

## 6262 HOMEWORK 1

### 1. PRELIMINARY RESULTS

**1.1. Some basic facts.** If we have some set  $A \subset \Omega$ , we define the indicator function  $\mathbb{1}_A$  by

$$\mathbb{1}_A(\omega) = \begin{cases} 1 & \omega \in A \\ 0, & \omega \notin A. \end{cases}$$

For instance if  $\Omega = \mathbb{R}$ , the real line, we have that  $\mathbb{1}_{[a,b]}(x) = 1$  if and only if  $x \in [a, b]$ . Notice that this is also equal to  $\mathbb{1}_{(-\infty, b]} \mathbb{1}_{[a, \infty)}$ .

If  $X$  is a random variable, the cdf is given by

$$F_X(x) = \mathbb{P}(X \leq x).$$

This contains most of the properties of the individual random variable.

If  $X$  is continuous, then the pdf (the probability density function) is given by

$$(1.1) \quad f_X(x) = F'_X(x)$$

at "almost all points". By almost all points we admit that there might be some points on the real line where  $F_X$  is not differentiable, though this is negligible from the point of view of measure theory (i.e. if of Lebesgue measure 0).

If  $X$  is a random variable, then for any function  $\psi : \mathbb{R} \rightarrow \mathbb{R}$ , we have

$$(1.2) \quad \mathbb{E}[\psi(X)] = \begin{cases} \sum_x \psi(x) p_X(x), & X \text{ discrete with pmf } p_X \\ \int \psi(x) f_X(x) dx, & \text{if } X \text{ is continuous with density } f_X. \end{cases}$$

For two random variables  $(X, Y)$ , then for a function in two variables

$$(1.3) \quad \mathbb{E}[\psi(X, Y)] = \begin{cases} \sum_{x,y} \psi(x, y) \mathbb{P}_{X,Y}(x, y), & (X, Y) \text{ discrete with joint pmf } p_{X,Y} \\ \int \psi(x, y) f_{X,Y}(x, y) dx dy, & (X, Y) \text{ is continuous with joint density } f_{X,Y}. \end{cases}$$

**1.2. Independence of Normal variables.** If  $(X, Y)$  is a two dimensional normal distribution, then  $X$  and  $Y$  are independent if and only if the correlation between them is 0. In other words,  $X$  and  $Y$  are independent iff  $\text{Cov}(X, Y) = 0$ , or alternatively,  $\mathbb{E}[XY] = \mathbb{E}[X]\mathbb{E}[Y]$ .

In addition, if  $(X, Y)$  is a normal vector, then  $(aX + bY, cX + dY)$  is also a normal vector.

**1.3. Conditional Expectation.** Given two random variables  $X$  and  $Y$  which are square integrable, the definition of the conditional expectation of  $X$  given  $Y$  is interpreted as the function  $\phi(Y)$  such that

$$(1.4) \quad \mathbb{E}[(X - \phi(Y))^2]$$

is minimized over all possible choices of the function  $\phi$  such that  $\phi(Y)$  remains square integrable. We write  $\mathbb{E}[X|Y] = \phi(Y)$  or in more statistical slang  $\mathbb{E}[X|Y = y] = \phi(y)$ , though this could be a bit confusing.

We saw in class that the characterization of  $\phi(Y)$  is given by the following equality

$$(1.5) \quad \mathbb{E}[X\phi(Y)] = \mathbb{E}[\phi(Y)\psi(Y)]$$

for any other choice of the function  $\psi$ .

As properties of the conditional expectation show the following.

**1.4. Unbiased estimators and MVUE.** For a family of distributions  $f(x; \theta)$ , a statistics  $T = u(X_1, X_2, \dots, X_n)$  based on a  $n$  samples  $X_1, X_2, \dots, X_n$  is called an unbiased estimator of  $\theta$  if

$$\mathbb{E}_\theta[T] = \theta$$

for any choice of  $\theta$ . We say that  $T$  is an MVUE if for any other unbiased estimator  $U$ ,

$$\text{Var}(T) \leq \text{Var}(U) \text{ for all } \theta.$$

In other words, an unbiased estimator predicts correctly the parameter  $\theta$  in average. The condition of MVUE, gives the unbiased estimator with the smallest possible error in the estimation of  $\theta$ , where here by error we really mean the  $L^2$  norm of the difference  $T - \theta$ .

### 1.5. Sufficient statistic and basic results.

**Definition 1.** Given  $f(x; \theta)$  a family of densities, and a sample  $X_1, X_2, \dots, X_n$  a sample, a statistic  $T = u(X_1, X_2, \dots, X_n)$  is called sufficient if

$$(1.6) \quad \frac{f(x_1; \theta)f(x_2; \theta) \dots f(x_n; \theta)}{f_T(u(x_1, x_2, \dots, x_n); \theta)} = H(x_1, x_2, \dots, x_n).$$

This is the definition from Hogg's book. This is a little confusing if both terms in the ratio on the left are zero. The alternative form of (1.6)

$$(1.7) \quad f(x_1; \theta)f(x_2; \theta) \dots f(x_n; \theta) = f_T(u(x_1, x_2, \dots, x_n); \theta)H(x_1, x_2, \dots, x_n).$$

Notice that in this form,  $H$  is a function which does not depend on  $\theta$ .

**Theorem 2 (Factorization Theorem).**  $T = u(x_1, x_2, \dots, x_n)$  is a sufficient statistics if and only if

$$f(x_1; \theta)f(x_2; \theta) \dots f(x_n; \theta) = k_1(u(x_1, x_2, \dots, x_n); \theta)k_2(x_1, x_2, \dots, x_n),$$

for some function  $k_1(t; \theta)$  and  $k_2(x_1, x_2, \dots, x_n)$ , where  $k_2$  does not depend on  $\theta$ .

**Theorem 3 (Rao-Blackwell).** If  $T$  is a sufficient statistic and  $Y$  is an unbiased estimator which is not a function of  $T$ , then  $U = \mathbb{E}[Y|T] = \phi(T)$  is also an unbiased estimator with

$$\text{Var}(U) < \text{Var}(T).$$

In particular,  $Y$  is not an MVUE.

The notion of complete statistic is the following.

**Definition 4.** We say that a statistic  $T$  is complete if  $\mathbb{E}_\theta[\phi(T)] = 0$  for all  $\theta$  implies that  $\phi(T) \equiv 0$ .

In other words,  $\phi(T)$  is completely determined by the expectation of  $\mathbb{E}_\theta[\phi(T)]$ . To see this, if we have two functions  $\phi_1$  and  $\phi_2$  with the same expectations, then by taking the difference and using the above definition leads to the conclusion that  $\phi_1(T) = \phi_2(T)$ , which means essentially identifiability.

**Theorem 5 (Lehman-Schaffé).** If  $T$  is a sufficient and complete such that for some function  $\phi$ ,  $\phi(T)$  is unbiased, then this is the only unbiased estimator of this form (i.e., function of  $T$  and unbiased). In particular this is actually the MVUE.

