

Differential Geometry: Homework 7

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Problem 1.

Prove that the real projective space \mathbb{RP}^n is orientable if and only if n is odd.

Proof.

By the hint, I'll start by showing that the antipodal map f on $S^n = \{(x_1, \dots, x_{n+1}) : \sum x_i^2 = 1\} \subset \mathbb{R}^{n+1}$ is orientation preserving if and only if n is odd. In particular this map is

$$(x_1, x_2, \dots, x_{n+1}) \xrightarrow{f} (-x_1, -x_2, \dots, -x_{n+1})$$

Let $[\omega] = [dx_1 \wedge dx_2 \wedge \dots \wedge dx_{n+1}]$ be the standard orientation on \mathbb{R}^{n+1} , then

$$\begin{aligned} f_*([\omega]) &= [f^*\omega] \\ &= [d(-x_1) \wedge \dots \wedge d(-x_{n+1})] \\ &= [(-1)^{n+1} dx_1 \wedge \dots \wedge dx_{n+1}] \\ &= [(-1)^{n+1} \omega]. \end{aligned}$$

Thus the antipodal map is orientation preserving exactly when $(-1)^{n+1} = 1$, that is, when n is odd.

Recall that in Homework 4, problem 5b, we showed that $\mathbb{RP}^n \cong S^n/\mathbb{Z}_2$ where \mathbb{Z}_2 acted on S^n by the above map, $x \mapsto -x$. \square

Problem 2.

Let S^2 denote the unit sphere in \mathbb{R}^3 , $\{(r_1, r_2, r_3) \mid r_1^2 + r_2^2 + r_3^2 = 1\}$ with atlas $\mathcal{A} = \{(U_i^\pm, \pi_i^\pm)\}_{i=1,2,3}$ where

$$U_i^+ = \{r_i > 0\} \cap S^2, \text{ and } U_i^- = \{r_i < 0\} \cap S^2,$$

and π_i^\pm is the projection away from the i th coordinate.

(a) Is \mathcal{A} a Euclidean oriented atlas?

(b) Let

$$\sigma = \frac{r_1 dr_2 \wedge dr_3 - r_2 dr_1 \wedge dr_3 + r_3 dr_1 \wedge dr_2}{(r_1^2 + r_2^2 + r_3^2)^{3/2}}$$

be a two-form on $\mathbb{R}^3 \setminus \{0\}$. Prove that σ restricted to S^2 is closed.

(c) Prove that σ restricted to S^2 is not exact.

Proof.

(a) We will whether or not given any (U_α, ϕ_α) and (U_β, ϕ_β) , the determinant of d of the transition function $\det(d(\phi_\beta \circ \phi_\alpha^{-1})_{\phi_\alpha(p)}) > 0$ for all $p \in U_\alpha \cap U_\beta$. Notice that in particular, the inverse map of $\pi_1^- : U_1^- \rightarrow \mathbb{R}^2$ is

$$(x, y) \xrightarrow{(\pi_1^-)^{-1}} (-\sqrt{1-x^2-y^2}, x, y).$$

So consider $\pi_2^+ \circ (\pi_1^-)^{-1}$

$$(x, y) \xrightarrow{(\pi_1^-)^{-1}} (-\sqrt{1-x^2-y^2}, x, y) \xrightarrow{\pi_2^+} (-\sqrt{1-x^2-y^2}, y),$$

which has Jacobian matrix

$$\det \begin{bmatrix} \frac{\partial(-\sqrt{1-x^2-y^2})}{\partial x} & \frac{\partial(-\sqrt{1-x^2-y^2})}{\partial y} \\ \frac{\partial y}{\partial x} & \frac{\partial y}{\partial y} \end{bmatrix} = \det \begin{bmatrix} \frac{-x}{\sqrt{1-x^2-y^2}} & \frac{-y}{\sqrt{1-x^2-y^2}} \\ 0 & 1 \end{bmatrix} = \frac{-x}{\sqrt{1-x^2-y^2}}.$$

Since this is evaluated at $\pi_1^-(p)$ where $p \in U_1^- \cap U_2^+$, (the second coordinate of p and consequently the first coordinate of $\pi_1^-(p)$) the determinant is negative. Thus \mathcal{A} is not orientation preserving.

(b) In order to show that σ is closed, we need to show that $d\sigma = 0$. Since σ is restricted to S^2 , no division by zero will occur.

$$\begin{aligned} d\sigma &= d\left(\frac{r_1 dr_2 \wedge dr_3}{(r_1^2 + r_2^2 + r_3^2)^{3/2}}\right) - d\left(\frac{r_2 dr_1 \wedge dr_3}{(r_1^2 + r_2^2 + r_3^2)^{3/2}}\right) + d\left(\frac{r_3 dr_1 \wedge dr_2}{(r_1^2 + r_2^2 + r_3^2)^{3/2}}\right) \\ &= \frac{\partial}{\partial r_1} \left(\frac{r_1}{(r_1^2 + r_2^2 + r_3^2)^{3/2}}\right) dx_1 \wedge dr_2 \wedge dr_3 \\ &\quad - \frac{\partial}{\partial r_2} \left(\frac{r_2}{(r_1^2 + r_2^2 + r_3^2)^{3/2}}\right) dr_2 \wedge dr_1 \wedge dr_3 \\ &\quad + \frac{\partial}{\partial r_3} \left(\frac{r_3}{(r_1^2 + r_2^2 + r_3^2)^{3/2}}\right) dr_3 \wedge dr_1 \wedge dr_2 \\ &= \frac{-2r_1^2 + r_2^2 + r_3^2}{(r_1^2 + r_2^2 + r_3^2)^{5/2}} dx_1 \wedge dr_2 \wedge dr_3 \\ &\quad + \frac{r_1^2 - 2r_2^2 + r_3^2}{(r_1^2 + r_2^2 + r_3^2)^{5/2}} dr_1 \wedge dr_2 \wedge dr_3 \\ &\quad + \frac{r_1^2 + r_2^2 - 2r_3^2}{(r_1^2 + r_2^2 + r_3^2)^{5/2}} dr_1 \wedge dr_2 \wedge dr_3 \\ &= 0 \, dr_1 \wedge dr_2 \wedge dr_3 \end{aligned}$$

- (c) The idea here is that because the equator of S^2 is a set of measure zero, we can approximate the integral over U_1^+ and U_2^- (and thus S^2) by (the limit of) compact sets V_r^+ and V_r^- , given by

$$V_r^\pm = \{(\pi_1^\pm)^{-1}(x, y) \mid x^2 + y^2 \leq r\}.$$

This is to say, we can compute the integral over S^2 by

$$\int_{S^2} \sigma = \lim_{r \rightarrow 1} \int_{V_r^+} \sigma + \int_{V_r^-} \sigma.$$

To make integration easier, let's break up σ into pieces

$$\sigma = f_1 dr_2 \wedge dr_3 + f_2 dr_1 \wedge dr_3 + f_3 dr_1 \wedge dr_2.$$

so

$$\int_{V_r^+} \sigma = \int_{\pi_1^+(V_r^+)} ((\pi_1^+)^{-1})^* \sigma = \int_{\pi_1^+(V_r^+)} ((\pi_1^+)^{-1})^* (f_1 dr_2 \wedge dr_3 + f_2 dr_1 \wedge dr_3 + f_3 dr_1 \wedge dr_2)$$

Now some intermediate computations of $((\pi_1^+)^{-1})^* dr_i$ (note that $r_i: \mathbb{R}^3 \rightarrow \mathbb{R}$ is the projection map to the i -th coordinate):

$$\begin{aligned} ((\pi_1^+)^{-1})^* dr_1 &= d(r_1 \circ (\pi_1^+)^{-1}) = d(\sqrt{1-x^2-y^2}) = -\frac{x}{\sqrt{1-x^2-y^2}} dx - \frac{y}{\sqrt{1-x^2-y^2}} dy \\ ((\pi_1^+)^{-1})^* dr_2 &= d(r_2 \circ (\pi_1^+)^{-1}) = dx \\ ((\pi_1^+)^{-1})^* dr_3 &= d(r_3 \circ (\pi_1^+)^{-1}) = dy \end{aligned}$$

so by exploiting some cancellation,

$$\begin{aligned} ((\pi_1^+)^{-1})^* dr_1 \wedge dr_2 &= -\frac{y}{\sqrt{1-x^2-y^2}} dy \wedge dx \\ ((\pi_1^+)^{-1})^* dr_1 \wedge dr_3 &= -\frac{x}{\sqrt{1-x^2-y^2}} dx \wedge dy \\ ((\pi_1^+)^{-1})^* dr_2 \wedge dr_3 &= dx \wedge dy \end{aligned}$$

