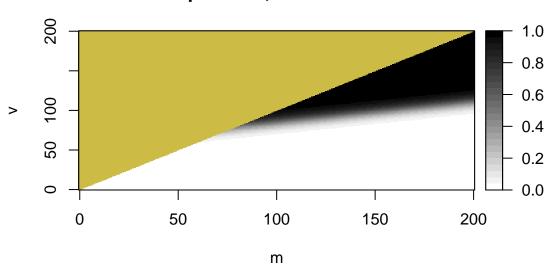
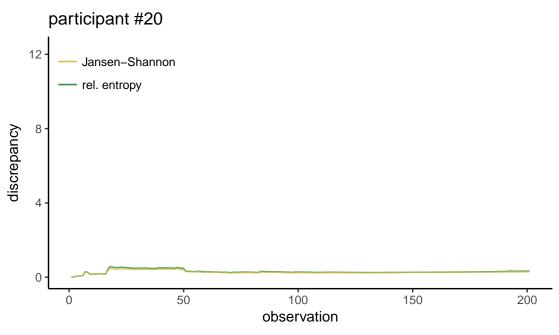
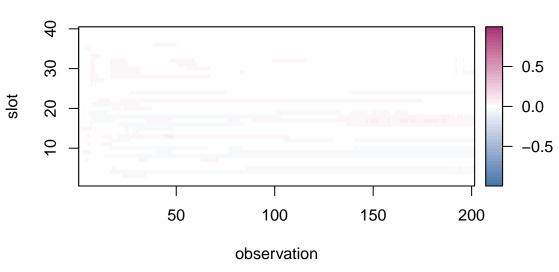


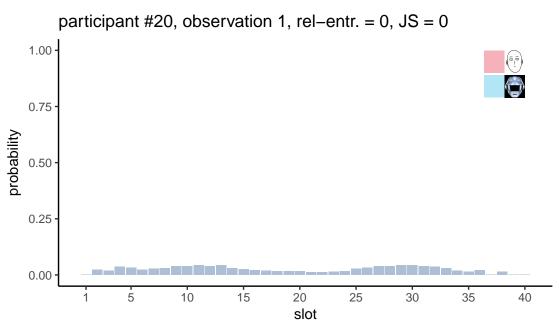
h for part. #20, stubbornness = 27.3





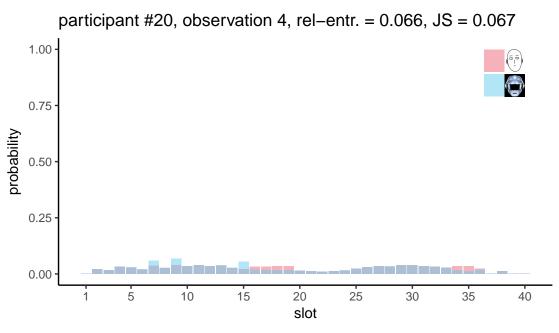
participant #20, sqrt(robot-participant)

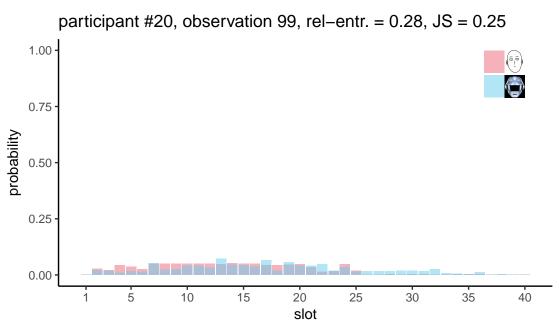




participant #20, observation 2, rel-entr. = 0.018, JS = 0.016 1.00 0.75 probability 0.25 0.00 15 5 10 25 30 35 20 40 slot

participant #20, observation 3, rel-entr. = 0.049, JS = 0.048 1.00 0.75 probability 0.25 0.00 15 25 5 10 30 35 20 40 slot





participant #20, observation 100, rel-entr. = 0.28, JS = 0.25 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 30 35 40 slot

participant #20, observation 101, rel-entr. = 0.28, JS = 0.25 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 30 35 40 slot

participant #20, observation 102, rel-entr. = 0.28, JS = 0.25 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 30 35 40 slot

participant #20, observation 197, rel-entr. = 0.33, JS = 0.29 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 35 30 40 slot

participant #20, observation 198, rel-entr. = 0.33, JS = 0.29 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 35 30 40 slot

participant #20, observation 199, rel-entr. = 0.33, JS = 0.29 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 35 30 40 slot

participant #20, observation 200, rel-entr. = 0.33, JS = 0.29 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 35 30 40 slot