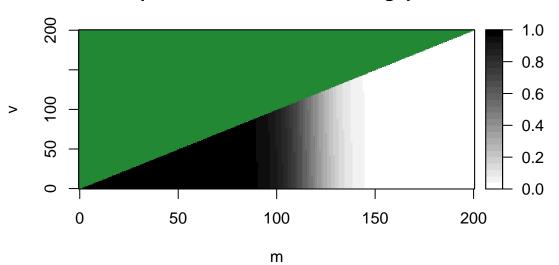
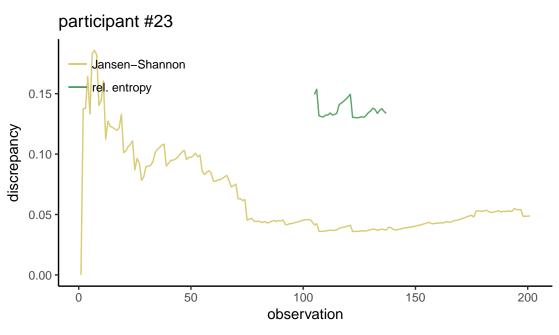
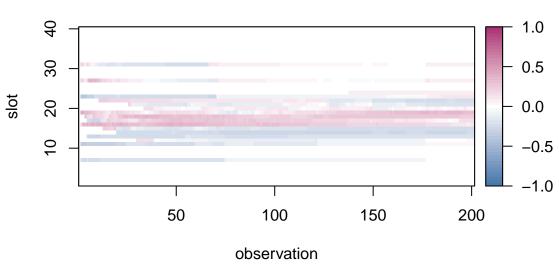


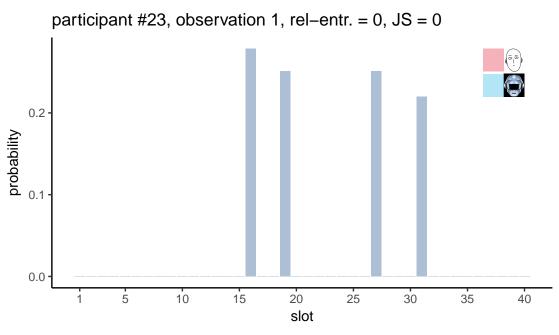
part. #23, stub. = 7.02, changepoint:





participant #23, sqrt(robot-participant)





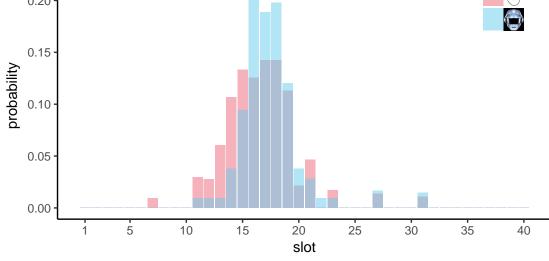
participant #23, observation 2, rel-entr. = 0.43, JS = 0.14 0.3 probability 0.1 0.0 10 15 30 25 20 35 40 slot

participant #23, observation 3, rel-entr. = 0.43, JS = 0.14 0.3 probability 0.2 -0.1 0.0 10 15 30 20 25 35 40 slot

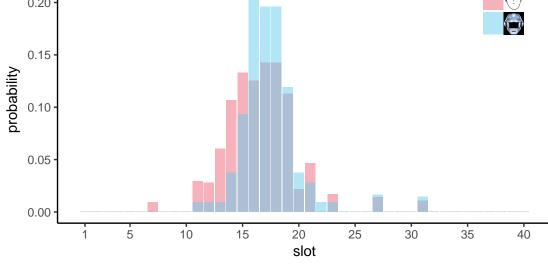
participant #23, observation 4, rel-entr. = 2, JS = 0.16 0.3 probability 0.0 10 15 25 30 20 35 40 slot

participant #23, observation 99, rel-entr. = 0.28, JS = 0.045 0.20 0.15 probability 0.05 0.00 15 25 35 5 10 20 30 40 slot

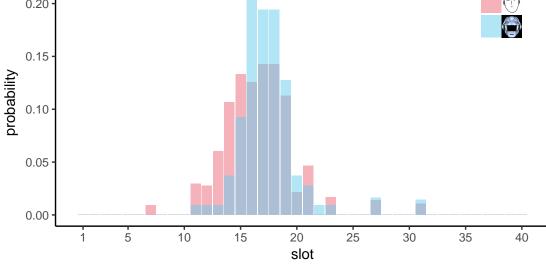
participant #23, observation 100, rel-entr. = 0.29, JS = 0.045 0.20 0.15



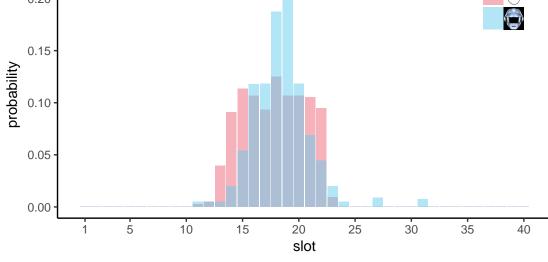
participant #23, observation 101, rel-entr. = 0.29, JS = 0.046 0.20 0.15 probability



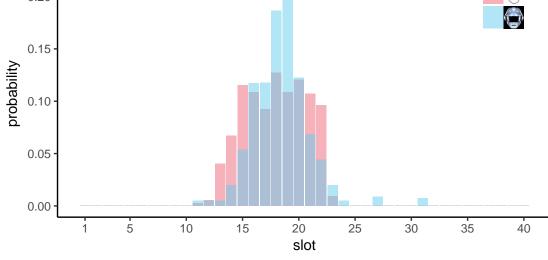
participant #23, observation 102, rel-entr. = 0.28, JS = 0.046 0.20 0.15 probability 0.10



participant #23, observation 197, rel-entr. = 0.47, JS = 0.054 0.20 0.15



participant #23, observation 198, rel-entr. = 0.45, JS = 0.048 0.20 0.15



participant #23, observation 199, rel-entr. = 0.45, JS = 0.049 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #23, observation 200, rel-entr. = 0.44, JS = 0.049 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot