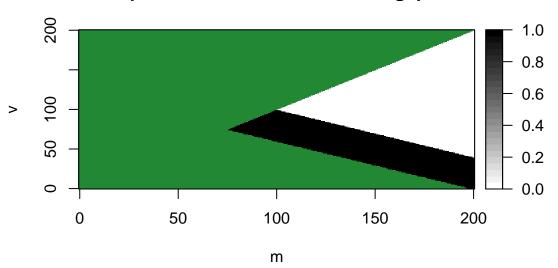
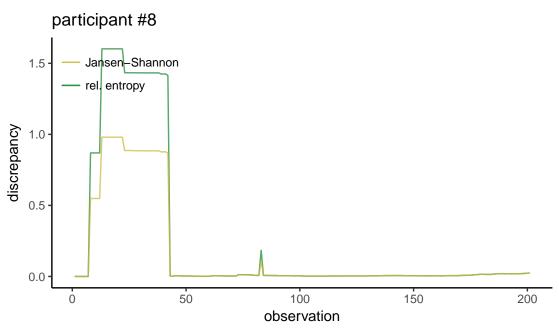
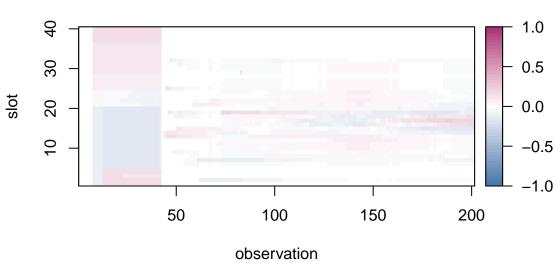


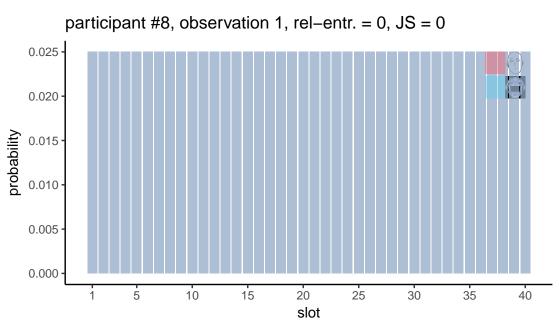
## **part.** #8, **stub.** = **0.00275**, **changepoint**:



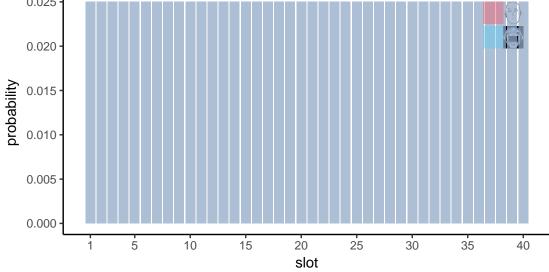


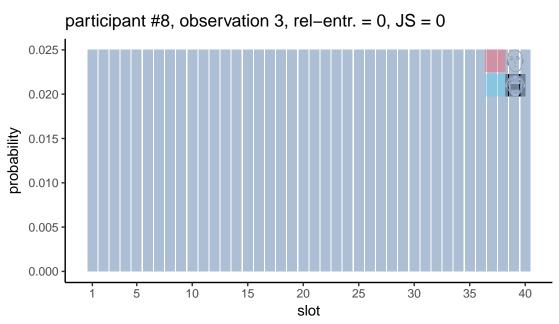
## participant #8, sqrt(robot-participant)



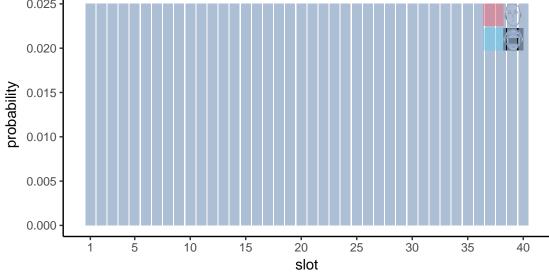


participant #8, observation 2, rel-entr. = 2.2e-16, JS = 5.6e-17

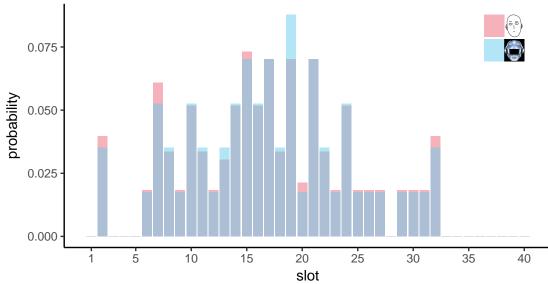




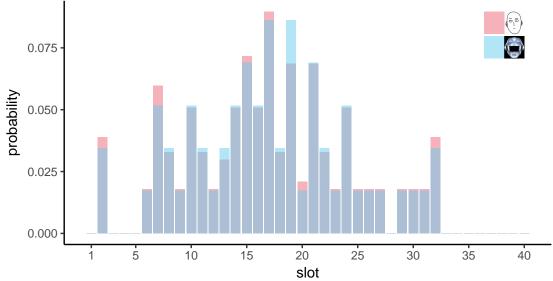
participant #8, observation 4, rel-entr. = 2.2e-16, JS = 5.6e-17



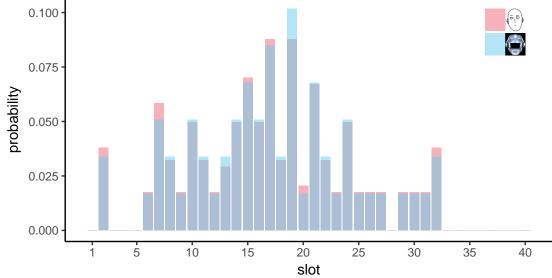
participant #8, observation 99, rel-entr. = 0.0043, JS = 0.0043



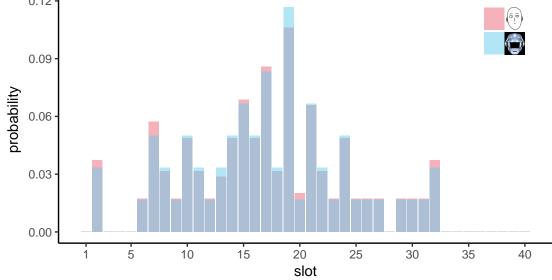
participant #8, observation 100, rel-entr. = 0.0043, JS = 0.0043



participant #8, observation 101, rel-entr. = 0.0032, JS = 0.0032



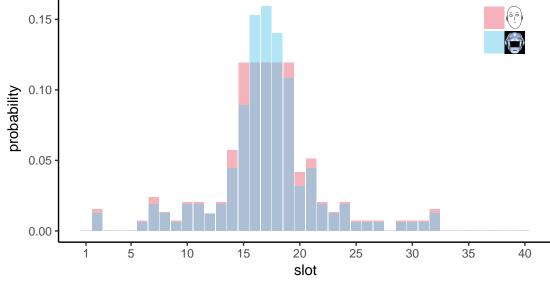
participant #8, observation 102, rel-entr. = 0.0026, JS = 0.0026



participant #8, observation 197, rel-entr. = 0.02, JS = 0.02 0.15 0.10 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #8, observation 198, rel-entr. = 0.02, JS = 0.02 0.15 probability 0.10 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #8, observation 199, rel-entr. = 0.022, JS = 0.022



participant #8, observation 200, rel-entr. = 0.023, JS = 0.023

