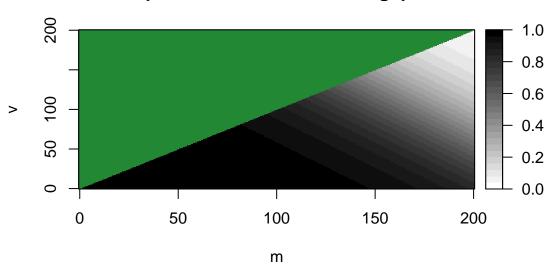
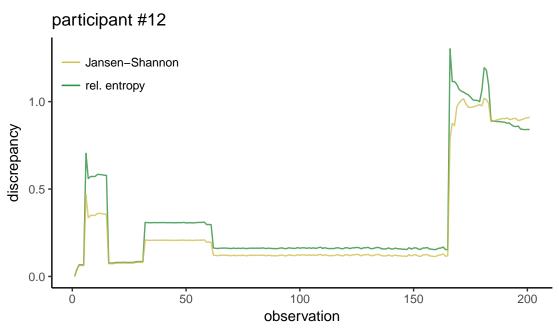
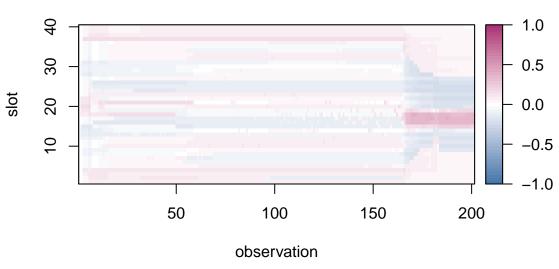


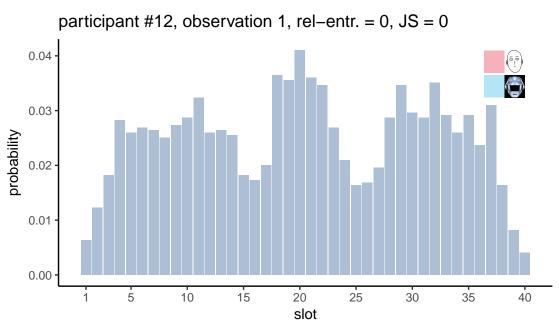
part. #12, stub. = 8.6, changepoint:



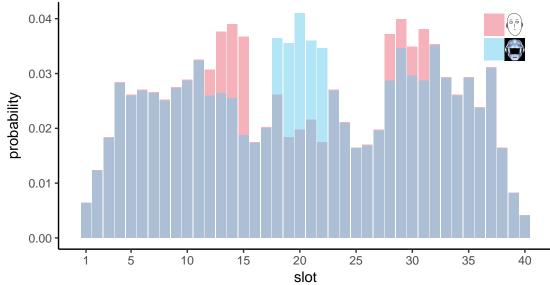


participant #12, sqrt(robot-participant)

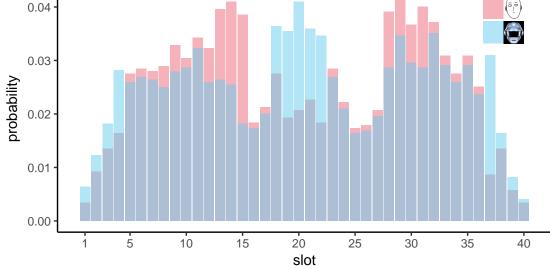




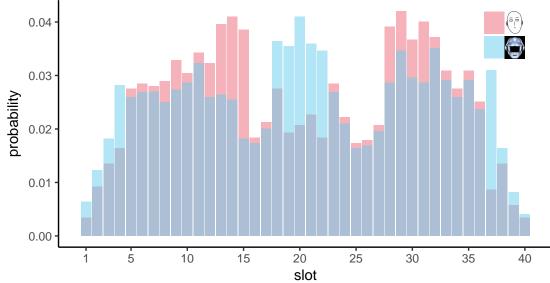
participant #12, observation 2, rel-entr. = 0.041, JS = 0.039



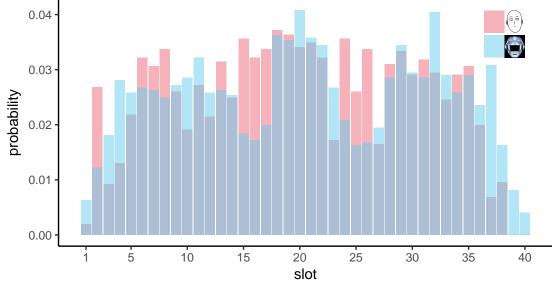
participant #12, observation 3, rel-entr. = 0.066, JS = 0.063 0.04



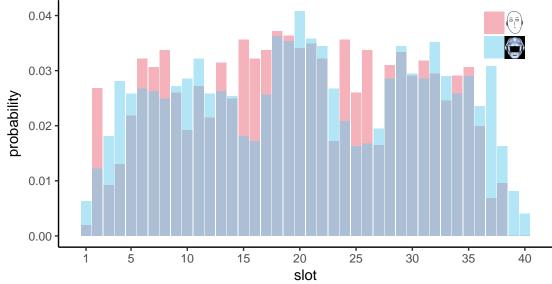
participant #12, observation 4, rel-entr. = 0.067, JS = 0.063



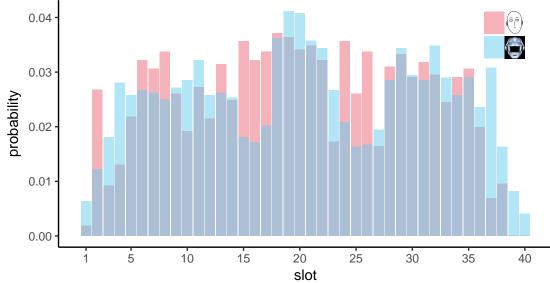
participant #12, observation 99, rel-entr. = 0.16, JS = 0.12



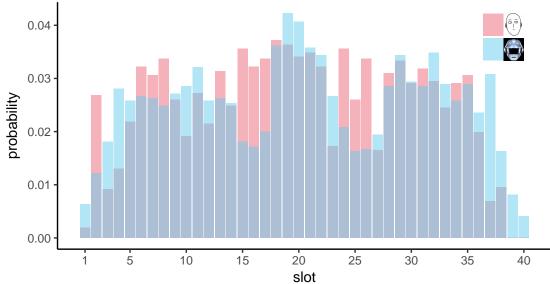
participant #12, observation 100, rel-entr. = 0.16, JS = 0.12



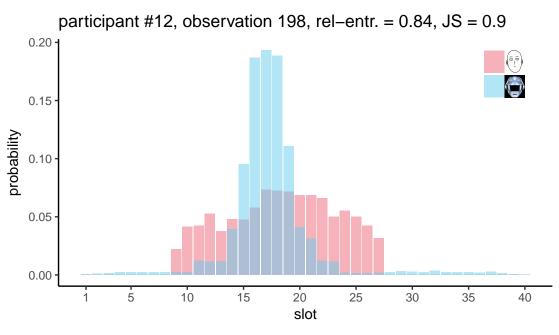
participant #12, observation 101, rel-entr. = 0.16, JS = 0.12



participant #12, observation 102, rel-entr. = 0.16, JS = 0.12



participant #12, observation 197, rel-entr. = 0.84, JS = 0.9 0.20 0.15 probability 0.05 0.00 10 15 25 5 20 30 35 40 slot



participant #12, observation 199, rel-entr. = 0.84, JS = 0.9 0.20 0.15 probability 0.05 0.00 10 15 25 5 20 30 35 40 slot

participant #12, observation 200, rel-entr. = 0.84, JS = 0.91 0.20 0.15 probability 0.05 0.00 10 15 25 5 20 30 35 40 slot