

HW 5

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2. SVM

1.

$$\max_{\frac{2c}{\|w\|}} \text{ subject to } y^i(w^T x^i + b) \geq c \equiv \max_{\frac{1}{\|w\|}} \text{ subject to } y^i(w^T x^i + b) \geq 1$$

The two statements are equivalent. Given any solution, the other statement can be achieved by scaling w and b . This does not change the goodness of the classifiers.

2.

$$L(w, b, \alpha) = \frac{1}{2}w^T w + \sum_{i=1}^m \alpha_i(1 - y_i(w^T x_i + b))$$

$$\frac{\partial L(w, b, \alpha)}{\partial w} = w - \sum_{i=1}^m \alpha_i y_i x_i = 0 \therefore w = \sum_{i=1}^m \alpha_i y_i x_i$$

This implies that the weight vector is a linear combination of the feature vectors.

3.

Given KKT conditions: $\alpha_i(1 - y_i(w^T x_i + b)) = 0$;

$1 - y_i(w^T x_i + b) = 0$ if x_i is on margin

else $1 - y_i(w^T x_i + b) < 0$

$\therefore \alpha_i = 0$ if x_i not on margin.

The sum from part 2, $w = \sum_{i=1}^m \alpha_i y_i x_i$ will only contain data points on the margin.

4.

4.a

The training points will remain linearly separable if x_3 remains on the left side of the line formed by positive samples, x_1 and x_2 . Therefore, for $0 \leq h \leq 1$, the training points will remain linearly separable.

4.b

The orientation of the maximum margin decision boundary does not change as h changes in the linearly separable range. The 2 hyper planes that defined the boundary are parallel to each other when the data points are separable.

3. Neural Network and Backward propogation

1.

$$l(w, \alpha, \beta) = \sum_{i=1}^m (y_i - \sigma(w^T z_i))^2$$

$$\frac{\partial l(w, \alpha, \beta)}{\partial w} = \sum_{i=1}^m \frac{\partial}{\partial w} (y_i - \sigma(w^T z_i))^2 = \sum_{i=1}^m -2(y_i - \sigma(w^T z_i)) * \frac{\partial}{\partial w} (\sigma u^i)$$

$$\text{Given: } \sigma(x) = \frac{1}{1+e^{-x}} : \quad \frac{\partial \sigma}{\partial x} = \frac{-1}{(1+e^{-x})} \frac{e^{-x}}{1+e^{-x}} = \sigma(x) \left(\frac{1+e^{-x}}{1+e^{-x}} - \frac{1}{1+e^{-x}} \right) = \sigma(x)(1 - \sigma(x))$$

$$\frac{\partial}{\partial w} (\sigma(w^T z^i)) = \sigma(w^T z^i)(1 - \sigma(w^T z^i))z^i$$

$$\therefore \frac{\partial l(w, \alpha, \beta)}{\partial w} = - \sum_{i=1}^m 2(y_i - \sigma(u_i))\sigma(u_i)(1 - \sigma(u_i))z_i$$

2.

$$\frac{\partial l(w, \alpha, \beta)}{\partial \alpha} = \frac{\partial l}{\partial z_1^i} \frac{\partial z_1^i}{\partial \alpha} = (- \sum_{i=1}^m 2(y_i - \sigma(u_i))\sigma(u_i)(1 - \sigma(u_i))w_1)(\sigma(\alpha^T x^i)(1 - \sigma(\alpha^T x^i))x^i)$$

$$\frac{\partial l(w, \alpha, \beta)}{\partial \beta} = \frac{\partial l}{\partial z_2^i} \frac{\partial z_2^i}{\partial \beta} = (- \sum_{i=1}^m 2(y_i - \sigma(u_i))\sigma(u_i)(1 - \sigma(u_i))w_2)(\sigma(\beta^T x^i)(1 - \sigma(\beta^T x^i))x^i)$$

4. Feature Selection and Change-point detection

1.

$$I(U, C) = \frac{N_{11}}{N} \log_2 \frac{NN_{11}}{N_1 N_{.1}} + \frac{N_{01}}{N} \log_2 \frac{NN_{01}}{N_0 N_{.1}} + \frac{N_{10}}{N} \log_2 \frac{NN_{10}}{N_1 N_{.0}} + \frac{N_{00}}{N} \log_2 \frac{NN_{00}}{N_0 N_{.0}}$$

$$I(\text{prize}, \text{spam}) = \frac{150}{16160} \log_2 \frac{150*16160}{160*11150} + \frac{1000}{16160} \log_2 \frac{1000*16160}{16000*11150} + \frac{10}{16160} \log_2 \frac{10*16160}{160*15010} + \frac{15000}{16160} \log_2 \frac{15000*16160}{16000*15010} = 0.03302$$

$$I(\text{hello}, \text{spam}) = \frac{145}{16160} \log_2 \frac{145*16160}{160*11145} + \frac{11000}{16160} \log_2 \frac{11000*16160}{16000*11145} + \frac{15}{16160} \log_2 \frac{15*16160}{160*5015} + \frac{5000}{16160} \log_2 \frac{5000*16160}{16000*5015} = 0.001948$$

Given $I(\text{prize}, \text{spam}) > I(\text{hello}, \text{spam})$, ‘prize’ is more informative for deciding email spam.

2.

CUSUM Statistic Derivation

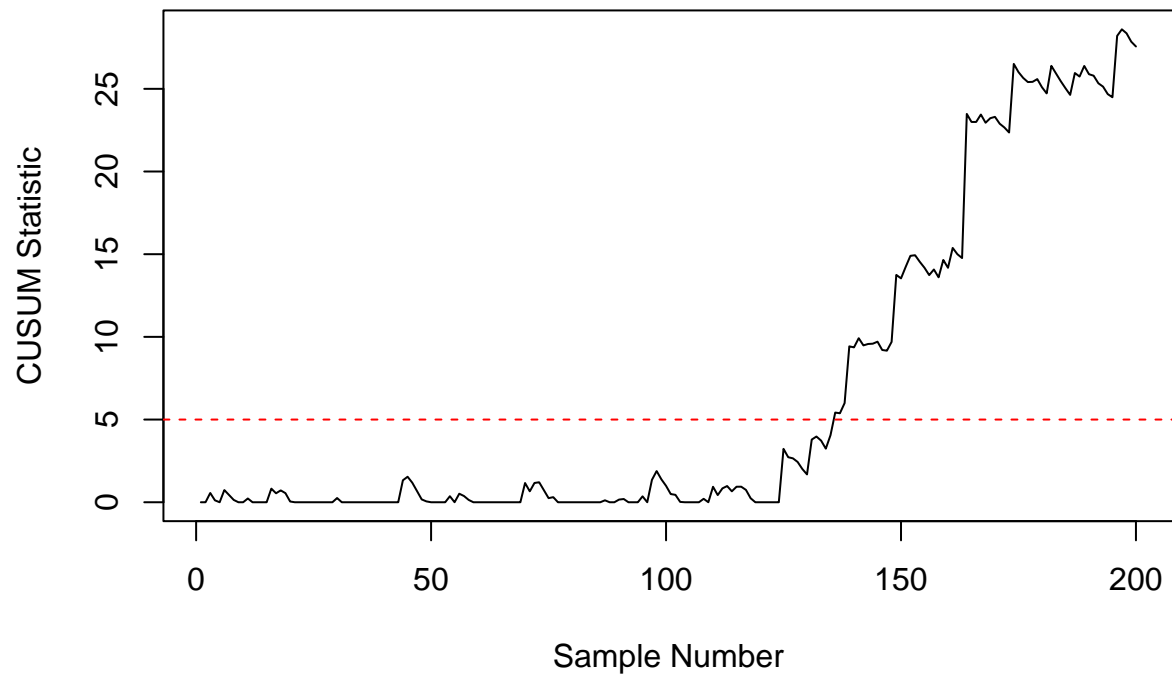
$$L_t = \log \left(\frac{f_1(x_t)}{f_0(x_t)} \right) = \log \left(\frac{N(0.5, 1.5)}{N(0, 1)} \right) = \log \left(\frac{\frac{1}{\sqrt{2\pi \cdot 1.5^2}} \exp \left(-\frac{(x_t - 0.5)^2}{2(1.5^2)} \right)}{\frac{1}{\sqrt{2\pi}} \exp \left(-\frac{x_t^2}{2} \right)} \right)$$

Simplifying this expression:

$$L_t = \log \left(\frac{1}{\sqrt{1.5^2}} \exp \left(-\frac{(x_t - 0.5)^2}{2(1.5^2)} + \frac{x_t^2}{2} \right) \right)$$

$$W_t = \max(W_{t-1} + L_t, 0)$$

CUSUM Change Point Detection



[1] 27.55964