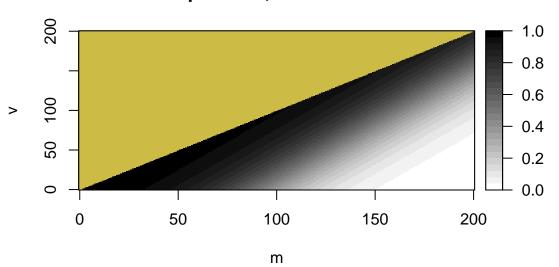
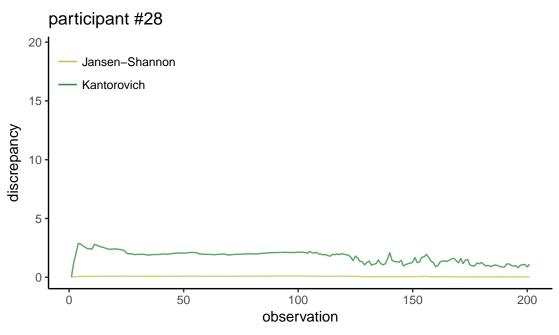


## h for part. #28, stubbornness = 28.2





## participant #28, sqrt(robot-participant)

