

## USING 2D-FFT TO SEARCH FAST RADIO BURST

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### ABSTRACT

Fast Radio Burst have been found from pulsar data for many years. There are several FRB search algorithm like tree algorithm, FDMT et. Here we proposed a different FRB searching algorithm which basically trace a curve in frequency-time image. This algorithm is mainly realized by two dimensional Fast Fourier Transform. We take a 2D FFT on the  $f^{-2}(t)$  data map, Then trace the signal along the angle of straight line. In this searching method, it's easier to remove RFI in large scale and will bring a speed up benefit in well-developed 2D FFT library both in CPU and GPU code.

Fast Radio Burst is a high energy radio signal found in the Universe. The first one is found by Lorimer Duncn in 2007, now people always call it as Lormeter burst. Like Pulsar, Its a wide band radio sgnal, when it go through the inter stellar or inter galaxy medium, the higher frequency will go faster than lower frequency. When Signal go through dense of ISM The origin of FRB is still unclear, there are lots of theories trying to describe what FRB is.

*Keywords:* 2DFFT ,FAST radio burst

## 1. INTRODUCTION

Fast radio bursts (FRBs) are bright ( $\sim$ Jy) and short ( $\sim$ ms) bursts of radio emission that have dispersion measures (DMs) in excess of the line of sight DM contribution expected from the electron distribution of our Galaxy. To date 18 FRBs have been reported — most of them detected at the Parkes telescope (????????) and one each at the Arecibo (?) and Green Bank telescopes (?).

A plethora of source models have been proposed to explain the properties of FRBs (see e.g. ?, for a brief review). According to the models, the excess DM for FRBs may be intrinsic to the source, placing it within the Galaxy; it may arise mostly from the intergalactic medium, placing a source of FRBs at cosmological distances ( $z \sim 0.2-1$ ) or it may arise from the host galaxy, placing a source of FRBs at extragalactic, but not necessarily cosmological, distances ( $\sim 100$  Mpc).

Since the only evidence to claim an extragalactic origin for FRBs has been the anomalously high DM, some models also attempted to explain the excess DM as a part of the model, thus allowing FRBs to be Galactic. All FRBs observed to date have been detected with single dish radio telescopes, for which the localization is of order arcminutes, insufficient to obtain an unambiguous association with any object. To date, no independent information about their redshift, environment, and source could be obtained due to the lack of an accurate localization of FRBs. ? attempted to identify the host of FRB 150418 on the basis of a fading radio source in the field that was localized to a  $z = 0.492$  galaxy. However, later work identified the radio source as a variable active galactic nucleus (AGN) that may not be related to the source (????).

Repeated radio bursts were observed from the location of the Arecibo-detected FRB Search Algorithm (?), with the same DM as the first detection, indicating a common source. As discussed by ?, it is unclear whether the repetition makes FRB Search Algorithm unique among known FRBs, or whether radio telescopes other than Arecibo lack the sensitivity to readily detect repeat bursts from other known FRBs.

? used the Karl G. Jansky Very Large Array (VLA) to directly localize the repeated bursts from FRB Search Algorithm with 100-mas precision and reported an unresolved, persistent radio source and an extended optical counterpart at the location with a chance coincidence probability of  $\approx 3 \times 10^{-4}$  — the first unambiguous identification of multi-wavelength counterparts to FRBs. Independently, ? used the European VLBI Network (EVN) to localize the bursts and the persistent

source and showed that both are co-located within  $\sim 12$  milliarcseconds.

Here we report a new algorithm to search FRBs .

## 2. BASICS OF INCOHERENT DEDISPERSION

The dispersion of the electromagnetic wave pulse cause a delay in arrival time at frequency  $\nu$  compared with the reference frequency  $\nu_0$ , which is given by :

$$\Delta t(\nu) = -D(\nu^{-2} - \nu_0^{-2}) \quad (1)$$

where  $D$  is the dispersion measure times a dispersion constant. Thus , We may model a burst with a very short intrinsic width as :

$$I(t, \nu) = I_0(\nu) \delta_D(t - t_s - \frac{D}{\nu^2}) \quad (2)$$

Where  $\delta D$  is the Dirac delta function,  $t_s$  marks the signal starting time for infinitely high frequency. If the bandwidth is small, we can approximate

$$\frac{D}{\nu^2} \approx \frac{D}{\nu_0^2} (1 - 2 \frac{\nu - \nu_0}{\nu_0})$$

denote  $\Delta \nu \equiv \nu - \nu_0$ , and assume that the spectrum is not too steep such that within the observing band the signal is constant, then

$$\begin{aligned} I(t, \nu) &\approx I_0 \delta_D(t - t_s - \frac{D}{\nu_0^2} (1 - 2 \frac{\Delta \nu}{\nu_0})) \\ &= I_0 \delta_D(t - t_0 + \frac{2D}{\nu_0^3} \Delta \nu) \end{aligned} \quad (3)$$

where  $t_0$  is the arrival time of the signal at thre reference frequency  $\nu_0$ .

Now consider an integral of this signal between frequency  $\nu_1$  and  $\nu_2$  , the signal strength would be

$$s = \int d\nu \int dt I(t, \nu) = (\nu_2 - \nu_1) I_0 = I_0 B \quad (4)$$

Where  $B = \nu_2 - \nu_1$  is the bandwidth. Now consider the noise. Suppose the data is digitized with time interval  $\delta t$  and frequency channel bandwidth  $\delta \nu$ . For the incoherent dedispersion, the signal within each time interval and frequency channel is

$$I_n = \frac{2kT_{sys}}{A_{eff} \sqrt{\delta \nu \delta t}} \quad (5)$$

Suppose we are observing between  $\nu_1, \nu_2$  with a total of  $N_\nu$  channels, and processing a time interval  $T = N_t \delta t$  where  $T \geq \Delta t(\nu_1) - \Delta t(\nu_2)$ , i.e. the whole of the dispersed signal is within the data frame.

For incoherent dedispersion, in the absence of the pulse signal, the whole read out of the data frame is given by

$$n = \int d\nu \int dt I_n = \frac{2kT_{sys}}{A_{\text{eff}}} \frac{(\nu_2 - \nu_1)T}{\sqrt{\delta\nu\delta t}} \quad (6)$$

$$= \frac{2kT_{sys}}{A_{\text{eff}}} B^{1/2} T^{1/2} N_\nu^{1/2} N_t^{1/2}$$

So the raw signal to noise ratio is given

$$\text{SNR}_{\text{raw}} = \frac{I_0 A_{\text{eff}}}{2kT_{sys}} \left( \frac{B}{N_\nu N_t T} \right)^{1/2} \quad (7)$$

In a perfect incoherent dedispersion, we sum up all the signal, which is still given by  $s$ . However, we compare it with the noise in the same dedispersion  $\nu - t$  track, not the whole data frame. The noise along the same track is given by

$$n = \int d\nu \int dt I_n \delta_D(t - t_0 + \frac{2D}{\nu_0^3} \Delta\nu) = B I_n \quad (8)$$

Then

$$\text{SNR}_{\text{opt}} = \frac{I_0}{I_N} = \frac{I_0 A_{\text{eff}}}{2kT_{sys}} \left( \frac{BT}{N_\nu N_t} \right)^{1/2} \quad (9)$$

Now consider a pulse of finite width. We replace the Dirac  $\delta$  function by a Gaussian function with the same normalization

$$\delta_D(t - t') \rightarrow g(t - t') \equiv \frac{1}{(2\pi)^{1/2}\sigma} \exp\left[-\frac{(t - t')^2}{2\sigma^2}\right] \quad (10)$$

If the pulse intrinsic width  $\sigma > \delta t$ , then in a dedispersion along the track only the part of the signal within one time bin would be included, which gives

$$\int_{-\delta t}^{+\delta t} d\Delta t \frac{1}{\sqrt{2\pi}\sigma} e^{-\Delta t^2/2\sigma^2} = \text{erf}\left(\frac{\delta t}{\sqrt{2}\sigma}\right) \approx \sqrt{\frac{2}{\pi}} \frac{\delta t}{\sigma} \quad (11)$$

Where the last holds for the case  $\delta t \ll \sigma$ , so in this case

$$s = I_0 B \sqrt{\frac{2}{\pi}} \frac{\delta t}{\sigma} \quad (12)$$

While the noise is still given by Eq.(8), so in this case

$$\text{SNR}_{\text{fin}} = \frac{I_0}{I_n} = \frac{I_0 A_{\text{eff}}}{2kT_{sys}} \left( \frac{BT}{N_t N_\nu} \right)^{1/2} \sqrt{\frac{2}{\pi}} \frac{\delta t}{\sigma} \quad (13)$$

### 3. IMPLEMENTED 2DFFT ON BURST SEARCH

Assuming data output from Transient Incoherent Search backend are in  $(f, t)$  format with size  $[N_{ch}, N_{tsamp}]$ . We could get the signal line are showing up as a curve line which are complied with relationship of  $f^{-2} \sim t$  in raw data map from eq. (1). As the form of curve after 2D-FFT is much more complex than a straight line. Hence we take the 2D-FFT on  $(f^{-2}, t)$  map. In order to get  $(f^{-2}, t)$  map, we use interpolation along the frequency axis in  $(f, t)$  map. The  $(f^{-2}, t)$  map still has shape of  $[N_{ch}, N_{tsamp}]$ , in this case total information could get conservation.

From eq.(1), define  $k_1 = -\frac{1}{D}$ . We could rewrite eq.(1) as

$$f^{-2} = k_1 t + b \quad (14)$$

where  $b$  is decided by start time. Apply Fourier pair:  $(f^{-2}, t) \sim (v, u)$ , Then process 2D FFT on eq.(14) :

$$\begin{aligned} & \int \int \delta(k_1 t + b - f^{-2}) e^{-i2\pi(ut + v f^{-2})} dt df^{-2} \\ &= \delta(u + k_1 v) \cdot e^{-i2\pi vb} \end{aligned} \quad (15)$$

In  $(v, u)$  map, Signal line format has been changed into  $v = -k_1^{-1}u$  with slope  $k_2 = -\frac{1}{k_1} = -D$ , where  $D = DM \cdot 4.15 \times 10^{-6} \text{ms} \cdot \text{MHz}^2 \cdot \text{pc}^{-1} \cdot \text{cm}^3$ . Considered unit of  $f^{-2}$  and  $t$  axis after FFT will become  $[\max(f^{-2}) - \min(f^{-2})]^{-1}$  and  $T^{-1}$ . Actually DM we got from slope  $k_2$  is:

$$DM = -\frac{1}{C} \cdot \frac{T}{\max(f^{-2}) - \min(f^{-2})} \cdot k_2 \quad (16)$$

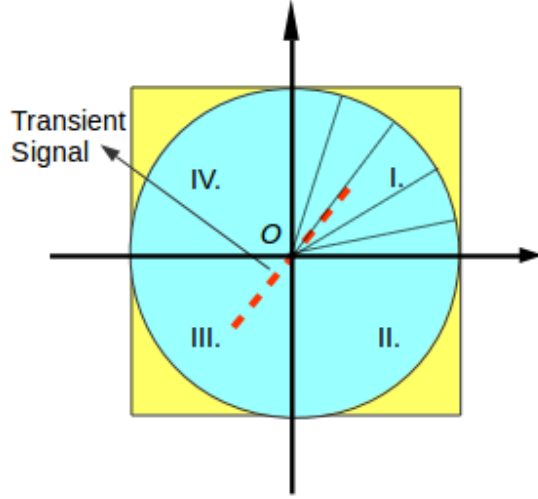
And the  $b$  comes to module factor in  $e^{-i2\pi vb}$ . It is still straight but perpendicular to previous straight. Furthermore, wherever the signal arise in raw data map, it always go cross the center of 2D-FFT map. Take advantage of these property, we could search transient signal on 2D-FFT map along specific angle.

