

## HW3

(Please use **MATLAB** to finish the following problems)

1.

**CP3.1** Determine a state variable representation for the following transfer functions (without feedback) using the **ss** function:

$$(a) \quad G(s) = \frac{1}{s + 10}$$

$$(b) \quad G(s) = \frac{s^2 + 5s + 3}{s^2 + 8s + 5}$$

$$(c) \quad G(s) = \frac{s + 1}{s^3 + 3s^2 + 3s + 1}$$

2.

**CP3.2** Determine a transfer function representation for the following state variable models using the **tf** function:

$$(a) \quad \mathbf{A} = \begin{bmatrix} 0 & 1 \\ 2 & 8 \end{bmatrix}, \mathbf{B} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \mathbf{C} = [1 \quad 0]$$

$$(b) \quad \mathbf{A} = \begin{bmatrix} 1 & 1 & 0 \\ -2 & 0 & 4 \\ 5 & 4 & -7 \end{bmatrix}, \mathbf{B} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, \mathbf{C} = [0 \quad 1 \quad 0]$$

$$(c) \quad \mathbf{A} = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix}, \mathbf{B} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \mathbf{C} = [-2 \quad 1].$$

3.

**CP3.4** Consider the system

$$\dot{\mathbf{x}}(t) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & -2 & -5 \end{bmatrix} \mathbf{x}(t) + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u(t),$$

$$y(t) = [1 \quad 0 \quad 0] \mathbf{x}(t).$$

- Using the `tf` function, determine the transfer function  $Y(s)/U(s)$ .
- Plot the response of the system to the initial condition  $\mathbf{x}(0) = [0 \quad -1 \quad 1]^T$  for  $0 \leq t \leq 10$ .
- Compute the state transition matrix using the `expm` function, and determine  $\mathbf{x}(t)$  at  $t = 10$  for the initial condition given in part (b). Compare the result with the system response obtained in part (b).

4.

**CP3.7** Consider the following system:

$$\dot{\mathbf{x}}(t) = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \mathbf{x}(t) + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u(t)$$

$$y(t) = [1 \quad 0] \mathbf{x}(t)$$

with

$$\mathbf{x}(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}.$$

Using the `lsim` function obtain and plot the system response (for  $x_1(t)$  and  $x_2(t)$ ) when  $u(t) = 0$ .

5.

**CP3.8** Consider the state variable model with parameter  $K$  given by

$$\dot{\mathbf{x}}(t) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -2 & -K & -2 \end{bmatrix} \mathbf{x}(t) + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u(t),$$

$$y(t) = [1 \quad 0 \quad 0] \mathbf{x}(t).$$

Plot the characteristic values of the system as a function of  $K$  in the range  $0 \leq K \leq 100$ . Determine that range of  $K$  for which all the characteristic values lie in the left half-plane.