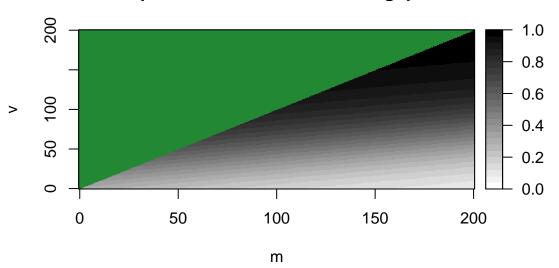
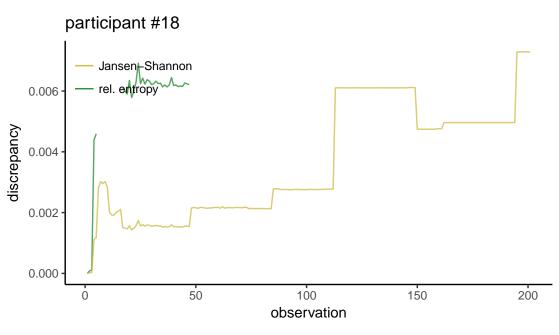
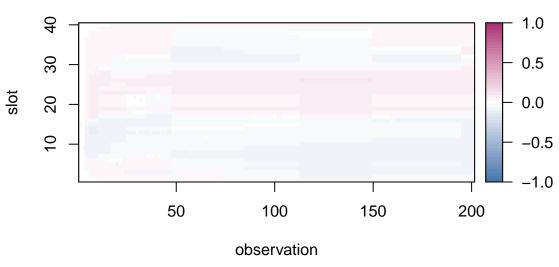


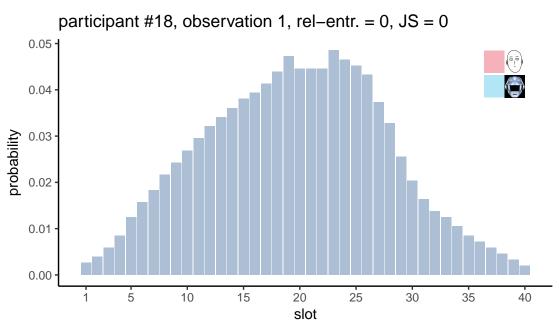
part. #18, stub. = 6.41, changepoint:





participant #18, sqrt(robot-participant)

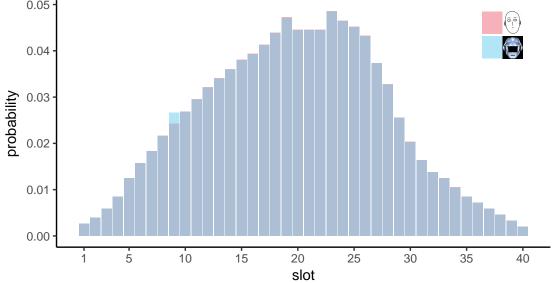




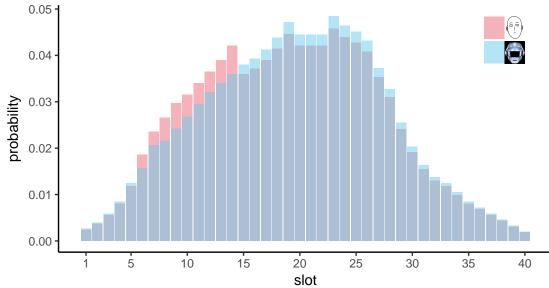
participant #18, observation 2, rel-entr. = 8e-05, JS = 2e-05 0.05 0.04 probability 0.03 0.02 0.01 0.00 15 25 30 5 10 20 35 40

slot

participant #18, observation 3, rel-entr. = 0.00012, JS = 2.9e-05



participant #18, observation 4, rel-entr. = 0.0044, JS = 0.0011 0.05

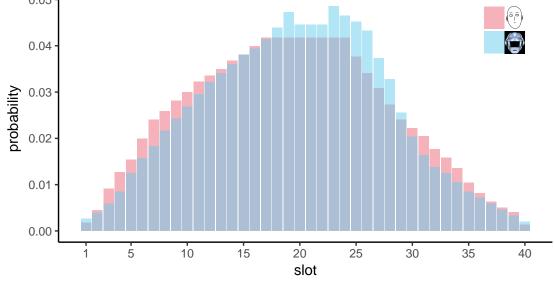


participant #18, observation 99, rel-entr. = 0.011, JS = 0.0028 0.05 0.04 probability 0.03 0.02 0.01 0.00 15 25 30 5 10 20 35 40

slot

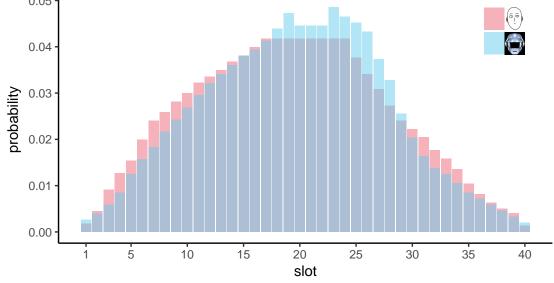
0.05

participant #18, observation 100, rel-entr. = 0.011, JS = 0.0028



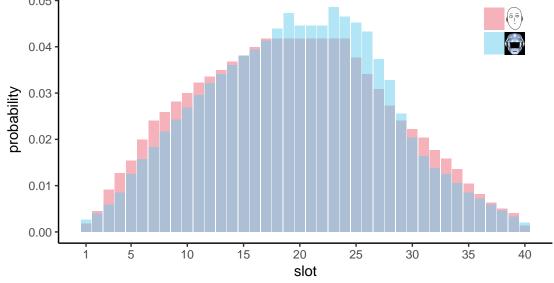
0.05

participant #18, observation 101, rel-entr. = 0.011, JS = 0.0028

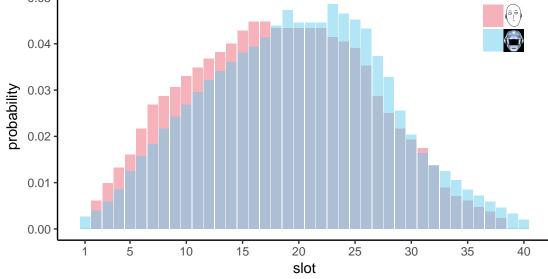


0.05 0.04

participant #18, observation 102, rel-entr. = 0.011, JS = 0.0028



participant #18, observation 197, rel-entr. = 0.12, JS = 0.0073 0.05 0.04 probability 0.03 0.02



participant #18, observation 198, rel-entr. = 0.12, JS = 0.0073 0.05 0.04 probability 0.03 0.02 0.01 0.00

20

slot

25

30

35

40

15

10

5

participant #18, observation 199, rel-entr. = 0.12, JS = 0.0073 0.05 0.04 probability 0.03 0.02 0.01 0.00

20

slot

25

30

35

40

15

10

5

participant #18, observation 200, rel-entr. = 0.12, JS = 0.0073 0.05 0.04 probability 0.03 0.02 0.01

20

slot

25

30

35

40

15

10

0.00

5