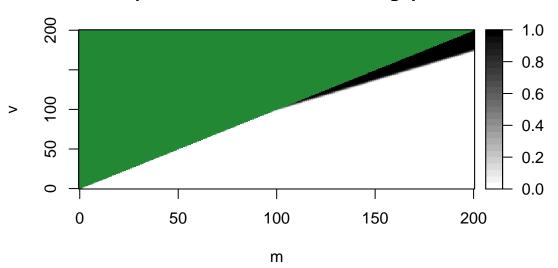
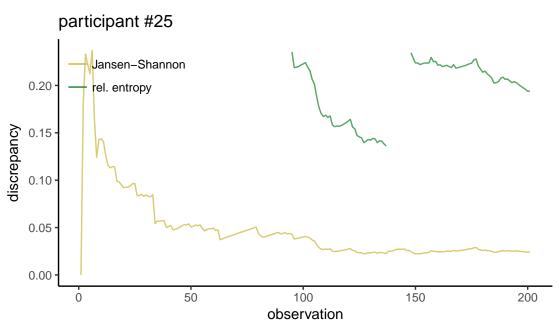
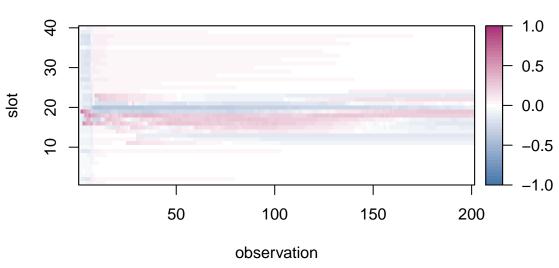


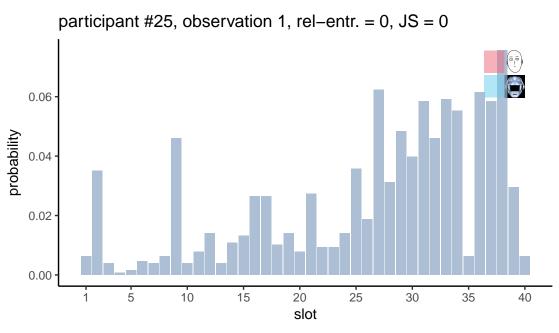
part. #25, stub. = 0.832, changepoint:

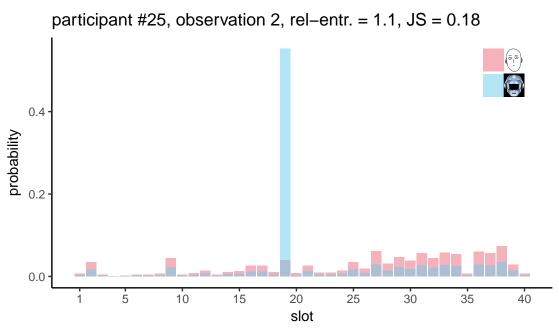




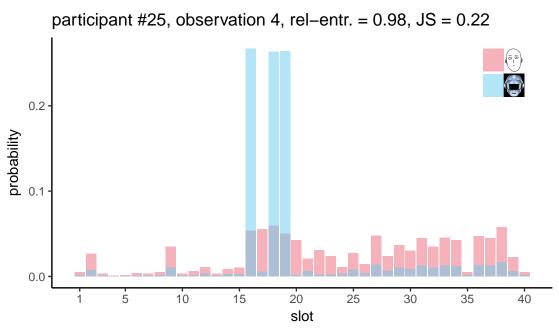
participant #25, sqrt(robot-participant)







participant #25, observation 3, rel-entr. = 1.2, JS = 0.23 0.3 probability 0.1 0.0 25 30 20 10 15 35 40 slot



participant #25, observation 99, rel-entr. = 0.22, JS = 0.04 0.20 0.15 probability 0.10 0.05 0.00 15 25 30 35 5 10 20 40 slot

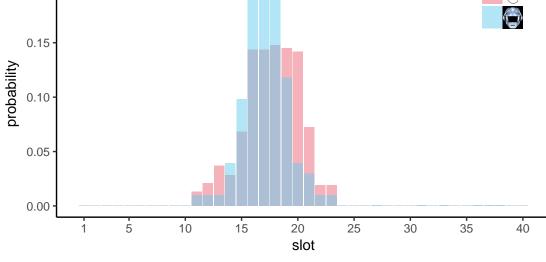
participant #25, observation 100, rel-entr. = 0.22, JS = 0.04 0.20 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40

slot

participant #25, observation 101, rel-entr. = 0.22, JS = 0.041 0.20 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40

slot

participant #25, observation 102, rel-entr. = 0.22, JS = 0.04 0.20 0.15 probability



participant #25, observation 197, rel-entr. = 0.2, JS = 0.025 0.20 0.15 probability 0.10 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #25, observation 198, rel-entr. = 0.2, JS = 0.025 0.20 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #25, observation 199, rel-entr. = 0.2, JS = 0.024 0.20 0.15 probability 0.10 0.05

20

slot

25

30

35

40

15

10

0.00

5

participant #25, observation 200, rel-entr. = 0.19, JS = 0.024 0.20 0.15

