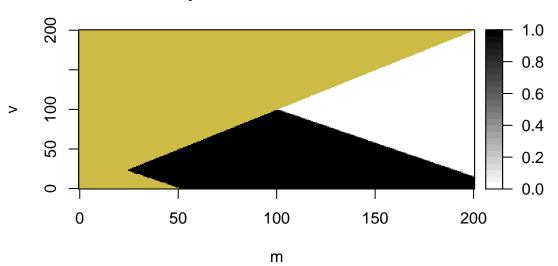
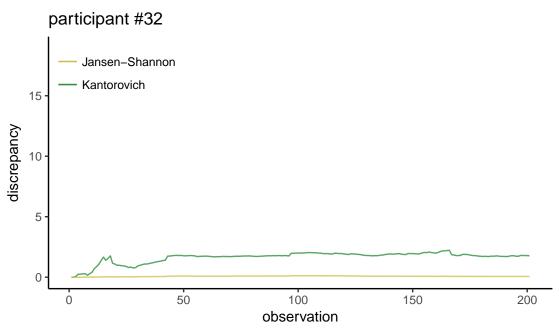


## h for part. #32, stubbornness = 19.6





## participant #32, sqrt(robot-participant)

