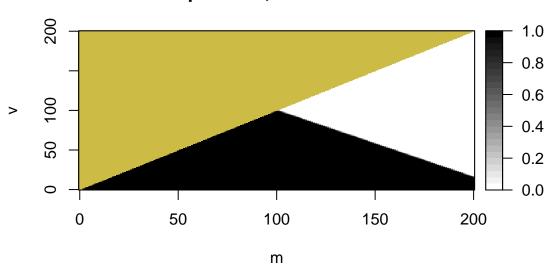
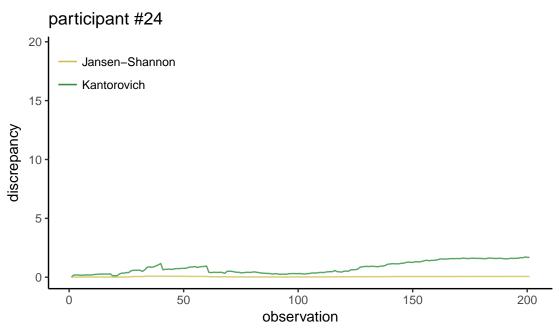


## h for part. #24, stubbornness = 10.8





## participant #24, sqrt(robot-participant)

