

HW4

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1 Pose Estimation

1.a

Nc =

0.8313	-0.5542	0.0429
0.8298	0.5532	0.0727
0.8480	0.5300	0.0094
0.8174	-0.5682	0.0944
0.8497	-0.5270	-0.0173
0.7894	0.6024	0.1179
0.0948	0.9950	0.0331
0.1171	0.9892	0.0877
0.0365	0.9988	-0.0338

1.b

R =

0.0188	0.1104	0.5660
-0.2164	-0.0236	1.3489
0.0268	0.0654	0.2118

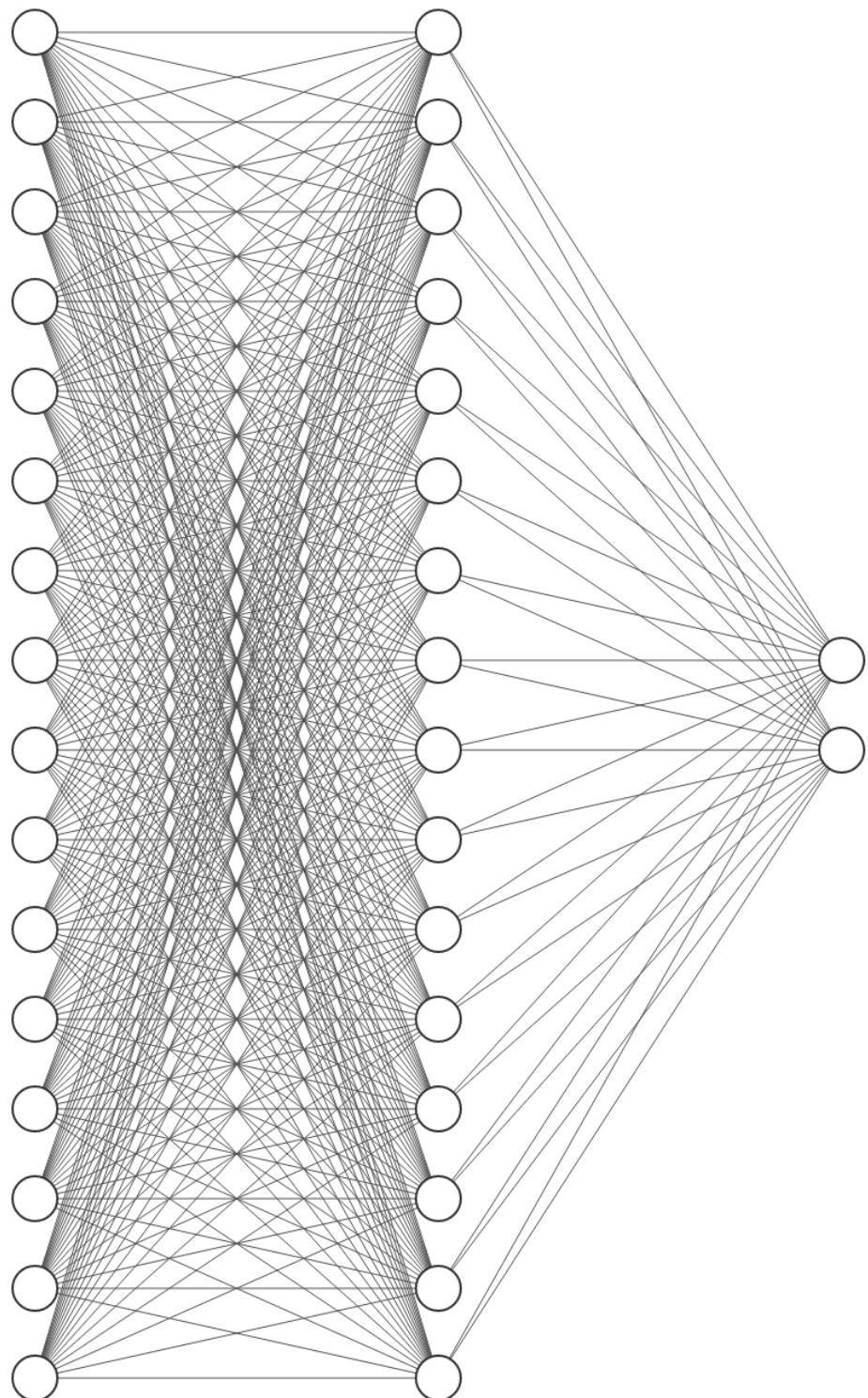
T =

-0.2555
-0.7265
0.4455

2. Artificial Neural Network

2.a

There is 1 hidden layer, 16 inputs for each pixel, and 2 outputs for the 2 different structures.



2.b

$$\omega_{qp}^{tot} = \omega_{qp}^k + \Delta\omega_{qp} = \omega_{qp} - \frac{\partial E_q}{\partial \omega_{qp}}$$

$$\frac{\partial E_q}{\partial \omega_{qp}} = \frac{\partial E_q}{\partial I_q} \cdot \frac{\partial I_q}{\partial \omega_{qp}}, \quad \frac{\partial I_q}{\partial \omega_{qp}} = \frac{\partial}{\partial \omega_{qp}} \sum_{i=1}^{N_q} \omega_{qi} O_p \rightarrow O_p$$

$$\Delta\omega_{qp} = -\alpha \frac{\partial E_q}{\partial I_q} O_p$$

$$\frac{\partial E_q}{\partial I_q} = \frac{\partial E_q}{\partial O_p} \cdot \frac{\partial O_p}{\partial I_q}$$

$$\frac{\partial}{\partial \omega_{qp}} \left\{ (r_q - O_q) \rightarrow (r_q - O_p) \right\} = h(I_q) = O_p(1 - O_p)$$

$$\boxed{\Delta\omega_{qp} = \alpha(r_q - O_p) h(I_q) O_p}$$

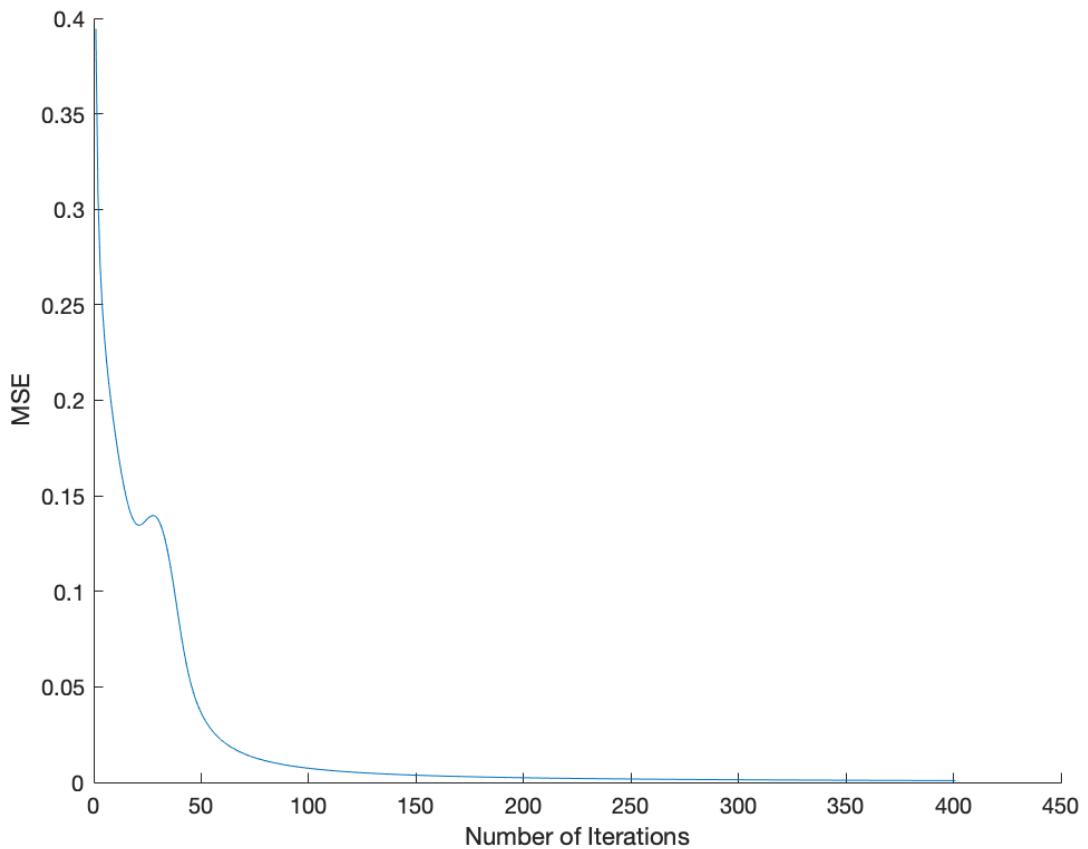
$$\Delta\omega_{pj} = -\alpha \frac{\partial E}{\partial \omega_{pj}} = -\alpha \frac{\partial E}{\partial O_p} \frac{\partial O_p}{\partial I_p} \frac{\partial I_p}{\partial \omega_{pj}}$$

$$\frac{\partial E}{\partial O_p} = \frac{\partial}{\partial O_p} \left(\frac{1}{2} (r_j - O_q)^2 \right) \downarrow \quad \frac{\partial O_p}{\partial I_p} = O_p(1 - O_p) \quad \frac{\partial I_p}{\partial \omega_{pj}} = O_j$$

$$\downarrow \quad \frac{\partial O_p}{\partial I_p} = O_p(1 - O_p)$$

$$\boxed{\therefore \Delta\omega_{pj} = \frac{1}{2} (r_j - O_q) O_p (1 - O_p)}$$

2.c



2.d

01 =

**0.0154
0.9813**

02 =

**0.0569
0.8955**

03 =

**0.4485
0.3495**

Based on the output values, the model seems to predict the structure with accuracy.

3. Color

3.I ACC

$$h_i(x,y) = G_{oc} f_i(x,y) - G_{os} f_k(x,y)$$

$\times \text{DOG} = G_{oc} - G_{os}$

$$h_1(x,y) = G_{oc} R - G_{os}(R-G) \rightarrow (G_{oc} - G_{os})R + G_{os}G = \text{DOG}(R) + G_{os}(G)$$

$$h_2(x,y) = G_{oc} G - G_{os}(R-G) = \text{DOG}(G) + G_{oc}(R) - G_{os}(R-G)$$

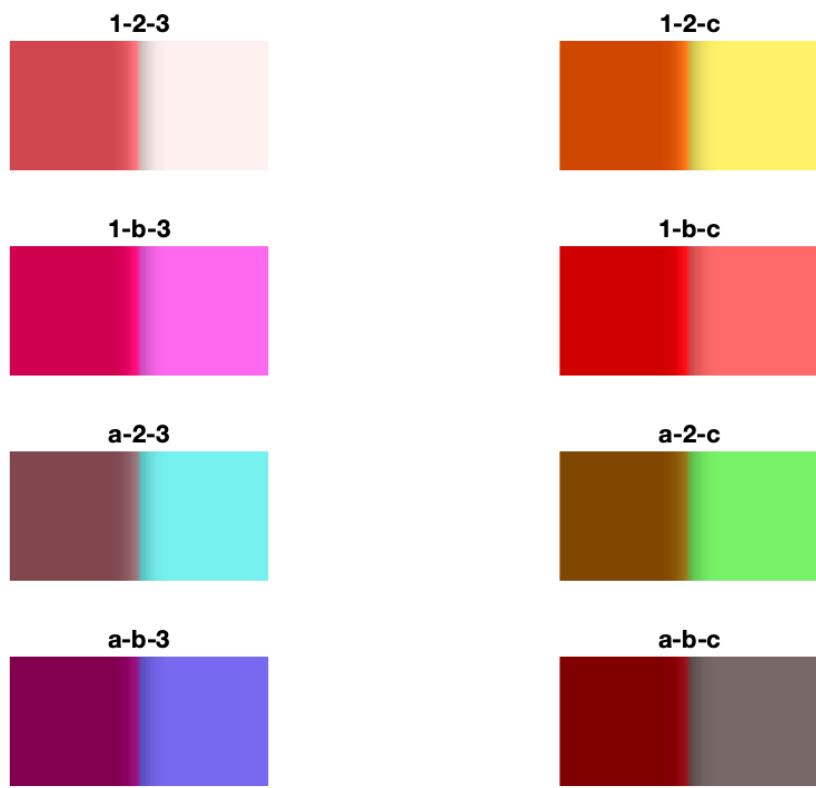
~~$h_3(x,y)$~~

$$h_3(x,y) = G_{oc} B - G_{os}(R-G) = \text{DOG}(B) + G_{os}(B-R)$$

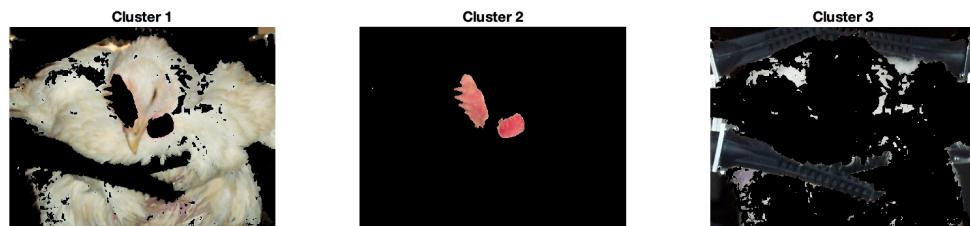
$$h_4(x,y) = G_{oc} R \cdot G_{os}(R+G-B) = \text{DOG}(R) + G_{os}(B-G)$$

$$h_5(x,y) = G_{oc} G - G_{os}(R+G-B) = \text{DOG}(G) + G_{os}(B-R)$$

$$h_6(x,y) = G_{oc} B - G_{os}(R+G-B) = \text{DOG}(B) + G_{os}(2R-(G+B))$$



3.II Color-based Image Segmentation



3.III PCA

C =

0.0824	0.0773	0.0665
0.0773	0.0773	0.0670
0.0665	0.0670	0.0594

V =

0.6109	0.5973	0.5197
0.7720	-0.3038	-0.5584
-0.1756	0.7423	-0.6467

D =

0.2146
0.0039
0.0006

