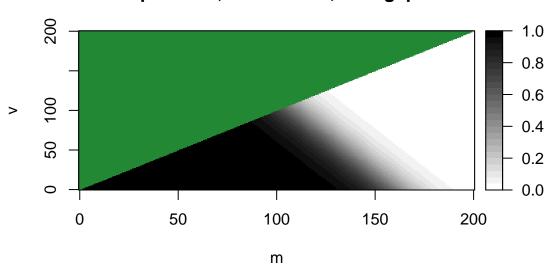
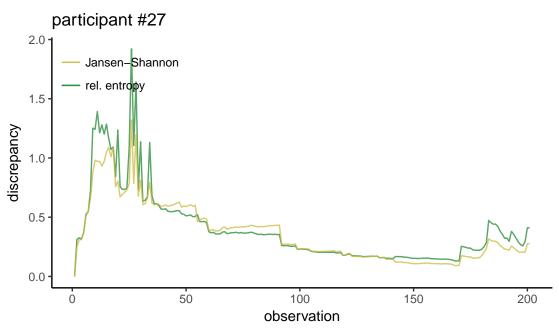
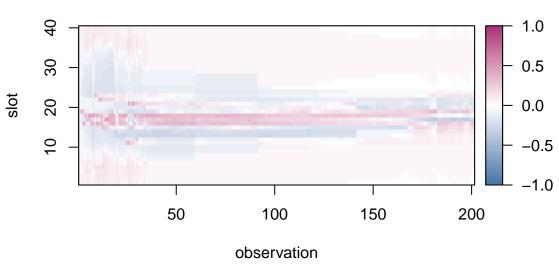


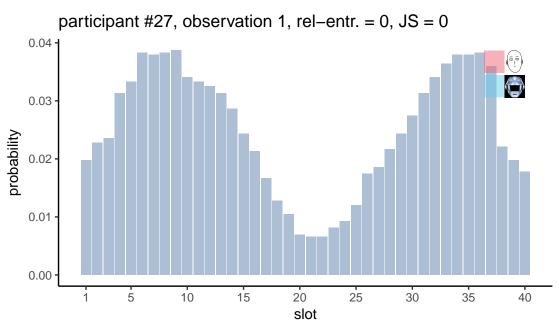
part. #27, stub. = 2.62, changepoint:





participant #27, sqrt(robot-participant)





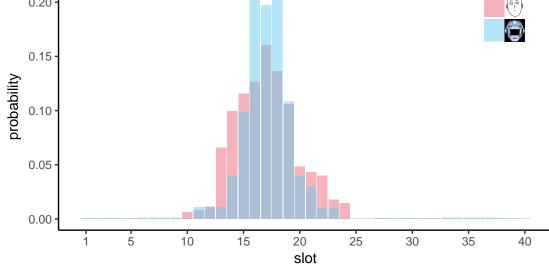
participant #27, observation 2, rel-entr. = 0.31, JS = 0.25 0.20 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #27, observation 3, rel-entr. = 0.33, JS = 0.31 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

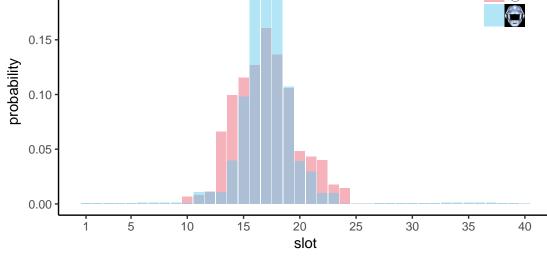
participant #27, observation 4, rel-entr. = 0.32, JS = 0.31 0.15 probability 0.10 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #27, observation 99, rel-entr. = 0.23, JS = 0.23 0.20 0.15 probability 0.05 0.00 10 15 25 30 5 20 35 40 slot

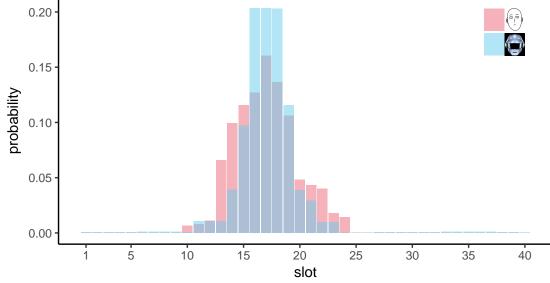
participant #27, observation 100, rel-entr. = 0.23, JS = 0.23



participant #27, observation 101, rel-entr. = 0.23, JS = 0.23 0.20 0.15



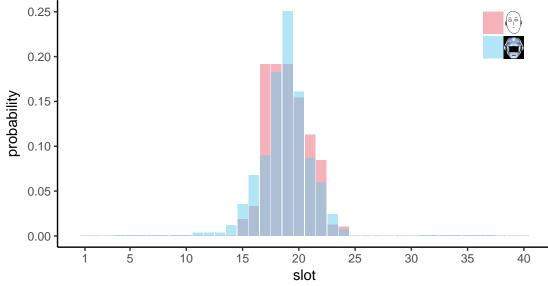
participant #27, observation 102, rel-entr. = 0.23, JS = 0.23



participant #27, observation 197, rel-entr. = 0.27, JS = 0.2 0.2 probability 0.0 10 20 15 25 30 35 40 slot

participant #27, observation 198, rel-entr. = 0.26, JS = 0.21 0.2 probability 0.0 10 25 15 20 30 35 40 slot

participant #27, observation 199, rel-entr. = 0.29, JS = 0.21



participant #27, observation 200, rel-entr. = 0.41, JS = 0.28 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot