

# Programming fundamentals

## Graphs

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# Plan for today

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- Graph traversals

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- Path finding

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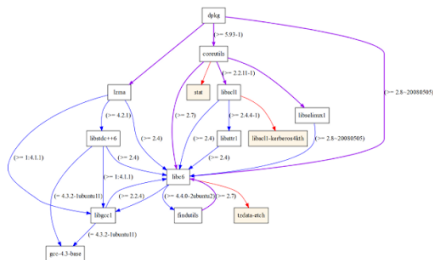
- Graphs
- Graph traversals
- Path finding
- NetworkX library

A graph is a collection of vertices and edges between them. There are different kinds of graphs, depending on:

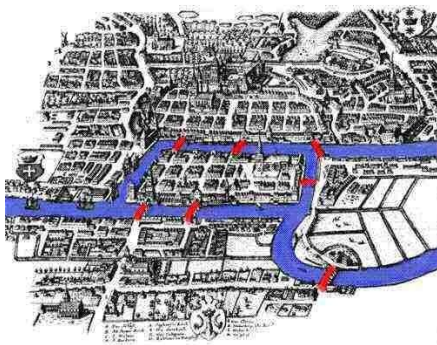
- If there are cycles in them
- If the edges have weight
- if the edges have direction

# Graphs

Graphs are used, for example, to represent dependencies between libraries



# Graphs



Or to represent famous problems



Graphs are used to solve games. For board games, for example, each vertex in the graph represents a possible state of the board, and edges represent moves by players.



# Graphs - representation

We can represent graphs using either **adjacency matrices** or **adjacency lists**.

# Graphs - representation

## Adjacency matrix

	a	b	c	d
a	0	1	0	0
b	1	0	1	1
c	0	1	0	1
d	0	1	1	1

# Graphs - representation

## Adjacency list

```
graph = {  
    1: [2,3,4],  
    2: [5, 6],  
    3: [],  
    4: [7, 8],  
    5: [],  
    6: [],  
    7: [],  
    8: []  
}
```

# Graphs - homework

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- ❷ Create a graph in Python that represents a subway map.
- ❸ Create a graph in Python that represents friendship in Facebook.



# Graphs - homework

- ❶ Create a graph in Python that represents a group of people and the debts between them.
- ❷ Create a graph in Python that represents a subway map.
- ❸ Create a graph in Python that represents friendship in Facebook.
- ❹ Think of a way of implementing them using either adjacency lists or adjacency matrices.

# Graph traversals

A graph traversal is the process of exploring a graph.

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A graph traversal is the process of exploring a graph.

There are two main ways of doing Graph traversals:

- Breadth First Search (**BFS**)
- Depth First search (**DFS**)

**Depth-first search** is a technique for traversing graphs in which we will go through a branch of it until we find its end before going to the next branch.

On the other hand, **Breadth-first search** will visit all the neighbors of a given node before moving to the next level of the graph.

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This is the traversal we will focus on today

# Understanding BFS

The technique we will use in order to traverse the queue can be described as follows:

- 1 Start from the given start node.

*our queue will be **FIFO***

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- 1 Start from the given start node.
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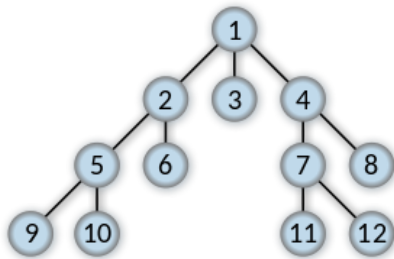
# Understanding BFS

The technique we will use in order to traverse the queue can be described as follows:

- 1 Start from the given start node.
- 2 queue neighbors of start.
- 3 while the queue is not empty, keep exploring neighbors, in order.

*our queue will be **FIFO***

# Understanding BFS



```
graph = {  
    1: [2,3,4],  
    2: [5, 6],  
    3: [],  
    4: [7, 8],  
    5: [],  
    6: [],  
    7: [],  
    8: []  
}
```

Let's see in the whiteboard how we would traverse this graph using BFS

# Implementing BFS

```
def bfs(graph, start):  
    queue = [start]  
    visited = []  
    while queue != []:  
        current = queue[0]  
        queue.pop(0)  
        for neighbor in graph[current]:  
            if neighbor not in visited:  
                queue.append(neighbor)  
        visited.append(current)  
    return visited
```

# Path finding

Path finding is one of the most recurrent problems in graphs.

We will solve this problem by doing some small modifications to the **bfs** implementation.

# Path finding

Create a new function **find\_all\_paths(graph, start)** that uses **BFS** and returns a dictionary with all the paths to nodes connected to **start**.

You can start by modifying the code in **bfs**.

# Path finding

```
def find_all_paths(graph, start):  
    queue = [start]  
    paths = {start: [start]}  
  
    while queue:  
        current = queue.pop(0)  
        for neighbor in graph[current]:  
            if neighbor not in paths:  
                paths[neighbor] = paths[current] + [neighbor]  
                queue.append(neighbor)  
  
    return paths
```

# Path finding

Now that we have the paths to all nodes from our start node to all connected nodes, we can easily find the one we're looking for

```
def find_path(graph, start, end):  
    paths = find_all_paths(graph, start)  
  
    if end in graph:  
        return graph[end]  
    else:  
        return None
```

# NetworkX library

The NetworkX library is a library for dealing with graphs. Its **very** powerful, and we can use it for most graph related tasks.

It is already included in Anaconda, so we don't need to download it again.



# NetworkX. DiGraphs

The convention is to import the library under the **nx** name.

In this example we are creating a directed graph with three nodes and two edges.

```
import networkx as nx
```

```
G = nx.DiGraph()
```

```
G.add_node(1)
```

```
G.add_node(2)
```

```
G.add_node(3)
```

```
G.add_edge(1, 2)
```

```
G.add_edge(2, 3)
```

# NetworkX. DiGraphs

We can also use the **edges** and **nodes** methods to get the relevant parts of the graph respectively.

```
# returns the edges
```

```
G.edges
```

```
# returns the nodes
```

```
G.nodes
```

# NetworkX. DiGraphs

```
import networkx as nx
```

```
# when called without params, will return  
# shortest paths from all nodes to all nodes
```

```
nx.shortest_path(G)
```

```
# this will return all the shortest paths  
# starting at node 4
```

```
nx.shortest_path(G, 4)
```

```
# this will return the shortest path from 1  
# to 4
```

```
nx.shortest_path(G, 1, 4)
```

# Exercises

- Create a function named **six\_or\_less** that returns whether two nodes in the graph are at distance 6 or less.
- Create a function **degrees** that receives a graph and returns a dictionary with the degree of each node.
- Investigate the NetworkX library. Use it to **draw the graph** we have been working on in class.