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## Abstract

Some examples of Mathematical Equations rendered in LaTeX

# 1 Algebra

The well known Pythagorean theorem  $x^2 + y^2 = z^2$  was proved to be invalid for exponents greater than 2.

Thus the more general equation has no integer solutions:

$$x^n + y^n = z^n$$

$$\begin{aligned} A &= \frac{\pi r^2}{2} \\ &= \frac{1}{2} \pi r^2 \end{aligned} \tag{1}$$

## 1.1 Aligning Equations

$$\begin{aligned} a + b \times a - b &= (a + b)(a - b) &= a^2 - b^2 \\ x + y \times x - y &= (x + y)(x - y) &= x^2 - y^2 \\ p + q \times p - q &= (p + q)(p - q) &= p^2 - q^2 \end{aligned}$$

$$\begin{aligned} (a + b)^2 &= a^2 + 2ab + b^2 \\ (a - b)^2 &= a^2 - 2ab + b^2 \end{aligned}$$

$$\begin{aligned} f(x) &= x^2 \\ g(x) &= \frac{1}{x} \\ F(x) &= \int_b^a \frac{1}{3} x^3 \end{aligned}$$

## 1.2 Various Examples

$$F = G\left(\frac{m_1m_2}{r^2}\right)$$

$$\left[\frac{N}{\left(\frac{L}{p}\right)-(m+n)}\right]$$

$$y=1+\left(\frac{1}{x}+\frac{1}{x^2}+\frac{1}{x^3}+\ldots+\frac{1}{x^{n-1}}+\frac{1}{x^n}\right)$$

$$\left(\begin{array}{ccc}1&5&8\\0&2&4\\3&3&-8\end{array}\right)$$

## 2 Trigonometry

$$\sin^2(\theta) + \cos^2(\theta) = 1$$

## 3 Operators

$$\lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

This operator changes when used alongside text  $\lim_{x \rightarrow h}(x-h)$ .

$$\begin{aligned} f(x) &= \sum_{i=0}^n \frac{a_i}{1+x} \\ f(x) &= \sum_{i=0}^n \frac{a_i}{1+x} \\ f(x) &= \sum_{i=0}^n \frac{a_i}{1+x} \\ f(x) &= \sum_{i=0}^n \frac{a_i}{1+x} \end{aligned}$$

### 3.1 Fractions and Binomials

$$\begin{aligned} &\frac{1 + \frac{x}{y}}{1 + \frac{1}{1 + \frac{1}{z}}} \\ &\frac{1}{\sqrt{x}} \\ &a_0 + \frac{1}{a_1 + \frac{1}{a_2 + \frac{1}{a_3 + \frac{1}{a_4}}}} \end{aligned}$$

Mixing text and equations:

$$\begin{aligned} f(x) &= \frac{P(x)}{Q(x)} \text{ and } f(x) = \frac{P(x)}{Q(x)} \\ \binom{n}{k} &= \frac{n!}{k!(n-k)!} \end{aligned}$$

## 4 Matrices

The identity matrix:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

### 4.1 Greek Letters

$\alpha \quad \beta \quad \gamma \quad \delta \quad \epsilon \quad \zeta \quad \eta \quad \theta \quad \iota \quad \kappa \quad \lambda \quad \mu \quad \nu \quad \xi \quad \omicron \quad \pi \quad \rho \quad \sigma \quad \tau \quad \upsilon \quad \phi \quad \chi \quad \psi \quad \omega$

### 4.2 Binary Operators

$\times \quad \otimes \quad \oplus \quad \cup \quad \cap$

### 4.3 Relation Operators

$< \quad > \quad \subset \quad \supset \quad \subseteq \quad \supseteq$

### 4.4 Other Symbols

$\int \quad \oint \quad \Sigma \quad \Pi$

- $\mathbb{P}$  Prime numbers
- $\mathbb{W}$  Whole numbers
- $\mathbb{N}$  Natural numbers
- $\mathbb{Z}$  Integers
- $\mathbb{Q}$  Rational numbers
- $\mathbb{R}$  Real numbers
- $\mathbb{C}$  Complex numbers
- $\mathbb{H}$  Quaternions
- $\mathbb{O}$  Octonions
- $\mathbb{S}$  Sedenions

$\langle\langle\langle\langle\rangle\rangle\rangle\rangle$

## 5 Complex Numbers

$$i^2 = -1$$

$$z = x + iy$$

$$\mathbb{C}$$

$$\{z, \bar{z}\} \in \mathbb{C}$$

$$\Re(z) = a$$

$$\Im(z) = b$$

$$\Re(z), \Im(z)$$

$$\operatorname{Re}(z), \operatorname{Im}(z)$$

$$\Re(z), \Im(z)$$

$$z = a + ib$$

$$\bar{z} = a - ib$$

$$\Re z = a$$

$$\Im z = b$$

$$z_1 \bar{z}_2$$

$$\overline{z_1 z_2}$$

## 6 Navier-Stokes Equations

### 6.1 Einstein Summation Convention

$$\frac{\partial \rho}{\partial t} + \frac{\partial(\rho u_i)}{\partial x_i} = 0 \quad (2)$$

$$\frac{\partial(\rho u_i)}{\partial t} + \frac{\partial[\rho u_i u_j]}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \frac{\partial \tau_{ij}}{\partial x_j} + \rho f_i \quad (3)$$

$$\frac{\partial(\rho e)}{\partial t} + (\rho e + p) \frac{\partial u_i}{\partial x_i} = \frac{\partial(\tau_{ij} u_j)}{\partial x_i} + \rho f_i u_i + \frac{\partial(\dot{q}_i)}{\partial x_i} + r \quad (4)$$

The Einstein summation convention dictates that: When a sub-indices (here  $i$  or  $j$ ) is twice or more repeated in the same equation, one sums across the n-dimensions.

So, in the context of Navier-Stokes in three spatial dimensions, one repeats the term three times, each time changing the indice for one representing the corresponding dimension (ie 1, 2, 3 or  $x, y, z$ ).

The first equation is therefore a shorthand representation of:  $\frac{\partial \rho}{\partial t} + \frac{\partial(\rho u_1)}{\partial x_1} + \frac{\partial(\rho u_2)}{\partial x_2} + \frac{\partial(\rho u_3)}{\partial x_3} = 0$ .

The second equation is actually a superposition of three separable equations which could be written in a three-line form: one line equation for each  $i$  in each of which one sums the three terms for the  $j$  sub-indices.

### 6.2 Classic Notation with $\longrightarrow, \otimes, \nabla$

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u}) = 0 \quad (5)$$

$$\frac{\partial(\rho \vec{u})}{\partial t} + \vec{\nabla} \cdot [\overline{\rho \vec{u} \otimes \vec{u}}] = -\vec{\nabla} \vec{p} + \vec{\nabla} \cdot \vec{\bar{\tau}} + \rho \vec{f} \quad (6)$$

$$\frac{\partial(\rho e)}{\partial t} + \vec{\nabla} \cdot ((\rho e + p) \vec{u}) = \vec{\nabla} \cdot (\vec{\bar{\tau}} \cdot \vec{u}) + \rho \vec{f} \cdot \vec{u} + \vec{\nabla} \cdot (\vec{\dot{q}}) + r \quad (7)$$

Here  $\otimes$  denotes the tensor product which forms a tensor from the constituent vectors. A double bar denotes a tensor. These equations using the Classic Notation are equivalent to the earlier three using the Einstein Summation Convention.

### 6.3 Navier Stokes Equation 3D Cartesia Coordinates

$$\begin{aligned} x : \rho (\partial_t u_x + u_x \partial_x u_x + u_y \partial_y u_x + u_z \partial_z u_x) = \\ -\partial_x p + \mu (\partial_x^2 u_x + \partial_y^2 u_x + \partial_z^2 u_x) + \\ \frac{1}{3} \mu \partial_x (\partial_x^2 u_x + \partial_y^2 u_y + \partial_z^2 u_z) + p g_x \end{aligned}$$

$$\begin{aligned}
y : \rho (\partial_t u_y + u_x \partial_x u_y + u_y \partial_y u_y + u_z \partial_z u_y) = \\
-\partial_y p + \mu (\partial_x^2 u_y + \partial_y^2 u_y + \partial_z^2 u_y) + \\
\frac{1}{3} \mu \partial_y (\partial_x^2 u_x + \partial_y^2 u_y + \partial_z^2 u_z) + p g_y
\end{aligned}$$

$$\begin{aligned}
z : \rho (\partial_t u_z + u_x \partial_x u_z + u_y \partial_y u_z + u_z \partial_z u_z) = \\
-\partial_z p + \mu (\partial_x^2 u_z + \partial_y^2 u_z + \partial_z^2 u_z) + \\
\frac{1}{3} \mu \partial_z (\partial_x^2 u_x + \partial_y^2 u_y + \partial_z^2 u_z) + p g_z
\end{aligned}$$

**7 Logarithms**

$$\log xy = \log x + \log y$$

**8 Calculus**

$$\frac{df}{dt} = \lim_{h \rightarrow 0} \frac{f(t+h) - f(t)}{h}$$

**9 Newton's Law of Gravity**

$$F = G \frac{m_1 m_2}{d^2}$$

**10 Complex Numbers**

$$i^2 = -1$$

**11 Euler's Formula for Polyhedra**

$$F - E + V = 2$$



## 12 Maxwell's Equations

## 13 The Normal Distribution

$$\Phi(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

## 14 The Wave Equation

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$$

## 15 The Fourier Transform

$$\hat{f}(\xi) = \int_{-\infty}^{\infty} f(x) e^{2\pi i x \xi} dx$$

## 16 The Second Law of Thermodynamics

$$dS \geq 0$$

## 17 Relativity

$$E = mc^2$$

This equation states Einstein's mass energy equivalence relationship.

## 18 Relativity

$$i\hbar \frac{\partial}{\partial t} \Psi = \hat{H} \Psi$$

## 19 Information Thoery

$$H = - \sum_x p(x) \log p(x)$$

## 20 Chaos Thoery

$$x_{t+1} = kx_t(1 - x_t)$$

## 21 Black-Scholes Equation

$$\frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + rS \frac{\partial V}{\partial S} + \frac{\partial V}{\partial t} - rV = 0$$

## 22 References

- [https://www.overleaf.com/learn/latex/Mathematical\\_expressions](https://www.overleaf.com/learn/latex/Mathematical_expressions)
- <https://github.com/EdwardCalzia/Latex-Formulas>
- [https://latex-programming.fandom.com/wiki/List\\_of\\_LaTeX\\_symbols](https://latex-programming.fandom.com/wiki/List_of_LaTeX_symbols)
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