

TENSOR FIELDS ON MANIFOLDS

PAG.1

def.: A C^∞ -covariant tensor field of order τ on a C^∞ -manifold is a function

$$\Phi: M \ni p \mapsto \phi_p \in \mathcal{T}(T_p M)$$

such that $\forall X_1, \dots, X_\tau$ C^∞ -vector fields on an open subset $U \subset M$ then

$\Phi(X_1, \dots, X_\tau): U \rightarrow \mathbb{R}$ is a C^∞ -function

$$\mathcal{T}(M) := \left\{ \begin{array}{l} \text{C}^\infty \text{-covariant vector fields of order } \tau \\ \text{on } M \end{array} \right\}$$

Examples:

• $\tau = 1$: covector

• $\tau = 2$: bilinear forms

Rmk: A covariant tensor field of order τ $\Phi \in \mathcal{T}(M)$ is $C^\infty(M)$ -linear in each variable:

If $f \in C^\infty(M)$:

$$\Phi(X_1, \dots, fX_i, \dots, X_\tau) = f\Phi(X_1, \dots, X_i, \dots, X_\tau)$$

because Φ_p is \mathbb{R} -linear $\forall p \in M$.

Recall: V vector space $\rightsquigarrow \Phi: V \times V \times \dots \times V \rightarrow \mathbb{R}$
is determined by its components

If (U, φ) coordinate neighborhood &
 E_1, \dots, E_n coordinate frames

$\Rightarrow \underbrace{\Phi(E_{j_1}, \dots, E_{j_r})}_{\text{Components of } \Phi}$ determine Φ

FACTS / Exercises:

- ① $\mathcal{T}(M)$ is a vector space over \mathbb{R} Def.
- ② Let $F: M \rightarrow N$ be C^∞ -map of manifolds. Then
 each C^∞ -covariant tensor field Φ on N
 determines a C^∞ -covariant tensor field $F^*\Phi$
 on M by the formula:

$$(F^*\Phi)_p(X_{1p}, \dots, X_{np}) = \Phi_p(F_*(X_{1p}), \dots, F_*(X_{np}))$$
- The map $F^*: \mathcal{T}(N) \rightarrow \mathcal{T}(M)$ is linear
 & takes

symmetric tensors	to	symmetric
alternating		alternating

 tensors.

- ③ $d: \mathcal{T}(M) \rightarrow \mathcal{T}(M)$ are defined in the
 $f: \mathcal{T}(M) \rightarrow \mathcal{T}(M)$ same way as
 $M = V$

Similarly,

$$(1) \Delta^2 = \Delta ; \quad \mathcal{J}^2 = \mathcal{J}$$

$$(2) \Delta(\tau^*(M)) = \tilde{\Delta}(M) \quad \& \quad \mathcal{J}(\tau^*(M)) = \tilde{\Sigma}(M)$$

$$(3) \begin{aligned} \phi \text{ alternating} &\Leftrightarrow \Delta\phi = \phi \\ \text{symmetric} &\Leftrightarrow \mathcal{J}\phi = \phi \end{aligned}$$

(4*) If $F: M \rightarrow N$ is C^∞ -mapping

$\Rightarrow \Delta$ and \mathcal{J} commute w.r.t. $F^*: \tau^*(N) \rightarrow \tau^*(M)$

multiplication of tensor fields

If $\varphi \in \tau^*(M)$ then $\varphi \otimes \psi$ can be defined as well:

$$\psi \in \tau^*(M) \quad (\varphi \otimes \psi)_p := \varphi_p \otimes \psi_p \in \tau^{r+s}(T_p M)$$

↑ defines a tensor field $\in C^\infty$!

we need to check in local coordinates:

$$(\varphi \otimes \psi)(E_{i_1}, \dots, E_{i_{r+s}}) = \underbrace{\varphi(E_{i_1}, \dots, E_{i_r})}_{C^\infty} \cdot \underbrace{\psi(E_{i_{r+1}}, \dots, E_{i_{r+s}})}_{C^\infty}$$

↓
product of C^∞ -functions
 $\in C^\infty$!

Thm: The mapping $\tau^*(M) \times \tau^*(M) \rightarrow \tau^{r+s}(M)$ bilinear & associative.
 If w^1, \dots, w^n is a basis of $\tau^*(M)$ then every element of $\tau^*(M)$ is a linear combination w.r.t. C^∞ -coefficients

of $\{\omega^{i_1} \otimes \dots \otimes \omega^{i_n}\}_{1 \leq i_1, \dots, i_n \leq n}$

If $F: N \rightarrow M$ is a C^∞ -mapping, $\varphi \in \mathcal{T}^*(M)$, $\psi \in \mathcal{T}^*(N)$

$$\Rightarrow F^*(\varphi \otimes \psi) = F^*(\varphi) \otimes F^*(\psi) \quad \text{tensor fields}$$

proof: at each point.

+
result when $M = V$ \square

~~Recall~~ $M \subset \mathbb{R}^n$ with coordinate chart

~~and globally defined basis e_1, \dots, e_n~~

~~Proof~~

$$E_1, \dots, E_n \text{ coordinate frame} \rightarrow E_i = \theta^{-1}_*(\frac{\partial}{\partial x^i}) \quad (*)$$

$\omega^1, \dots, \omega^n$ duals

\omega^i = \theta^*(dx^i)

Corollary: $(U, \theta) \subset M$ coordinate neighbourhood

Each $\varphi \in \mathcal{T}^*(U)$ has a unique expression of the form

$$\varphi = \sum_{i_1} \dots \sum_{i_n} a_{i_1 \dots i_n} \omega^{i_1} \otimes \dots \otimes \omega^{i_n}$$

where at each point of U , ~~the components~~

$a_{i_1 \dots i_n} = \varphi(E_{i_1}, \dots, E_{i_n})$ are the components

of φ in the basis $\{\omega^{i_1} \otimes \dots \otimes \omega^{i_n}\}$ are $C^\infty(U)$.

~~Proof:~~ proof: apply them here

$$E_i = \theta^{-1}_*(\frac{\partial}{\partial x^i}) \quad \omega^i = \theta^*(dx^i) \quad (*)$$

IMPORTANT

EXAMPLE M manifold $\theta \in \Lambda^k(M)$

$U \subset M$ open subset $i: U \rightarrow M$ inclusion

\Rightarrow ~~$\circ\circ\circ\circ\circ\circ\circ$~~ $i^*: \Lambda^k M \rightarrow \Lambda^k U$

$$\theta \mapsto i^* \theta =: \theta|_U$$

(U, φ) coordinate neighborhood

$\varphi(q) = (x^1(q), \dots, x^n(q))$ coordinate functions on U

\downarrow dx^1, \dots, dx^n linearly independent elements of $\Lambda^1 U$
 $\Leftrightarrow C^\infty$ -field of coframes on U

$\Lambda(U)$ generated by $1, \langle dx^1, \dots, dx^n \rangle$ as algebra
over $C^\infty(U)$

$$\bullet \Lambda^0(U) = C^\infty(U)$$

$$\bullet \Lambda^1(U) = \langle dx^1, \dots, dx^n \rangle$$

\Rightarrow locally every k -form θ on M has a unique repres.
on U of the form:

$$\theta_U = \sum_{1 \leq i_1 < \dots < i_k \leq n} a_{i_1 \dots i_k} dx^{i_1} \wedge \dots \wedge dx^{i_k}$$

$$\text{wt } a_{i_1 \dots i_k} \in C^\infty(U)$$

~~$\circ\circ\circ\circ\circ\circ\circ$~~

$$= \sum_{\substack{\text{all} \\ i_1, \dots, i_k}} \frac{1}{k!} b_{i_1 \dots i_k} dx^{i_1} \wedge \dots \wedge dx^{i_k}$$

(repetition included)

$U \subset M$ open set

E_1, \dots, E_n field of frames

{ dual basis

$\omega^1, \dots, \omega^n$ $\omega^i(E_j) = \delta_j^i$ coframes

(U, φ) $\varphi(q) = (x^1(q), \dots, x^n(q))$

$$\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n}$$

$$dx^1, \dots, dx^n$$

The exterior algebra on manifolds

def: An alternating covariant tensor field of order \geq on M will be called an exterior differential form of degree \geq (\geq -form)

$$\tilde{\Lambda}^*(M) := \left\{ \text{ \geq -forms on } M \right\} \subset \overset{\text{subspace}}{\tilde{\tau}^*(M)}$$

Thm:

let $\Lambda(M)$ denote the vector space over \mathbb{R} of all exterior differential forms. Then for

$\varphi \in \tilde{\Lambda}^*(M)$ the formula

$\varphi \in \tilde{\Lambda}^s(M)$

$(\varphi \wedge \psi)_p := \varphi_p \wedge \psi_p$ defines an associative product

$$\text{wt } (\varphi \wedge \psi) = (-1)^{rs} \cdot \varphi \wedge \psi$$

Furthermore, $(\tilde{\Lambda}(M), \wedge)$ is an algebra over \mathbb{R} .

