

FFMPEG读取关键帧（c++）

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设法使用 **av_read_frame** 获得所有框架，其中逐帧地顺序读取，再用**AVFrame-> key_frame**判断关键帧，将其进行保存。

主要提取代码如下：

```
//获得帧图大小
PictureSize = avpicture_get_size(AV_PIX_FMT_BGR24, pCodecCtx->width, pCodecCtx->height);
buf = (uint8_t*)av_malloc(PictureSize);
if (buf == NULL) {
    printf("av malloc failed!\n");
    system("pause");
    exit(1);
}
avpicture_fill((AVPicture *)pFrameRGB, buf, AV_PIX_FMT_BGR24, pCodecCtx->width, pCodecCtx->height);
//设置图像转换上下文
pSwsCtx = sws_getContext(pCodecCtx->width, pCodecCtx->height, pCodecCtx->pix_fmt, pCodecCtx->width, pCodecCtx->height, AV_PIX_FMT_RGB24, 0, 0, 0);
i = 0;
while (av_read_frame(pFormatCtx, &packet) >= 0) {
    if (packet.stream_index == videoStream) {
        //解码
        avcodec_decode_video2(pCodecCtx, pFrame, &frameFinished, &packet);
        if (frameFinished) {
            if (pFrame->key_frame) {
                //转换图像格式，将解压出来的YUV420P的图像转换为BRG24的图像
                sws_scale(pSwsCtx, (const uint8_t* const*)pFrame->data, pFrame->linesize, 0, pCodecCtx->height, pFrameRGB->data, pFrameRGB->linesize);
                //保存为bmp图
                SaveAsBMP(pFrameRGB, pCodecCtx->width, pCodecCtx->height, i, 24);
                i++;
            }
        }
        av_free_packet(&packet);
    }
}
```

注意① ffmpeg 中的函数 **av_read_frame** 是用来完成解封装的过程，它会从码流里面提取每一个音频、视频帧，它使用了结构体 **AVPacket** 来记录每一帧的信息。

```
AVPacket avpkt;
av_init_packet(&avpkt);

while (!interrupt) {
    int ret = av_read_frame(ic, &avpkt);
    if (ret < 0) {
        break;
    }
    // processing
}

av_free_packet(&avpkt);
```

每循环一次，就从码流中解封装并且提取了一帧数据，并存放在了 AVPacket 结构体中。

注意② 用 AVPacket 的成员变量 stream_index 判断 Packet 到底是音频还是视频：

```
int video_stream_idx = av_find_best_stream(ic, AVMEDIA_TYPE_VIDEO, -1, -1, NULL, 0);
int audio_stream_idx = av_find_best_stream(ic, AVMEDIA_TYPE_AUDIO, -1, -1, NULL, 0);

if (avpkt.stream_index == video_stream_idx) {
    LOGD("read a video frame");
} else if (avpkt.stream_index == audio_stream_idx) {
    LOGD("read audio frame");
}
```

读取视频文件，提取关键帧并保存关键帧代码如下：

```
#include "stdafx.h"
#include <windows.h>
#include <WinGDI.h>
#include <iostream>
#include <iosfwd>
#include <fstream>

#define __STDC_CONSTANT_MACROS
extern "C"
{

    #include <libavcodec/avcodec.h> //处理原始音频和视频流的解码
    #include <libavutil/opt.h>
    #include <libavutil/channel_layout.h>
    #include <libavutil/common.h>
    #include <libavutil/imgutils.h>
    #include <libavutil/mathematics.h>
    #include <libavutil/samplefmt.h>
    #include <libavformat/avformat.h> //处理解析视频文件并将包含在其中的流分离出来
    #include <libswscale/swscale.h>
    #include <libavutil/imgutils.h>
    #include <libavutil/parseutils.h>
}

#pragma comment(lib, "avcodec.lib")
#pragma comment(lib, "avdevice.lib")
#pragma comment(lib, "avfilter.lib")
#pragma comment(lib, "avformat.lib")
#pragma comment(lib, "avutil.lib")
#pragma comment(lib, "swscale.lib")
#pragma comment(lib, "postproc.lib")
#pragma comment(lib, "swresample.lib")
using namespace std;
//定义BMP文件头

#ifndef _WINGDI_
#define _WINGDI_
typedef struct tagBITMAPFILEHEADER {
    WORD    bfType;
    DWORD   bfSize;
```

```

    WORD    bfReserved1;
    WORD    bfReserved2;
    DWORD    bfOffBits;
} BITMAPFILEHEADER, FAR *LPBITMAPFILEHEADER, *PBITMAPFILEHEADER;

