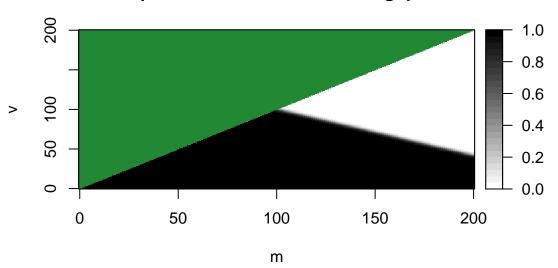
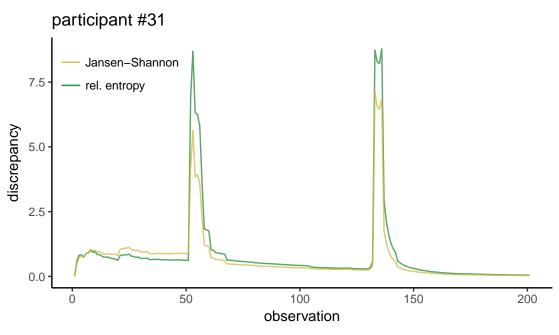
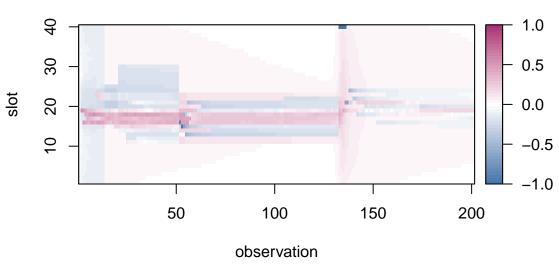


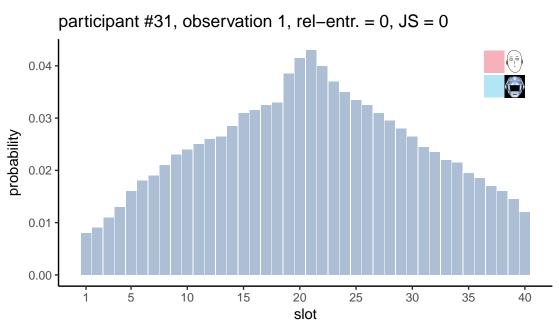
part. #31, stub. = 1.49, changepoint:

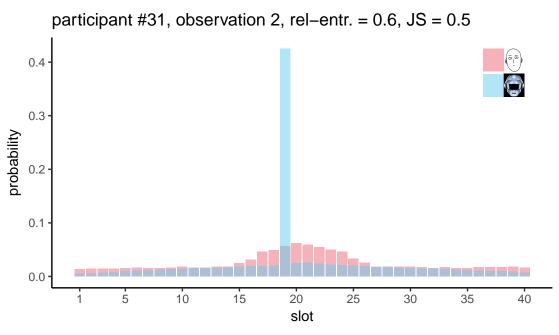




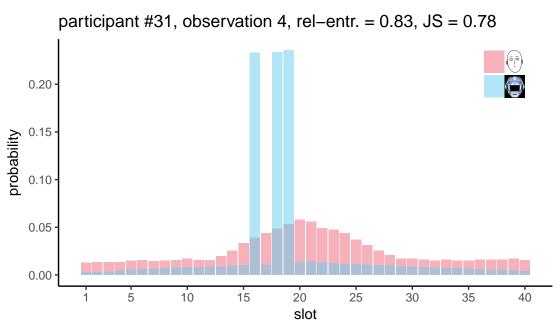
## participant #31, sqrt(robot-participant)





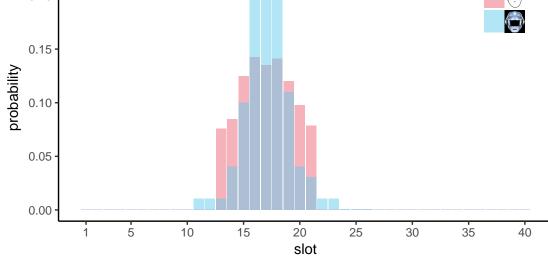


participant #31, observation 3, rel-entr. = 0.83, JS = 0.72 0.3 probability 0.0 25 30 10 15 20 35 40 slot

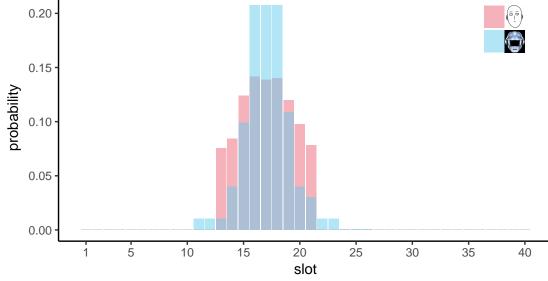


participant #31, observation 99, rel-entr. = 0.43, JS = 0.34 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

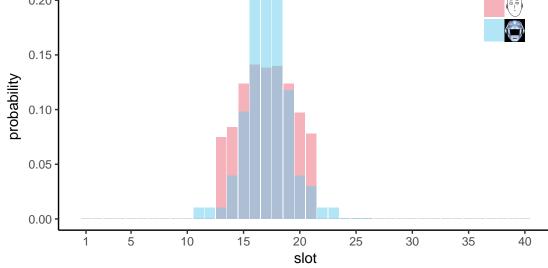
participant #31, observation 100, rel-entr. = 0.43, JS = 0.34 0.20 0.15



participant #31, observation 101, rel-entr. = 0.42, JS = 0.34



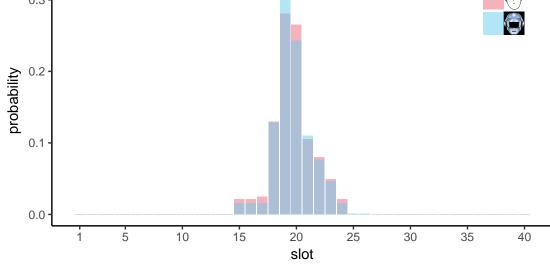
participant #31, observation 102, rel-entr. = 0.42, JS = 0.33



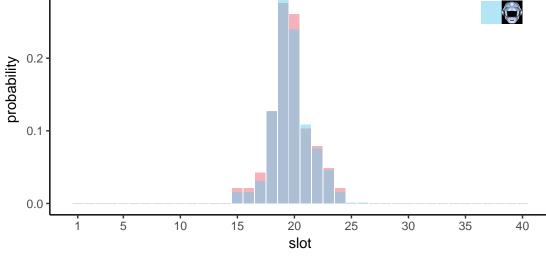
participant #31, observation 197, rel-entr. = 0.055, JS = 0.039 0.3 probability 0.2 0.1 0.0 10 15 25 30 20 35 40

slot

participant #31, observation 198, rel-entr. = 0.053, JS = 0.038 0.3 0.2 0.1



participant #31, observation 199, rel-entr. = 0.052, JS = 0.037 0.3



participant #31, observation 200, rel-entr. = 0.052, JS = 0.036 0.3

