

Building the Bloomberg Interest Rate Curve – Definitions and Methodology.

Abstract

The goal of this document is to describe the process of interest rate (IR) curve construction and stripping in the Bloomberg terminal. We first introduce various types of rates used during curve stripping, then discuss the type of instruments commonly used in building the IR curves (cash rates, futures and IR swaps). Attention is given to a functional form of the curve (a.k.a. interpolation methods) and algorithms for building the curve under these different interpolation methods (i.e. curve *stripping*). We also cover various types of IR curve stripping including both single-currency and cross-currency curve stripping.

1. Interest Rate Curve – Definition

The IR Curve is an object which allows one to calculate a discount factor for every date in the future, thus providing us with the risk-free present value (*PV*) of a unit of currency (say, \$1) paying on that particular future date. It is widely used to calculate present values of a known set of payments (i.e. cash flows) for certain IR instruments. While in some situations one can construct an IR curve which takes in an additional discount (i.e. spread over risk free curve) due to risk of default of the counterparty, this document leaves the discussion of default or credit risk out. For the sake of simplicity, we will assume that the IR curves described in this document produce risk-free present values.

A second use for IR curves is to calculate projected forward rates between two dates ($d_1 \rightarrow d_2$) in the future. A typical example is to construct the payments of a 'floating leg' of an IR swap which pays, say, quarterly an amount of interest equal to 3-month LIBOR rate on a given notional. While the actual payments that will be made in the future are not known until we reach that point in time when LIBOR is fixed, the *PV* of this stream of payments is correct if we apply current projections of forward rates based on the known curve.

2. Types of Interest Rate

The definition of a *simple spot rate* r_s is expressed as:

$$DF(d_0, d) = \frac{1}{1 + r_c(t) \cdot \tau} \quad (1)$$

Here d_0 is the start date. Usually it is the settlement date of a financial instrument. d is some date in the future, $\tau = \tau(d_0, d)$ is the time interval between two dates (d_0, d) in years, and $DF(d_0, d)$ is the discount factor from the date d to start date d_0 . The only undefined term in the above definition is the method to convert a pair of dates (d_0, d) into a time interval τ in years. This conversion method is formally called *Day Count Convention*. There is more than one way of doing this: e.g. both *ACT/360* and *ACT/365* are very widely accepted conventions in the financial markets. For *ACT/360*, we assume there are 360 days per year and $\tau(d_1, d_2) =$

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$$PV(fixed\ leg) = \sum_{i=1}^n [N \cdot K \cdot \tau(i) \cdot DF(t_i)] + N \cdot DF(t_n)$$

For the floating leg, the payment amount is not determined from a known fixed rate, but relies on projected forward rates based on the forward curve. Without loss of generality, the present value can be readily expressed as:

$$PV(float\ leg) = \sum_{i=1}^n [N \cdot R(i) \cdot \hat{\tau}(i) \cdot DF(t_i)] + N \cdot DF(t_n)$$

For a typical vanilla swap, the payments in the floating leg are calculated based on a (L)IBOR rate at the accrual start time of the correspondent time interval. These rates change as market instrument rates change, thus the name *floating leg*.

$$PV(leq1) - PV(leq2) = 0$$

5. Interpolation Methods

If there are N number of instruments on the curve, to ensure that we have a unique solution, the discount factor function $DF(t)$ should have also N degrees of freedom. Therefore, $DF(t)$ is typically defined as a parametric function with N independent parameters:

$$DF(t) = DF(t, p_1, p_2, \dots p_N).$$

One way to achieve this is to break $DF(t)$ into N time intervals with the i^{th} interval covering period $[t_{i-1}, t_i]$. Here, t_i is the maturity time of the i^{th} instrument on the curve and $t_0 = 0$ is just the lower boundary of the discount factor function. The function will have N independent

[illegible]

parameters, one for each segment. There are typically two methods to solve for this system to determine $DF(t)$:

1) *Bootstrapping* method, where each time interval on the curve has exactly one independent degree of freedom and it does not affect previous time intervals. In this case the curve is built by adjusting one piece at a time while moving from shorter maturities to longer maturities.

2) *Global* method, where all or at least some degrees of freedom of the curve affect its overall shape, and therefore one needs to solve a general system of N non-linear equations with N unknown variables at the same time.

Currently the Bloomberg terminal allows the user to choose one of the 4 functional forms for the IR curve (a.k.a. *interpolation methods*). By typing **{SWDF DFLT <GO>}**, one will see the following screen:

1) Save		Swap Curve Defaults (UUID 21144274)	
Swap Curve Defaults			
1) Curve Settings		1) DV01/KRR Curve Settings	
Curve Defaults		Cross Currency Basis Defaults	
<input type="radio"/> Pay=Ask / Receive=Bid <input checked="" type="radio"/> Pay=Mid / Receive=Mid <input type="radio"/> Pay=Bid / Receive=Ask		<input type="radio"/> Basis side matches leg side <input type="radio"/> Basis side matches default curve side <input checked="" type="radio"/> Basis side always at mid	
Interpolation Method			
<input type="radio"/> 1 - Piecewise linear (Simple-comp) <input type="radio"/> 2 - Smooth forward/Piecewise quadratic <input checked="" type="radio"/> 3 - Step-function forward <input type="radio"/> 4 - Piecewise linear (Continuous-comp)			
Brazilian Curve Interpolation Method			
<input type="radio"/> 1 - Linear <input checked="" type="radio"/> 2 - Exponential <input type="radio"/> 3 - Natural cubic spline			

Fig. 2: Screen allowing user to choose curve interpolation method

On this screen one can choose 1 through 4 under the “Interpolation Method” section:

- 1) Piecewise linear
- 2) Smooth forward/Piecewise quadratic
- 3) Step-function forward
- 4) Piecewise linear

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$$DF(t) = \frac{1}{1 + r_s(t_1) \cdot t} \quad \text{when } t \in [0, t_1]$$

$$DF(t) = \frac{1}{1 + r_s(t_M) \cdot t} \quad \text{when } t \in [t_M, \infty]$$

Swap Curve Builder

Actions ▾ Modes ▾ Export Settings ▾
 EUR ▾ 201 - EUR (vs. 3M EURIBOR) ▾ Name EUR (vs. 3M EURIBOR) ▾ Default Privilege Global ▾ 02/02/23 ▾

Curve Construction Curve Analysis
 Curve # 201 - EUR (vs. 3M EURIBOR) ▾ Shift +0.00 bp
 Interpolation Piecewise Linear (Simple) ▾ Index Fixing EUR003M 2.54000%
 Settle Date 02/06/23 ▾
 Curve Side Mid ▾

Stripped Curve Forward Analysis Curve Horizon
 Interval 3M ▾ Tenor 3M ▾ Up to 30Yr ▾

Date	Zero Rate	Forward Rate
02/06/2023	N.A.	2.5672
05/06/2023	2.5672	3.3938
08/06/2023	2.9874	3.5472
11/06/2023	3.1760	3.5462
02/06/2024	3.2693	3.3529
05/06/2024	3.2859	3.1411
08/06/2024	3.2615	2.9306
11/06/2024	3.2139	2.7705
02/06/2025	3.1581	2.6567
05/06/2025	3.1037	2.5595
08/06/2025	3.0488	2.4584
11/06/2025	2.9947	2.3590
02/06/2026	2.9413	2.5529
05/06/2026	2.9121	2.4989
08/06/2026	2.8824	2.4449
11/06/2026	2.8530	2.3917

Fig. 3a: Spot rate (blue) and forward rate (orange) graphs for EUR curve with interpolation method 1.

from solving a series of continuity equations at the boundaries (see Appendix 3). Fig.3g shows an example of stripping results using BRL interpolation method 3 for BRL curve S89.

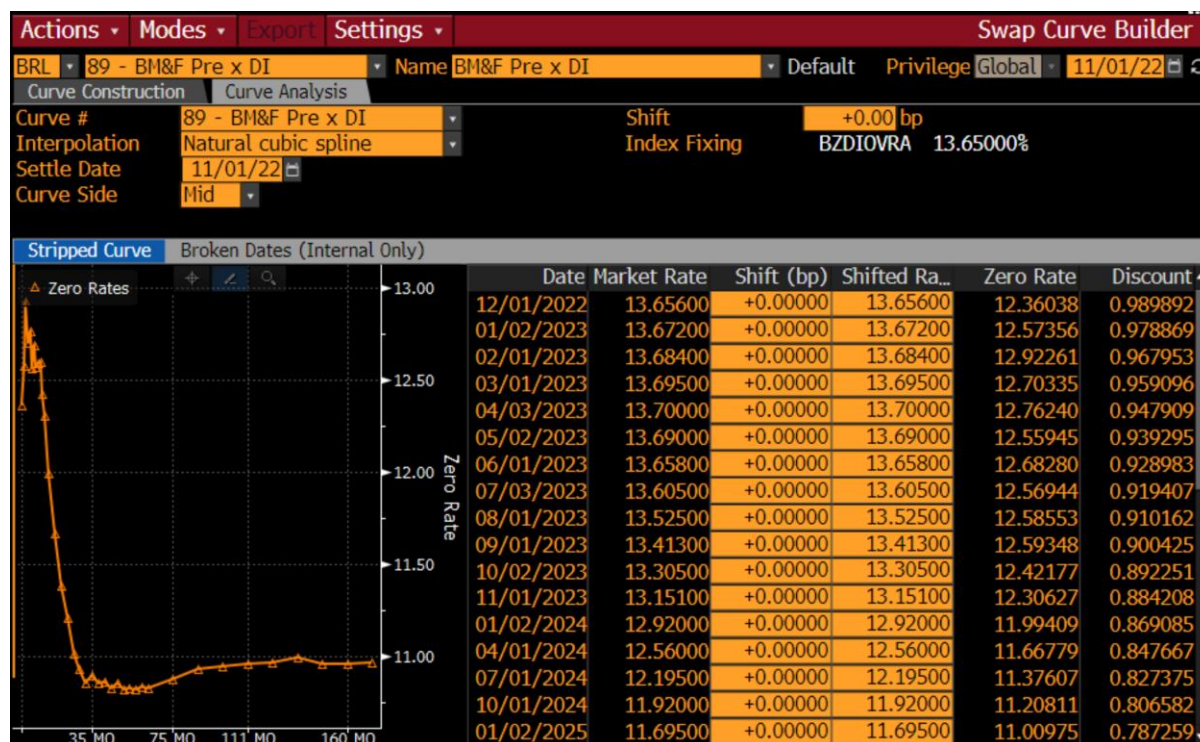


Fig. 3g: Spot rate graphs for BRL curve S89 with BRL interpolation method 3.

IR Curve stripping

We detail the stripping process for various types of IR curve in this section. Please note that all the unknown variables (i.e. to be solved for) are marked in red in the formulas below.

6.1 Vanilla Swap Curve

A vanilla swap instrument comprises a fixed and floating leg with associated market quote being the rate on the fixed leg. Figure 6a shows a standard 5 year vanilla swap instrument on SAR 3Mo SAIBOR curve S166. For the sake of simplicity, we still start with a currency where the market (generally) and Bloomberg still assume single curve stripping. In Fig.6a, the fixed leg pays 4.1935% interest every year, while the floating leg pays a floating 3Mo SAIBOR rate every 3 months.

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$$PV(3Mo\ leg) = \sum_i [N \cdot (R(i, S15) + spread) \cdot \hat{\tau}(i) \cdot df(t_i, S198)] + N \cdot df(t_M, S198)$$

$$PV(6Mo\ leg) = \sum_i [N \cdot R(j, S485) \cdot \hat{\tau}(j) \cdot df(t_j, S198)] + N \cdot df(t_M, S198)$$

Please note that both curve S15 and S198 are stripped before stripping curve S485, thus the PV on the 3Mo leg can be readily calculated and becomes a constant. While on the 6Mo leg, the effective rates from S485 are directly linked to the unknown discount factors from S485, which is similar to the above OIS discounting case. Finally, solving $PV(3Mo\ leg) = PV(6Mo\ leg)$ can determine a series of discount factors and finalize the $DF(t)$ for S485.

[illegible]

$$FXFwd(t) = FXSpot * \frac{df(t_{FXS}, S92)}{df(t_{FXS}, S490)} * \frac{df(t, S490)}{df(t, S92)}$$

where FX_{Spot} is the USD-EUR spot exchange rate, $FX_{Fwd}(t)$ is USD-EUR FX Forward rate at maturity t , and t_{FXS} is the FX settlement time. When we begin building the curve, all the terms in the above equation are known except for $df(t_{FXS}, S92)$ and $df(t, S92)$. When the first FX forward instrument is added, the curve builder solves for both $df(t_{FXS}, S92)$ and $df(t, S92)$. Once $df(t_{FXS}, S92)$ is known and stored, adding subsequent maturities, t , completely determine $df(t, S92)$.

