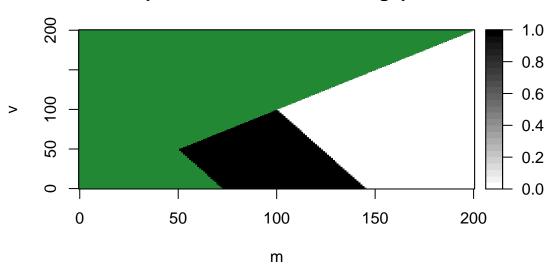
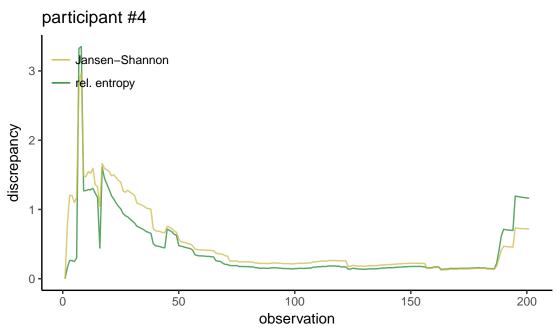
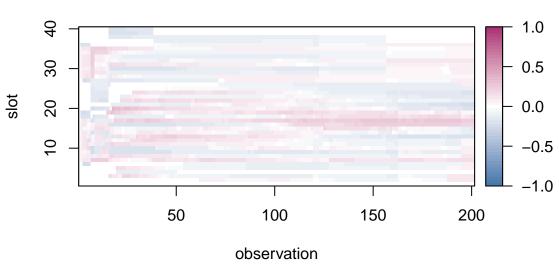


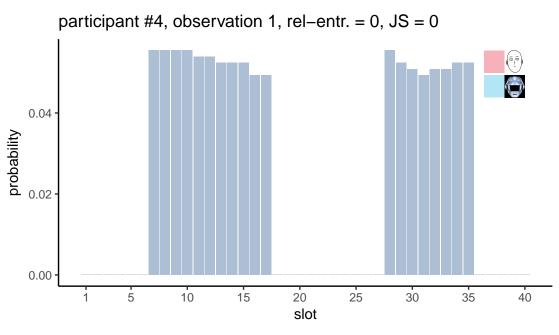
part. #4, stub. = 7.19, changepoint:



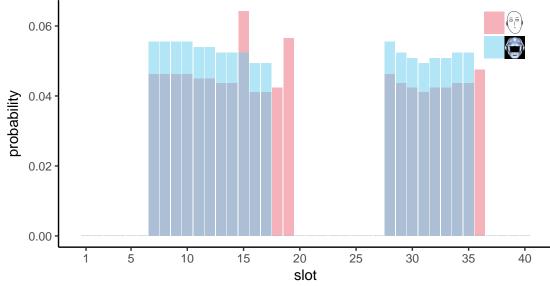


participant #4, sqrt(robot-participant)

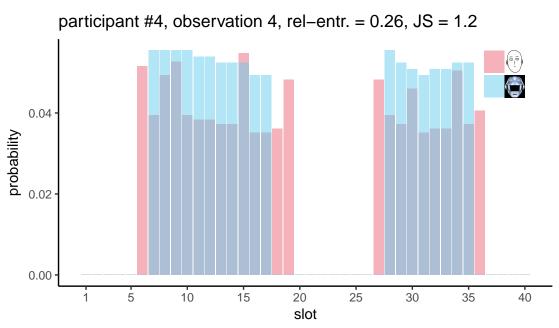




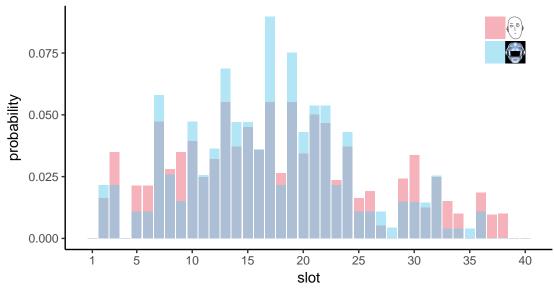
participant #4, observation 2, rel-entr. = 0.16, JS = 0.78



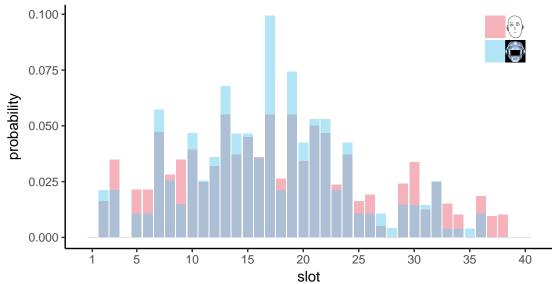
participant #4, observation 3, rel-entr. = 0.26, JS = 1.2 0.04 probability 0.00 slot



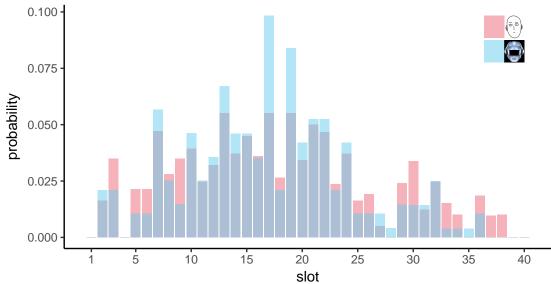
participant #4, observation 99, rel-entr. = 0.14, JS = 0.21



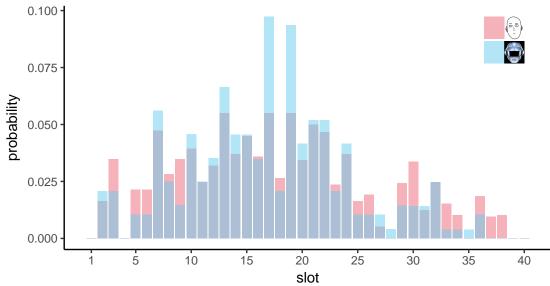
participant #4, observation 100, rel-entr. = 0.14, JS = 0.22



participant #4, observation 101, rel-entr. = 0.15, JS = 0.22



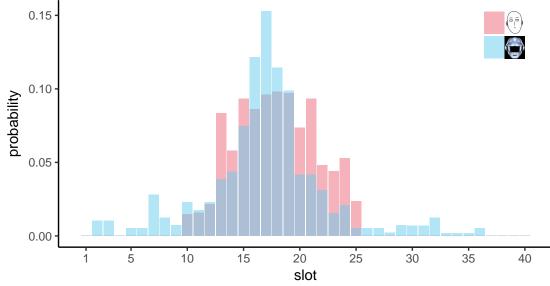
participant #4, observation 102, rel-entr. = 0.15, JS = 0.22



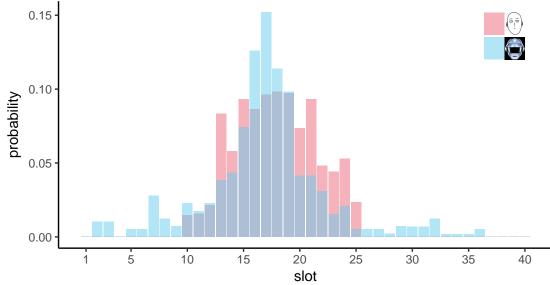
participant #4, observation 197, rel-entr. = 1.2, JS = 0.73 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40

slot

participant #4, observation 198, rel-entr. = 1.2, JS = 0.72



participant #4, observation 199, rel-entr. = 1.2, JS = 0.72



participant #4, observation 200, rel-entr. = 1.2, JS = 0.72

