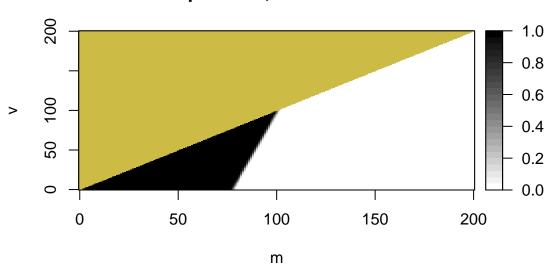
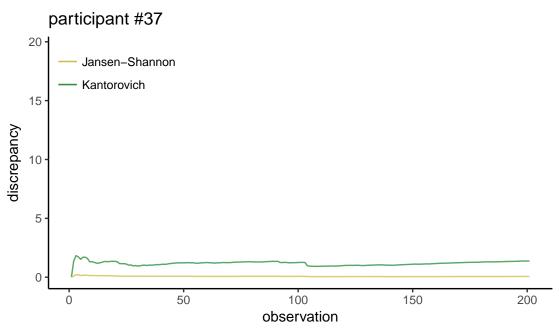
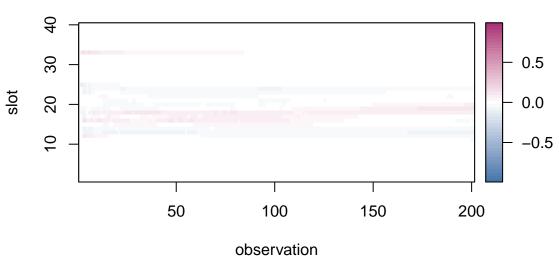


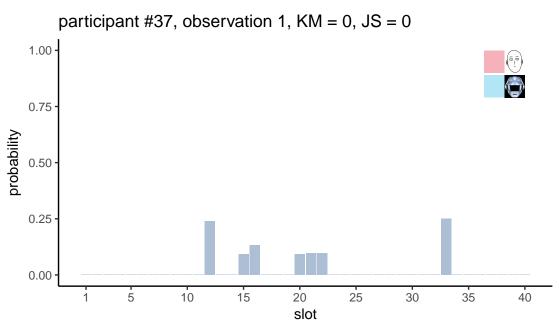
h for part. #37, stubbornness = 6.84

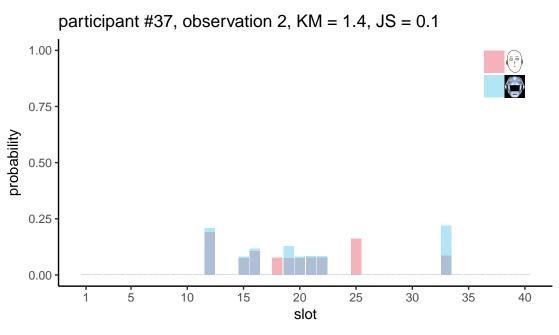


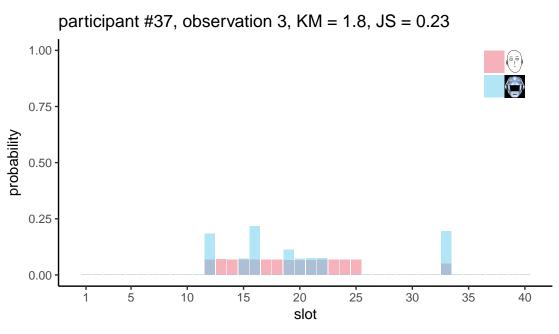


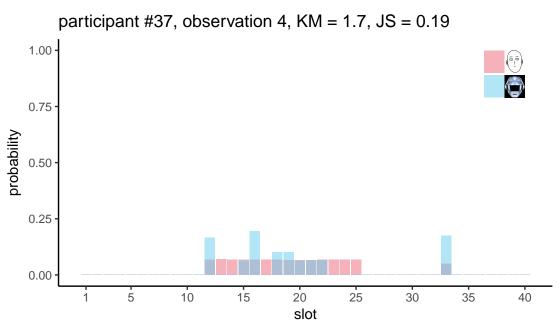
participant #37, sqrt(robot-participant)

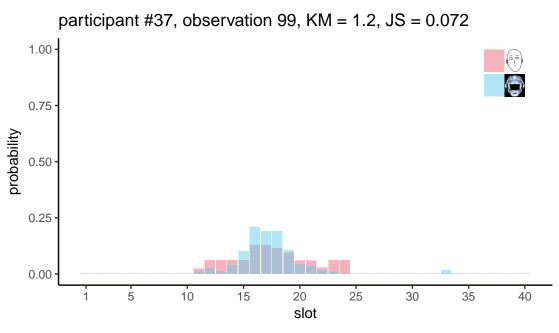


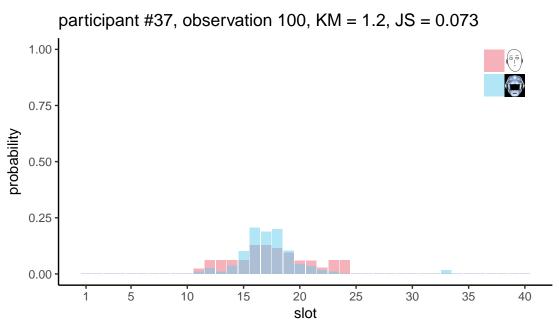


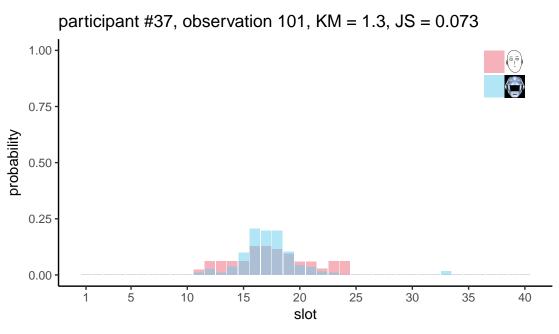


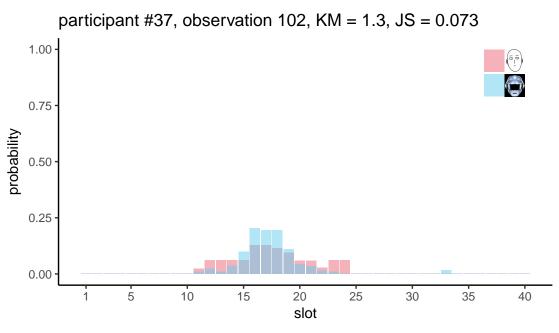


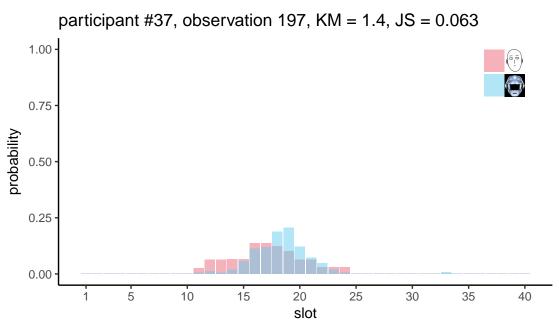












participant #37, observation 198, KM = 1.4, JS = 0.063 1.00 0.75 probability 0.25 0.00 10 15 25 30 5 20 35 40 slot