For the phase term  $e^{-i2\pi vb}$ , it will modulate the signal intensity monotonically along straight line of 2D-FFT map. if we sum along straight line directly, we might not get the highest signal noise ratio. An effective and feasible method is to take a second FFT along straight line, then whole signal will turn into a spot. The whole process will take 4 steps to accomplish, we called them : Re-bin, 2D-FFT, Polar transform, 1D-FFT. Data after these process called map with process suffix separately, e.g. data after Re-bin Re-bin map.

#### 3.1. polar coordinate transform

As DM always bigger than zero, so  $k_2$  is always positive. It indicate signal after 2D-FFT is a straight line

which will only appear in 1/2 of 2DFFT map. For example, Fig.1 shows a signal line location after 2DFFT, it won't show up in quadrant II and IV, but only quadrant I and III. nevertheless quadrant I and III are conjugate to each other, we can only take 1 of them.



**Figure 1.** Signal on 2DFFT map

For purpose of search transient on 2D-FFT map, we need trace every slope of line which go cross center. It's easier to get each straight which pass through center from parameter radius and angle coordinate  $(r, \theta)$ . Thus it's better to take a coordinate transform. In Fig. 1, If we make use of quadrant I, we can take map center as origin  $O$ , and horizontal axis as original axis, then each line go cross center will have radius and angle information.

As tiny scale before FFT will decide large structure after FFT. Taking care of direction of FFT, Signal length in 2D-FFT map depend on width of signal line on re-bin map. Similarly, For polarization coordinates transform, the angle resolution could get from the length of signal line on re-bin map. Note width and length of signal before 2D-FFT is  $w_s$  and  $l_s$ , the length and width of signal after 2D-FFT will be  $l_{FFT} = 1/w_s$  and  $w_{FFT} = 1/l_s$  separately. Dimension of pixel need to be considered when actually process. Thus It's not necessary to take the whole data of quadrant I but pixels who's radius value smaller than  $l_{FFT}$ . Furthermore, if  $DM$  range are already set up, the boundary angle of slope  $[\theta_{DM_{min}}, \theta_{DM_{max}}]$  are also been decided according to Eq 16. Thus pixel who's angle of slope are beyond boundary could be cast through.

There are a lot of ways to take polar coordinate transform. But here we are taking interpolation which might

be more smooth. Interpolation algorithm are showed on Algorithm I.

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**Algorithm 1** The Interpolation Algorithm

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Input: Data after FFT denote in  $\mathcal{F}(f^{-2}, t)$  whose shape assume to be  $[N_{chan}, N_{samp}]$ ;  $DM$  range that observer want to search; Reasonable width of pulse:  $w_s$ , Generally take minimum width value from FRB already known.  
Output: Polar coordinate data denote in  $\mathcal{P}(r, \theta)$ . Shape of data is  $[N_r, N_\theta]$ .

Calculate  $\theta$  boundary and  $r$  range from given

**for** iteration  $i = 1$  to  $i = \log_2 N_f$  **do**

**for**  $f_0$  in the range  $[f_{min}, f_{max}]$  with steps  $2^i \delta_f$  **do**

$$f_2 = f_0 + 2^i \delta_f$$

$$f_1 = \frac{f_2 - f_0}{2}$$

$$C_{f_2, f_0} = \frac{f_1^{-2} - f_0^{-2}}{f_2^{-2} - f_0^{-2}}$$

$$\Delta t_{max}(i, f_0) = N_\Delta \frac{f_0^{-2} - (f_0 + 2^i \delta_f)^{-2}}{f_{min}^{-2} - f_{max}^{-2}}$$

**for**  $\Delta t$  in the range  $[0, \Delta t_{max}(i, f_0)]$  **do**

**for**  $t_0$  in range  $[C_{f_2, f_0} \Delta t, N_t]$  **do**

$$t_1 = t_0 - C_{f_2, f_0} \Delta t$$

$$A_{f_0}^{f_2}(t_0, \Delta t) = A_{f_0}^{f_1}(t_0, t_0 - t_1) + A_{f_1}^{f_2}(t_1, t_1 - t_2)$$

**end for**

**for**  $t_0$  in the range  $[0, C_{f_2, f_0} \Delta t]$  **do**

$$A_{f_0}^{f_2}(t_0, \Delta t) = A_{f_0}^{f_1}(t_0, C_{f_2, f_0} \Delta t)$$

**end for**

**end for**

**end for**

**end for**

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After polar coordinate transform, signal line will exist at some exact angle  $\theta$ . As shows in right top of Fig 4.

### 3.2. Turn signal line into spot

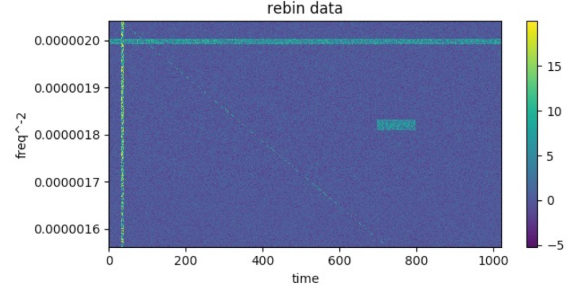
As we discussed before, the phase term  $e^{-i2\pi vb}$  could disturb the signal. Since phase term is monotonically and data are complex number, if we integrate along radius directly, signal intensity will be blended. We also can't take absolute value then sum, due to noise will be amplified. A reasonable method is to take another FFT along radius axis, so that the influence of phase term will be eliminated. After this we could get Signal Noise Ratio by

$$SNR = \frac{Max\ Value}{std}$$

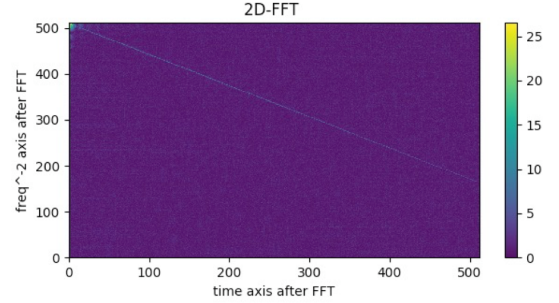
When we know where the highest SNR is, we can get the angle of it, finally calculate the  $DM$  Value from Eq.(16). The entire procedure are showed by Fig4 The Data are generated by SIGPROC and parameter are simulated from TianLai Array FRB backend request which Time resolution is 1 millisecond, Band width is 100 MHz and central Frequency is 750 Mhz, with 1024 Frequency Channels.

### 3.3. Advantage on RFI removing

There are 2 sorts of regular RFI: At certain frequency last long time, At certain time stamp but with large bandwidth, corresponding to horizontal and vertical line separately in image of Re-bin data. After 2D FFT, they will rotate 90°, but all of them go through center no matter what frequency or time stamp they are. Therefore, Regular type of RFI could be removed simply by discarding data after 2D FFT at horizontal and vertical line that go cross center. An example could be seen from Fig. 2.



(a) Add RFI manually on Re-bin map



(b) RFI are removed on 2D FFT map

**Figure 2.** Plot (a) shows Re-bin map which are add 3 RFI manually: Time domain and frequency domain and short bad data area. Seeing from Plot (b), RFI are removed clearly.

## 4. DETECTION OF OBSERVED FRB DATA

Observed FRB data are tested through this algorithm.

## 5. COMPUTE COMPLEXITY AND BENCHMARK

### 5.1. Compute Complexity

In 2D-FFT algorithm, The most time consuming step is 2D-FFT Compared with some Transients algorithm like *BruteForce*, *Tree*,

