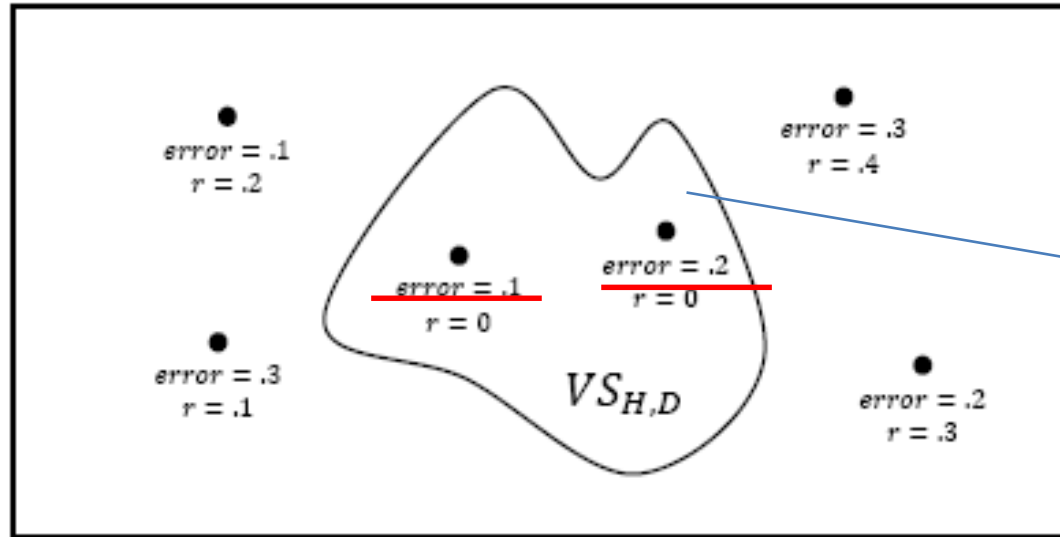
Q2:



- Which of the following statements is true about PAC learning?
- (A) The parameters ε should be less than $\frac{1}{2}$.
- (B) The algorithm is expected to output a hypothesis that is approximately correct.
- (C) If the concept is PAC learnable, we can get an accurate hypothesis with a high enough probability in a short time.
- (D) All of the above.

Exhausting the Version Space

Hypothesis Space H



**

r : training error
error: true error

This version space is **0.3-exhausted**.

(r is training error, $error$ is true error)

Definition

The version space $VS_{H,D}$ is ϵ -**exhausted** with respect to \mathcal{C} and \mathbb{D} , if every hypothesis h in $VS_{H,D}$ has error less than ϵ with respect to \mathcal{C} and \mathbb{D} .

$$(\forall h \in VS_{H,D}) \text{error}_{\mathbb{D}}(h) < \epsilon$$

所有



Question

- Given training error is 0 (i.e. hypothesis is in version space), what is the true error?
- \Rightarrow How many examples can make version space ε -exhausted?

Probability of Exhausting the Version Space



- How many examples ϵ -exhaust the VS?

Theorem (Haussler, 1988)

If H is finite, and D is a sequence of $m \geq 1$ independent random examples (from distribution \mathbb{D}) of some target concept c , then for any $0 \leq \epsilon \leq 1$, the probability that $VS_{H,D}$ is not ϵ -exhausted is less than or equal to

$$|H|e^{-\epsilon m}.$$

- The above theorem bounds the probability that any **consistent** learner will output a hypothesis h with $\text{error}_{\mathbb{D}}(h) \geq \epsilon$.
- If we want to this probability to be below δ

$$|H|e^{-\epsilon m} \leq \delta \quad \xRightarrow{\log} \quad m \geq \frac{1}{\epsilon} (\ln |H| + \ln(1/\delta))$$

1- δ 的機率輸出夠準確的 hypothesis 所需要的 example

充分但不必要條件!!

Q3:

- Which of the following statements is true about the probability of the version space is not ε -exhausted?
- (A) By this theorem , we can know the most number of example drawn from distribution, that we can get a hypothesis such that the true error is large than or equal to ε .
- (B) According to this, we can infer that if, Pr will be large than or equal to $|H|e^{-\varepsilon m}$.
- (C) m is the symbol of the number of the examples.
- (D) The theorem is still true, if H is infinite.

Proof of ϵ -exhausting (1/2)

- What is the probability that version space is not ϵ -exhausted if m examples are given?

Proof: ϵ -exhausting the version space.

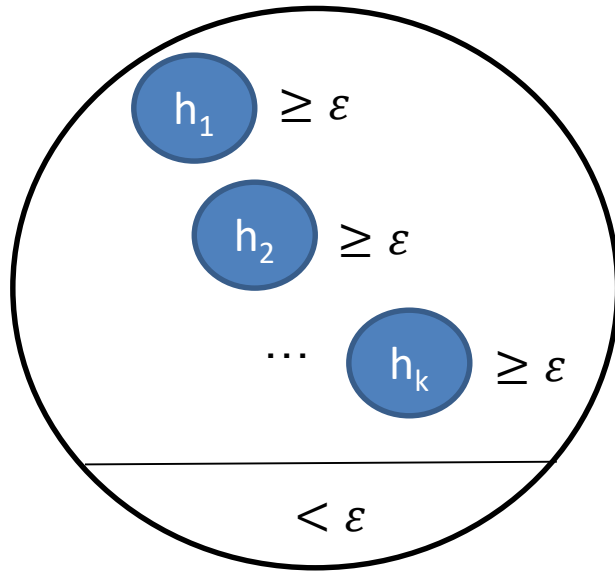
- Let h_1, \dots, h_k be all hypotheses in H with true errors greater than ϵ with respect to c .
- Fail to ϵ -exhausting the VS iff at least one of these hypotheses consistent with all m examples.
- Such prob. for a single hypothesis and a single random example is $(1 - \epsilon)$; or $(1 - \epsilon)^m$ for all m examples.
- The prob. that fail to ϵ -exhausting is at most $k(1 - \epsilon)^m$.

For k 個 hypothesis

$$k(1 - \epsilon)^m \leq |H|(1 - \epsilon)^m \leq |H|e^{-\epsilon m}$$



Proof of ε -exhausting (2/2)



$$\forall h \quad error_{ID}(h_i) \geq \varepsilon$$

$h(x_1) : +$
 $c(x_1) : +$

$\left. \begin{array}{l} h(x_1) : + \\ c(x_1) : + \end{array} \right\}$ h has to consistent with c
 Otherwise, h is not in the version space.
 The probability of h consistent with c
 based on x_1 is $1 - \varepsilon$

$h(x_2) : -$
 $c(x_2) : -$

$\left. \begin{array}{l} h(x_2) : - \\ c(x_2) : - \end{array} \right\}$ The probability of h consistent with c
 based on x_2 is $1 - \varepsilon$

\vdots m examples

After asking m times, the probability of h consistent with c is $(1 - \varepsilon)^m$

Learning Conjunctions of Boolean Literals



- Recall that $m \geq \frac{1}{\epsilon}(\ln |H| + \ln(1/\delta))$ examples are sufficient to assure with probability at least $(1 - \delta)$ that every h in $VS_{H,D}$ satisfies $error_{\mathbb{D}}(h) \leq \epsilon$.
 - Suppose H contains conjunctions of constraints on up to n boolean attributes.
 - $|H| = 3^n$. Every attribute can be (+, -, don't care)
 - $m \geq \frac{1}{\epsilon}(n \ln 3 + \ln(1/\delta))$
 - Boolean conjunctions is PAC-learnable!
- Polynomial in $\frac{1}{\epsilon}$.
Polynomial in $\frac{1}{\delta}$.
Polynomial in n

EnjoySport Revisit

- Inn *EnjoySport*, if we consider only conjunctions, $|H| = 973$.

$$m \geq \frac{1}{\epsilon} (\ln 973 + \ln(1/\delta))$$

- If want to assure that with probability **95%**, *VS* contains only hypotheses with $\text{error}_{\mathbb{D}}(h) \leq 0.1$, then it is sufficient to have m examples, where

$$m \geq \frac{1}{0.1} \left(\ln 973 + \ln \frac{1}{0.05} \right)$$

$m \geq 98.8 \Rightarrow m=99$ 就充分
 \Rightarrow 給99個example，就有95%以上的機率可以輸出一個true error<10%的hypothesis 23

Agnostic Learning

(Learning Inconsistent Hypotheses)

- The equation $m \geq \frac{1}{\epsilon}(\ln |H| + \ln(1/\delta))$ tells us how many training examples suffice to ensure that every hypotheses in H having zero training error will have true error of at most ϵ .

$C \neq H$

- However, if $c \notin H$, zero training error may not be achievable.
- We desire to know how many examples suffice to ensure $error_{\mathbb{D}}(h) \leq error_D(h) + \epsilon$.

- Hoeffding bounds:** $|\bar{X} - \mu|$

$$\Pr(error_{\mathbb{D}}(h) > error_D(h) + \epsilon) \leq e^{-2m\epsilon^2}$$

- Sample complexity in this case:

$$\Pr((\exists h \in H) error_{\mathbb{D}}(h) > error_D(h) + \epsilon) \leq \underbrace{|H|}_{H\text{個}} e^{-2m\epsilon^2} \leq \delta$$

$$m \geq \underbrace{\frac{1}{2\epsilon^2}}_{H\text{個}} (\ln |H| + \ln(1/\delta))$$

Infinite Hypothesis Space

- The above sample complexity has two drawbacks:
 - ① Weak bounds.
 - ② H has to be finite.
- We need another measure of the complexity of H .

Definition

A **dichotomy** of a set S is a partition of S into two disjoint subsets.

Definition

A set of instances S is **shattered** by hypothesis space H iff for every dichotomy of S there exists some hypothesis in H consistent with this dichotomy.

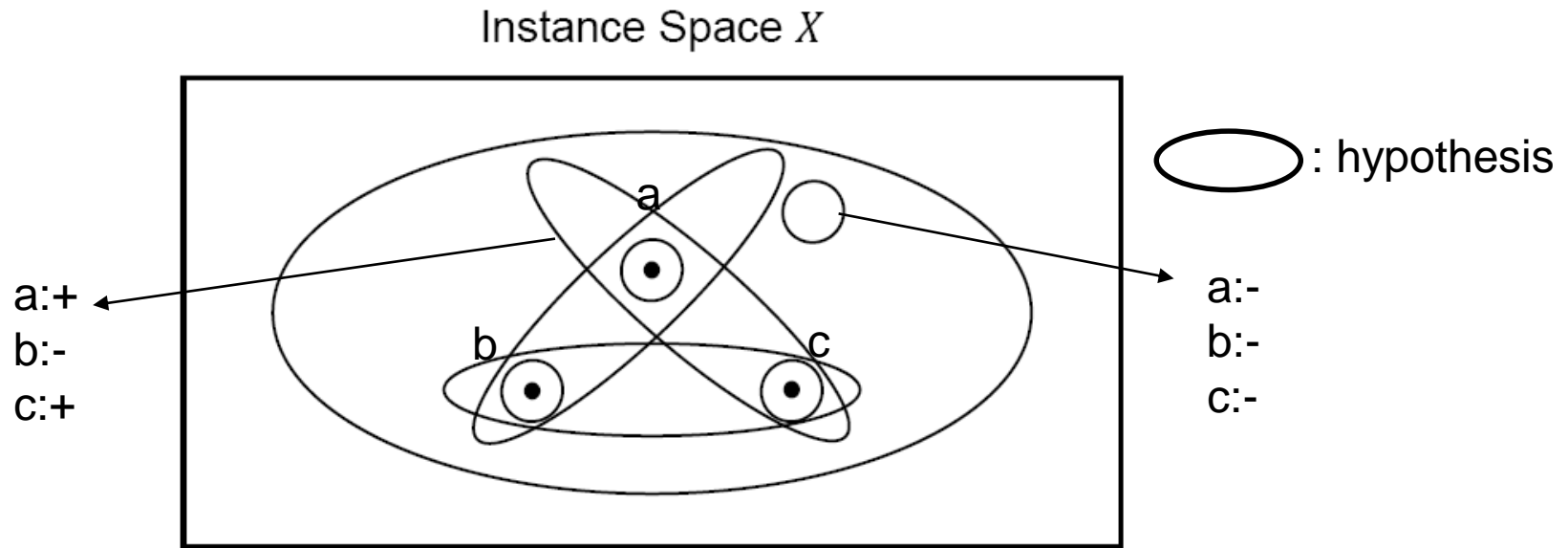
$$S = \{a, b, c\} \Rightarrow \left. \begin{array}{l} \{a\} \\ \{b, c\} \end{array} \right\} h \in H \quad \{a\}:+ \quad \{b, c\}:-$$

Shattering a Set of Instances (1/2)

- S is a subset of instances, $S \subseteq X$; $2^{|S|}$ distinct dichotomies in total.
- Each $h \in H$ imposes a dichotomy on S :

$$\{x \in S | h(x) = 0\} \text{ and } \{x \in S | h(x) = 1\}$$

- H shatters S iff every dichotomy of S is represented by some $h \in H$.



a, b, c instances have 8 dichotomies.

=>如果8個dichotomies對應的h都在H裡
=>S is shattered by H

Shattering a Set of Instances (2/2)

- H shatter $S \Rightarrow |H| \geq 2^{|S|}$

a	b	c	
+	+	+	h_1
+	+	-	h_2
...			...
-	-	-	h_8

} 8個h
均屬於H

The Vapnik-Chervonenkis (VC) Dimension



- The ability to shatter a set of instances is closely related to the **inductive bias** of the hypothesis space.
- An **unbiased** hypothesis space can represent every possible concept (dichotomy) over X : **An unbiased hypothesis space shatters X .**
- What if H cannot shatter X , but can shatter a subset S ?
- Intuitively, the larger S is, the more expressive H is.

Definition

The **Vapnik-Chervonenkis dimension**, $VC(H)$, of hypothesis space H is the size of the largest finite subset of instance space X shattered by H . If arbitrarily large finite sets of X can be shattered by H , then $VC(H) \equiv \infty$.

- Note that for any finite H , $VC(H) \leq \log_2 |H|$. $\Rightarrow |H| \geq 2^{|S|} \Rightarrow |H| \geq 2^{VC(H)}$
 \Rightarrow 雙邊取log



Why VC Dimension?

- Make VC dimension to define sample complexity.
- Since $m \geq \log|H|$ is too weak, we will use VC Dimension to bound.

Q4:

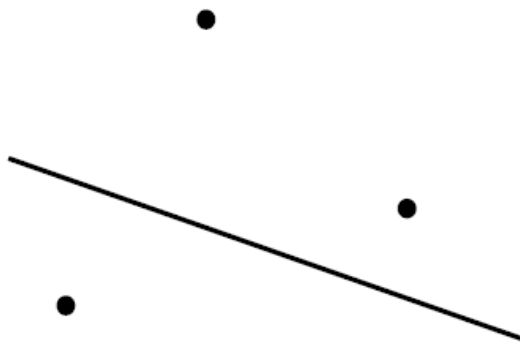
- Which of the following statements is the application of VC dimension?
- (A) The complexity of the model.
- (B) The accuracy of the prediction.
- (C) The speed of the computation.
- (D) The upper bound of the training examples.

VC Dimension (1/3)

- Instances are real numbers: $X = \mathbb{R}$
- Hypotheses are real intervals: $h_{ab} = a < x < b$; $H = \{\forall a, b \ h_{ab}\}$
- Consider $S = \{3.1, 5.7\}$. H shatters S , why?
- For any set of 3 instances: $S = \{x, y, z\}$, where $x < y < z$. There is no way for H to represent this dichotomy: $\{x, z\}$ and $\{y\}$.

$$VC(H) = 2$$

- For 2D points (X) and line separations (H), $VC(H) = 3$.



(a)

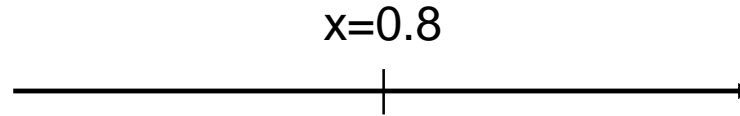


(b)

Example: 1 Instance on a Line

$$X = \mathbb{R}$$

$$|H| = \infty$$



$\{x\} \Rightarrow$ Dichotomy: $\emptyset, \{x\}$
 $\{x\}, \emptyset$

Is there h can make $\emptyset: +, \{x\}: -$? \Rightarrow don't include x : $h_{10,20}$

Is there h can make $\{x\}: +, \emptyset: -$? \Rightarrow include x : $h_{0,1}$

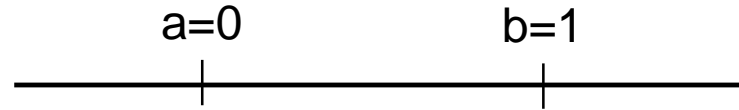
$h_{10,20}$ and $h_{0,1}$ are belong to $H \Rightarrow H$ shatter $\{x\}$

$VC(H) = ?$ $VC(H) \geq 1$

Example: 2 Instances on a Line

$$X = \mathbb{R}$$

$$|H| = \infty$$



Dichotomy: 4 \Rightarrow

+	+
+	-
-	+
-	-

Is there h can **get** + + ? \Rightarrow Include a and b: $h_{5,5}$

Is there h can **get** + - ? \Rightarrow Include a and not include b: $h_{-5,0.5}$

Is there h can **get** - + ? \Rightarrow not include a and include b: $h_{0.5,5}$

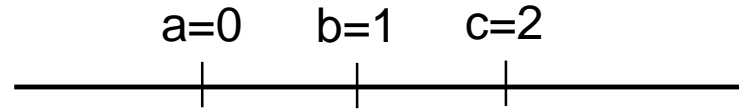
Is there h can **get** - - ? \Rightarrow not include a and b: $h_{20,40}$

All h are belong to $H \Rightarrow H$ shatter $\{a,b\}$

$VC(H)=?$ $VC(H) \geq 2$

Example: 3 Instances on a Line

$$X = \mathbb{R}$$
$$|H| = \infty$$



Dichotomy: 8

Is there h can get + - + ? \Rightarrow Include a , c and not include b :??

\Rightarrow We cannot get a “ h ” to shatter **any** 3 instances in the line.

By definition of VC, we have to shatter “**every**” dichotomy

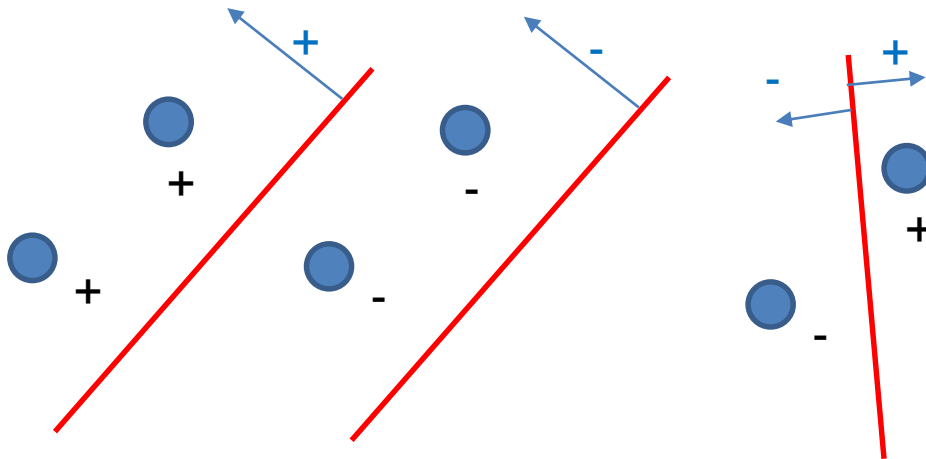
$$\Rightarrow VC(H) \neq 3$$

$$\Rightarrow VC(H) = 2$$

Example: Linear Classifier with 2 Instances



$$X = \mathbb{R}^2 = \{(x, y) / x, y \in \mathbb{R}\}$$
$$m(H) = \{(x, y) / ax + by + c \geq 0, a, b, c \in \mathbb{R}\}$$

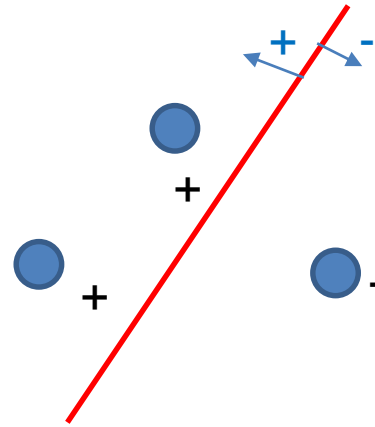
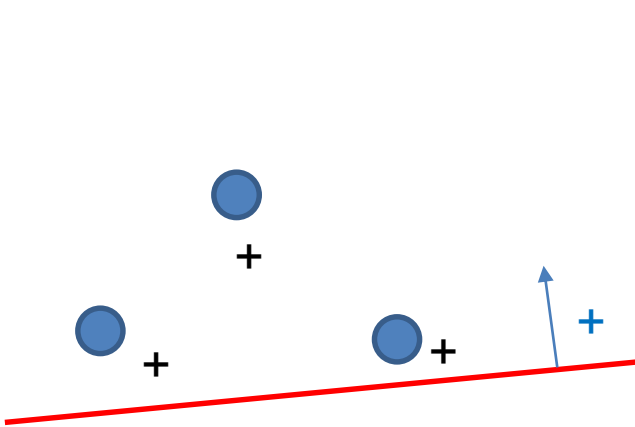


$$VC(H) = ?$$
$$\Rightarrow VC(H) \geq 2$$

Example: Linear Classifier with 3 Instances



$$X = \mathbb{R}^2 = \{(x, y) / x, y \in \mathbb{R}\}$$
$$m(H) = \{(x, y) / ax + by + c \geq 0, a, b, c \in \mathbb{R}\}$$



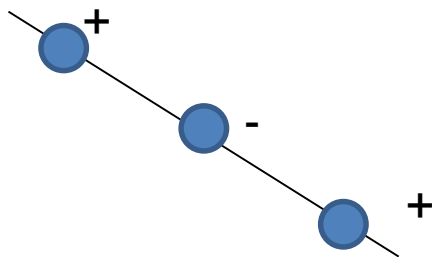
$VC(H) = ?$
 $\Rightarrow VC(H) \geq 3$

Example: Linear Classifier with 3 Instances



$$X = \mathbb{R}^2 = \{(x,y) | x,y \in \mathbb{R}\}$$
$$m(H) = \{(x,y) | ax+by+c \geq 0, a,b,c \in \mathbb{R}\}$$

If 3 instances are on a line??



We cannot find a linear classifier to shatter 3 instances on a line.

So $VC(H) \geq 2$??

Definition

The **Vapnik-Chervonenkis dimension**, $VC(H)$, of hypothesis space H is the size of the largest finite subset of instance space X shattered by H . If arbitrarily large finite sets of X can be shattered by H , then $VC(H) \equiv \infty$.

Q5:

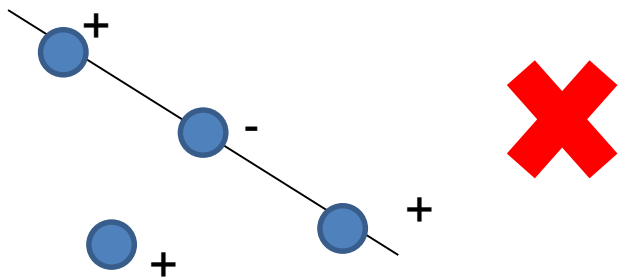
- Consider the case on the 2D plane. $VC(H)=?$
- (A) 2
- (B) 3
- (C) 4
- (D) 8

Example: Linear Classifier with 4 Instances

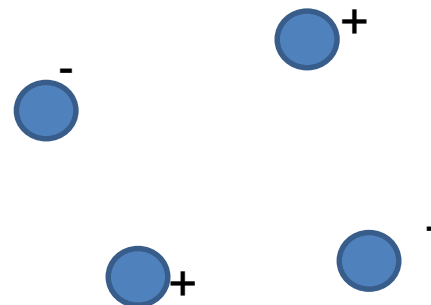


$$X = \mathbb{R}^2 = \{(x, y) / x, y \in \mathbb{R}\}$$
$$m(H) = \{(x, y) / ax + by + c \geq 0, a, b, c \in \mathbb{R}\}$$

Case 1: Any 3 instances are on a line.



Case 2: Any 3 instances are not on a line.



Dichotomy: 16

\Rightarrow There is one dichotomy cannot be shattered.

\Rightarrow XOR problem.

$VC(H) = ?$

$\Rightarrow VC(H) \neq 4$

$\Rightarrow VC(H) = 3$

Linear Classifier in n Dimension



- Linear classifier in n dimension => In general, the VC is $n+1$