Semidefinite programming

The what, why and how.

PETER BROWN -- TÉLÉCOM PARIS / INRIA
QSI SCHOOL ON QUANTUM CRYPTOGRAPHY - 31.01.24

$$\max \operatorname{Tr}[CX]$$

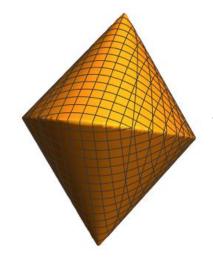
s.t.
$$\operatorname{Tr}[F_i X] \leq \omega_i \quad \forall i$$

$$X \succeq 0$$

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$$\sum_{i} \lambda_{i} \omega_{i}$$
s.t.
$$\sum_{i} \lambda_{i} F_{i} - C \succeq 0$$

$$\lambda_{i} \geq 0 \quad \forall i$$

The what



This is an SDP

$$\max x$$
s.t. $x + y \le 2$

$$\begin{pmatrix} 1 & x \\ x & y \end{pmatrix} \succeq 0$$

$$\begin{pmatrix} 2 & x + y \\ x + y & 2x \end{pmatrix} \succeq 0$$

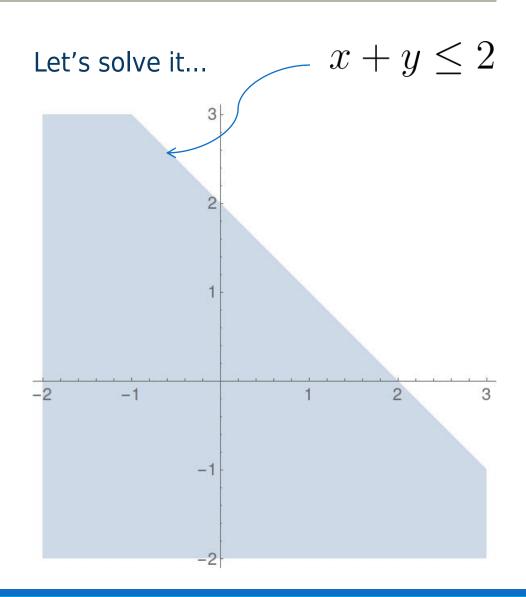
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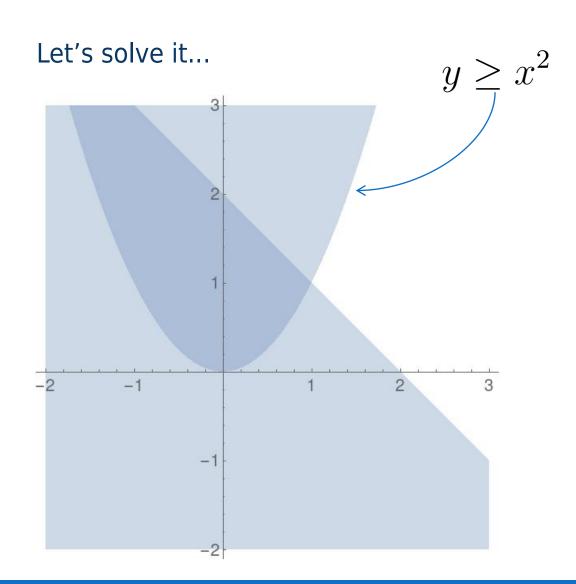
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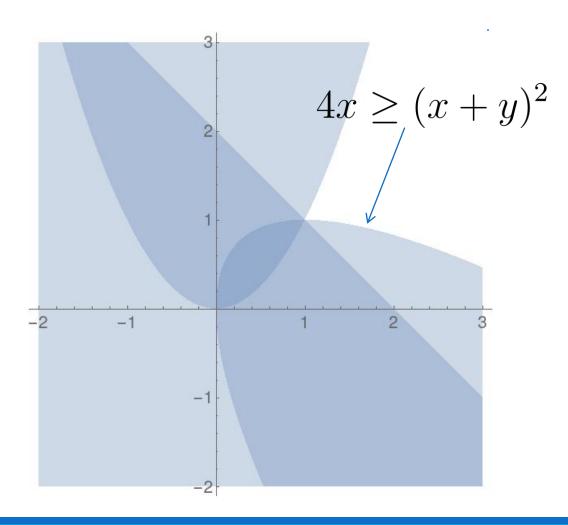
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Let's solve it...



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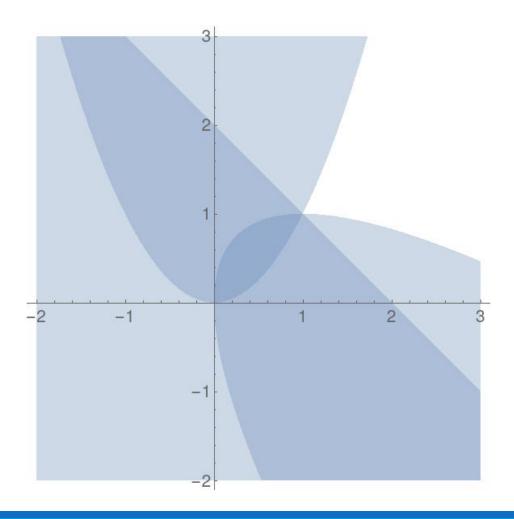
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Biggest x satisfying all constraints?



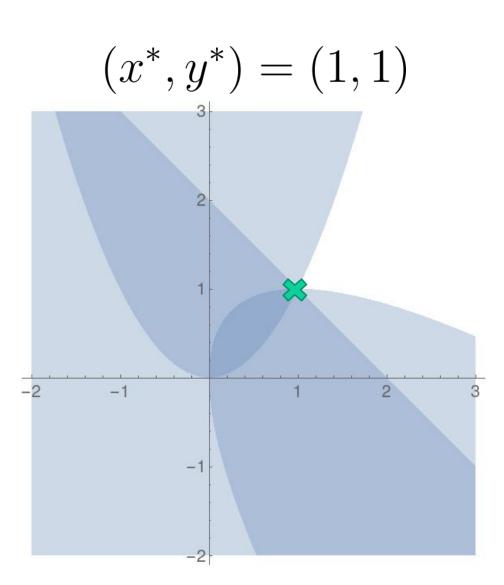
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So what's an SDP?

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SDPs are optimization problems satisfying

- Linear objective function
- Linear (in)equalities
- Semidefinite constraints (variables appear linearly)

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s.t.
$$\alpha$$

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- Linear objective function
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Importantly

- Efficient to solve!
- Guaranteed global optima!

Definition (SDP)

An SDP is an optimization of the following form

$$\max \quad \operatorname{Tr}[CX]$$
s.t.
$$\operatorname{Tr}[F_iX] \leq \omega_i \quad \forall i$$

$$X \succeq 0$$

where the <u>Hermitian</u> matrices C, F_i and $\omega_i \in \mathbb{R}$ are fixed.

Note:

$$\operatorname{Tr}[AX] = \sum_{ij} a_{ij} x_{ji}$$
 Just linear combination of elements of X

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- Standard forms not unique across literature, e.g.

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where Φ is a Hermitian preserving linear map. [Watrous, The Theory of Quantum Information (2018)]

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Exercise: Convert between the two standard forms.

SDPs fall into one of the following categories:

Optimal value exists and attained

$$\max x$$

s.t.
$$x \leq 2$$

SDPs fall into one of the following categories:

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Optimal value exists but not attained

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s.t.
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 $x \ge 0$

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Lower bounds on

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are "easy" to find. (why?)

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$$0 \le \text{Tr}[(\sum_{i} \lambda_{i} F_{i} - C)X] \tag{PSD}$$

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If we define the *primal* SDP as

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Then the dual SDP is

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- Equality (strong duality) almost always... but not always.
- Duals can give new insights / simpler forms / new interpretations!

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Theorem (Slater):

When does the primal value equal the dual value?

- 1. If the primal is *strictly feasible* then the primal value equals dual value and dual is attained.
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Example

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A bit of magic...

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Strictly feasible (x,y) = (1/2,1/2)

Optimal value: 1

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Solution:
$$a=-b=c=1/3$$
 Optimal value: 1 $d=e=f=0$

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Guarantees optimal solution found!

$$d = e = f = 0$$

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- Two perspectives on the problem (primal & dual)

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- Two perspectives on the problem (primal & dual)
- Weak duality always holds.

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- Guaranteed to find optimal value (approximately)
- Two perspectives on the problem (primal & dual)
- Weak duality always holds.
- Strong duality almost always holds (easy sufficient condition to check).

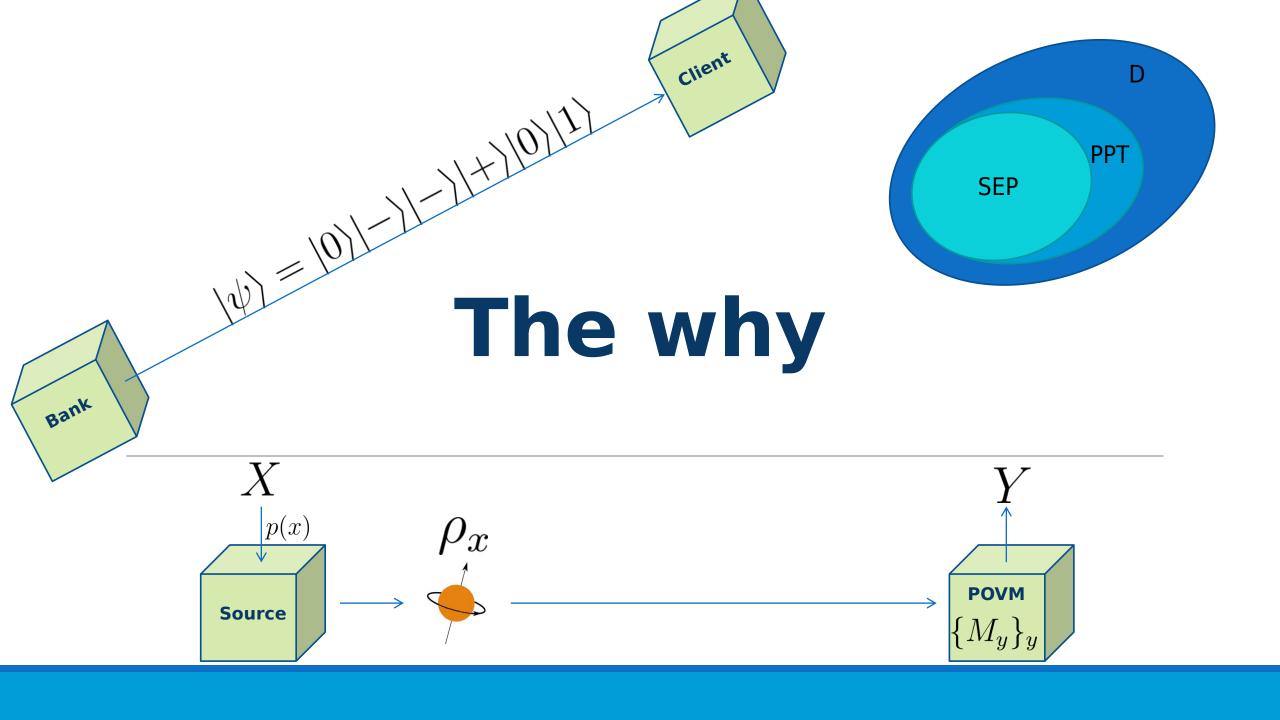
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Ouantum channels

$$\{C_{AB} \mid C_{AB} \succeq 0, \operatorname{Tr}_B[C_{AB}] = \mathbb{I}_A\}$$

$$\Phi: L(A) \to L(B)$$
 $C_{AB} := \sum_{ij} |i\rangle\langle j| \otimes \Phi(|i\rangle\langle j|)$

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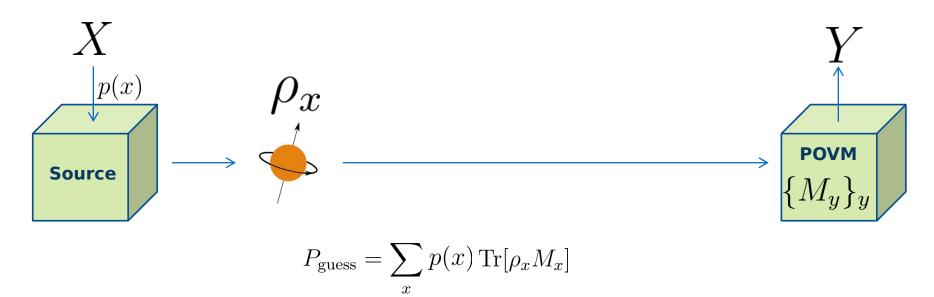
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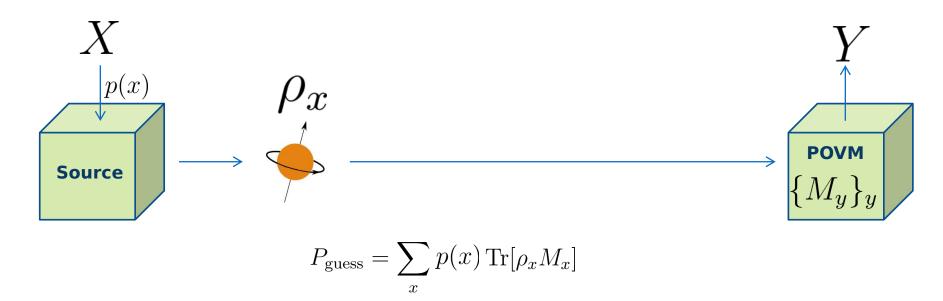
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SDPs are lurking everywhere...

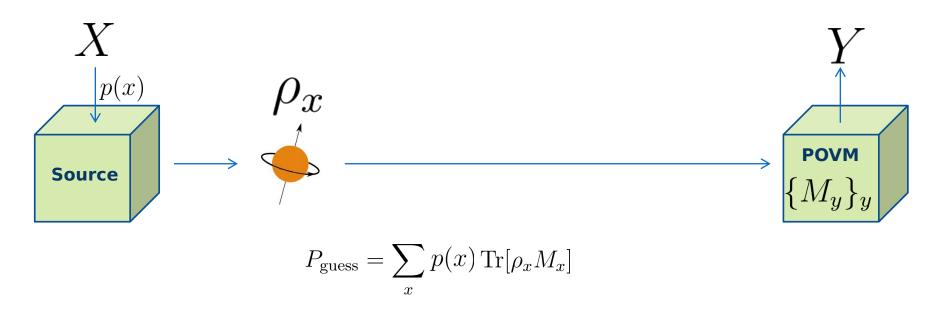
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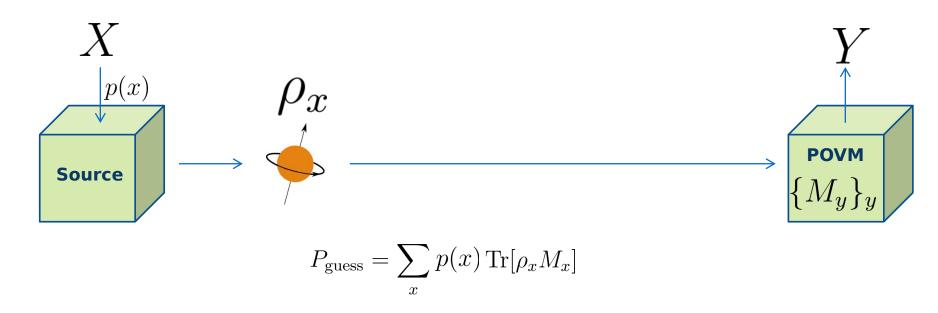
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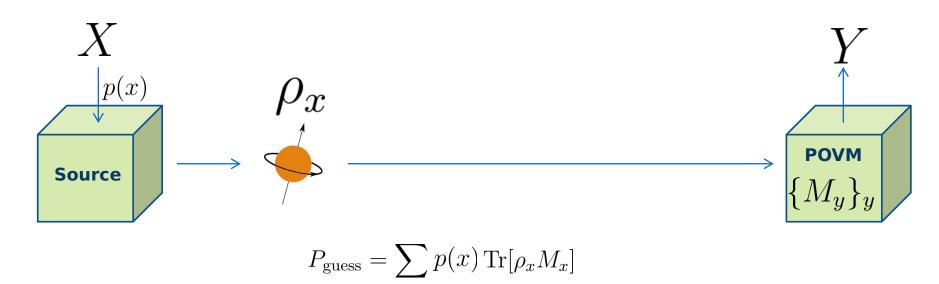
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Just computational basis, perfect discrimination!



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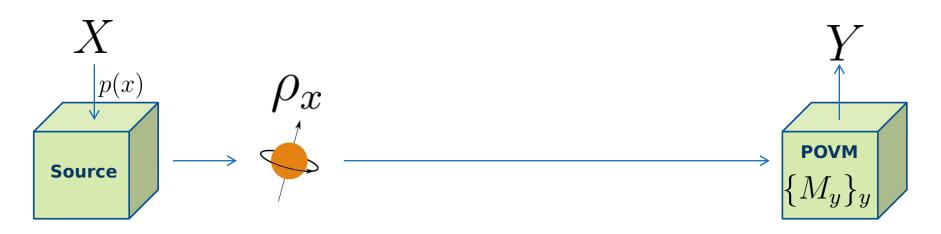
Just computational basis, perfect discrimination!

General case (It's just an SDP :))

$$\max \sum_{x} p(x) \operatorname{Tr}[\rho_x M_x]$$

$$\sum_{x} M_x = \mathbb{I}$$

$$M_x \succeq 0 \quad \forall x$$



More complex example

I send $|0\rangle$ with prob 1/2, $|+\rangle$ with prob 1/4 and $|-\rangle$ with prob 1/4.

Still simple but already tough to solve by hand.



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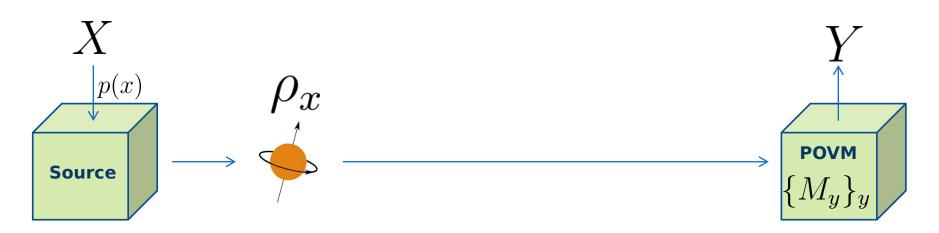
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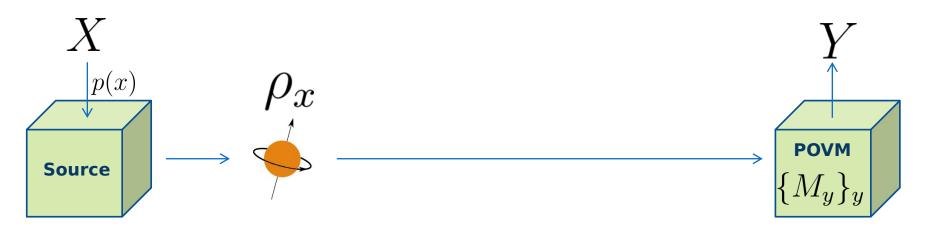
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Immediate solution from SDP: optimal probability 2/3

$$M_0 = \begin{pmatrix} 8/9 & 0 \\ 0 & 0 \end{pmatrix} \qquad M_1 = \begin{pmatrix} 1/18 & 1/6 \\ 1/6 & 1/2 \end{pmatrix} \qquad M_2 = \begin{pmatrix} 1/18 & -1/6 \\ -1/6 & 1/2 \end{pmatrix} \qquad \text{A recipe for how to perform the experiment!}$$

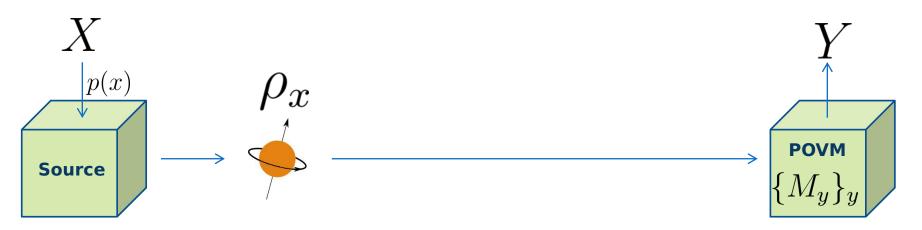
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Discrimination - many variants



• Fundamental information processing task -- channel coding

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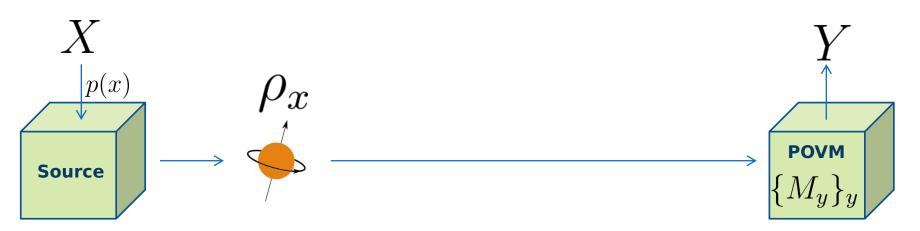


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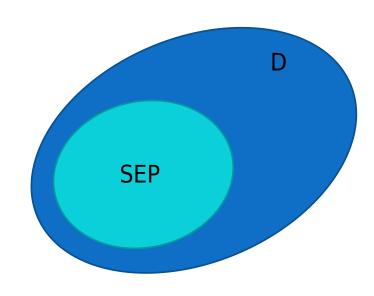
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- Interesting variants
 - 1. Never wrong but allowed to say "I don't know" (Unambiguous)
 - 2. Discriminate between measurements
 - 3. Antidiscrimination -- "How badly can I discriminate?"

A bipartite state ho_{AB} is *separable* if there exist states au_i on A, σ_i on B, and a distribution p_i such that

$$\rho_{AB} = \sum_{i} p_i \tau_i \otimes \sigma_i$$

otherwise we say ρ_{AB} is entangled.

