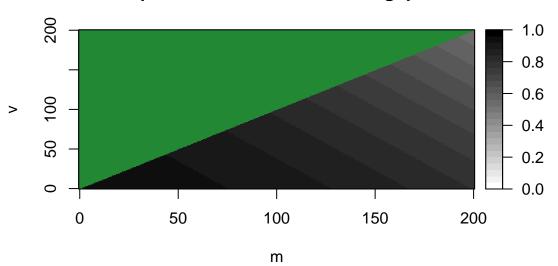
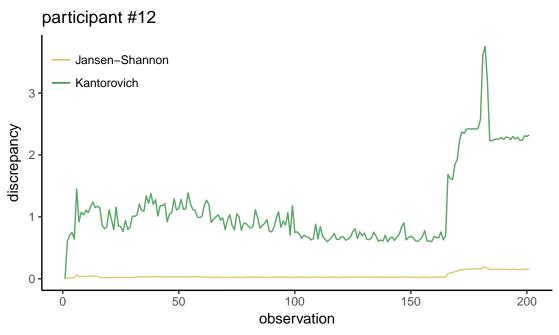
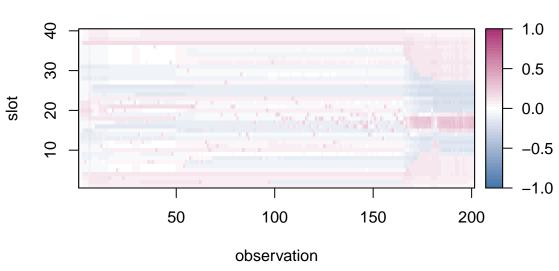


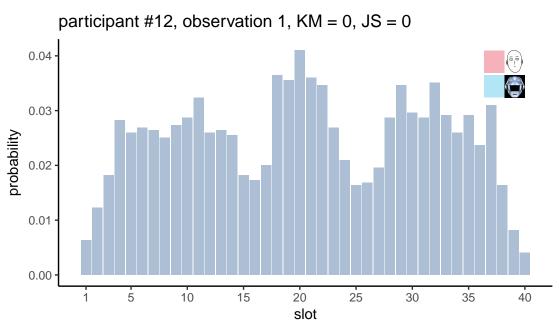
part. #12, stub. = 4.97, changepoint:

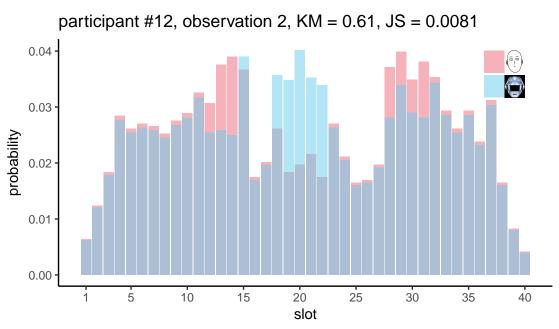


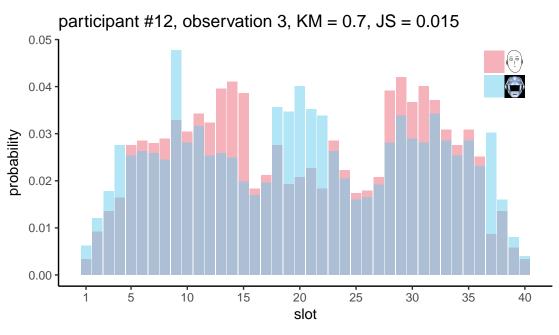


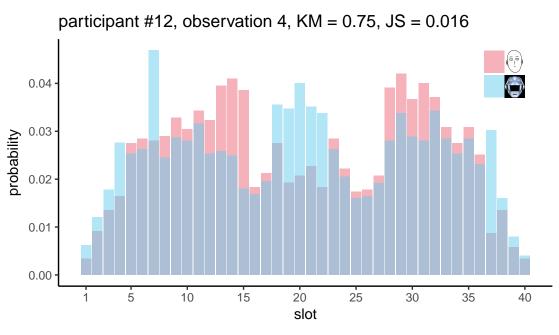
participant #12, sqrt(robot-participant)

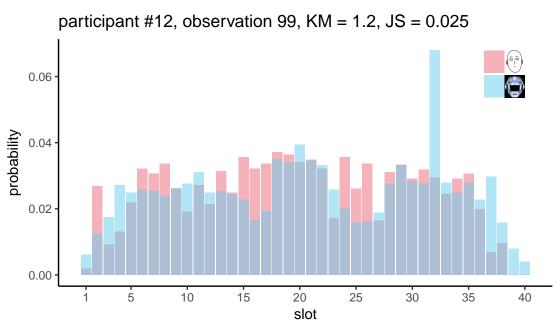


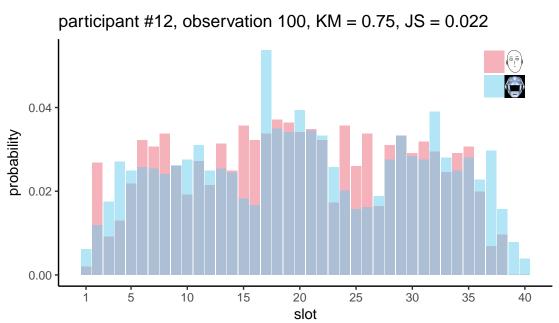


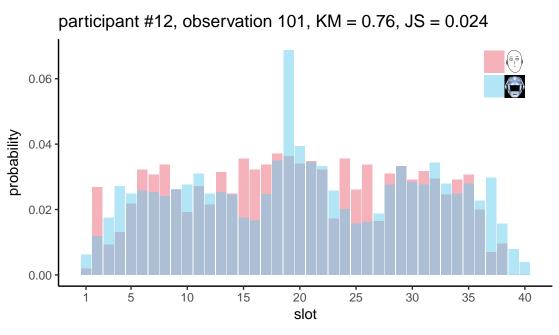


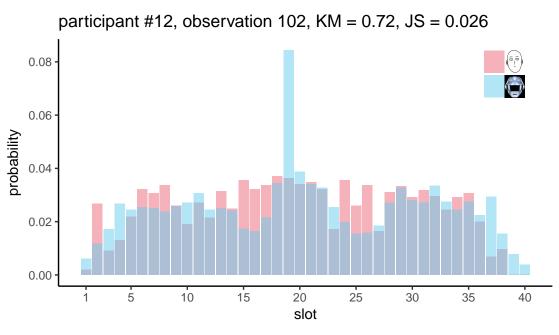


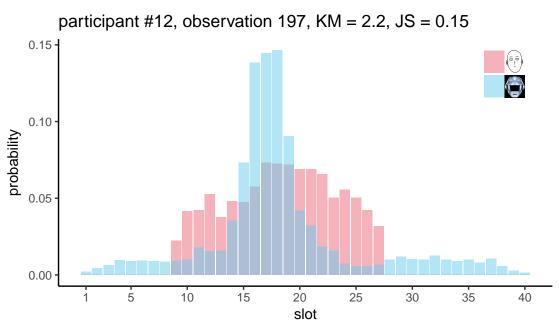












participant #12, observation 198, KM = 2.2, JS = 0.15 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