## 2. EXPONENTIAL FAMILY

A family of pmfs/pdfs  $f(x; \theta)$  is called a regular exponential family if

$$(2.1) \quad f(x; \theta) = e^{p(\theta)K(x)+S(x)+q(\theta)} \text{ for } x \in \mathcal{S}$$

and here  $\mathcal{S}$  does not depend on the parameter  $\theta$  and the function  $K$  is not constant on the set  $\mathcal{S}$ .

**Theorem 6.** If  $f(x; \theta)$  is a regular exponential family and  $X_1, X_2, \dots, X_n$  is a sample from  $f(x; \theta)$  then

$$T = \sum_{k=1}^n K(X_k)$$

is a sufficient and complete statistic. In addition, if we can find a function  $\phi$ , such that  $\phi(T)$  is unbiased, then  $\phi(T)$  is the unique MVUE.

## 3. HOMEWORK + SOLUTIONS

- Problem 1.** (1) If  $Y = 0$ , then  $E[X|Y] = E[X]$ . Interpret this.  
 (2) The function  $\phi$  may not be unique, however  $\phi(Y)$  is uniquely defined.  
 (3) If  $X$  and  $Y$  are independent, then  $E[X|Y] = E[X]$ . Interpret this.  
 (4) If  $Z = h(Y)$  for another function  $h$ , then  $E[Z|Y] = h(Y)\phi(Y)$ . Written alternatively,  $E[Z|Y] = Z\phi(Y)$ .  
 (5) If  $X = g(Y)$ , then  $E[X|Y] = g(Y)$ .  
 (6) Argue that if  $E[X|Y] = \phi(Y)$  and  $E[Z|Y] = \psi(Y)$ , then  $E[X + Z|Y] = \phi(Y) + \psi(Y)$ .

**Solution.** (1) The functions of the variable  $Y$  is simply a real number, this means that we need to look for the best number  $\mu$  which minimize the quadratic loss function

$$E[(X - \mu)^2].$$

We did in class that this is the mean. In fact it is easy to see by simply differentiating with respect to  $\mu$  and setting this to be equal to 0.

- (2) The uniqueness of  $\phi(Y)$  is based on the fact that if we have two such representations,  $E[X|Y] = \phi_1(Y)$  and  $E[X|Y] = \phi_2(Y)$  then by property (1.5), then

$$E[X\psi(Y)] = E[\phi_1(Y)\psi(Y)] = E[\phi_2(Y)\psi(Y)]$$

for any choice of  $\psi$ . This implies in turn that

$$E[(\phi_1(Y) - \phi_2(Y))\psi(Y)] = 0$$

for all choices of  $\psi$ , which mean that  $\phi_1(Y) = \phi_2(Y)$ .

The non-uniqueness of  $\phi_1$  and  $\phi_2$  are given by the fact that for instance  $Y \geq 0$ , then we can take for instance  $\phi_1(x) = x$  and  $\phi_2(x) = x^+ = \max(x, 0)$ , are two different functions with the property that they coincide on the positive real line but are not equal on the whole real line.

- (3) If  $X$  is independent of  $Y$ , then the conditioning with respect to  $Y$  should behave like conditioning on constant random variables. Formally we have that if  $E[X|Y] = \phi(Y)$ , then by (1.5)

$$E[X\psi(Y)] = E[\phi(Y)\psi(Y)]$$

now on the other hand, because  $X$  and  $Y$  are independent,

$$E[X\psi(Y)] = E[X]E[\psi(Y)] = E[E[X]\psi(Y)]$$

thus the constant  $E[X]$  plays the role of the function of  $\phi(Y)$  in (1.5) for  $E[X|Y]$ .

- (4) This follows from (1.5) because

$$\mathbb{E}[XZ\psi(Y)] = \mathbb{E}[Xh(Y)\psi(Y)] = \mathbb{E}[\phi(Y)h(Y)\psi(Y)]$$

we used again (1.5) with  $\psi(Y)$  replaced by  $h(Y)\psi(Y)$ . This means that we can now argue that  $\phi(Y)h(Y) = \mathbb{E}[ZX|Y]$  again by utilizing (1.5).

- (5) This is easy because using the definition from (1.4), the choice of  $\phi(Y) = g(Y)$  gives  $\mathbb{E}[(X - \phi(Y))^2] = 0$  which is the minimum possible value. This means that  $\mathbb{E}[g(Y)|Y] = g(Y)$ .
- (6) This follows again using the property (1.5) we can write

$$\mathbb{E}[X\zeta(Y)] + \mathbb{E}[Z\zeta(Y)] = \mathbb{E}[\phi(Y)\zeta(Y)] + \mathbb{E}[\psi(Y)\zeta(Y)] = \mathbb{E}[(\phi(Y) + \psi(Y))\zeta(Y)]$$

for any choice of  $\zeta(Y)$ . In particular again by the characterization from (1.5) applied to  $X + Z$  and  $\phi(Y) + \psi(Y)$  gives that  $\mathbb{E}[X + Z|Y] = \phi(Y) + \psi(Y)$ .

□

**Problem 2.** If the pair  $(X, Y)$  has a joint pmf or pdf, show that

$$(3.1) \quad \mathbb{E}[X|Y = y] = \phi(y) \text{ where } \phi(y) = \begin{cases} \sum_x x \frac{p_{X,Y}(x,y)}{p_Y(y)} & (X, Y) \text{ are discrete with pmf } p_{X,Y} \\ \int x \frac{f_{X,Y}(x,y)}{f_Y(y)} dx & (X, Y) \text{ have joint pdf } f_{X,Y}. \end{cases}$$

**Solution.** This is pretty straightforward. We only need to show that for any choice of the function  $\psi$ , we have from (1.3) that

$$\mathbb{E}[X\psi(Y)] = \sum_{x,y} x\psi(y)p_{X,Y}(x,y) = \sum_y \psi(y) \sum_x x \frac{p_{X,Y}(x,y)}{p_Y(y)} p_Y(y) = \sum_y \psi(y) \phi(y) p_Y(y) = \mathbb{E}[\phi(Y)\psi(Y)]$$

where in the last equation we used (1.2) for the variable  $Y$  and the function  $\phi(y)\psi(y)$ .

A similar proof works for the case of continuous distributions, just replacing the summation with the integration. □

**Problem 3.** Compute the following conditional expectations:

- (1)  $\mathbb{E}[X|X^2]$  if  $X \sim \text{Exp}(\lambda)$ .
- (2)  $\mathbb{E}[X|X^3]$  if  $X \sim N(0, 2)$ .
- (3)  $\mathbb{E}[X - 2X^4|X^2]$  for  $X \sim N(0, 2)$ .
- (4) Give an example of two different functions  $\phi_1$  and  $\phi_2$  such that  $\mathbb{E}[X|X^2] = \phi_1(X^2)$  and also  $\mathbb{E}[X|X^2] = \phi_2(X^2)$ . Are  $\phi_1(X^2)$  and  $\phi_2(X^2)$  equal?
- (5)  $\mathbb{E}[\cos(X)|X^2]$  if  $X \sim N(0, 1)$ .
- (6)  $\mathbb{E}[X|Y]$  if  $X, Y$  are iid  $N(0, 1)$ .
- (7)  $\mathbb{E}[X + X^2|X^4]$  for  $X \sim N(0, 1)$ .
- (8)  $\mathbb{E}[X|X + 2Y]$  if  $X, Y$  are iid  $N(0, 1)$ .

**Solution.** (1) Using the fact that  $X \geq 0$ , we actually have that  $X = \sqrt{X^2}$  and thus using the first problem, part 5) we get that  $\mathbb{E}[X|X^2] = X$ .

- (2) Similar to the first part, we have that  $X = (X^3)^{1/3}$ , thus  $\mathbb{E}[X|X^3] = X$ .
- (3) Using the first problem, the additivity from part 6) we get that

$$\mathbb{E}[X - 2X^4|X^2] = \mathbb{E}[X|X^2] - 2\mathbb{E}[X^4|X^2] = -2X^4$$

because we showed in class that  $\mathbb{E}[X|X^2] = 0$ . This can be redone here in a different way, namely observing that we can write  $X = Z|X|$  where  $Z$  is a Bernoulli  $\pm 1$  with equal probabilities. In addition  $Z$  and  $|X|$  can be assumed independent. Therefore using a combination of the first problem, more precisely, the third and the fifth, we get that  $\mathbb{E}[X|X^2] = \mathbb{E}[Z|X||X^2] = |X|\mathbb{E}[Z|X^2] = |X|\mathbb{E}[Z] = 0$ .

- (4) This is basically the comment from problem 1, part 2. Take for instance  $X$  to be exponential and we have  $\mathbb{E}[X|X^2] = X = \phi_1(X)$  with  $\phi_1(x) = x$  on one hand, and also  $\mathbb{E}[X|X^2] = \phi_2(X)$  with  $\phi_2(x) = \max(x, 0)$ .
- (5) The key is that  $\cos(x) = \cos(|x|) = \cos(\sqrt{x^2})$ , thus

$$\mathbb{E}[\cos(X)|X^2] = \mathbb{E}[\cos(\sqrt{X^2})|X^2] = \cos(\sqrt{X^2}) = \cos(|X|) = \cos(X)$$

where we used the first problem, part 5) to write  $\cos(X)$  as a function of  $X^2$ .

- (6) If  $X, Y$  are independent, we get everything from Problem 1, part 3). Thus  $\mathbb{E}[X|Y] = \mathbb{E}[X] = 0$ .
- (7)  $\mathbb{E}[X + X^2|X^4] = \mathbb{E}[X|X^4] + \mathbb{E}[X^2|X^4] = X^2$ , because  $\mathbb{E}[X|X^4] = 0$ , with an argument like we did in class for  $\mathbb{E}[X|X^2]$  or just above.
- (8) This is more complicated. There are two ways of doing it. One is to use Problem 2 and find the joint density of  $(X, X + 2Y)$  and then use that formula. The other is based on writing  $X$  as a sum of a function of  $X + 2Y$  and another piece which will be independent of  $X + 2Y$ . The easier and faster way of is the latter.

We can use the facts outlined at the beginning of this section to write

$$X = a(X + 2Y) + b(2X - Y)$$

and try to figure out the constants  $a, b$  such this writing is valid. Equating the coefficient of  $X$  and  $Y$  gives  $a + 2b = 1$  and  $2a - b = 0$ , or  $b = 2a$  and  $5a = 1$ , which means that  $a = 1/5$  while  $b = 2/5$ . The key is now that

$$(X + 2Y, 2X - Y)$$

is a normal vector with independent components because the covariance  $Cov(X + 2Y, 2X - Y) = 2Cov(X, X) + 3Cov(Y, X) - Cov(Y, Y) = Var(X) - Var(Y) = 0$ . Now, using the first Problem, we get

$$\mathbb{E}[X|X + 2Y] = \mathbb{E}[(X + 2Y)/5|X + 2Y] + (2/5)\mathbb{E}[(2X - Y)|X + 2Y] = (X + 2Y)/5 + \mathbb{E}[2X - Y] = (X + 2Y)/5.$$

□

**Problem 4.** (1) If  $(X, Y)$  are iid uniform on  $(0, 1)$ , find  $\mathbb{E}[X|X + Y]$ . Can you explain?

(2) If  $(X, Y)$  are uniform on  $0 < x < y < 1$ , find  $\mathbb{E}[X|Y]$ .

(3) Assume  $(X, Y)$  take the values  $(0, 1), (2, 3), (3, 4), (2, 4), (4, 1)$  with equal probability. Compute  $\mathbb{E}[X|Y]$ .

**Solution.** (1) The key here is that symmetry between  $X$  and  $Y$ . Thus we can use the second problem to argue that  $\mathbb{E}[X|X + Y] = \phi(X + Y)$  and  $\mathbb{E}[Y|X + Y] = \phi(X + Y)$ . Now adding the two together, we obtain  $\mathbb{E}[X + Y|X + Y] = 2\phi(X + Y)$ . Therefore,  $\phi(X + Y) = (X + Y)/2$ , so  $\mathbb{E}[X|X + Y] = (X + Y)/2$ .

Another solution would be to compute the joint density of  $(X, X + Y)$  and then use the second Problem. This is possible, however is very long because we have to also use a change of variables in two dimensions.

(2) For this part we really have to use Problem 2. Thus we have

$$f_{X,Y}(x, y) = \frac{1}{2} \text{ on the domain } 0 < x < y < 1.$$

Therefore,

$$f_Y(y) = \int f_{X,Y}(x, y) dx = \frac{y}{2} \text{ for } 0 < y < 1.$$

Thus

$$\phi(y) = \int x \frac{f_{X,Y}(x, y)}{f_Y(y)} dx = \int_0^y x/y dx = y/2$$

and thus  $\mathbb{E}[X|Y] = Y/2$ .

- (3) For this we again can use the second Problem to compute the function  $\phi$ . We get that  $Y$  has marginal given by 1, 3, 4 with probabilities  $2/5$ ,  $1/5$  and  $2/5$ . What we need to find now is

$$(3.2) \quad \phi(y) = \sum_x x p_{X,Y}(x, y) / p_Y(y) = \begin{cases} 5/2 & y = 1 \\ 2 & y = 3 \\ 5/2 & y = 4 \end{cases}$$

and  $\mathbb{E}[X|Y] = \phi(Y)$ .

□

**Remark 7.** There is a point in the last part of this problem. We computed the conditional expectation with the formula from (3.1). However the point is that the variable  $Y$  is discrete and thus can be written in the form

$$(3.3) \quad Y = \sum_k \alpha_k \mathbb{1}_{A_k}$$

for some partition  $\{A_k\}_k$  of the sample space. Here, for an event  $A$  (a subset in the sample space), we set

$$\mathbb{1}_A(\omega) = \begin{cases} 1 & \omega \in A \\ 0, & \text{otherwise} . \end{cases}$$

In our case at hand we have

$$Y = \mathbb{1}_{\{Y=1\}} + 3\mathbb{1}_{\{Y=3\}} + 4\mathbb{1}_{\{Y=4\}}$$

Notice that if we write everything explicitly, we would have that the sample space where both  $X$  and  $Y$  are defined is given by  $\Omega = \{(0, 1), (2, 3), (3, 4), (2, 4), (4, 1)\}$  with the uniform probability on it. Thus the subsets  $\{Y = 1\} = \{(0, 1), (4, 1)\}$ ,  $\{Y = 3\} = \{(2, 3)\}$  and  $\{Y = 4\} = \{(3, 4), (2, 4)\}$ . The point is that now a variable of the form  $\phi(Y)$  is perfectly defined by prescribing the values  $\phi(1)$ ,  $\phi(3)$  and  $\phi(4)$ . Therefore we would have the following writing

$$\phi(Y) = \phi(1)\mathbb{1}_{\{Y=1\}} + \phi(3)\mathbb{1}_{\{Y=3\}} + \phi(4)\mathbb{1}_{\{Y=4\}}.$$

This explains why the function above, in (3.2) is defined in this way. The conditional expectation is thus perfectly well defined in terms of the function  $Y$ .

As a more general lesson, we have the following conclusion. If  $Y$  is discrete and written in the form (3.3), we then have

$$\phi(Y) = \sum_k \phi(\alpha_k) \mathbb{1}_{A_k}.$$

This explains why the function  $\phi$  has to be specified only at the values  $\alpha_k$  and it does not really matter how is defined at any other points.

This situation appears also in Problem 6 below.

**Problem 5.** If  $(X, Y)$  have joint pdf given by  $f_{X,Y}(x, y) = 12(2x + y^2)/7$  on the set  $0 < x < y < 1$  and 0 otherwise, find  $\mathbb{E}[X|Y]$ .

**Solution.** Here we use the second problem. The function we need to compute is

$$\phi(y) = \int x f_{X,Y}(x, y) / f_Y(y) dx = \frac{y(3y + 4)}{6(y + 1)}.$$

for  $0 < y < 1$ .

□

**Problem 6.** Flip a coin until the head comes up and let  $X$  be the number of flips. Compute  $\mathbb{E}[X | \cos(\pi X/2)]$ .

**Solution.** First we need to notice that  $\cos(\pi X/2)$  takes only values  $-1, 0, 1$ . Thus we can use the comments in the Remark 7 for more explanation. Our sample space is  $\Omega = \{1, 2, 3, \dots\}$ . In fact we can write this as

$$\cos(\pi y/2) = 0 \times \mathbb{1}_A(y) + (-1) \times \mathbb{1}_B(y) + 1 \times \mathbb{1}_C(y)$$

where  $A = \{1, 3, 5, 7, 9, 11, 13, \dots\}$ ,  $B = \{2, 6, 10, \dots\}$  and  $C = \{4, 8, 12, \dots\}$  and  $\mathbb{1}_A(y) = 1$  if  $y \in A$  and 0 otherwise. Notice that the sets  $A, B, C$  form a partition of the whole space.

Thus we need to compute the conditional expectation  $\mathbb{E}[X | \cos(\pi X/2)] = \phi(Y)$  where  $\phi$  has to be specified at three values, namely,  $0, -1, 1$ . Thus it suffices to study the value at the points  $-1, 0, 1$  because

$$\phi(Y) = \phi(0)\mathbb{1}_A + \phi(-1)\mathbb{1}_B + \phi(1)\mathbb{1}_C.$$

Now from the definition (1.5), we need to check that

$$\mathbb{E}[X\psi(\cos(\pi X/2))] = \mathbb{E}[\phi(Y)\psi(Y)].$$

for any function  $\psi$ . Taking  $\psi(y) = \mathbb{1}_A(y)$  we obtain the value of  $\phi(0)$  which is in fact given by

$$\begin{aligned} \mathbb{E}[X\psi(\cos(\pi X/2))] &= \mathbb{E}[X\mathbb{1}_A(y)] = \sum_{x \in A} x\mathbb{P}(X = x) = 1/2 + 3/2^3 + 5/2^5 + 7/2^7 + 9/2^9 + \dots \\ &= \sum_{k=0}^{\infty} (2k+1)/2^{2k+1} = 10/9. \end{aligned}$$

In a similar fashion, for  $\psi(y) = \mathbb{1}_B(y)$ , we get

$$\begin{aligned} \mathbb{E}[X\psi(\cos(\pi X/2))] &= \mathbb{E}[X\mathbb{1}_B(y)] = \sum_{x \in B} x\mathbb{P}(X = x) = 2/2^2 + 6/2^6 + 10/2^{10} + \dots \\ &= \sum_{k=0}^{\infty} (4k+2)/2^{4k+2} = 136/225. \end{aligned}$$

and for  $\phi = \mathbb{1}_C(y)$  we finally get

$$\begin{aligned} \mathbb{E}[X\psi(\cos(\pi X/2))] &= \mathbb{E}[X\mathbb{1}_C(y)] = \sum_{x \in C} x\mathbb{P}(X = x) = 4/2^4 + 8/2^8 + 12/2^{12} + \dots \\ &= \sum_{k=1}^{\infty} (4k)/2^{4k} = 64/225. \end{aligned}$$

Thus,

$$\mathbb{E}[X | \cos(\pi X/2)] = \frac{10}{9}\mathbb{1}_A(Y) + \frac{136}{225}\mathbb{1}_B(Y) + \frac{64}{225}\mathbb{1}_C(Y).$$

Thus if we define the function

$$\phi(y) = \begin{cases} 10/9 & y = 0 \\ 136/225 & y = -1 \\ 64/225 & y = 1 \end{cases}$$

Then we can write

$$\mathbb{E}[X | \cos(\pi X/2)] = \phi(\cos(\pi X/2)).$$

Notice that we used here the identity

$$\sum_{k=0}^{\infty} k\rho^k = \rho/(1-\rho)^2$$

to compute the various sums above. □

**Problem 7.** Let  $\mathbb{E}[X|Y] = \phi(Y)$  and using (1.5) show that  $\mathbb{E}[X] = \mathbb{E}[\phi(Y)]$  and

$$(3.4) \quad \text{Var}(X) = \text{Var}(\phi(Y)) + \mathbb{E}[(X - \phi(Y))^2].$$

In particular argue that  $\text{Var}(X) \geq \text{Var}(\phi(Y))$  with equality if and only if  $X = \phi(Y)$  or that  $X$  is a function of  $Y$ .

**Solution.** We worked the idea in class. Denote  $\mathbb{E}[X|Y] = \phi(Y)$  and notice in the first place that  $\mathbb{E}[\phi(Y)] = \mathbb{E}[X]$  as one can see from (1.5) for  $\psi(y) = 1$ . Here are some details. Write

$$(3.5) \quad \begin{aligned} \text{Var}(X) &= \mathbb{E}[(X - \mathbb{E}[X])^2] = \mathbb{E}[(X - \phi(Y) + \phi(Y) - \mathbb{E}[X])^2] \\ &= \mathbb{E}[(X - \phi(Y))^2] + \mathbb{E}[(\phi(Y) - \mathbb{E}[X])^2] + 2\mathbb{E}[(X - \phi(Y))(\phi(Y) - \mathbb{E}[X])] \end{aligned}$$

Now, using (1.5) with  $\psi(y) = \phi(y) - \mathbb{E}[X]$ , we get that  $\mathbb{E}[X\psi(Y)] = \mathbb{E}[\phi(Y)\psi(Y)]$  and this means that  $\mathbb{E}[(X - \phi(Y))\psi(Y)] = 0$ , thus the last term in (3.5) is 0.

To finish the rest, we notice that  $\mathbb{E}[(\phi(Y) - \mathbb{E}[X])^2] = \mathbb{E}[(\phi(Y) - \mathbb{E}[\phi(Y)])^2] = \text{Var}(\phi(Y))$ . Putting all together, we get the relation (3.4). □

**Problem 8.** Show that if  $X_1, X_2, \dots, X_n$  is a sample and  $T = u(x_1, x_2, \dots, x_n)$  is a sufficient statistic, then for any one-to-one map  $g: \mathbb{R} \rightarrow \mathbb{R}$ ,  $\bar{T} = g(T)$  is also a sufficient statistic.

**Solution.** We discussed this in class, however here are some details. This is based on the factorization Theorem 3 and the writing

$$\begin{aligned} f(x_1; \theta)f(x_2; \theta) \dots f(x_n; \theta) &= k_1(u(x_1, x_2, \dots, x_n); \theta)k_2(x_1, x_2, \dots, x_n) \\ &= k_1(g^{-1}(g(u(x_1, x_2, \dots, x_n))); \theta)k_2(x_1, x_2, \dots, x_n) \\ &= \tilde{k}_1(g(u(x_1, x_2, \dots, x_n))); \theta)k_2(x_1, x_2, \dots, x_n) \end{aligned}$$

where  $\tilde{k}_1(t; \theta) = k_1(g^{-1}(t); \theta)$ . This shows, again from the factorization theorem that  $\bar{T}$  is also a sufficient statistic. □

**Problem 9.** Assume  $X_1, X_2, \dots, X_n$  is a sample with density

$$f(x; \theta) = \begin{cases} \theta x^{\theta-1}, & 0 < x < 1 \\ 0 & \text{otherwise.} \end{cases}$$

- (1) Show that  $T = \prod_{k=1}^n X_k$  is a sufficient statistic. Also show that  $T = \sum_{k=1}^n \ln(X_k)$  is also a sufficient statistic.
- (2) Show that  $U = \sum_{k=1}^n X_k$  IS NOT a sufficient statistic.

**Solution.** (1) The fastest way of seeing this is to realize that  $f(x; \theta)$  is a regular exponential family because we can write it as

$$f(x; \theta) = \begin{cases} e^{(\theta-1)\ln(x) + \ln(\theta)} & 0 < x < 1 \\ 0, & \text{otherwise,} \end{cases}$$



thus it is of the form (2.1) with  $\mathcal{S} = (0, 1)$ ,  $p(\theta) = \theta - 1$ ,  $K(x) = \ln(x)$ ,  $S(x) = 0$  and  $q(\theta) = \ln(\theta)$ . This implies that  $V = \sum_{k=1}^n \ln(X_k)$  is a sufficient and complete statistic. Now combining this with Problem 8 with the function  $g(x) = e^x$ , gives that  $T = g(V) = e^{\sum_{k=1}^n \ln(X_k)} = e^{\ln(\prod_{k=1}^n X_k)} = \prod_{k=1}^n X_k$  is also a sufficient statistic. This answers the first part of the problem.

There is a second argument to the fact that  $T$  is a sufficient statistic and this is based on the factorization theorem 2. Essentially we have that

$$f(x_1; \theta) f(x_2; \theta) \dots f(x_n; \theta) = \theta^n \left( \prod_{k=1}^n x_k \right)^{\theta-1}$$

which means with  $k_1(y; \theta) = \theta^n y^{\theta-1}$  for  $0 < y < 1$  and  $k_2(x_1, \dots, x_n) = 1$ , we have the conclusion that  $T$  is a sufficient statistic. To show that  $\bar{T}$  is a sufficient statistic, we just need to use Problem 8

- (2) To show that  $U$  is not a sufficient statistic we need to show that we can not use for instance the factorization theorem. We assume by contradiction that  $U$  is a sufficient statistic and thus

$$f(x_1; \theta) f(x_2; \theta) \dots f(x_n; \theta) = \theta^n \left( \prod_{k=1}^n x_k \right)^{\theta-1} = k_1\left(\sum_{k=1}^n x_k; \theta\right) k_2(x_1, x_2, \dots, x_n)$$

for all choices of  $x_1, x_2, \dots, x_n \in (0, 1)$  and  $\theta > 0$ . This is hard to believe at first site, because on the left hand side we have a function of the product, while on the other hand we have a function of the sum and  $\theta$ . To show though that this is not possible, we can argue with the fact that

$$k_2(x_1, x_2, \dots, x_n) = \frac{f(x_1; \theta) f(x_2; \theta) \dots f(x_n; \theta)}{k_1\left(\sum_{k=1}^n x_k; \theta\right)}$$

Since the right hand side does not depend on  $\theta$ , we can pick one as a reference, say for instance  $\theta = 1$ . Thus we would have that

$$\frac{f(x_1; \theta) f(x_2; \theta) \dots f(x_n; \theta)}{k_1\left(\sum_{k=1}^n x_k; \theta\right)} = \frac{f(x_1; \theta) f(x_2; 1) \dots f(x_n; 1)}{k_1\left(\sum_{k=1}^n x_k; 1\right)} = \frac{1}{k_1\left(\sum_{k=1}^n x_k; 1\right)}.$$

In particular this means that

$$\theta^n \left( \prod_{k=1}^n x_k \right)^{\theta-1} = \frac{k_1\left(\sum_{k=1}^n x_k; \theta\right)}{k_1\left(\sum_{k=1}^n x_k; 1\right)}.$$

At this point,  $\theta$  no longer play any role, the game here is between the sum and the products of  $x$ 's. For instance, if we take  $\theta = 2$ , we obtain that

$$2^n x_1 x_2 \dots x_n = \frac{k_1\left(\sum_{k=1}^n x_k; 2\right)}{k_1\left(\sum_{k=1}^n x_k; 1\right)} \text{ for all } 0 < x_1, x_2, \dots, x_n < 1.$$

This is contradictory because for instance if we take  $x_1 = x_2 = \dots = x_n = 1/n$ , the sum is 1 and the product is  $1/n^n$ . However if we change this slightly, by taking  $x_1 = x_2 = \dots = x_{n-2} = 1/n$  and  $x_{n-1} = 1/n - \epsilon$  and  $x_n = 1/n + \epsilon$ , the sum will be the same, however the product becomes something different, namely,  $(1 - n^2 \epsilon^2)/n^n$  which gives different values for different values of  $\epsilon$ .

□

**Problem 10.** Let  $X_1, X_2, \dots, X_n$  be a sample from a uniform distribution on  $[0, \theta]$ . Show that  $T = \max\{X_1, X_2, \dots, X_n\}$  is a sufficient statistic. Do this using the definition and also using the factorization theorem.

Is this a complete statistic? Why or why not?

**Solution.** Before we jump into the details of the solution, notice that we can rewrite

$$f(x; \theta) = \frac{1}{\theta} \mathbb{1}_{[0, \theta]}(x) = \frac{1}{\theta} \mathbb{1}_{[0, \infty)}(x) \mathbb{1}_{(-\infty, \theta]}(x).$$

The first approach is using the definition. In the first place we need to find the density of the  $T$ . This is usually done by first computing the cdf (the cumulative distribution function) and then taking the derivative as guaranteed by (1.1).

Now, take  $x \in (0, \theta)$ . We have

$$\begin{aligned} \mathbb{P}(T \leq x) &= \mathbb{P}(\max\{X_1, X_2, \dots, X_n\} \leq x) = \mathbb{P}(X_1 \leq x, X_2 \leq x, \dots, X_n \leq x) \\ &= \mathbb{P}(X_1 \leq x) \mathbb{P}(X_2 \leq x) \dots \mathbb{P}(X_n \leq x) = (x/\theta)^n. \end{aligned}$$

Of course we have that  $F_T(x) = 0$  if  $x \leq 0$  and  $F_T(x) = 1$  for  $x > \theta$ . Taking the derivative, we get that

$$f_T(x) = n \frac{x^{n-1}}{\theta^n} \text{ for } 0 < x < \theta \text{ and } 0 \text{ otherwise.}$$

which we can write as

$$(3.6) \quad f_T(x; \theta) = \frac{n}{\theta^n} x^{n-1} \mathbb{1}_{(-\infty, \theta]}(x) \mathbb{1}_{[\theta, \infty)}(x)$$

For any  $x_1, x_2, \dots, x_n \in (0, \theta)$ ,

$$\frac{f(x_1; \theta) f(x_2; \theta) \dots f(x_n; \theta)}{f_T(\max\{x_1, x_2, \dots, x_n\}; \theta)} = \frac{1}{n \max\{x_1, x_2, \dots, x_n\}^{n-1}}.$$

The left hand side becomes 0 if for instance one  $x_k < 0$ . The left hand side is also 0 if one of the  $x$ 's becomes  $> \theta$ . In this case what seems to be happening is that the ratio  $\frac{f(x_1; \theta) f(x_2; \theta) \dots f(x_n; \theta)}{f_T(\max\{x_1, x_2, \dots, x_n\}; \theta)}$  in fact depends on  $\theta$ . This is because the ratio is ill defined for some values of  $x$ 's. This is why I added a clarification in the Definition 1 between the equation (1.6) and (1.7). If we write according to (1.7), then we have a better form

$$\begin{aligned} (3.7) \quad f(x_1; \theta) f(x_2; \theta) \dots f(x_n; \theta) &= \mathbb{1}_{[0, \theta]}(x_1) \mathbb{1}_{[0, \theta]}(x_2) \dots \mathbb{1}_{[0, \theta]}(x_n) \\ &= \frac{1}{\theta^n} \mathbb{1}_{(-\infty, \theta]}(x_1) \mathbb{1}_{(-\infty, \theta]}(x_2) \dots \mathbb{1}_{(-\infty, \theta]}(x_n) \mathbb{1}_{[0, \infty)}(x_1) \mathbb{1}_{[0, \infty)}(x_2) \dots \mathbb{1}_{[0, \infty)}(x_n) \\ &\stackrel{(*)}{=} \frac{1}{\theta^n} \mathbb{1}_{(-\infty, \theta]}(\max\{x_1, x_2, \dots, x_n\}) \mathbb{1}_{[0, \infty)}(\min\{x_1, x_2, \dots, x_n\}) \\ &\stackrel{(**)}{=} f_T(\max\{x_1, x_2, \dots, x_n\}; \theta) \frac{\mathbb{1}_{[0, \infty)}(\min\{x_1, x_2, \dots, x_n\})}{\max\{x_1, x_2, \dots, x_n\}^{n-1}}. \end{aligned}$$

where the equality (\*) is justified by the fact that all  $x_k$  are  $\leq \theta$  if and only if  $\max\{x_1, x_2, \dots, x_n\} \leq \theta$  while all  $x_k$  are non-negative if and only if  $\min\{x_1, x_2, \dots, x_n\}$  is non-negative. Also equality (\*\*) is justified by (3.6). Thus we can take  $H(x_1, x_2, \dots, x_n) = \frac{\mathbb{1}_{[0, \infty)}(\min\{x_1, x_2, \dots, x_n\})}{\max\{x_1, x_2, \dots, x_n\}^{n-1}}$  which now it does not depend at all on  $\theta$ .

The second argument uses the factorization theorem as follows and the sequence of equalities in (3.8) only up until (including) equality (\*). In other words, we write

$$\begin{aligned} f(x_1; \theta) f(x_2; \theta) \dots f(x_n; \theta) &= \frac{1}{\theta^n} \mathbb{1}_{(-\infty, \theta]}(\max\{x_1, x_2, \dots, x_n\}) \mathbb{1}_{[0, \infty)}(\min\{x_1, x_2, \dots, x_n\}) \\ &= k_1(\max\{x_1, x_2, \dots, x_n\}; \theta) k_2(x_1, x_2, \dots, x_n) \end{aligned}$$

and from factorization Theorem 2, we get the conclusion.  $\square$

**Problem 11.** Find a sufficient statistic for a sample from  $\text{Beta}(\theta, 2)$ . Recall that the density of  $\text{Beta}(\alpha, \beta)$  has density  $\frac{x^{\alpha-1}(1-x)^{\beta-1}}{B(\alpha, \beta)}$  where  $B(\alpha, \beta) = \frac{\Gamma(\alpha)\Gamma(\beta)}{\Gamma(\alpha+\beta)}$  and  $\Gamma(\alpha) = \int_0^\infty x^{\alpha-1}e^{-x}dx$ .

**Solution.** The Beta distribution is given by density

$$f(x; \theta) = \frac{x^{\theta-1}(1-x)}{\theta(\theta+1)} \mathbb{1}_{[0,1]}(x)$$

in other words, the density is  $\frac{x^{\theta-1}(1-x)}{\theta(\theta+1)}$  for  $x \in [0, 1]$  and is 0 otherwise. The shortcut to the problem is to notice that this is written as

$$f(x; \theta) = e^{\ln(\frac{x^{\theta-1}(1-x)}{\theta(\theta+1)})} = e^{(\theta-1)\ln(x) + \ln(1-x) - \ln(\theta(\theta+1))}$$

for  $0 < x < 1$  and 0 otherwise. Thus, this is a regular exponential family and consequently, a complete and sufficient statistic based on a sample of size  $n$  is  $T = \sum_{k=1}^n \ln(x_k) = \ln(\prod_{k=1}^n x_k)$ . This is also the MVUE for the parameter  $\theta$ .  $\square$

**Problem 12.** Find a sufficient statistics for a sample from a Bernoulli distribution with parameter  $\theta$ . Is this statistic sufficient? Can you find the MVUE for the sample? Hint: write the pmf as  $f_X(x; \theta) = \theta^x(1-\theta)^{1-x}$ .

**Solution.** We discussed this in class. For completeness, just notice that

$$f(x; \theta) = e^{\ln(\theta)x + \ln(1-\theta)(1-x)} = e^{\ln(\theta/(1-\theta))x + \ln(1-\theta)}$$

and consequently, for a sample of size  $n$ , we have a complete and sufficient statistics given by  $T = \sum_{k=1}^n X_k$ . This is not unbiased, but a simple calculation gives that

$$\mathbb{E}[T] = n\theta$$

therefore a quick fix is that  $T/n$  is an unbiased estimator and according to the combination of Rao-Blackwell and Lehman-Shaffe's Theorems 3 and 5, we get that  $T/n$  is the MVUE.  $\square$

**Problem 13.** If  $X_1, X_2, \dots, X_n$  is a sample from the  $\text{Poisson}(\lambda)$ , then  $\sum_{k=1}^n X_k$  is a sufficient statistic. Find a MVUE? Justify your answer.

**Solution.** We did this in class, and is based on the fact that the Poisson is a regular exponential family, with

$$f(x; \theta) = e^{\ln(\theta)x - \ln(x!) - \theta}$$

and thus a complete and sufficient statistic is  $T = \sum_{k=1}^n X_k$ . Again, as in Bernoulli case from Problem 12,  $\mathbb{E}[T] = n\theta$  and consequently,  $T/n$  is the MVUE for  $\theta$ .  $\square$

**Problem 14.** Assume that  $X_1, X_2, \dots, X_n$  is a sample from the density

$$f(x; \theta) = \begin{cases} e^{-(x-\theta)}, & x > \theta \\ 0, & \text{otherwise.} \end{cases}$$

- (1) Is  $f(x; \theta)$  a regular exponential family?
- (2) Find a sufficient statistic for  $\theta$ .

**Solution.** (1) This is not a regular exponential family because the support of each  $f(x; \theta)$  depends on  $\theta$ , thus, it does not satisfy the definition in Definition 2.1 because we have

$$f(x; \theta) = \begin{cases} e^{-x-\theta}, & x > \theta \\ 0, & \text{otherwise.} \end{cases}$$

This looks as an exponential family, except that the support (the set where the density is non-zero) depends on  $\theta$ . This is not okay with the definition.

- (2) Intuitively, a sufficient statistic is a statistic which contains almost all information about  $\theta$ . One observation is that if we have a sample  $x_1, x_2, \dots, x_n$ , then  $\theta < \min\{x_1, x_2, \dots, x_n\}$ . This suggests something about the min.

To find a sufficient statistic we try to use the factorization property to unravel the structure. First we write

$$f(x; \theta) = \mathbb{1}_{[\theta, \infty)}(x) e^{-(x-\theta)}$$

We take the  $n$  sample and the likelihood function to write

$$\begin{aligned} f(x_1; \theta) f(x_2; \theta) \dots f(x_n; \theta) &= \mathbb{1}_{[\theta, \infty)}(x_1) e^{-(x_1-\theta)} \mathbb{1}_{[\theta, \infty)}(x_2) e^{-(x_2-\theta)} \dots \mathbb{1}_{[\theta, \infty)}(x_n) e^{-(x_n-\theta)} \\ &= \mathbb{1}_{[\theta, \infty)}(\min\{x_1, x_2, \dots, x_n\}) e^{n\theta} e^{-(x_1+x_2+\dots+x_n)} \\ &= k_1(\min\{x_1, x_2, \dots, x_n\}; \theta) k_2(x_1, x_2, \dots, x_n) \end{aligned}$$

where  $k_1(y; \theta) = \mathbb{1}_{[\theta, \infty)}(y) e^{n\theta}$  and  $k_2(x_1, x_2, \dots, x_n) = e^{-(x_1+x_2+\dots+x_n)}$ .

These satisfy the condition from the factorization Theorem 2 and thus guarantees that  $T = \min\{X_1, X_2, \dots, X_n\}$  is a sufficient statistic. □

**Problem 15.** If  $X$  is a single sample from  $N(0, \theta)$ ,  $\theta > 0$  then  $X$  is a sufficient but not complete statistic for  $\theta$ . Can you give an example of a sufficient and complete statistic?

**Solution.** Interestingly,

$$f(x; \theta) = e^{x^2/(2\theta) - (1/2) \ln(2\pi\theta)}.$$

Thus this is a regular exponential family. This gives  $X^2$  as a complete and sufficient statistic for a single sample. However this does not show why  $X$  is a sufficient statistic because  $X$  is not a function of  $X^2$ .

On the other hand, we can write

$$f(x; \theta) = k_1(x; \theta) k_2(x)$$

with  $k_1(x; \theta) = e^{x^2/(2\theta) - (1/2) \ln(2\pi\theta)}$  and  $k_2(x) = 1$ . This shows now, from the factorization Theorem 2 that  $T = X$  is a sufficient statistic.

$X$  itself is not complete because we can find a function  $\phi$  such that  $\mathbb{E}[\phi(X)] = 0$  for all  $\theta$ , without having  $\phi$  identically 0. Indeed, the most natural function we can think of is an odd function. The simplest of them is  $\phi(x) = x$  and indeed we have  $\mathbb{E}[X] = 0$  for any  $\theta$ . Thus  $X$  is not complete. □

**Problem 16.** Show that the family  $N(\theta, \theta)$  for  $\theta > 0$  is a regular exponential family, but  $N(\theta, \theta^2)$  is not. Can you find a MVUE for  $\theta$ .

**Solution.** Clearly for  $N(\theta, \theta)$  we have

$$f(x; \theta) = \frac{1}{\sqrt{2\pi\theta}} e^{-(x-\theta)/(2\theta)} = e^{-x^2/(2\theta) + x - \theta/2 - (1/2) \ln(2\pi\theta)}$$

and this is a regular family with  $K(x) = x^2$ ,  $p(\theta) = -1/(2\theta)$ ,  $S(x) = x$ ,  $q(\theta) = -\theta/2 - (1/2) \ln(2\pi\theta)$ . From this we get that an MVUE for  $\theta$ , based on a sample  $X_1, X_2, \dots, X_n$  is  $\sum_{k=1}^n X_k^2$ .

The other family, namely  $N(\theta, \theta^2)$  has

$$f(x; \theta) = \frac{1}{\sqrt{2\pi\theta^2}} e^{-(x-\theta)/(2\theta^2)} = e^{-x^2/(2\theta^2) + x\theta - 1/2 - (1/2) \ln(2\pi\theta^2)}.$$

It is not possible to write  $-x^2/(2\theta^2) + x\theta = p(\theta)K(x)$  because we would have for  $\theta = 1$ ,  $p(1)K(x) = -x^2/2 + x$ , while for  $\theta = -1$ ,  $p(-1)K(x) = -x^2/2 - x$ . This means that  $p(1)$  and  $p(-1)$  would be non-zero and subtracting the two equalities would give  $(p(1) - p(-1))K(x) = 2x$ , thus  $K$  must be of the form  $K(x) = ax$ . Plugging this back into  $p(1)K(x) = -x^2/2 + x$ , shows that  $p(1)ax = -x^2/2 + x$  which is not possible. □

**Problem 17.** Let  $f(x; \theta)$  for  $\theta$  positive integer be the uniform distribution on  $\{1, 2, 3, \dots, \theta\}$ . Take a sample  $X_1, X_2, \dots, X_n$ .

- (1) Set  $T = \max\{X_1, X_2, \dots, X_n\}$ . Show that  $T$  is a sufficient statistic.
- (2) Show that  $T$  is also a complete statistic.
- (3) Prove that  $U = \frac{T^{n+1} - (T-1)^{n+1}}{T^n - (T-1)^n}$  is the unique MVUE of  $\theta$ .

**Solution.** (1) This is very similar to the Problem 10 and we use here the factorization theorem. First write

$$f(x; \theta) = \frac{1}{\theta} \mathbb{1}_{[0, \theta]}(x)$$

and then for an  $n$  sample  $x_1, x_2, \dots, x_n$  we have

$$\begin{aligned} f(x_1; \theta) f(x_2; \theta) \dots f(x_n; \theta) &= \frac{1}{\theta^n} \mathbb{1}_{[0, \theta]}(x_1) \mathbb{1}_{[0, \theta]}(x_2) \dots \mathbb{1}_{[0, \theta]}(x_n) \\ &= \frac{1}{\theta^n} \mathbb{1}_{(-\infty, \theta]}(x_1) \mathbb{1}_{(-\infty, \theta]}(x_2) \dots \mathbb{1}_{(-\infty, \theta]}(x_n) \mathbb{1}_{[0, \infty)}(x_1) \mathbb{1}_{[0, \infty)}(x_2) \dots \mathbb{1}_{[0, \infty)}(x_n) \\ &= \frac{1}{\theta^n} \mathbb{1}_{(-\infty, \theta]}(\max\{x_1, x_2, \dots, x_n\}) \mathbb{1}_{[0, \infty)}(\min\{x_1, x_2, \dots, x_n\}). \end{aligned}$$

Thus from factorization Theorem 2 with  $k_1(x; \theta) = \mathbb{1}_{(-\infty, \theta]}(x)/\theta^n$  and  $k_2(x_1, x_2, \dots, x_n) = \mathbb{1}_{[0, \infty)}(\min\{x_1, x_2, \dots, x_n\})$  we conclude that  $T = \max\{X_1, X_2, \dots, X_n\}$  is a sufficient statistic.

- (2) The completeness is a little different. We need to first compute the distribution of  $T$ . This is done by first computing the cumulative function and then extracting the pmf. Thus, for  $t \in \{0, 1, 2, \dots, \theta\}$

$$\begin{aligned} F_T(t) &= \mathbb{P}(\max\{X_1, X_2, \dots, X_n\} \leq t) = \mathbb{P}(X_1 \leq t, X_2 \leq t, \dots, X_n \leq t) \\ &= \mathbb{P}(X_1 \leq t) \mathbb{P}(X_2 \leq t) \dots \mathbb{P}(X_n \leq t) \\ &= \left(\frac{t}{\theta}\right)^n \end{aligned}$$

Thus

$$(3.8) \quad \mathbb{P}(T = t) = \mathbb{P}(T \leq t) - \mathbb{P}(T \leq t - 1) = \frac{t^n - (t - 1)^n}{\theta^n} \text{ for } t \in \{1, 2, \dots, \theta\}.$$

To see if the estimator  $T$  is complete, we need to check that if  $\phi$  is a function, then (from (1.2))

$$\mathbb{E}[\phi(T)] = \sum_{k=1}^{\theta} \phi(k) \mathbb{P}(T = k) = \sum_{k=1}^{\theta} \phi(k) \frac{k^n - (k - 1)^n}{\theta^n}$$

If this is 0 for any choice of  $\theta$ , this means that  $\sum_{k=1}^{\theta} \phi(k)(k^n - (k - 1)^n) = 0$ , thus, for  $\theta = 1$  we get  $\phi(1) = 0$ , for  $\theta = 2$ , we get that  $\phi(2)(2^n - 1) = 0$  and thus  $\phi(2) = 0$ . In general if we subtract the equalities obtained for  $\theta$  and  $\theta - 1$ , we get

$$\phi(\theta)(\theta^n - (\theta - 1)^n) = 0$$

which gives  $\phi(\theta) = 0$  for any  $\theta = 1, 2, \dots$ . In particular this means that  $\phi$  is identically 0 on the positive integers, which means that  $T$  is a complete statistic.

- (3) If we show that  $U = \frac{T^{n+1} - (T-1)^{n+1}}{T^n - (T-1)^n}$ , then the combination of Theorems 3 and 5 shows that the estimator  $U$  is the MVUE. Thus the only thing we need to show is that  $U$  is unbiased. To this end, we use (1.2) to compute

$$\mathbb{E}[U] = \mathbb{E}[\phi(T)] = \sum_{t=1}^{\theta} \frac{t^{n+1} - (t - 1)^{n+1}}{t^n - (t - 1)^n} \mathbb{P}(T = t)$$

where  $\phi(t) = \frac{t^{n+1} - (t-1)^{n+1}}{t^n - (t-1)^n}$ . Now using (3.8), we have

$$\begin{aligned} \mathbb{E}[U] &= \sum_{t=1}^{\theta} \frac{t^{n+1} - (t - 1)^{n+1}}{t^n - (t - 1)^n} \frac{t^n - (t - 1)^n}{\theta^n} \\ &= \frac{1}{\theta^n} \sum_{t=1}^{\theta} (t^{n+1} - (t - 1)^{n+1}) \\ &= \frac{1}{\theta^n} \theta^{n+1} = \theta \end{aligned}$$

where the last sum is a telescoping sum and thus it simplifies to the last term. Consequently,  $U$  is an unbiased estimator and thus unique MVUE. □