

ML 2019 Hw4 Report

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1. 請使用不同的 autoencoder model，以及不同的降維方式(降到不同維度)，討論其 reconstruction loss & public / private accuracy。

- (1) Autoencoder (CNN : 3 \rightarrow 8 \rightarrow 16 \rightarrow 32, Linear : 512 \rightarrow 256 \rightarrow 128) + tSNE(2維)
reconstruction loss :
public accuracy : 0.82703
private accuracy : 0.82126
- (2) Autoencoder (CNN : 3 \rightarrow 8 \rightarrow 16 \rightarrow 32 \rightarrow 64, Linear : 512 \rightarrow 128) + tSNE(2維)
reconstruction loss : 0.09422
public accuracy : 0.78238
private accuracy : 0.79333
- (3) Autoencoder (CNN : 3 \rightarrow 8 \rightarrow 16 \rightarrow 32, Linear : 512 \rightarrow 256 \rightarrow 128) + PCA(32維)
reconstruction loss : 0.12726
public accuracy : 0.51222
private accuracy : 0.52174
- (4) Autoencoder (CNN : 3 \rightarrow 8 \rightarrow 16 \rightarrow 32 \rightarrow 64, Linear : 512 \rightarrow 128) + PCA(32維)
reconstruction loss : 0.09422
public accuracy : 0.52814
private accuracy : 0.51968

從結果來看，tSNE 表現跟 PCA 差了不少次元，然後 reconstruction loss 越小不一定越好。

2. 從 dataset 選出2張圖，並貼上原圖以及經過 autoencoder 後 reconstruct 的圖片。

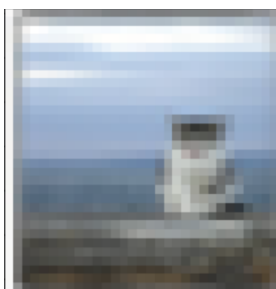
圖片一(原圖)



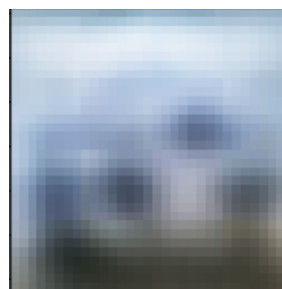
圖片一(reconstruct)



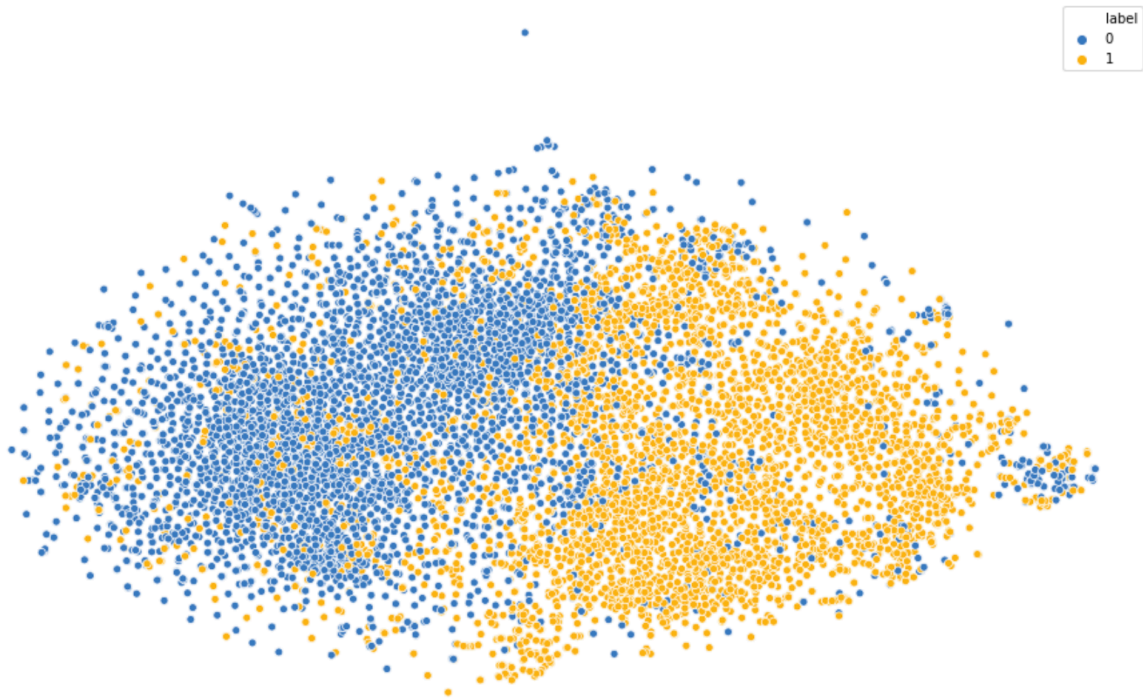
圖片二(原圖)



