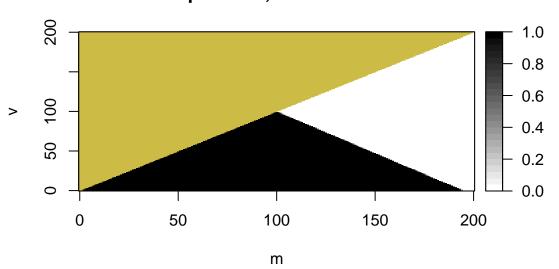
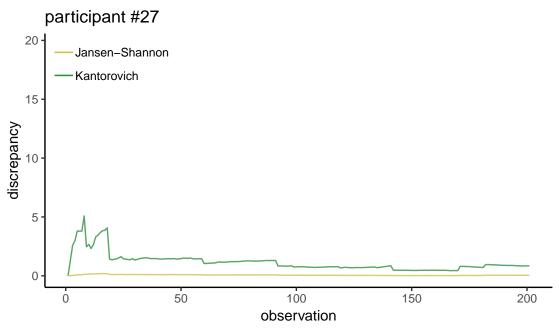


## h for part. #27, stubbornness = 4.71





## participant #27, sqrt(robot-participant)

