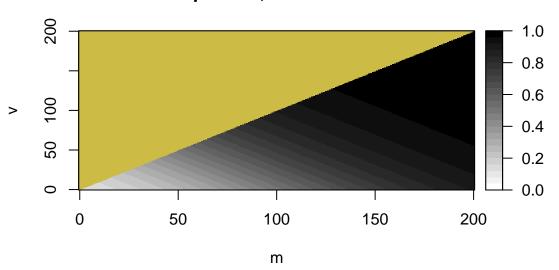
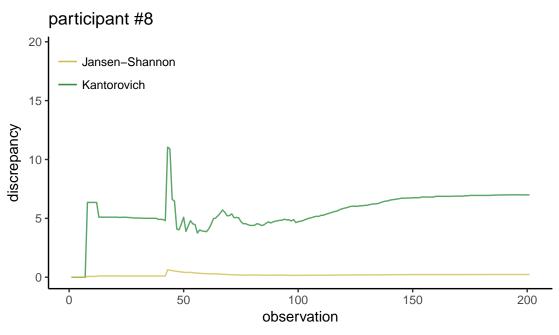


h for part. #8, stubbornness = 7.68





participant #8, sqrt(robot-participant)

