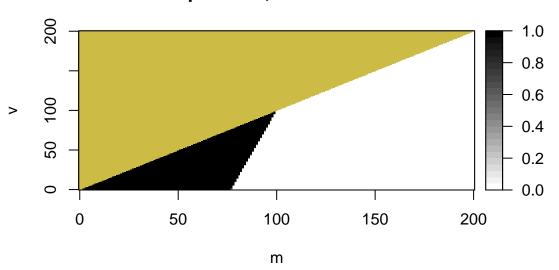
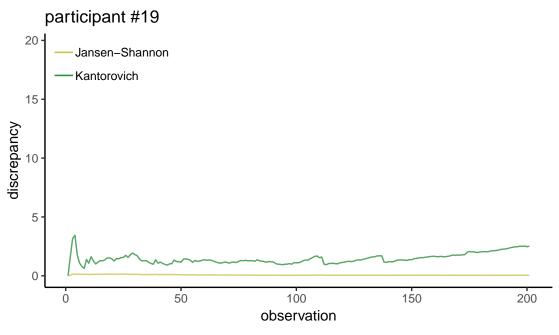


h for part. #19, stubbornness = 2.66





participant #19, sqrt(robot-participant)

