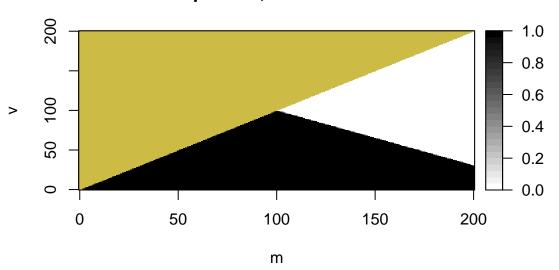
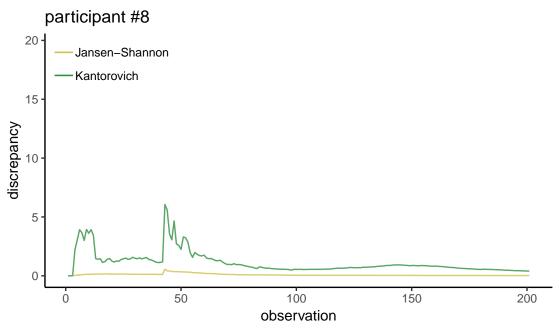
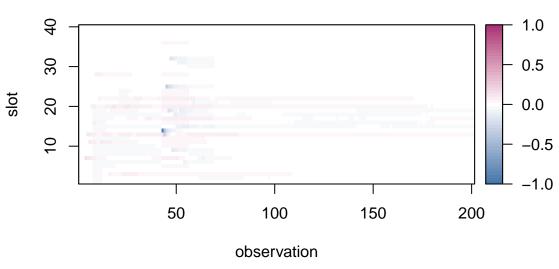


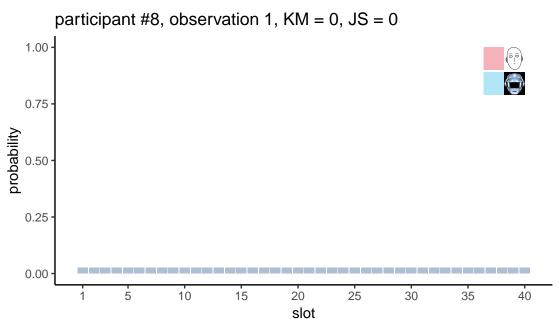
h for part. #8, stubbornness = 5.59

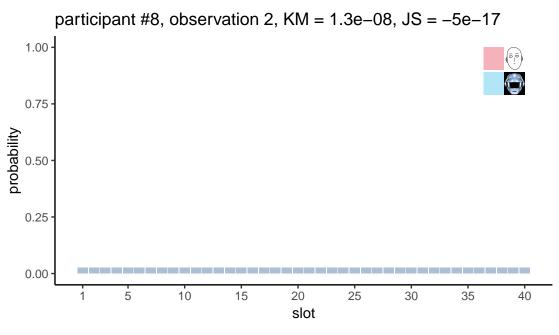


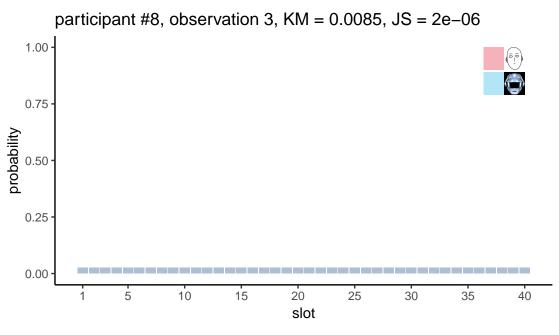


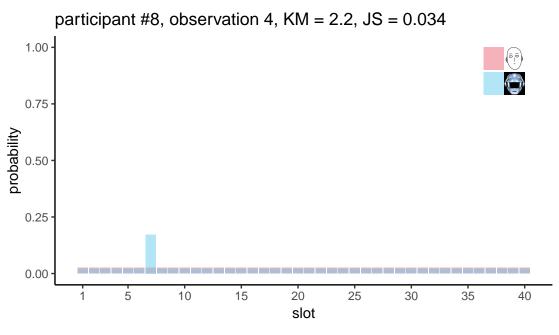
participant #8, sqrt(robot-participant)

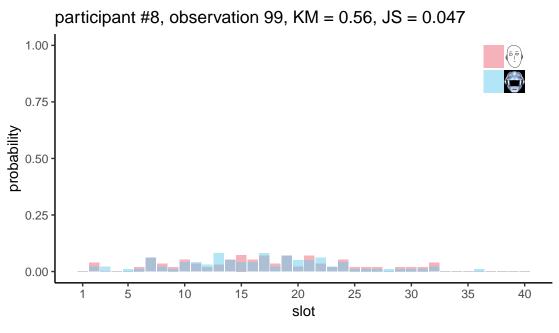


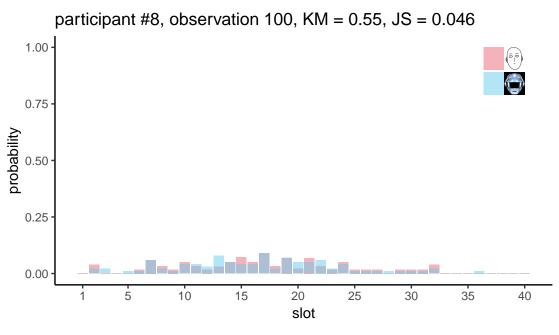


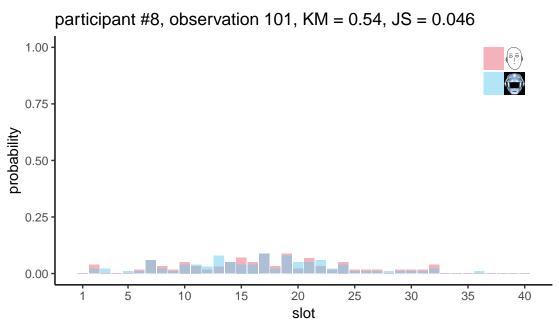


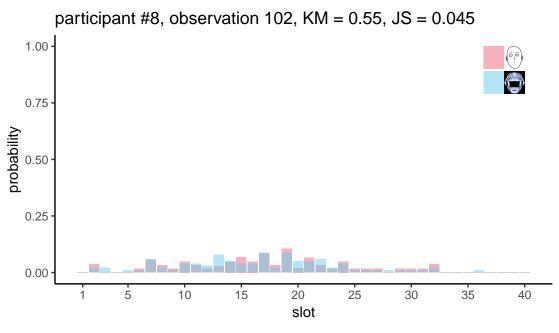












participant #8, observation 197, KM = 0.43, JS = 0.023 1.00 0.75 probability 0.25 0.00 10 15 20 25 30 35 40 5 slot