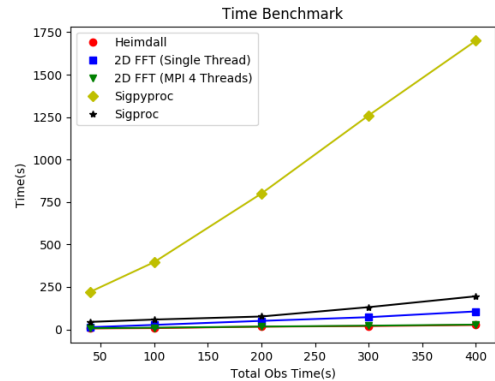
*TREE*

*BRUTE FORCE*

*FDMT*

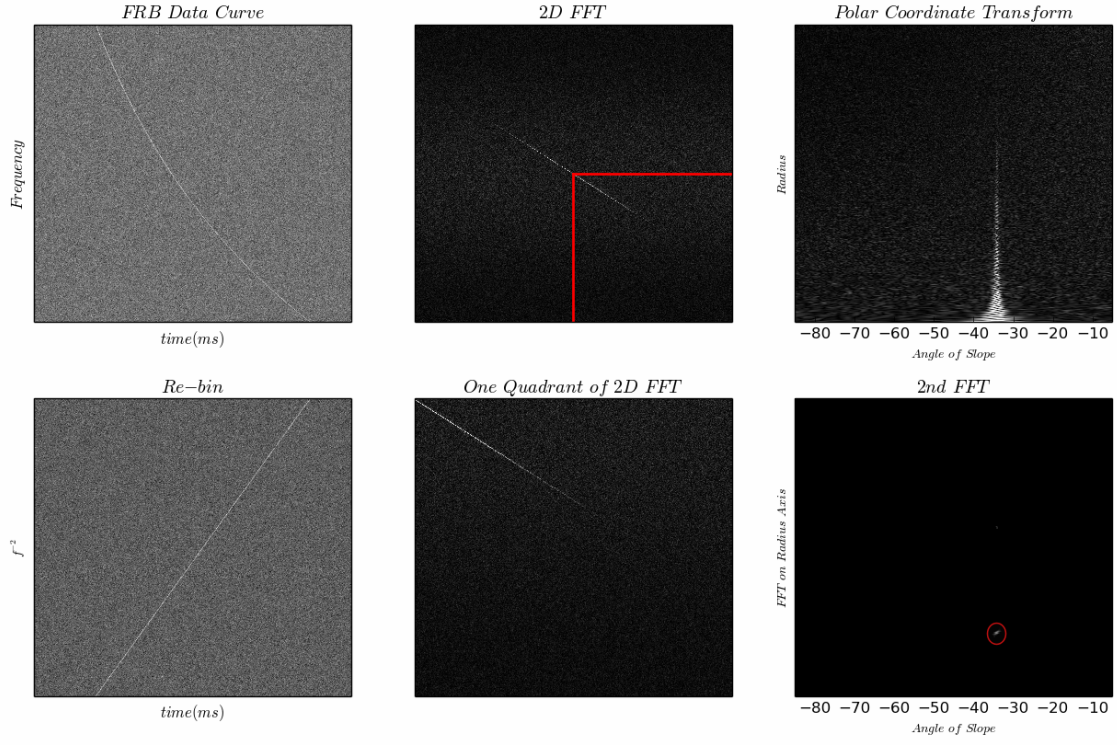
*2DFFT*

### 5.2. Benchmark



**Figure 3.** Benchmark of Transient search software: Sigproc, Sigpyproc, Heimdall, 2DFFT

## REFERENCES



**Figure 4.** The whole process of 2DFFT algorithm. Left top is Raw data of FRB data curve in  $f(t)$  form which are follow Eq(1). Left bottom is Re-bin process on Raw data, after this process curve in the Left top will come to a straight line in  $f^{-2}(t)$  form. Mid top is Re-bin Data after 2D FFT. Straight line in Left bottom turn into a straight line that rotate  $90^\circ$  and go through center. As discussed in Sec 3.1, we could only take one quadrant data. Here we take data inside red line area of Mid top. One quadrant data are showed in Mid bottom. In Mid bottom image, Left top point is taken as origin and top horizontal line as origin axis, Then calculate the radius and angle of slope of each pixel and change this image into polar coordinate image of  $(radius, angle)$  form as showed in Right top. As phase term influence, interference texture could be found on 2D FFT image. Then final step is doing 1D FFT along radius axis on polar coordinate data, then entire signal line will converge to several spots as showed in Right bottom.

## REFERENCES

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