Gene regulatory network drift and speciation



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Background

- Developmental systems drift: many different molecular pathways can yield identical phenotypes. For example, in *Drosophila melanogaster* and *D. simulans*, bristle patterning is identical, yet in hybrid crosses, bristle patterns are different, suggesting divergent molecular mechanisms¹.
- Here we model gene regulatory networks as linear dynamical systems.
- We analytically describe the set of all phenotypically equivalent gene regulatory network architectures.
- Evolution can explore this set, despite selective and environmental stasis.
- Using quantitative genetics, we show that over time, this neutral process can lead to rapid hybrid phenotypic divergence and incompatibility (\sim on the order of N_e).

The set of all phenotypically identical gene networks of any size

$$\mathcal{A}_n(A_0) = \{A : Ce^{At}B = Ce^{A_0t}B \text{ for } t \ge 0\}$$

= $\{A : CA^kB = CA_0^kB \text{ for } 1 \le k \le n-1\}$

We denote $\mathcal{A}_n(A_0)$ as the set of all n-dimensional gene network architectures equivalent to A_0 , where A_0 is any linear gene network.

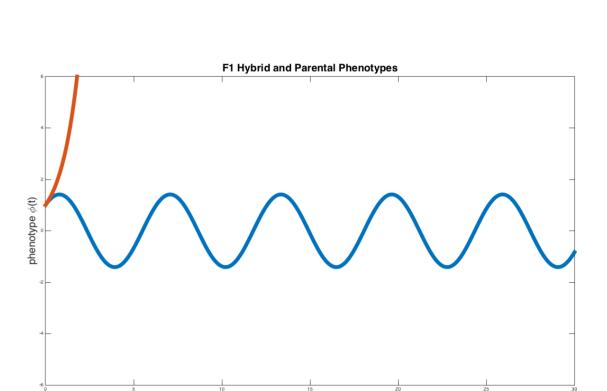
Gene regulatory networks as linear dynamical systems

$$\begin{cases} \dot{\kappa}(t) &= A\kappa(t) + Bu(t) \\ \phi(t) &= C\kappa(t) \end{cases}$$

- A: gene regulatory network ($n \times n$ matrix); rows are *cis*-regulatory elements.
- u(t): environmental input at time t.
- B: how the organism processes its input ($n \times l$ matrix).
- $\kappa(t)$: all molecular concentrations at time t the **kryptotype**.
- C: filtered molecular dynamics relevant to survival ($l \times n$ matrix).
- $\phi(t)$: molecular concentrations, visible to selection, at time t the **phenotype**.

Neutral evolution leads to hybrid incompatibility

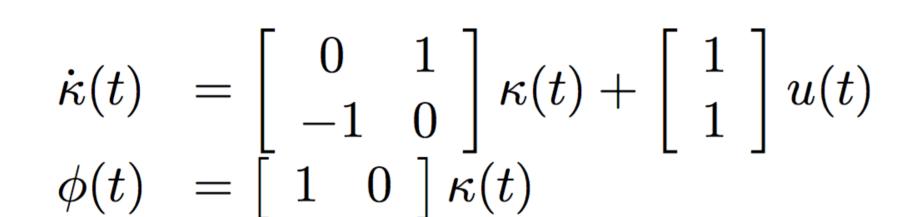
- Diploid F_1 hybrids are formed by averaging the two parental gene networks A and A'.
- F_2 hybrids are formed by first recombining genes (swapping rows between A and A'), then next, two gametes are chosen and averaged.
- Fitness is scored as a Gaussian function of phenotypic distance.

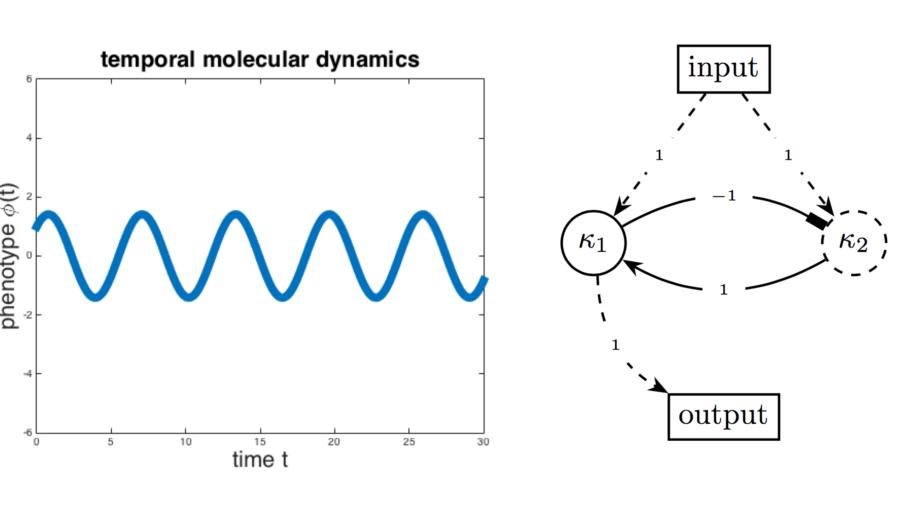


- Oscillators (from Ex. 1) A(0) and A(2) F_1 s
- Parents (blue), hybrids (orange).
- Hybrid $\phi_{F_1}(t) = e^t$

Example 1: oscillating two-gene network

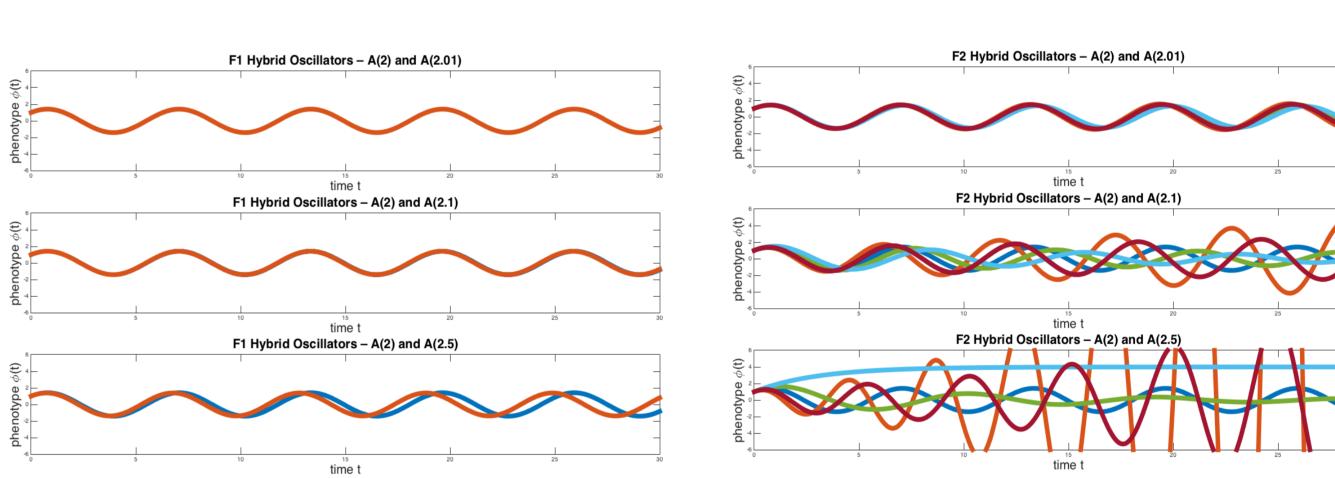
- A two-gene regulatory network with oscillating gene-1 expression.
- Environmental input is simply an impulse (a dirac delta).





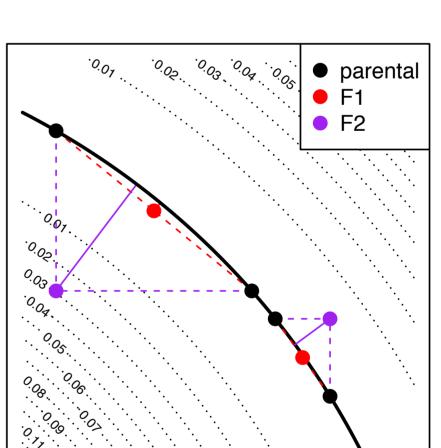
$$\phi(t) = \sin(t) + \cos(t)$$

Example 2: hybrid phenotypic divergence in a two-gene oscillator



Phenotypes diverge quadratically in ${\cal F}_2$ and quartically in ${\cal F}_1$ hybrids, with respect to change in network architecture.

Example of a phenotypic landscape. The dark **black** line is the phenotypically identical gene network space, and numbers are phenotypic divergence.



Different network architectures produce identical phenotypes

$$\dot{\kappa}(t) = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \kappa(t) + \begin{bmatrix} 1 \\ 1 \end{bmatrix} u(t)$$

$$\phi(t) = \begin{bmatrix} 1 & 0 \end{bmatrix} \kappa(t)$$

$$\dot{\widehat{\kappa}}(t) = \begin{bmatrix} 2 & -1 \\ 5 & -2 \end{bmatrix} \widehat{\kappa}(t) + \begin{bmatrix} 1 \\ 1 \end{bmatrix} u(t)
\widehat{\phi}(t) = \begin{bmatrix} 1 & 0 \end{bmatrix} \widehat{\kappa}(t)$$

$$\phi(t) = \widehat{\phi}(t) = \sin(t) + \cos(t)$$

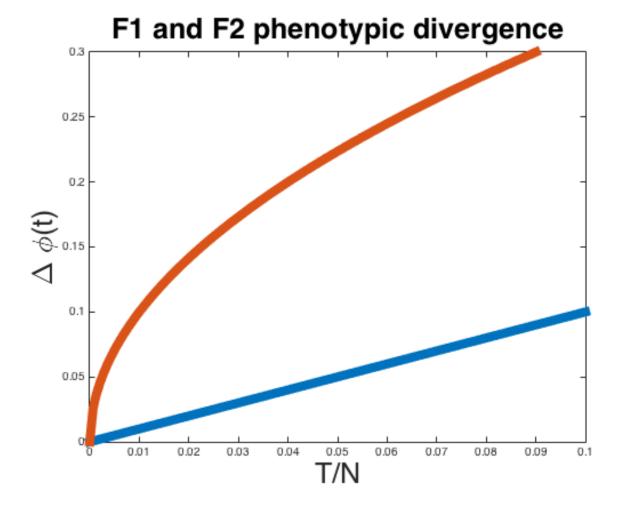
Expected phenotypic divergence rate in allopatric populations under static and identical selective and environmental pressures

Using a quantitative genetics model and a Gaussian fitness function, the phenotypic divergence (locally) is,

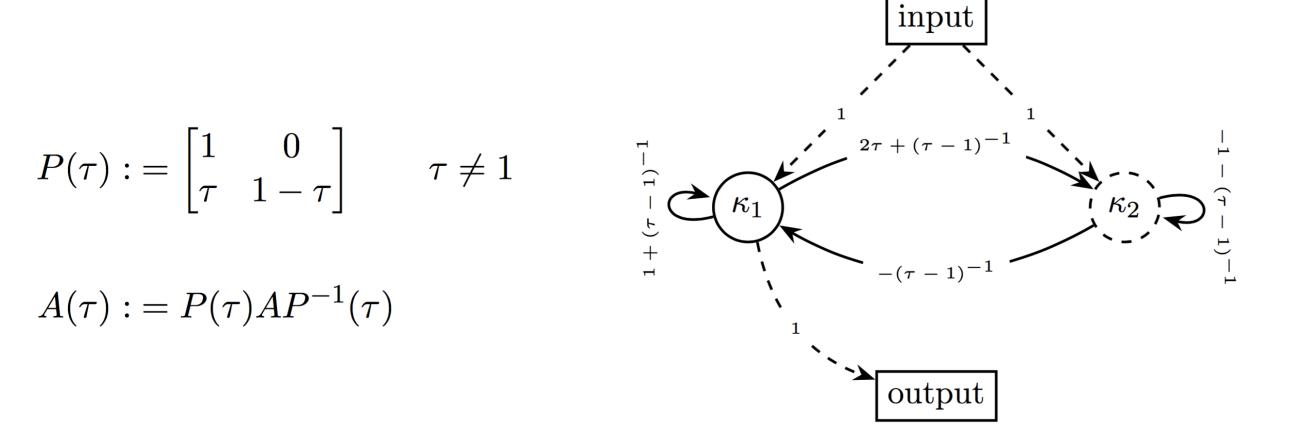
$$\Delta \phi_{F_1}(t) \approx c_1 \frac{T}{N} \text{ in } F_1 \text{ (blue),}$$

$$\Delta \phi_{F_2}(t) \approx c_2 \sqrt{\frac{T}{N}} \text{ in } F_2 \text{ (orange)}$$

formed by mating allopatric populations of size N isolated for T generations, where c_1 and c_2 are constants.



The set of all two-gene oscillators with identical phenotypes



Here the set of all phenotypically identical two-gene oscillator networks is given by any coordinate change that preserves B and C. More generally, without preserving input or output matrices, or network size, this set is given by the Kalman decomposition².

Future work

Apply model to study other evolutionary phenomena such as the necessity of complexity. Are gene regulatory networks Rube Goldberg machines? Is there a gene network ratchet?

References

- JR True & ES Haag. Developmental system drift and flexibility in evolutionary trajectories. *Evolution & development*, 3(2):109–119, 2001
- 2001.2. RE Kalman. Mathematical description of linear dynamical systems. *J.S.I.A.M Control*, 1963.