## Georgia Institute of Technology George W. Woodruff School of Mechanical Engineering ME6406 Machine Vision (Fall 2023)

Assignment #1: Extended due date Saturday, September 23<sup>rd</sup>, 2023 (23:59 EDT)

All programs should be written using MATLAB. Solutions must be consolidated into a **single pdf file** (including all results and an explanation of results) and a **zip file** (including all m-files used for the results). Solutions must be submitted electronically through **Canvas**. Late solutions will be penalized at a 10% deduction from the homework score and will NOT be accepted 24 hours after the due date. Without a signed honor code, your exams and assignments will NOT be graded.

### 1. Pin-hole optics

Consider a pinhole projection circle (PPC with diameter  $d_P$ ) scanning along the diagonal line ( $C_PC_L$ ) to the circular landmark as shown in Fig. 1, where s ( $-d_P/2 \le s \le +d_P/2$ ) is the distance from the intersecting line to the PPC center  $C_P$ .

- a) Derive the mathematical expression for  $\delta a/\delta O$  as a function of  $S(=s/d_P)$ , where  $\delta a$  is the overlapping area and  $\delta O$  is the pin-hole projection area, in terms of the ratio  $\rho (= d_L/d_P)$ .
- b) Plot  $\delta a/\delta O$  for the range,  $-0.5 \le S \le 0.5$  and  $\rho = 2$ . Discuss the effect of  $\rho$  on  $\delta a/\delta O$  by considering two cases,  $0 < \rho < 1$ , and  $\rho \ge 1$ .

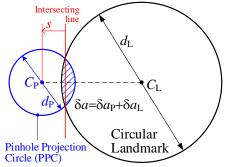


Fig. 1. Pin-hole model of a landmark

### 2. <u>Histogram Equalization (HE)</u>

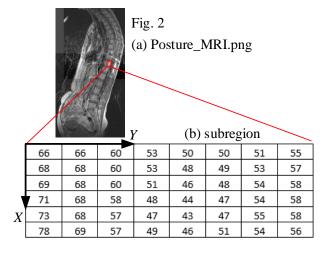
Fig. 2(a) shows an 8-bit gray-level MRI image (Posture\_MRI.png) of a human and a subregion in a matrix (Fig. 2b). For your convenience, the data are also given in the 'sub\_region\_matrix.xlsx' file.

a) Compute the HE of the region matrix by completing Table 1. Show the sub-region matrixes before and after the HE.

(MATLAB *histeq* command is NOT allowed in 2a).

Table 1

Gray-level	# of pixels	CDF	$q_k$	$\mathbf{round}(q_k)$
43	1	1	5.313	5
:	:	:	:	:
:	:	:	:	:
78	2	48	255	255



- b) Perform the HE on an image by writing a Matlab script. Demonstrate your work as follows:
  - I. Read in and display the 'Posture\_MRI.png'.
  - II. Compare by displaying the original and processed images and their histograms.

You may use the Matlab functions: imshow, imhist or hist, histeq for Part 2b).

#### 3. <u>Filtering masks</u>

#### Sobel operator (Parts 3a, b)

a) Use a 3x3 Sobel operator to calculate the *magnitude* and *direction* of the gradient at pixel (3, 5) in Fig. 2(b). Indicate the direction of the gradient on the pixel. (Note: Sobel operator is coordinate dependent. Be sure to use consistent coordinate systems on the sub-regions.)

b) Write a Matlab script to compute the gradient of an image. For illustration, use the Sobel operator on the image "checker.png" shown in Fig. 3(a). Display the gradient images ( $G_x$ ,  $G_y$ , G). You are encouraged to compare with that computed using Matlab functions *edge* and *imgradientxy*; explain if any differences.

#### Gaussian operator (Parts 3c to f)

c) Plot the Gaussian function in the range  $(-5 \le x \le 5, -5 \le y \le 5)$  for  $\sigma = 1, 3, 5$ :

$$G(x,y) = \frac{1}{2\pi\sigma^2} \exp\left(\frac{-(x^2 + y^2)}{2\sigma^2}\right)$$

Suggested Matlab functions: meshgrid.m, surf.m

- d) Use a Gaussian filtering mask to smooth the image 'Texture.png' (Fig. 3b); specifically, compare the smoothing effects of different  $\sigma$  (= 1, 3, and 5) on the image. Note: Use the proper mask size for a specified  $\sigma$  to smooth an image. Suggested Matlab functions: imfilter.m
- e) Perform an edge detection using the DoG function (difference of two Gaussians on the image "nut\_and\_shell.png" (Fig.4), demonstrating your work with  $\sigma_c = 1$  and  $\sigma_s = 10$ .
- f) An interesting observation in a human visual system (HVS) suggests our HVS uses DoG functions (Part 3e) to discriminate closely similar colors and detect an edge. Consider an image consisting of two 100<sup>2</sup>-pixel RGB color patterns with [Red, Green, Blue] values:

Color Pattern I (left): [130, 115, 108] and Color Pattern II (right): [110, 97, 96].

i) Compute the 3 transformed components  $[h_1, h_2, h_3]$  to create a new color image using the equations on the right, where  $h_i$  (with i=1, 2, and 3) represent the transformed values:

$$h_1(x, y) = DoG * R + G_{\sigma s} * [2R + G - B]$$

$$h_2(x, y) = DoG * G + G_{\sigma s} * [R + 2G - B]$$

$$h_3(x, y) = DoG * B + G_{\sigma s} * [R + G]$$

- ii) Plot the color patterns before and after the color filtering;
- iii) Computing the norm d between the two color vectors before and after the filtering:

$$d = \sqrt{(R_{\rm I} - R_{\rm II})^2 + (G_{\rm I} - G_{\rm II})^2 + (B_{\rm I} - B_{\rm II})^2}$$

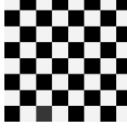


Figure 3(a) checker.png

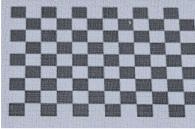


Figure 3(b) Texture.png



Figure 4. nut\_and\_shell.png

# 4. <u>Low-level information processing</u>

This problem shows the process of obtaining some low-level information from an image.

- a) Read in and convert the image 'nut\_and\_shell.png' into a gray-scale image. Binarize the image using 3 different thresholds. Preferably one over- and one under-estimate and the other in between. (Hint: Use the histogram to get an idea of what thresholds to pick).
- b) Obtain the area and centroid of the nut and shell in the image with the appropriate threshold.
- c) Find all the boundaries of the nut and shell.

Suggested Matlab functions: rgb2gray.m, im2bw.m, bwlabel.m, regionprops.m, bwboundaries.m