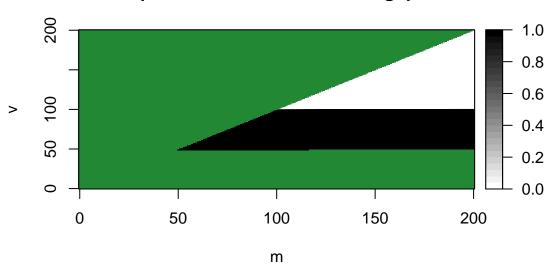
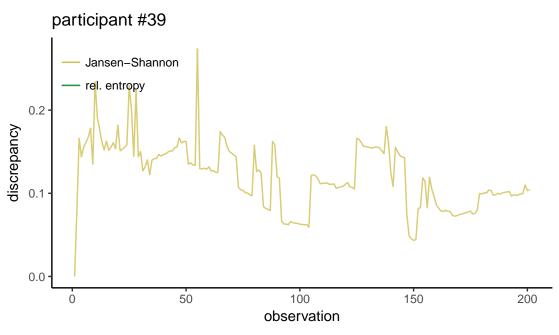
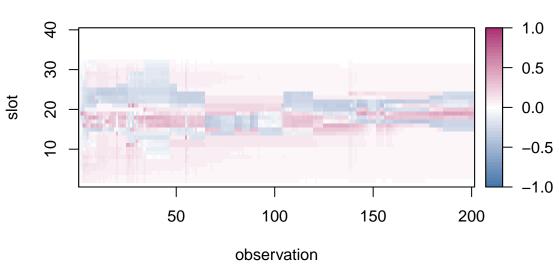


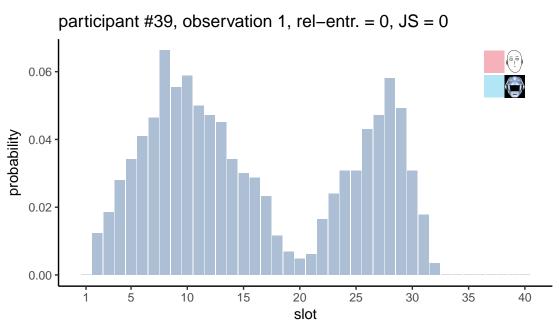
part. #39, stub. = 2.36, changepoint:

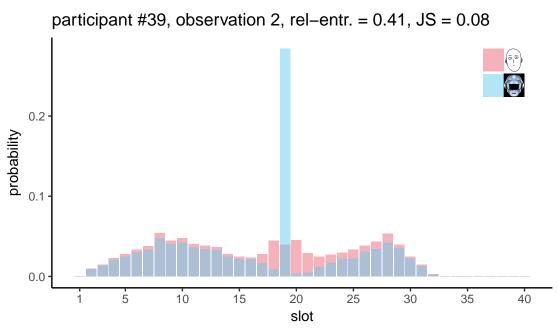


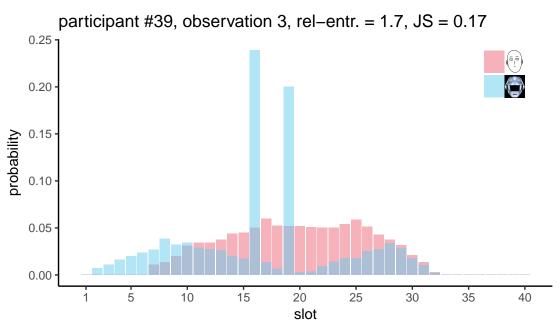


participant #39, sqrt(robot-participant)



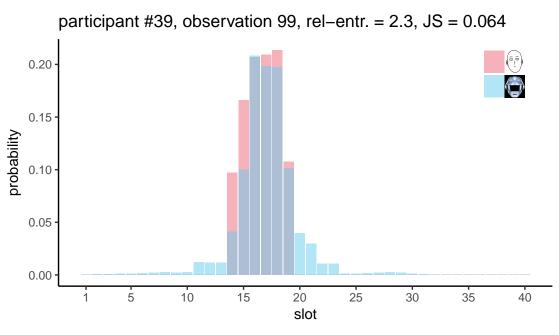






participant #39, observation 4, rel-entr. = 1.5, JS = 0.14 0.20 0.15 probability 0.10 0.05 0.00 15 25 30 35 5 10 20 40

slot

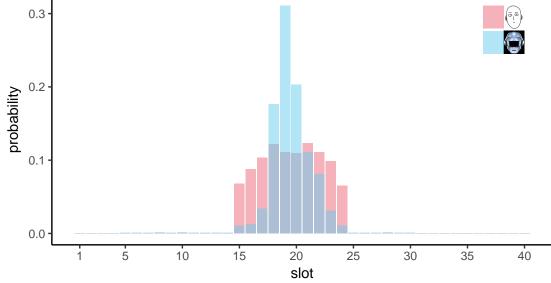


participant #39, observation 100, rel-entr. = 2.2, JS = 0.063 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #39, observation 101, rel-entr. = 2.2, JS = 0.063 0.20 0.15 probability 0.05 0.00 10 15 25 35 5 20 30 40 slot

participant #39, observation 102, rel-entr. = 2.2, JS = 0.062 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #39, observation 197, rel-entr. = 0.58, JS = 0.099



participant #39, observation 198, rel-entr. = 0.58, JS = 0.1 0.3 probability 0.1 0.0 10 25 15 20 30 . 40 35 slot

participant #39, observation 199, rel-entr. = 0.61, JS = 0.11 0.3 probability 0.1

10

15

20

slot

25

30

35

. 40

0.0

participant #39, observation 200, rel-entr. = 0.59, JS = 0.1 0.3 -0.2

