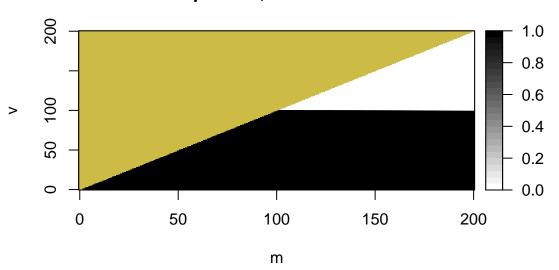
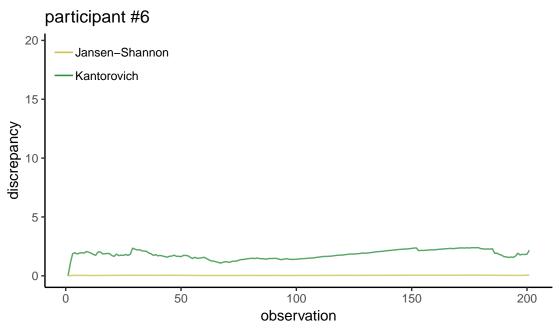


## h for part. #6, stubbornness = 46.5





## participant #6, sqrt(robot-participant)

