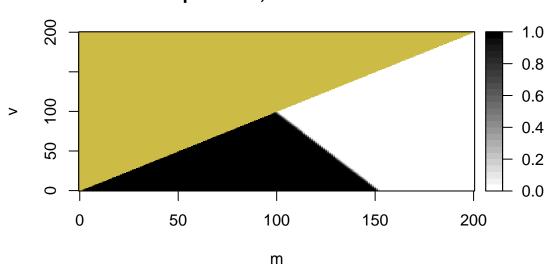
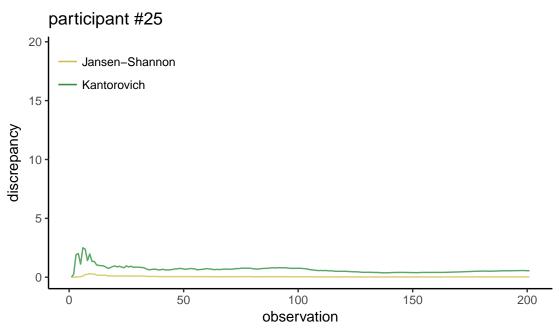
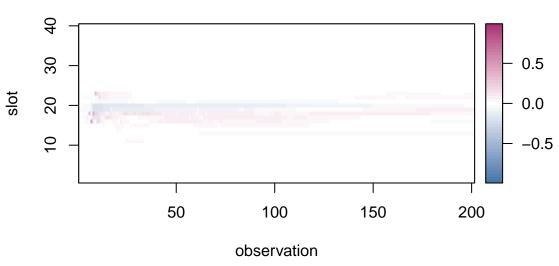


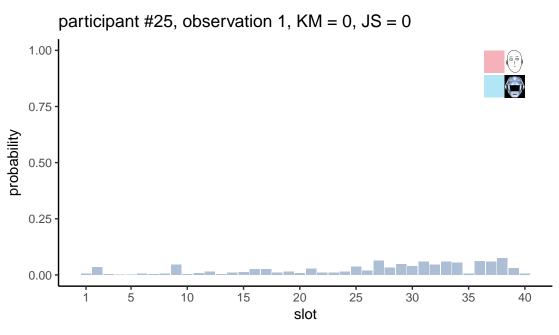
h for part. #25, stubbornness = 0.212

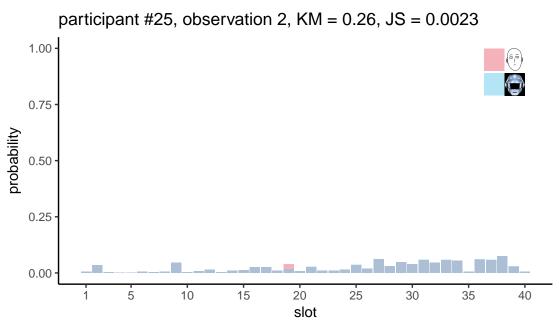


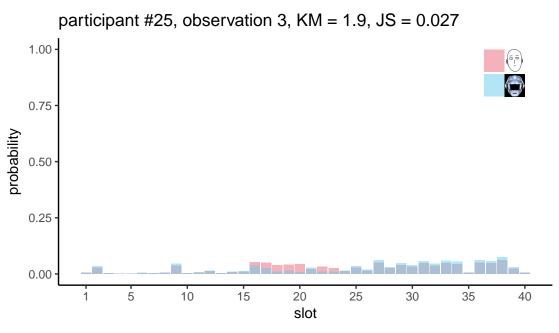


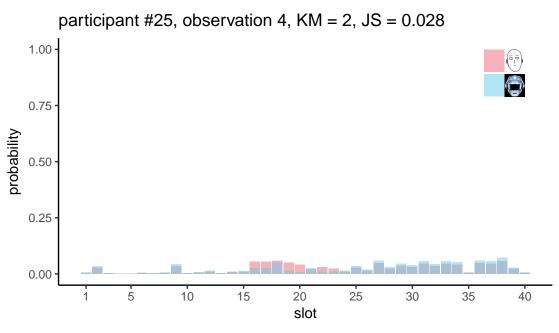
participant #25, sqrt(robot-participant)

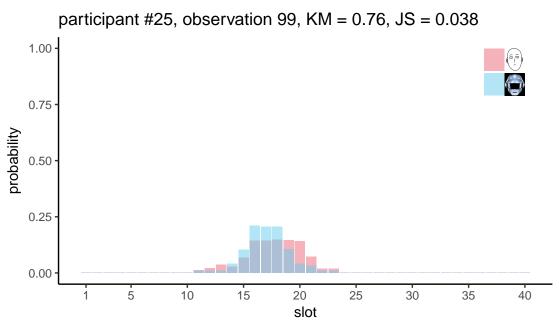


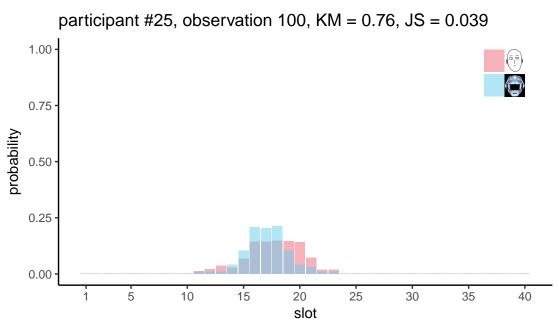


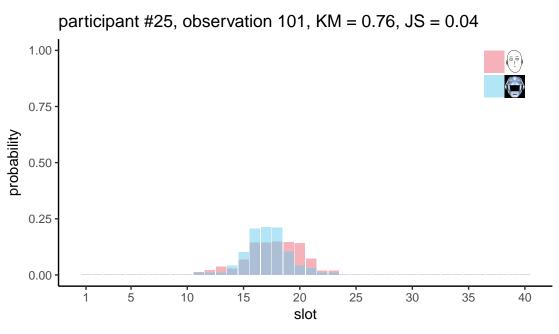




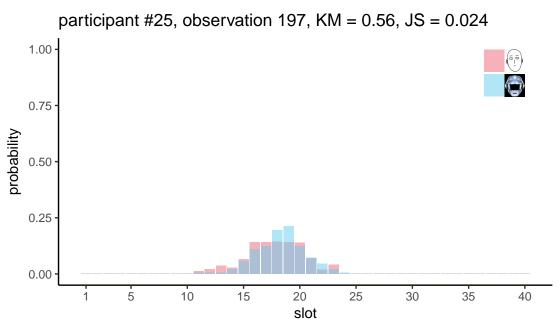


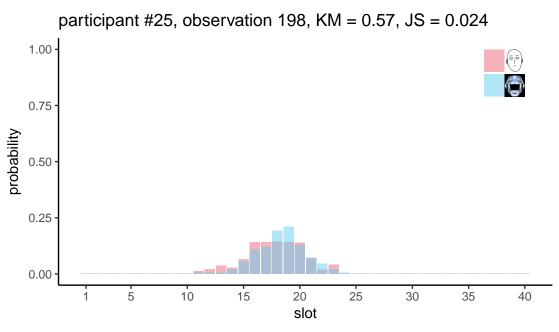






participant #25, observation 102, KM = 0.74, JS = 0.039 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot





participant #25, observation 199, KM = 0.56, JS = 0.0231.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

participant #25, observation 200, KM = 0.55, JS = 0.023 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot