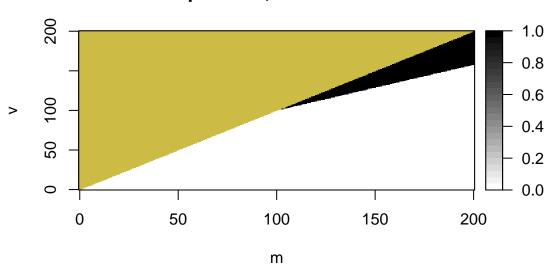
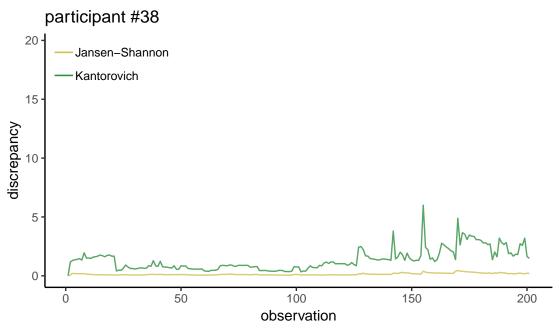


h for part. #38, stubbornness = 1.45





participant #38, sqrt(robot-participant)