圖片二(reconstruct)



3. 請在二維平面上視覺化 label 的分佈。



(4. math problem 在下面。)

4. Refer to math problem ◦

$$1. \text{cov}(X) = \frac{1}{10} \sum_{i=1}^{10} (x_i - \mu)(x_i - \mu)^T, \mu = [5.4 \ 8 \ 9.8]$$

$$= \begin{bmatrix} 12.09 & 0.5 & 7.28 \\ 0.5 & 12.2 & 2.9 \\ 7.28 & 2.9 & 8.16 \end{bmatrix}$$

→ eigenvalues and eigenvectors of $\text{cov}(X)$

$$\lambda_3 = 5.47 \quad \lambda_2 = 11.63 \quad \lambda_1 = 15.3$$

$$\mu_3 = \begin{bmatrix} 0.4 \\ 0.34 \\ -0.85 \end{bmatrix} \quad \mu_2 = \begin{bmatrix} -0.68 \\ 0.73 \\ -0.03 \end{bmatrix} \quad \mu_1 = \begin{bmatrix} -0.62 \\ -0.59 \\ -0.52 \end{bmatrix}$$

(a) The principal axes =

$$\mu_1 = \begin{bmatrix} -0.62 \\ -0.59 \\ -0.52 \end{bmatrix} \quad \mu_2 = \begin{bmatrix} -0.68 \\ 0.73 \\ -0.03 \end{bmatrix} \quad \mu_3 = \begin{bmatrix} 0.4 \\ 0.34 \\ -0.85 \end{bmatrix} *$$

(b)

$$W = \begin{bmatrix} -0.62 & -0.59 & -0.52 \\ -0.68 & 0.73 & -0.03 \\ 0.4 & 0.34 & -0.85 \end{bmatrix}, \quad z_i = W \cdot X \text{ (i-th principal component)}$$

$$z_1 = \begin{bmatrix} -3.36 \\ 0.71 \\ 1.48 \end{bmatrix} \quad z_4 = \begin{bmatrix} -7.94 \\ 5.06 \\ 1.16 \end{bmatrix} \quad z_7 = \begin{bmatrix} -14.96 \\ -0.47 \\ 1.37 \end{bmatrix} \quad z_{10} = \begin{bmatrix} -16.3 \\ 1.11 \\ -1.75 \end{bmatrix}$$

$$z_2 = \begin{bmatrix} -9.79 \\ 3.03 \\ -0.04 \end{bmatrix} \quad z_5 = \begin{bmatrix} -12.37 \\ 6.84 \\ -5.02 \end{bmatrix} \quad z_8 = \begin{bmatrix} -7.08 \\ 3.81 \\ -3.05 \end{bmatrix}$$

$$z_3 = \begin{bmatrix} -13.62 \\ 6.53 \\ 2.42 \end{bmatrix} \quad z_6 = \begin{bmatrix} -7.19 \\ -1.84 \\ -3.3 \end{bmatrix} \quad z_9 = \begin{bmatrix} -12.86 \\ -3.95 \\ -0.97 \end{bmatrix} *$$

(c) average reconstruction error

$$= \frac{1}{10} \sum_{i=1}^{10} (x_i - y_i)^2$$

$$= 6.064 *$$

2.

(a) $A \in \mathbb{R}^{m \times n}$

(1) Symmetric:

① for AA^T : $(AA^T)^T = (A^T)^T A^T = AA^T$, by definition of symmetry, AA^T is symmetric.

② for $A^T A$: $(A^T A)^T = A^T (A^T)^T = A^T A$, by definition of symmetry, $A^T A$ is symmetric. *

(2) positive semi-definite:

z 為所有非零實係數向量, $\in \mathbb{R}^m$ or \mathbb{R}^n

① for AA^T : $z^T AA^T z = \underbrace{(A^T z)^T A^T z}_{\text{Square of the inner product of } A^T z, \text{ thus must } \geq 0}} = \|A^T z\|^2 \geq 0$

② for $A^T A$: $z^T A^T A z = \underbrace{(Az)^T Az}_{\text{Square of inner product of } Az, \text{ thus must } \geq 0}} = \|Az\|^2 \geq 0$

$\Rightarrow AA^T$ and $A^T A$ are both positive semi-definite matrix. *

(3) share some non-zero eigenvalue:

① for AA^T : $AA^T x = \lambda x$, if $\lambda \neq 0$, $A^T A(A^T x) = \lambda(A^T x)$, $\lambda = A^T A = \|A\|^2$

② for $A^T A$: $A^T A x = \lambda x$, if $\lambda \neq 0$, $AA^T(Ax) = \lambda(Ax)$, $\lambda = AA^T = \|A\|^2$

$\Rightarrow AA^T$ and $A^T A$ share the same non-zero eigenvalue. *

(b)

Let $x = (x_1, x_2, \dots, x_n) \in \mathbb{R}^m$

By definition, covariance matrix of $x = E[(x - \mu)(x - \mu)^T]$, 其中 $\mu = E[x] = \frac{1}{n} \sum_{i=1}^n x_i$

$\Rightarrow \text{Cov}(x) = E[(x - \mu)(x - \mu)^T] = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)(x_i - \mu)^T$

\Rightarrow let $M = (x - \mu)(x - \mu)^T$ and M is thus a symmetric positive semi-definite matrix.

for all 非零實係數向量 v , $v^T M v \geq 0$.

$\Rightarrow v^T M v \geq 0$

$\Rightarrow E[v^T M v] \geq 0$

$\Rightarrow v^T E[M] v \geq 0$, 其中 $E[M] = E[(x - \mu)(x - \mu)^T] = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)(x_i - \mu)^T = \Sigma$

$\Rightarrow v^T \Sigma v \geq 0$

\Rightarrow 由此可知, Σ is a symmetric positive semi-definite matrix 得證. *

(c)

Let $x = (x_1, x_2, \dots, x_n)$

Set, $\Sigma = \frac{1}{N} x x^T = U \Lambda U^T$, then

$\text{Trace}(\Phi^T \Sigma \Phi) = \frac{1}{N} \text{Trace}(\Phi^T x x^T \Phi)$

$= \frac{1}{N} \|\Phi^T x\|_F^2$

$= \frac{1}{N} \sum_{i=1}^n \|\Phi^T x_i\|^2$

$= \frac{1}{N} \sum_{i=1}^n \|\hat{x}_i^{(S)}\|^2$

$\Rightarrow 0 \leq \frac{1}{N} \sum_{i=1}^n \|\hat{x}_i^{(S)}\|^2 \leq \frac{1}{N} \sum_{i=1}^n \|\hat{x}_i^{(RA)}\|^2$

3. objective = find $g_{T+1}^k(x)$, $\forall k \in 1 \sim K$.

Minimize $\text{loss}(g_1^1, g_1^2, \dots, g_1^K)$

$$\begin{cases} g_{T+1}^k(x) = g_T^k(x) - \eta \frac{\partial L(g)}{\partial g_T^k(x)} & \downarrow \\ & \text{same direction} \\ g_{T+1}^k(x) = g_T^k(x) + \alpha_{T+1}^k f_{T+1}^k(x) & \uparrow \end{cases}$$

其中 $\frac{\partial L(g)}{\partial g_T^k(x)} = \sum_{i=1}^n \exp\left(\frac{1}{K-1} \sum_{k \neq y_i} g_T^k(x_i) - \hat{y}_i^T(x_i) \cdot D\right)$, $D = \begin{cases} \frac{1}{K-1} & \text{if } k \neq y_i \\ -1 & \text{else} \end{cases}$

\Rightarrow then find $f_{T+1}(x)$ maximizing $\sum_{i=1}^n \exp\left(\frac{1}{K-1} \sum_{k \neq y_i} g_T^k(x_i) - \hat{y}_i^T(x_i) \cdot D\right) \cdot f_{T+1}(x)$

and find α_{T+1}^k minimizing $L(g)$ so that $\frac{\partial L}{\partial \alpha_T^k} = 0$.

其中 $\frac{\partial L}{\partial \alpha_T^k} = \sum_{i=1}^n \exp\left(\frac{1}{K-1} \sum_{k \neq y_i} \sum_{t=1}^T \alpha_t^k f_t(x_i) - \sum_{t=1}^T \hat{y}_i^T(x_i) \cdot \varepsilon\right) \cdot \varepsilon$, $\varepsilon = \begin{cases} \frac{f_t(x_i)}{K-1} & \text{if } k \neq y_i \\ f_t(x_i) & \text{else} \end{cases}$