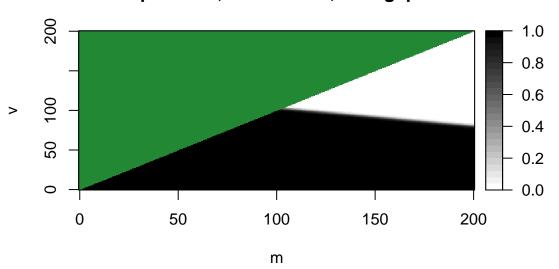
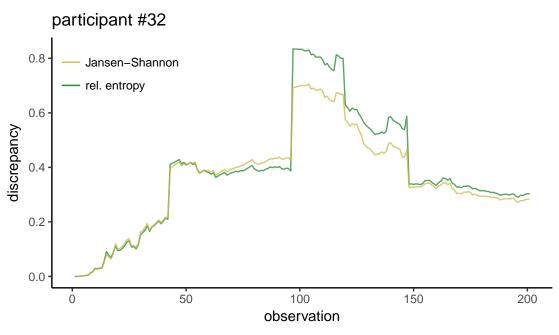
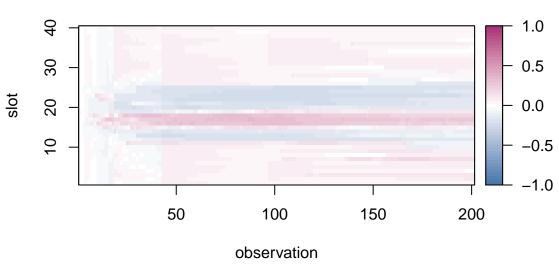


part. #32, stub. = 24.6, changepoint:



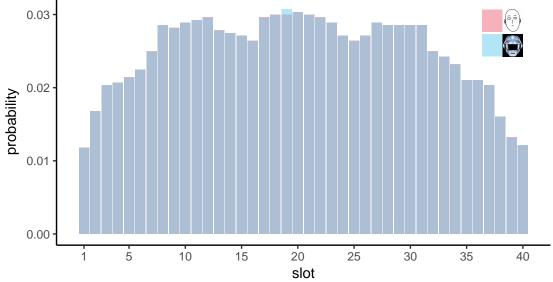


participant #32, sqrt(robot-participant)

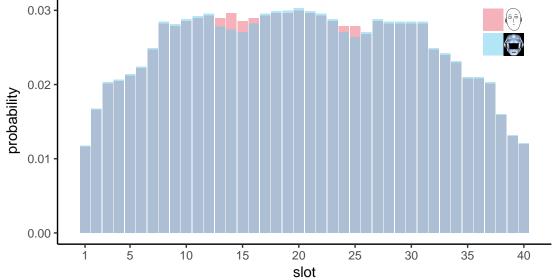


participant #32, observation 1, rel-entr. = 0, JS = 0 0.03 0.02 probability 0.01 0.00 15 25 30 5 10 20 35 40 slot

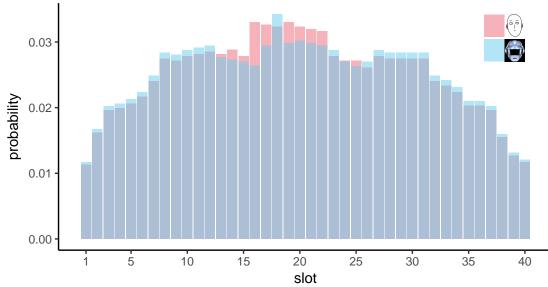
participant #32, observation 2, rel-entr. = 9.3e-06, JS = 9.3e-06



participant #32, observation 3, rel-entr. = 0.00025, JS = 0.00025



participant #32, observation 4, rel-entr. = 0.0017, JS = 0.0018



participant #32, observation 99, rel-entr. = 0.83, JS = 0.7 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #32, observation 100, rel-entr. = 0.83, JS = 0.7 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #32, observation 101, rel-entr. = 0.83, JS = 0.7 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #32, observation 102, rel-entr. = 0.83, JS = 0.7 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #32, observation 197, rel-entr. = 0.3, JS = 0.28 0.10 probability 0.00 slot

participant #32, observation 198, rel-entr. = 0.3, JS = 0.28 0.10 probability 0.00 slot

participant #32, observation 199, rel-entr. = 0.3, JS = 0.28 0.10 probability 0.00 slot

participant #32, observation 200, rel-entr. = 0.3, JS = 0.28 0.10 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot