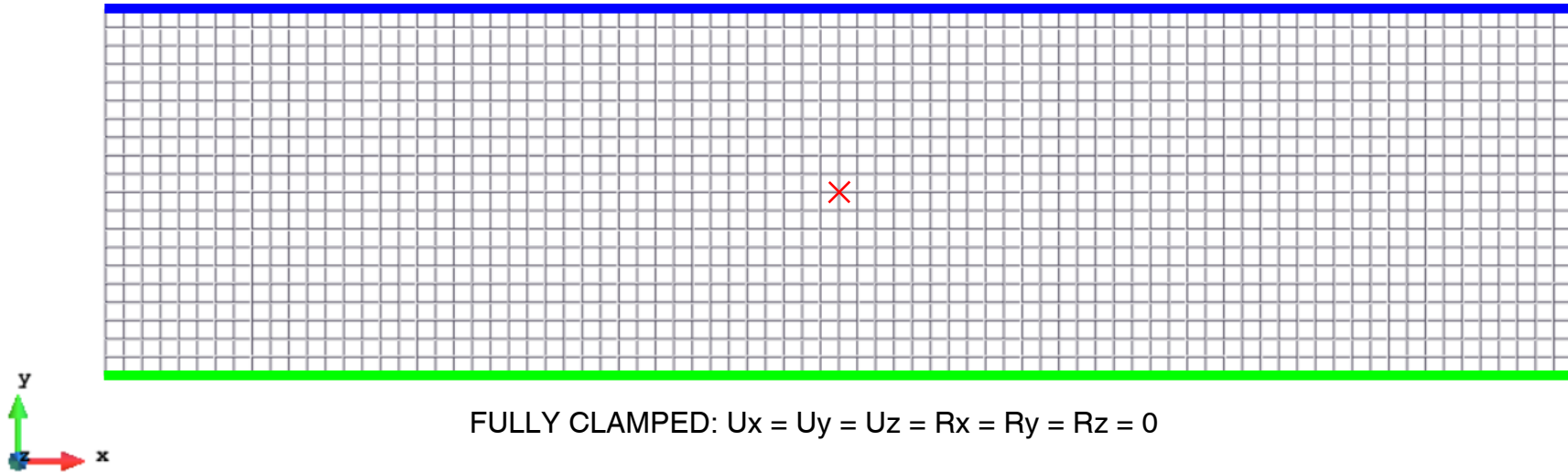


LINE RESTRAINT: $U_x = \delta$, $U_y = U_z = 0$



FULLY CLAMPED: $U_x = U_y = U_z = R_x = R_y = R_z = 0$