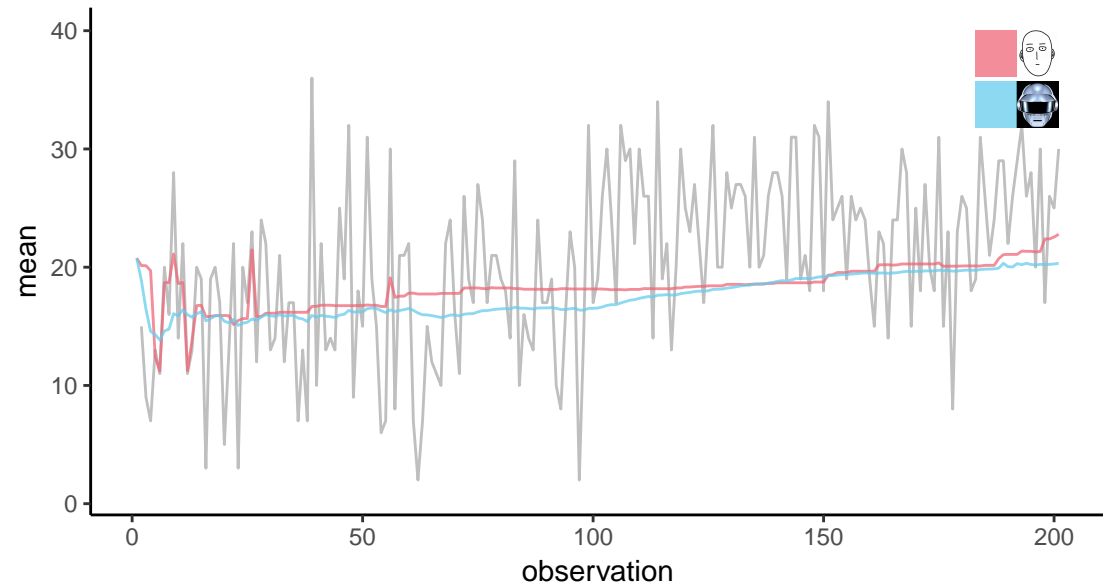
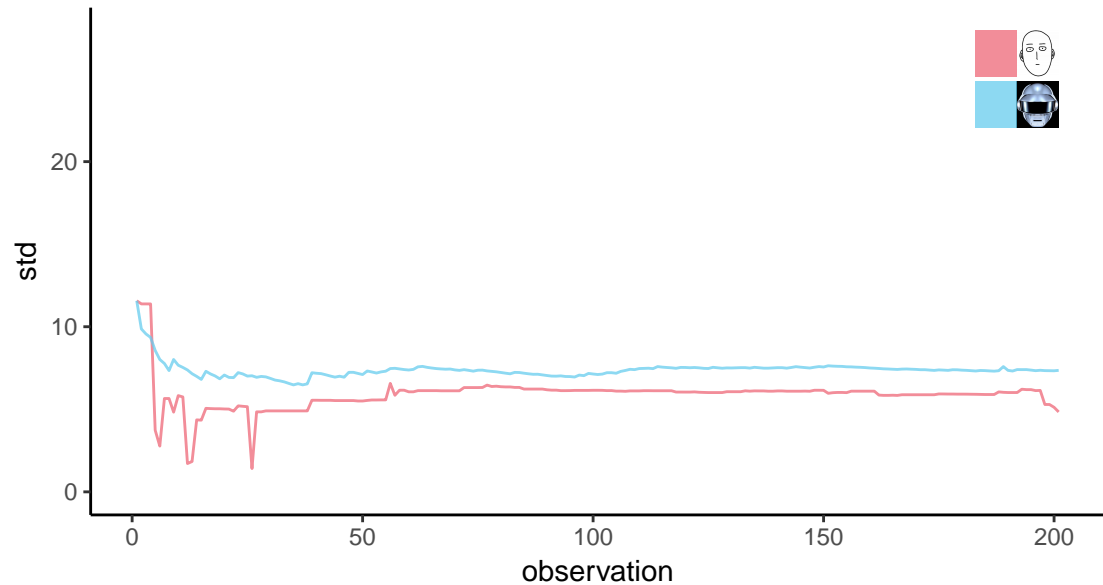


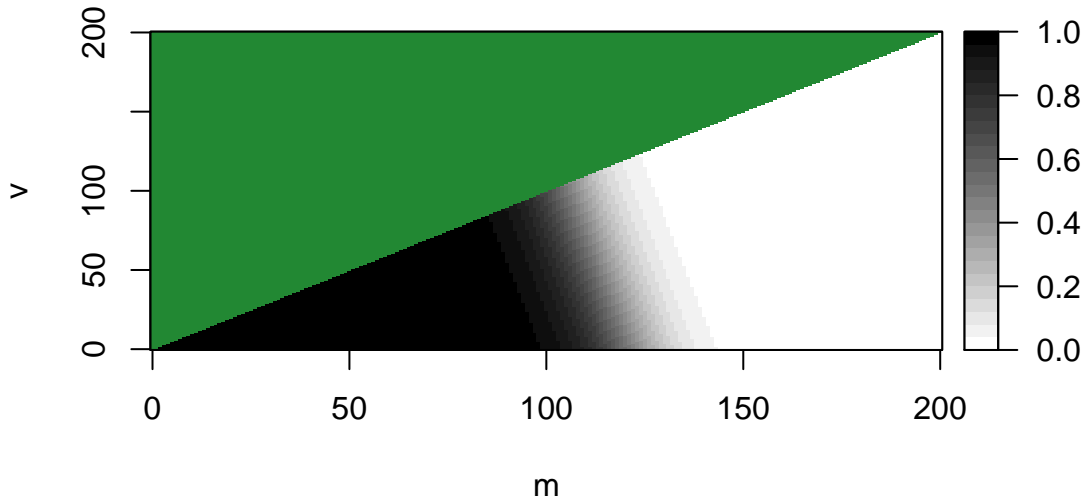
participant #1, means (black: plinko outcomes)



