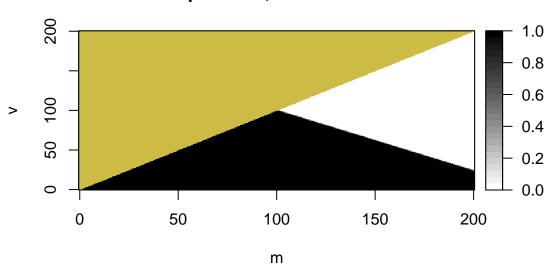
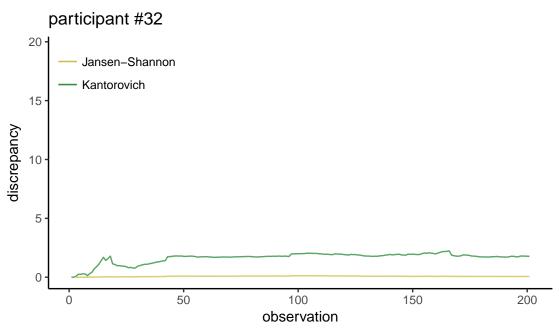


h for part. #32, stubbornness = 19.5





participant #32, sqrt(robot-participant)

