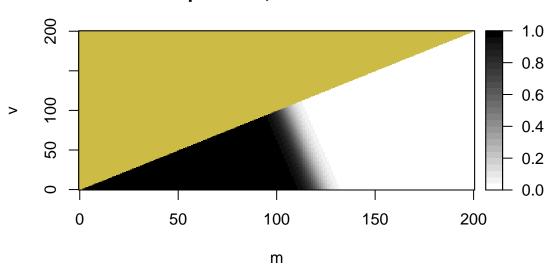
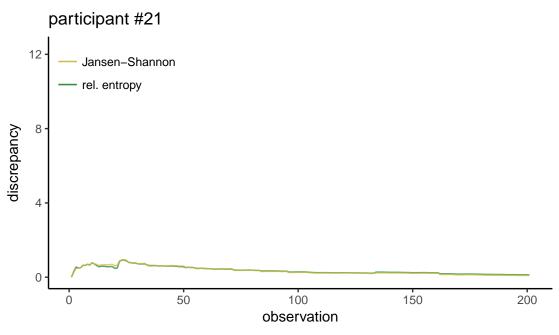
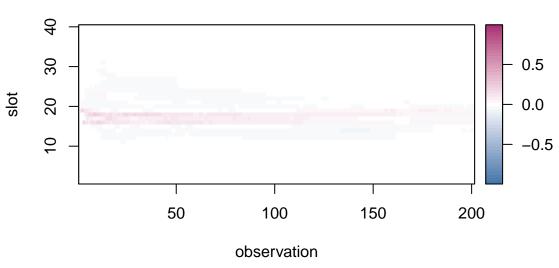


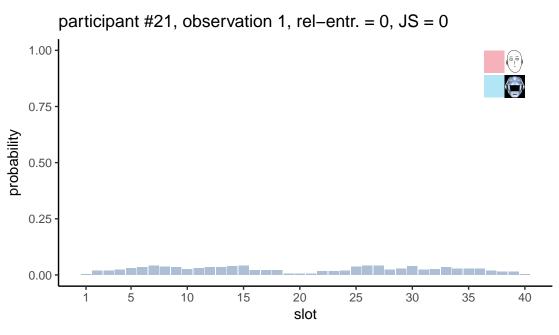
h for part. #21, stubbornness = 3.42





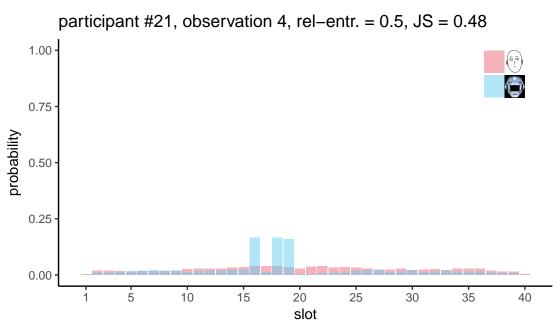
participant #21, sqrt(robot-participant)

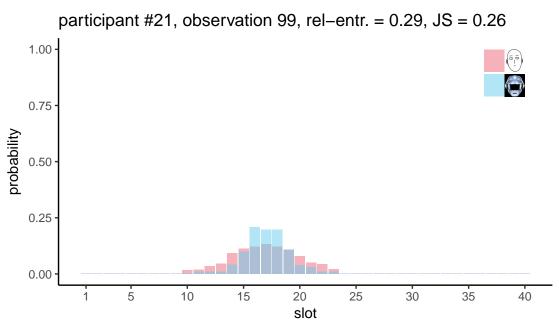




participant #21, observation 2, rel-entr. = 0.3, JS = 0.26 1.00 0.75 probability 0.25 0.00 5 10 15 25 35 20 30 40 slot

participant #21, observation 3, rel-entr. = 0.55, JS = 0.46 1.00 0.75 probability 0.25 0.00 10 15 25 5 35 20 30 40 slot





participant #21, observation 100, rel-entr. = 0.29, JS = 0.26 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

participant #21, observation 101, rel-entr. = 0.29, JS = 0.27 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

participant #21, observation 102, rel-entr. = 0.29, JS = 0.27 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

participant #21, observation 197, rel-entr. = 0.13, JS = 0.094 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

participant #21, observation 198, rel-entr. = 0.13, JS = 0.094 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

participant #21, observation 199, rel-entr. = 0.13, JS = 0.092 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

participant #21, observation 200, rel-entr. = 0.13, JS = 0.094 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot