



A Fast Methodology Flow for IP Input and Max Output Cap Characterization

Peter H. Chen, Harrison Liu, Peter Pong, Jim Wang, and Jerry Hong

Faraday Technology Corporation
10-2 Li-Hsin First Road
Science-Based Industrial Park
Hsinchu, Taiwan 300, ROC

{pchen, hcliu, pong, jhwang, jhong}@faraday-tech.com

ABSTRACT

This paper proposes a fast and generic working methodology flow for Input Cap and Max Output Cap of Intellectual Property (IP), i.e., input cap and max output cap characterization with partial circuit extraction and SPICE simulation. With this Methodology/Algorithm, the run-time is tremendously cut down from weeks into seconds. More than 1500 test cases (counted by pin) are used in combination with 250 Faraday IPs for different technologies to validate the methodology/algorithm, which forms an essential part of Faraday's MxCAE (IP characterization) methodology flow.



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1.0 Introduction

As IP designs grow bigger, it is very common for IPs to contain more than 500K transistors. The growing number of transistors increases the difficulty for SPICE in solving the circuit matrix, thereby causing the non-convergence problem. However, the time-to-market of IP delivery and ASIC design is critical. As IPs grow bigger and bigger and SPICE simulation run-time grows exponentially, causing an NP (Non-Polynomial) problem, it is impractical to get the input and output cap through the whole IP simulation. Some commercial tools provide I-V curve or circuit simplification to reduce the run-time; however, the accuracy is not good enough and the run-time so reduced is limited and remains a problem for IP simulation.

With the methodology and algorithm presented in this paper, the run-time for input cap and output cap characterization can be reduced from weeks long to within seconds/minutes. The accuracy of the input cap and output cap is within 90% or above [3, 4, 5]. At Faraday, such run-time and accuracy are acceptable by IP designers. This methodology/algorithm has been successfully implemented and verified as an essential part of Faraday's MxCAE tool (a Mixed Signal Characterization and Verification Tool at Faraday) to find the maximum loading and input cap [3, 4]. By now, it has been fully verified by all IPs under 0.18 μm (and below) process technology for both regular power and low leakage libraries which contain more than 250 released IPs.

2.0 Methodology Flow Overview

Figure 1 shows the methodology flow for finding the input cap and max loading of an IP. It is part of Faraday's IP characterization (MxCAE) flow.

The step of cleaning up SPICE includes removing the correction of the power setup and floating resistors.

The analog pin and special IO pin are skipped without characterization. The characterization is only concerned about pins with digital signals. Hence, special IO pins, such as those for reference signal or special resistor configuration, are ignored.

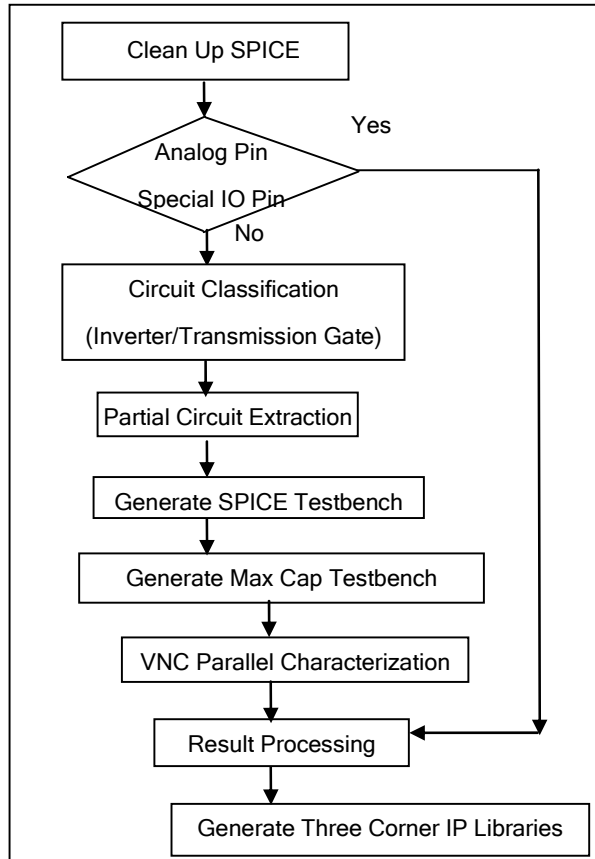


Figure 1. Flowchart of Input Cap and Max Loading Search for IPs

3.0 Partial Circuit Extraction and SPICE Simulation

The partial circuit extraction and SPICE simulation are used to find the input cap.

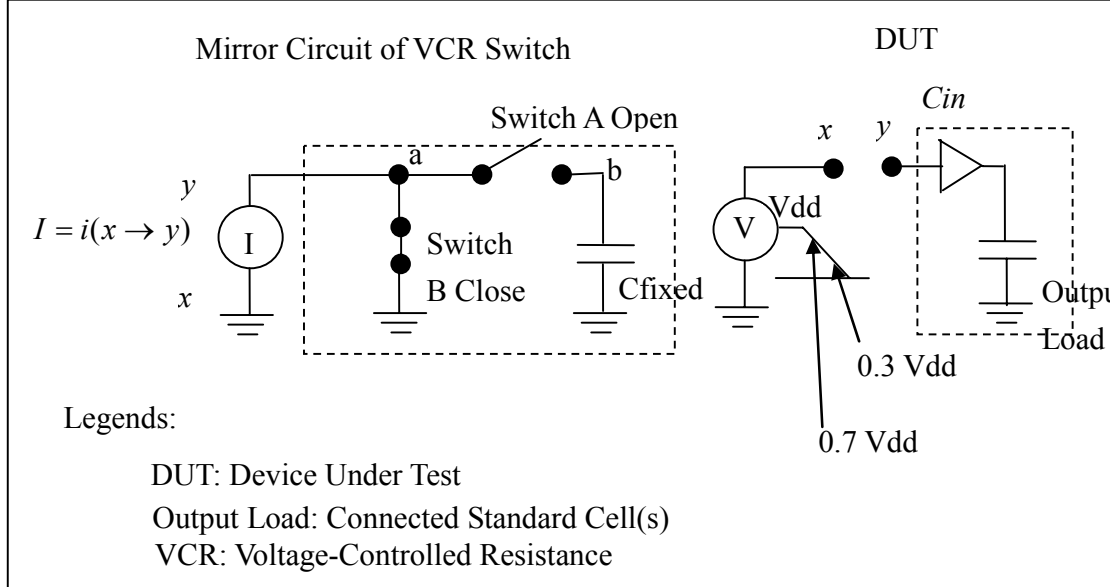


Figure 2. Mirror Circuit of VCR Switch and Device Under Test

In Figure 2, the Mirror Circuit of VCR Switch is used to measure the current at $x \rightarrow y$. Initially, switch A is opened and switch B closed when $V(y) < 0.3 \cdot V_{dd}$ and $V(y) > 0.7 \cdot V_{dd}$. It starts to charge IP Under Test (IUT) with current when $0.3 \cdot V_{dd} \leq V(y) \leq 0.7 \cdot V_{dd}$ (switch A close and switch B open).

From the charge formula, $Q = I \cdot t = V \cdot C$, we have the following derivation:

From the switch side:

$$Q = \max(Vb) \cdot C_{fixed} \quad (1)$$

From the device side:

$$Q = \int_{0.3V_{dd}}^{0.7V_{dd}} C_{in} \cdot dV = 0.4V_{dd} \cdot C_{in} \quad (2)$$

Where, C_{in} is the downstream capacitance of device and the loading capacitance.

From (1) and (2), we have:

$$Q = \max(Vb) \cdot C_{fixed} \cong 0.4V_{dd} \cdot C_{in} \quad (3)$$

Therefore, we have:

$$C_{in} \cong \max(Vb) \cdot C_{fixed} / 0.4V_{dd} \quad (4)$$

Note: The C_{fixed} ($1.5 \cdot 10^{-10}$) should be on a bigger order for DUT to charge and discharge.

The following Voltage Control Resistances (VCRs) are used to control the switch depending on the input voltages. Figure 3 shows the relations between resistance and voltage.

