

**Probability and Applied Statistics Formula Sheet**  
**Alexis Petito**

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**Definition 1.1 – Mean of n Measured Responses.**

The mean of a sample  $n$  measured responses.

$$\bar{y} = \frac{1}{n} \sum_{i=1}^n y_i$$

**Definition 1.2 – Variance of Sample Measurements**

The variance of a sample of measurements.

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (y_i - \bar{y})^2$$

**Definition 1.3 – Standard Deviation of Sample Measurements**

Standard deviation of a sample measurements.

$$s = \sqrt{s^2}$$

**Definition 2.7 - Permutations**

Ordered arrangement of  $r$  distinct objects called a *permutation*.

$$P_r^n = \frac{n!}{(n-r)!}$$

**Definition 2.8 - Combinations**

The number of *combinations* of  $n$  objects taken  $r$  at a time

$$C_r^n = \frac{P_r^n}{r!} = \frac{n!}{r! (n-r)!}$$

**Theorem 2.3 – n Objects into K Groups**

The number of ways partitioning  $n$  distinct objects into  $k$  distinct groups containing  $n_i$  objects, respectively where each object appears in exactly one group and  $\sum_{i=1}^k n_i = n$ , is

$$N = \binom{n}{n_1 n_2 \dots n_k} = \frac{n!}{n_1! n_2! \dots n_k!}$$

**Definition 2.9 – A Given B**

The *conditional probability of an event A*, given that an event B has occurred, is equal to

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

**Definition 2.10 – Determining Independence**

Two events A and B are said to be *independent* if any one of the following holds:

$$P(A|B) = P(A)$$

$$P(B|A) = P(B)$$

$$P(A \cap B) = P(A)P(B)$$

Otherwise, the events are said to be *dependent*.

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### Theorem 2.5 - The Multiplicative Law of Probability

The probability of the intersection of two events A and B is

$$P(A \cap B) = P(A)P(B|A)$$

$$= P(B)P(A|B)$$

If A and B are independent, then

$$P(A \cap B) = P(A)P(B)$$

### Theorem 2.6 - The Additive Law of Probability

The probability of the union of two events A and B is

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

If A and B are mutually exclusive events,  $P(A \cap B) = 0$  and

$$P(A \cup B) = P(A) + P(B)$$

### Theorem 2.7 – Determine A from $\bar{A}$

If A is an event, then

$$P(A) = 1 - P(\bar{A})$$

### Definition 2.11 – Partition of S

For some positive integer  $k$ , let the sets  $B_1, B_2, B_3, \dots, B_k$  be such that

1.  $S = B_1 \cup B_2 \cup \dots \cup B_k$
2.  $B_i \cap B_j = \emptyset$ , for  $i \neq j$

Then the collection of sets  $\{B_1, B_2, \dots, B_k\}$  is said to be a *partition* of S

### Theorem 2.8

Assume that  $\{B_1, B_2, \dots, B_k\}$  is a partition of S (see definition 2.11) such that  $P(B_i) > 0$ , for  $i = 1, 2, \dots, k$ . Then for any event A

$$P(A) = \sum_{i=1}^k P(A|B_i)P(B_i)$$

### Theorem 2.9 - Bayes' Rule

Assume that  $\{B_1, B_2, \dots, B_k\}$  is a partition of S (see definition 2.11) such that  $P(B_i) > 0$ , for  $i = 1, 2, \dots, k$ . Then

$$P(B_j|A) = \frac{P(A|B_j)P(B_j)}{\sum_{i=1}^k P(A|B_i)P(B_i)}$$

### Bayes' Theorem

Bayes Theorem: For two events A and B in sample space S, with  $P(A) > 0$  and  $P(B) > 0$ ,

$$P(A|B) = \frac{P(A|B)P(B)}{P(A)}$$

If  $0 < P(B) < 1$ , we may write by the *Theorem of Total Probability*.

$$P(B|A) = \frac{P(A|B)P(B)}{P(A|B)P(B) + P(A|\bar{B})P(\bar{B})}$$

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### Conditional Probability

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

### Probability Mass Function

$$p(y) = P(Y = y)$$

### Expected Value

Let  $Y$  be a discrete random variable with the probability function  $p(y)$ . Then the *expected value* of  $Y$ ,  $E(Y)$ , is defined to be,

$$E(Y) = \sum_{y \in Y} yp(y)$$

### Theorem 3.2 – Binomial Distribution

Let  $Y$  be a discrete random variable with probability function  $p(y)$  and  $g(y)$  be a real-valued function of  $Y$ . Then the expected value of  $g(Y)$

Is given by,

$$E[g(Y)] = \sum_{all\ y} g(y)p(y)$$

### Definition 3.5 – Expected Variance of a Random Variable

If  $Y$  is a random variable with mean  $E(Y) = \mu$ , the variance of a random variable  $Y$  is defined to be the expected value of  $(Y - \mu)^2$ . That is,

$$V(Y) = E[(Y - \mu)^2]$$

### The Standard Deviation of $Y$

$$\sqrt{V[Y]}$$

### Binomial Distribution

$$p(y) = P(Y = y) = \binom{n}{y} p^y q^{n-y} \quad y \in \{0, 1, 2, \dots, n\}$$

### Theorem 3.7 – Binomial Distribution Expected Value and Variance

Let  $Y$  be a binomial random variable based on  $n$  trials and success probability  $p$ . Then,

$$\mu = E(Y) = np \text{ (Mean/Expected)}$$

$$\sigma^2 = V(Y) = npq \text{ (Standard Deviation)}$$

### Geometric Distribution

$$p(y) = P(Y = y) = q^{y-1}p$$

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**Extra Geometric Distribution Formulas**

A success occurs on or before the  $n$ th trial.

$$P(X \leq n) = 1 - (1 - p)^n$$

A success occurs before the  $n$ th trial.

$$P(X < n) = 1 - (1 - p)^{n-1}$$

A success occurs on or after the  $n$ th trial.

$$P(X \geq n) = (1 - p)^{n-1}$$

A success occurs after the  $n$ th trial.

$$P(X > n) = (1 - p)^n$$

**Theorem 3.8 – Geometric Distribution Expected Value and Variance**

If  $Y$  is a random variable with geometric distribution,

$$\mu = E(Y) = \frac{1}{p} \text{ and } \sigma^2 = V(Y) = \frac{1 - p}{p^2}$$

**Hypergeometric Distribution**

$$p(y) = P(Y = y) = P(A) = \frac{n_A}{n_S} = \frac{\binom{r}{y} \times \binom{N-r}{n-y}}{\binom{N}{n}}$$

**Theorem 3.10 – Hypergeometric Distribution Expected Value and Variance**

If  $Y$  is a random variable with hypergeometric distribution,

$$\mu = E(Y) = \frac{nr}{N} \text{ and } \sigma^2 = V(Y) = n \left( \frac{r}{N} \right) \left( \frac{N-r}{N} \right) \left( \frac{N-n}{N-1} \right)$$

**Negative Binomial Distribution**

$$p(y) = \binom{y-1}{r-1} p^r q^{y-r}$$

**Theorem 3.9 – Negative Binomial Distribution Expected Value and Variance.**

If  $Y$  is a random variable with negative binomial distribution,

$$\mu = E(Y) = \frac{r}{p} \text{ and } \sigma^2 = V(Y) = \left( \frac{r(1-p)}{p^2} \right)$$

**Definition 3.11 – Poisson Distribution**

A random variable  $Y$  is said to have *Poisson probability distribution* if and only if,

$$p(y) = \frac{\lambda^y}{y!} e^{-\lambda}, \quad y = 0, 1, 2, \dots, \lambda > 0.$$

**Theorem 3.11 – Poisson Distribution Expected Value and Variance**

If  $Y$  is a random variable possessing a Poisson Distribution with parameter  $\lambda$ , then

$$\mu = E(Y) = \lambda \text{ and } \sigma^2 = V(Y) = \lambda$$

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**Theorem 3.4 – Chebyshev’s Theorem**

Let  $Y$  be a random variable with mean  $\mu$  and finite variance  $\sigma^2$ . Then, for any constant  $k > 0$ ,

$$P(|Y - \mu| < k\sigma) \geq 1 - \frac{1}{k^2} \text{ or } P(|Y - \mu| \geq k\sigma) \leq \frac{1}{k^2}$$