

Security Arguments and Tool-based Design of Block Ciphers

PhD Defense

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Topics of the Thesis

Based on mainly four papers:

Security Arguments

- A. Canteaut, L. Kölsch, and F. Wiemer. *Observations on the DLCT and Absolute Indicators*. 2019. iacr: [2019/848](#)
- A. Canteaut, V. Lallemand, G. Leander, P. Neumann, and F. Wiemer. “Bison – Instantiating the Whitened Swap-Or-Not Construction”. In: *EUROCRYPT 2019, Part III*. 2019, pp. 585–616. iacr: [2018/1011](#)

Tool-based Design

- T. Kranz, G. Leander, K. Stoffelen, and F. Wiemer. “Shorter Linear Straight-Line Programs for MDS Matrices”. In: *IACR Trans. Symm. Cryptol.* 2017.4 (2017), pp. 188–211. iacr: [2017/1151](#)
- G. Leander, C. Tezcan, and F. Wiemer. “Searching for Subspace Trails and Truncated Differentials”. In: *IACR Trans. Symm. Cryptol.* 2018.1 (2018), pp. 74–100

The General Setting

Block Ciphers and Security Notion

Def.: Block Cipher

- $E : \mathcal{K} \times \mathcal{M} \rightarrow \mathcal{C}$ family of permutations, with
 \mathcal{K} the key space, \mathcal{M} the message space,
 and \mathcal{C} the cipher space
- In practice: $\mathcal{K} = \mathbb{F}_2^m$ and $\mathcal{M} = \mathcal{C} = \mathbb{F}_2^n$.
 $E : \mathbb{F}_2^m \times \mathbb{F}_2^n \rightarrow \mathbb{F}_2^n$ is the *encryption*,
 $D = E^{-1}$ the *decryption*,
 m the *key length* and n the *block length*.

Further $E_k = E(k, \cdot)$ and $\text{Perm}_n = \{f : \mathbb{F}_2^n \rightarrow \mathbb{F}_2^n \mid f \text{ is permutation}\}$ the set of n -bit permutations.

Def.: Security

A block cipher E is (q, t, ε) -secure, if the (CPA)-advantage of every (q, t) -adversary is bound by ε :

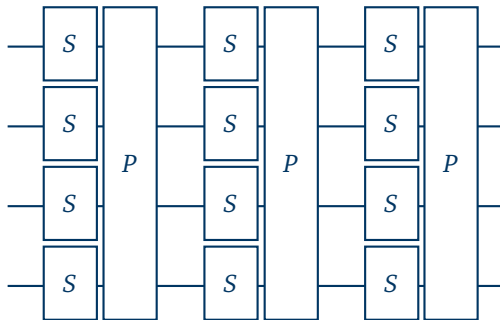
$$\text{Adv}_E^{\text{PRP-CPA}}(\mathcal{A}_{q,t}) := \left| \Pr_{k \in_R \mathbb{F}_2^m} [\mathcal{A}_{q,t}^{F_k} = 1] - \Pr_{f \in_R \text{Perm}_n} [\mathcal{A}_{q,t}^f = 1] \right| \leq \varepsilon .$$

In practice: security of a block cipher always security against known attacks.

Substitution Permutation Networks

The most common design structure for block ciphers

Exemplary SPN Structure

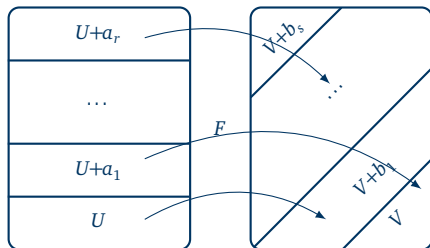


- S-box $S : \mathbb{F}_2^n \rightarrow \mathbb{F}_2^n$ provides *confusion* and non-linearity on small blocks (typically $3 \leq n \leq 8$)
- Linear layer $P : \mathbb{F}_2^{kn} \rightarrow \mathbb{F}_2^{kn}$ provides *diffusion* and spreads the S-box influence over the whole state
- Key-alternating: the round keys are added in between the rounds

- 1 Introduction
- 2 Subspace Trail Attack
- 3 Propagating Subspaces
- 4 Security for SPNs against Subspace Trail Attacks
- 5 Conclusion

Subspace Trail Cryptanalysis

Idea: Subspace Trails



Def.: Subspace Trails [GRR16] (FSE'16)

Let $U_0, \dots, U_r \subseteq \mathbb{F}_2^n$, and $F : \mathbb{F}_2^n \rightarrow \mathbb{F}_2^n$. If

$$\forall a \in U_i^\perp : \exists b \in U_{i+1}^\perp : F(U_i + a) \subseteq U_{i+1} + b,$$

these subspaces form a *subspace trail* (ST).

Notation: $U_0 \Rightarrow^F \dots \Rightarrow^F U_r$.

The Problem/Our Goal

Find a solution to

Problem: Security against Subspace Trails

Given an SPN with round function F , consisting of

- k parallel applications of an S-box $S : \mathbb{F}_2^n \rightarrow \mathbb{F}_2^n$ and
- a linear layer $L : \mathbb{F}_2^{kn} \rightarrow \mathbb{F}_2^{kn}$.

Compute an upper bound on the length of any subspace trail through the cipher.

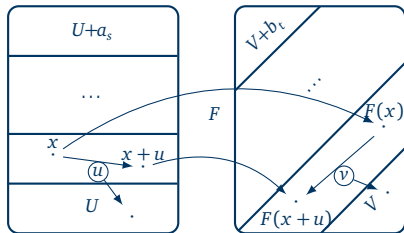
Subspace Propagation

Given a starting subspace U , we can efficiently compute the corresponding longest subspace trail.

Lemma

Let $U \xrightarrow{F} V$ be a ST. Then for all $u \in U$ and all $x: F(x) + F(x+u) \in V$.

Proof



Computing the subspace trail

- To compute the next subspace, we have to compute the image of the derivatives.

Propagate a Basis

Actually it is enough to compute only the image of the derivatives in direction of U 's basis vectors.

Lemma

Given $U \subseteq \mathbb{F}_2^n$ with basis $\{b_1, \dots, b_k\}$. Then $\text{Span} \left\{ \bigcup_{u \in U} \text{Im } \Delta_u(F) \right\} = \text{Span} \left\{ \bigcup_{b_i} \text{Im } \Delta_{b_i}(F) \right\}$.

Proof: \supseteq trivial, \subseteq by induction over the dimension k of U

Let $u = \sum_{i=1}^k \lambda_i b_i$ and $v \in \text{Im } \Delta_u(F)$, i. e. there exists an x s. t.

$$v = F(x) + F(x + \sum_{i=1}^k \lambda_i b_i) = F(y + \lambda_k b_k) + F(y + \sum_{i=1}^{k-1} \lambda_i b_i) = \lambda_k \Delta_{b_k}(F)(y) + \lambda' \Delta_{u'}(F)(y).$$

Thus $v \in \text{Span} \left\{ \text{Im } \Delta_{b_k}(F) \cup \text{Im } \Delta_{u'}(F) \right\}$, where u' is contained in a $(k-1)$ dimensional subspace.

ComputeTrail Algorithm

Computation of Subspace Trails

Input: A nonlinear function $F : \mathbb{F}_2^n \rightarrow \mathbb{F}_2^n$, a subspace U .

Output: A subspace trail $U \xrightarrow{F} \dots \xrightarrow{F} V$.

```

1 function ComputeTrail( $F, U$ )
2   if  $\dim U = n$  then return  $U$ 
3    $V \leftarrow \emptyset$ 
4   for  $u_i$  basis vectors of  $U$  do
5     for enough  $x \in_R \mathbb{F}_2^n$  do
6        $V \leftarrow V \cup \Delta_{u_i}(F)(x)$ 
7    $V \leftarrow \text{Span}\{V\}$ 
8   return  $U \xrightarrow{F} \text{ComputeTrail}(F, V)$ 

```

Remaining Problem: cyclic STs

Correctness: previous two lemmata

Runtime:

- Line 4: max. n iterations
- Line 5: $n + c$ random vectors are enough
- Recursions: can stop after $r < n$ rounds
- Overall: $\mathcal{O}(n^3)$ evaluations of F

How to Bound the Length of Subspace Trails

Goal

Give an upper bound on the length of any subspace trail.

Naïve Approach I

$\forall U \subseteq \mathbb{F}_2^m$ run `ComputeTrail(F, U)`

Naïve Approach II

$\forall u \subseteq \mathbb{F}_2^m \setminus \{0\}$ run `ComputeTrail(F, Span {u})`

Problem

Exponentially many starting subspaces.

Problem

Still $2^m - 1$ starting subspaces.

Often used heuristic

Activate single S-boxes only. That is, for a round function with k S-boxes which are n -bit wide, choose $U = \{0\}^i \times V \times \{0\}^{k-i-1}$, where $V \subseteq \mathbb{F}_2^n$.

Activating a single S-box only

Problem

Heuristic not valid in general when we want to prove a bound on the subspace trail length. In particular one can construct examples where the best subspace trail does activate more than one S-box in the beginning.

The good case

However, we will see next a sufficient condition for the case when the heuristic is valid.

The Connection to Linear Structures

Let us observe how a single S-box S behaves regarding subspace trails:

Given a subspace trail $U \xrightarrow{S} V$, this implies

$$\Delta_u(S)(x) \in V \quad \text{for all } x \in \mathbb{F}_2^n \text{ and } u \in U.$$

By definition of the dual space V^\perp :

$$\langle \alpha, \Delta_u(S)(x) \rangle = 0 \quad \text{for all } \alpha \in V^\perp,$$

which are exactly the *linear structures* of S :

$$\text{LS}(S) := \{(\alpha, u) \mid \langle \alpha, \Delta_u(S)(x) \rangle \text{ is constant for all } x\}$$

S-boxes without Linear Structures

This observation implies that S-boxes without linear structures (e.g. the AES S-box) exhibit only two important subspace trails:

$$\{0\} \rightrightarrows \{0\} \quad \text{and} \quad \mathbb{F}_2^n \rightrightarrows \mathbb{F}_2^n$$

We can further show that subspace trails over an S-box layer without linear structures are direct products of the above two subspace trails.

Proof

$$\text{For all } \alpha = (\alpha_1, \dots, \alpha_k) \in V^\perp: \quad \langle \alpha, \Delta_u(F)(x) \rangle = \left\langle \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_k \end{pmatrix}, \begin{pmatrix} \Delta_{u_1}(S)(x_1) \\ \vdots \\ \Delta_{u_k}(S)(x_k) \end{pmatrix} \right\rangle = \sum_{i=1}^k \langle \alpha_i, \Delta_{u_i}(S)(x_i) \rangle = 0$$

Theorem

Let F be an S-box layer of k parallel S-boxes $S : \mathbb{F}_2^n \rightarrow \mathbb{F}_2^n$. If S has no non-trivial linear structures, then for every subspace trail $U \rightrightarrows^F V$:

$$U = V = U_1 \times \dots \times U_k,$$

with $U_i \in \{\{0\}, \mathbb{F}_2^n\}$.

S-boxes without Linear Structures

Resistance of SPN against Subspace Trails, without linear structures

The length ℓ of any subspace trail is upper bounded by

$$\ell \leq \max_{U \in \{\{0\}, \mathbb{F}_2^n\}^k} |\text{ComputeTrail}(F, U)|,$$

which needs 2^k evaluations of the ComputeTrail algorithm.

S-boxes with Linear Structures

Compared to the no-linear-structures-case, V^\perp can now contain much more elements, namely all combinations of linear structures, such that their corresponding constants sum to zero.

Instead, we can show that (for any not-trivially-insecure S-box) the subspace after the first S-box layer contains at least one element of a specific structure:

$$W_{i,\alpha} = \{0\}^{i-1} \times \{0, \alpha\} \times \{0\}^{k-i}.$$

Resistance of SPN against Subspace Trails, with linear structures

The length ℓ of any subspace trail is upper bounded by

$$\ell \leq \max_{W_{i,\alpha}} |\text{ComputeTrail}(F', W_{i,\alpha})| + 1,$$

which needs $k \cdot 2^n$ evaluations of the `ComputeTrail` algorithm.

Note: F' first applies the linear layer, then the S-box layer (b/c of the skipped first S-box layer).

Conclusion

Thanks for your attention!

Applications of ComputeTrail

- Bound longest probability-one subspace trail
- Link to Truncated Differentials
- Finding key-recovery strategies

