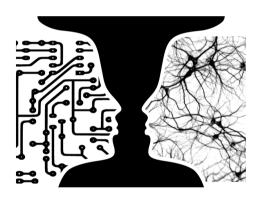
Adaptation de domaine en apprentissage automatique:

Introduction et approche PAC-Bayésienne

Pascal Germain

Groupe de Recherche en Apprentissage Automatique de l'Université Laval



Travail conjoint avec

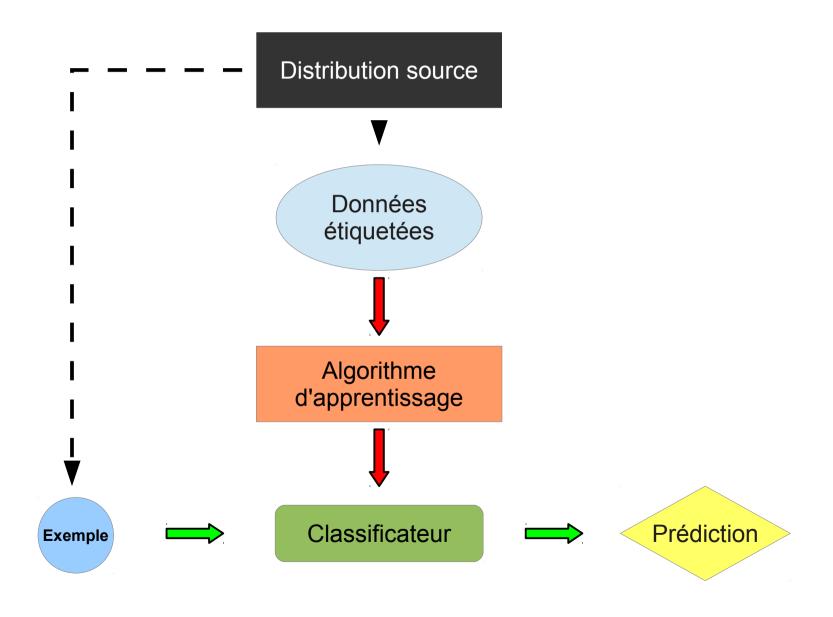
François Laviolette (Université Laval), Emilie Morvant (Aix-Marseille Université), Amaury Habrard (Université Jean-Monnet de Saint-Étienne)

Plan de match

- 1) Classification classique vs adaptation de domaine
- 2) Problème de classification classique
 - Représentation des données
 - Classificateur à noyau
 - Apprentissage PAC-Bayésien
- 3) Problème d'adaptation de domaine
 - Représentation des données
 - Divergence entre les domaines
 - Apprentissage PAC-Bayésien
- 4) Résultats empiriques

Classification classique **vs**Adaptation de domaine

Problème de classification classique





Exemple

critiques de films

An insult to Douglas Adams'

memory

I agree entirely with "darkgenius" comments. This movie is a travesty of the book and the TV series; a cutesy version totally lacking in the wit and satire of the original. Read more

Published 5 months ago by John W Beare

Don't Panic!

If you haven't listened to the BBC radio-play, this isn't bad! Purists, no doubt, will dispute my verdict but the fact of the matter is THGTTG (see title) does have Douglas Adams' ...

Read more

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On Blu-ray, even better

I've seen this movie on TV and wanted to add it to my collection. I couldn't find it locally so when I saw it on amazon and on Blu-ray, I picked it up. Read more

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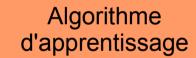
Read more

Published on Aug 22 2006 by Daniel Jolley

??? Mindbending

I will not recommend this movie for people who haven't read at least two or three of Douglas Adams' books on hitchhiking. Read more

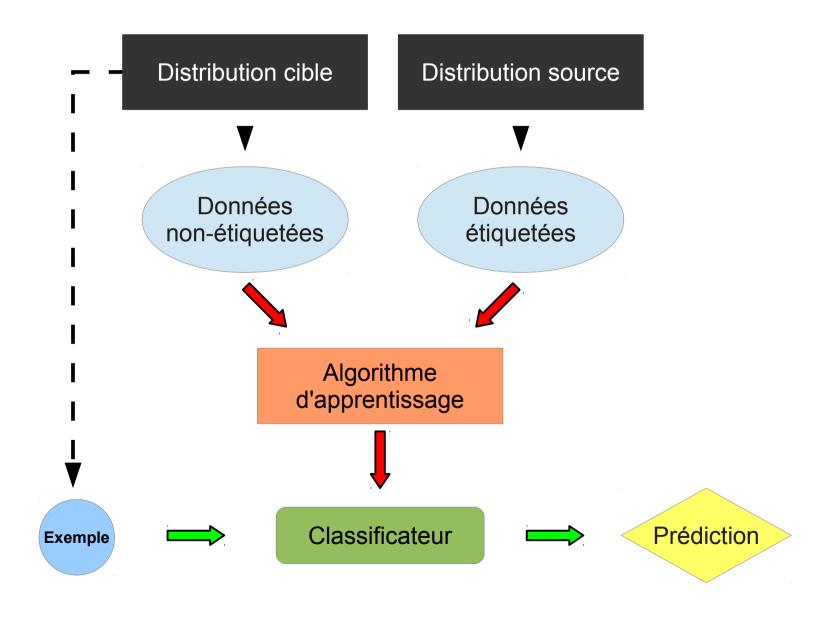
Published on Mar 28 2006 by alper bac



Classificateur



Problème d'adaptation de domaine





Exemple



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Algorithme d'apprentissage

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Problème de classification classique

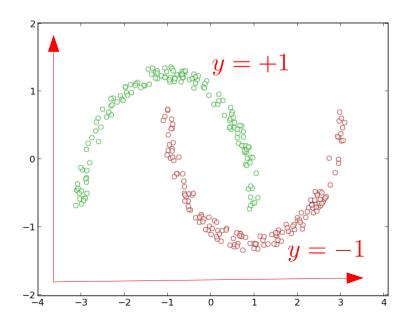
Représentation des données

- Chaque exemple est une paire $(\mathbf{x}, y) \sim D$
 - Description $\mathbf{x} \in \mathbb{R}^d$
 - Étiquette $y \in \{-1, +1\}$

Distribution source

Ensemble d'entraînement:

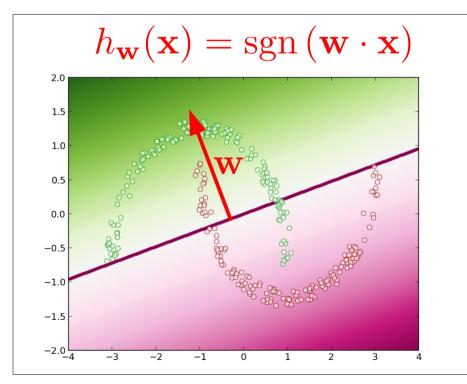
$$S = \{(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), \dots, (\mathbf{x}_m, y_m)\} \sim D^m$$

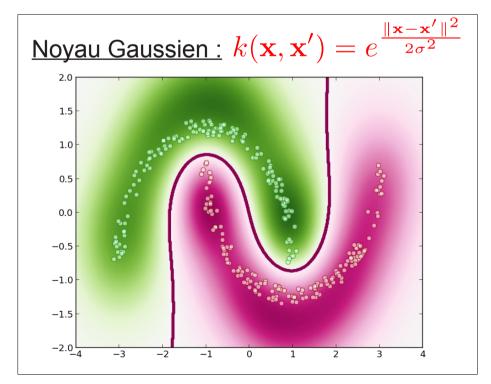


Classificateur à noyau (kernel)

- Classificateur linéaire: exprimé par un vecteur de poids $\mathbf{w} \in \mathbb{R}^d$
- Noyau: Exprime un produit scalaire $k(\mathbf{x},\mathbf{x}') \to \mathbb{R}$
- Classificateur à noyau: Classificateur linéaire dans un espace augmenté exprimé comme une combinaison linéaire des exemples $\alpha \in \mathbb{R}^m$

$$\mathbf{w} \cdot \mathbf{x} = \sum_{i=1}^{m} \alpha_i k(\mathbf{x}_i, \mathbf{x})$$





