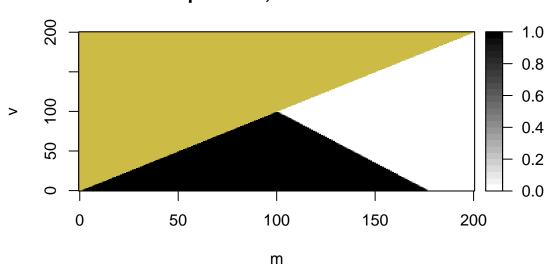
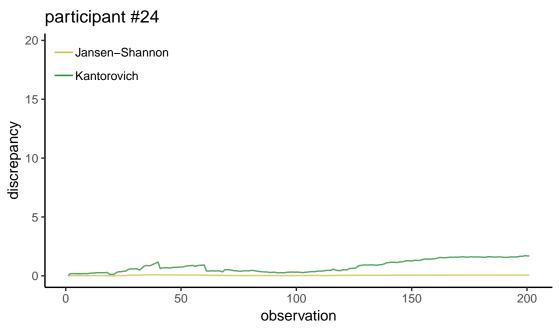


h for part. #24, stubbornness = 11.2





participant #24, sqrt(robot-participant)

