

Perceptron Learning Algorithm

The perceptron is a simple supervised machine learning algorithm and one of the earliest neural network architectures. It was introduced by Rosenblatt in the late 1950s. A perceptron represents a binary linear classifier that maps a set of training examples (of d dimensional input vectors) onto binary output values using a $d - 1$ dimensional hyperplane. But Today, we will implement **Multi-Classes Perceptron Learning Algorithm Given:**

- dataset $\{(x^i, y^i)\}, i \in (1, M)$
- x^i is d dimension vector, $x^i = (x_1^i, \dots, x_d^i)$
- y^i is multi-class target variable $y^i \in \{0, 1, 2\}$

A perceptron is trained using gradient descent. The training algorithm has different steps. In the beginning (step 0) the model parameters are initialized. The other steps (see below) are repeated for a specified number of training iterations or until the parameters have converged.

Step0: Initial the weight vector and bias with zeros

Step1: Compute the linear combination of the input features and weight. $y_{pred}^i = \arg \max_k W_k * x^i + b$

Step2: Compute the gradients for parameters W_k, b . **Derive the parameter update equation Here (5 points)**

#

TODO: Derive you answer hear

#

Using svm loss function

$$L = \sum_{i=1}^N \max(0, W_i * x_i + b - W_{y_i} * x_i - b) = \sum_{i=1}^N \max(0, W_i * x_i - W_{y_i} * x_i)$$

$$\frac{dL}{dW_i} = \begin{cases} 0 & L \leq 0 \text{ or other} \\ x & \text{if } i \text{ is the wrong predicted label} \\ -x & \text{if } i \text{ is the right label} \end{cases}$$

$$\frac{dL}{db} = 0$$

In []:

```
from sklearn import datasets
import numpy as np
from sklearn.model_selection import train_test_split
import matplotlib.pyplot as plt
import random

np.random.seed(0)
random.seed(0)
```

In []:

```
iris = datasets.load_iris()
X = iris.data
print(type(X))
y = iris.target
y = np.array(y)
print('X_Shape:', X.shape)
print('y_Shape:', y.shape)
print('Label Space:', np.unique(y))
```

```
<class 'numpy.ndarray'>
X_Shape: (150, 4)
y_Shape: (150,)
Label Space: [0 1 2]
```

In []:

```
## split the training set and test set
X_train,X_test,y_train,y_test=train_test_split(X,y,test_size=0.3, random_state=0
)
print('X_train_Shape:', X_train.shape)
print('X_test_Shape:', X_test.shape)
print('y_train_Shape:', y_train.shape)
print('y_test_Shape:', y_test.shape)
print(type(y_train))
```

```
X_train_Shape: (105, 4)
X_test_Shape: (45, 4)
y_train_Shape: (105,)
y_test_Shape: (45,)
<class 'numpy.ndarray'>
```

In []:

```

class MultiClsPLA(object):

    ## We recommend to absorb the bias into weight. W = [w, b]

    def __init__(self, X_train, y_train, X_test, y_test, lr, num_epoch, weight_d
imension, num_cls):
        super(MultiClsPLA, self).__init__()
        self.X_train = X_train
        self.y_train = y_train
        self.X_test = X_test
        self.y_test = y_test
        self.weight = self.initial_weight(weight_dimension, num_cls)
        self.sample_mean = np.mean(self.X_train, 0)
        self.sample_std = np.std(self.X_train, 0)
        self.num_epoch = num_epoch
        self.lr = lr
        self.total_acc_train = []
        self.total_acc_tst = []

    def initial_weight(self, weight_dimension, num_cls):
        #####
        ## TODO: Initialize the weight with ##
        ## small std and zero mean gaussian ##
        #####
        weight = np.zeros((num_cls, weight_dimension + 1 ))
        return weight

    def data_preprocessing(self, data):
        #####
        ## TODO: Normlize the data ##
        #####
        norm_data = (data - self.sample_mean) / self.sample_std
        return norm_data

    def train_step(self, X_train, y_train, shuffle_idx):
        np.random.shuffle(shuffle_idx)
        X_train = X_train[shuffle_idx]
        y_train = y_train[shuffle_idx]
        train_acc = 0

        #####
        ## TODO: to implement the training process ##
        ## and update the weights ##
        #####
        dw = np.zeros_like(self.weight)

        for i in range(X_train.shape[0]):
            scores = np.dot(self.weight, X_train[i].transpose())
            predicted_label = np.argmax(scores)
            if (predicted_label != y_train[i]):
                dw[predicted_label] += self.lr * X_train[i]
                dw[y_train[i]] -= self.lr * X_train[i]
            else:
                train_acc += 1
        self.weight -= dw
        train_acc /= X_train.shape[0]
        return train_acc

    def test_step(self, X_test, y_test):

