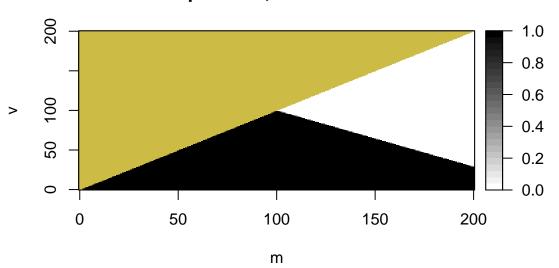
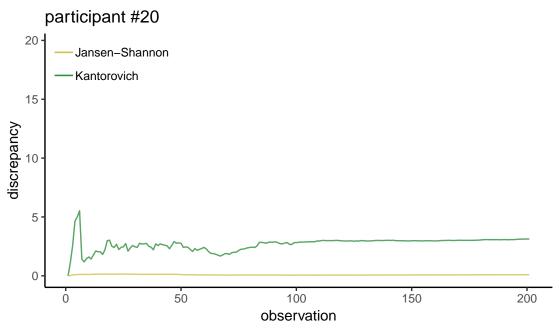


## h for part. #20, stubbornness = 3.51





## participant #20, sqrt(robot-participant)

