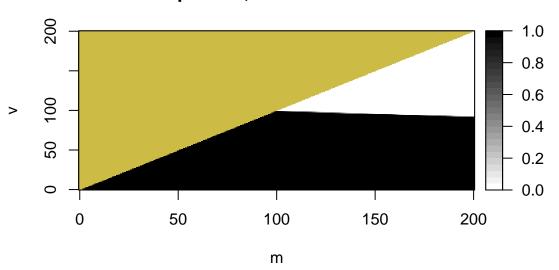
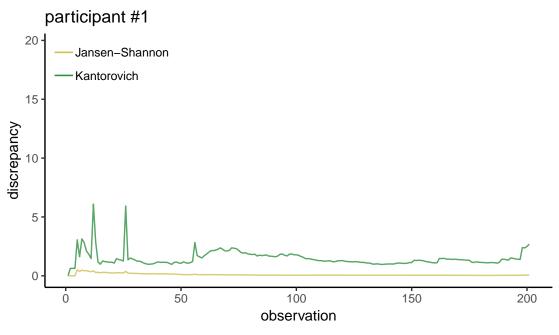


h for part. #1, stubbornness = 0.00392





participant #1, sqrt(robot-participant)

