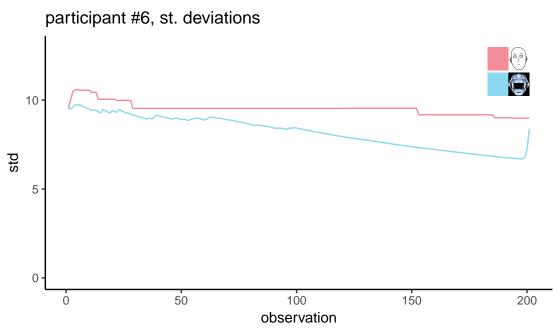
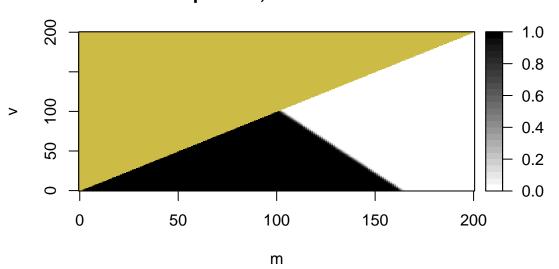
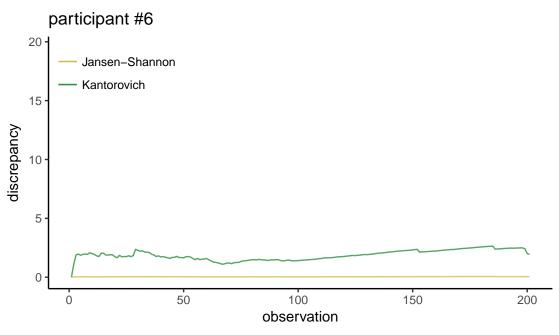


observation



h for part. #6, stubbornness = 47.1





participant #6, sqrt(robot-participant)

