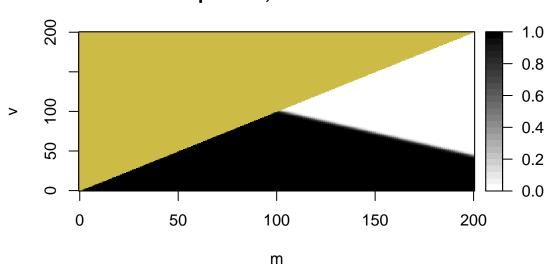
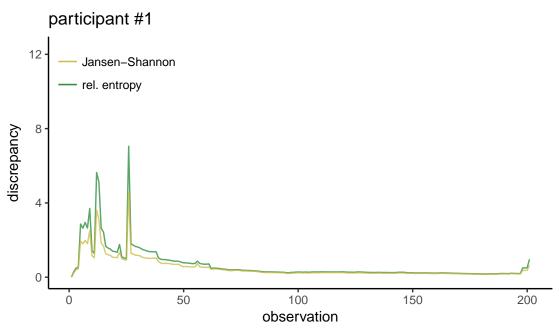


h for part. #1, stubbornness = 3.6





participant #1, sqrt(robot-participant)

