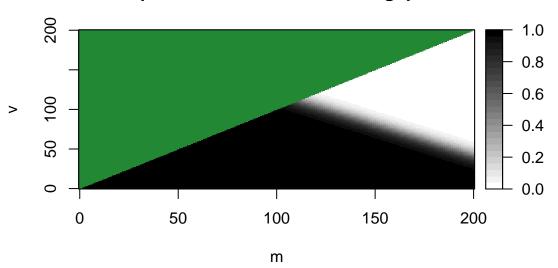
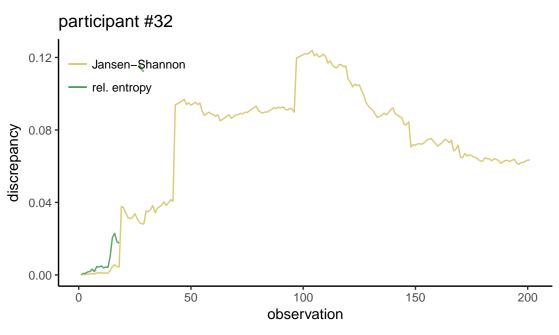
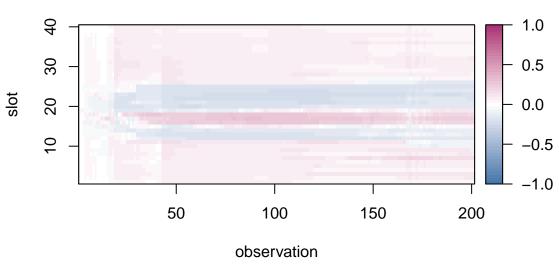


part. #32, stub. = 43.4, changepoint:



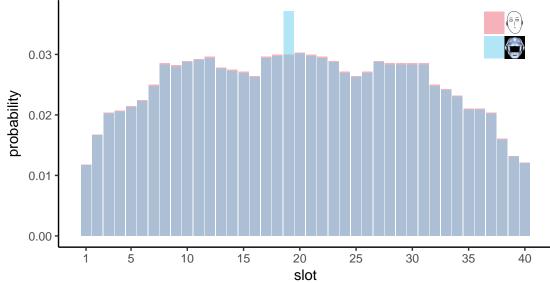


participant #32, sqrt(robot-participant)

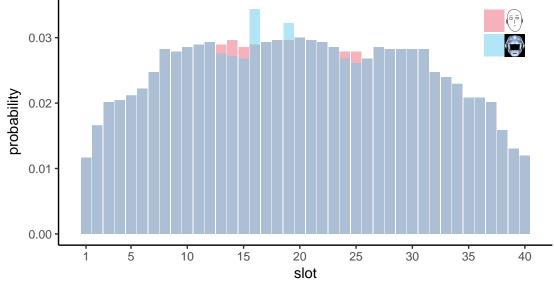


participant #32, observation 1, rel-entr. = 0, JS = 0 0.03 0.02 probability 0.01 0.00 15 25 30 5 10 20 35 40 slot

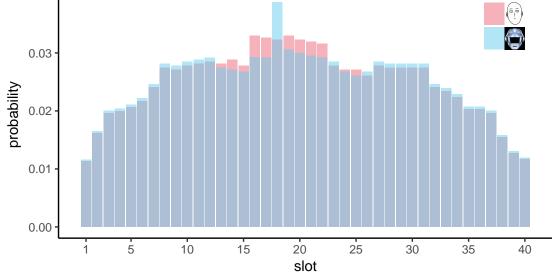
participant #32, observation 2, rel-entr. = 0.00082, JS = 2e-04



participant #32, observation 3, rel-entr. = 0.00086, JS = 0.00021

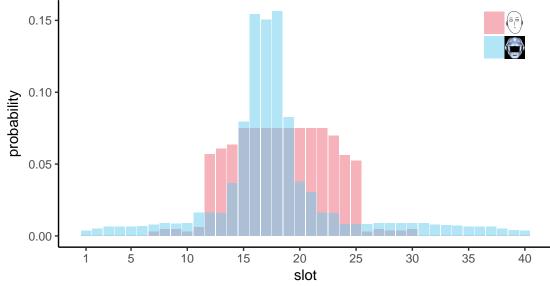


participant #32, observation 4, rel-entr. = 0.0017, JS = 0.00042 0.04 -

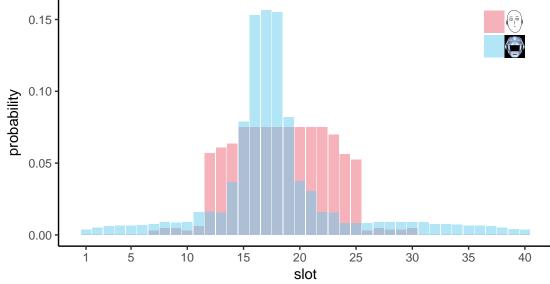


participant #32, observation 99, rel-entr. = 1.7, JS = 0.12 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

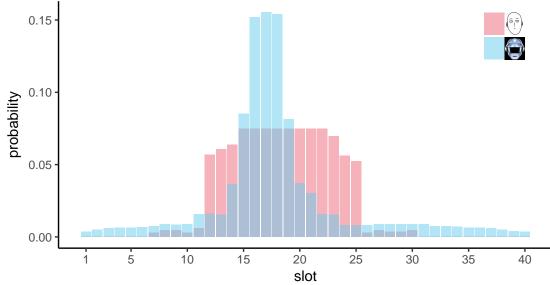
participant #32, observation 100, rel-entr. = 1.7, JS = 0.12



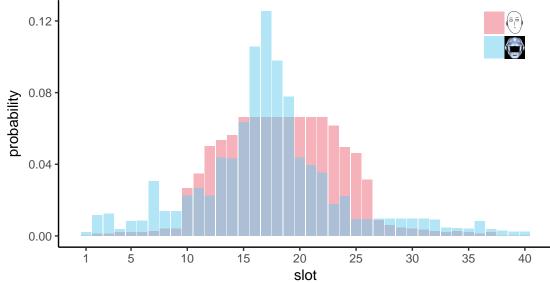
participant #32, observation 101, rel-entr. = 1.7, JS = 0.12



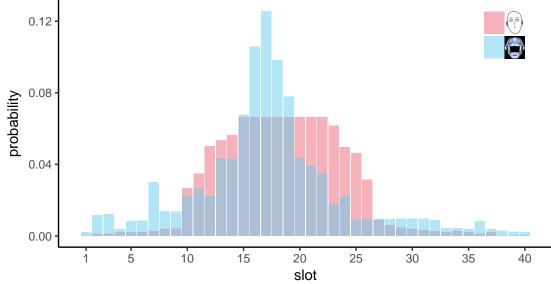
participant #32, observation 102, rel-entr. = 1.7, JS = 0.12



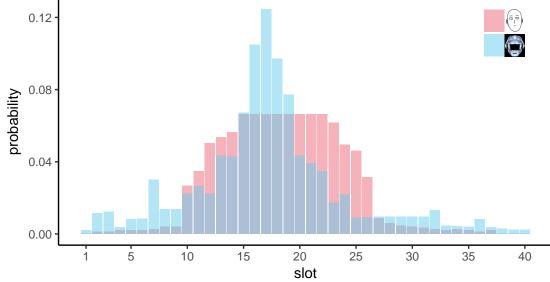
participant #32, observation 197, rel-entr. = 0.4, JS = 0.062



participant #32, observation 198, rel-entr. = 0.4, JS = 0.062



participant #32, observation 199, rel-entr. = 0.4, JS = 0.063



participant #32, observation 200, rel-entr. = 0.4, JS = 0.063 0.10 probability 0.00 slot