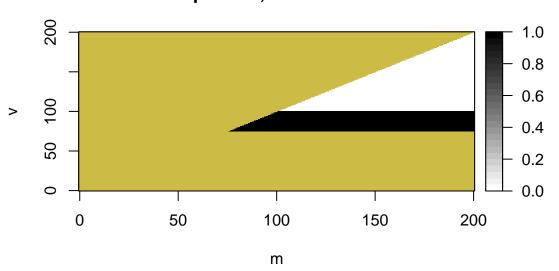
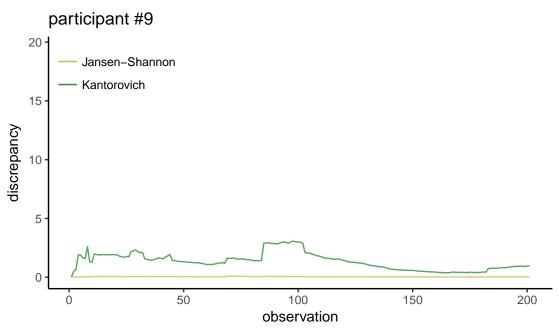
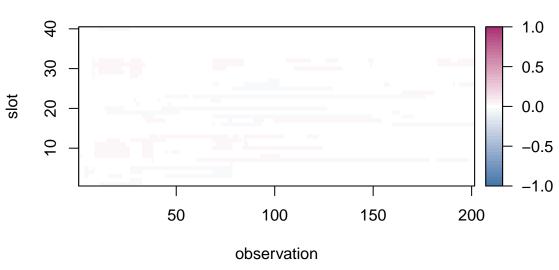


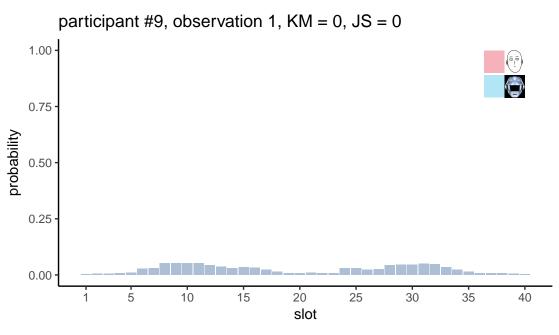
## h for part. #9, stubbornness = 31.7

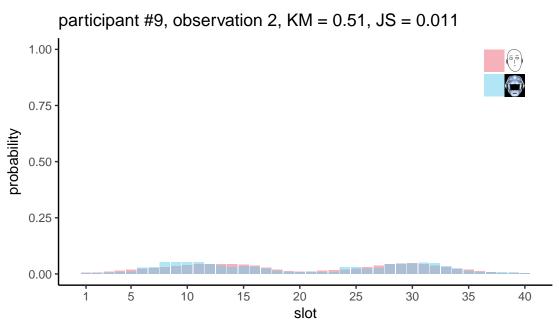




## participant #9, sqrt(robot-participant)







participant #9, observation 3, KM = 0.67, JS = 0.0121.00 0.75 probability 0.25 0.00 10 15 25 5 30 35 20 40 slot