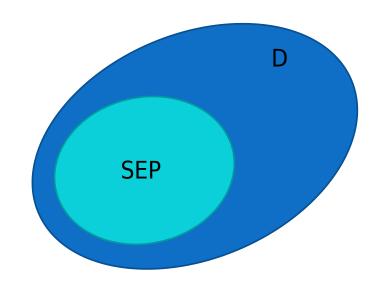


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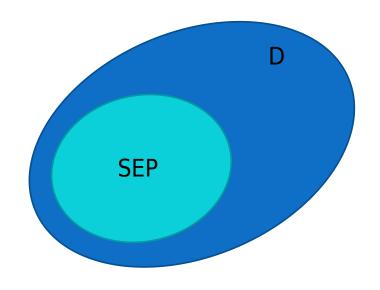
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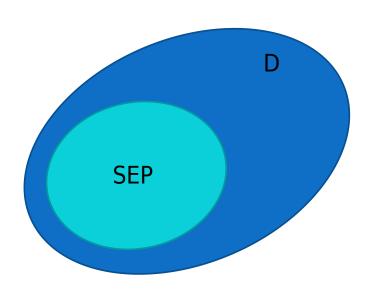
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Separable states remain PSD under partial transpose





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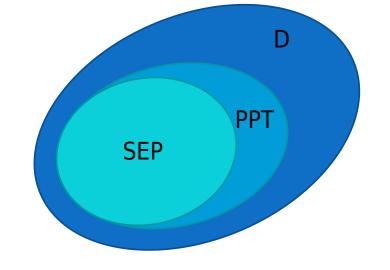
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$$\rho_{AB}^{T_B} = \sum_{i} p_i \tau_i \otimes \sigma_i^T \succeq 0$$

Consider the set of all states that remain positive after partial transpose

$$PPT := \{ \rho_{AB} \mid Tr[\rho] = 1, \, \rho \succeq 0, \, \rho^{T_B} \succeq 0 \}$$

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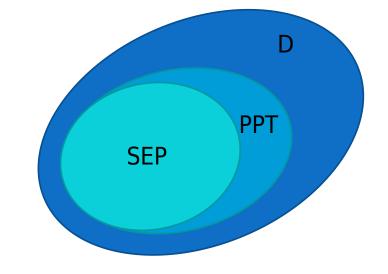
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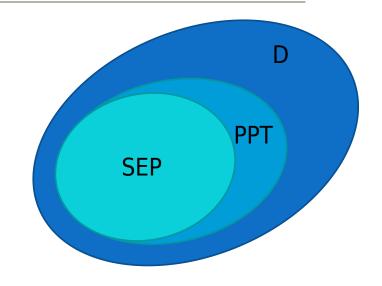
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Can check with SDP! Easy:)

For fixed ρ_{AB} consider the SDP

$$\max \lambda$$

s.t.
$$\rho_{AB}^{T_B} - \lambda \mathbb{I} \succeq 0$$

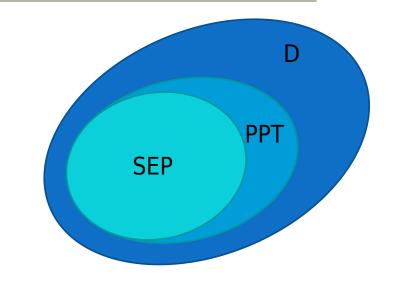


For fixed ρ_{AB} consider the SDP

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Computes smallest eigenvalue of $ho_{AB}^{T_B}$ **Exercise:** prove this

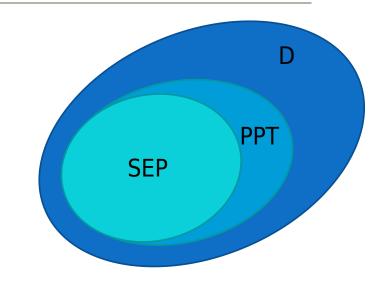


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We can use this SDP to quantify entanglement

$$\lambda^* < 0$$

$$\iff$$

$$\rho_{AB}^{T_B} \not\succeq 0$$

$$\Longrightarrow$$

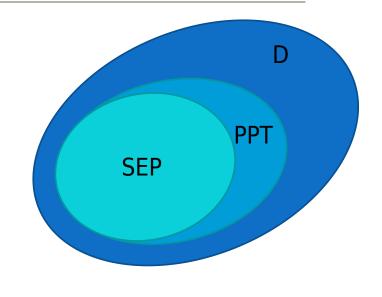
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Dual SDP is
$$\min \quad \mathrm{Tr}[W\rho_{AB}]$$

$$\mathrm{s.t.} \quad \mathrm{Tr}[W] = 1$$

$$W^{T_B} \succeq 0$$

Strong duality holds (why?)

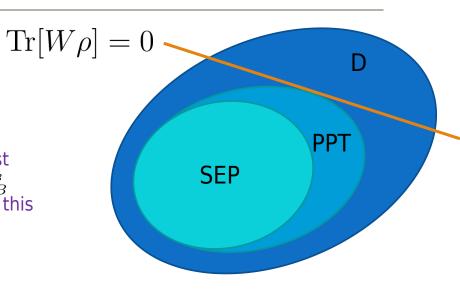
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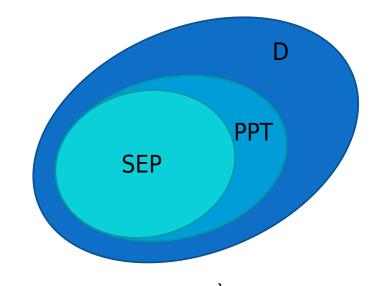
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Dual gives experimental procedure!

- For any feasible W, by weak duality of SDPs ${\rm Tr}[W\sigma_{AB}]<0 \implies \sigma_{AB} \ {\rm is \ entangled}$
- And W is an observable, can measure in the lab!

Example

Consider
$$|\psi_{\theta}\rangle = \cos(\theta)|00\rangle + \sin(\theta)|11\rangle$$
 for $\theta \in (0, \pi/4]$



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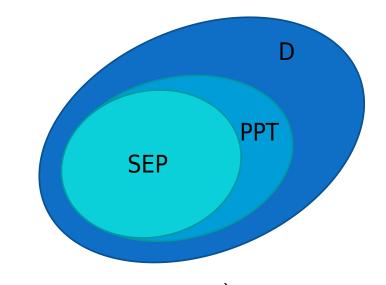
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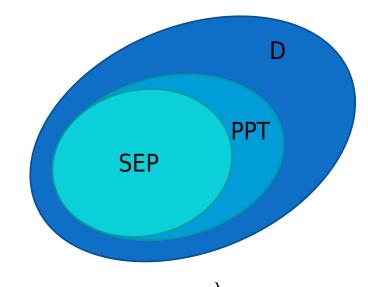
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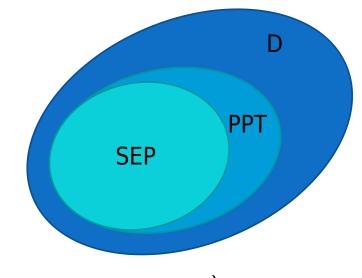
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$$W^* = \begin{pmatrix} 0 & 0 & 0 & -1/2 \\ 0 & 1/2 & 0 & 0 \\ 0 & 0 & 1/2 & 0 \\ -1/2 & 0 & 0 & 0 \end{pmatrix} \quad \begin{array}{l} \text{Can verify entanglement} \\ \text{in the lab with this!} \\ \text{on the lab with this with this with this with this with this with the lab with this with this with the lab with the$$

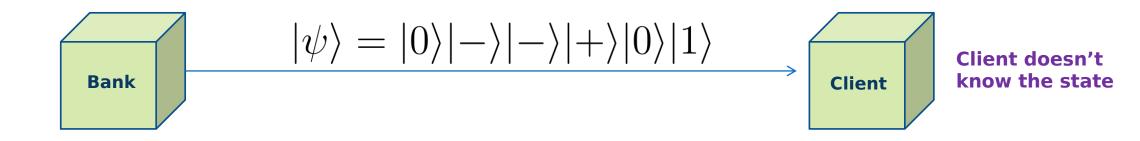
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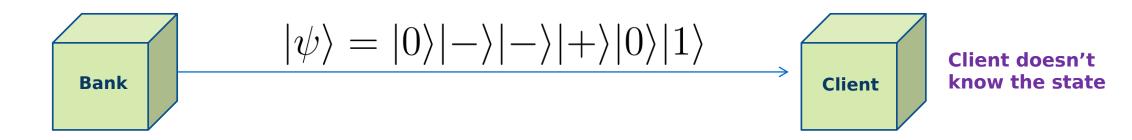
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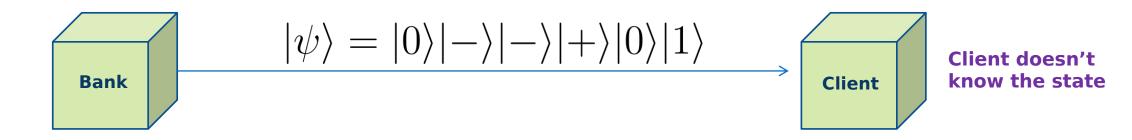
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 Client doesn't know the state

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Security intuition: If user tries to learn $|\psi\rangle$ they disturb it which is detected by bank's check.

(No-cloning / measurement disturbance -- same as BB84)

Quantum money II - no-cloning

Intuition: quantum money is secure because of no-cloning

Theorem (No cloning)

 $\not\exists$ a quantum channel \mathcal{E} such that for all states $|\psi\rangle$

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Conjecture (Some cloning?)

 \exists a quantum channel \mathcal{E} such that for all states $|\psi\rangle$

$$\mathcal{E}(|\psi\rangle\langle\psi|) \approx |\psi\rangle\langle\psi| \otimes |\psi\rangle\langle\psi|$$

The some cloning conjecture could make the security of quantum money very impractical.

Quantum money III - quick aside on channels

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$$C_{AB}^{\mathcal{E}} := \sum_{ij} |i\rangle\langle j| \otimes \mathcal{E}(|i\rangle\langle j|)$$

satisfies $C_{AB}^{\mathcal{E}} \succeq 0$ and $\mathrm{Tr}_B[C_{AB}^{\mathcal{E}}] = \mathbb{I}_A$

TL;DR - Channels are PSD matrices in disguise!

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TL;DR - Channels are PSD matrices in disguise!

We can also recover channel action from Choi matrix

$$\mathcal{E}(
ho) = \mathrm{Tr}_A\left[(
ho^T\otimes \mathbb{I}_B)C_{AB}
ight]$$
 Importantly, linear in Choi matrix!

Quantum money IV - cloning task

Cloning game

I send you one of the states $\{|\psi_x\rangle\}_x$ with probability p(x). You must design a channel that clones the states with largest average fidelity

$$\sum p(x)\langle \psi_x|^{\otimes 2}\mathcal{E}(|\psi_x\rangle\langle \psi_x|)|\psi_x\rangle^{\otimes 2}$$

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$$\mathcal{E}(\rho) = V \rho V^\dagger \quad \text{where } V = \begin{pmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 1 \end{pmatrix} \quad \begin{array}{l} \text{Exercise: Use Choi lemma to show it is quantum channel} \\ \end{array}$$

Then
$$\mathcal{E}(|0\rangle\langle 0|) = |0\rangle\langle 0| \otimes |0\rangle\langle 0|$$
 and $\mathcal{E}(|1\rangle\langle 1|) = |1\rangle\langle 1| \otimes |1\rangle\langle 1|$

Perfect cloning! (but not surprising - perfectly distinguishable)

The optimal cloner can be found using the SDP

$$\max \sum_{x} p(x) \left(\langle \overline{\psi_x} | \otimes \langle \psi_x | \otimes \langle \psi_x | \right) C_{A_1 A_2 A_3} \left(| \overline{\psi_x} \rangle \otimes | \psi_x \rangle \otimes | \psi_x \rangle \right)$$

s.t.
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SDP returns optimal fidelity **AND** the best channel!

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achieves average fidelity 3/4.

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Can use SDP to prove n-copy cloning scales as (3/4)ⁿ

Exercise: Find 4 qubit states that are harder to clone than the Wiesner conjugate coding states.



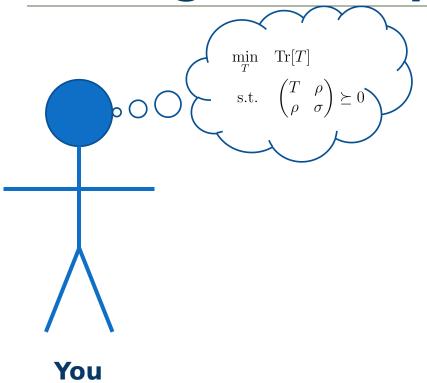




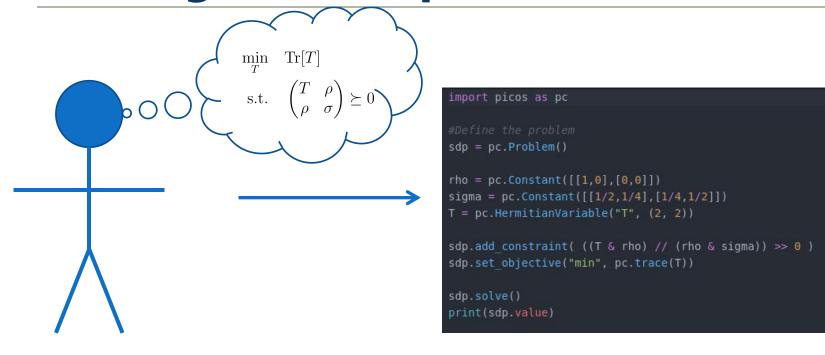
The how



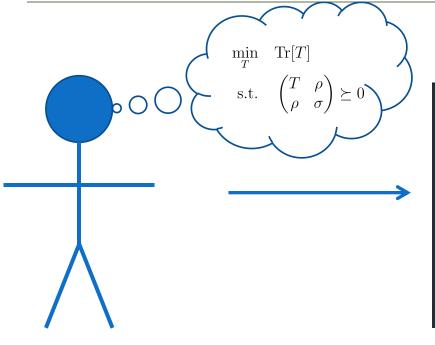




You



High-level modeller



You

```
import picos as pc

#Define the problem
sdp = pc.Problem()

rho = pc.Constant([[1,0],[0,0]])
sigma = pc.Constant([[1/2,1/4],[1/4,1/2]])
T = pc.HermitianVariable("T", (2, 2))

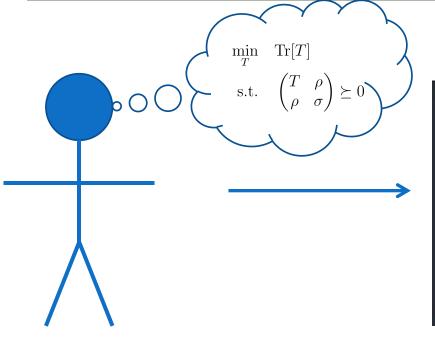
sdp.add_constraint( ((T & rho) // (rho & sigma)) >> 0 )
sdp.set_objective("min", pc.trace(T))

sdp.solve()
print(sdp.value)
```



