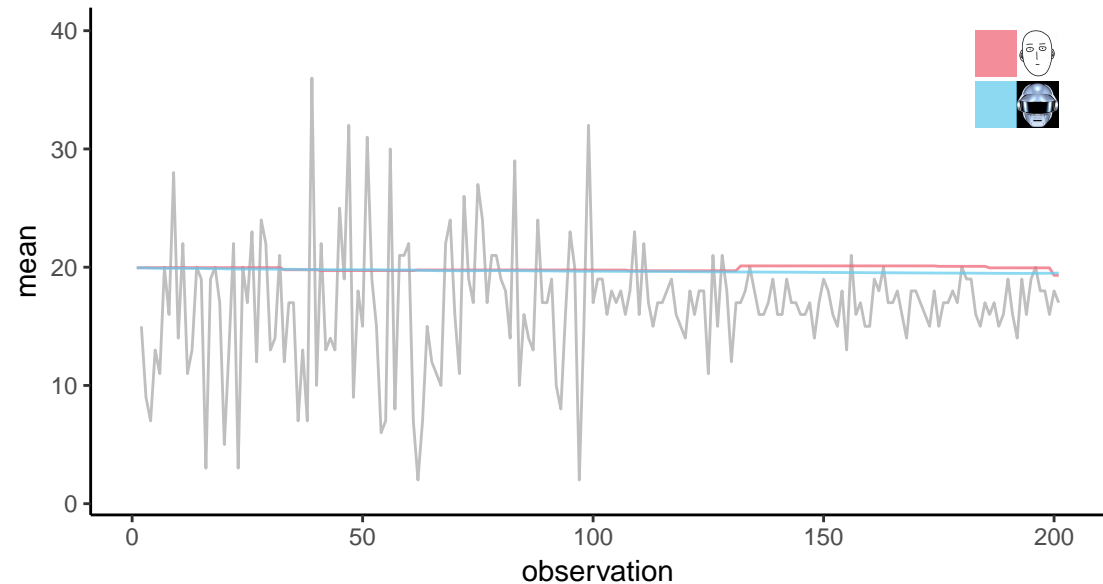
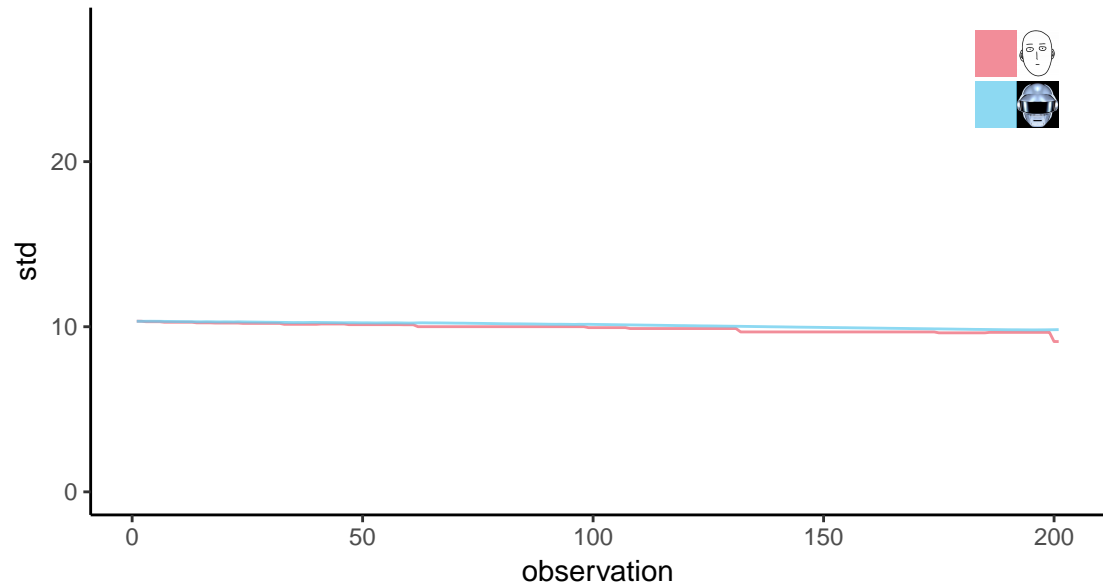