Apprentissage PAC-Bayésien

Théorème PAC-Bayes (spécialisé aux classificateurs linéaires)

• Pour tout domaine *I*

(Langford et Shawe-Taylor, 2002)

- Pour toute *confiance* $\delta \in (0,1]$
- Pour tout paramètre $c \in (0,\infty)$

$$\Pr_{S \sim D^m} \left(\forall \mathbf{w} \in \mathbb{R}^d : \underline{R_D(G_{\mathbf{w}})} \leq \frac{1}{1 - e^{-c}} \left[c \cdot \underline{R_S(G_{\mathbf{w}})} + \frac{\frac{1}{2} \|\mathbf{w}\|^2 + \ln \frac{1}{\delta}}{m} \right] \right) \geq 1 - \delta.$$

Risque

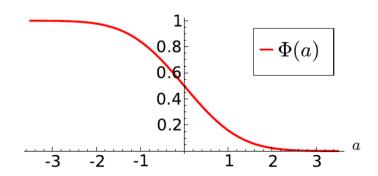
$$R_D(G_{\mathbf{w}}) = \mathbf{E}_{(\mathbf{x},y)\sim D} \Phi\left(y \frac{\mathbf{w} \cdot \mathbf{x}}{\|\mathbf{x}\|}\right)$$

Risque empirique

$$R_S(G_{\mathbf{w}}) = \sum_{i=1}^{m} \Phi\left(y_i \frac{\mathbf{w} \cdot \mathbf{x}_i}{\|\mathbf{x}_i\|}\right)$$

Régularisateur

(Catoni, 2007)



Apprentissage PAC-Bayésien

Théorème PAC-Bayes (spécialisé aux classificateurs linéaires)

Pour tout domaine

- (Langford et Shawe-Taylor, 2002)
 - (Catoni, 2007)

- Pour toute *confiance* $\delta \in (0,1]$
- Pour tout paramètre $c \in (0, \infty)$

$$\Pr_{S \sim D^m} \left(\forall \mathbf{w} \in \mathbb{R}^d : \underline{R_D(G_{\mathbf{w}})} \leq \frac{1}{1 - e^{-c}} \left[c \cdot \underline{R_S(G_{\mathbf{w}})} + \frac{\frac{1}{2} \|\mathbf{w}\|^2 + \ln \frac{1}{\delta}}{m} \right] \right) \geq 1 - \delta.$$

Risque

$$R_D(G_{\mathbf{w}}) = \mathbf{E}_{(\mathbf{x},y)\sim D} \Phi\left(y \frac{\mathbf{w} \cdot \mathbf{x}}{\|\mathbf{x}\|}\right)$$

Risque empirique

$$R_S(G_{\mathbf{w}}) = \sum_{i=1}^{m} \Phi\left(y_i \frac{\mathbf{w} \cdot \mathbf{x}_i}{\|\mathbf{x}_i\|}\right)$$

Régularisateur

Algorithme d'apprentissage

(Germain et al., 2009)

Étant donné un ensemble S de m exemples et un paramètre C:

Trouver le
$$\mathbf{w}$$
 qui minimise : $C \cdot m \, \overline{R_S(G_\mathbf{w})} + \frac{1}{2} ||\mathbf{w}||^2$

Problème d'adaptation de domaine

Représentation des données

• Exemples sources (\mathbf{x}^s, y^s)

Distribution source

- Description $\mathbf{x}^s \in \mathbb{R}^d$
- Étiquette $y^s \in \{-1, +1\}$
- Exemples cibles $(\mathbf{x}^t, y^t) \sim D_T \blacktriangleleft$

Distribution cible

- Description $\mathbf{x}^t \in \mathbb{R}^d$
- Étiquette $y^t \in \{-1, +1\}$

Représentation des données

• Exemples sources (\mathbf{x}^s, y^s)

✓ Distribution source

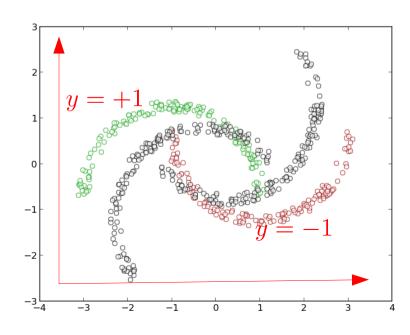
- Description $\mathbf{x}^s \in \mathbb{R}^d$
- Étiquette $y^s \in \{-1, +1\}$
- Exemples cibles $(\mathbf{x}^t) \sim D_{T'} \blacktriangleleft$

Distribution cible

- Description $\mathbf{x}^t \in \mathbb{R}^d$
- Étiquette $y^t \in \{-1, +1\}$
- Ensembles d'entraînement

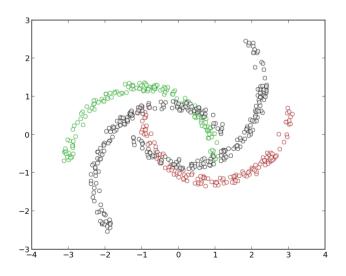
$$S = \{(\mathbf{x}_1^s, y_1^s), \dots, (\mathbf{x}_m^s, y_m^s)\} \sim D_S^m$$

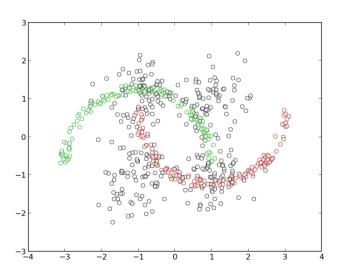
$$T = \{\mathbf{x}_1^t, \dots, \mathbf{x}_m^t\} \sim D_{T'}^m$$



Quand l'adaptation est-elle possible?

- Question: Dans quelle(s) situation(s) est-il possible de s'adapter au domaine cible?
- <u>Réponse (partielle)</u>: Lorsque les domaines source et cible sont « semblables ».
- On a donc besoin d'une mesure permettant de quantifier la <u>« distance »</u> entre les distributions.





Divergence entre les distributions

Théorème

(Ben-David et al., 2010)

Soit D_S une distribution source et D_T une distribution cible.

Soit \mathcal{H} une famille de classificateurs. Pour tout $h \in \mathcal{H}$, on a

$$R_{D_T}(h) \le R_{D_S}(h) + \frac{1}{2} d_{\mathcal{H}\Delta\mathcal{H}}(D_{S'}, D_{T'}) + \min_{h^* \in \mathcal{H}} \left[R_{D_T}(h^*) + R_{D_S}(h^*) \right]$$

Risque cible

Risque source

Meilleur risque conjoint

Divergence

$$\frac{1}{2}d_{\mathcal{H}\Delta\mathcal{H}}(D_{S'}, D_{T'}) = \sup_{h, h' \in \mathcal{H}} \left| \mathbf{E}_{\mathbf{x}^s \sim D_{S'}} \mathbf{I}[h(\mathbf{x}^s) \neq h'(\mathbf{x}^s)] - \mathbf{E}_{\mathbf{x}^t \sim D_{T'}} \mathbf{I}[h(\mathbf{x}^t) \neq h'(\mathbf{x}^t)] \right|$$

Divergence entre les distributions



Soit D_S une distribution source et D_T une distribution cible.

Pour tout $\mathbf{w} \in \mathbb{R}^d$, représentant un classificateur linéaire, on a

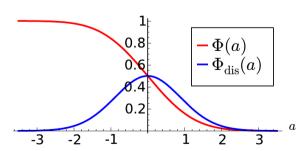
$$R_{D_T}(G_{\mathbf{w}}) \le R_{D_S}(G_{\mathbf{w}}) + \operatorname{dis}_{\mathbf{w}}(D_{S'}, D_{T'}) + R_{D_T}(G^*) + \lambda_{\mathbf{w}}^*$$

$$\begin{array}{c|c} \textbf{Risque cible} & \textbf{Risque source} \\ R_{D_T}(G_{\mathbf{w}}) = \underset{(\mathbf{x}^t, y^t) \sim D_T}{\mathbf{E}} \Phi \left(y^t \frac{\mathbf{w} \cdot \mathbf{x}^t}{\|\mathbf{x}^t\|} \right) & R_{S_T}(G_{\mathbf{w}}) = \underset{(\mathbf{x}^s, y^s) \sim D_S}{\mathbf{E}} \Phi \left(y^s \frac{\mathbf{w} \cdot \mathbf{x}^s}{\|\mathbf{x}^s\|} \right) \end{array}$$

$$R_{S_T}(G_{\mathbf{w}}) = \mathbf{E}_{(\mathbf{x}^s, y^s) \sim D_S} \Phi\left(y^s \frac{\mathbf{w} \cdot \mathbf{x}^s}{\|\mathbf{x}^s\|}\right)$$

Meilleur risque cible

Mesure de capacité d'adaptation



Divergence

$$\operatorname{dis}_{\mathbf{w}}(D_{S'}, D_{T'}) = \left| \underset{\mathbf{x}^s \sim D_{S'}}{\mathbf{E}} \Phi_{\operatorname{dis}} \left(\frac{\mathbf{w} \cdot \mathbf{x}^s}{\|\mathbf{x}^s\|} \right) - \underset{\mathbf{x}^t \sim D_{T'}}{\mathbf{E}} \Phi_{\operatorname{dis}} \left(\frac{\mathbf{w} \cdot \mathbf{x}^t}{\|\mathbf{x}^t\|} \right) \right|$$

Apprentissage PAC-Bayésien

Nouveau théorème PAC-Bayes (spécialisé aux classificateurs linéaires)

- Pour tout domaines D_S et D_T
- Pour toute *confiance* $\delta \in (0,1]$
- Pour tout paramètres $c \in (0,\infty)$ et $\alpha \in (0,\infty)$

$$\Pr_{\substack{(S \times T) \sim \\ (D_S \times D_T)^m}} \left(\begin{array}{c} \forall \mathbf{w} \in \mathbb{R}^d : \boxed{R_{D_T}(G_{\mathbf{w}}) + \operatorname{dis}(D_{S'}, D_{T'})} \\ \leq c' \cdot R_S(G_{\mathbf{w}}) + \alpha' \cdot \operatorname{dis}(S, T) + \left(\frac{c'}{c} + \frac{2\alpha'}{\alpha}\right) \frac{\frac{1}{2} ||\mathbf{w}||^2 + \ln \frac{3}{\delta}}{m} \end{array} \right) \geq 1 - \delta.$$

avec
$$c' = \frac{c}{1 - e^{-c}}$$
 et $\alpha' = \frac{2\alpha}{1 - e^{-\alpha}}$

Algorithme d'apprentissage

Étant donné des ensembles S et T de m exemples et deux paramètres C et A, trouver le W qui minimise :

$$C m R_S(G_{\mathbf{w}}) + A m \operatorname{dis}_{\mathbf{w}}(S,T) + \frac{1}{2} ||\mathbf{w}||^2$$

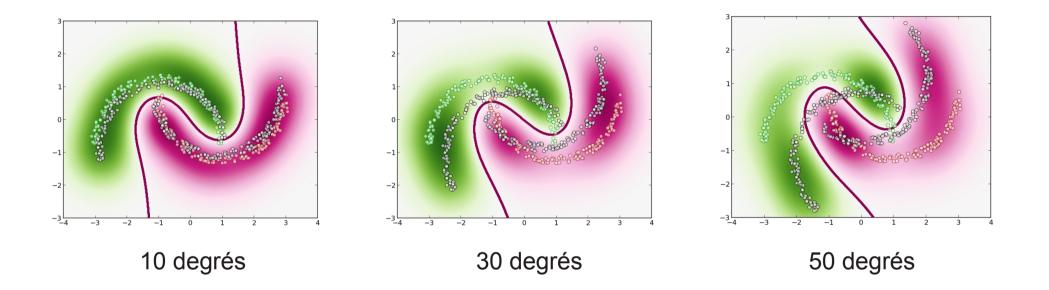
Risque source empirique

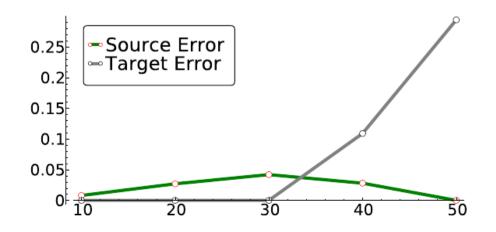
Divergence empirique

Régularisateur

Résultats empiriques

Problème jouet







Amazon reviews



critiques de livres

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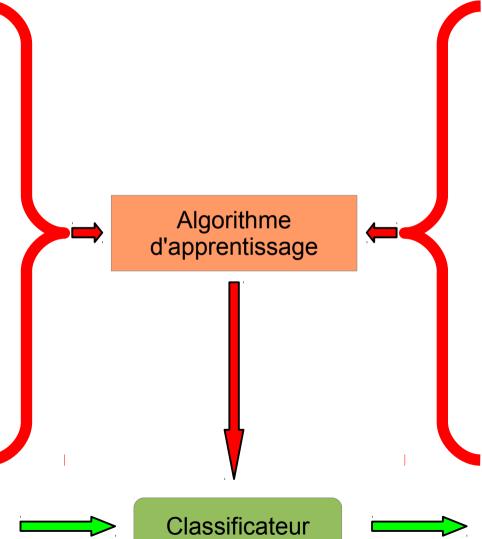
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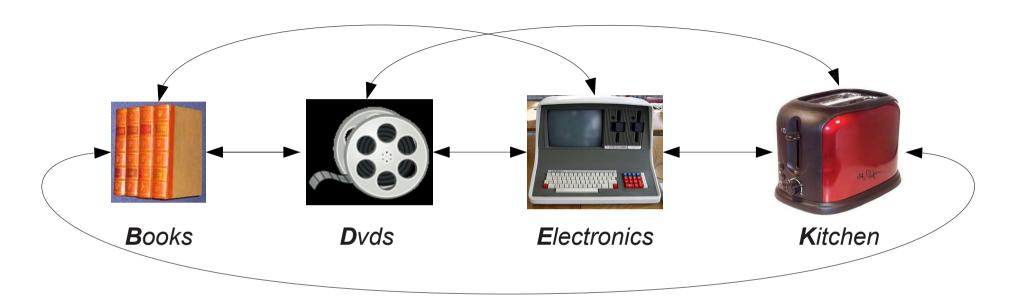
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Read more

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Amazon reviews



 ${\tt TABLE\ 2-Taux\ d'erreurs\ sur}\ \textit{Amazon\ reviews}.\ B,\ D,\ E,\ K\ correspondent\ \grave{a}\ \textit{books},\ \textit{DVDs},\ electronics,\ kitchen.$

| | | $B\rightarrow D$ | $B \rightarrow E$ | В→К | $D \rightarrow B$ | $D \rightarrow E$ | $D \rightarrow K$ | $E \rightarrow B$ | $E \rightarrow D$ | $E \rightarrow K$ | $K \rightarrow B$ | $K\rightarrow D$ | $K \rightarrow E$ | Avg. |
|---|--------------|------------------|-------------------|-------|-------------------|-------------------|-------------------|-------------------|-------------------|-------------------|-------------------|------------------|-------------------|-------|
| | $PBGD3^{CV}$ | | | 0.236 | | l | 0.211 | 0.268 | 0.245 | 0.127 | 0.255 | 0.244 | 0.235 | 0.226 |
| | SVM^{CV} | | | 0.251 | 0.203 | 0.269 | 0.232 | 0.287 | 0.267 | 0.129 | 0.267 | 0.253 | 0.149 | 0.231 |
| | $ASVM^{RCV}$ | | 0.226 | l | | | | 0.305 | ' | 0.149 | 0.259 | 0.198 | 1 1 | |
| C | $CODA^{RCV}$ | 0.181 | 0.232 | 0.215 | 0.217 | 0.214 | 0.181 | 0.275 | 0.239 | 0.134 | 0.247 | 0.238 | 0.153 | 0.210 |
| F | $PBDA^{RCV}$ | 0.183 | 0.263 | 0.229 | 0.197 | 0.241 | 0.186 | 0.232 | 0.221 | 0.141 | 0.247 | 0.233 | 0.129 | 0.208 |

Fin.