

Probability and Applied Statistics Formula Sheet
Alexis Petito

Definition 1.1 – Mean of n Measured Responses.

The mean of a sample n measured responses.

$$\bar{y} = \frac{1}{n} \sum_{i=1}^n y_i$$

Definition 1.2 – Variance of Sample Measurements

The variance of a sample of measurements.

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (y_i - \bar{y})^2$$

Definition 1.3 – Standard Deviation of Sample Measurements

Standard deviation of a sample measurements.

$$s = \sqrt{s^2}$$

Definition 2.7 - Permutations

Ordered arrangement of r distinct objects called a *permutation*.

$$P_r^n = \frac{n!}{(n-r)!}$$

Definition 2.8 - Combinations

The number of *combinations* of n objects taken r at a time

$$C_r^n = \frac{P_r^n}{r!} = \frac{n!}{r! (n-r)!}$$

Theorem 2.3 – n Objects into K Groups

The number of ways partitioning n distinct objects into k distinct groups containing n_i objects, respectively where each object appears in exactly one group and $\sum_{i=1}^k n_i = n$, is

$$N = \binom{n}{n_1 n_2 \dots n_k} = \frac{n!}{n_1! n_2! \dots n_k!}$$

Definition 2.9 – A Given B

The *conditional probability of an event A*, given that an event B has occurred, is equal to

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

Definition 2.10 – Determining Independence

Two events A and B are said to be *independent* if any one of the following holds:

$$P(A|B) = P(A)$$

$$P(B|A) = P(B)$$

$$P(A \cap B) = P(A)P(B)$$

Otherwise, the events are said to be *dependent*.

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Theorem 2.5 - The Multiplicative Law of Probability

The probability of the intersection of two events A and B is

$$P(A \cap B) = P(A)P(B|A) \\ = P(B)P(A|B)$$

If A and B are independent, then

$$P(A \cap B) = P(A)P(B)$$

Theorem 2.6 - The Additive Law of Probability

The probability of the union of two events A and B is

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

If A and B are mutually exclusive events, $P(A \cap B) = 0$ and

$$P(A \cup B) = P(A) + P(B)$$

Theorem 2.7 – Determine A from \bar{A}

If A is an event, then

$$P(A) = 1 - P(\bar{A})$$

Definition 2.11 – Partition of S

For some positive integer k , let the sets $B_1, B_2, B_3, \dots, B_k$ be such that

1. $S = B_1 \cup B_2 \cup \dots \cup B_k$
2. $B_i \cap B_j = \emptyset$, for $i \neq j$

Then the collection of sets $\{B_1, B_2, \dots, B_k\}$ is said to be a *partition* of S

Theorem 2.8

Assume that $\{B_1, B_2, \dots, B_k\}$ is a partition of S (see definition 2.11) such that $P(B_i) > 0$, for $i = 1, 2, \dots, k$. Then for any event A

$$P(A) = \sum_{i=1}^k P(A|B_i)P(B_i)$$

Theorem 2.9 - Bayes' Rule

Assume that $\{B_1, B_2, \dots, B_k\}$ is a partition of S (see definition 2.11) such that $P(B_i) > 0$, for $i = 1, 2, \dots, k$. Then

$$P(B_j|A) = \frac{P(A|B_j)P(B_j)}{\sum_{i=1}^k P(A|B_i)P(B_i)}$$

Bayes' Theorem

Bayes Theorem: For two events A and B in sample space S, with $P(A) > 0$ and $P(B) > 0$,

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

If $0 < P(B) < 1$, we may write by the *Theorem of Total Probability*.

$$P(B|A) = \frac{P(A|B)P(B)}{P(A|B)P(B) + P(A|\bar{B})P(\bar{B})}$$

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Conditional Probability

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

Probability Mass Function

$$p(y) = P(Y = y)$$

Expected Value

Let Y be a discrete random variable with the probability function $p(y)$. Then the *expected value* of Y , $E(Y)$, is defined to be,

$$E(Y) = \sum_{y \in Y} yp(y)$$

Theorem 3.2 – Binomial Distribution

Let Y be a discrete random variable with probability function $p(y)$ and $g(y)$ be a real-valued function of Y . Then the expected value of $g(Y)$

Is given by,

$$E[g(Y)] = \sum_{all\ y} g(y)p(y)$$

Definition 3.5 – Expected Variance of a Random Variable

If Y is a random variable with mean $E(Y) = \mu$, the variance of a random variable Y is defined to be the expected value of $(Y - \mu)^2$. That is,

$$V(Y) = E[(Y - \mu)^2]$$

The Standard Deviation of Y

$$\sqrt{V[Y]}$$

Binomial Distribution

$$p(y) = P(Y = y) = \binom{n}{y} p^y q^{n-y} \quad y \in \{0, 1, 2, \dots, n\}$$

Theorem 3.7 – Binomial Distribution Expected Value and Variance

Let Y be a binomial random variable based on n trials and success probability p . Then,

$$\mu = E(Y) = np \text{ (Mean/Expected)}$$

$$\sigma^2 = V(Y) = npq \text{ (Standard Deviation)}$$

Geometric Distribution

$$p(y) = P(Y = y) = q^{y-1}p$$

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Extra Geometric Distribution Formulas

A success occurs on or before the n th trial.

$$P(X \leq n) = 1 - (1 - p)^n$$

A success occurs before the n th trial.

$$P(X < n) = 1 - (1 - p)^{n-1}$$

A success occurs on or after the n th trial.

$$P(X \geq n) = (1 - p)^{n-1}$$

A success occurs after the n th trial.

$$P(X > n) = (1 - p)^n$$

Theorem 3.8 – Geometric Distribution Expected Value and Variance

If Y is a random variable with geometric distribution,

$$\mu = E(Y) = \frac{1}{p} \text{ and } \sigma^2 = V(Y) = \frac{1 - p}{p^2}$$

Hypergeometric Distribution

$$p(y) = P(Y = y) = P(A) = \frac{n_A}{n_S} = \frac{\binom{r}{y} \times \binom{N-r}{n-y}}{\binom{N}{n}}$$

Theorem 3.10 – Hypergeometric Distribution Expected Value and Variance

If Y is a random variable with hypergeometric distribution,

$$\mu = E(Y) = \frac{nr}{N} \text{ and } \sigma^2 = V(Y) = n \left(\frac{r}{N} \right) \left(\frac{N-r}{N} \right) \left(\frac{N-n}{N-1} \right)$$

Negative Binomial Distribution

$$p(y) = \binom{y-1}{r-1} p^r q^{y-r}$$

Theorem 3.9 – Negative Binomial Distribution Expected Value and Variance.

If Y is a random variable with negative binomial distribution,

$$\mu = E(Y) = \frac{r}{p} \text{ and } \sigma^2 = V(Y) = \left(\frac{r(1-p)}{p^2} \right)$$

Definition 3.11 – Poisson Distribution

A random variable Y is said to have *Poisson probability distribution* if and only if,

$$p(y) = \frac{\lambda^y}{y!} e^{-\lambda}, \quad y = 0, 1, 2, \dots, \lambda > 0.$$

Theorem 3.11 – Poisson Distribution Expected Value and Variance

If Y is a random variable possessing a Poisson Distribution with parameter λ , then

$$\mu = E(Y) = \lambda \text{ and } \sigma^2 = V(Y) = \lambda$$

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Theorem 3.4 – Chebyshev’s Theorem

Let Y be a random variable with mean μ and finite variance σ^2 . Then, for any constant $k > 0$,

$$P(|Y - \mu| < k\sigma) \geq 1 - \frac{1}{k^2} \text{ or } P(|Y - \mu| \geq k\sigma) \leq \frac{1}{k^2}$$