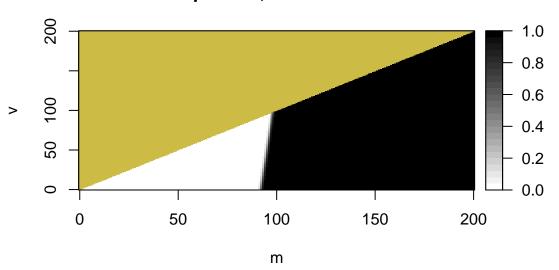
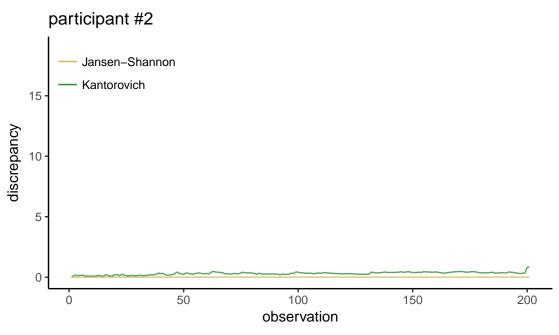


## h for part. #2, stubbornness = 71.5





## participant #2, sqrt(robot-participant)

