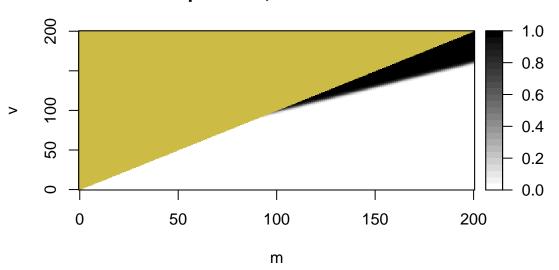
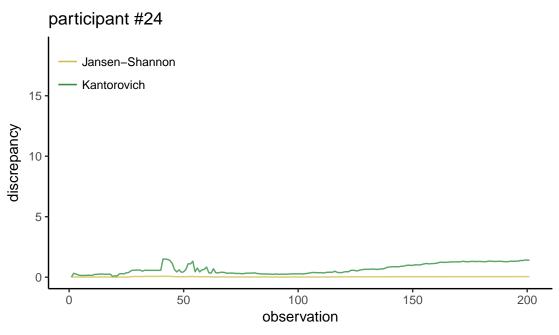


h for part. #24, stubbornness = 2.71





participant #24, sqrt(robot-participant)