You can see the transformed instruments in the ICVS snapshot above. In the FX forwards section, the last column shows the basis spread of the FX Basis swap that produces the same discount factor at the corresponding maturity as the FX forward, for that tenor.

A cross currency (XCCY) basis swap is a financial instrument where each counterparty exchanges payments in a different currency.

[illegible]

During stripping, the mathematical equation representing this swap is simply $PV(USD) = PV(HKD)$. Please note that S10 and S490 are already stripped, so all their derived values (forward rates / discount factors) are already determined. Principals on the USD/HKD legs are also determined at the inception of the swap. Thus $PV(USD)$ is actually a constant and the only unknowns are the discount factors from S96, which can be determined by solving the above equation.

6.6 Cross Currency Basis Curve Stripping (Mark-to-Market)

Basis swaps with this MTM feature are commonly referred to as resettable basis swaps, and an example can be viewed in the Bloomberg terminal by entering **{SWPM -FLFL USD EUR -MTM<GO>}**. In Fig.6e, please note the USD leg has a “*Notional Reset by FX” label at the top to indicate the mark-to-market notional resetting feature has been enabled for this leg of the swap. Also, in Fig 6f, we can see that the notional principal changes at every payment time on the USD leg.

[illegible]

Fig. 6e. 5Y MTM cross currency EUR/USD basis swap instrument on curve S92.

Fig. 6f. Example of cash flows of a 5Y MTM cross currency EUR/USD basis swap instrument on curve S92.

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At the i^{th} payment time for each side, let's assume $Notional(i)$ is the principal for this period, $F(i)$ is the projected forward rate derived from curve S490 or S514, $df(i)$ is the corresponding discount factor and $spread$ is the basis spread quote applied (on EUR leg for curve S92). We also assume the final principals need to be exchanged at maturity.

$$PV(EUR) = \sum_{i=1}^N [R(i, S514) + spread] \cdot \tau(i) \cdot df(t_i, S92) + df(t_N, S92)$$
$$\text{Coupon Payment } CP(j) = \text{Notional}(j, \text{USD}) \cdot R(j, S490) \cdot \tau(j)$$

Please note the final principal exchange pays off the entire principal amount, and $Notional(j, USD)$ becomes zero after the last payment.

$$Notional(j, USD) = Notional(USD) \cdot \frac{df(t_{j-1}^{FX}, EUR)}{df(t_{i-1}^{FX}, USD)} = Notional(USD) \cdot \frac{df(t_{j-1}^{FX}, S92)}{df(t_{i-1}^{FX}, S490)}$$

Since the notional on EUR-leg is fixed to be 1, $Notional(USD)$ is just initial FX rate (USD:EUR). Thus, we can write $PV(USD)$ as follows (M is the number of payments on this leg):

$$\begin{aligned} PV(USD) &= \sum_{j=1}^M [CP(j) + PE(j)] \cdot df(t_j, S490) \\ &= \sum_{j=1}^{M-1} [CP(j) + PE(j)] \cdot df(t_j, S490) + [CP(M) + Notional(M, USD)] \cdot df(t_M, S490) \end{aligned}$$

[illegible]

2) Completing Non-Anchor Chains via Interpolation. Next, we need to complete all the non-anchor chains. For S45, there are five such chains: 1MO (Cash) / 1 X 7 (FRA) / 7 X 13 (FRA) / 13 X 19 (FRA); 2MO (Cash) / 2 X 8 (FRA) / 8 X 14 (FRA) / 14 X 20 (FRA); etc. If any FRAs within these chains are missing, we linearly interpolate the FRA rate based on its neighboring FRAs from the anchor chain. The interpolation follows a weighted approach: for a missing FRA spanning T1 to T2, the rate is calculated as a weighted sum of the closest available FRAs in the anchor chain, with weights determined by the proportion of overlap in months. For example: if the 13 X 19 FRA rate is missing, then we calculate its FRA rate by adding (5 / 6) of 12 X 18 (FRA) and (1 / 6) of 18 X 24 (FRA) on the anchor chain; similarly, if the 1 X 7 FRA rate is missing, then we calculate its FRA rate by adding (5 / 6) of 6MO (Cash) and (1 / 6) of 6 X 12 (FRA). We emphasize that all the missing FRAs computed at this stage are based on linear interpolation of elements in the anchor chain from step 1. This ensures a smooth transition between observed and interpolated rates.

4) Final Stripping with Implied Cash Instruments. These implied cash instruments (1MO, 2MO,..., 5MO) are included in the final stripping along all the original calibration instruments with the aim of smoothing the forward rates across the FRA region.

Since these implied cash instruments are not exposed, they cannot be seen in **{SWDF 45 <GO>}**. As a result, users may notice that zero rates before 6Mo won't match their chosen interpolation (extrapolation, more accurately) method. This discrepancy arises because these implied cash rates are internally computed using the algorithm described above.

[illegible]

6.8 Ultimate Forward Rate (UFR) Curve Stripping (EIOPA methodology)

Insurance companies, for example, write insurance policies that can imply liabilities that materially exceed the tenors for most routinely traded securities in the public markets. Life insurance liabilities can routinely exceed 60-70 years, and retirement participation agreements have actuarial requirements that mandate the use of longevity risk that can exceed 100 years. Thus, the European Insurance and Occupational Pensions Authority (EIOPA) has chosen a prescriptive approach to the accounting of forward rates beyond those visible in the market.

In brief, this methodology requires constructing a risk-free interest rate curve based on selected market instruments which are further adjusted for credit risk using credit adjustment spread (CAS). Then this curve is stripped in accordance with the Smith-Wilson interpolation method, which ensures that the long end forward rate will converge to the UFR value published by EIOPA, at a speed determined by the given convergence criteria. The detailed information regarding this methodology can be found on the official EIOPA website:

https://www.eiopa.europa.eu/tools-and-data/risk-free-interest-rate-term-structures_en