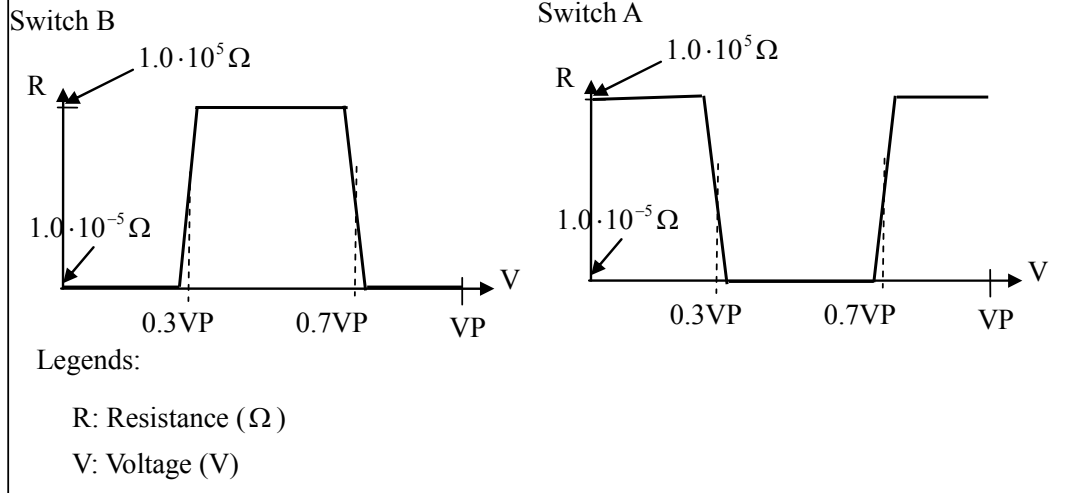


Figure 3. VCRs for Switch A and Switch B

3.1 SPICE VCR Control

The SPICE VCR command will be used for Piecewise Linearity (PWL). VCR controls in a time-independent manner whether to open or to close the switch depending on the applied voltage.

```
Gxxx n+ n- VCR PWL (1) in+ in- <DELTA=val> <SCALE=val>
+ <M=val> <TC1=val> <TC2=val> x, y
+ <IC=val> <SMOOTH=val>
```

The following shows an example of VCR operation between node a and node b in Figure 2 and Figure 5. The switch A is opened before and after the operating voltages of 0.3VP and 0.7VP, and closed between the operating voltages of 0.3VP and 0.7VP. The switch B is closed at before and after 0.3VP and 0.7VP and closed otherwise.

```
grb a_a a_b_b vcr pwl(1) CLK gnd
+ 0.00,1.0e+15 'IPCVP*0.3-0.001',1.0e+15
+ 'IPCVP*0.3',1.0e-05 'IPCVP*0.7',1.0e-05
+ 'IPCVP*0.7+0.001',1.0e+15 IPCVP,1.0e+15
```

3.2 Applying Voltage

Figure 4 shows the voltage VP is applied with a slope between 1 and 4 nsec.

```
Vx x 0 PWL(0n sv 1n sv 4ns ev)
Where sv = VP and ev = 0.
```

As shown in Figure 5, the applied voltage drops gradually from VP to 0 between 1 and 4 nsec. Switch A is closed and switch B opened between 0.7VP and 0.3VP, and the current starts to charge IUT with $I(x \rightarrow y)$.



The first two layers of devices are extracted to represent the input capacitance of entire IPs. The effects from the third layer to the output pins of IPs are neglected, similar to standard cell characterization. In standard cell characterization, only the device (first layer) is considered, the second layer being represented with an output loading.

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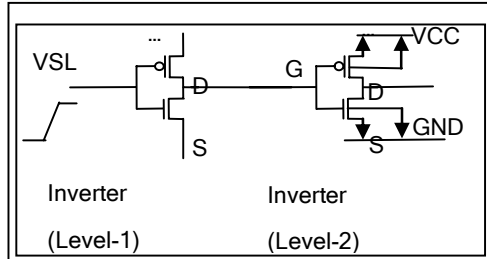


Figure 6. Two Layers of Inverters

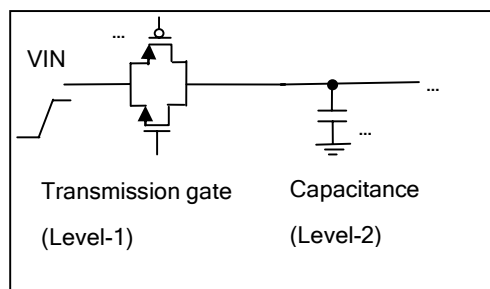


Figure 7. Transmission Gate and Capacitance

Note 1: The transmission gate can be CMOS or just NMOS or PMOS.

Note 2: During the extraction, the gate port on the transmission gate is set to Voltage High if it is an NMOS and set to ground if it is a PMOS. However, in cases where the input pin is disabled, the gate port will be tied to high or ground.

Note 3: In order to prevent DC path error caused by device floating, the output of the second-level device has to be disconnected and tied to high or low during the device extraction. In the second-level inverter, if S (Source) or D (Drain) has the same name as the substrate (B), then the S or D has to be tied to high for PMOS and tied to low for NMOS.

4.1 Device Extraction Algorithm

The first level of input circuit contains the inverter or transmission gate. If the first level of input gate is the transmission gate, the second layer will be followed by capacitance.

To store the level-1 device code:

1. Loop all the input pins and IO pins.
2. If the input is connected to gate, then mark the cell type to inverter cell and store the SPICE code.
3. If the input is connected to source or drain, then mark the cell type to transmission gate and store the SPICE code.

To search for the input for the level-2 device:

1. Loop all the input pins and IO pins.

2. For each level-2 device: If the level-1 cell type is an inverter, connect the output of level-1 devices to the gate of level-2 devices. Pull appropriate High (VCCA, VCKK, VCC33A, VCC18A, etc) or Low (GNDA, GNDK) to the source or drain of level-2 devices. To find the appropriate power level: If designer already specify the power level, such as VCC33A or VCC18A for 3.3V or 1.8 V, respectively, then use the designer's value; otherwise, use the device naming rule (N_33_LL, N_33_G2) to determine the power level. (Figure 6)
3. For level-2 device: If the level-1 cell type is a transmission gate, then the level-2 device should be a capacitor: One of the terminals should be connected to level-1 transmission gate. Ground the other terminal of level-2 device. (Figure 7)

Note that some pins (TA, TB, TC) are reserved by Faraday for resistance testing purpose (to determine the voltage level, for example) in some IPs (such as Band Gap for stable reference voltage). Those pins are not characterized and will be partially or totally burned in the final delivery. The SPICE netlist should be clean up for TA, TB, and TC during the SPICE code cleanup.

4.2 Result Processing

If HSPICE fails to get the result with current timing step, it automatically shrinks the timing step and reruns until the job is concluded. The final result is listed in the *.lis file and the *.mtN file (where N = 0, 1, 2, ...). The *.mtN contains the final input capacitance, in which the N is figured out by parsing and counting from the SPICE result file.

The HSPICE command CONVERGE invokes different methods to solve non-convergence problems:

CONVERGE = -1: Use with DCON = -1, to disable auto-convergence.

CONVERGE = 0: auto-convergence (default).

CONVERGE = 1: Uses the Damped Pseudo Transient algorithm. If simulation does not converge within the amount of CPU time (set in the CPTIME control option), then simulation halts.

CONVERGE = 2: Uses a combination of DCSTEP and GMINDC ramping. Not used in the auto-convergence flow.

CONVERGE = 3: Invokes the source-stepping method. Not used in the auto-convergence flow.

CONVERGE = 4: Uses the GMATH ramping method. Even you did not set it in an .OPTION statement, the CONVERGE option activates if a matrix floating-point overflows, or if HSPICE reports a time step too small error. Default = 0. If a matrix floating-point overflows, CONVERGE = 1.

4.3 Device Extraction Example

The following demonstrates the extracted SPICE code for a Best Corner of an ADC:

* Spice Net List: adc020ha01



```
*****
* Tran Test
*****
.tran 0.001ns 7ns
*****
* Probe
*****
.meas tran vc max v(b_b_b, gnd)
.meas cpin_A_0_0 param='(vc * CFIXED)/(0.4 * VP)'
*****
* Control Accuracy
*****
.option post captab nopage interp
.option CONVERGE=1
.option GMINDC=1.E-12

*****
* Parameters
*****
.param CFIXED = 1.0e-14
.param IPCVP = VP
.param sv = VP
.param ev = 0
.param VP = 1.98
*****
* Mirror Circuit of VCR Switch
*****
vameter x CLK dc 0
* current source between node of Node a_a_a
gi a_a_a gnd cur='i1(vameter)'
ccb b_b_b gnd CFIXED
gra a_a_a gnd vcr pwl(1) CLK gnd
+ 0.00,1.0e-05 'IPCVP*0.3-0.001',1.0e-05
+ 'IPCVP*0.3',1.0e+15 'IPCVP*0.7',1.0e+15
+ 'IPCVP*0.7+0.001',1.0e-05 IPCVP,1.0e-05
grb a_a_a b_b_b vcr pwl(1) CLK gnd
+ 0.00,1.0e+15 'IPCVP*0.3-0.001',1.0e+15
+ 'IPCVP*0.3',1.0e-05 'IPCVP*0.7',1.0e-05
+ 'IPCVP*0.7+0.001',1.0e+15 IPCVP,1.0e+15
*****
* Stimulus
*****
Vx x 0 PWL(0n sv 1n sv 4ns ev)
```



```
.ic v(a_a_a) = 0
.ic v(b_b_b) = 0
```

* Circuit Extraction (Input Setup)

```
MXI0-XI113-XI60-XI194-MP2__1 XI0-XI113-XI60-NET115 CLK VCCK VCCK P_18_G2
L=0.18U W=2U AD=1.14P AS=0.54P PD=3.14U PS=0.54U
MXI0-XI113-XI60-XI194-MP2__2 XI0-XI113-XI60-NET115 CLK VCCK VCCK P_18_G2
L=0.18U W=2U AD=0.54P AS=0.54P PD=0.54U PS=0.54U
MXI0-XI113-XI60-XI194-MP2__3 XI0-XI113-XI60-NET115 CLK VCCK VCCK P_18_G2
L=0.18U W=2U AD=0.54P AS=0.54P PD=0.54U PS=0.54U
MXI0-XI113-XI60-XI194-MP2__4 XI0-XI113-XI60-NET115 CLK VCCK VCCK P_18_G2
L=0.18U W=2U AD=0.54P AS=0.54P PD=0.54U PS=0.54U
MXI0-XI113-XI60-XI194-MN1__1 XI0-XI113-XI60-NET115 CLK XI0-XI113-XI60-XI194-
NET3 GNDK N_18_G2 L=0.18U W=2U AD=0.54P AS=1.14P PD=0.54U PS=3.14U
MXI0-XI113-XI60-XI194-MN1__2 XI0-XI113-XI60-NET115 CLK XI0-XI113-XI60-XI194-
NET3 GNDK N_18_G2 L=0.18U W=2U AD=0.54P AS=0.54P PD=0.54U PS=0.54U
MXI0-XI113-XI60-XI194-MN1__3 XI0-XI113-XI60-NET115 CLK XI0-XI113-XI60-XI194-
NET3 GNDK N_18_G2 L=0.18U W=2U AD=0.54P AS=0.54P PD=0.54U PS=0.54U
MXI0-XI113-XI60-XI194-MN1__4 XI0-XI113-XI60-NET115 CLK XI0-XI113-XI60-XI194-
NET3 GNDK N_18_G2 L=0.18U W=2U AD=0.54P AS=0.54P PD=0.54U PS=0.54U
```

* Output

```
.GLOBAL VCC GND
VDDK VCCK 0 VP
VGNDK GNDK 0 DC 0
```

* Models

```
.prot
.lib '/home/hp26b/newasic/fsa0b_v/model/fsa0b_v.mod' PFNF

.unprot
.temp -40
.end
```

5.0 Conclusions



The following table shows the rule of thumb of run time and accuracy.

| Method | Run time | Accuracy |
|-------------------------------|--------------------|----------------------|
| Interpolation | < seconds | ~85% |
| Circuit Extraction Simulation | Seconds to minutes | 90%-100% |
| IO Instance Based Simulation | Minutes to hours | > 95% |
| Full Chip Simulation | Hours to months | 100% or 0% if failed |

The device extraction and the SPICE simulation have been proven to be successful by all the 1149 IPs implemented as the test cases. Due to run-time consideration, we cannot compare the accuracy among all these IPs. As a rule of thumb, however, the accuracy is around 90%-100% according to some selected IPs and our designers' judgment.

6.0 Acknowledgements

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7.0 References

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