Transpose of a madrix A is denoted by AT Cols of AT are rows of A.  $\frac{EX}{2} \begin{bmatrix} 1 & 2 & 3 \end{bmatrix}^{T} = \begin{bmatrix} 1 & 4 \\ 2 & 5 \end{bmatrix}, \quad (A^{T})_{ij} = A_{ji}$ (A+B)T = AT+BT to see this of AB

(AX)T first.  $(AT')^{T} = (AT)^{-1} = T = AA^{-1}$   $(ABC)^{T} = CTBTAT$   $T = T^{T} = (AA^{-1})^{T} = (A^{-1})^{T} A^{T}$ In particular: A = LDU, AT = UTDTLT must be (AT)

Note: if xiy are col. vectors then the dot product (inner product) xoy can be written as! xTy = xoy  $\begin{bmatrix} \\ \\ \\ \\ \\ \\ \end{bmatrix} = x \cdot y$  $(Ax)y = (Ax)Ty = xTATy = xT(ATy) = x \cdot ATy.$ 

Symmetrice matrices Sis symmetric if ST = S, Sij = Sji Ex. [13], [10] Juverse of a symm. nettoix is symmetric:  $(S^{-1})^T = (S^T)^{-1} = S^{-1}$ For every madrix A, the products AAT ATA are symmetric  $(AA^T)^T = (A^T)^T A^T = AA^T.$ 

$$S = \begin{bmatrix} 1 & u & 5 \\ u & 2 & 6 \\ 3 & R_{3} \rightarrow R_{3} - 5R_{1} \end{bmatrix} \begin{bmatrix} 1 & u & 5 \\ 0 & -14 & -14 \\ 0 & -14 & -22 \end{bmatrix} \xrightarrow{R_{3} \rightarrow R_{3} - R_{1}} \begin{bmatrix} 1 & u & 5 \\ 0 & -14 & -14 \\ 0 & -14 & -22 \end{bmatrix} \xrightarrow{R_{3} \rightarrow R_{3} - SR_{1}} \begin{bmatrix} 1 & u & 5 \\ 0 & -14 & -22 \end{bmatrix} \xrightarrow{R_{3} \rightarrow R_{3} - R_{2}} \begin{bmatrix} 1 & u & 5 \\ 0 & -14 & -22 \end{bmatrix} \xrightarrow{R_{3} \rightarrow R_{3} - R_{2}} \begin{bmatrix} 1 & u & 5 \\ 0 & -14 & -22 \end{bmatrix} \xrightarrow{R_{3} \rightarrow R_{3} - R_{2}} \begin{bmatrix} 1 & u & 5 \\ 0 & -14 & -22 \end{bmatrix} \xrightarrow{R_{3} \rightarrow R_{3} - R_{2}} \begin{bmatrix} 1 & u & 5 \\ 0 & -14 & -22 \end{bmatrix} \xrightarrow{R_{3} \rightarrow R_{3} - R_{2}} \begin{bmatrix} 1 & u & 5 \\ 0 & -14 & -22 \end{bmatrix} \xrightarrow{R_{3} \rightarrow R_{3} - R_{3}} \begin{bmatrix} 1 & u & 5 \\ 0 & -14 & -22 \end{bmatrix} \xrightarrow{R_{3} \rightarrow R_{3} - R_{3}} \begin{bmatrix} 1 & u & 5 \\ 0 & -14 & -22 \end{bmatrix} \xrightarrow{R_{3} \rightarrow R_{3} - R_{3}} \xrightarrow{R_{3} \rightarrow R_{3}} \begin{bmatrix} 1 & u & 5 \\ 0 & -14 & -22 \end{bmatrix} \xrightarrow{R_{3} \rightarrow R_{3} - R_{3}} \xrightarrow{R_{3} \rightarrow R_{3}} \xrightarrow{R_$$

Why kis harnens? For an invertible A, of A=LDU where Los lower trang with I's on the dieg, uis upper trang, with 1's on the diag, hen such decomp. is unique! A= LDU= L1 D1 U1  $I = L'_1 L = D_1 u_1 u'_1 D_1 \longrightarrow u_1 = u$ So Lower Lorans. Di=D

L=Li

L=Li

L=Li

L=D

S = (L) D(J) SO LIUT and UILT S= ST = LUT DTZT =(4)P(T) To find LDU decomp. A a symm. S: i) Do row elimination to find DU (D dieg., Unpper triang with 1's on the dieg.) 2) L is automatically = UT For symm. matrices, instead of LDU-decount., we usually say LDLT-decomp-

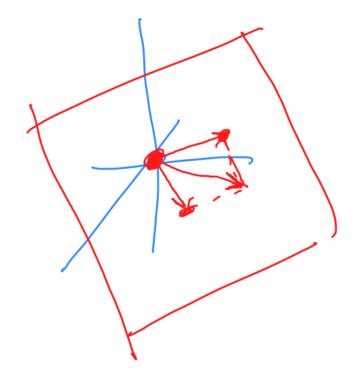
Not all invertible matrices have an Lu-decomp.! Ex. [0 1 2 ] [0 0 ] = P · Lo all swaps first: PA = LU · do all swaps afterwards: A = LPU what Plook like? P= [1]

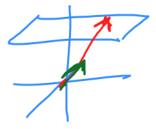
P is called a permutation matrix. feauture: P = PT.

Why do we want LU-decomp-? A=LU solve Ax= b  $\mathcal{L}(\mathcal{U} \times) = 6$ 1) solve Ly 25, get some y=c 2) solve Ux=contraugular, easy to solve

Vector spaces and subspaces A real vector space is a set of elements (called vectors) with rules for vector addition and for multiplication by a real number. Ex. M vector sp. of 2x2 real matrices F vector sp. of all real functions f(x). O,Z vector sp. that consists only of the zero rector sp. of all col-vectors with components.

## Ex. A plane through 10,0,0)





Def A subspace of a vector space is a set of vectors (including 0) that satisfies the two regs: If o, w are vectors in the subspace, cany real number then (i) vtw is in the subspace (ii) co is in the subspace. In short: linear combinations stay in the subspace. Ex. Make c=-1 not a subspace

(10,5)+(-6,-6)=(4,-1) (10,5)+(-6,-6)=(4,-1) (10,5)+(-6,-6)=(4,-1) (10,5)+(-6,-6)=(4,-1)

All possible subspaces of R?!

L line through 10,0,0)

P plane through (0,0,0)

R3 whole space

D zero subspace