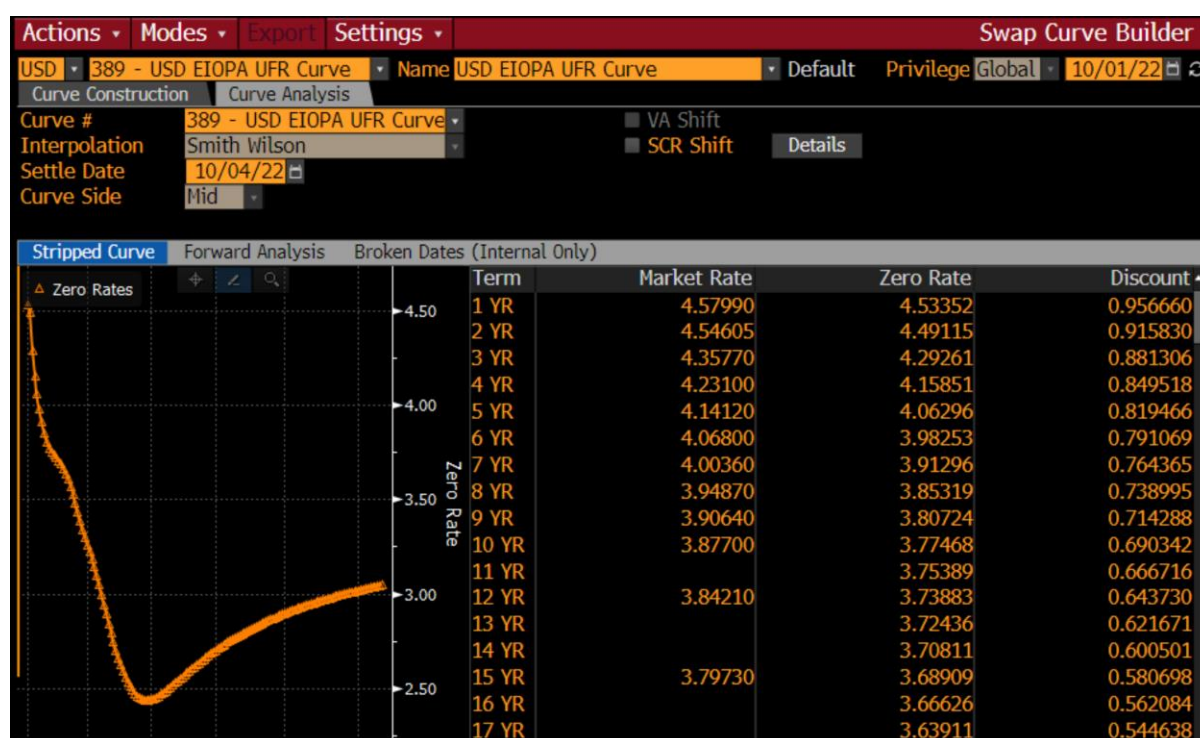


Fig. 6g. Example of the stripping results from USD UFR curve S389.

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$$DF(t) = \exp[-L(t)]$$

And L -polynomial is constructed as in its general form:

Here T_i is the maturity of the i^{th} instrument that matures after t_c on the curve. The big summation is done for all the instruments at $i \in [1, \dots, N]$ such that $T_i < t$, and this term makes $L(t)$ a piecewise cubic polynomial function. At each time $= T_i$, a new cubic polynomial term is added in a manner that assures that first and second order derivatives of $L(t)$ are continuous. There are N lambdas together with four extra parameters (b, c, d and P) in the above formula, therefore we need four boundary conditions to reduce the number of freedoms back to N in the curve stripping.

where $df(t)$ is an arbitrary function that covers the region from zero to the joint time t_c . Based on the requirements, we can impose appropriate boundary conditions at time t_c to connect these two functions properly.

This leads to two constraint equations:

Let's move on to the short end side, where we need to satisfy the continuity condition at the joint point t_c . Please note this is the $t = 0$ point for $L(t)$ internally, and in this region L -polynomial is reduced to:

[illegible]

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Since $L(0) = d$, we can see that parameter d is pre-determined by the joint function $df(t)$ at t_c point. And there is one more freedom to eliminate, we usually set $b = 0$ for simplicity. It will not only make $b \cdot t^2$ term disappear, but also lead to a simpler form of the above eq.2. After renaming the unknown parameter c to λ_0 , L -polynomial becomes:

The ultimate unknown parameters to be solved are $[\lambda_0, \lambda_1, \dots, \lambda_{N-1}]$ and both λ_N and P can be derived from eq.1 and eq.2 above.

$$L(t) = \lambda_0 \cdot t + \frac{1}{6} \sum_{T_i \leq t} \lambda_i \cdot (t - T_i)^3 - \frac{1}{6} P \cdot t^3$$

Since $L(0) = d$ and $L'(0) = c$, both parameter d and c are pre-determined by the joint function $df(t)$ at t_c point. The corresponding constraint equations are:

$$df'(t_c) = df(t_c) \cdot (-c) \quad (eq.4)$$

$$L(t) = (\lambda_0 \cdot t^2 + c \cdot t + d) + \frac{1}{6} \sum_{T_i \leq t} \lambda_i \cdot (t - T_i)^3 - \frac{1}{6} P \cdot t^3$$

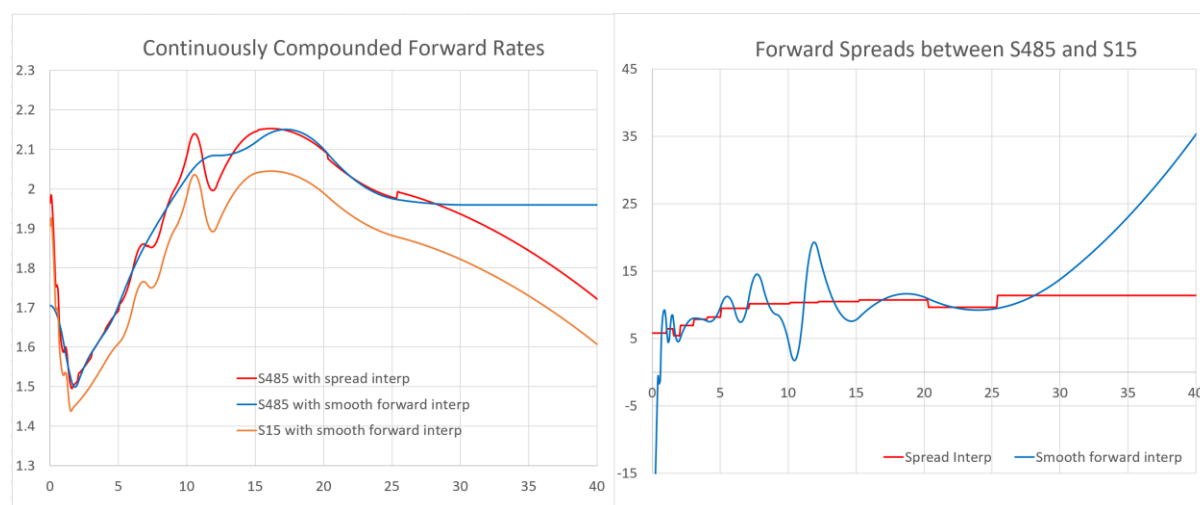
Overall, the curve is 'smooth' e.g. the forward rate has a continuous first order derivative, and it has N degrees of freedom. It is easy to see that change in any parameter λ_i where $i \in [0, \dots, N-1]$ leads to changes in λ_N and P , thus affecting the value of the function everywhere. Therefore, to strip curve with this interpolation, one needs to solve a system of N non-linear equations with N variables. The Newton Raphson method is used, with an initial guess found using interpolation method 1 (linear simple zero rate).

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This interpolation takes in a so-called base curve and applies a constant continuous forward spread (for each segment) on top of the forward rate generated directly from base curve to get the final forward rate. So, the final continuously compounded forward rate can be expressed as following:

Usually, t_1 is taken at the start time of this segment (t_s), which is the maturity time of the pervious instrument for most of the case. Thus, the discount factors at any time t within this segment can be readily calculated by:

Since the base curve is given from outside and already stripped, the $baseCCFwd(t_1, t_2)$ can be directly computed at any period. The only unknown variables left are the above $fwdSpread(s)$, one for each segment. The stripping process will apply a bootstrapping solver to determine all of these values one by one under no-arbitrage principal. The biggest advantage of this interpolation method is to allow the user to capture the feature of the benchmark (base curve), and focus on the deviation from it. Below is a graph that plots the continuously compounded forward rates for NZD 6Mo basis curve S485 under spread interpolation (red) as a function of time. It also displays the same forward rates for S485 using smooth forward interpolation, and the underlying NZD 3Mo curve S15 for comparison. It is quite obvious that the stripping results based on the spread interpolation are tracking the underlying curve much better than that from the smooth forward interpolation. Furthermore, smooth forward interpolation completely loses track of the underlying curve especially in the extrapolation region (beyond 30 years), while the spread interpolation still tracks it very well by keeping a constant distance above S.

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Let's first assume the second order derivatives at boundary x_i is k_i . Since the second order derivative $f_i''(x)$ of a cubic polynomial $f_i(x)$ is a linear function of x , we can rewrite $f_i''(x)$ to the following form based on k_i and k_{i+1} :

After integrating this function twice, we can get a general expression for the cubic polynomial $f_i(x)$ as:

Here C_1 and C_0 are two constants of integration. They can be further determined by using continuity constraints at boundaries: $f_i(x_i) = y_i$ and $f_i(x_{i+1}) = y_{i+1}$. This will finally transform $f_i(x)$ to:

This is the most general form of cubic splines based on the unknown second order derivatives at the boundaries. Additionally, we still need to ensure smoothness of the first order derivatives at the boundary, i.e., $f'_{i-1}(x_i) = f'_i(x_i)$, and this forces all the k_i to satisfy:

It is obvious to see from above equation that not all k_i are independent and we only have two extra degrees of freedom here. Normally, we will set the first and last k_i to be zero and the resulting $f_i(x)$ is called **natural cubic splines** which is also the BRL interpolation method 3 in our system. However, natural cubic spline is not the only valid result. By imposing different two extra constraints, we can have different final form of cubic splines $f_i(x)$ and they are all valid solutions to the given set of points.

[illegible]

References

- [1] John C. Hull, Options, Futures and Other Derivatives, Fifth edition, chapter 23, page 566
- [2] G. Kirikos and D. Novak, Convexity Conundrums, Risk, March 1997, pp 60-61
- [3] IR Futures Convexity: DOCS 2089953

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