# QKAN: Quantum Kolmogorov-Arnold Networks

Petr Ivashkov,<sup>1,2</sup> Po-Wei Huang,<sup>1</sup> Kelvin Koor,<sup>1</sup> Lirandë Pira,<sup>1</sup> Patrick Rebentrost <sup>1,3</sup>

<sup>1</sup>Centre for Quantum Technologies, National University of Singapore, Singapore

<sup>2</sup>Department of Information Technology and Electrical Engineering, ETH Zurich, Zurich, Switzerland

<sup>3</sup>Department of Computer Science, National University of Singapore, Singapore

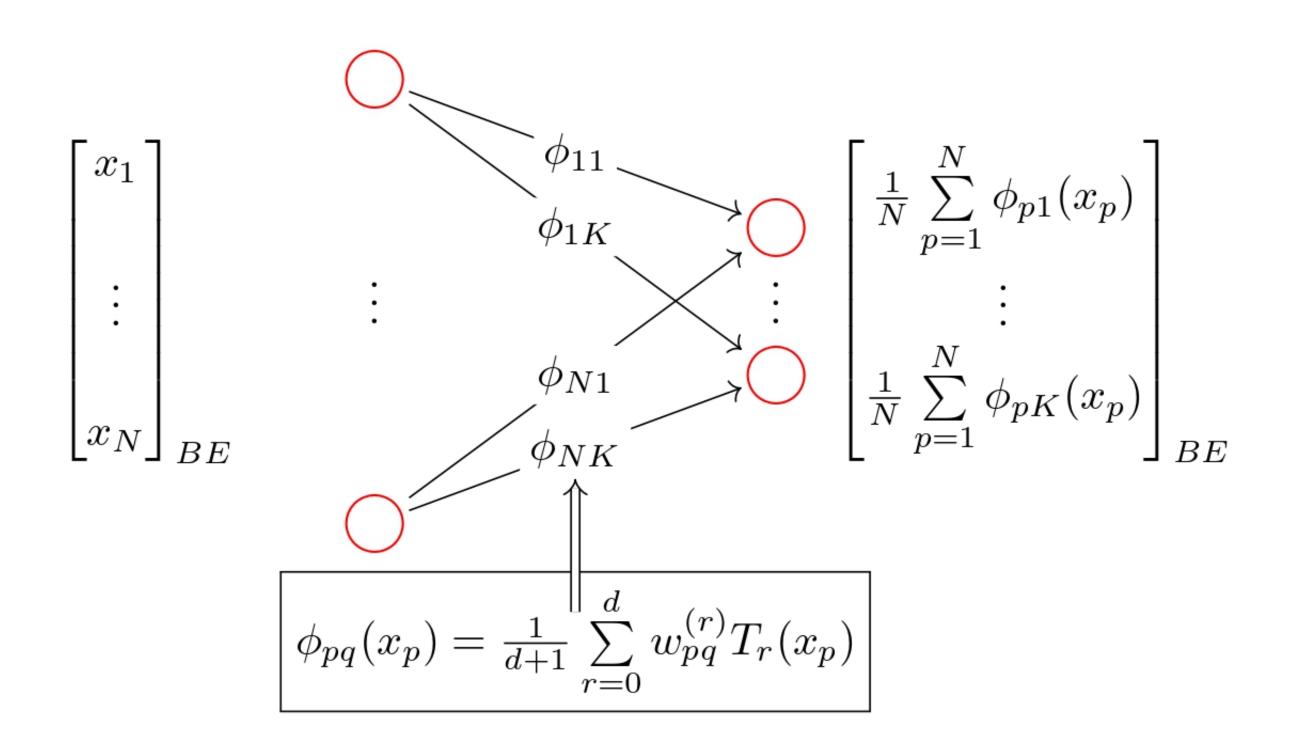
#### RESULT

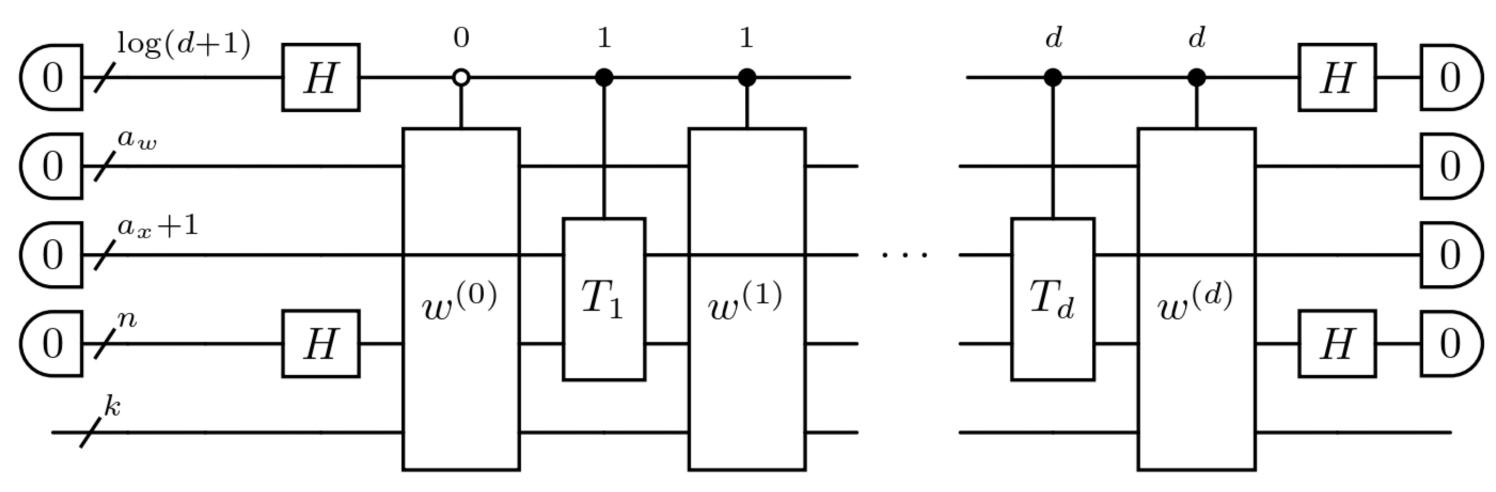
We design a quantum version of Kolmogorov-Arnold networks <sup>[1]</sup> (KAN) called QKAN, based on block encodings and quantum linear algebra subroutines such as QSVT. QKAN takes as input a block-encoding of the input vector and outputs a block-encoding of the transformed vector. By integrating parameterized quantum circuits, QKAN can serve as both a trainable quantum machine learning model and a multivariate state preparation subroutine.

INPUT QKAN LAYER OUTPUT

CIRCUIT

[1] Z. Liu et al., arXiv:2404.19756





The circuit corresponds to a block-encoding of  $2^k$ -dim output vector of a single-layer QKAN.

## QKAN CONSTRUCTION

(1) Diagonal-block-encoding: Embed input vector diagonally into a unitary <sup>[2]</sup>. [2] A.G. Rattew, P. Rebentrost, arXiv:2309.09839

$$U_{x} = \begin{bmatrix} x_{1} & 0 & \cdots & 0 & | & & & \\ 0 & x_{2} & \cdots & 0 & | & & & \\ \vdots & \vdots & \ddots & \vdots & | & & & \\ 0 & 0 & \cdots & x_{N} & | & & & \\ & & & & & & & * \end{bmatrix} =: \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ x_{N} \end{bmatrix}_{BE}$$

- (2) CHEB: Apply Chebyshev polynomials  $T_r(x)$  up to degree d via QSVT.
- (3) MUL: Multiply each polynomial by the corresponding weight encoding.
- (4) LCU: Combine weighted encodings with a Hadamard superposition.
- (5) SUM: Sum activation outputs using Hadamards to yield final encoding.

(1) DBE	(2) CHEB	(3) MUL	(4) LCU	(5) SUM
$egin{bmatrix} x_1 \ dots \ x_1 \ dots \ x_N \ dots \ x_N \end{bmatrix}_{BE}$	$ \begin{bmatrix} T_r(x_1) \\ \vdots \\ T_r(x_1) \\ \vdots \\ T_r(x_N) \\ \vdots \\ T_r(x_N) \end{bmatrix}_{BE} $	$\begin{bmatrix} w_{11}^{(r)} T_r(x_1) \\ \vdots \\ w_{1K}^{(r)} T_r(x_1) \\ \vdots \\ w_{N1}^{(r)} T_r(x_N) \\ \vdots \\ w_{NK}^{(r)} T_r(x_N) \end{bmatrix}$	$ \begin{array}{c}                                     $	$\rightarrow \begin{bmatrix} \frac{1}{N} \sum_{p=1}^{N} \phi_{p1}(x_p) \\ \vdots \\ \frac{1}{N} \sum_{p=1}^{N} \phi_{pK}(x_p) \end{bmatrix}_{BE}$

**Complexity:** 

An L-layer QKAN requires  $\mathcal{O}\left(d^{2L}/2^L\right)$  applications of controlled block-encodings of input and weights.

## **APPLICATIONS**

### Regression (classical output)

Informal Theorem:

Given controlled block-encodings of input and weights

$$U_x:(1,a_x,arepsilon_x),\quad U_{w^{(r)}}:(1,a_w,arepsilon_w),$$

we can estimate each entry of a single QKAN layer

$$\Phi(\boldsymbol{x})_q = \frac{1}{N} \sum_{p=1}^N \phi_{pq}(x_p)$$

to additive  $(4d\sqrt{\varepsilon_x} + \varepsilon_w + \delta)$  - precision using\*  $\mathcal{O}\left(d^2/\delta\right)$  calls to controlled- $U_x$  and controlled- $U_{w^{(r)}}$ .

#### State-preparation (quantum output)

Informal Theorem:

Given controlled block-encodings of input and weights

$$U_x:(1,a_x,arepsilon_x),\quad U_{w^{(r)}}:(1,a_w,arepsilon_w),$$

we can prepare a quantum state  $|\psi\rangle$  with amplitudes corresponding to a *K*-dim QKAN layer

$$\left\| |\psi\rangle - \frac{1}{N} \sum_{q=1}^{K} \left( \frac{1}{N} \sum_{p=1}^{N} \phi_{pq}(x_p) \right) |q\rangle_k \right\|_2 \le \varepsilon,$$

using\*  $\mathcal{O}(\sqrt{K}d^2/\mathcal{N})$  calls to controlled- $U_x$  and controlled- $U_{w^{(r)}}$ .

\* d is the maximal degree of Chebyshev polynomials.

# FAQ

- What is QKAN? A quantum neural-network architecture that emulates the classical KAN.
- What is the core idea? Interpret the eigenvalues of a block-encoded matrix as neural network nodes, then leverage QSVT to implement nonlinear activation functions.
- ▶ What is the main advantage over classical KANs? The runtime depends implicitly on the input dimension N through the cost of the block-encoding. A polylog(N) block-encoding potentially delivers an exponential speedup.
- What is the main disadvantage? The runtime grows exponentially with the number L of network layers.







