Overfitting Intuitions

Lecture 2: Over-fitting – the "enemy"

Why such *cheap* minimization algorithms ? (e.g. GD)

 \rightarrow Do we *really* want to minimize $J(\theta, X_{train})$ The **true objective:** obtain **good performance** on new (unseen) data, which are *different*, but *similar*

We want <u>"generalization"</u>

It's a very *ill-posed* problem!

- Example:
 - **Can we define** the probability distribution of the subspace of dog pictures, within the space of 100x100 pixels RGB pictures?
 - \rightarrow We can picture the space of 100x100 pixels RGB pictures. It's a 3.10⁴-dimensional hypercube, easy.
 - → Subspace of *dog pictures*: **no** (unthinkable-of manifold, and it makes no human sense to define this mathematically)
 - → We may just assume simple things, like, probably that manifold has a smaller *intrinsic dimension*. But it'll be difficult to measure, etc.
 - → so instead, we use **data**

Over-fitting intuitive definition

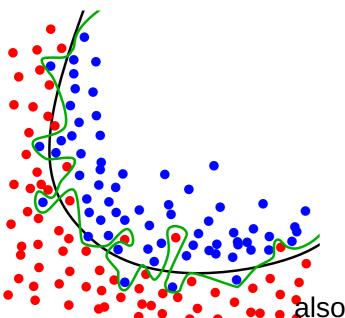
Reminder:

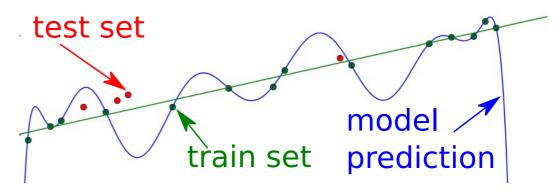
N points are always *exactly* interpolated by an (N-1)th-order polynomial.

→ Yes, but with **horrible over-fitting:**

Classification: Cover theorem states that N points are always linearly separable in N dimensions

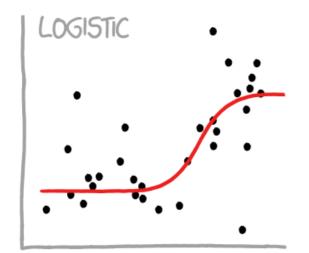
→ Same problem:





We want to do well...

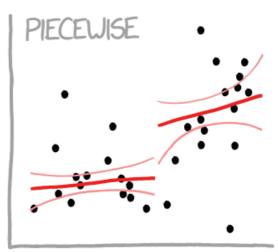
also on the *test set*!



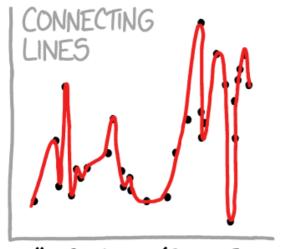
"I NEED TO CONNECT THESE TWO LINES, BUT MY FIRST IDEA DIDN'T HAVE ENOUGH MATH."



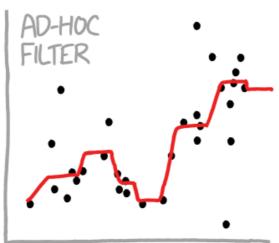
"LISTEN, SCIENCE IS HARD.
BUT I'M A SERIOUS
PERSON DOING MY BEST."



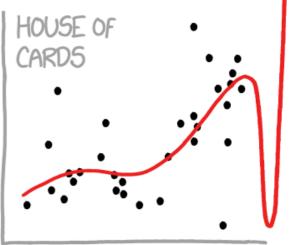
"I HAVE A THEORY, AND THIS IS THE ONLY DATA I COULD FIND."



"I CLICKED 'SMOOTH LINES' IN EXCEL."



"I HAD AN IDEA FOR HOW TO CLEAN UP THE DATA. WHAT DO YOU THINK?"



"AS YOU CAN SEE, THIS MODEL SMOOTHLY FITS THE- WAIT NO NO DON'T EXTEND IT AAAAAA!!"

Measuring the over-fitting: concept of *Test set*

Over-fitting: visually, in 2D, easy to see

→ but how to characterize it quantitatively?

With only N data points:

- We simulate the arrival of **new data** by setting aside some examples. N_{test}
- We **train** the model with the $N_{train} = N N_{test}$ examples (opimization of the parameters Θ)
- We **test** the model (measure performance) on the "new" data N_{test} (test: *model prediction* vs. *Ground Truth*)

Measuring the over-fitting: concept of *Test set*

- Few errors ≃ good performance
- The difference between
 - *train* set error
 - test set error

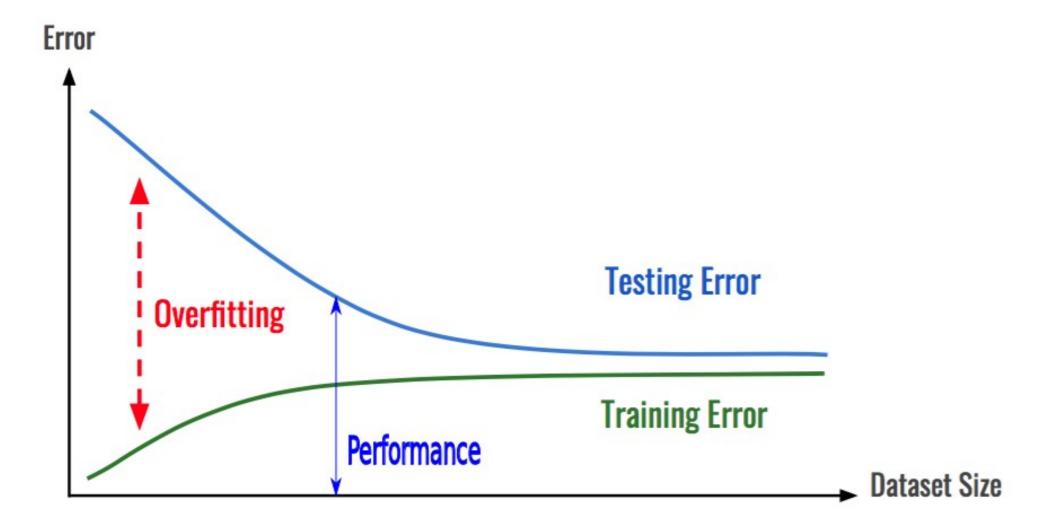
is <u>a</u> measure of over-fitting

- → Low overfitting = good generalization
- → High overfitting = bad generalization

Amount of overfitting ≠ performance

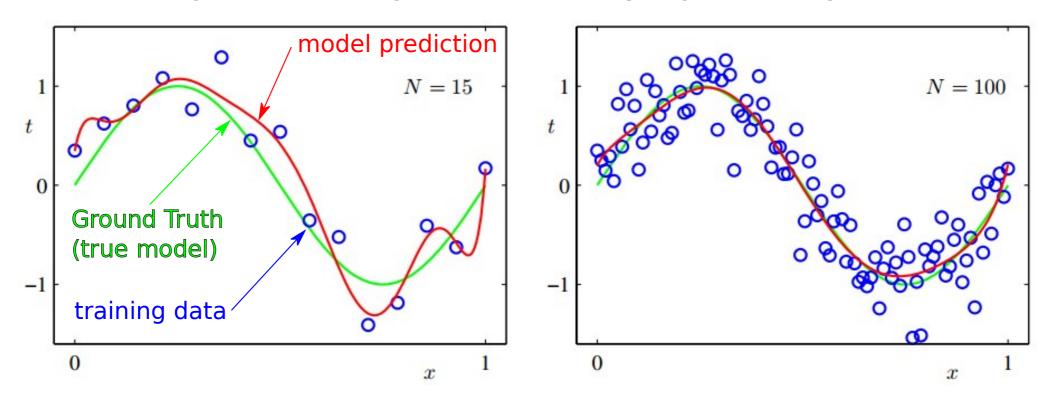
Overfit vs Train set size

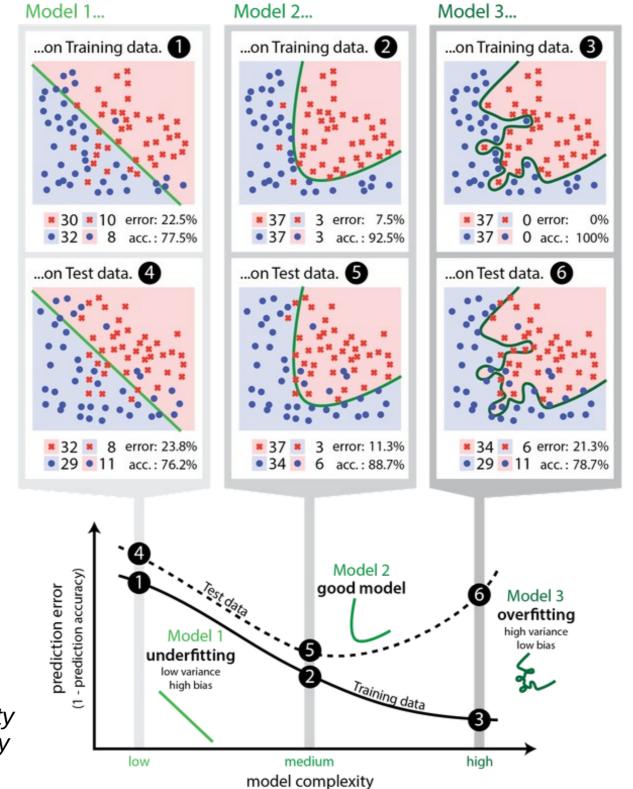
• For instance, set: $N_{test} = 0.2N, N_{train} = 0.8N$



Overfit vs Train set size

 Restrain overfitting by adding more training data (here, using a 9th order polynomial)





Model *complexity* = model *capacity*

Hypothesis Space

• Useful concept:

```
H = \{ f \mid f \text{ can be expressed by your model} \}
= \{ f_{\theta} \mid \theta \in \Theta \}
```

Concept of hyper-parameter

Not really a choice: Train set size Ntrain (quite fundamental)

→ use as much as available, + study the *learning curve*

Overfitting depends on many choices: the hyper-parameters μ

- Learning rate η $\mathbb{P}(heta_0)$
- Initialization of parameters
- Learning strategy (size m of the mini-batch for instance)
- **Stopping criterion** (iterative methods: *MaxIter* or *tolerance*)
- Pre-processing choices (standardization or not, etc)
- Model capacity (or complexity): not well defined. It's a bit of everything.
 Concretely: number of parameters (Cardinal of Θ), architecture, Kernel,...
 - \rightarrow Basically, everything that is not a parameter (a $\theta \in \Theta$) ... is a hyperparameter!
 - \rightarrow Let's optimize also these hyper-parameters μ !

Validation Set

If we also optimize the hyper-params, then we can also over-fit them !?!



Train set Train parameters (Hyper-param. fixed) $\mu = \mu_0$ Validation set Optimize hyper-param. $\mu \to \mu^*$ $\theta = \theta^*$ (Parameters fixed) Test set (single use!) (Hyper-param. fixed) $\mu = \mu^*$ (Parameters fixed)

→ measure performances

Over-fitting General things

How to improve performance?

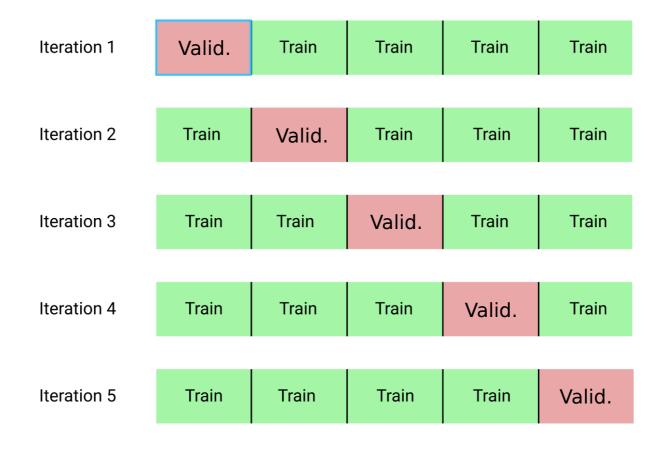
- Seeing a lot of overfitting?
 - → reduce the model complexity (try simpler models)
- Little to no overfit ?
 - → try more *expressive*, more *flexible* models

Searching the *global minimum* $J(\theta, X_{train})$.. or not ?

- → "best fit" possible but... on the *train set*!
- → in general, global min. = large over-fit.
- Ill-defined problem: what is generalizability?
 - → How to sample "the set of all 2D images showing a dog" ? → Generative Models. Quality ??
 - → Transfer Learning

a Cross-Validation K-fold CV

• Make K folds, e.g. K=5 train/validation splits



→ reduces the splitting-related noise

Another Cross-Validation Leave-one-out CV (LOO)

Def: Like K-fold but with $K=N_{train}$.

- Useful esp. for small data sets (reduce N_{train} by only 1 example)
- Reasonable only for small data sets (otherwise, too many computations)

Key concepts

- Generalization, over-fitting, under-fitting, performance
- The split : Train, validation, test
- Amount of overfitting ≠ performance
- Train set size
- Hyper-parameters
- Complexity ~ capacity ~ expressiveness
- Cross-Validation
- Curse of dimensionality

To go further: keywords

- I strongly encourage you to read :
 Bishop section 3.2 "Bias-Variance decomposition"
 It's very well explained and a quite basic argument no time to cover it now
- Basic stuff: *Hypothesis space*, finite vs infinite.
 - 1) **Double Descent**: *catastrophic overfitting* (without regul) happens esp. when N=P.
 - + there is an *implicit regularization* obtained by over-parametrization (when P>N, provided some simple conditions).
 - → see works of **Francis Bach**.
 - 2) A rather classic, finite-dim, finite set approach:
- Vapnik—Chervonenkis dimension (VC dimension)
- Probably approximately correct learning (PAC learning)
 - 3) Another kind of approach:

There are exact results for *random data sets* (some are physcists' or mathematicians works). More keywords: tensor PCA, planted solution, random constraint satisfaction problems (CSP), dynamic threshold (algorithmic threshold), Information Theoretic threshold (IT),

→ See works of **Gerard Ben-Arous, Lenka Zdeborova**, and others