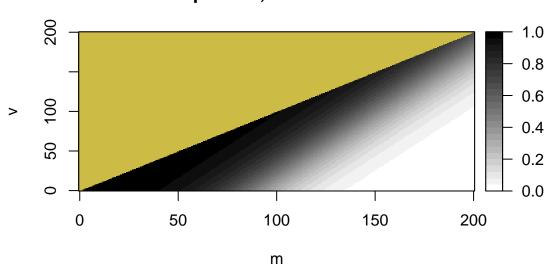
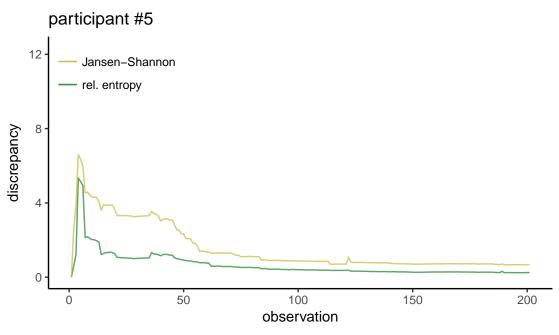
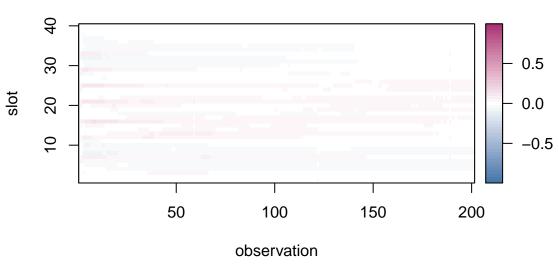


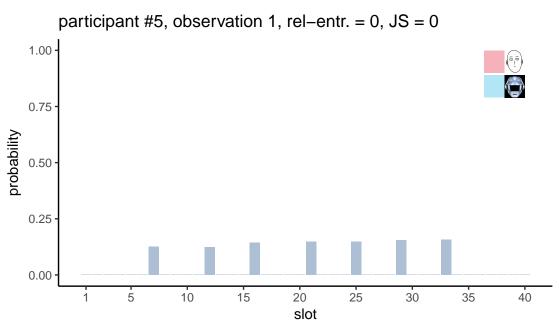
h for part. #5, stubbornness = 27.2

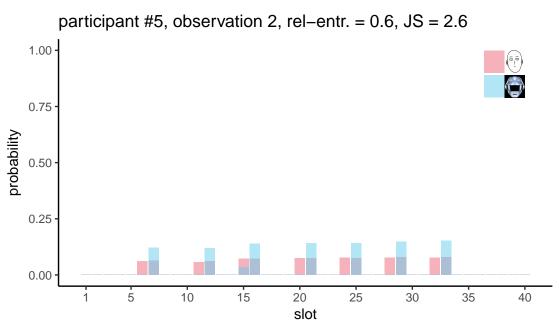




participant #5, sqrt(robot-participant)







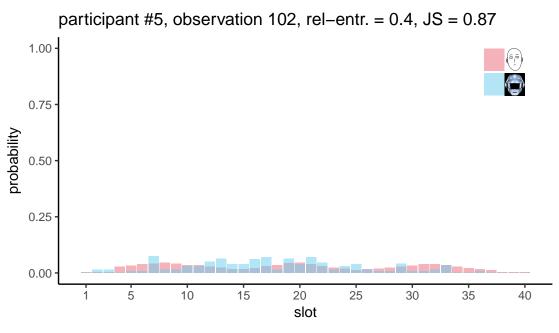
participant #5, observation 3, rel-entr. = 1.2, JS = 3.8 1.00 0.75 probability 0.25 0.00 15 25 30 5 10 20 35 40 slot

participant #5, observation 4, rel-entr. = 5.3, JS = 6.6 1.00 0.75 probability 0.25 0.00 15 25 30 5 10 20 35 40 slot

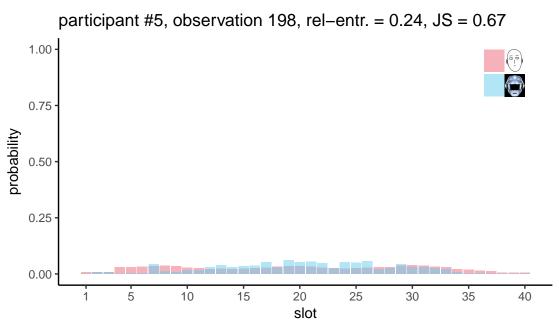
participant #5, observation 99, rel-entr. = 0.4, JS = 0.87 1.00 0.75 probability 0.25 0.00 15 25 30 5 10 20 35 40 slot

participant #5, observation 100, rel-entr. = 0.41, JS = 0.88 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 30 35 40 slot

participant #5, observation 101, rel-entr. = 0.41, JS = 0.88 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 30 35 40 slot



participant #5, observation 197, rel-entr. = 0.24, JS = 0.67 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 30 35 40 slot



participant #5, observation 199, rel-entr. = 0.25, JS = 0.68 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 30 35 40 slot