```

```

typedef struct tagBITMAPINFOHEADER {
    DWORD    biSize;
    LONG     biWidth;
    LONG     biHeight;
    WORD     biPlanes;
    WORD     biBitCount;
    DWORD    biCompression;
    DWORD    biSizeImage;
    LONG     biXPelsPerMeter;
    LONG     biYPelsPerMeter;
    DWORD    biClrUsed;
    DWORD    biClrImportant;
} BITMAPINFOHEADER, FAR *LPBITMAPINFOHEADER, *PBITMAPINFOHEADER;

```

```
#endif
```

//保存BMP文件的函数

```

void SaveAsBMP(AVFrame *pFrameRGB, int width, int height, int index, int bpp)
{
    char buf[5] = { 0 }; //bmp头
    BITMAPFILEHEADER bmpheader;
    BITMAPINFOHEADER bmpinfo;
    FILE *fp;
    char *filename = new char[255]; //文件存放路径, 根据自己的修改
    sprintf_s(filename, 255, "%s_%d.bmp", "E:/ffmpeg/keyFrame/", index);
    if ((fp = fopen(filename, "wb+")) == NULL) {
        printf("open file failed!\n");
        return;
    }
    bmpheader.bfType = 0x4d42;
    bmpheader.bfReserved1 = 0;
    bmpheader.bfReserved2 = 0;
    bmpheader.bfOffBits = sizeof(BITMAPFILEHEADER) + sizeof(BITMAPINFOHEADER);
    bmpheader.bfSize = bmpheader.bfOffBits + width*height*bpp / 8;
    bmpinfo.biSize = sizeof(BITMAPINFOHEADER);
    bmpinfo.biWidth = width;
    bmpinfo.biHeight = -height;
    bmpinfo.biPlanes = 1;
    bmpinfo.biBitCount = bpp;
    bmpinfo.biCompression = BI_RGB;
    bmpinfo.biSizeImage = (width*bpp + 31) / 32 * 4 * height;
    bmpinfo.biXPelsPerMeter = 100;
    bmpinfo.biYPelsPerMeter = 100;
    bmpinfo.biClrUsed = 0;
    bmpinfo.biClrImportant = 0;
    fwrite(&bmpheader, sizeof(bmpheader), 1, fp);
    fwrite(&bmpinfo, sizeof(bmpinfo), 1, fp);
    fwrite(pFrameRGB->data[0], width*height*bpp / 8, 1, fp);
    fclose(fp);
}

```

```

int main()
{
    //printf("%d\n", avcodec_version());

    unsigned int i = 0, videoStream = -1;
    AVFormatContext *pFormatCtx;
    AVCodecContext *pCodecCtx;
    AVCodec *pCodec;
    AVFrame *pFrame, *pFrameRGB;
    struct SwsContext *pSwsCtx;
    const char *filename = "E:/ffmpeg/中国合伙人.flv";

```

```

int frameFinished;
int PictureSize;
AVPacket packet;
uint8_t *buf;
//注册解码器
av_register_all();
avformat_network_init();
pFormatCtx = avformat_alloc_context();

//AVInputFormat *pInputFormt = av_find_input_format("dshow");
if (avformat_open_input(&pFormatCtx, filename, NULL, NULL) != 0) {

    printf("%s\n", "failed");
    system("pause");
}
//获取视频流信息
if (avformat_find_stream_info(pFormatCtx, NULL)<0) {
    printf("%s\n", "couldn't find stream info");
    system("pause");
}

//获取视频数据
for (int i = 0; i<pFormatCtx->nb_streams; i++)

    if (pFormatCtx->streams[i]->codec->codec_type == AVMEDIA_TYPE_VIDEO) {
        //AVMEDIA_TYPE_VIDEO
        //AV_CODEC_ID_H264
        videoStream = i;
    }

if (videoStream == -1) {
    printf("%s\n", "find video stream failed");
    system("pause");
    exit(1);
}
pCodecCtx = pFormatCtx->streams[videoStream]->codec;
pCodec = avcodec_find_decoder(pCodecCtx->codec_id);

if (pCodec == NULL) {
    printf("%d\n", "avcode find decoder failed!");
    system("pause");
    exit(1);
}
//打开解码器
if (avcodec_open2(pCodecCtx, pCodec, NULL)<0) {
    printf("avcode open failed!\n");
    system("pause");
    exit(1);
}
//为每帧图像分配内存
pFrame = av_frame_alloc();
pFrameRGB = av_frame_alloc();

if (pFrame == NULL || pFrameRGB == NULL) {
    printf("av frame alloc failed!\n");
    system("pause");
    exit(1);
}
//获得帧图大小
PictureSize = avpicture_get_size(AV_PIX_FMT_BGR24, pCodecCtx->width, pCodecCtx->height);
buf = (uint8_t*)av_malloc(PictureSize);
if (buf == NULL) {
    printf("av malloc failed!\n");
    system("pause");
}

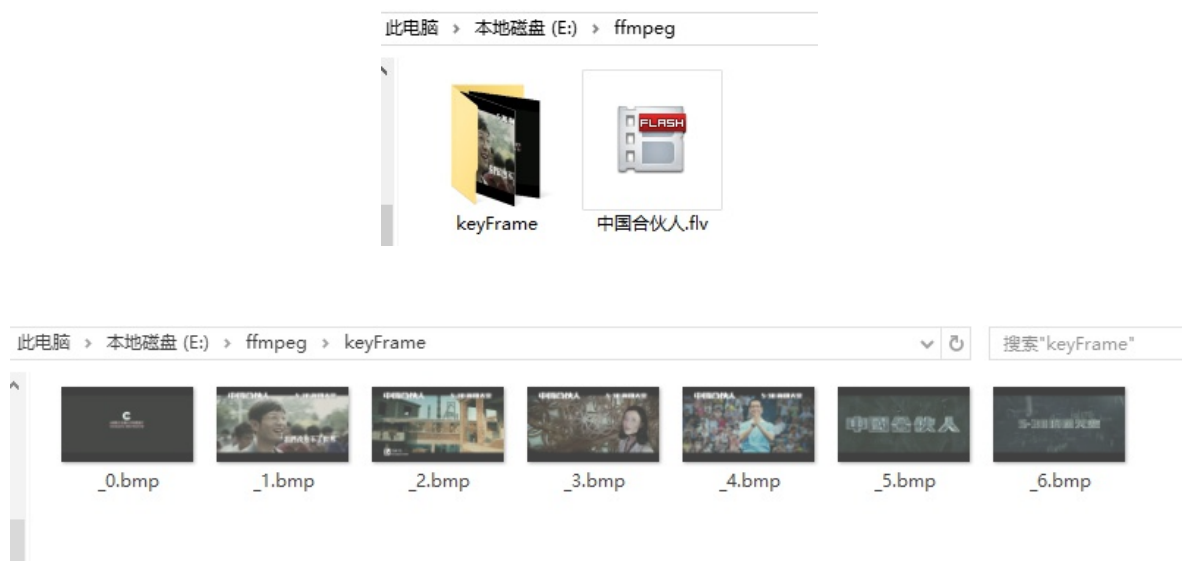
```

```

    exit(1);
}
avpicture_fill((AVPicture *)pFrameRGB, buf, AV_PIX_FMT_BGR24, pCodecCtx->width, pCodecCtx->height);
//设置图像转换上下文
pSwsCtx = sws_getContext(pCodecCtx->width, pCodecCtx->height, pCodecCtx->pix_fmt, pCodecCtx->width, pCodecCtx->height, AV_PIX_FMT_RGB24, AV_PIX_FMT_BGR24, 0, 0, 0);
i = 0;
while (av_read_frame(pFormatCtx, &packet) >= 0) {
    if (packet.stream_index == videoStream) {
        //解码
        avcodec_decode_video2(pCodecCtx, pFrame, &frameFinished, &packet);
        if (frameFinished) {
            if (pFrame->key_frame) {
                //转换图像格式，将解压出来的YUV420P的图像转换为BRG24的图像
                sws_scale(pSwsCtx, (const uint8_t* const*)pFrame->data, pFrame->linesize, 0, pCodecCtx->height, pFrameRGB->data, pFrameRGB->linesize);
                //保存为bmp图
                SaveAsBMP(pFrameRGB, pCodecCtx->width, pCodecCtx->height, i, 24);
                i++;
            }
        }
        av_free_packet(&packet);
    }
}
sws_freeContext(pSwsCtx);
av_free(pFrame);
av_free(pFrameRGB);
avcodec_close(pCodecCtx);
avformat_close_input(&pFormatCtx);
printf("关键帧已保存在设置路径! \n");
system("pause");
return 0;
}

```

运行效果:



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