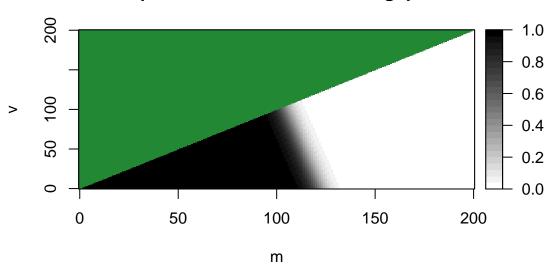
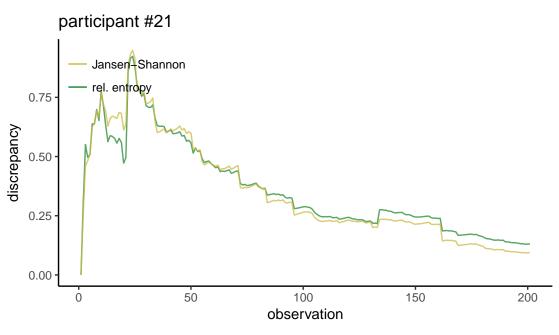
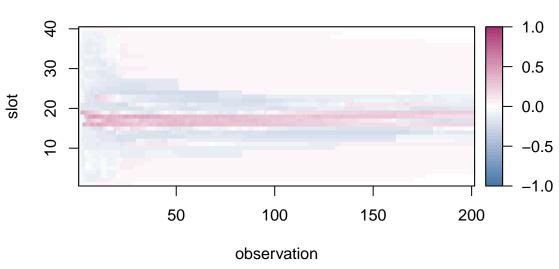


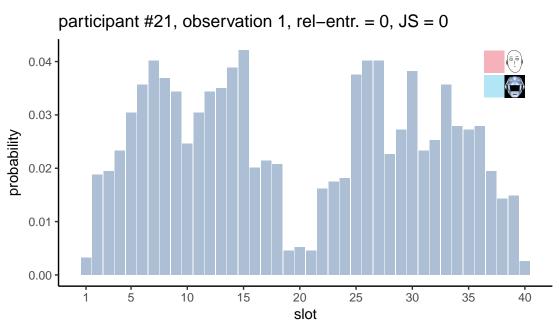
part. #21, stub. = 3.42, changepoint:

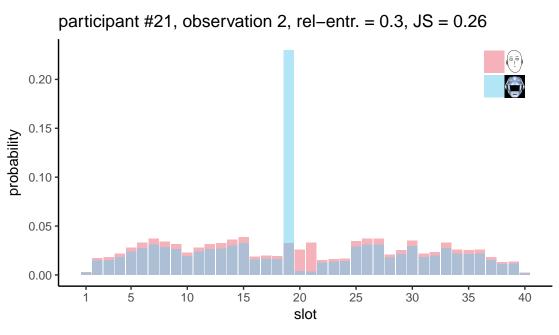




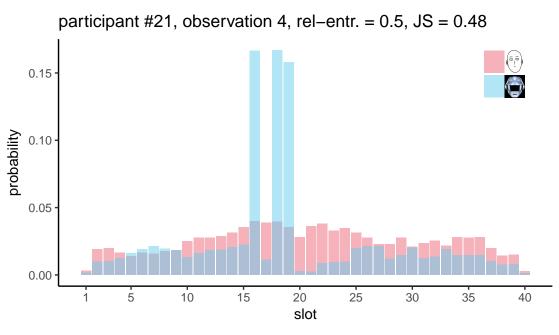
participant #21, sqrt(robot-participant)





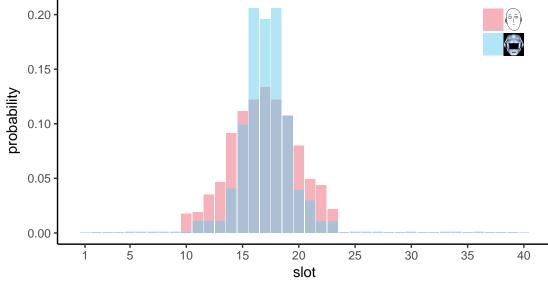


participant #21, observation 3, rel-entr. = 0.55, JS = 0.46 0.20 0.15 probability 0.05 0.00 15 25 5 10 20 30 35 40 slot

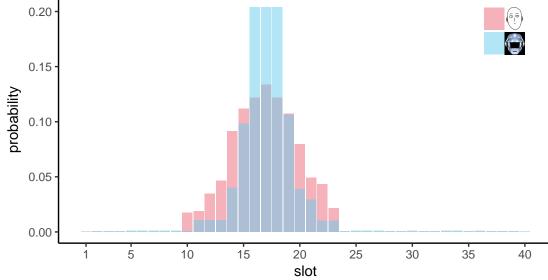


participant #21, observation 99, rel-entr. = 0.29, JS = 0.26 0.20 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

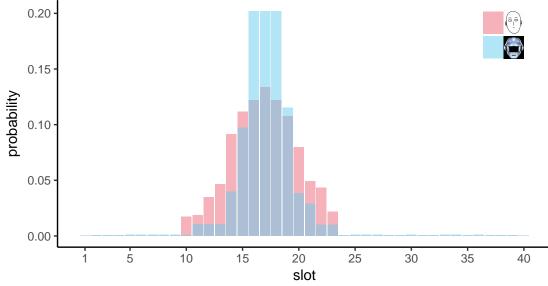
participant #21, observation 100, rel-entr. = 0.29, JS = 0.26



participant #21, observation 101, rel-entr. = 0.29, JS = 0.27



participant #21, observation 102, rel-entr. = 0.29, JS = 0.27



participant #21, observation 197, rel-entr. = 0.13, JS = 0.094 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #21, observation 198, rel-entr. = 0.13, JS = 0.094 0.20 0.15 probability 0.05 0.00

20

slot

25

30

35

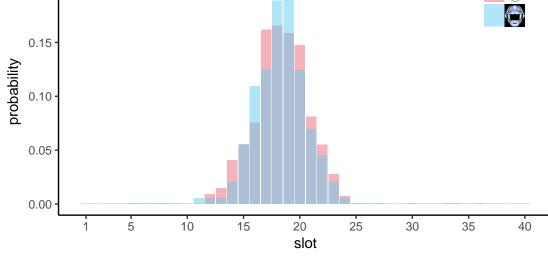
40

10

5

15

participant #21, observation 199, rel-entr. = 0.13, JS = 0.092 0.20 0.15



participant #21, observation 200, rel-entr. = 0.13, JS = 0.094 0.20 0.15 probability

