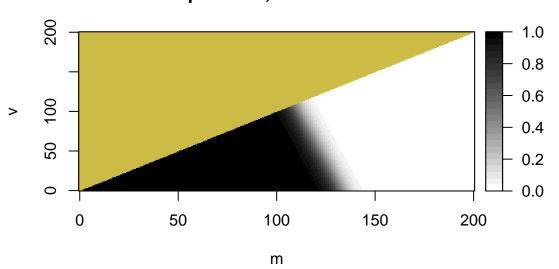
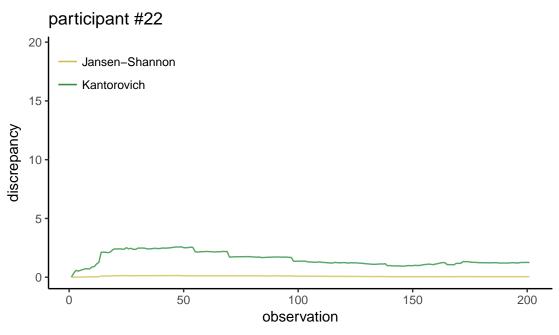


## h for part. #22, stubbornness = 21.1





## participant #22, sqrt(robot-participant)

