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Author Correction: Research on underwater robot ranging technology based on semantic segmentation and binocular vision

Qing Hu, Kekuan Wang, Fushen Ren & Zhongyang Wang

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In the original version of this Article, Qing Hu was incorrectly listed as a corresponding author. The correct corresponding author for this Article is Zhongyang Wang. Correspondence and request for materials should be addressed to wzy1719393666@126.com.

The original Article has been corrected.



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