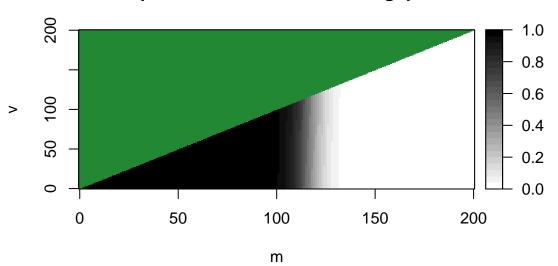
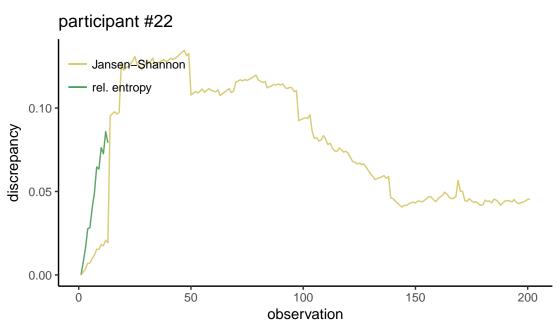
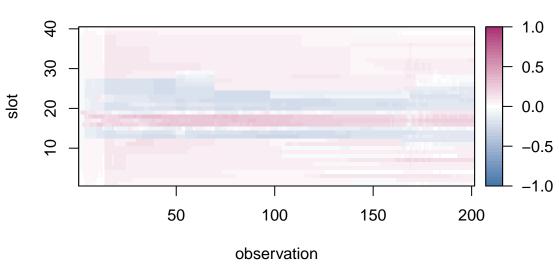


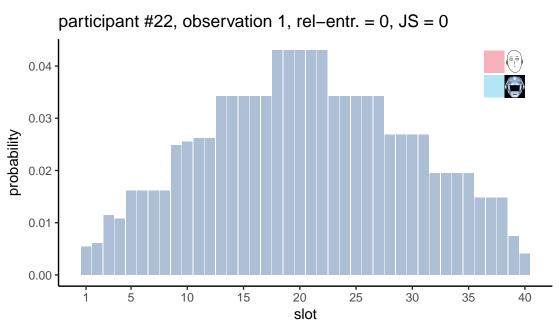
part. #22, stub. = 33.9, changepoint:



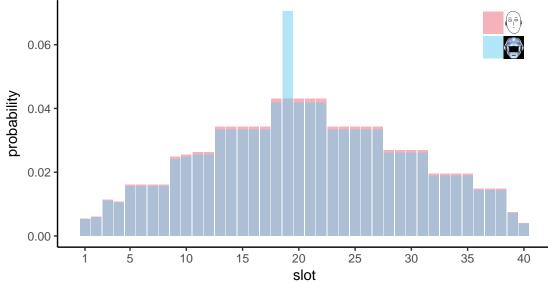


participant #22, sqrt(robot-participant)

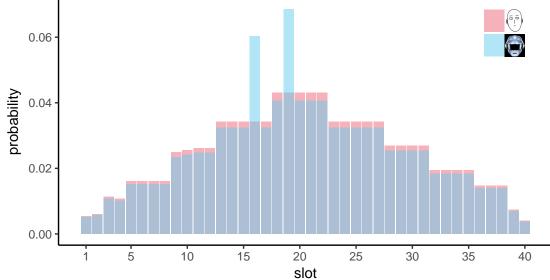




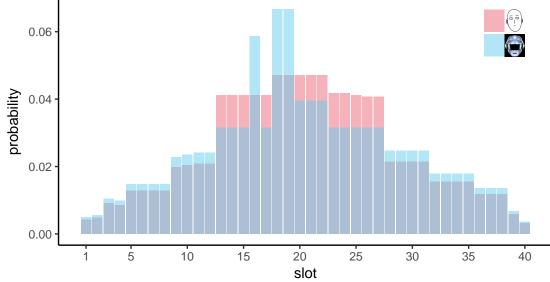
participant #22, observation 2, rel-entr. = 0.0077, JS = 0.0018



participant #22, observation 3, rel-entr. = 0.016, JS = 0.0036



participant #22, observation 4, rel-entr. = 0.028, JS = 0.0069



participant #22, observation 99, rel-entr. = 1.5, JS = 0.093 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #22, observation 100, rel-entr. = 1.5, JS = 0.094 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #22, observation 101, rel-entr. = 1.5, JS = 0.094 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #22, observation 102, rel-entr. = 1.5, JS = 0.094 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #22, observation 197, rel-entr. = 0.2, JS = 0.043 0.10 probability 0.00 slot

participant #22, observation 198, rel-entr. = 0.2, JS = 0.044 0.10 probability 0.00 slot

participant #22, observation 199, rel-entr. = 0.2, JS = 0.044 0.10 probability 0.00 slot

participant #22, observation 200, rel-entr. = 0.2, JS = 0.045 0.10 probability 0.00 slot