

Connection
To Hubo

HuboWalkPanel

CommandBiped ParamsQuad ParamsBalance Parameters

Ach Networking

Connect

Disconnect

IP Address

192

168

0

201

Status: Not Connected

Control Method

☒ GUI

☐ Joystick

Launch Joystick

Status: Off

ZMP Commands

☐ Walk Continuously

Walk Distance:

0.20

Turn-in-place Angle:

0.50

Max Steps:

10

Turn Radius:

5.00

Turn

Forward

Turn

Left

Stop

Right

Backward

Go Quad

Go Biped

Static Commands

Height

COM-X Offset (m)

0.0000

Balance

Off

ZMP State

Result: ZMP_RUNNING

Walk Mode: BIPED_MODE

Walk
Commands

Balance
Commands