

**1-4, 5**

By definition of  $\wedge$ :

$$(p - p_1) \wedge (p - p_2) \cdot (p - p_3) = \det(p - p_1, p - p_2, p - p_3)$$

Notice that  $p = p_1, p_2, p_3$  satisfy the equation since one of the vectors is zero and thus the determinant is zero. Since the det is a linear equation, the equation must be a plane or be a trivial equation (which describes all of  $\mathbb{R}^3$ ). The equation cannot be trivial however since  $p_1, p_2, p_3$  are not colinear

**1-4 6**

Consider any point satisfying the equation  $p = ut + p_0$  (where  $p_0 = (x_0, y_0, z_0)$ ). Plugging  $p$  into either plane equation yields

$$p \cdot v_i - d_i = u \cdot v_i t + p_0 \cdot v_i - d_i = (v_1 \wedge v_2) \cdot v_i + (p_0 \cdot v_i - d_i)$$

We have  $(v_1 \wedge v_2) \cdot v_i = 0$  and since  $p_0$  is a point in both planes,  $p_0$  satisfies the plane equation for both planes  $p_0 \cdot v_i - d_i = 0$ . Thus  $p \cdot v_i - d_i = 0$ , the line is the intersection of the planes

**1-4 10**

We have

$$\begin{pmatrix} u \cdot u & u \cdot v \\ u \cdot v & v \cdot v \end{pmatrix} = \begin{pmatrix} u_1 & u_2 \\ v_1 & v_2 \end{pmatrix} \begin{pmatrix} u_1 & v_1 \\ u_2 & v_2 \end{pmatrix}$$

Which is easily verified by multiplying out the matrices on the right  
The book establishes

$$\begin{vmatrix} u \cdot u & u \cdot v \\ u \cdot v & v \cdot v \end{vmatrix} = A^2$$

Thus since determinant is invariant by transposition

$$\begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} = \begin{vmatrix} u_1 & v_1 \\ u_2 & v_2 \end{vmatrix}$$

$$A^2 = \begin{vmatrix} u \cdot u & u \cdot v \\ u \cdot v & v \cdot v \end{vmatrix} = \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} \begin{vmatrix} u_1 & v_1 \\ u_2 & v_2 \end{vmatrix} = \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix}^2$$

**1-4 11a**

We have that  $|(u \wedge v) \cdot w| = \det(u, v, w)$ . It is a commonly known fact that the volume of the parallel pipet spanned by  $u, v, w$  is  $\det(u, v, w)$ . This can be geometrically established by noticing that  $|u \wedge v|$  is the area of the quadrilateral spanned by  $u, v$  and  $u \wedge v$  is the perpendicular vector to this quadrilateral. We have that the dot product of  $w$  with  $u \wedge v$  is

the length of the projection of  $w$  to  $u \wedge v$  multiplied by  $|u \wedge v|$  which is precisely the area of the parallel pipet

### 1-4 12

( $\Rightarrow$ ) If there exists  $u$  such that  $u \wedge v = w$ . We have that  $w \cdot v = (u \wedge v) \cdot v = \det(u, v, v) = 0$ . Thus  $v$  and  $w$  are perpendicular

( $\Leftarrow$ ) If  $w, v$  are perpendicular, define  $u = \frac{v \wedge w}{|v|^2}$ . Since  $u, v$  are perpendicular to  $w$ , we know that  $w, u \wedge v$  are colinear. Notice that (since  $u$  and  $v$  are perpendicular)  $|u \wedge v| = |u||v| = \frac{|w||v|^2}{|v|^2} = |w|$ . Thus  $w = \pm(u \wedge v)$ . By the right hand rule we have that  $w = u \wedge v$  since  $u = v \wedge w$ . This choice of  $u$  was unique

### 1-4 13

By the product rule for  $\wedge$ :

$$\frac{d}{dt}(u(t) \wedge v(t)) = u'(t) \wedge v(t) + u(t) \wedge v'(t)$$

By bilinearity of  $\wedge$ :

$$= a(u(t) \wedge v(t)) + b(v(t) \wedge v(t)) + c(u(t) \wedge u(t)) - a(u(t) \wedge v(t))$$

$v(t) \wedge v(t) = u(t) \wedge u(t) = 0$  yields

$$= a(u(t) \wedge v(t) - u(t) \wedge v(t)) = 0$$

Thus the derivative is zero for all  $t$  so  $u(t) \wedge v(t)$  is constant

### 1-5 1

(a) Calculating  $|\alpha'(s)|$  :

$$|\alpha'(s)| = \sqrt{\frac{a^2}{c^2} \sin^2 \frac{s}{c} + \frac{a^2}{c^2} \cos^2 \frac{s}{c} + \frac{b^2}{c^2}} = \sqrt{\frac{a^2(\sin^2 \frac{s}{c} + \cos^2 \frac{s}{c}) + b^2}{c^2}} = \sqrt{\frac{a^2 + b^2}{c^2}} = 1$$

Thus  $\alpha$  is parameterized by arclength

(b) Curvature is  $|\alpha''(s)|$ .

$$\kappa = |\alpha''(s)| = \sqrt{\frac{a^2}{c^4} \cos^2 \frac{s}{c} + \frac{a^2}{c^4} \sin^2 \frac{s}{c}} = \frac{a}{c^2}$$

Torsion is  $\tau = |\frac{d}{ds}(\alpha'(s) \wedge \frac{\alpha''(s)}{\kappa})|$ :

We have

$$\frac{\alpha''(s)}{\kappa} = (-\cos \frac{s}{c}, -\sin \frac{s}{c}, 0)$$

$$\alpha'(s) = (\frac{-a}{c} \sin \frac{s}{c}, \frac{a}{c} \cos \frac{s}{c}, \frac{b}{c})$$

$$\alpha' \wedge \frac{\alpha''}{\kappa} = (0, 0, \frac{a}{c} \sin^2 \frac{s}{c} + \frac{a}{c} \cos^2 \frac{s}{c}) = (0, 0, \frac{a}{c})$$

Thus

$$\tau(s) = 0$$

(c) We already found the binormal vector:

$$b(s) = \alpha' \wedge \frac{\alpha''}{\kappa} = (0, 0, \frac{a}{c})$$

We have that the plane is

$$0 = (p - \alpha(s)) \cdot b(s) = \frac{a}{c}(z - \frac{bs}{c})$$

(d) We have the normal vector is

$$n(s) = \frac{\alpha''(s)}{\kappa} = (-\cos \frac{s}{c}, -\sin \frac{s}{c}, 0)$$

Since the third component is zero,

$$n(s) \cdot e_3 = 0$$

so  $n(s)$  is always perpendicular to the  $z$  axis (meets the axis at an angle of  $\pi/2$ ).

we know the line  $tn(s) + \alpha(s)$  always intersects the  $z$  axis since we can choose  $t$  to be  $a$  and we get  $an(s) + \alpha(s) = (0, 0, \frac{bs}{c})$

(e) We know the tangent line direction vector is

$$t(s) = \alpha'(s) = (\frac{-a}{c} \sin \frac{s}{c}, \frac{a}{c} \cos \frac{s}{c}, \frac{b}{c})$$

We have that

$$t(s) \cdot e_3 = \frac{b}{c}$$

is constant, thus the angle between the two vectors is constant

## 1-5 2

From lecture and in the book we have the following identities

$$\alpha'(s) = t(s)$$

$$\alpha''(s) = \kappa(s)n(s)$$

$$\alpha'''(s) = \kappa'(s)n(s) + \kappa(s)n'(s)$$

$$n'(s) = -\tau(s)b(s) - \kappa(s)t(s)$$

So we have

$$-\frac{\alpha'(s) \wedge \alpha''(s) \cdot \alpha'''(s)}{|\kappa(s)|^2} = -\frac{\kappa(s)t(s) \wedge n(s) \cdot (\kappa'(s)n(s) + \kappa(s)n'(s))}{|\kappa(s)|^2}$$

$t(s) \wedge n(s) \cdot n(s) = 0$  so we have

$$= -\frac{\kappa(s)t(s) \wedge n(s) \cdot \kappa(s)n'(s)}{|\kappa(s)|^2} = -\frac{\kappa^2(s)(t(s) \wedge n(s)) \cdot (-\tau(s)b(s) - \kappa(s)t(s))}{|\kappa(s)|^2}$$

$t(s) \wedge n(s) \cdot t(s) = 0$  so

$$= \tau(s)t(s) \wedge n(s) \cdot b(s)$$

Since  $b(s)$  is defined as  $t(s) \wedge n(s)$  and the norm is 1, this yields

$$= \tau(s)b(s) \cdot b(s) = \tau(s)$$

#### 1-5 4

Letting  $\alpha(s)$  be the curve parameterized by arc length and  $p$  the point, there exists a scalar function  $c(s)$  where  $c(s)n(s) + \alpha(s) = p$ . Differentiating both sides yields,

$$c'(s)n(s) + c(s)n'(s) + \alpha'(s) = 0$$

We have the identity  $n' = -\kappa t - \tau b$

$$c'(s)n(s) + c(s)(-\kappa(s)t(s) - \tau(s)b(s)) + t(s) = 0$$

$$c'(s)n(s) + (-\kappa(s)c(s) + 1)t(s) - c(s)\tau(s)b(s) = 0$$

Notice that this is a sum of the linear independent vectors  $n, t, b$  equal to zero. Thus it must be the case that  $c'(s) = -\kappa(s)c(s) + 1 = c(s)\tau(s) = 0$ . This shows that  $\tau(s) = 0$  which means  $\alpha$  is contained in a plane (as we established in lecture). We have that  $c'(s) = 0$  so  $c(s)$  is constant and so since  $-\kappa(s)c(s) + 1$ ,  $\kappa(s)$  is constant, which we know means  $\alpha$  is contained in a circle

#### 1-5 5

(a) Letting  $p$  be the point, there exists a scalar function  $c(s)$  where  $c(s)t(s) + \alpha(s) = p$ . Differentiating yields

$$c'(s)t(s) + c(s)t'(s) + \alpha'(s) = 0$$

$$(c'(s) + 1)t(s) + c(s)\kappa(s)n(s) = 0$$

Since  $t, n$  are linearly independent,  $c'(s) + 1 = \kappa(s)c(s) = 0$ . Since  $c'(s) \neq 0$ , it must be the case that  $c(s) \neq 0$  so  $\kappa(s) = 0$ . Thus  $\alpha''(s) = 0$ , solving this differential equation yields  $\alpha(s) = c_1 t + c_0$  for some constants  $c_0, c_1$ . Thus  $\alpha$  is a line

(b) Not necessarily, consider the curve

$$\alpha(t) = (|t|, t, 0)$$

This curve is not contained in a line, yet the tangent line (when defined) crosses the origin

### 1-5 6

(a) By definition of  $|\cdot|$  and orthogonal transformations:  $|p(u)| = \sqrt{p(u) \cdot p(u)} = \sqrt{u \cdot u} = |u|$ . We have  $\cos(\theta_p)|p(u)||p(v)| = |p(u) \cdot p(v)| = |u \cdot v| = |u||v|\cos(\theta)$ . Since norms are invariant we get  $\cos(\theta_p) = \cos(\theta)$  since  $0 \leq \theta \leq \pi$  this implies  $\theta = \theta_p$

(b) Since  $p$  is linear, it suffices to show it is true for the basis  $e_1, e_2, e_3$  since we have  $p(v) = v_1p(e_1) + v_2p(e_2) + v_3p(e_3)$ . So

$$p(v) \wedge p(w) = \sum_{i,j \in [3]} v_i w_j p(e_i) \wedge p(e_j)$$

We have that since  $p(e_j) \cdot p(e_k) = e_j \cdot e_k$ , We have that  $p(e_1), p(e_2), p(e_3)$  are still all orthogonal to each other. Thus the vector product of two must be the other. (Not the negative of the other since the transformation is orientation preserving). Thus  $p(e_i) \wedge p(e_j) = p(e_k) = p(e_i \wedge e_j)$

(c) Since each of the described quantities is obtained by taking derivatives and norms of a parameterized curve, it suffices to show differentiation is invariant.

By Linearity we have

$$\begin{aligned} p\left(\frac{d}{ds}\alpha(s)\right) &= p(\alpha'_1(s)e_1 + \alpha'_2(s)e_2 + \alpha'_3(s)e_3) \\ &= p(\alpha'_1(s)e_1) + p(\alpha'_2(s)e_2) + p(\alpha'_3(s)e_3) = \alpha'_1(s)p(e_1) + \alpha'_2(s)p(e_2) + \alpha'_3(s)p(e_3) = \frac{d}{ds}p(\alpha(s)) \end{aligned}$$