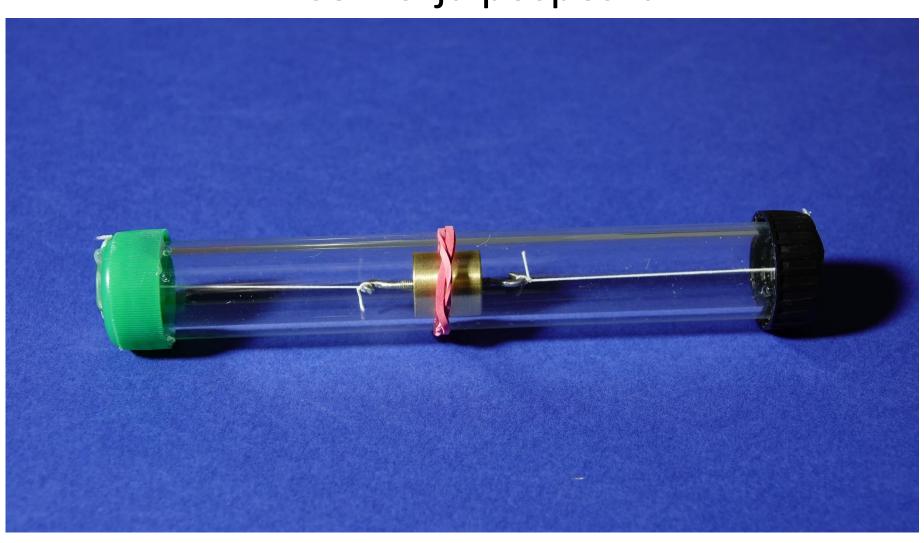
## Raziskovanje sil pri gibanju teles z uporabo mobilnega telefona

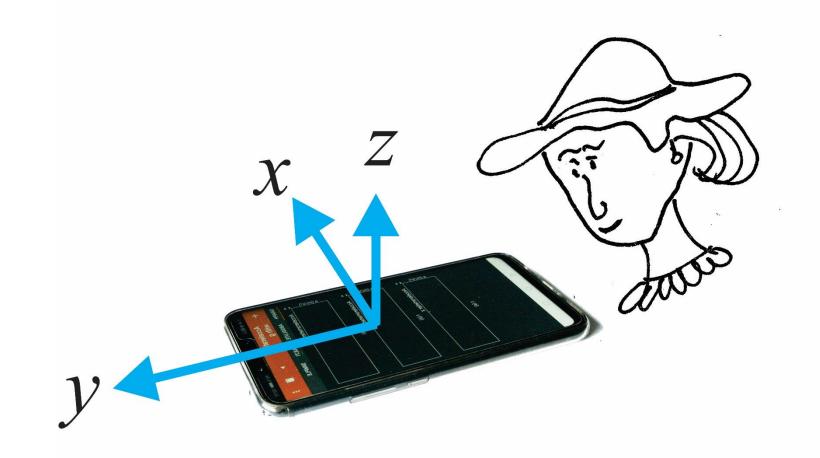
Gorazd Planinšič SSS 13.12.2019

Glej tudi navodila za delavnico!

## Preprost analogni model senzorja pospeška

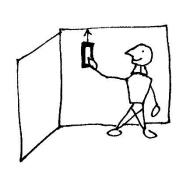


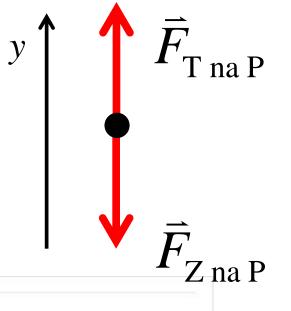
Smeri koordinatnih osi, ki jih uporablja program Phyphox

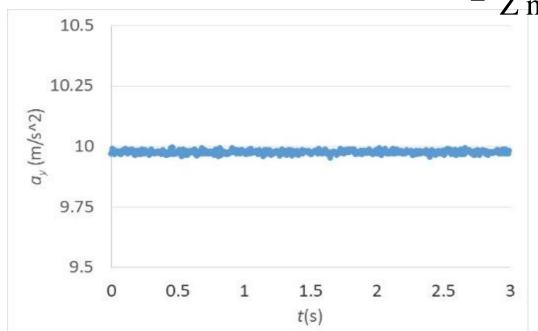


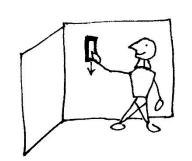
Pospešek  $a_x$ , ki ga prikaže telefon je enak sili  $F_x$  s katero deluje telefon na majhno telo v telefonu, deljeno z maso tega telesa (enako za y in z)

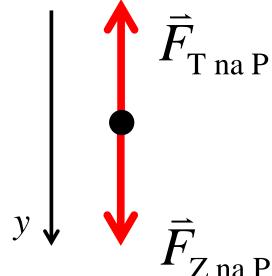
Privzamemo lahko, da so premiki merilnega telesa zanemarljivo majhni v primerjavi z velikostjo telesa (=vzmet s katero je vpeto telo na ohišje telefona je zelo trda).

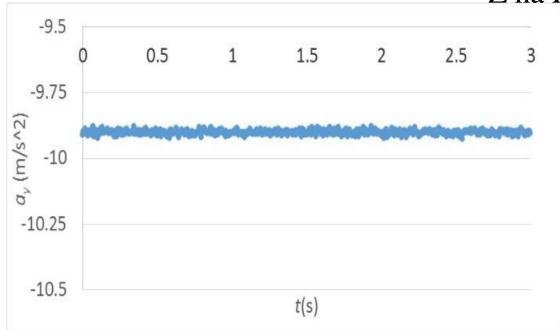




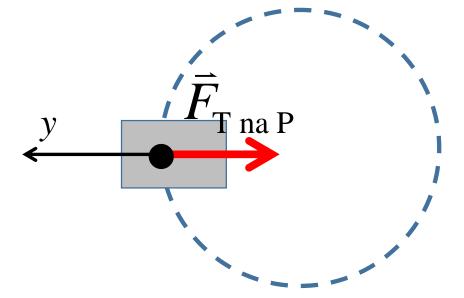




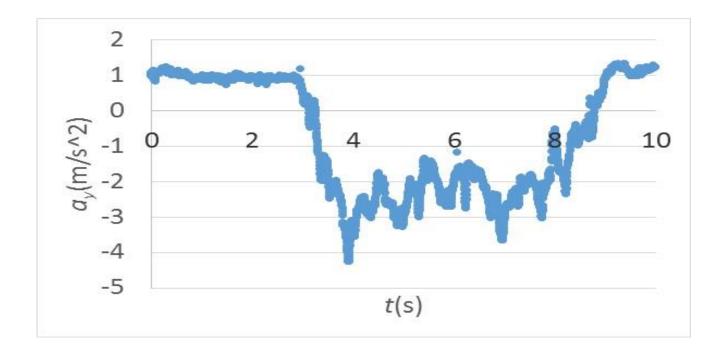






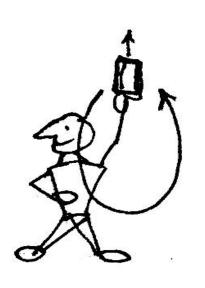


Pogled od zgoraj



$$F_{\text{TnaP}} = m \frac{v^2}{R} \Longrightarrow$$

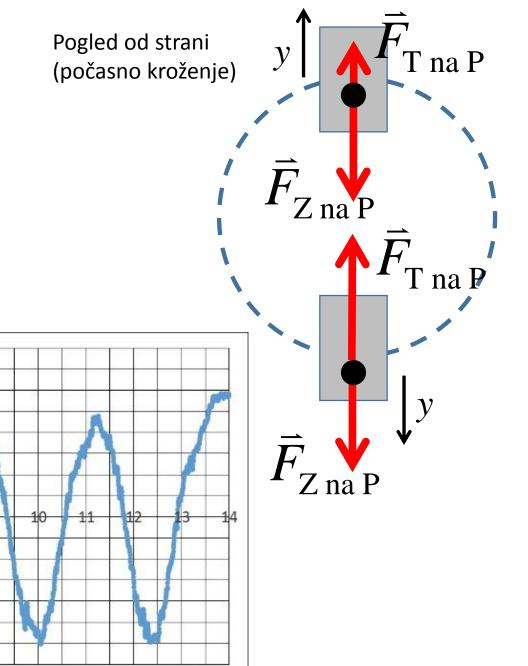
$$a_y = \frac{F_{\text{TnaP}}}{m} = \frac{v^2}{R} = \left(\frac{2\pi}{T_0}\right)^2 R$$

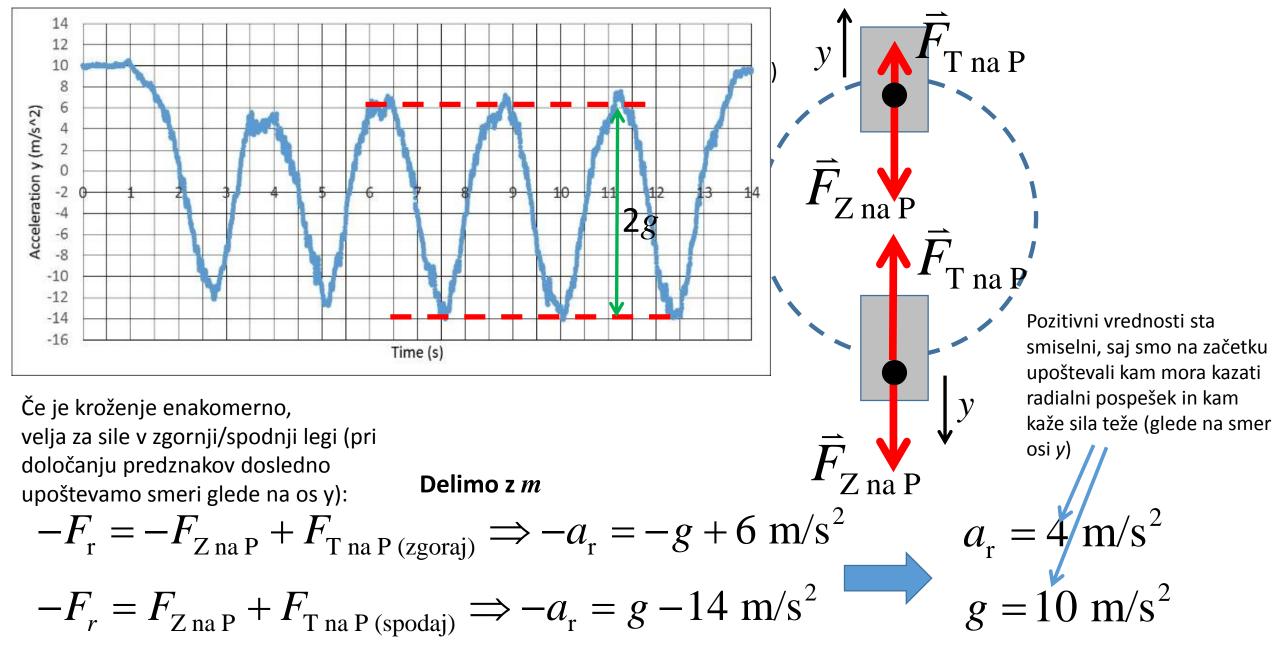


Acceleration y (m/s^2)

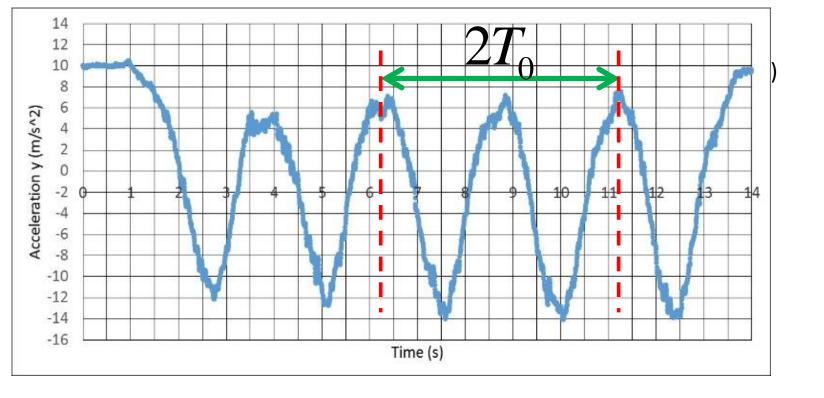
-8 -10 -12 -14 -16

Time (s)



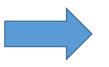


Ugotovitev: pri enakomernem kroženju v navpični ravnini je razlika med največjim in najmanjšim pospeškom, ki ga izmeri telefon enaka 2g



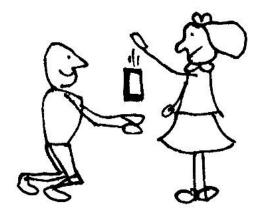
$$a_{\rm r} = 4 \text{ m/s}^2$$

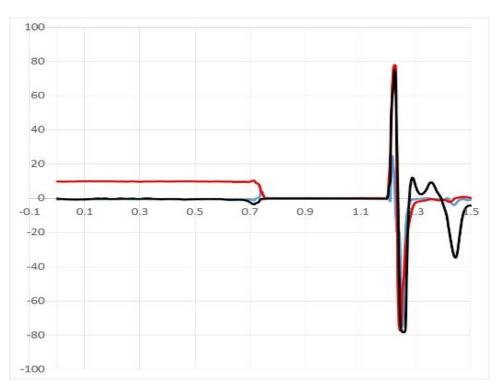
$$T_0 \approx 2,5 \text{ s}$$



$$R = a_{\rm r} \left(\frac{T_0}{2\pi}\right)^2 = 0,63 \text{ m}$$

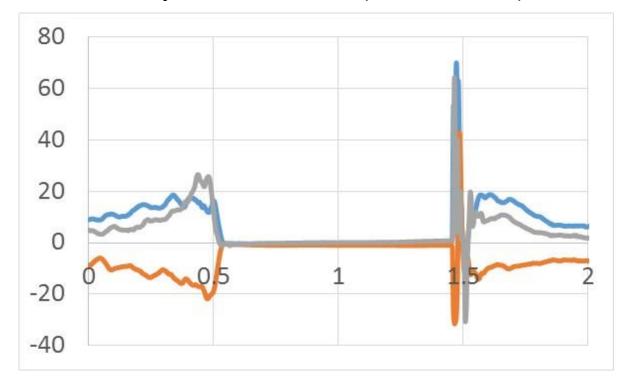
Rezultat se smiselno ujema s tipično dolžino roke (za odraslo osebo)



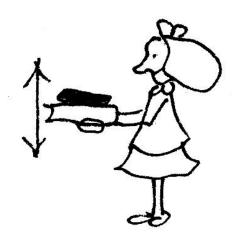




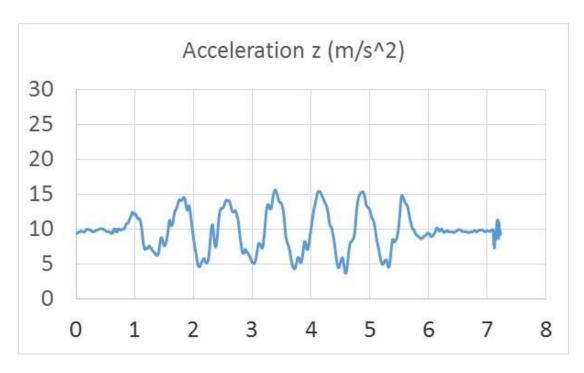
Poskus izvedemo s proženjem z zakasnitvijo ali z upravljanjem telefona na daljavo z računalnikom ( *Remote access*)



Povezava z zanimivim primerom: googlaj "Vomit comet"



Telefon ne poskakuje



Telefon je začel poskakovati pri cca t=8 s

