ZYC0076_UNO_360servo_English

If the servo is 360 degree version, Please burn file ZYC0076_UNO instead of Arduino_UNO.

Some parameters can be modified as required.(It's about line 247)

```
void motorleft()
{
    MOTORservo.write(110);  //调节速度 90~180 逆时针
    delay(80);  //每次转向的执行时间
}
void motorright()
{
    MOTORservo.write(70);  //调节速度 0~90 顺时针
    delay(80);  //每次转向的执行时间
}
```

MOTORservo.write(90); The digital speed adjustment in brackets ranges from 0 to 180,90 is to stop rotation;

0~90, the smaller the right turn faster;

90~180, the larger the left turn, the faster.

Delay(); Is the delay function, and the execution time of each servo rotation can be adjusted, the default is 80ms.