High-level modeller

Solver



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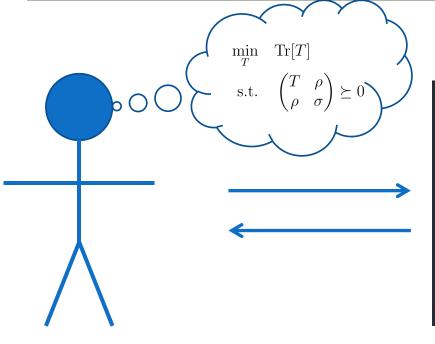
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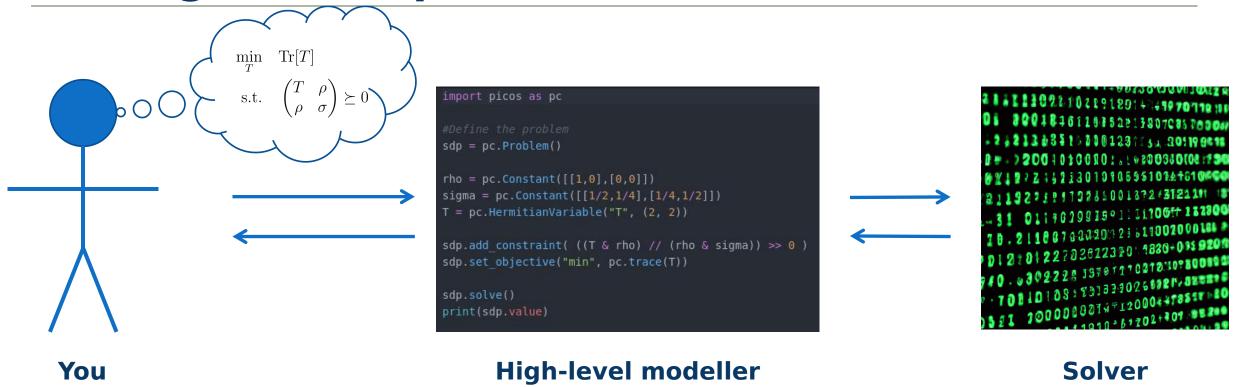
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High-level modeller

Solver



It's easy to SDP in practice:)

High-level modelling

High level modelling allows us to code SDPs like we're writing the mathematics.

High-level modelling

High level modelling allows us to code SDPs like we're writing the mathematics.

A very non-exhaustive list...

Programming language	Available modellers
python	PICOS / CVXPY / PyLMI-SDP
matlab	YALMIP / CVX
julia	Convex.jl
mathematica	built-in

High-level modelling

Example in PICOS (python)

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import picos as pc
sdp = pc.Problem()
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M0 = pc.HermitianVariable("M0", (2, 2))
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sdp.add constraint( MO + M1 + M2 == [[1,0],[0,1]] )
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obj = pc.trace(0.5 * M0 * rho0 + 0.25 * M1 * rho1 + 0.25 * M2 * rho2)
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Defining variables

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POVM constraints

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Objective function

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Solve it please!

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```

To solve other discrimination problems need to modify only a few lines!

Defining constants

Defining variables

POVM constraints

Objective function

Solve it please!

Solvers

Modelling languages interact with various solvers

Available solvers	Completely unbiased opinion
Mosek	Best overall solver
SCS	Fast and inaccurate "My problem is too big for the other solvers"
SDPA (family)	"I really need a lot of precision"
CVXOPT / SeDuMi / SDPT3 / Hypatia /	

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CVXOPT / SeDuMi / SDPT3 / Hypatia /	

And they're easy to use...

```
22 import mosek
23 sdp.solve(solver='mosek')
```

Surprisingly powerful for applications in mathematical proofs!

Surprisingly powerful for applications in mathematical proofs!

SDP relaxations
 My problem is not an SDP but can be bounded by one

NPA hierarchy

See arXiv:2307.02551 for a review focused on quantum applications

Lasserre hierarchy

DPS hierarchy

Surprisingly powerful for applications in mathematical proofs!

SDP relaxations

NPA hierarchy

Lasserre hierarchy

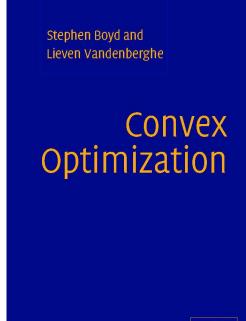
DPS hierarchy

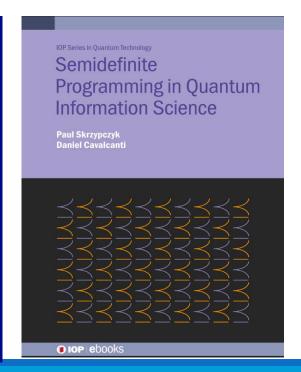
Resources

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Surprisingly powerful for applications in mathematical proofs!

SDP relaxations

NPA hierarchy

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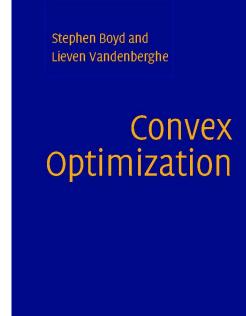
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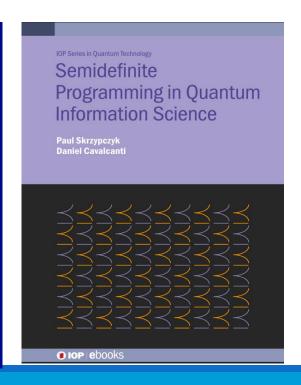
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Bonus slides

Duality gap example

$$\begin{array}{ll}
\max & -a - d \\
s.t. & a = 0 \\
d + 2c = 1 \\
\begin{pmatrix} a & b & c \\ b & d & e \\ c & e & f \end{pmatrix} \succeq 0
\end{array}$$

min
$$\lambda_2$$
s.t.
$$\begin{pmatrix} \lambda_1 + 1 & 0 & \lambda_2 \\ 0 & \lambda_2 + 1 & 0 \\ \lambda_2 & 0 & 0 \end{pmatrix} \succeq 0$$

Optimal value: -1

Optimal value: 0

SDP standard forms - Rewriting tricks

Some tricks

min/max

$$\min f(x) = -\max -f(x)$$

Equalities -> Inequalities

$$x = y \iff x \le y \text{ and } -x \le -y$$

Inequalities -> Equalities + slack

$$x \le y \iff x = y + s \text{ and } s \ge 0$$

Hermitian matrices

$$X$$
 is Hermitian

$$\iff$$

$$X$$
 is Hermitian \iff $X = X_1 - X_2$ and $X_1, X_2 \succeq 0$

Multiple PSD constraints

$$X \succeq 0 \text{ and } Y \succeq 0 \iff \begin{pmatrix} X & 0 \\ 0 & Y \end{pmatrix} \succeq 0$$

Step 1: Form the Lagrangian (Big function of all the variables + some new ones...)

$$\max f(x)$$
s.t. ...

Step 1: Form the *Lagrangian*

Step 1.1: Add the objective

$$\max f(x) \qquad \mathcal{L} = f(x)$$
s.t. ...

Just start Lagrangian with objective

Step 1: Form the Lagrangian

Step 1.2: Add real inequalities

$$\max f(x) \qquad \mathcal{L} = f(x) + \dots \\ \text{s.t.} \qquad \cdots \qquad + \lambda_i (w_i - g_i(x)) \\ g_i(x) \le w_i$$

For each real inequality:

1. Rewrite as positive inequality
$$w_i - g_i(x) \ge 0$$

2. Introduce dual variable
$$\lambda_i > 0$$

3. Add product to Lagrangian
$$\lambda_i(w_i-g_i(x))$$

Step 1: Form the Lagrangian

Step 1.3: Add real equalities

max
$$f(x)$$
 $\mathcal{L} = f(x) + \dots$
s.t. \cdots $+ \mu_i(v_i - h_i(x))$
 $h_i(x) = v_i$

For each real inequality:

$$v_i - h_i(x) = 0$$

$$\mu_i \in \mathbb{R}$$

$$\mu_i(v_i - h_i(x))$$

Step 1: Form the Lagrangian

Step 1.4: Add PSD inequalities

$$\max f(x) \longrightarrow \mathcal{L} = f(x) + \dots + \operatorname{Tr}[A_i(W_i - G_i(x))]$$
s.t.
$$G_i(x) \preceq W_i$$

For each PSD inequality:

1. Rewrite as positive inequality
$$W_i - G_i(x) \succeq 0$$

2. Introduce dual variable
$$A_i \succeq 0$$

3. Add "product" to Lagrangian
$$\operatorname{Tr}[A_i(W_i-G_i(x))]$$

Step 1: Form the Lagrangian

Step 1.4: Add matrix equalities

max
$$f(x)$$
 $\mathcal{L} = f(x) + \dots$
s.t. \cdots $+ \text{Tr}[B_i(V_i - H_i(x))]$
 $H_i(x) = V_i$

For each PSD inequality:

1. Rewrite as 0 equality
$$V_i - H_i(x) = 0$$

- 2. Introduce dual variable B_i (Hermitian)
- 3. Add "product" to Lagrangian $\operatorname{Tr}[B_i(V_i-H_i(x))]$

Step 1: Form the Lagrangian

$$\mathcal{L} = f(x)$$

$$+ \sum_{i} \lambda_{i}(w_{i} - g_{i}(x))$$

$$+ \sum_{i} \mu_{i}(v_{i} - h_{i}(x))$$

$$+ \sum_{i} \text{Tr}[A_{i}(W_{i} - G_{i}(x))]$$

$$+ \sum_{i} \text{Tr}[B_{i}(V_{i} - H_{i}(x))]$$

Dual variables:
$$\lambda_i \geq 0$$
 $\mu_i \in \mathbb{R}$ $A_i \succeq 0$ B_i (Hermitian)

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We can recover primal constraints by asking:

Step 1: Form the Lagrangian

$$\mathcal{L} = f(x) \qquad \qquad \text{When is Lagrangian bounded if we min} \\ + \sum_i \lambda_i (w_i - g_i(x)) \xrightarrow{\min} \qquad \text{Not } -\infty \quad \text{iff} \quad w_i - g_i(x) \geq 0 \\ + \sum_i \mu_i (v_i - h_i(x)) \\ + \sum_i \operatorname{Tr}[A_i(W_i - G_i(x))] \\ + \sum_i \operatorname{Tr}[B_i(V_i - H_i(x))]$$

Dual variables: $\lambda_i \geq 0$ $\mu_i \in \mathbb{R}$ $A_i \succeq 0$ B_i (Hermitian)

We can recover primal constraints by asking:

Not
$$-\infty$$
 iff $w_i - g_i(x) \ge 0$

Step 1: Form the Lagrangian

Dual variables:
$$\lambda_i \geq 0$$
 $\mu_i \in \mathbb{R}$ $A_i \succeq 0$ B_i (Hermitian)

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$$\mathcal{L} = f(x) \qquad \qquad \text{When is Lagrangian bounded if we mini} \\ + \sum_i \lambda_i (w_i - g_i(x)) \xrightarrow{\min_{\lambda_i \geq 0}} \quad \text{Not } -\infty \quad \text{iff} \quad w_i - g_i(x) \geq 0 \\ + \sum_i \mu_i (v_i - h_i(x)) \xrightarrow{\mu_i \in \mathbb{R}} \quad \text{Not } -\infty \quad \text{iff} \quad v_i - h_i(x) = 0$$

$$+\sum_{i} \operatorname{Tr}[A_{i}(W_{i}-G_{i}(x))]$$

$$+\sum_{i} \operatorname{Tr}[B_{i}(V_{i}-H_{i}(x))]$$

Step 1: Form the Lagrangian

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Step 1: Form the Lagrangian

Dual variables: $\lambda_i \geq 0$ $\mu_i \in \mathbb{R}$ $A_i \succeq 0$ B_i (Hermitian)

We can recover primal constraints by asking:

 $\mathcal{L} = f(x)$ When is Lagrangian **bounded** if we **minimize** over **dual** variables?

$$+\sum_{i} \lambda_{i}(w_{i} - g_{i}(x)) \xrightarrow{\min_{\lambda_{i} \geq 0}} \text{Not } -\infty \text{ iff } w_{i} - g_{i}(x) \geq 0$$

$$+\sum_{i} \mu_{i}(v_{i}-h_{i}(x)) \xrightarrow{\min_{\mu_{i} \in \mathbb{R}}} \operatorname{Not} -\infty \text{ iff } v_{i}-h_{i}(x) = 0$$

$$+\sum_{i} \operatorname{Tr}[A_i(W_i - G_i(x))] \xrightarrow{\min}_{A_i \succeq 0} \operatorname{Not} -\infty \text{ iff } W_i - G_i(x) \succeq 0$$

$$+\sum_{i} \operatorname{Tr}[B_i(V_i - H_i(x))] \xrightarrow{\min} \operatorname{Not} -\infty \text{ iff } V_i - H_i(x) = 0$$

Step 1: Form the Lagrangian

Dual variables: $\lambda_i > 0$ $\mu_i \in \mathbb{R}$ $A_i \succeq 0$ B_i (Hermitian)

We can recover primal constraints by asking:

When is Lagrangian **bounded** if we **minimize** over **dual** variables?

$$\mathcal{L} = f(x) \qquad \qquad \text{When is Lagrangian bounded if we minimiz} \\ + \sum_i \lambda_i (w_i - g_i(x)) \xrightarrow{\min_{\lambda_i \geq 0}} \quad \text{Not } -\infty \quad \text{iff} \quad w_i - g_i(x) \geq 0 \\ + \sum_i \mu_i (v_i - h_i(x)) \xrightarrow{\mu_i \in \mathbb{R}} \quad \text{Not } -\infty \quad \text{iff} \quad v_i - h_i(x) = 0$$

Lagrangian contains all information about primal SDP

$$+\sum_{i} \operatorname{Tr}[A_{i}(W_{i}-G_{i}(x))] \xrightarrow{\min}_{A_{i} \succeq 0} \operatorname{Not} -\infty \text{ iff } W_{i}-G_{i}(x) \succeq 0$$

$$+\sum_{i} \operatorname{Tr}[B_i(V_i - H_i(x))] \xrightarrow{\min} \operatorname{Not} -\infty \text{ iff } V_i - H_i(x) = 0$$

Step 2: Rearrange the Lagrangian

$$\mathcal{L} = \sum_i \lambda_i w_i + \sum_j \mu_j v_j + \sum_k \mathrm{Tr}[A_k W_k] + \sum_l \mathrm{Tr}[B_l V_l] \tag{Terms without primal variables}$$

$$- \left(\sum_j \lambda_i g_i(x) + \sum_j \mu_j h_j(x) + \sum_k \mathrm{Tr}[A_k G_k(x)] + \sum_l \mathrm{Tr}[B_l H_l(x)] \right) \tag{Terms with primal variables}$$

Step 3: Form the dual

$$\mathcal{L} = \sum_{i} \lambda_{i} w_{i} + \sum_{j} \mu_{j} v_{j} + \sum_{k} \text{Tr}[A_{k} W_{k}] + \sum_{l} \text{Tr}[B_{l} V_{l}]$$
$$- \left(\sum_{i} \lambda_{i} g_{i}(x) + \sum_{j} \mu_{j} h_{j}(x) + \sum_{k} \text{Tr}[A_{k} G_{k}(x)] + \sum_{l} \text{Tr}[B_{l} H_{l}(x)] \right)$$

Step 3: Form the dual

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$$- \left(\sum_{i} \lambda_{i} g_{i}(x) + \sum_{j} \mu_{j} h_{j}(x) + \sum_{k} \text{Tr}[A_{k} G_{k}(x)] + \sum_{l} \text{Tr}[B_{l} H_{l}(x)] \right)$$

Step 3: Form the dual

$$\mathcal{L} = \sum_{i} \lambda_{i} w_{i} + \sum_{j} \mu_{j} v_{j} + \sum_{k} \text{Tr}[A_{k} W_{k}] + \sum_{l} \text{Tr}[B_{l} V_{l}]$$
$$- \left(\sum_{i} \lambda_{i} g_{i}(x) + \sum_{j} \mu_{j} h_{j}(x) + \sum_{k} \text{Tr}[A_{k} G_{k}(x)] + \sum_{l} \text{Tr}[B_{l} H_{l}(x)] \right)$$

When is Lagrangian **bounded** if we **maximize** over **primal** variables?

$$\min \sum_{i} \lambda_{i} w_{i} + \sum_{j} \mu_{j} v_{j} + \sum_{k} \operatorname{Tr}[A_{k} W_{k}] + \sum_{l} \operatorname{Tr}[B_{l} V_{l}]$$

s.t. Constraints on dual variables implied by boundedness

$$\lambda_i \geq 0, \ \mu_j \in \mathbb{R}, \ A_k \succeq 0, \ B_l \text{ Hermitian.}$$

Constraints introduced when forming Lagrangian

Example: $\max x$

s.t.
$$x + y \le 2$$

$$\begin{pmatrix} 1 & x \\ x & y \end{pmatrix} \succeq 0$$

$$\begin{pmatrix} 2 & x + y \\ x + y & 2x \end{pmatrix} \succeq 0$$

Example: max x

s.t.
$$x + y \le 2$$

$$\begin{pmatrix} 1 & x \\ x & y \end{pmatrix} \succeq 0$$

$$\begin{pmatrix} 2 & x + y \\ x + y & 2x \end{pmatrix} \succeq 0$$

$$\mathcal{L} = x + \lambda(2 - x - y) + \text{Tr} \left[\begin{pmatrix} a & b \\ b & c \end{pmatrix} \begin{pmatrix} 1 & x \\ x & y \end{pmatrix} \right]$$

$$+ \text{Tr} \left[\begin{pmatrix} d & e \\ e & f \end{pmatrix} \begin{pmatrix} 2 & x + y \\ x + y & 2x \end{pmatrix} \right]$$

Example: max

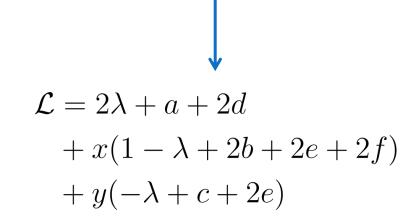
s.t.
$$x + y \le 2$$

$$\begin{pmatrix} 1 & x \\ x & y \end{pmatrix} \succeq 0$$

$$\begin{pmatrix} 2 & x + y \\ x + y & 2x \end{pmatrix} \succeq 0$$

$$\mathcal{L} = x + \lambda(2 - x - y) + \text{Tr} \left[\begin{pmatrix} a & b \\ b & c \end{pmatrix} \begin{pmatrix} 1 & x \\ x & y \end{pmatrix} \right]$$

$$+ \text{Tr} \left[\begin{pmatrix} d & e \\ e & f \end{pmatrix} \begin{pmatrix} 2 & x + y \\ x + y & 2x \end{pmatrix} \right]$$



Example: max

s.t.
$$x + y \le 2$$

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$$\begin{pmatrix} 2 & x + y \\ x + y & 2x \end{pmatrix} \succeq 0$$

$$\mathcal{L} = x + \lambda(2 - x - y) + \text{Tr} \left[\begin{pmatrix} a & b \\ b & c \end{pmatrix} \begin{pmatrix} 1 & x \\ x & y \end{pmatrix} \right]$$

$$+ \text{Tr} \left[\begin{pmatrix} d & e \\ e & f \end{pmatrix} \begin{pmatrix} 2 & x + y \\ x + y & 2x \end{pmatrix} \right]$$

min
$$2\lambda + a + 2d$$

s.t. $1 - \lambda + 2b + 2e + 2f = 0$ $\mathcal{L} = 2\lambda + a + 2d$
 $-\lambda + c + 2e = 0$ $+x(1 - \lambda + 2b + 2e + 2f)$
 $\begin{pmatrix} a & b \\ b & c \end{pmatrix} \succeq 0, \begin{pmatrix} d & e \\ e & f \end{pmatrix} \succeq 0$ $+y(-\lambda + c + 2e)$
 $\lambda \geq 0$.

Example:
$$\max x$$

s.t.
$$x + y \le 2$$

$$\begin{pmatrix} 1 & x \\ x & y \end{pmatrix} \succeq 0$$

$$\begin{pmatrix} 2 & x + y \\ x + y & 2x \end{pmatrix} \succeq 0$$

$$\mathcal{L} = x + \lambda(2 - x - y) + \text{Tr} \left[\begin{pmatrix} a & b \\ b & c \end{pmatrix} \begin{pmatrix} 1 & x \\ x & y \end{pmatrix} \right]$$

$$+ \text{Tr} \left[\begin{pmatrix} d & e \\ e & f \end{pmatrix} \begin{pmatrix} 2 & x + y \\ x + y & 2x \end{pmatrix} \right]$$

$$\min \quad a + 2c + 2d + 4e$$

s.t.
$$1 + 2b - c + 2f = 0$$

$$\min 2\lambda + a + 2d$$

s.t.
$$1 - \lambda + 2b + 2e + 2f = 0$$
$$-\lambda + c + 2e = 0$$

$$\begin{pmatrix} a & b \\ b & c \end{pmatrix} \succeq 0, \ \begin{pmatrix} d & e \\ e & f \end{pmatrix} \succeq 0$$
$$\lambda \ge 0.$$

$$\mathcal{L} = 2\lambda + a + 2d$$
- $+ x(1 - \lambda + 2b + 2e + 2f)$
+ $y(-\lambda + c + 2e)$