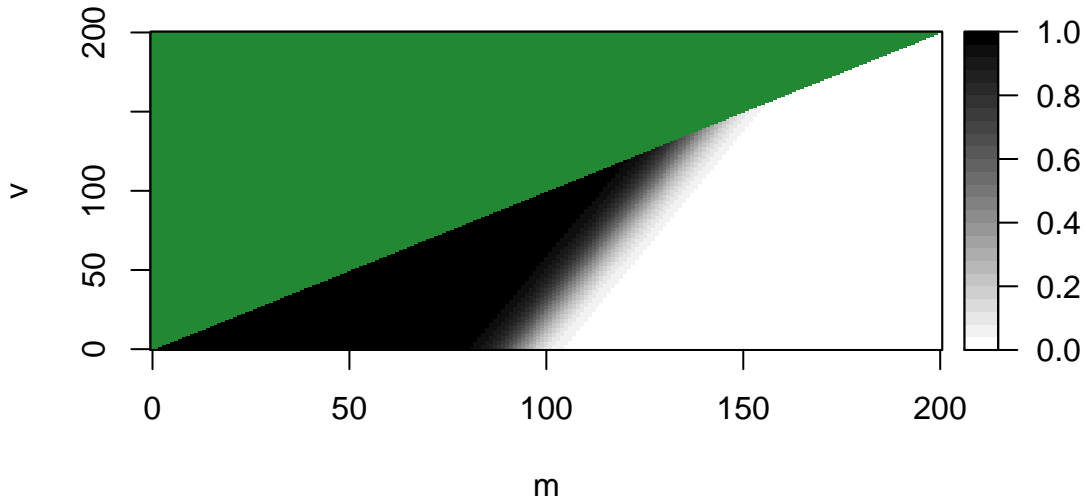
participant #2, means (black: plinko outcomes)



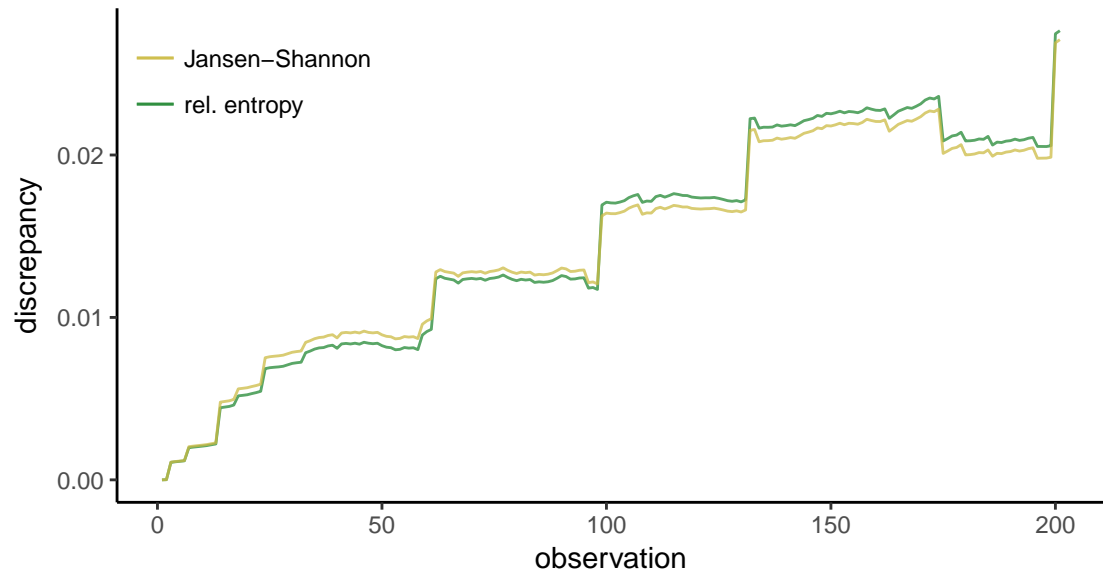
participant #2, st. deviations



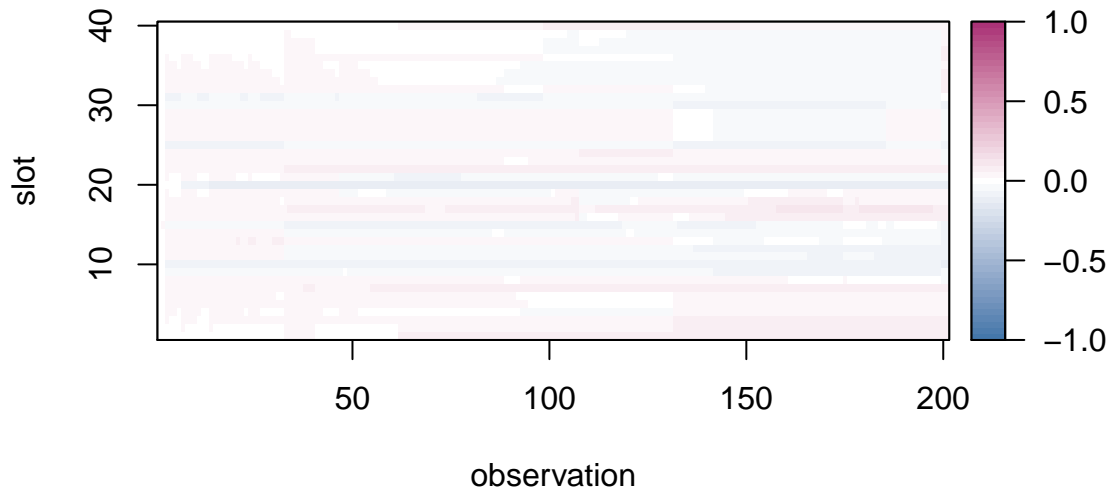
part. #2, stub. = 1.09e+03, changepoint:



