Assumptions 6.2.1 (Additional Regularity Conditions). Regularity conditions (R3) and (R4) are given by

- (R3) The pdf $f(x;\theta)$ is twice differentiable as a function of θ .
- (R4) The integral $\int f(x;\theta) dx$ can be differentiated twice under the integral sign as a function of θ .

in the endpoints of the interval in which $f(x;\theta) > 0$ and that we can interchange integration and differentiation with respect to θ . Our derivation is for the continuous case, but the discrete case can be handled in a similar manner. We begin with the Note that conditions (R1)-(R4) mean that the parameter θ does not appear identity

$$1 = \int_{-\infty}^{\infty} f(x; \theta) \, dx.$$

Taking the derivative with respect to θ results in

$$0 = \int_{-\infty}^{\infty} \frac{\partial f(x; \theta)}{\partial \theta} \, dx.$$

The latter expression can be rewritten as

$$0 = \int_{-\infty}^{\infty} \frac{\partial f(x;\theta)/\partial \theta}{f(x;\theta)} f(x;\theta) \, dx,$$

or, equivalently,

$$0 = \int_{-\infty}^{\infty} \frac{\partial \log f(x;\theta)}{\partial \theta} f(x;\theta) \, dx. \tag{6.2.1}$$

Writing this last equation as an expectation, we have established

$$E\left[\frac{\partial \log f(X;\theta)}{\partial \theta}\right] = 0; \tag{6.2.2}$$

that is, the mean of the random variable $\frac{\partial \log f(X;\theta)}{\partial \theta}$ is 0. If we differentiate (6.2.1) again, it follows that

$$0 = \int_{-\infty}^{\infty} \frac{\partial^2 \log f(x;\theta)}{\partial \theta^2} f(x;\theta) \, dx + \int_{-\infty}^{\infty} \frac{\partial \log f(x;\theta)}{\partial \theta} \frac{\partial \log f(x;\theta)}{\partial \theta} f(x;\theta) \, dx. \tag{6.2.3}$$

The second term of the right side of this equation can be written as an expectation, which we call **Fisher information** and we denote it by $I(\theta)$; that is,

$$I(\theta) = \int_{-\infty}^{\infty} \frac{\partial \log f(x;\theta)}{\partial \theta} \frac{\partial \log f(x;\theta)}{\partial \theta} f(x;\theta) dx = E \left[\left(\frac{\partial \log f(X;\theta)}{\partial \theta} \right)^{2} \right]. \quad (6.2.4)$$

From equation (6.2.3), we see that $I(\theta)$ can be computed from

$$I(\theta) = -\int_{-\infty}^{\infty} \frac{\partial^2 \log f(x;\theta)}{\partial \theta^2} f(x;\theta) \, dx = -E \left[\frac{\partial^2 \log f(X;\theta)}{\partial \theta^2} \right]. \tag{6.2.5}$$

Using equation (6.2.2), Fisher information is the variance of the random variable $\frac{\partial \log f(X;\theta)}{\partial \theta}$; i.e.,

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$$I(\theta) = \operatorname{Var}\left(\frac{\partial \log f(X;\theta)}{\partial \theta}\right). \tag{6.2}$$

Usually, expression (6.2.5) is easier to compute than expression (6.2.4),

Remark 6.2.1. Note that the information is the weighted mean of either

$$\left[\frac{\partial \log f(x;\theta)}{\partial \theta}\right]^2 \quad \text{or} \quad -\frac{\partial^2 \log f(x;\theta)}{\partial \theta^2}$$

where the weights are given by the pdf $f(x;\theta)$. That is, the greater these derivatives are on the average, the more information that we get about θ . Clearly, if they were equal to zero [so that θ would not be in $\log f(x;\theta)$], there would be zero information about θ . The important function

$$\partial \log f(x;\theta)$$

is called the score function. Recall that it determines the estimating equations for the mle; that is, the mle $\hat{\theta}$ solves

$$\sum_{i=1}^{n} \frac{\partial \log f(x_i; \theta)}{\partial \theta} = 0$$

for θ.

Example 6.2.1 (Information for a Bernoulli Random Variable). Let X be Bernoulli

$$\begin{array}{ccc} \log f(x;\theta) &=& x \log \theta + (1-x) \log (1-\theta) \\ \frac{\partial \log f(x;\theta)}{\partial \theta} &=& \frac{x}{\theta} - \frac{1-x}{1-\theta} \\ \frac{\partial^2 \log f(x;\theta)}{\partial \theta^2} &=& -\frac{x}{\theta^2} - \frac{1-x}{(1-\theta)^2}. \end{array}$$

Clearly,

$$I(\theta) = -E\left[\frac{-X}{\theta^2} - \frac{1 - X}{(1 - \theta)^2}\right]$$
$$= \frac{\theta}{\theta^2} + \frac{1 - \theta}{(1 - \theta)^2} = \frac{1}{\theta} + \frac{1}{(1 - \theta)} = \frac{1}{\theta(1 - \theta)}$$

which is larger for θ values close to zero or one.

Example 6.2.2 (Information for a Location Family). Consider a random sample X_1, \ldots, X_n such that

$$X_i = \theta + e_i, \quad i = 1, \dots, n,$$
 (6.2.7)