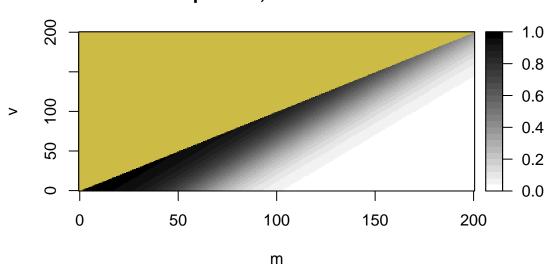
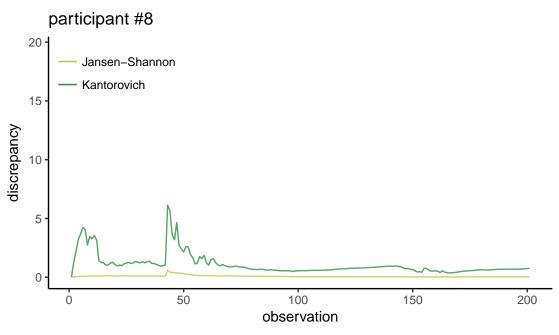


h for part. #8, stubbornness = 7.46





participant #8, sqrt(robot-participant)