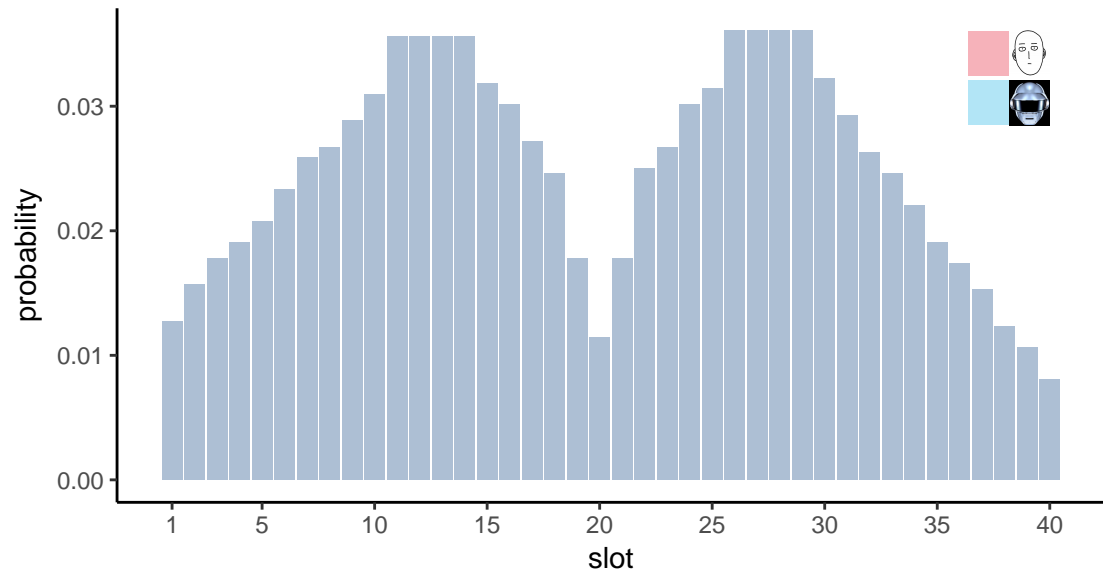
participant #2



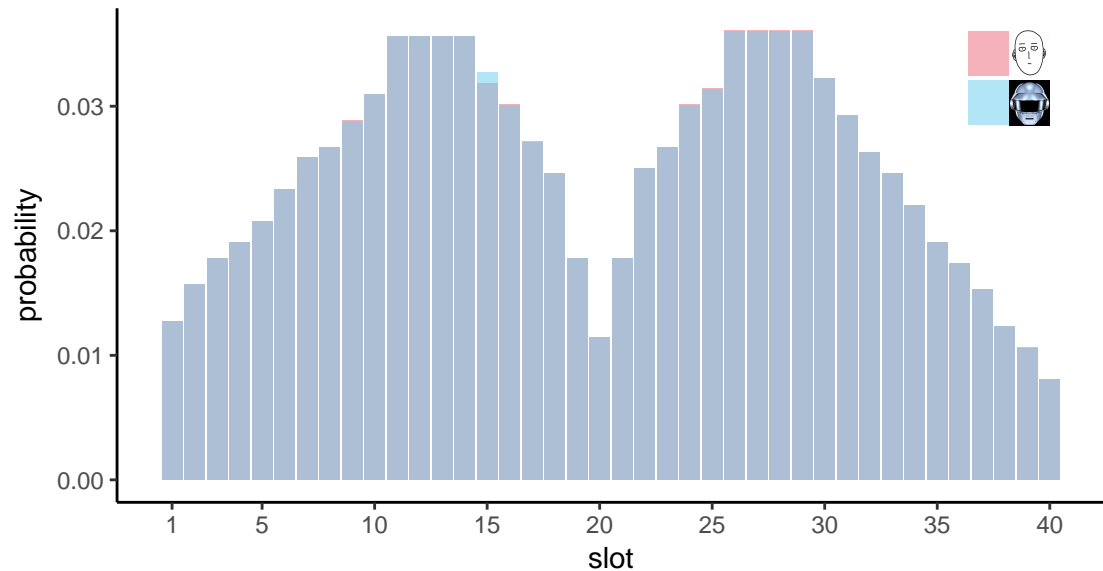
participant #2, $\sqrt{\text{robot-participant}}$



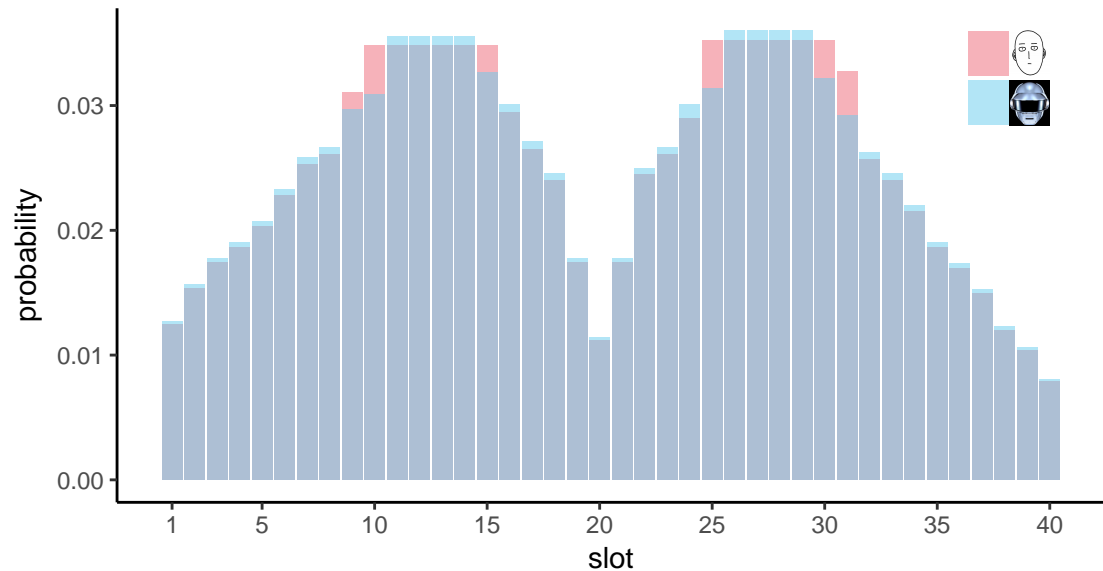
participant #2, observation 1, rel-entr. = 0, JS = 0



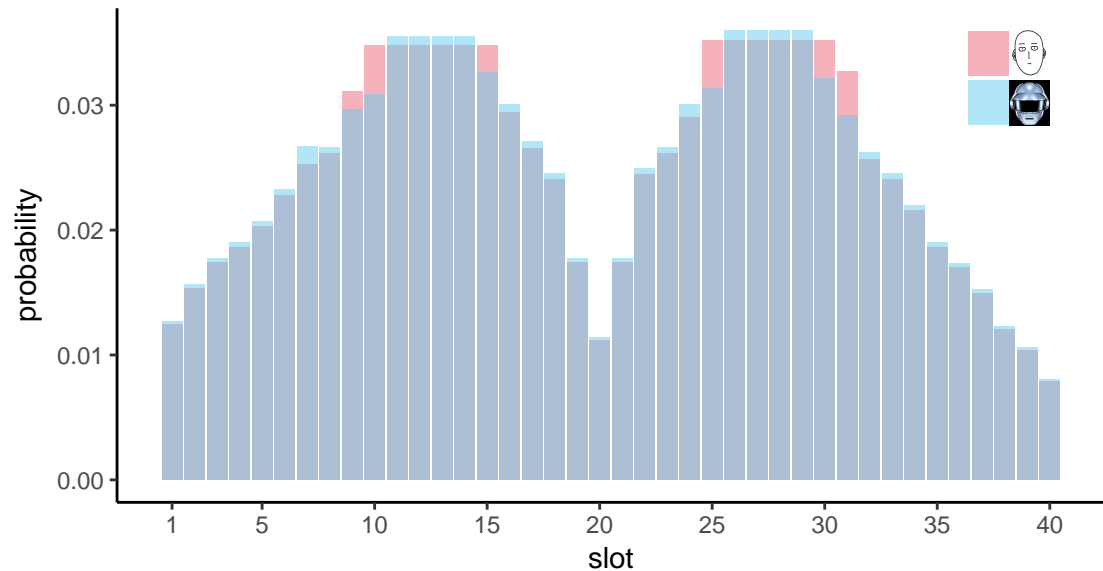
participant #2, observation 2, rel-entr. = $1.3\text{e-}05$, JS = $1.3\text{e-}05$



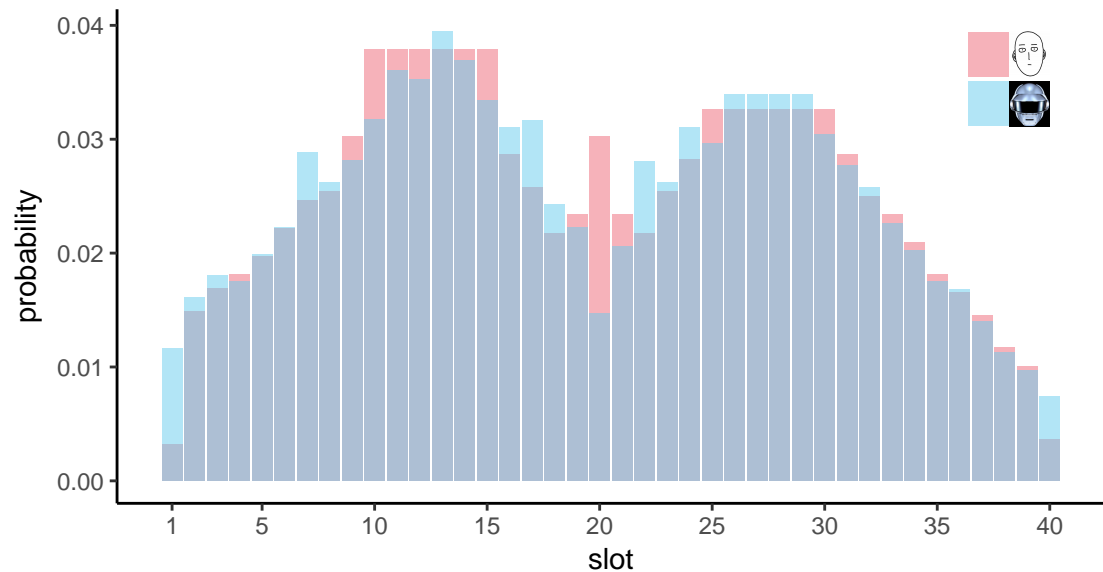
participant #2, observation 3, rel-entr. = 0.0011, JS = 0.0011



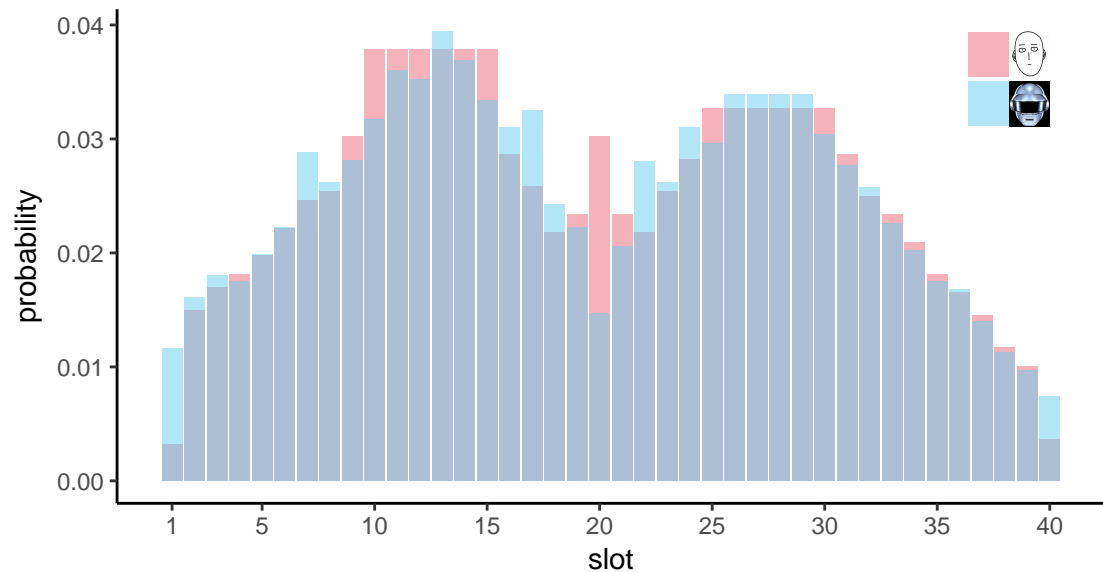
participant #2, observation 4, rel-entr. = 0.0011, JS = 0.0011



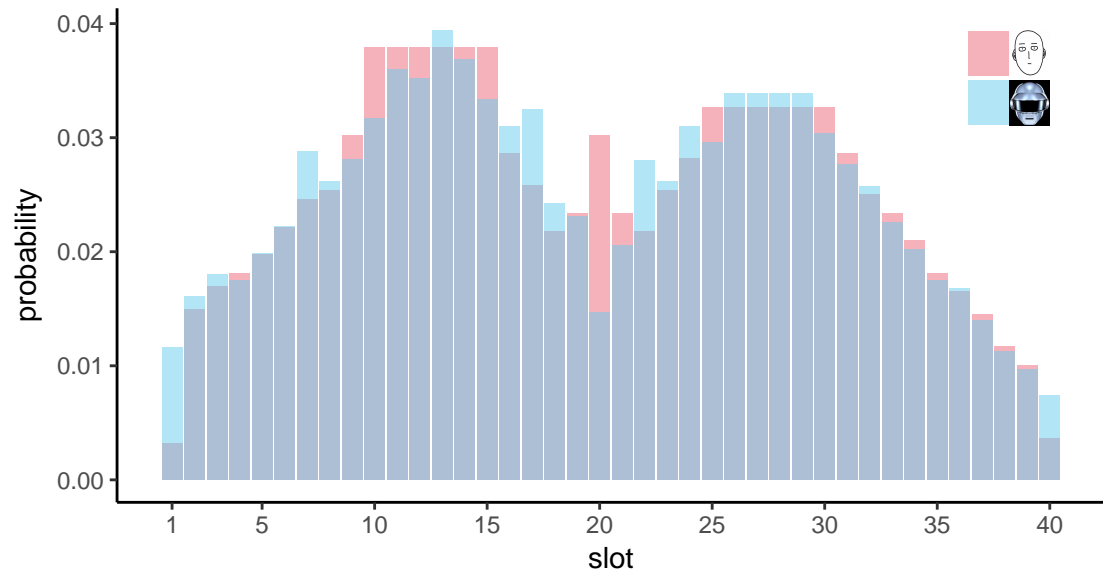
participant #2, observation 99, rel-entr. = 0.017, JS = 0.016



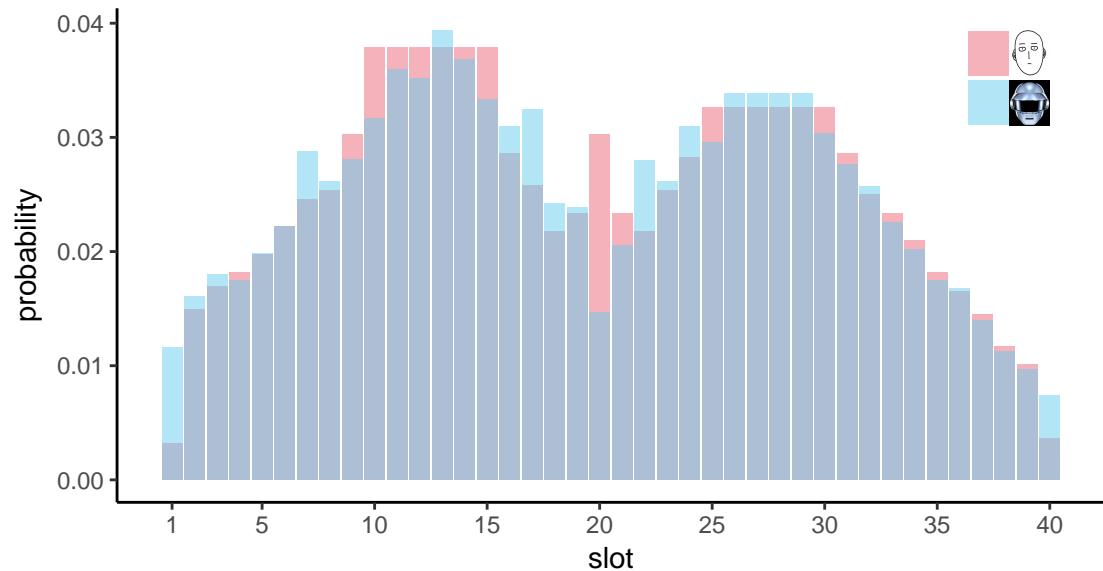
participant #2, observation 100, rel-entr. = 0.017, JS = 0.016



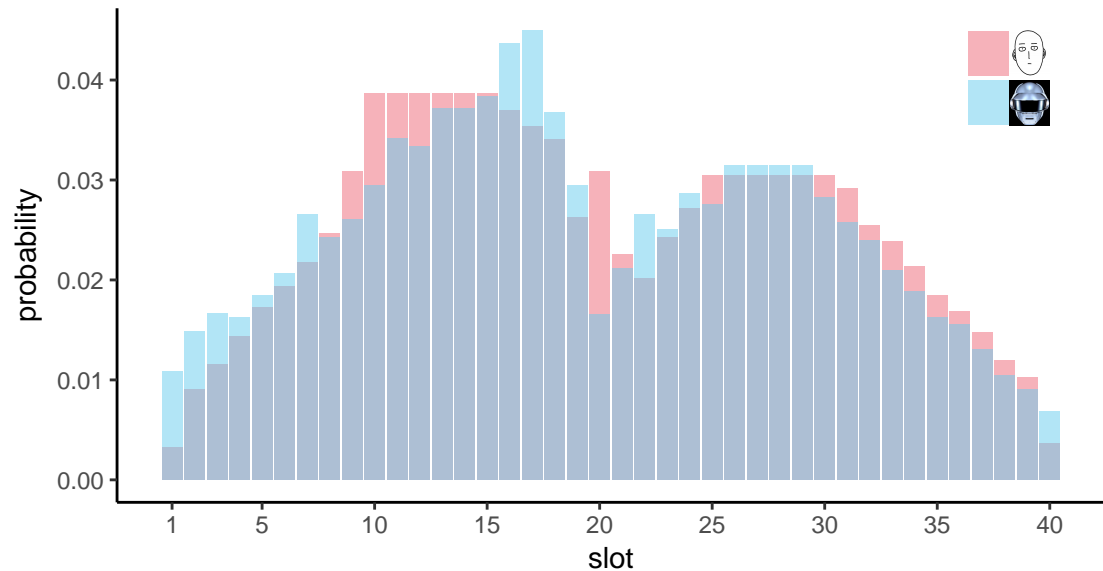
participant #2, observation 101, rel-entr. = 0.017, JS = 0.016



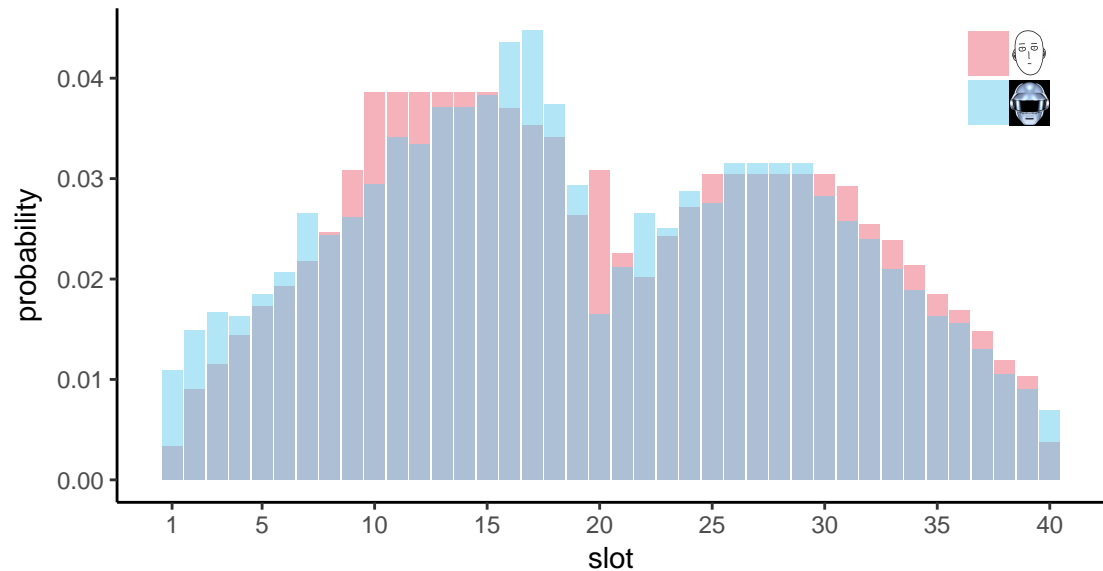
participant #2, observation 102, rel-entr. = 0.017, JS = 0.016



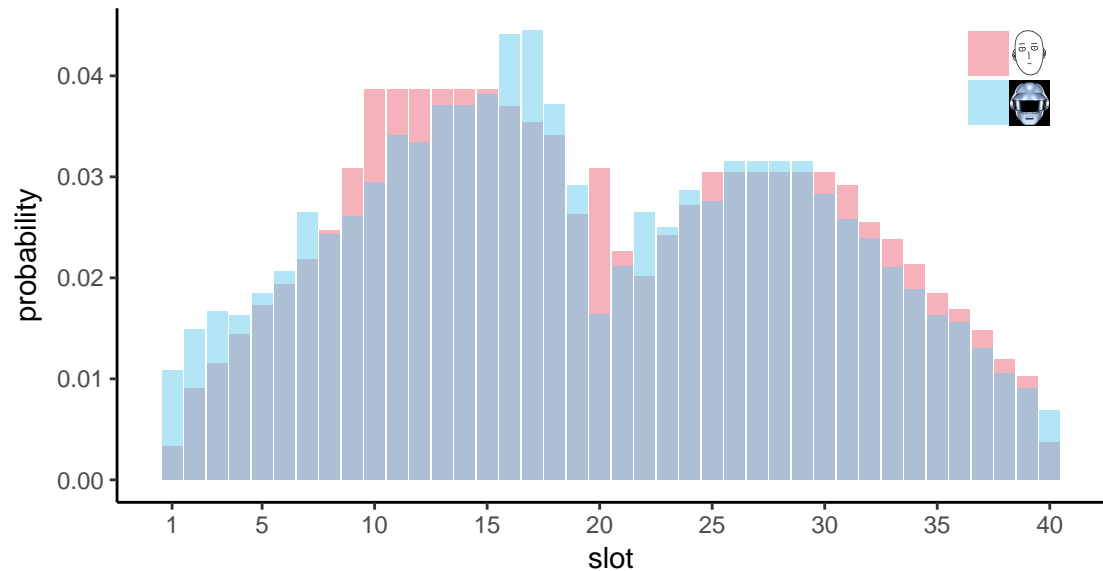
participant #2, observation 197, rel-entr. = 0.021, JS = 0.02



participant #2, observation 198, rel-entr. = 0.021, JS = 0.02



participant #2, observation 199, rel-entr. = 0.021, JS = 0.02



participant #2, observation 200, rel-entr. = 0.027, JS = 0.027