```

```

num_sample = X_test.shape[0]
test_acc = 0

#####
##  TODO: Evaluate the test set and    ##
##  return the test acc                ##
#####
for i in range(num_sample):
    scores = np.dot(self.weight, X_test[i].transpose())
    predicted_label = np.argmax(scores)
    if (predicted_label == y_test[i]):
        test_acc += 1

test_acc /= X_test.shape[0]
return test_acc

def train(self):

    self.X_train = self.data_preprocessing(data=self.X_train)
    self.X_test = self.data_preprocessing(data=self.X_test)

    num_sample = self.X_train.shape[0]

    #####
    ### TODO: In order to absorb the bias into weights ###
    ### we need to modify the input data.                ###
    ### So You need to transform the input data          ###
    #####
    self.X_train = np.concatenate((self.X_train, np.ones((self.X_train.shape
[0],1))), axis=1)
    self.X_test = np.concatenate((self.X_test, np.ones((self.X_test.shape[0
],1))), axis=1)

    shuffle_index = np.array(range(0, num_sample))
    for epoch in range(self.num_epoch):
        training_acc = self.train_step(X_train=self.X_train, y_train=self.y_
train, shuffle_idx=shuffle_index)
        tst_acc = self.test_step(X_test=self.X_test, y_test=self.y_test)
        self.total_acc_train.append(training_acc)
        self.total_acc_tst.append(tst_acc)
        print('epoch:', epoch, 'traing_acc:%.3f'%training_acc, 'tst_acc:%.3
f'%tst_acc)

    def vis_acc_curve(self):
        train_acc = np.array(self.total_acc_train)
        tst_acc = np.array(self.total_acc_tst)
        plt.plot(train_acc)
        plt.plot(tst_acc)
        plt.legend(['train_acc', 'tst_acc'])
        plt.show()

```

In []:

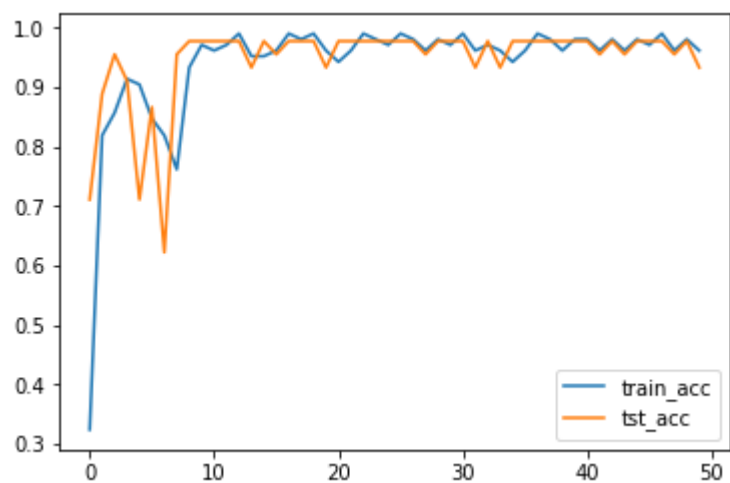
```
np.random.seed(0)
random.seed(0)

PLA = MultiClsPLA(X_train, y_train, X_test, y_test, 0.001, 50, 4, 3)

PLA.train()
PLA.vis_acc_curve()

#####
### TODO:
### 1. You need to import the model and pass some parameters.
### 2. Then training the model with some epoches.
### 3. Visualize the training acc and test acc versus epoches
```

```
epoch: 0 traing_acc:0.324 tst_acc:0.711
epoch: 1 traing_acc:0.819 tst_acc:0.889
epoch: 2 traing_acc:0.857 tst_acc:0.956
epoch: 3 traing_acc:0.914 tst_acc:0.911
epoch: 4 traing_acc:0.905 tst_acc:0.711
epoch: 5 traing_acc:0.848 tst_acc:0.867
epoch: 6 traing_acc:0.819 tst_acc:0.622
epoch: 7 traing_acc:0.762 tst_acc:0.956
epoch: 8 traing_acc:0.933 tst_acc:0.978
epoch: 9 traing_acc:0.971 tst_acc:0.978
epoch: 10 traing_acc:0.962 tst_acc:0.978
epoch: 11 traing_acc:0.971 tst_acc:0.978
epoch: 12 traing_acc:0.990 tst_acc:0.978
epoch: 13 traing_acc:0.952 tst_acc:0.933
epoch: 14 traing_acc:0.952 tst_acc:0.978
epoch: 15 traing_acc:0.962 tst_acc:0.956
epoch: 16 traing_acc:0.990 tst_acc:0.978
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epoch: 47 traing_acc:0.962 tst_acc:0.956
epoch: 48 traing_acc:0.981 tst_acc:0.978
epoch: 49 traing_acc:0.962 tst_acc:0.933
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In []: