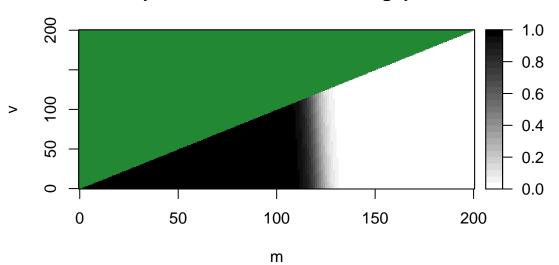
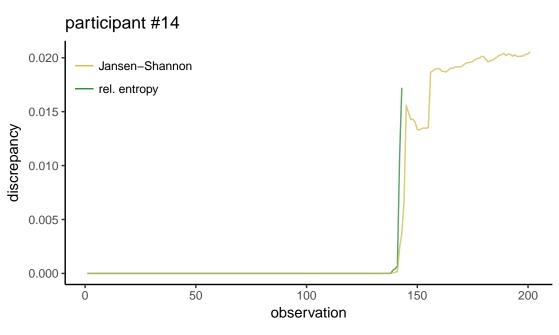
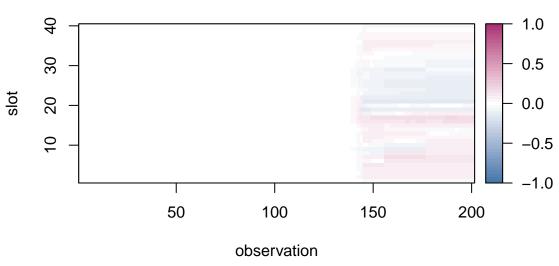


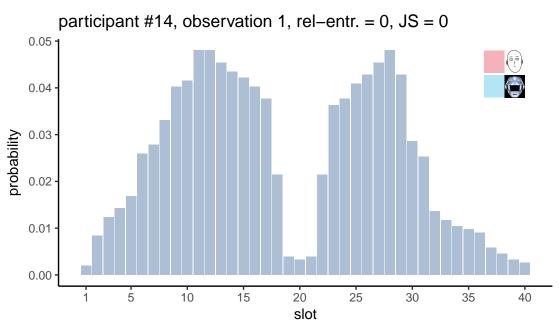
part. #14, stub. = 403, changepoint:





## participant #14, sqrt(robot-participant)



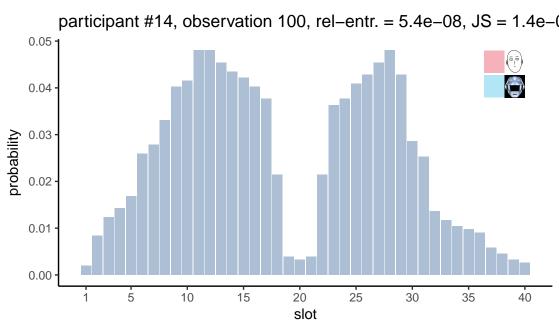


participant #14, observation 2, rel-entr. = 9.3e-09, JS = 2.3e-09 0.05 -0.04 0.03 probability 0.02 0.01 0.00 15 25 30 5 10 20 35 40 slot

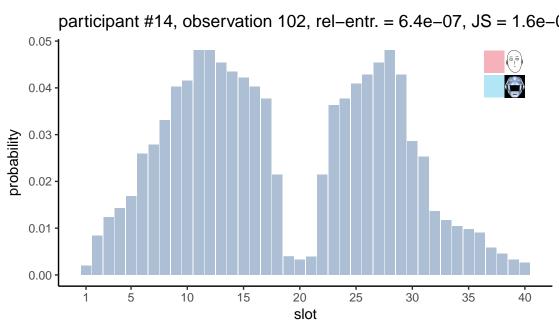
participant #14, observation 3, rel-entr. = 1e-08, JS = 2.5e-09 0.05 0.04 0.03 probability 0.02 0.01 0.00 15 25 30 5 10 20 35 40 slot

participant #14, observation 4, rel-entr. = 1.5e-08, JS = 3.7e-09 0.05 0.04 0.03 probability 0.02 0.01 0.00 15 25 30 5 10 20 35 40 slot

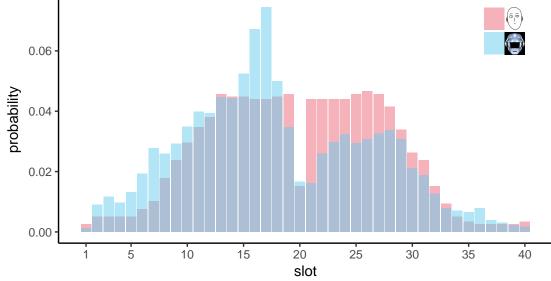
participant #14, observation 99, rel-entr. = 1.5e-07, JS = 3.8e-08 0.05 -0.04 0.03 probability 0.02 0.01 0.00 15 25 5 10 20 30 35 40 slot



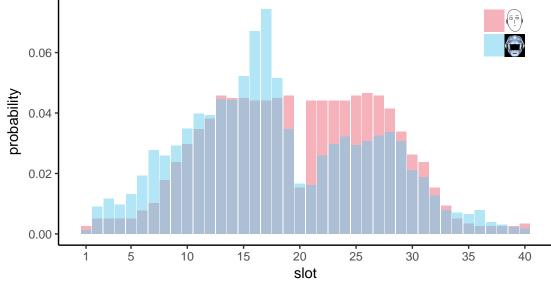
participant #14, observation 101, rel-entr. = 5.5e-07, JS = 1.4e-0 0.05 -0.04 0.03 probability 0.02 0.01 0.00 15 25 30 5 10 20 35 40 slot



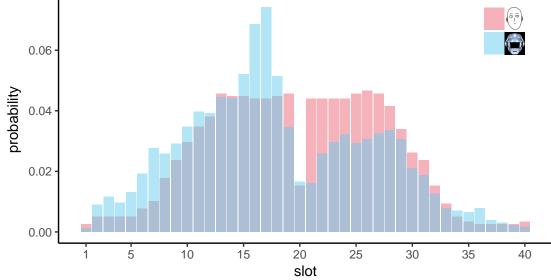
participant #14, observation 197, rel-entr. = 0.084, JS = 0.02



participant #14, observation 198, rel-entr. = 0.084, JS = 0.02



participant #14, observation 199, rel-entr. = 0.085, JS = 0.02



participant #14, observation 200, rel-entr. = 0.085, JS = 0.02

