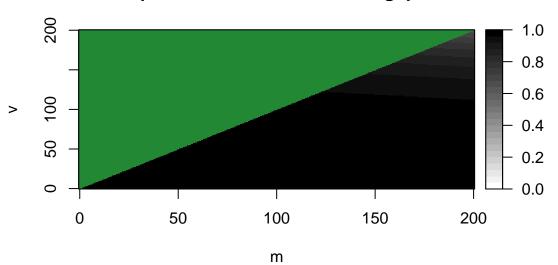
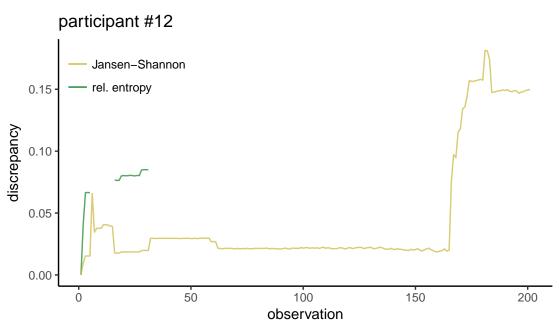
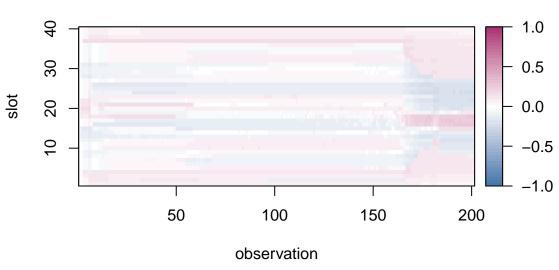


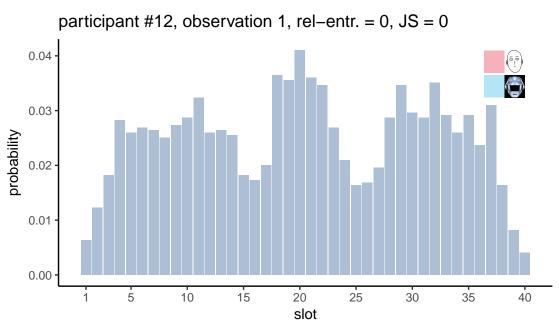
part. #12, stub. = 49.7, changepoint:



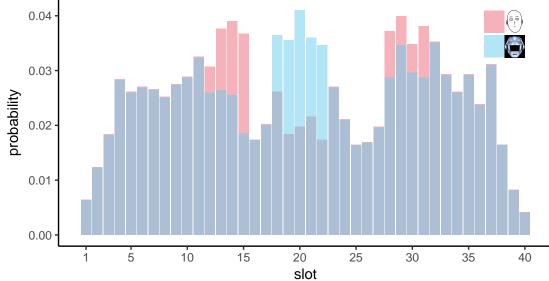


## participant #12, sqrt(robot-participant)

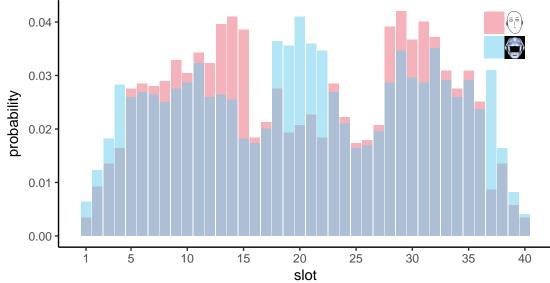




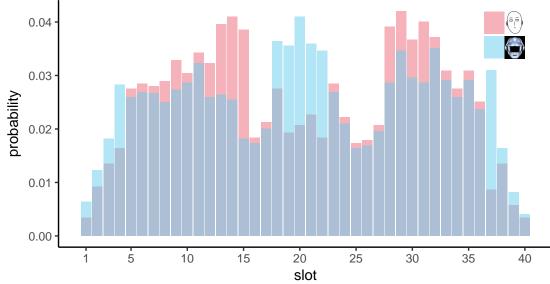
participant #12, observation 2, rel-entr. = 0.041, JS = 0.0097



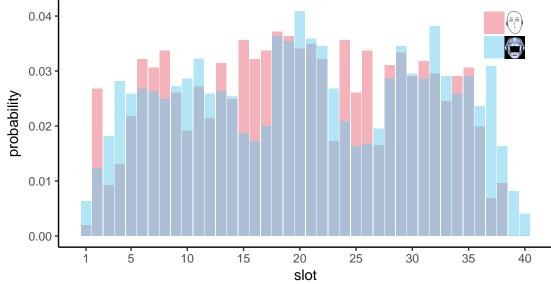
participant #12, observation 3, rel-entr. = 0.067, JS = 0.015



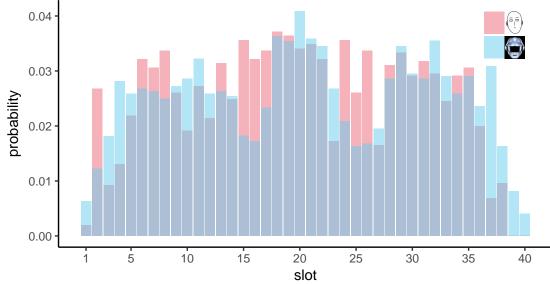
participant #12, observation 4, rel-entr. = 0.067, JS = 0.015



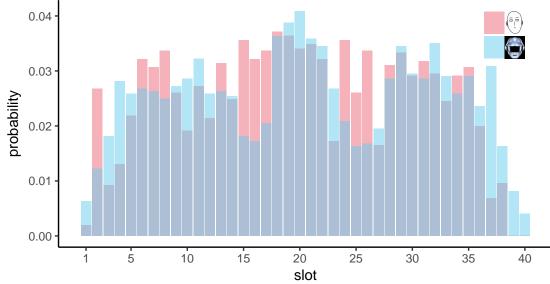
participant #12, observation 99, rel-entr. = 0.25, JS = 0.022



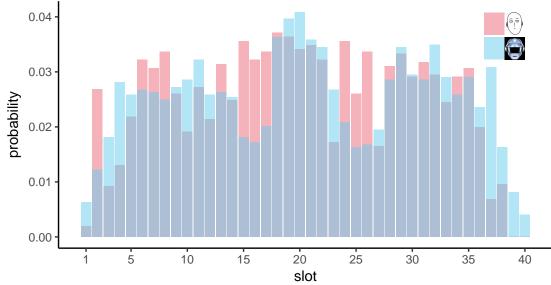
participant #12, observation 100, rel-entr. = 0.25, JS = 0.022



participant #12, observation 101, rel-entr. = 0.25, JS = 0.022



participant #12, observation 102, rel-entr. = 0.25, JS = 0.022



participant #12, observation 197, rel-entr. = 3.2, JS = 0.15 0.10 probability 0.00 slot

participant #12, observation 198, rel-entr. = 3.1, JS = 0.15 probability 0.00 slot

participant #12, observation 199, rel-entr. = 3, JS = 0.15 0.10 probability 0.00 slot

participant #12, observation 200, rel-entr. = 3, JS = 0.15 0.15 0.10 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot