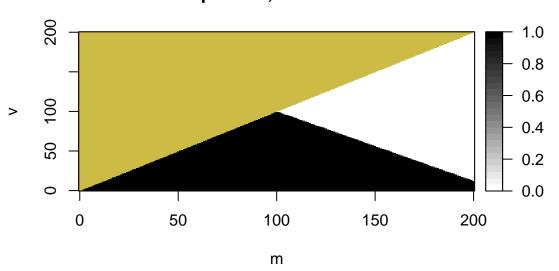
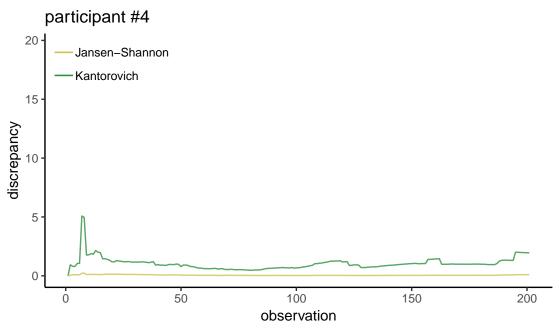
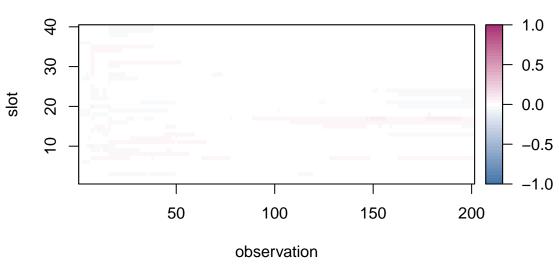


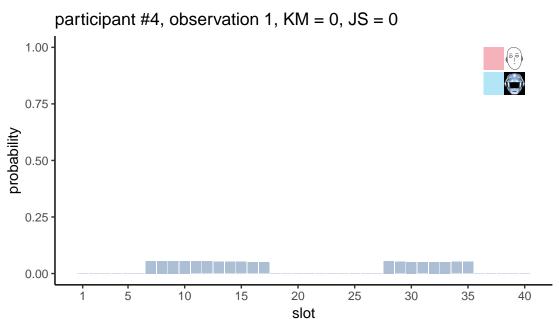
h for part. #4, stubbornness = 32

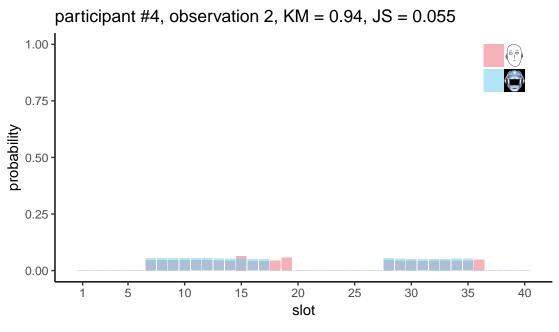


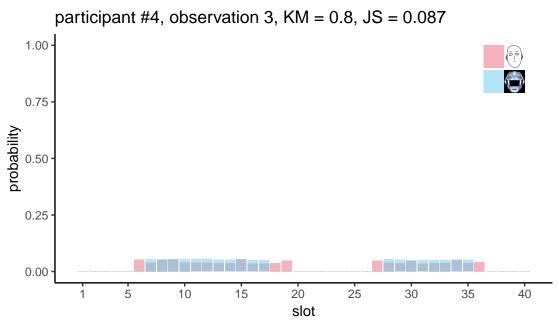


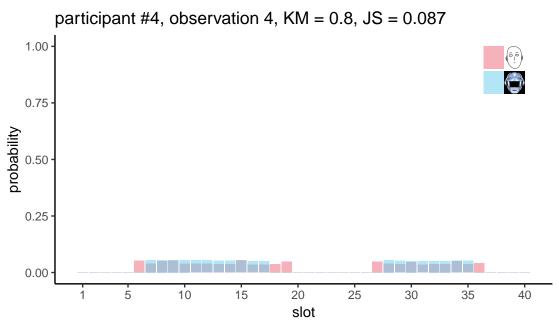
participant #4, sqrt(robot-participant)

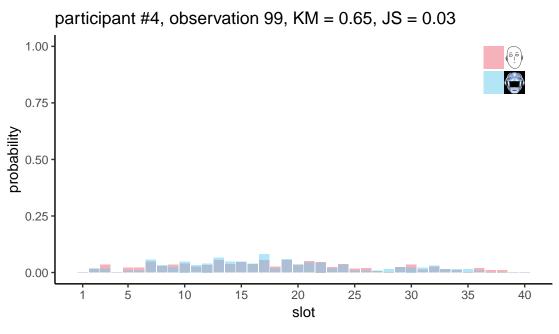












participant #4, observation 100, KM = 0.68, JS = 0.031 1.00 0.75 probability 05.0 0.25 0.00 5 10 15 20 25 30 35 40 slot

participant #4, observation 101, KM = 0.69, JS = 0.031 1.00 0.75 probability 05.0 0.25 0.00 5 10 15 20 25 30 35 40 slot

