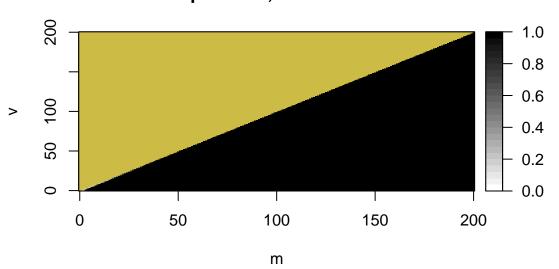
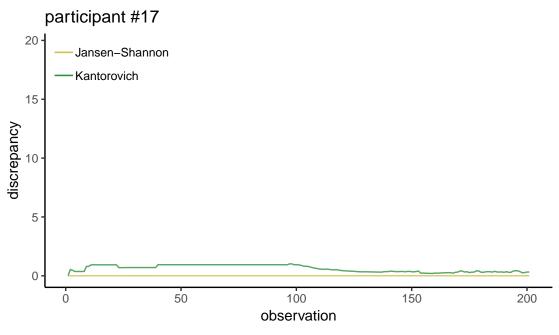


h for part. #17, stubbornness = 178





participant #17, sqrt(robot-participant)

