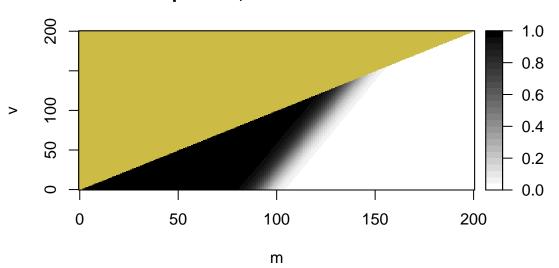
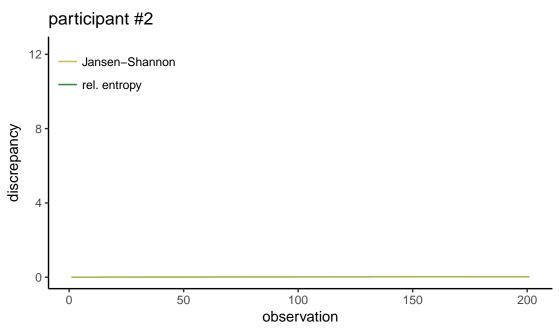
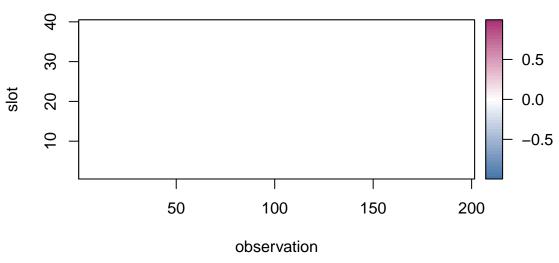


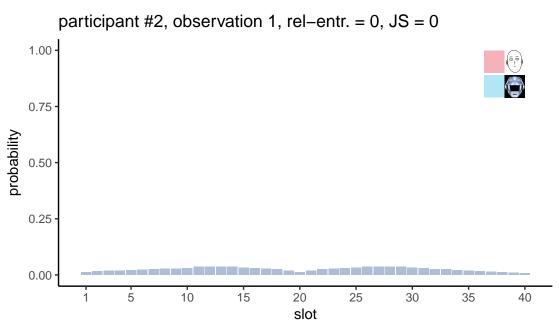
## h for part. #2, stubbornness = 1.09e+03





## participant #2, sqrt(robot-participant)

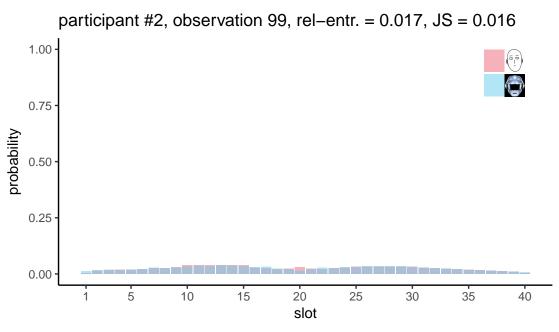




participant #2, observation 2, rel-entr. = 1.3e-05, JS = 1.3e-05 1.00 0.75 probability 0.25 0.00 5 10 15 25 20 30 35 40 slot

participant #2, observation 3, rel-entr. = 0.0011, JS = 0.0011 1.00 0.75 probability 0.25 0.00 5 10 15 25 20 30 35 40 slot

participant #2, observation 4, rel-entr. = 0.0011, JS = 0.0011 1.00 0.75 probability 0.25 0.00 5 10 15 25 20 30 35 40 slot



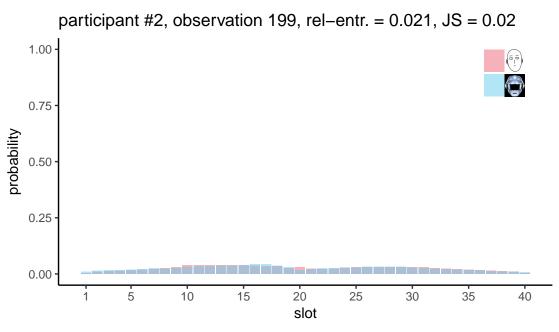
participant #2, observation 100, rel-entr. = 0.017, JS = 0.016 1.00 0.75 probability 0.25 0.00 10 5 15 25 20 30 35 40 slot

participant #2, observation 101, rel-entr. = 0.017, JS = 0.016 1.00 0.75 probability 0.25 0.00 10 5 15 25 20 30 35 40 slot

participant #2, observation 102, rel-entr. = 0.017, JS = 0.016 1.00 0.75 probability 0.25 0.00 5 10 15 25 20 30 35 40 slot

participant #2, observation 197, rel-entr. = 0.021, JS = 0.02 1.00 0.75 probability 0.25 0.00 5 10 15 25 20 30 35 40 slot

participant #2, observation 198, rel-entr. = 0.021, JS = 0.02 1.00 0.75 probability 0.25 0.00 5 10 15 25 20 30 35 40 slot



participant #2, observation 200, rel-entr. = 0.027, JS = 0.027 1.00 0.75 probability 0.25 0.00 5 10 15 25 20 30 35 40 slot