(2) If $f \in C^\infty(M)$ then $(f\varphi) \wedge \psi = f(\varphi \wedge \psi)$
 $= \varphi \wedge (f\psi)$.

(3) If $\omega^1, \dots, \omega^n$ is a field of coframes on M

$\Rightarrow \left\{ \omega^{i_1} \wedge \dots \wedge \omega^{i_r} \right\}_{1 \leq i_1 < \dots < i_r \leq n}$ is a basis of $\tilde{\Lambda}^r(M)$.

Theorem:

If $F: M \rightarrow N$ is a C^∞ -mapping of manifolds
 $\Rightarrow F^*: \Lambda(N) \rightarrow \Lambda(M)$ is an algebra homomorphism.

$\Lambda(M)$ ~~is~~ exterior algebra on M
algebra of differential forms on M

ORIENTED VECTOR SPACE

V vector space $\dim V = n$

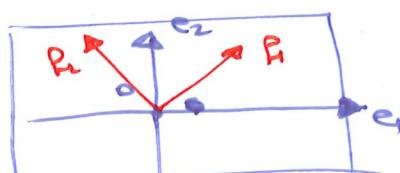
def: ~~open~~ Two bases $\{e_1, \dots, e_n\}$ & $\{p_1, \dots, p_n\}$ have the same orientation if $\det(d_i^j) > 0$ where $p_i = \sum_{j=1}^n d_i^j e_j$

Rmk: This is an equivalence relation on $\{\text{all bases of } V\}$ w/ 2 equivalence classes

def: An orientation on V is the choice of one equivalence class $\{e_1, \dots, e_n\}$. All basis w/ the same orientation of V are positively oriented.

$(V, [e_1, \dots, e_n])$ oriented vector space

EX. $V = \mathbb{R}^2$ $\{e_1, e_2\}$ canonical basis
 $e_1(1, 0) \quad e_2(0, 1)$



$\{p_1 = (1, 1); p_2 = (-1, 1)\}$ same orientation

$\{\mathbb{R}^2, \{(-1, 0); (0, 1)\}\}$ opposite orientation

We can express the same concept using $\Lambda^n V$

Recall $\dim \Lambda^n V = \binom{n}{n} = 1$

\Rightarrow every non-zero n-form is a basis for $\Lambda^n V$

Lemma:

let $\Omega \neq 0$ be an alternating covariant tensor on V of order $n = \dim V$. let e_1, \dots, e_n be a basis of V

Then for any set of vectors v_1, \dots, v_n w.t

$v_i = \sum \gamma_{i,j} e_j$ we have:

$$\Omega(v_1, \dots, v_n) = \det(\gamma_{j,i}) \Omega(e_1, \dots, e_n)$$

Expl.: up to a non-zero scalar ~~(det(γ_{j,i})~~ ($\Omega(e_1, \dots, e_n)$)

Ω coincides w.t the determinant of the components of its variables

Proof: multilinear

$$\Omega(v_1, \dots, v_n) \stackrel{\text{multilinear}}{=} \sum_{j_1, \dots, j_n} \alpha_1^{j_1} \dots \alpha_n^{j_n} \Omega(e_{j_1}, \dots, e_{j_n})$$

$$\stackrel{\text{antisymm.}}{\cong} \sum_{\sigma \in S_n} \text{sgn}(\sigma) \cdot \alpha_1^{\sigma(1)} \dots \alpha_n^{\sigma(n)} \Omega(e_1, \dots, e_n)$$

$$= \det(\alpha_i^j) \cdot \Omega(e_1, \dots, e_n) \quad \square$$

↗
definition
of determinant

Corollary: A non-vanishing $\Omega \in \Lambda^n V$ has the same sign on two bases if they have the same orientation.

proof:

Use the formula above \square

Fixing an orientation on $V \Leftrightarrow$ choosing $\Omega \neq 0$ on V

Corollary: Two forms Ω_1 and $\Omega_2 \in \Lambda^n V$ determine the same orientation on V iff

$$\Omega_1 = \lambda \cdot \Omega_2 \text{ wt } \lambda \in \mathbb{R}^+$$

~~they have the same orientation~~

proof: ~~The forms have the same sign~~

$$\dim \Lambda^n V = 1$$

$$\text{If } \Omega_1, \Omega_2 \neq 0 \Rightarrow \exists \lambda \in \mathbb{R}^* \quad \Omega_1 = \lambda \cdot \Omega_2$$

$\{v_1, \dots, v_n\}$ basis

$$\begin{aligned} \operatorname{sgn}(\Omega_1(v_1, \dots, v_n)) &= \lambda \cdot \operatorname{sgn}(\Omega_2(v_1, \dots, v_n)) \\ &= \text{iff. } \lambda > 0 \end{aligned}$$

(Two forms ~~have~~ determine the same orientation on all bases

\Leftrightarrow they have the same sign on all bases

Example :

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~~REVIEW~~

U vector space w/ $\Phi(v, w)$ positive definite inner product

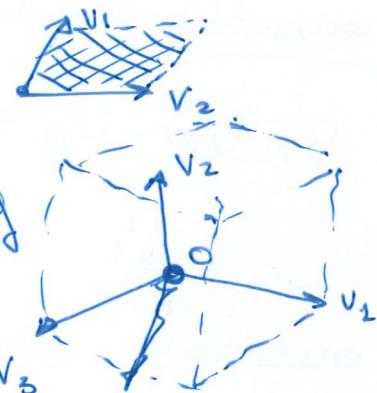
- Choose an orthonormal basis $\{e_1, \dots, e_n\}$ to determine its orientation.

- Choose Ω n-form w/ $\Omega(e_1, \dots, e_n) = +1$

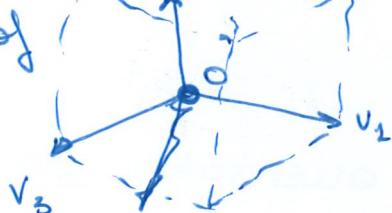
If $\{f_1, \dots, f_n\}$ is another orthonormal basis

$$\Rightarrow \Omega(f_1, \dots, f_n) = \det(\alpha_i^j) \cdot \Omega(e_1, \dots, e_n) \\ = \pm 1 \quad (\text{depending on orientation w/ respect to } \{e_1, \dots, e_n\})$$

n=2 : $\Omega(v_1, v_2) = \text{area of}$



n=3 : $\Omega(w_1, v_1, v_2) = \text{volume of}$



def: M manifold is orientable if it is possible to define a C^∞ n-form Ω on M which is not zero at ~~any point~~ any point. If such a form exists \Rightarrow M is oriented by the choice of Ω

Remark Example :

$(\mathbb{R}^n, \tilde{\Omega} = dx^1 \wedge \dots \wedge dx^n)$ natural orientation of \mathbb{R}^n

def: Let (M_1, Ω_1) oriented manifolds.
 (M_2, Ω_2)

\textcircled{F} $F: M_1 \rightarrow M_2$ orientation preserving if

$F^* \Omega_2 = \lambda \cdot \Omega_1$ wt $\lambda \in C_c^\infty: M \rightarrow \mathbb{R}^+$ positive function

def 2: M orientable if it can be covered wt

coherently oriented coordinate neighborhoods $\{U_\alpha, \varphi_\alpha\}$

that is, if $U_\alpha \cap U_\beta \neq \emptyset \Rightarrow \varphi_\alpha \circ \varphi_\beta^{-1}$ orientation-preserving

Thm: M orientable \Leftrightarrow def 2

proof:

Assume M orientable and choose $\Omega \in \Lambda^k M$ wt $\Omega \neq 0$
determines

Choose $\{U_\alpha, \varphi_\alpha\}$ covering of M ; wt local coordinates
 $x_\alpha^1, \dots, x_\alpha^n$ such that $\varphi_\alpha: U_\alpha \rightarrow \varphi_\alpha(U_\alpha) \subset (M, \Omega)$

$$(\varphi_\alpha^{-1})^* \Omega|_{U_\alpha} = \underbrace{\lambda_\alpha(x)}_{>0} dx_\alpha^1 \wedge \dots \wedge dx_\alpha^n \quad \text{wt } \lambda_\alpha > 0$$

Using previous lemma & corollary: if $U_\alpha \cap U_\beta \neq \emptyset$:

$$0 < \lambda_\alpha \det \left(\frac{\partial x_\alpha^i}{\partial x_\beta^j} \right) = \begin{pmatrix} dx_\alpha^i \\ dx_\beta^j \end{pmatrix} > 0 \text{ by hypothesis}$$

$$\Rightarrow \det \left(\frac{\partial x_\alpha^i}{\partial x_\beta^j} \right) > 0$$

\Rightarrow charts are coherently oriented.