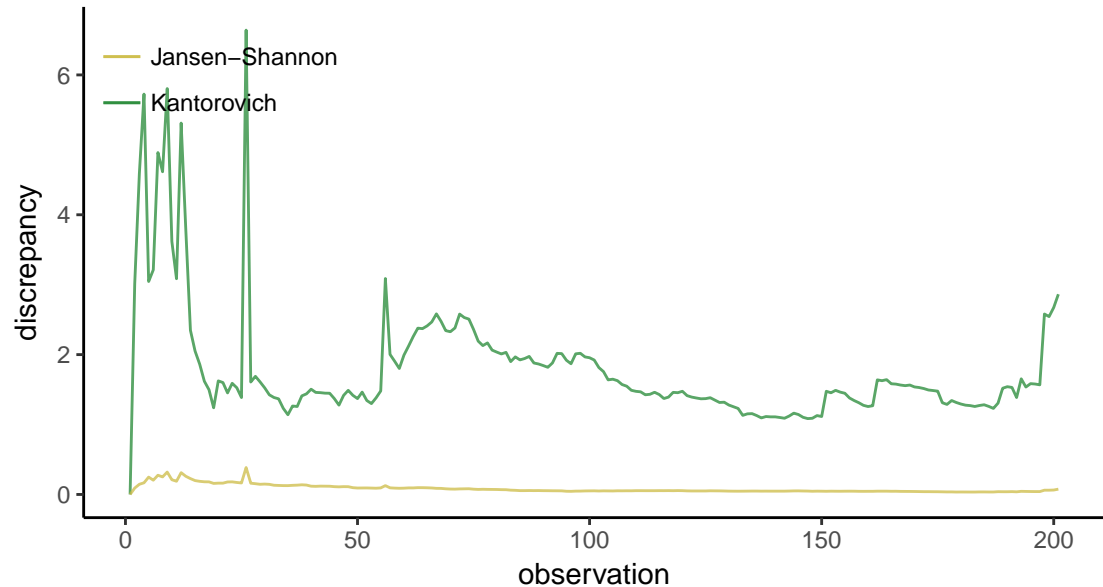
participant #1, st. deviations



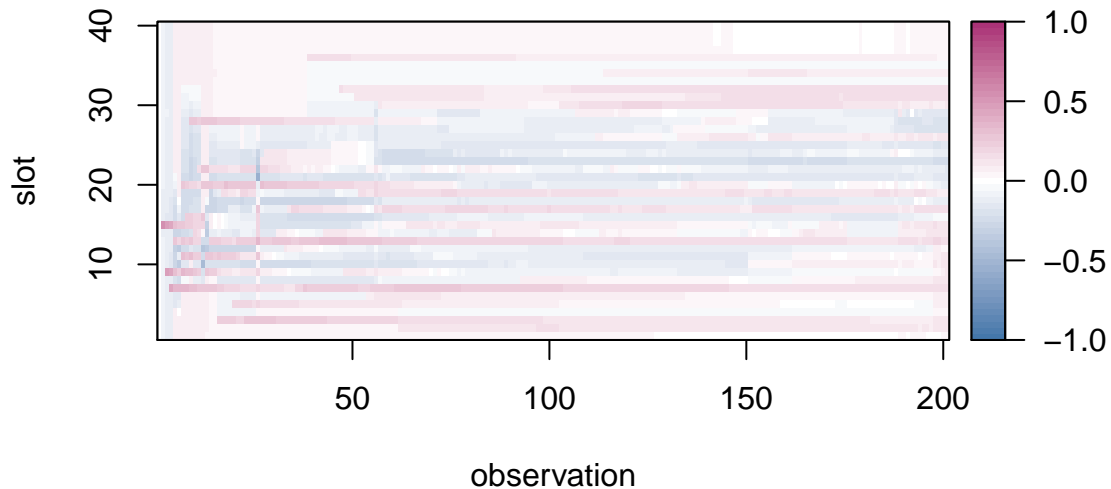
part. #1, stub. = 2.05, changepoint:



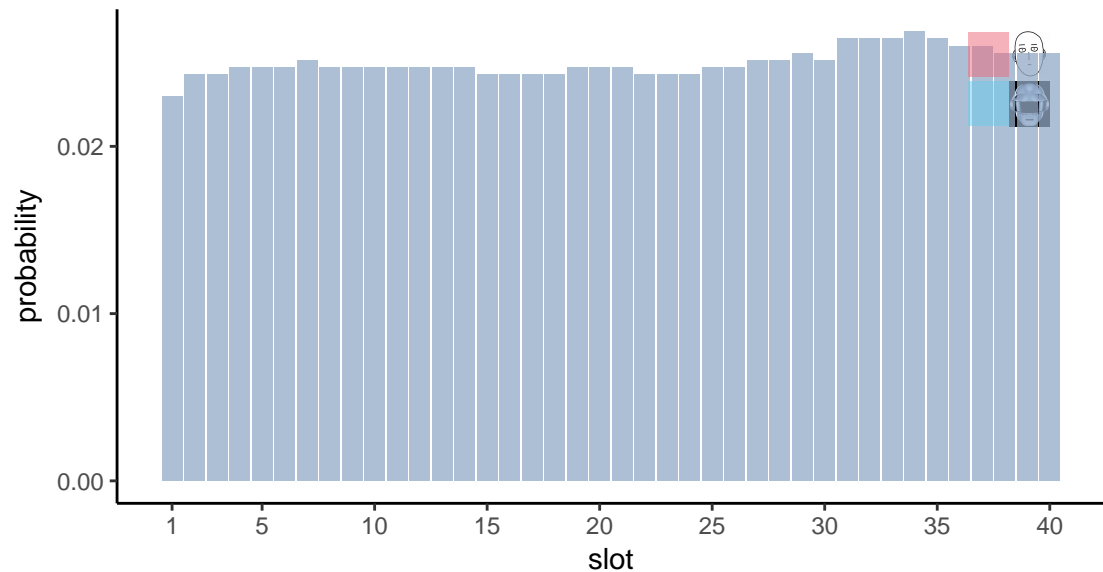
participant #1



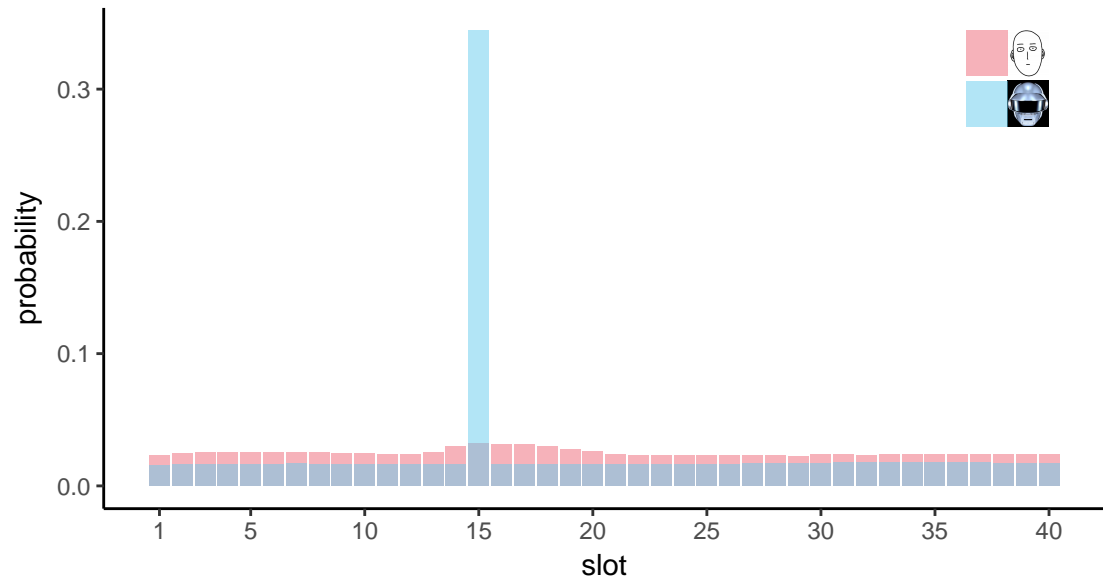
participant #1, $\sqrt{\text{robot-participant}}$



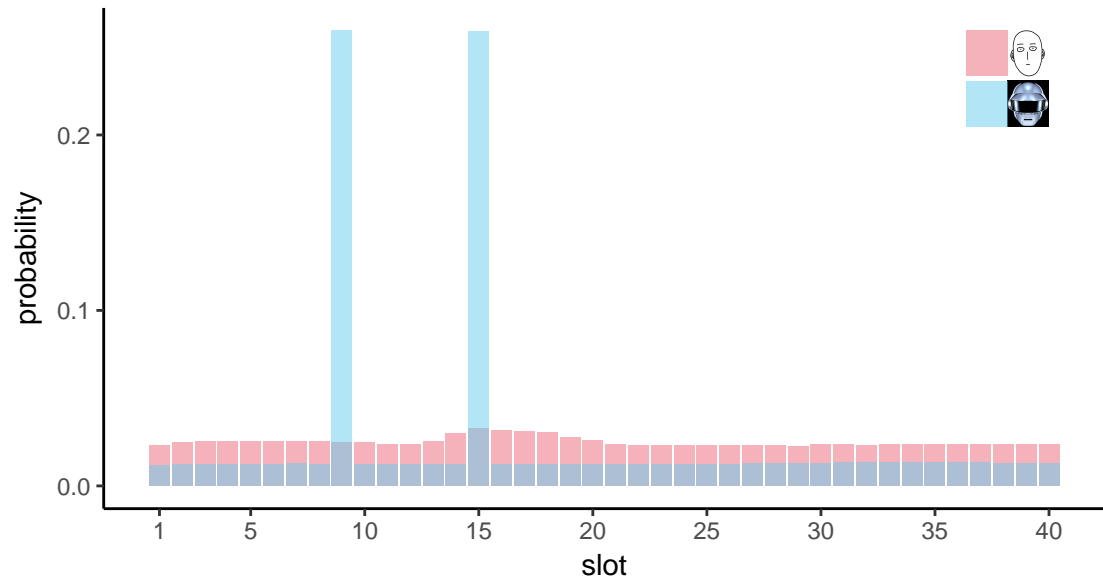
participant #1, observation 1, KM = 0, JS = 0



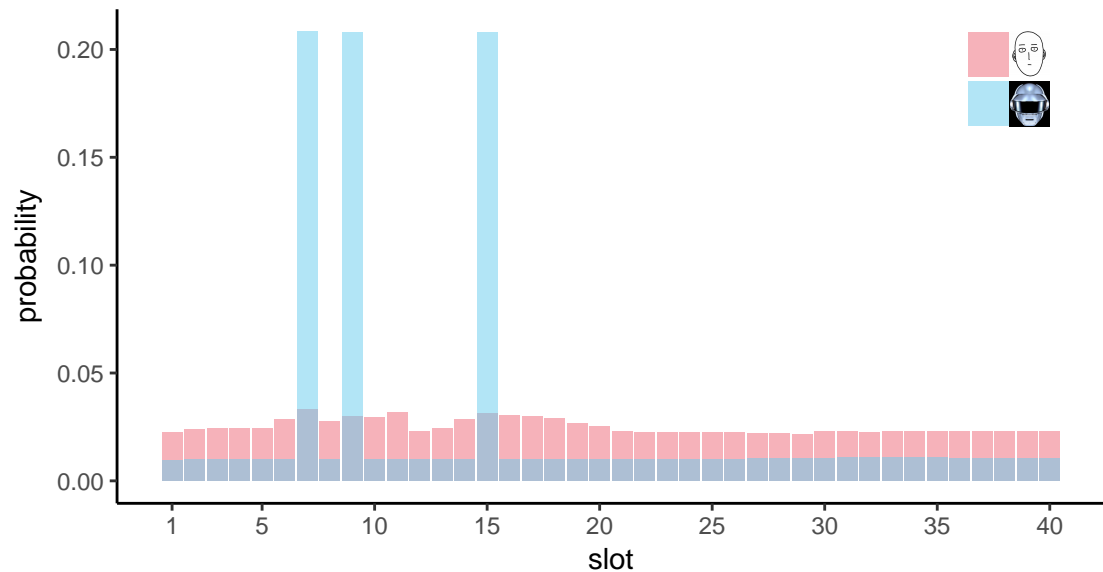
participant #1, observation 2, KM = 3, JS = 0.091



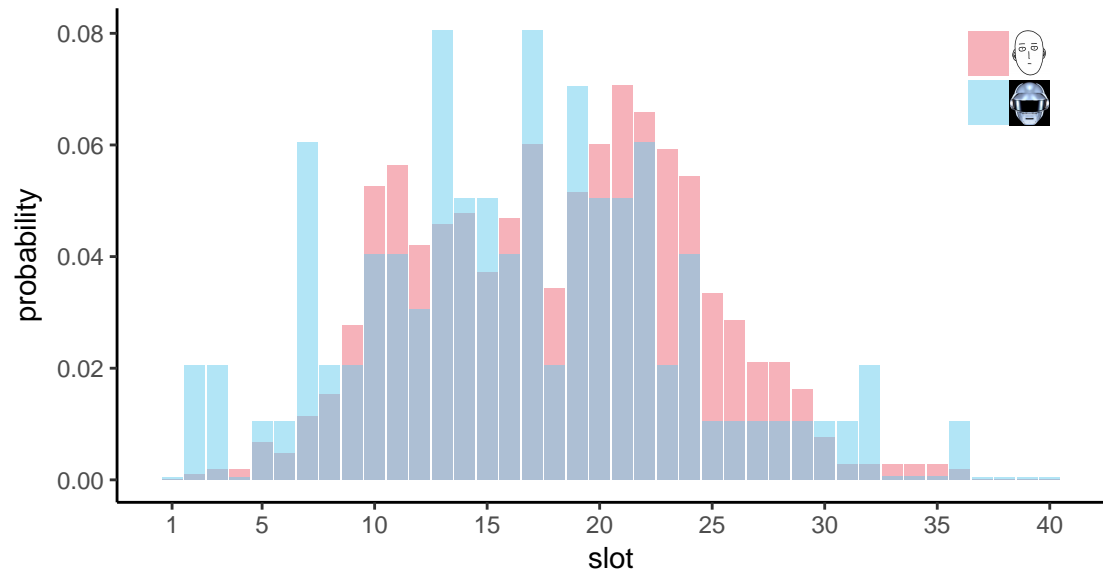
participant #1, observation 3, KM = 4.6, JS = 0.15



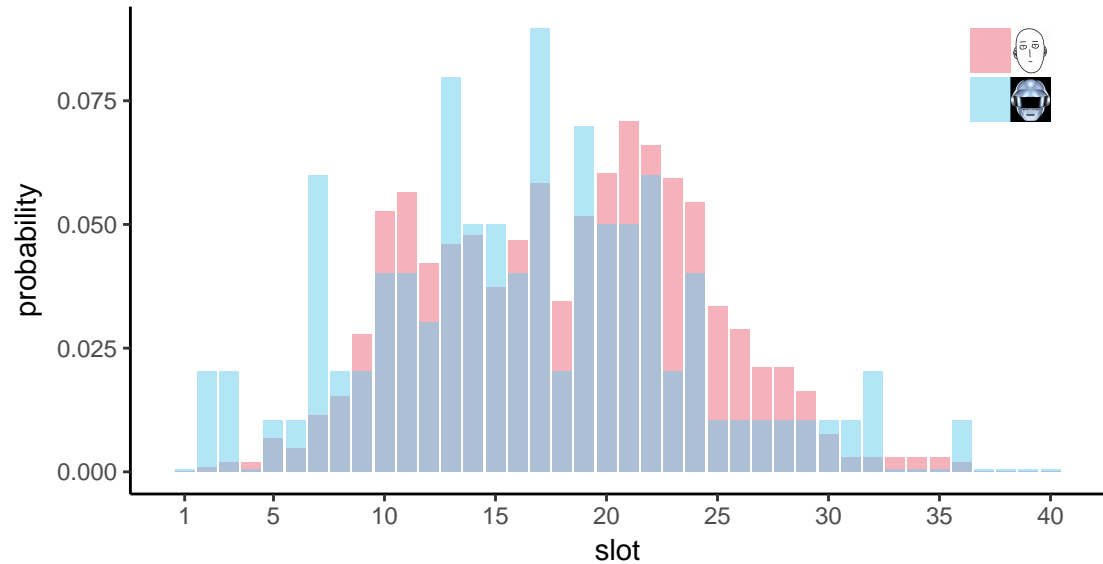
participant #1, observation 4, KM = 5.7, JS = 0.17



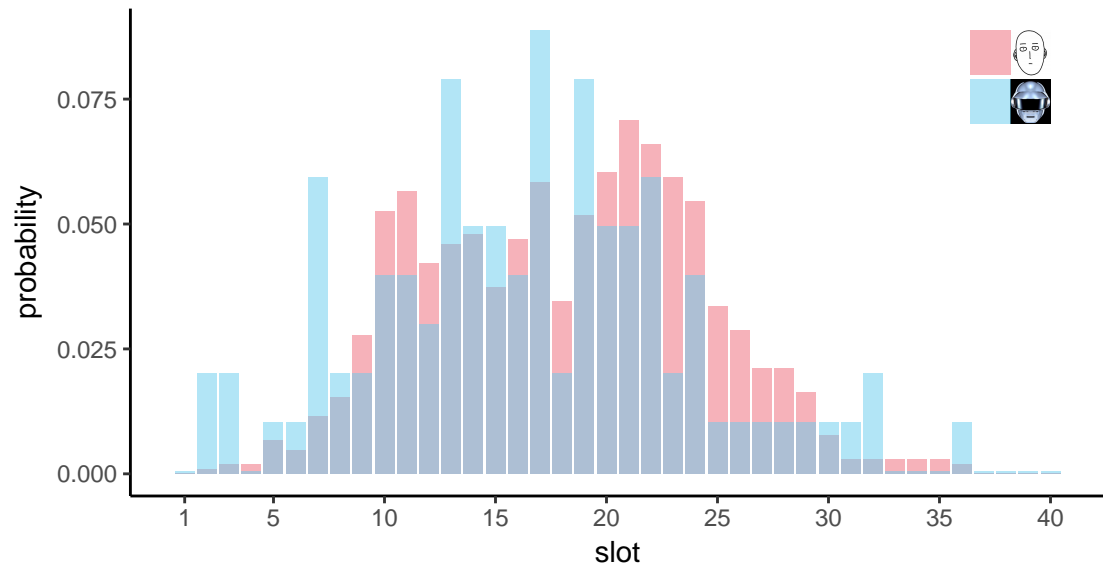
participant #1, observation 99, KM = 2, JS = 0.05



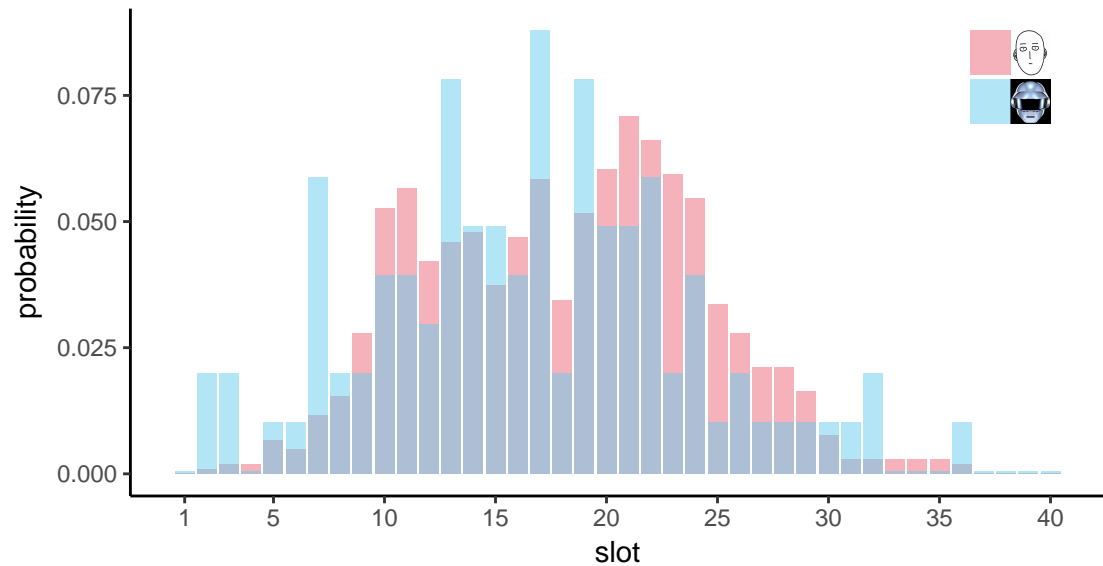
participant #1, observation 100, KM = 2, JS = 0.051



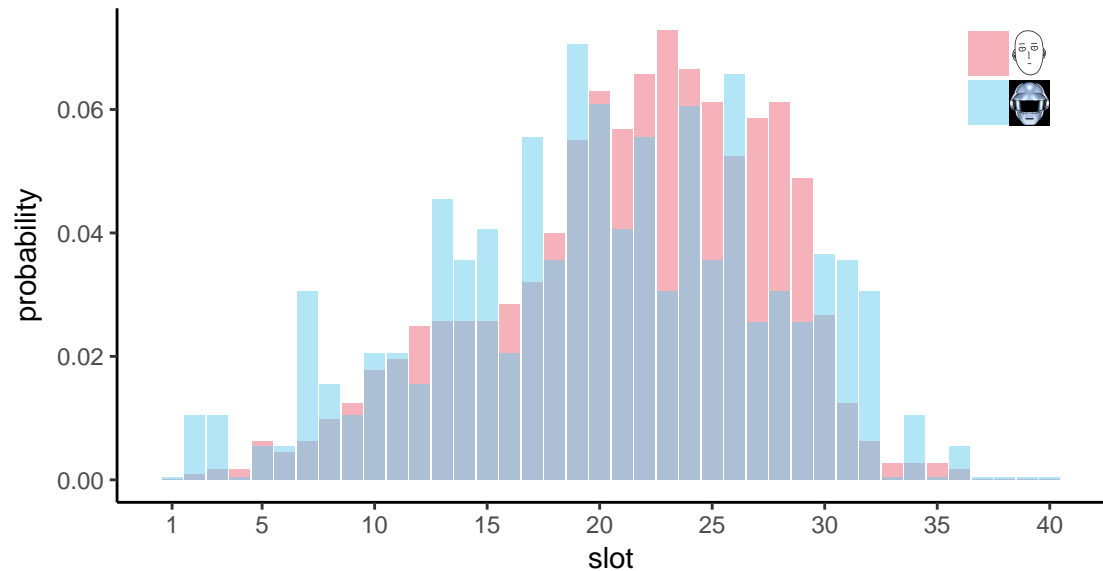
participant #1, observation 101, KM = 1.9, JS = 0.052



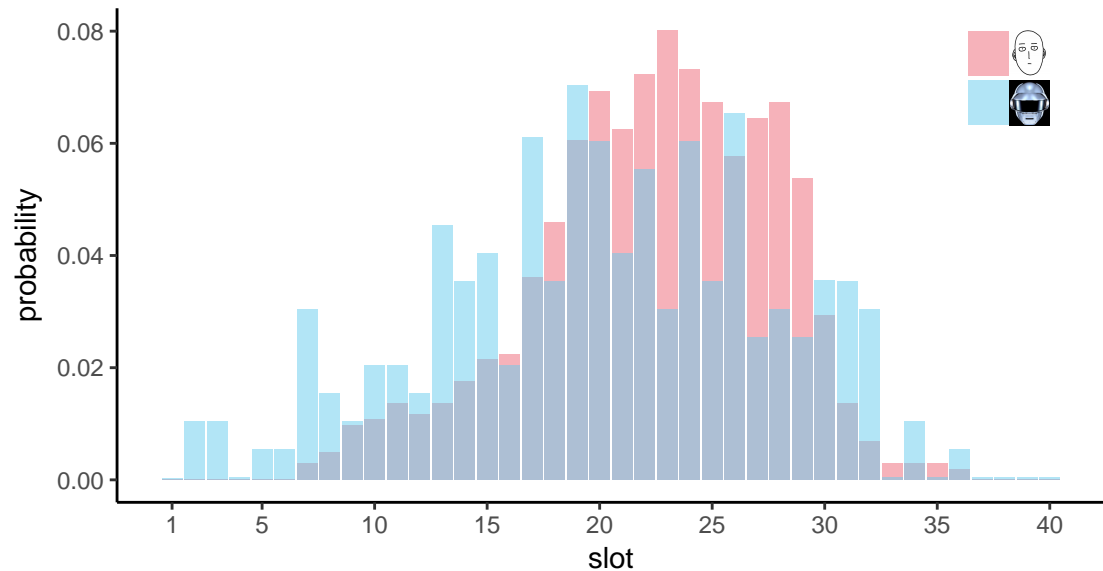
participant #1, observation 102, KM = 1.8, JS = 0.05



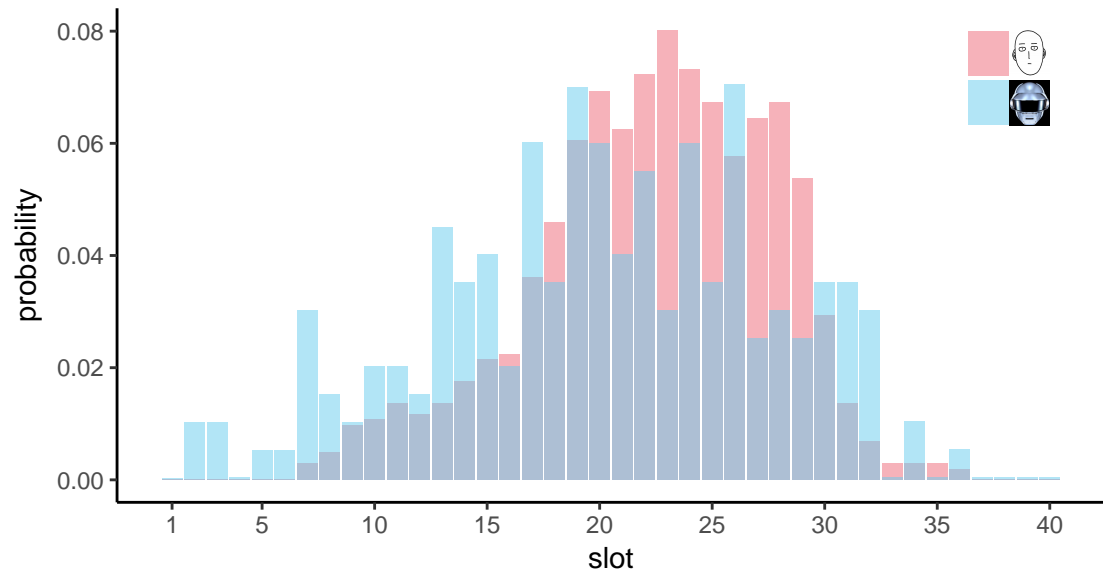
participant #1, observation 197, KM = 1.6, JS = 0.041



participant #1, observation 198, KM = 2.6, JS = 0.061



participant #1, observation 199, KM = 2.5, JS = 0.061



participant #1, observation 200, KM = 2.7, JS = 0.063

