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$A$  is continuous since its components are continuous functions. Given any point  $p \in S^2$  we can choose parametrizations  $x_1 : U_1 \subset \mathbb{R}^2 \rightarrow S^2$ ,  $x_2 : U_2 \subset \mathbb{R}^2 \rightarrow S^2$  such that  $p \in x_1(U_1)$ ,  $A(p) \in x_2(U_2)$ .

From class we established there are the following parametrizations we can choose from:

$$x_1, x_2 \in \{(\cos \theta \sin \varphi, \sin \theta \sin \varphi, \cos \varphi), (\cos \theta \sin \varphi + \pi, \sin \theta \sin \varphi + \pi, \cos \varphi + \pi), \\ (\cos \theta + \pi \sin \varphi, \sin \theta + \pi \sin \varphi, \cos \varphi) \dots \}$$

We must show that

$$x_2^{-1} \circ A \circ x_1$$

is differentiable at  $p$ . Notice that  $A = A^{-1}$  and thus by showing  $A$  is differentiable we have shown its inverse to be differentiable. Hence concluding  $A$  is a diffeomorphism.

It is clear this composition is differentiable since each component

$$x_2^{-1} \circ A \circ x_1(p) = (x_{2,1}^{-1}(-x_{1,1}(p_1)), x_{2,2}^{-1}(-x_{1,2}(p_2)), x_{2,3}^{-1}(-x_{1,3}(p_3)))$$

Is a composition of differentiable functions and thus differentiable regardless of choice of  $x_1, x_2$ .

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We have the diffeomorphism  $f : \mathbb{R}^2 \rightarrow P$  with  $f(x, y) = (x, y, z^2)$ . To establish  $f$  is a diffeomorphism, notice that  $f$  is also a parametrization. Thus the conditions of being a diffeomorphism rely on asking whether over any open set if

$$f^{-1} \circ f \circ \text{id}$$

is differentiable. This mapping is the identity mapping so clearly differentiable.

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The diffeomorphism  $f : S^2 \rightarrow E$  is defined by

$$f(x, y, z) = (ax, by, cz)$$

We have that this is a diffeomorphism since notice that for any parametrization  $x_1 : U \subset \mathbb{R}^2 \rightarrow S^2$  around a point  $p \in S^2$  we have a parametrization  $x_2 = f \circ x_1$  of  $E$  around  $f(p)$ . Thus we have

$$x_1^{-1} \circ f \circ x_2 = x_1^{-1} \circ f^{-1} \circ f \circ x_1 = \text{id}$$

is differentiable

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For diffeomorphism  $f : S_1 \rightarrow S_2$ , suppose we have the parameterizations around a point  $p \in S_1$  and  $f(p) \in S_2$

$$x_1 : U \subset \mathbb{R}^2 \rightarrow S_1, x_2 : V \subset \mathbb{R}^2 \rightarrow S_2$$

$$y_1 : U \subset \mathbb{R}^2 \rightarrow S_1, y_2 : V \subset \mathbb{R}^2 \rightarrow S_2$$

We need to show that if the parameterization with  $x_1, x_2$  establishes  $f$  to be differentiable then so does  $y_1, y_2$

We can use the change of Parameterization Theorem. Letting

$$W_1 = x_1(U) \cap y_1(U), W_2 = x_2(V) \cap y_2(V)$$

We have the diffeomorphisms  $h_1, h_2$

$$h_1 = x_1^{-1} \circ y_1 : y_1^{-1}(W_1) \rightarrow x_1^{-1}(W_1)$$

$$h_2 = x_2^{-1} \circ y_2 : y_2^{-1}(W_2) \rightarrow x_2^{-1}(W_2)$$

Notice that  $p \in W_1$  and  $f(p) \in W_2$  and thus when we restrict to the open set  $W_2$  such that

$$W_3 = x_1^{-1}(f^{-1}(W_2)) \cap y_1^{-1}(f^{-1}(W_2)) \subset W_1$$

$$y_2^{-1} \circ f \circ y_1|_{W_3} = h_2^{-1} \circ x_2^{-1} \circ f \circ x_1 \circ h_1$$

Thus we have that  $y_1, y_2$  establish  $f$  to be a diffeomorphism under this restriction since  $y_2^{-1} \circ f \circ y_1|_{W_3}$  is a composition of the diffeomorphic functions  $h_2^{-1}, x_2^{-1} \circ f \circ x_1, h_1$

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Checking the three conditions of an equivalence relation:

Reflexivity:

We have that the identity

$$\text{id} : S \rightarrow S$$

is a diffeomorphism and thus  $S \sim S$

Transitivity:

If we have the diffeomorphisms

$$f_1 : S_1 \rightarrow S_2, f_2 : S_2 \rightarrow S_3$$

Then it is the case that

$$f_3 = f_2 \circ f_1 : S_1 \rightarrow S_3$$

is a diffeomorphism. The reason for this is because for parameterizations

$$x_1 : U_1 \rightarrow S_1, x_2 : U_2 \rightarrow S_2, x_3 : U_3 \rightarrow S_3$$

establishing that  $f_1, f_2$  is diffeomorphic, we have that for a sufficiently small domain around our point  $p \in U_1$  in question

$$x_3^{-1} \circ f_3 \circ x_1 = x_3^{-1} \circ f_2 \circ x_2 \circ x_2^{-1} \circ f_1 \circ x_1$$

This is the composition of differentiable functions with differentiable inverses  $x_2^{-1} \circ f_1 \circ x_1, x_3^{-1} \circ f_2 \circ x_2$  and therefore is itself a differentiable function with differentiable inverse.

Thus  $f_3$  is a diffeomorphism so  $S_1 \sim S_3$

Symmetry:

If there exists the diffeomorphism

$$f : S_1 \rightarrow S_2$$

then it is the case that  $f^{-1}$  is a diffeomorphism as well and thus

$$f^{-1} : S_2 \rightarrow S_1$$

establishes  $S_2 \sim S_1$