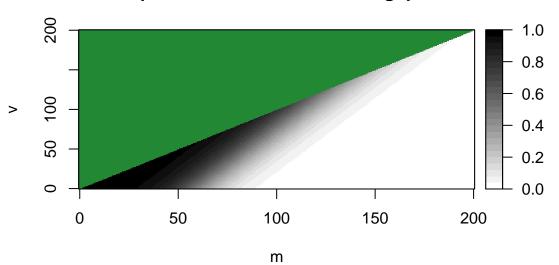
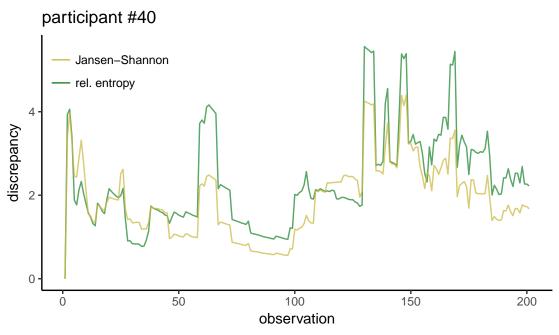
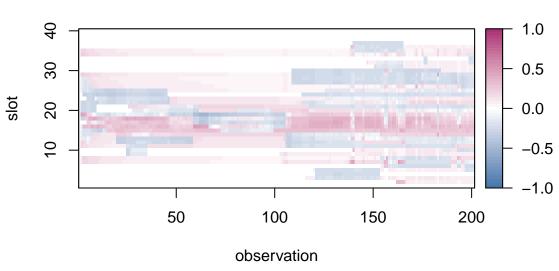


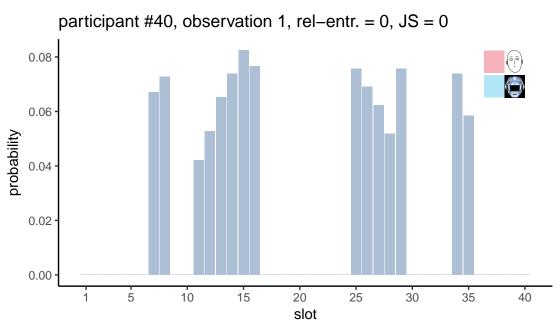
part. #40, stub. = 3.59, changepoint:



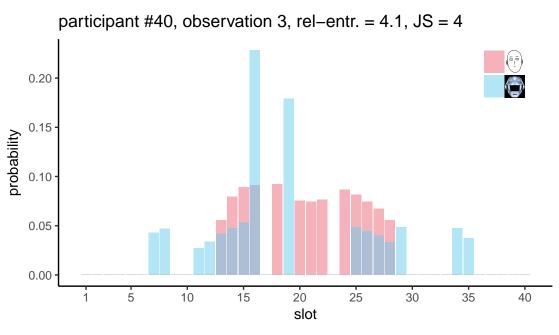


participant #40, sqrt(robot-participant)



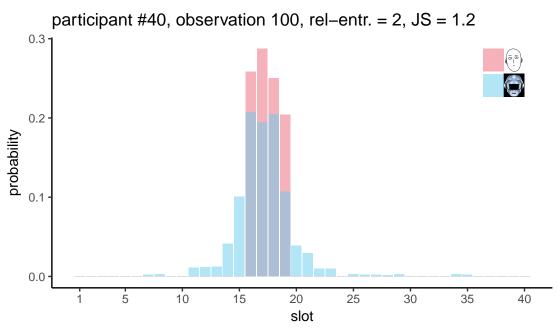


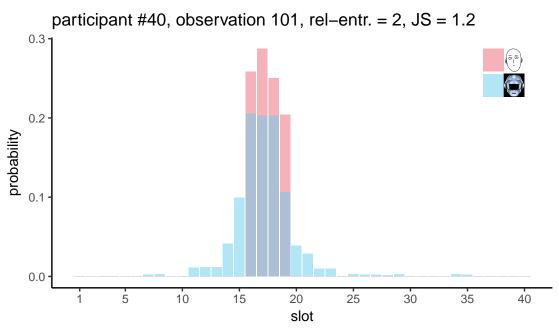
participant #40, observation 2, rel-entr. = 3.9, JS = 3.4 0.20 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot



participant #40, observation 4, rel-entr. = 3.4, JS = 3.3 0.20 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

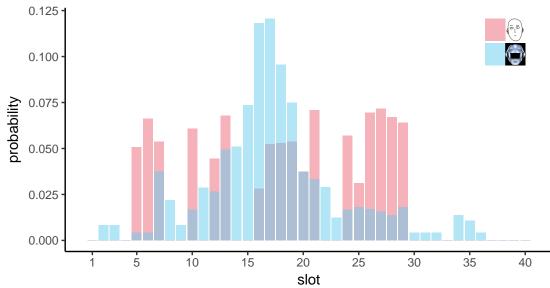
participant #40, observation 99, rel-entr. = 1.2, JS = 0.71 0.25 0.20 probability 0.15 0.05 0.00 10 15 25 30 5 20 35 40 slot





participant #40, observation 102, rel-entr. = 2.1, JS = 1.2 0.3 probability 0.0 10 20 30 15 25 35 40 slot

participant #40, observation 197, rel-entr. = 2.3, JS = 1.6



participant #40, observation 198, rel-entr. = 2.7, JS = 1.8 0.12 0.09 probability 0.06 0.03 0.00 15 25 30 5 10 20 35 40 slot

participant #40, observation 199, rel-entr. = 2.3, JS = 1.7 0.12 0.09 probability 0.06 0.03 0.00 15 25 30 5 10 20 35 40 slot

participant #40, observation 200, rel-entr. = 2.3, JS = 1.7 0.12 0.09 probability 0.06 0.03 0.00 15 25 30 5 10 20 35 40 slot