Similarly intermediate computations of $((\pi_1^+)^{-1})^* f_i = f_i \circ (\pi_1^+)^{-1}$:

$$\begin{aligned} (x, y) &\xrightarrow{(\pi_1^+)^{-1}} (\sqrt{1-x^2-y^2}, x, y) \xrightarrow{f_1} \frac{\sqrt{1-x^2-y^2}}{((\sqrt{1-x^2-y^2})^2 + x^2 + y^2)^{3/2}} = \sqrt{1-x^2-y^2} \\ (x, y) &\xrightarrow{(\pi_1^+)^{-1}} (\sqrt{1-x^2-y^2}, x, y) \xrightarrow{f_2} \frac{-x}{((\sqrt{1-x^2-y^2})^2 + x^2 + y^2)^{3/2}} = -x \\ (x, y) &\xrightarrow{(\pi_1^+)^{-1}} (\sqrt{1-x^2-y^2}, x, y) \xrightarrow{f_3} \frac{y}{((\sqrt{1-x^2-y^2})^2 + x^2 + y^2)^{3/2}} = y \end{aligned}$$

Using these computations shows that

$$\begin{aligned} \int_{V_r^+} \sigma &= \int_{\pi_1^+(V_r^+)} \underbrace{\frac{\sqrt{1-x^2-y^2} dx dy}{((\pi_1^+)^{-1})^*(f_1 dr_2 \wedge dr_3)}}_{\frac{1}{\sqrt{1-x^2-y^2}}} + \underbrace{\frac{x^2}{\sqrt{1-x^2-y^2}} dx dy}_{((\pi_1^+)^{-1})^*(f_2 dr_1 \wedge dr_3)} + \underbrace{\frac{y^2}{\sqrt{1-x^2-y^2}} dx dy}_{((\pi_1^+)^{-1})^*(f_3 dr_1 \wedge dr_2)} \\ &= \int_{\pi_1^+(V_r^+)} \frac{1}{\sqrt{1-x^2-y^2}} dx dy \\ &= \int_0^{2\pi} \int_0^r \frac{s}{\sqrt{1-s^2}} ds d\theta = \int_0^{2\pi} \left[-\sqrt{1-s^2} \right]_0^r d\theta = 2\pi(1 - \sqrt{1-r^2}) \end{aligned}$$

The integral on V_r^- follows very similarly, only the resulting integral has the opposite sign. These integrals do *not* cancel each other, because the orientation is opposite. Therefore σ restricted to S^2 is *not* exact because the integral does not vanish:

$$\int_{S^2} \sigma = 4\pi \neq 0.$$

□

Problem 3.

Suppose that $M = M_1 \amalg M_2$. Prove that

$$H_{dR}^k(M) = H_{dR}^k(M_1) \oplus H_{dR}^k(M_2)$$

Proof.

The cheapest way to see this is to appeal to the Mayer-Vietoris sequence:

$$\begin{array}{ccccccc} \dots \rightarrow \Omega^{k-1}(M_1 \cap M_2) & \rightarrow & H^k(M) & \xrightarrow{\phi} & H^k(M_1) \oplus H^k(M_2) & \rightarrow & \Omega^k(M_1 \cap M_2) \rightarrow \dots \\ \dots \rightarrow \Omega^{k-1}(\emptyset) & & \rightarrow H^k(M) & \xrightarrow{\phi} & H^k(M_1) \oplus H^k(M_2) & \rightarrow & \Omega^k(\emptyset) \rightarrow \dots \\ \dots \rightarrow 0 & & \rightarrow H^k(M) & \xrightarrow{\phi} & H^k(M_1) \oplus H^k(M_2) & \rightarrow & 0 \rightarrow \dots \end{array}$$

Because the sequence is exact,

$$0 \rightarrow H^k(M) \xrightarrow{\phi} H^k(M_1) \oplus H^k(M_2)$$

implies that ϕ is injective and

$$H^k(M) \xrightarrow{\phi} H^k(M_1) \oplus H^k(M_2) \rightarrow 0$$

implies that ϕ is surjective. Thus ϕ is an isomorphism, and

$$H_{dR}^k(M) = H_{dR}^k(M_1) \oplus H_{dR}^k(M_2).$$

□

Problem 4.

Use the Mayer-Vietoris sequence to prove that

$$H_{dR}^k(S^2) = \begin{cases} \mathbb{R} & k = 0, 2 \\ 0 & \text{otherwise} \end{cases},$$

and then prove by induction that

$$H_{dR}^k(S^n) = \begin{cases} \mathbb{R} & k = 0, n \\ 0 & \text{otherwise} \end{cases}.$$

Proof.

Base case.

Inductive step.

The inductive step requires three ingredients:

(i) The Mayer-Vietoris sequence is exact:

$$H^{k-1}(\mathbb{R}) \oplus H^{k-1}(\mathbb{R}) \rightarrow H^{k-1}(S^{n-1} \times (-\varepsilon, \varepsilon)) \rightarrow H^k(S^n) \rightarrow H^k(\mathbb{R}) \oplus H^k(\mathbb{R}).$$

(ii) By a lemma of Poincaré, the k -th de Rham cohomology group of Euclidean space is trivial

$$H^k(\mathbb{R}) = 0 \text{ for } k \neq 0$$

(iii) The product of the n -sphere with an interval is homotopic to the n -sphere

$$S^{n-1} \times (-\varepsilon, \varepsilon) \simeq S^{n-1}$$

Case 1. ($k = 0$)

Since S^n is connected, this follows from Tuesday's Lemma that $H^0(M) = \mathbb{R}$ for any connected manifold M .

Case 2. ($k = n \neq 1$)

This follows by induction. We know that $H^{n-1}(S^{n-1}) = \mathbb{R}$, so we have the exact sequence

$$\underbrace{H^{n-1}(\mathbb{R}) \oplus H^{n-1}(\mathbb{R})}_{0 \times 0 \text{ by (ii)}} \rightarrow \underbrace{H^{n-1}(S^{n-1} \times (-\varepsilon, \varepsilon))}_{=H^{n-1}(S^{n-1}) \text{ by (iii)}} \xrightarrow{\delta} H^n(S^n) \rightarrow \underbrace{H^n(\mathbb{R}) \oplus H^n(\mathbb{R})}_{0 \times 0 \text{ by (ii)}} \\ 0 \rightarrow \mathbb{R} \xrightarrow{\delta} H^n(S^n) \rightarrow 0.$$

which means that δ must be both injective and surjective, and thus $H^n(S^n) = \mathbb{R}$.

Case 2'. ($k = n = 1$)

We're allowed to assume this input, as it was shown in class that $H^1(S^1) = \mathbb{R}$.

Case 3. ($k \notin \{0, 1, n\}$)

$$\underbrace{H^{k-1}(S^{n-1} \times (-\varepsilon, \varepsilon))}_{=H^{k-1}(S^{n-1})=0} \rightarrow H^k(S^n) \rightarrow \underbrace{H^k(\mathbb{R}) \oplus H^k(\mathbb{R})}_{0 \times 0 \text{ by (ii)}} \\ 0 \rightarrow H^k(S^n) \rightarrow 0.$$

Therefore $H^k(S^n) = 0$

Case 3'. ($0 \neq k \neq n = 1$)

Similar to Case 2', we are allowed to assume that when $n = 1$, $H^k(S^1) = 0$ when $k \notin \{0, 1\}$.

Therefore the relationship holds by induction:

$$H_{dR}^k(S^n) = \begin{cases} \mathbb{R} & k = 0, n \\ 0 & \text{otherwise} \end{cases}.$$

□

Problem 5.

Give a careful computation of the de Rham cohomology (and hence, the Euler characteristic) of a genus g surface Σ_g .

Proof.

□

Problem 6.

(a) Let $S^1 = \mathbb{R}/\mathbb{Z}$, and fix an orientation on S^1 . For every $k \in \mathbb{Z}$ there is a map $F_k: S^1 \rightarrow S^1$ by $[z] \mapsto [kz]$. Compute the degree of F_k .

(b) Compute the degree of the reflection map $f: S^n \rightarrow S^n$

$$(x_1, \dots, x_{n+1}) \mapsto (-x_1, \dots, x_{n+1}).$$

Proof.

(a) F_k can be thought of as the map that winds the circle around itself k times. Let's first construct an oriented atlas for S^1

$$\begin{aligned} \mathcal{A} &= \{(U_\varepsilon, \phi), (V_\varepsilon, \psi)\} \\ U_\varepsilon &= \{[x] : \varepsilon < x < 1 - \varepsilon\} \text{ and } \phi([x]) = x - \lfloor x \rfloor \\ V_\varepsilon &= \{[x] : -2\varepsilon < x < 2\varepsilon\} \text{ and } \psi([x]) = \phi([x - 1/2]). \end{aligned}$$

This atlas is oriented because the transition map

$$\psi \circ \phi^{-1}: \underbrace{(\varepsilon, 2\varepsilon) \cup (1 - 2\varepsilon, 1 - \varepsilon)}_{\phi(U \cap V)} \rightarrow \underbrace{\left(\frac{1}{2} - 2\varepsilon, \frac{1}{2} - \varepsilon\right) \cup \left(\frac{1}{2} + \varepsilon, \frac{1}{2} + 2\varepsilon\right)}_{\phi(U \cap V)}$$

given by

$$x \xrightarrow{\phi^{-1}} [x] \xrightarrow{\psi} \begin{cases} x + \frac{1}{2} & \phi(x) \in (\varepsilon, 2\varepsilon) \\ x - \frac{1}{2} & \phi(x) \in (1 - 2\varepsilon, 1 - \varepsilon) \end{cases}$$

has derivative 1 at every point.

Now, the cohomological definition can be used to compute $\deg(F_k)$

$$\deg(F_k) = \frac{\int_{S^1} F_k^* \omega}{\int_{S^1} \omega}.$$

Although the map $t: \mathbb{R}/\mathbb{Z} \rightarrow \mathbb{R}$ given by $[x] \mapsto x$ is not a single-valued function, dt is well defined because t is injective on any sufficiently small neighborhood of the codomain. Then by computing

$$\int_{S^1} dt = \lim_{\varepsilon \rightarrow 0} \int_{V_\varepsilon} dt = \lim_{\varepsilon \rightarrow 0} \int_\varepsilon^{1-\varepsilon} (\phi^{-1})^* dt = \lim_{\varepsilon \rightarrow 0} \int_\varepsilon^{1-\varepsilon} d(t \circ \phi^{-1}) = \lim_{\varepsilon \rightarrow 0} \int_\varepsilon^{1-\varepsilon} dx = \lim_{\varepsilon \rightarrow 0} 1 - 2\varepsilon = 1.$$

Similarly

$$\int_{S^1} F_k^* dt = \lim_{\varepsilon \rightarrow 0} \int_\varepsilon^{1-\varepsilon} d(t \circ F_k^* dt \circ \phi^{-1}) = \lim_{\varepsilon \rightarrow 0} \int_\varepsilon^{1-\varepsilon} d(kx) = \lim_{\varepsilon \rightarrow 0} k(1 - 2\varepsilon) = k.$$

Thus $\deg(F_k) = k$.

(b) Since f is a diffeomorphism, $y = (1, 0, \dots, 0)$ is a regular value, and its preimage has only one point, call it p ,

$$f^{-1}(y) = \{(-1, 0, \dots, 0)\}.$$

Using the geometric definition of degree,

$$\deg(f) = \sum_{q \in f^{-1}(y)} \deg_q(f) = \deg_p(f).$$

Therefore the degree of f is 1 if df_p is orientation preserving, otherwise the degree of f is -1 . But a manual computation shows that df_p is orientation reversing,

$$df_p = \left[\frac{\partial f_i}{\partial x_j}(p) \right] = \begin{bmatrix} -1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix},$$

which has determinant of -1 . Therefore $\deg(f) = -1$.

□

Problem 7.

Proof.

□