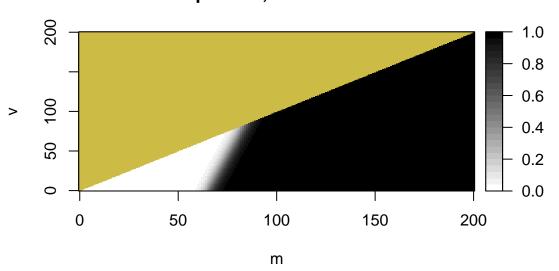
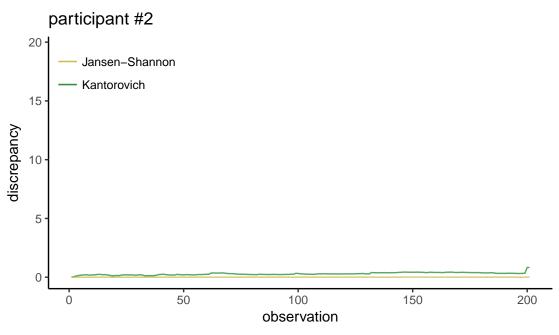


## h for part. #2, stubbornness = 240





## participant #2, sqrt(robot-participant)

