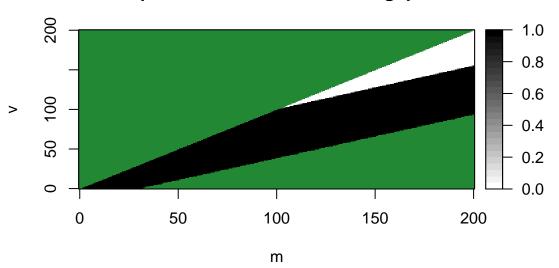
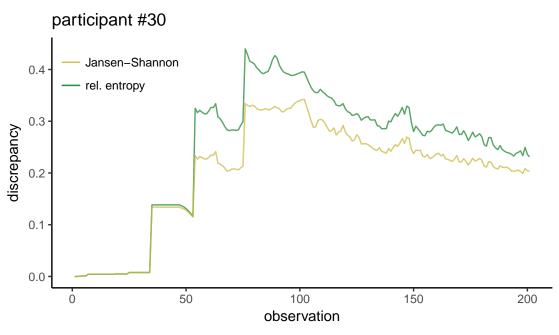
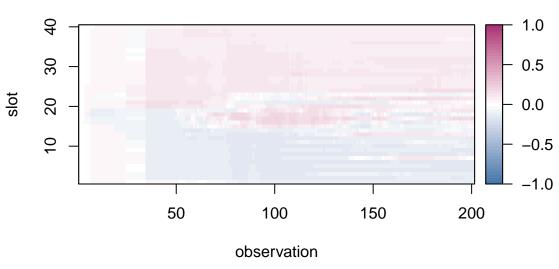


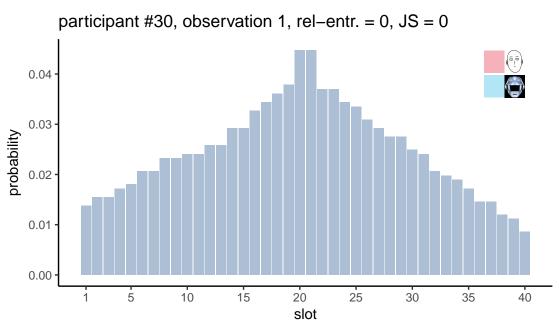
part. #30, stub. = 74.5, changepoint:



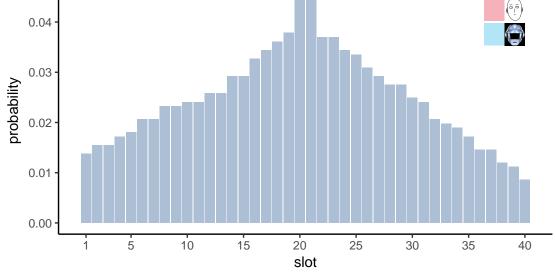


participant #30, sqrt(robot-participant)

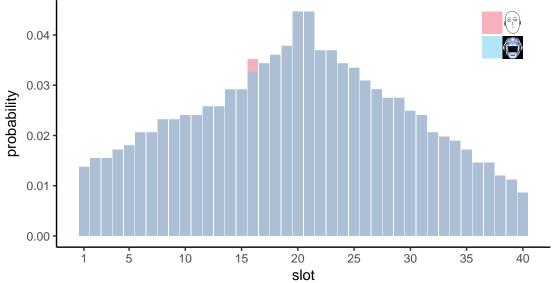




participant #30, observation 2, rel-entr. = -1.3e-17, JS = 9e-180.04

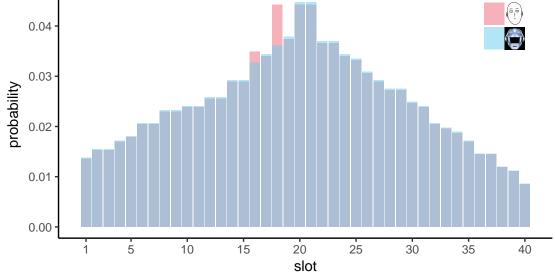


participant #30, observation 3, rel-entr. = 9.3e-05, JS = 9.5e-05



0.04

participant #30, observation 4, rel-entr. = 0.00092, JS = 0.00095



participant #30, observation 99, rel-entr. = 0.39, JS = 0.34 0.075 probability 0.050 0.025 0.000

20

slot

25

30

35

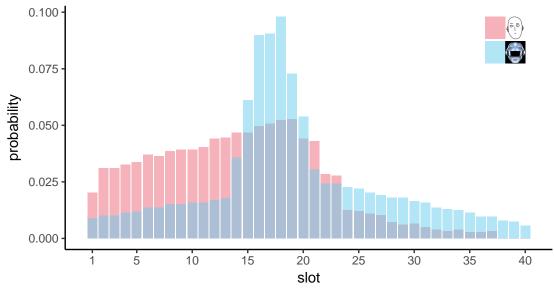
40

10

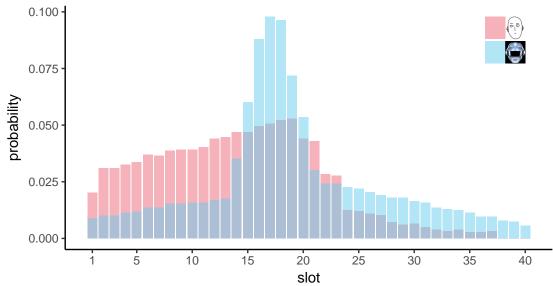
15

5

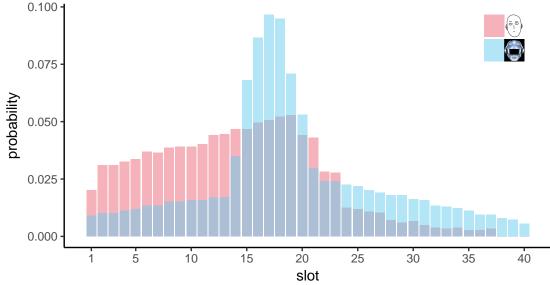
participant #30, observation 100, rel-entr. = 0.39, JS = 0.34



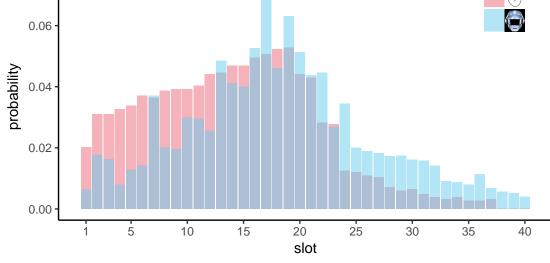
participant #30, observation 101, rel-entr. = 0.4, JS = 0.34

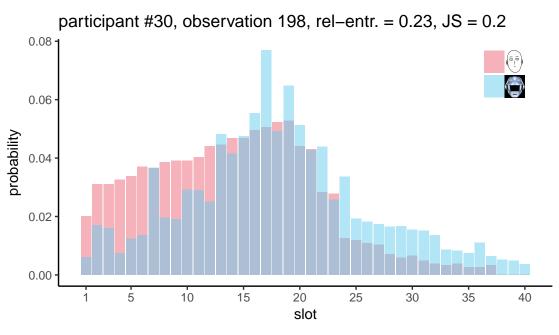


participant #30, observation 102, rel-entr. = 0.39, JS = 0.34

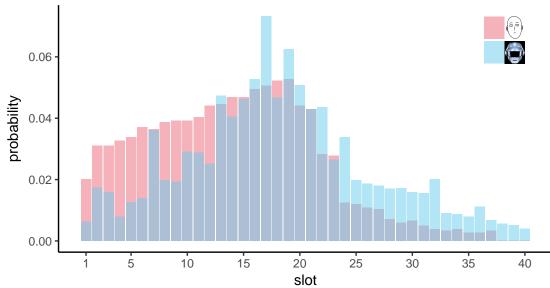


participant #30, observation 197, rel-entr. = 0.24, JS = 0.2 0.06 probability 0.04 0.02





participant #30, observation 199, rel-entr. = 0.25, JS = 0.21



participant #30, observation 200, rel-entr. = 0.24, JS = 0.2

