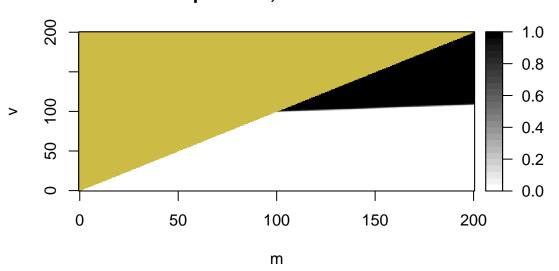
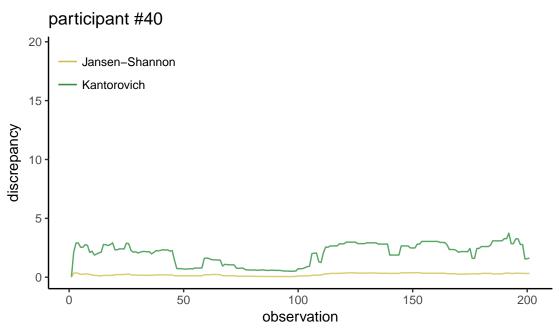


h for part. #40, stubbornness = 1.3





participant #40, sqrt(robot-participant)

