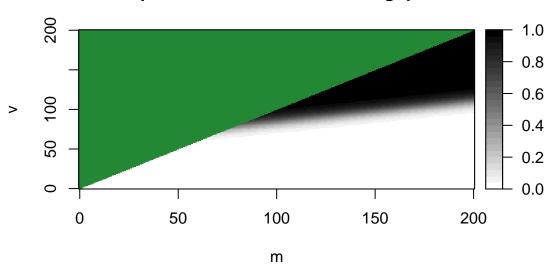
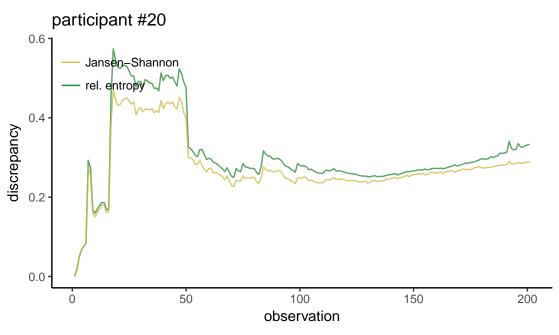
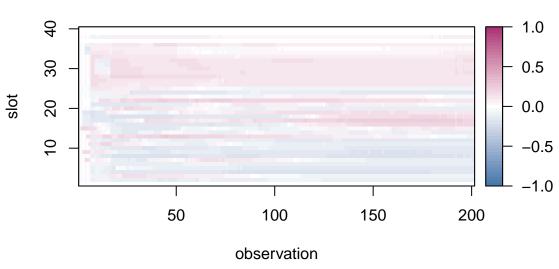


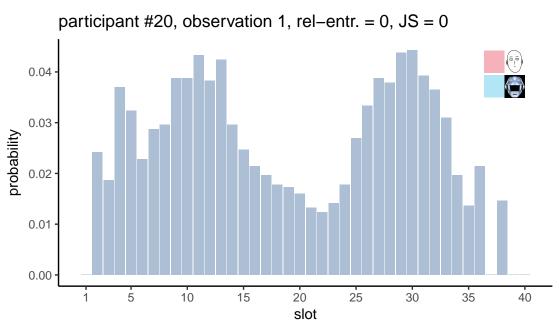
part. #20, stub. = 27.3, changepoint:



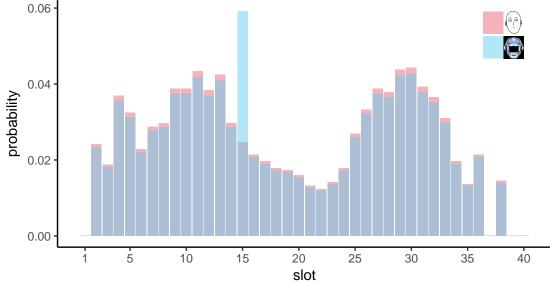


participant #20, sqrt(robot-participant)

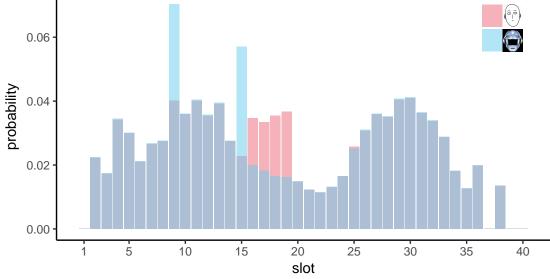




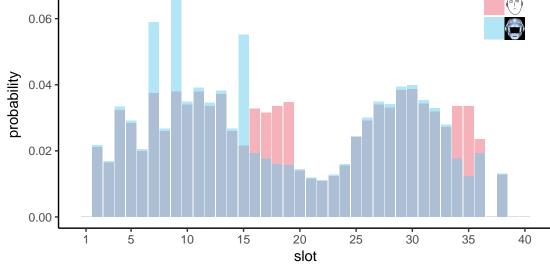
participant #20, observation 2, rel-entr. = 0.018, JS = 0.016



participant #20, observation 3, rel-entr. = 0.049, JS = 0.048 0.06 probability 0.04

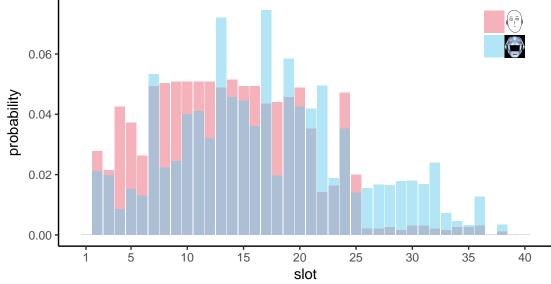


participant #20, observation 4, rel-entr. = 0.066, JS = 0.067 0.06 0.04

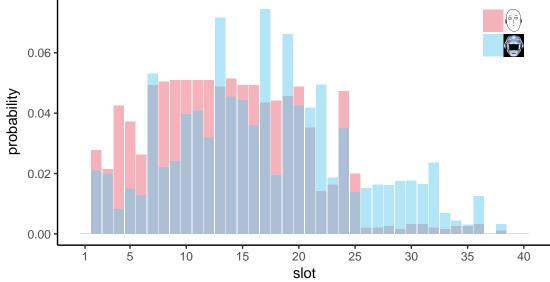


participant #20, observation 99, rel-entr. = 0.28, JS = 0.25 0.06 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

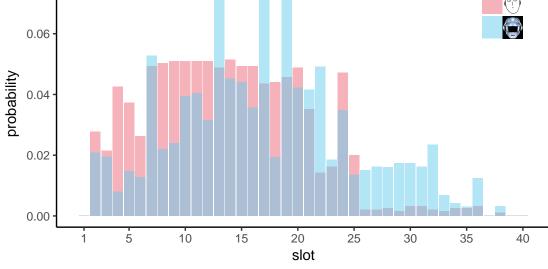
participant #20, observation 100, rel-entr. = 0.28, JS = 0.25

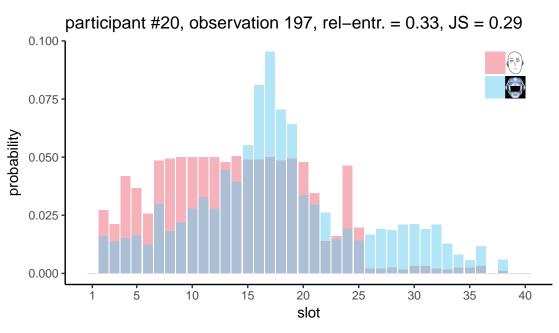


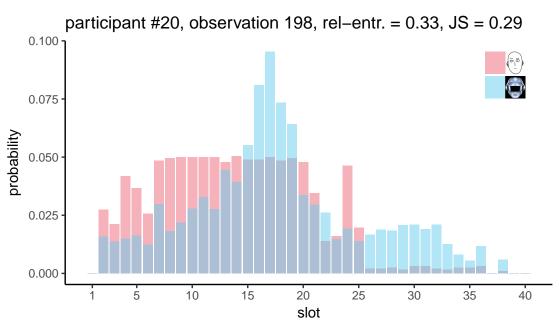
participant #20, observation 101, rel-entr. = 0.28, JS = 0.25



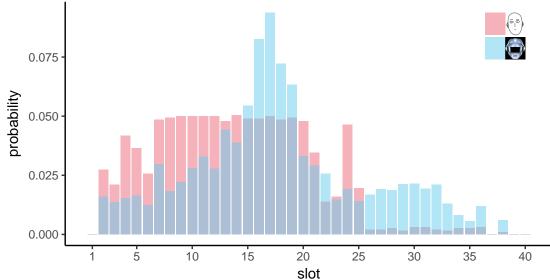
participant #20, observation 102, rel-entr. = 0.28, JS = 0.25 0.06 probability







participant #20, observation 199, rel-entr. = 0.33, JS = 0.29



participant #20, observation 200, rel-entr. = 0.33, JS = 0.29

