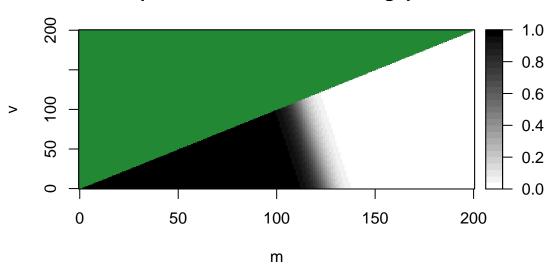
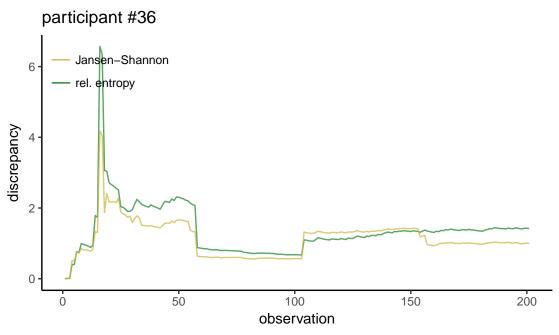
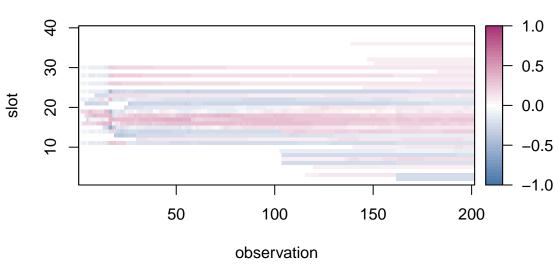


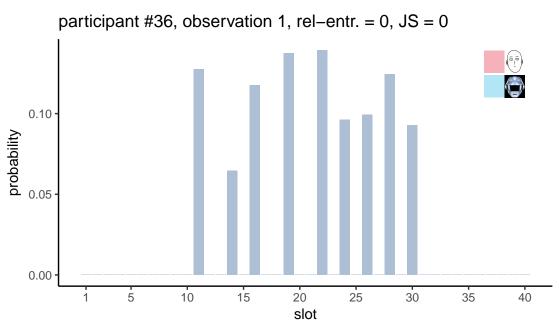
part. #36, stub. = 18.9, changepoint:



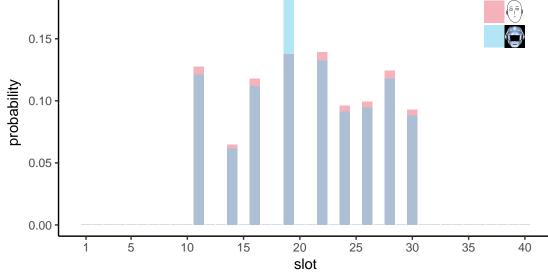


participant #36, sqrt(robot-participant)

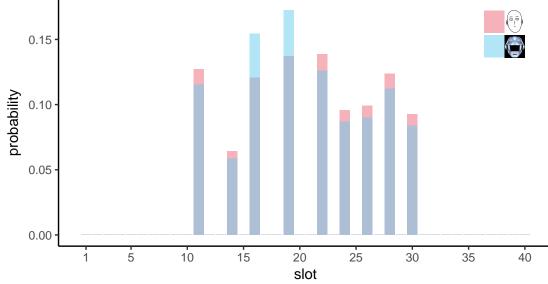




participant #36, observation 2, rel-entr. = 0.0073, JS = 0.0071



participant #36, observation 3, rel-entr. = 0.012, JS = 0.012



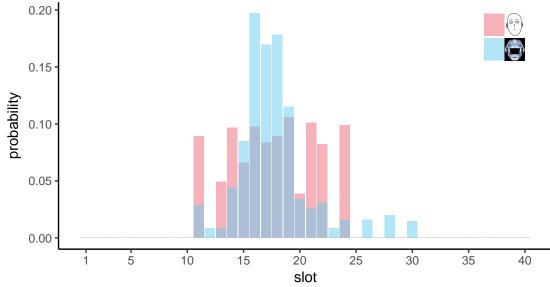
participant #36, observation 4, rel-entr. = 0.4, JS = 0.51 0.15 probability 0.10 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #36, observation 99, rel-entr. = 0.68, JS = 0.57 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20

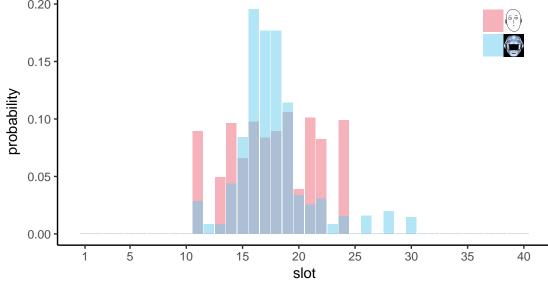
slot

40

participant #36, observation 100, rel-entr. = 0.68, JS = 0.57



participant #36, observation 101, rel-entr. = 0.68, JS = 0.57



participant #36, observation 102, rel-entr. = 0.68, JS = 0.57 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40

slot

participant #36, observation 197, rel-entr. = 1.4, JS = 0.99 0.10 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #36, observation 198, rel-entr. = 1.4, JS = 0.99 0.10 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

