RUSTikales Rust for beginners

- 1. Recap
- 2. Structs

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- 3. Associated functions

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- 3. Associated functions
- 4. Methods

- Ownership-Model
- References
- Borrow Checker

- Ownership-Model
- References
- Borrow Checker
- Functions are declared using the keyword fn
 - Functions can take in parameters
 - Functions can return values

```
fn add(n: i32, m: i32) -> i32 {
    return n + m;
▶ Run | Debug
fn main() {
    let n: i32 = 10;
    let m: i32 = 20;
    let sum: i32 = add(n, m);
    println!("\{\} + \{\} = \{\}", n, m, sum);
```

```
fn add(n: i32, m: i32) -> i32 {
    return n + m;
                          Return type
▶ Run | Debug
fn main() {
    let n: i32 = 10;
    let m: i32 = 20;
    let sum: i32 = add(n, m);
    println!("\{\} + \{\} = \{\}", n, m, sum);
```

```
fn add(n: i32, m: i32) -> i32 {
    return n + m; Parameters
▶ Run | Debug
fn main() {
    let n: i32 = 10;
    let m: i32 = 20;
    let sum: i32 = add(n, m);
    println!("\{\} + \{\} = \{\}", n, m, sum);
```

```
fn add(n: i32, m: i32) -> i32 {
    return n + m;
▶ Run | Debug
fn main() {
                                  Function call
                           → Every parameter requires an argument
    let n: i32 = 10;
    let m: i32 = 20;
    let sum: i32 = add(n, m);
     println!("\{\} + \{\} = \{\}", n, m, sum);
```

```
fn add(n: i32, m: i32) -> i32 {
     return n + m;
▶ Run | Debug
fn main() {
                                    Function call
                            → Every parameter requires an argument
     let n: i32 = 10;
                              → Returns a value which we can use
     let m: i32 = 20;
     let sum: i32 = add(n, m);
     println!("\{\} + \{\} = \{\}", n, m, sum);
```

```
fn forbidden(x: i32) {}
► Run | Debug
fn main() {
    let n: i32 = 10;
    forbidden(x: n);
    forbidden(x = n);
    forbidden(n);
```

```
fn forbidden(x: i32) {}
► Run | Debug
fn main() {
    let n: i32 = 10;
     forbidden(x: n);
                          Rust does not support named arguments
     forbidden(x = n)
     forbidden(n);
```

```
fn no_overload() {}
fn no_overload(x: i32) {}
fn no_overload() -> i32 { 0 }
```

```
fn no_overload() {}
fn no_overload(x: i32) {}
fn no_overload() -> i32 { 0 }
```

- Now that we're familiar with functions and basic types, we can write our first real programs
 - We want to create a console application where a ball bounces around the screen

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let mut ball_x: i32 = width / 2;
   let mut ball_y: i32 = height / 2;
    let mut ball_x_speed: i32 = 1;
    let mut ball_y_speed: i32 = 1;
    loop {
       print_window(ball_x, ball_y, width, height);
       // Ball bounce
       if ball x == 0 || ball x == width - 1 {
           ball_x_speed = -ball_x_speed;
        if ball_y == 0 || ball_y == height - 1 {
           ball_y_speed = -ball_y_speed;
        // Ball move
        ball_x += ball_x_speed;
        ball y += ball y speed;
        // Pause our application to simulate 60 FPS
       sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let mut ball_x: i32 = width / 2;
    let mut ball_y: i32 = height / 2;
    let mut ball_x_speed: i32 = 1;
    let mut ball y speed: i32 = 1;
    loop {
        print_window(ball_x, ball_y, width, height);
        // Ball bounce
        if ball_x == 0 || ball_x == width - 1 {
            ball_x_speed = -ball_x_speed;
        if ball_y == 0 || ball_y == height - 1 {
            ball_y_speed = -ball_y_speed;
                                                       Normal loop, our application will never stop
        // Ball move
        ball_x += ball_x_speed;
        ball y += ball y speed;
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
                                        Variables for the state of the application
    let mut ball_x: i32 = width / 2;
                                        → Our world is 60x20 units big
    let mut ball_y: i32 = height / 2;
                                        → Ball starts in the middle of the world
                                        → Ball moves to the bottom left
    let mut ball_x_speed: i32 = 1;
    let mut ball y speed: i32 = 1;
    loop {
        print_window(ball_x, ball_y, width, height);
        // Ball bounce
        if ball x == 0 || ball x == width - 1 {
            ball_x_speed = -ball_x_speed;
        if ball_y == 0 || ball_y == height - 1 {
            ball y speed = -ball y speed;
        // Ball move
        ball_x += ball_x_speed;
        ball y += ball y speed;
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let mut ball_x: i32 = width / 2;
    let mut ball_y: i32 = height / 2;
    let mut ball_x_speed: i32 = 1;
    let mut ball_y_speed: i32 = 1;
                                       This function prints the current state to the console
    loop {
        print_window(ball_x, ball_y, width, height);
        // Ball bounce
        if ball_x == 0 || ball_x == width - 1 {
            ball_x_speed = -ball_x_speed;
        if ball_y == 0 || ball_y == height - 1 {
            ball_y_speed = -ball_y_speed;
        // Ball move
        ball_x += ball_x_speed;
        ball y += ball y speed;
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let mut ball_x: i32 = width / 2;
    let mut ball_y: i32 = height / 2;
    let mut ball_x_speed: i32 = 1;
    let mut ball_y_speed: i32 = 1;
    loop {
        print_window(ball_x, ball_y, width, height);
           Ball bounce
        if ball_x == 0 || ball_x == width - 1 {
                                                    Simple bouncing logic:
            ball_x_speed = -ball_x_speed;
                                                    → If we're at the edge of the world, invert the velocity
                                                    → Ball moves in the opposite direction now
        if ball_y == 0 || ball_y == height - 1 {
                                                    → Breaks if the speed is not 1:^)
            ball_y_speed = -ball_y_speed;
         // Ball move
        ball_x += ball_x_speed;
        ball y += ball y speed;
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let mut ball_x: i32 = width / 2;
    let mut ball_y: i32 = height / 2;
    let mut ball_x_speed: i32 = 1;
    let mut ball_y_speed: i32 = 1;
    loop {
        print_window(ball_x, ball_y, width, height);
        // Ball bounce
        if ball x == 0 || ball x == width - 1 {
            ball_x_speed = -ball_x_speed;
        if ball_y == 0 || ball_y == height - 1 {
            ball_y_speed = -ball_y_speed;
         // Ball move
        <u>ball_x += ball_x_speed;</u> Update the position of the ball
        ball_y += ball_y_speed;
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let mut ball_x: i32 = width / 2;
    let mut ball_y: i32 = height / 2;
    let mut ball_x_speed: i32 = 1;
    let mut ball_y_speed: i32 = 1;
    loop {
        print_window(ball_x, ball_y, width, height);
        // Ball bounce
        if ball_x == 0 || ball_x == width - 1 {
            ball_x_speed = -ball_x_speed;
        if ball_y == 0 || ball_y == height - 1 {
            ball y speed = -ball y speed;
        // Ball move
                                        Rust is a fast language, we need to slow down our
                                        application so we can actually see the ball move
        ball_x += ball_x_speed;
        ball_y += ball_y_speed;
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```

Our world looks like this:



Our world looks like this:



```
pub fn main() {
    // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
                                         Notice how there is a lot of stuff to keep track of the ball state?
    let height: i32 = 20;
    let mut ball_x: i32 = width / 2;
    let mut ball_y: i32 = height / 2;
    let mut ball_x_speed: i32 = 1;
    let mut ball_y_speed: i32 = 1;
    loop {
        print_window(ball_x, ball_y, width, height);
        // Ball bounce
        if ball x == 0 || ball x == width - 1 {
            ball_x_speed = -ball_x_speed;
        if ball_y == 0 || ball_y == height - 1 {
            ball y speed = -ball y speed;
        // Ball move
        ball_x += ball_x_speed;
        ball y += ball y speed;
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
                                         Notice how there is a lot of stuff to keep track of the ball state?
    let height: i32 = 20;
                                                      → We need to initialize the ball
    let mut ball_x: i32 = width / 2;
                                                       → We need to update the ball
    let mut ball_y: i32 = height / 2;
    let mut ball_x_speed: i32 = 1;
    let mut ball_y_speed: i32 = 1;
    loop {
        print_window(ball_x, ball_y, width, height);
          Ball bounce
        if ball_x == 0 || ball_x == width - 1 {
            ball_x_speed = -ball_x_speed;
        if ball_y == 0 || ball_y == height - 1 {
            ball_y_speed = -ball_y_speed;
          Ball move
        ball_x += ball_x_speed;
        ball y += ball y speed;
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```

Structs are collections of values

- Structs are collections of values
- Structs allow us to create more complex data structures than just i32 or bool

- Structs are collections of values
- Structs allow us to create more complex data structures than just i32 or bool
- Structs are declared using the keyword struct

```
struct Point {
    x: i32,
    y: i32,
► Run | Debug
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
struct Point
    x: i32,
                Struct declaration
    y: i32,
► Run | Debug
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
struct Point {
    x: i32,
             Structs are made out of fields
▶ Run | Debug
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
struct Point {
    x: i32,
    y: i32,
▶ Run | Debug
fn main() {
                             Struct instantiation
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
struct Point {
    x: i32,
    y: i32,
▶ Run | Debug
fn main() {
                              Every field has to have a value
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
struct Point {
    x: i32,
    y: i32,
► Run | Debug
fn main() {p1 and p2 are instances of type Point
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
struct Point {
    x: i32,
    y: i32,
▶ Run | Debug
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
                      Using the dot operator, we can access fields
```

```
struct Point {
   x: i32,
   y: i32,
                    p1.x = 1
                    p2.y = 4
Run | Debug
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
struct Point {
    x: i32,
    y: i32,
                    p1.x = 1
► Run | Debug
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
struct Point {
    x: i32,
    y: i32,
                    p1.x = 1
► Run | Debug
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
struct Point {
    x: i32,
                             Structs are type definitions
    y: i32,
0 implementations
struct Line {
    points: Vec<Point>,
fn create_line(start: &Point, end: &Point) -> Line {
    panic!("Too much effort to figure this out :^)")
Run | Debug
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
struct Point {
    x: i32,
                              Structs are type definitions
    y: i32,
                           → Fields can be structs themselves
0 implementations
struct Line {
    points: Vec<Point>,
fn create_line(start: &Point, end: &Point) -> Line {
    panic!("Too much effort to figure this out :^)")
► Run | Debug
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
struct Point {
    x: i32,
                              Structs are type definitions
    y: i32,
                           → Fields can be structs themselves
                          → We can pass structs as parameters
0 implementations
struct Line {
    points: Vec<Point>,
fn create_line(start: &Point, end: &Point) -> Line {
    panic! ("Too much effort to figure this out :^)")
► Run | Debug
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
struct Point {
    x: i32,
                               Structs are type definitions
    y: i32,
                            → Fields can be structs themselves
                           → We can pass structs as parameters
                          → We can return structs from functions
0 implementations
struct Line {
    points: Vec<Point>,
fn create_line(start: &Point, end: &Point) -> Line {
    panic!("Too much effort to figure this out :^)")
► Run | Debug
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
struct Point {
    x: i32,
                                Structs are type definitions
    y: i32,
                             → Fields can be structs themselves
                           → We can pass structs as parameters
                           → We can return structs from functions
0 implementations
                       → And, of course, variables can have struct types
struct Line {
    points: Vec<Point>,
fn create_line(start: &Point, end: &Point) -> Line {
    panic!("Too much effort to figure this out :^)")
► Run | Debug
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
```

```
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };
    let line: Line = Line { points: vec![p1, p2] };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
}
```

```
fn main() {
    let p1: Point = Point { x: 1, y: 2 };
    let p2: Point = Point { x: 3, y: 4 };

    let line: Line = Line { points: vec![p1, p2] };
    println!("p1.x = {}", p1.x);
    println!("p2.y = {}", p2.y);
}

Normal Ownership and Borrow Checker rules apply to structs
    → By default, struct instances are always moved
```

```
struct Tree {
 value: i32,
 left: Tree,
 right: Tree
```

Struct instances, like other variables, are located on the Stack

Size of a struct must be known at compile time

```
struct Tree {
 value: i32,
 left: Tree,
 right: Tree
```

Struct instances, like other variables, are located on the Stack

- → Size of a struct must be known at compile time
- → The size of a struct is the size of all its fields

```
value: i32,
left: Tree,
right: Tree
```

Struct instances, like other variables, are located on the Stack

→ Size of a struct must be known at compile time

→ The size of a struct is the size of all its fields

→ Tree is recursive: We need the size of Tree to get its size!

→ Compiler error

```
struct Tree {
  value: i32,
  left: Box<Tree>,
  right: Box<Tree>
```

Struct instances, like other variables, are located on the Stack

→ Size of a struct must be known at compile time

→ The size of a struct is the size of all its fields

→ Tree is recursive: We need the size of Tree to get its size!

→ Compiler error

Solution: Add indirection

Box moves the value to the heap and is always pointer-sized

```
struct Tree {
  value: i32,
  left: Box<Tree>,
  right: Box<Tree>
```

Struct instances, like other variables, are located on the Stack

→ Size of a struct must be known at compile time

→ The size of a struct is the size of all its fields

→ Tree is recursive: We need the size of Tree to get its size!

→ Compiler error

Solution: Add indirection

→ Box moves the value to the heap and is always pointer-sized
→ sizeof<Tree> = sizeof<i32> + 2 * sizeof<Box> bytes
→ sizeof<Tree> = 4 + 2 * 8 = 20 bytes

Associated functions are functions associated with a type

- Associated functions are functions associated with a type
- Associated functions allow us to implement logic for types

- Associated functions are functions associated with a type
- Associated functions allow us to implement logic for types
- Associated functions are declared using the keyword impl

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
impl Line {
    fn new(start: &Point, end: &Point) -> Self {
        panic!("Still an unsolved problem :^)")
► Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x: 3, y: 4);
    let line: Line = Line::new(start: &p1, end: &p2);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
         return Self { x, y };
           Every function we declare in here
          gets associated with the type Point
impl Line {
    fn new(start: &Point, end: &Point) -> Self {
         panic!("Still an unsolved problem :^)")
► Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x:3, y:4);
    let line: Line = Line::new(start: &p1, end: &p2);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
         return Self { x, y };
impl Line {
    fn new(start: &Point, end: &Point) -> Self {
         panic! ("Still an unsolved problem :^)")
                   Every function we declare in here
                   gets associated with the type Line
► Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x:3, y:4);
    let line: Line = Line::new(start: &p1, end: &p2);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
         return Self { x, y };
                     Self is a type alias for the type we're currently implementing
impl Line {
    fn new(start: &Point, end: &Point) -> Self {
         panic!("Still an unsolved problem :^)")
► Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x:3, y:4);
    let line: Line = Line::new(start: &p1, end: &p2);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
         return Self { x, y }; Point
                 Point
                     Self is a type alias for the type we're currently implementing
impl Line {
                                                 Line
    fn new(start: &Point, end: &Point) -> Self {
         panic!("Still an unsolved problem :^)")
► Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x:3, y:4);
    let line: Line = Line::new(start: &p1, end: &p2);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
         return Self { x, y };
          In struct instantiations, if we assign the value of a variable to
            a field with the same name, we can save some typing
impl Line {
    fn new(start: &Point, end: &Point) -> Self {
         panic!("Still an unsolved problem :^)")
► Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x:3, y:4);
    let line: Line = Line::new(start: &p1, end: &p2);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
             This line is equivalent to
             return Point { x: x, y: y };
impl Line {
    fn new(start: &Point, end: &Point) -> Self {
         panic!("Still an unsolved problem :^)")
► Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x:3, y:4);
    let line: Line = Line::new(start: &p1, end: &p2);
```

```
impl Point {
     fn new(x: i32, y: i32) -> Self {
           return Self { x, y };
impl Line {
     fn new(start: &Point, end: &Point) -> Self {
           panic!("Still an unsolved problem :^)")
Because we're associating functions with a specific type, we can declare functions with the same name
                 → Point::new(x, y) is different from Line::new(start, end)
                    → Vec::new() is different from Point::new(x, y)
```

→ new() is different from Vec::new()

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
         return Self { x, y };
impl Line {
    fn new(start: &Point, end: &Point) -> Self {
         panic!("Still an unsolved problem :^)")
► Run | Debug
               When calling associated functions, we always have to specify the type
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x:3, y:4);
    let line: Line = Line::new(start: &p1, end: &p2);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
    fn distance(p1: &Point, p2: &Point) -> f64 {
        let dx: f64 = (p2.x - p1.x) as f64;
        let dy: f64 = (p2.y - p1.y) as f64;
        let xs: f64 = dx * dx;
        let ys: f64 = dy * dy;
        f64::sqrt(self: xs + ys)
▶ Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
   let p2: Point = Point::new(x:3, y:4);
    let d: f64 = Point::distance(&p1, &p2);
    println!("distance = {}", d);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
    fn distance(p1: &Point, p2: &Point) -> f64 {
        let dx: f64 = (p2.x - p1.x) as f64;
        let dy: f64 = (p2.y - p1.y) as f64;
        let xs: f64 = dx * dx;
        let ys: f64 = dy * dy;
        f64::sqrt(self:xs + ys)
          We can now implement special functions for our types
             → Here: Distance between two given points
► Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x: 3, y: 4);
    let d: f64 = Point::distance(&p1, &p2);
    println!("distance = {}", d);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
    fn distance(p1: &Point, p2: &Point) -> f64 {
        let dx: f64 = (p2.x - p1.x) as f64;
        let dy: f64 = (p2.y - p1.y) as f64;
        let xs: f64 = dx * dx;
        let ys: f64 = dy * dy;
        f64::sqrt(self:xs + ys)
               The last expression in a function is also the return value
                         → Writing return is optional
▶ Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x: 3, y: 4);
    let d: f64 = Point::distance(&p1, &p2);
    println!("distance = {}", d);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
    fn distance(p1: &Point, p2: &Point) -> f64 {
        let dx: f64 = (p2.x - p1.x) as f64;
        let dy: f64 = (p2.y - p1.y) as f64;
        let xs: f64 = dx * dx;
        let ys: f64 = dy * dy;
        f64::sqrt(self: xs + ys)
                                               How many calls to associated
                                       1/3
                                             functions are in this code snippet?
▶ Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x: 3, y: 4);
    let d: f64 = Point::distance(&p1, &p2);
    println!("distance = {}", d);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
    fn distance(p1: &Point, p2: &Point) -> f64 {
        let dx: f64 = (p2.x - p1.x) as f64;
        let dy: f64 = (p2.y - p1.y) as f64;
        let xs: f64 = dx * dx;
        let ys: f64 = dy * dy;
        f64::sqrt(self:xs + ys)
                                               How many calls to associated
                                        1/3
                                              functions are in this code snippet?
▶ Run | Debug
                                                        \rightarrow 4
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x:3, y:4);
    let d: f64 = Point::distance(&p1, &p2);
    println!("distance = {}", d);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
    fn distance(p1: &Point, p2: &Point) -> f64 {
        let dx: f64 = (p2.x - p1.x) as f64;
        let dy: f64 = (p2.y - p1.y) as f64;
        let xs: f64 = dx * dx;
        let ys: f64 = dy * dy;
        f64::sqrt(self:xs + ys)
▶ Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x: 3, y: 4);
    let d: f64 = Point::distance(&p1, &p2);
    println!("distance = {}", d); Because we only borrow p1 and p2,
                                    we can still use them after this line
```

Methods are a special kind of associated functions

- Methods are a special kind of associated functions
- Methods are all associated functions where the first parameter is either self, &self or &mut self

- Methods are a special kind of associated functions
- Methods are all associated functions where the first parameter is either self, &self or &mut self
- Methods allow us to easily call associated functions on struct instances

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
      distance(p1: &Point, p2: &Point) -> f64 {
        let dx: f64 = (p2.x - p1.x) as f64;
        let dy: f64 = (p2.y - p1.y) as f64;
        let xs: f64 = dx * dx;
                                   Currently an associated function
        let ys: f64 = dy * dy;
                                    → First parameter is not self
        f64::sqrt(self: xs + ys)
▶ Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x: 3, y: 4);
    let d: f64 = Point::distance(&p1, &p2);
    println!("distance = {}", d);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
    fn distance(&self, p2: &Point) -> f64 {
        let dx: f64 = (p2.x - self.x) as f64;
        let dy: f64 = (p2.y - self.y) as f64;
        let xs: f64 = dx * dx;
        let ys: f64 = dy * dy;
        f64::sqrt(self:xs + ys)
▶ Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x: 3, y: 4);
    let d: f64 = p1.distance(&p2);
    println!("distance = {}", d);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
    fn distance(&self, p2: &Point) -> f64 {
        let dx: f64 = (p2.x - self.x) as f64;
        let dy: f64 = (p2.y - self.y) as f64;
        let xs: f64 = dx * dx;
                                    distance is now a method
        let ys: f64 = dy * dy;
                                    → First parameter is &self
        f64::sqrt(self: xs + ys)
▶ Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x: 3, y: 4);
    let d: f64 = p1.distance(&p2);
    println!("distance = {}", d);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
    fn distance(&self, p2: &Point) -> f64 {
        let dx: f64 = (p2.x - self.x) as f64;
        let dy: f64 = (p2.y - self.y) as f64;
        let xs: f64 = dx * dx;
        let ys: f64 = dy * dy;
        f64::sqrt(self:xs + ys)
                              self is now a specific instance of type Point
                   → We don't need to provide the type, there's only one option what it can be
▶ Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x: 3, y: 4);
    let d: f64 = p1.distance(&p2);
    println!("distance = {}", d);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
    fn distance(&self, p2: &Point) -> f64 {
        let dx: f64 = (p2.x - self.x) as f64;
        let dy: f64 = (p2.y - self.y) as f64;
        let xs: f64 = dx * dx;
        let ys: f64 = dy * dy;
        f64::sqrt(self:xs + ys)
                           We can use the dot operator to call the method
                                   → p1 is passed as &self
▶ Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x: 3, y: 4);
    let d: f64 = p1.distance(&p2);
    println!("distance = {}", d);
```

```
impl Point {
    fn new(x: i32, y: i32) -> Self {
        return Self { x, y };
    fn distance(&self, p2: &Point) -> f64 {
        let dx: f64 = (p2.x - self.x) as f64;
        let dy: f64 = (p2.y - self.y) as f64;
        let xs: f64 = dx * dx;
        let ys: f64 = dy * dy;
        f64::sqrt(self:xs + ys)
                            We can use the dot operator to call the method
                                    → p1 is passed as &self
                            → We now need to provide one less argument
Run | Debug
fn main() {
    let p1: Point = Point::new(x:1, y:2);
    let p2: Point = Point::new(x: 3, y: 4);
    let d: f64 = p1.distance(&p2);
    println!("distance = {}", d);
```

```
fn update(&mut self, x: i32, y: i32) {
       self.x = x;
       self.y = y;
▶ Run | Debug
fn main() {
    let mut p1: Point = Point::new(x:1, y:2);
    println!("before: {}", p1.x);
    p1.update(x: 3, y: 4);
    println!("after: {}", p1.x);
```

```
fn update(&mut self, x: i32, y: i32) {
         self.x = x; Methods can also take mutable references to the instance
        self.y = y;
▶ Run | Debug
fn main() {
    let mut p1: Point = Point::new(x:1, y:2);
    println!("before: {}", p1.x);
    p1.update(x: 3, y: 4);
    println!("after: {}", p1.x);
```

```
fn update(&mut self, x: i32, y: i32) {
        self.x = x;
        self.y = y;
▶ Run | Debug
fn main() { To call a mutable method, we need to have a mutable instance
    let mut p1: Point = Point::new(x:1, y:2);
    println!("before: {}", p1.x);
    p1.update(x: 3, y: 4);
    println!("after: {}", p1.x);
```

```
fn update(&mut self, x: i32, y: i32) {
        self.x = x;
        self.y = y;
▶ Run | Debug
fn main() {
    let mut p1: Point = Point::new(x:1, y:2);
    println!("before: {}", p1.x);
    p1.update(x: 3, y: 4);
    println!("after: {}", p1.x);
      Rust automatically borrows for us, we don't need to write (&mut p1).update(...)
```

```
fn update(&mut self, x: i32, y: i32) {
       self.x = x;
       self.y = y;
▶ Run | Debug
fn main() {
   let mut p1: Point = Point::new(x:1, y:2);
   println!("before: {}", p1.x); before: 1
   p1.update(x: 3, y: 4);
   println!("after: {}", p1.x); after:
```

```
fn zero() -> Self {
        Self { x: 0, y: 0 }
    fn x(mut self, x: i32) -> Self {
        self.x = x;
        self
    fn y(mut self, y: i32) -> Self {
       self.y = y;
        self
} impl Point
► Run | Debug
fn main() {
    let p1: Point = Point::zero().x(3).y(4);
    println!("p1.x = {})", p1.x);
    println!("p1.y = {}", p1.y);
```

```
fn zero() -> Self {
        Self { x: 0, y: 0 }
    fn x(mut self, x: i32) -> Self {
        self.x = x;
                          Final version of methods:
        self
                       → Taking ownership of the instance
    fn y(mut self, y: i32) -> Self {
        self.y = y;
        self
} impl Point
► Run | Debug
fn main() {
    let p1: Point = Point::zero().x(3).y(4);
    println!("p1.x = {})", p1.x);
    println!("p1.y = {}", p1.y);
```

```
fn zero() -> Self {
        Self { x: 0, y: 0 }
    fn x(mut self, x: i32) -> Self {
        self.x = x;
         self
    fn y(mut self, y: i32) -> Self {
        self.y = y;
         self
} impl Point
                       Commonly seen with the builder pattern
► Run | Debug
                → Allows us to define a default instance, and set specific fields
fn main() {
    let p1: Point = Point::zero().x(3).y(4);
    println!("p1.x = {}", p1.x);
    println!("p1.y = {}", p1.y);
```

- Using our newfound knowledge, we can now use structs and methods for our ball application

```
struct Ball {
    x: i32,
    y: i32,
    x_speed: i32,
    y_speed: i32,
```

```
struct Ball {
                ball position in the world
      x_speed: i32,
     y_speed: i32,
```

```
struct Ball {
      x: i32,
      y: i32,
      x_speed: i32,
y_speed: i32,
                          velocity
```

```
impl Ball {
   fn check_bounce(&mut self, width: i32, height: i32) {
       if self.x == 0 || self.x == width - 1 {
            self.x_speed = -self.x_speed;
        if self.y == 0 || self.y == height - 1 {
           self.y_speed = -self.y_speed;
    fn move_ball(&mut self) {
       self.x += self.x_speed;
       self.y += self.y_speed;
```

```
impl Ball {
    fn check_bounce(&mut self, width: i32, height: i32) {
         if self.x == 0 || self.x == width - 1 {
              self.x speed = -self.x speed;
         if self.y == 0 || self.y == height - 1 {
              self.y_speed = -self.y_speed;
                                   Usually you would not use a redundant name, but move is a
                                         keyword and can't be a function name :^)
                                    → Redundant because we're implementing the struct Ball
       move_ball(&mut self) {
         self.x += self.x_speed;
         self.y += self.y_speed;
```

```
impl Ball {
    fn check_bounce(&mut self, width: i32, height: i32) {
        if self.x == 0 || self.x == width - 1 {
             self.x_speed = -self.x_speed;
        if self.y == 0 || self.y == height - 1 {
             self.y_speed = -self.y_speed;
                  Check if our ball instance hit the wall of the given world
    fn move_ball(&mut self) {
        self.x += self.x_speed;
        self.y += self.y_speed;
```

```
impl Ball {
    fn check_bounce(&mut self, width: i32, height: i32) {
        if self.x == 0 || self.x == width - 1 {
            self.x_speed = -self.x_speed;
        if self.y == 0 || self.y == height - 1 {
            self.y_speed = -self.y_speed;
    fn move_ball(&mut self)
        self.x += self.x_speed;
                                 Move the ball in our world
        self.y += self.y speed;
```

```
pub fn main() {
   // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let mut ball: Ball = Ball {
       x: width / 2,
       y: height / 2,
       x_speed: 1,
       y_speed: 1,
    loop {
        print_window(&ball, width, height);
        ball.check_bounce(width, height);
        ball.move_ball();
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from millis(1000 / 60));
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let mut ball: Ball = Ball {
        x: width / 2,
        y: height / 2,
                                  We now collected every relevant value
        x_speed: 1,
                                    for the ball state into a single struct
        y_speed: 1,
    };
    loop {
        print_window(&ball, width, height);
        ball.check_bounce(width, height);
        ball.move_ball();
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from millis(1000 / 60));
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let mut ball: Ball = Ball {
        x: width / 2,
        y: height / 2,
        x_speed: 1,
        y_speed: 1,
                              print_window() in the background was also
                               updated to take an instance of type Ball
    loop {
        print_window(&ball, width, height);
        ball.check_bounce(width, height);
        ball.move_ball();
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from millis(1000 / 60));
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let mut ball: Ball = Ball {
        x: width / 2,
        y: height / 2,
        x_speed: 1,
        y_speed: 1,
    loop { Our main loop is now more concise and readable, we can easily see what is going on
        print_window(&ball, width, height);
        ball.check_bounce(width, height);
        ball.move ball();
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from millis(1000 / 60));
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let mut ball: Ball = Ball {
        x: width / 2,
        y: height / 2,
        x_speed: 1,
                                    Additionally, because we isolated the ball logic,
        y_speed: 1,
                                    we can now easily create a whole list of balls :^)
    };
    loop {
        print window(&ball, width, height);
        ball.check_bounce(width, height);
        ball.move ball();
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from millis(1000 / 60));
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
   let ball: Ball = Ball { ···
    };
   let ball1: Ball = Ball { ···
    };
   let ball2: Ball = Ball { ···
    };
    let mut balls: Vec<Ball> = vec![ball, ball1, ball2];
    loop {
        print_window(&balls, width, height);
        for ball: &mut Ball in &mut balls {
            ball.check_bounce(width, height);
            ball.move_ball();
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```

```
pub fn main() {
   // Clear screen so we can freely use the cursor in print_window()
   print!("{}[2J", 27 as char);
   let width: i32 = 60;
   let height: i32 = 20;
   → We simply create more instances
   let ball1: Ball = Ball { ...
   };
    let ball2: Ball = Ball {|…
   };
    let mut balls: Vec<Ball> = vec![ball, ball1, ball2];
   loop {
       print_window(&balls, width, height);
       for ball: &mut Ball in &mut balls {
           ball.check_bounce(width, height);
           ball.move_ball();
       // Pause our application to simulate 60 FPS
       sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let ball: Ball = Ball { ···
    };
                                     → We simply create more instances
                                           → Add them to a list
   let ball1: Ball = Ball { ···
    };
    let ball2: Ball = Ball { ···
    };
    let mut balls: Vec<Ball> = vec![ball, ball1, ball2];
    loop {
        print_window(&balls, width, height);
        for ball: &mut Ball in &mut balls {
            ball.check_bounce(width, height);
            ball.move_ball();
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let ball: Ball = Ball { ···
    };
                                      → We simply create more instances
                                            → Add them to a list
    let ball1: Ball = Ball { ···
                                      → And apply our logic to all of them!
    };
    let ball2: Ball = Ball { ···
    };
    let mut balls: Vec<Ball> = vec![ball, ball1, ball2];
    loop {
        print_window(&balls, width, height);
        for ball: &mut Ball in &mut balls {
            ball.check_bounce(width, height);
            ball.move_ball();
           Pause our application to simulate 60 FPS
        sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```

```
pub fn main() {
    // Clear screen so we can freely use the cursor in print_window()
    print!("{}[2J", 27 as char);
    let width: i32 = 60;
    let height: i32 = 20;
    let ball: Ball = Ball { ···
    };
                                       → We simply create more instances
                                             → Add them to a list
    let ball1: Ball = Ball { ···
                                       → And apply our logic to all of them!
    };
                                        → And don't forget to draw all :^)
    let ball2: Ball = Ball { ···
    };
    let mut balls: Vec<Ball> = vec![ball, ball1, ball2];
    loop {
        print_window(&<u>balls</u>, width, height);
         for ball: &mut Ball in &mut balls {
             ball.check_bounce(width, height);
             ball.move_ball();
        // Pause our application to simulate 60 FPS
        sleep(dur: Duration::from_millis(1000 / 60));
} fn main
```



– Time for exercises!

```
1/3 struct Point {
      x: i32,
      y: i32,
      y: u32
  pub fn main() {
      let p: Point = Point { x: 1, y: 2 };
      println!("p.x = {}", p.x);
      println!("p.y = {}", p.y);
```

```
1/3 struct Point {
                                       Does the code compile?
                                       If yes, what does it print?
       x: i32,
       y: i32,
       y: u32
   pub fn main() {
       let p: Point = Point { x: 1, y: 2 };
       println!("p.x = {}", p.x);
       println!("p.y = {}", p.y);
```

```
1/3 struct Point {
                                            Does the code compile?
                                            If yes, what does it print?
        x: i32,
        <u>y</u>: i32,
                  Nope, field names must be unique:)
   pub fn main() {
        let p: Point = Point { x: 1, y: 2 };
        println!("p.x = {}", p.x);
        println!("p.y = {}", p.y);
```

```
struct Population {
    individuals: Vec<Individual>,
impl Population {
    fn get_average_age(&self) -> u32 {
        let mut sum: u32 = 0;
        for individual: &Individual in &self.individuals {
            sum += individual.age;
        sum / self.individuals.len() as u32
0 implementations
struct Individual {
    age: u32.
    height: u32,
pub fn main() {
    let bob: Individual = Individual { age: 32, height: 172 };
    let alice: Individual = Individual { age: 27, height: 160 };
    let mut population: Population = Population { individuals: vec![bob, alice] };
    population.individuals.push(Individual { age: 1, height: 50 });
    println!("Average age: {}", population.get_average_age());
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struct Population {
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        for individual: &Individual in &self.individuals {
             sum += individual.age;
                                                       The code does compile! This code is valid!
        sum / self.individuals.len() as u32
             Again, we can omit the return if the return value is the last expression in a function
                             → Don't forget to also omit the semicolon!
0 implementations
struct Individual {
    age: u32.
    height: u32,
pub fn main() {
    let bob: Individual = Individual { age: 32, height: 172 };
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        sum / self.individuals.len() as u32
                            After this line, there are three individuals in the population
                                            \rightarrow Bob, aged 32
0 implementations
                                           → Alice, aged 27
struct Individual {
                                            → Baby, aged 1
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    height: u32,
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                                           \rightarrow Bob, aged 32
0 implementations
                                           → Alice, aged 27
struct Individual {
                                           → Baby, aged 1
    age: u32.
    height: u32,
                                  The average age is 32+27+1=60/3=20:)
                                  Average age: 20
pub fn main() {
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        for individual: &Individual in &self.individuals {
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        sum / self.individuals.len() as u32
            If the population is empty, we divide by 0
0 implementations
struct Individual {
    age: u32.
    height: u32,
pub fn main() {
    let bob: Individual = Individual { age: 32, height: 172 };
    let alice: Individual = Individual { age: 27, height: 160 };
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            sum += individual.age;
        sum / self.individuals.len() as u32
0 implementations
struct Individual {
    age: u32.
    height: u32,
pub fn main() { Not using an associated function means we could set inhuman ages and heights
    let bob: Individual = Individual { age: 32, height: 172 };
    let alice: Individual = Individual { age: 27, height: 160 };
    let mut population: Population = Population { individuals: vec![bob, alice] };
    population.individuals.push(Individual { age: 1, height: 50 });
    println!("Average age: {}", population.get_average_age());
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        let mut sum: u32 = 0;
        for individual: &Individual in &self.individuals {
            sum += individual.age;
        sum / self.individuals.len() as u32
0 implementations
struct Individual {
    age: u32.
    height: u32,
pub fn main() {
                                                 We could add the same individual multiple times
    let bob: Individual = Individual { age: 32, height: 172 };
    let alice: Individual = Individual { age: 27, height: 160 };
    let mut population: Population = Population { individuals: vec![bob, alice] };
    population.individuals.push(Individual { age: 1, height: 50 });
    println!("Average age: {}", population.get_average_age());
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```
1/3 0 implementations
  struct A { child: D }
  0 implementations
  struct B { child: A }
  0 implementations
  struct C { child: B }
  0 implementations
  struct D { child: C }
```

```
1/3 0 implementations
                             Does this work?
  struct A { child: D }
  0 implementations
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  0 implementations
  struct D { child: C }
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```
1/3 0 implementations
                               Does this work?
  struct A { child: D }
  0 implementations
                               → sizeof<A> = sizeof<D>
  struct B { child: A }
  0 implementations
  struct C { child: B }
  0 implementations
  struct D { child: C }
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1/3 0 implementations
                                     Does this work?
   struct A { child: D }
  0 implementations
                                     → sizeof<A> = sizeof<D>
                                     → sizeof<B> = sizeof<A> = sizeof<D>
   struct B { child: A }
                                     → sizeof<C> = sizeof<B> = sizeof<A> = sizeof<D>
  0 implementations
  struct C { child: B }
  0 implementations
   struct D { child: C }
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```
1/3 0 implementations
                            Does this work?
  struct A { child: D }
  0 implementations
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  0 implementations
  struct C { child: B }
  0 implementations
  struct D { child: C }
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```
1/3 0 implementations
                                 Does this work?
  struct A { child: D }
  0 implementations
                                 → sizeof<A> = sizeof<D>
                                 → sizeof<B> = sizeof<A> = sizeof<D>
  0 implementations
                                 → To calculate the size of D, we need the size of D
                                 → Recursive
  struct C { child: B }
                                 → Does not work
  0 implementations
  struct D { child: C }
```

```
pub fn main() {
   let d: D = D {
        child: C {
            child: B {
                child: A {
                                                  Every field must have a value
                                          → We could never instantiate this struct anyway :(
                    child: D {
                        child: C {
                            child: B {
                                child: A {
                                    child: D {
                                         child: C {
                                             child: B {
                                                 child: A {
                                                     child: D {
                                                         child: C {
                                                             child: B {
                                                                 child: A {
                                                                     child: D {
                                                                         child: C {
                                                                              child: B {
                                                                                  child:
```

5. Next time

Traits