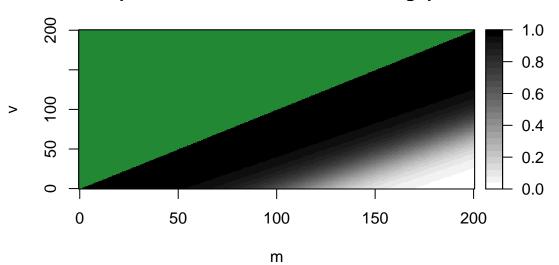
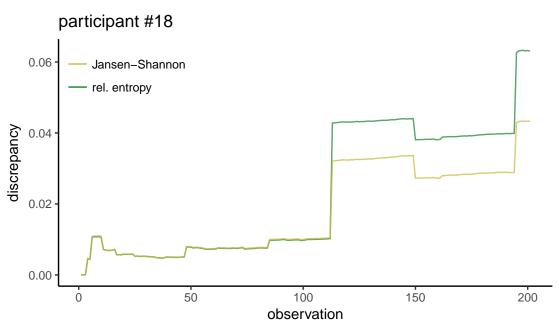
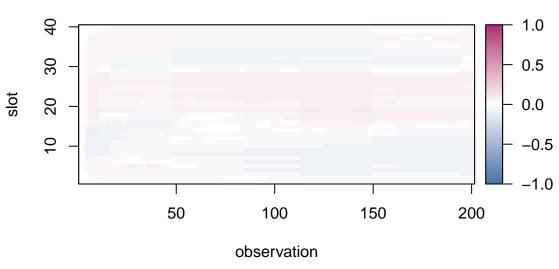


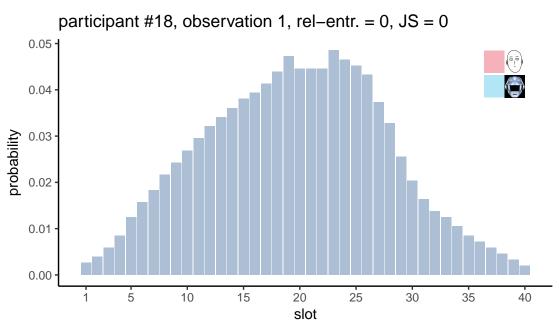
part. #18, stub. = 1.17e+03, changepoint:



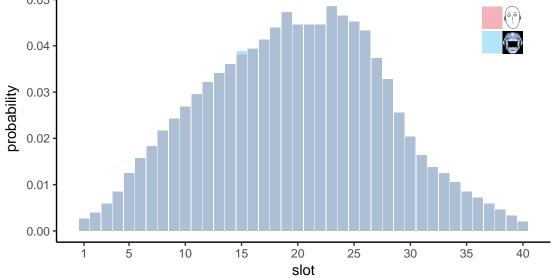


participant #18, sqrt(robot-participant)

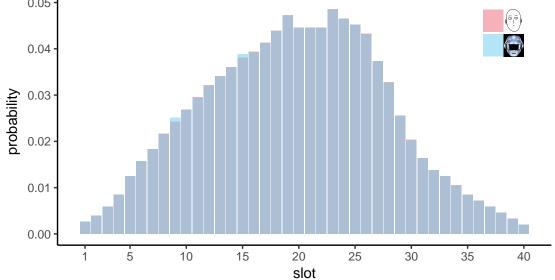


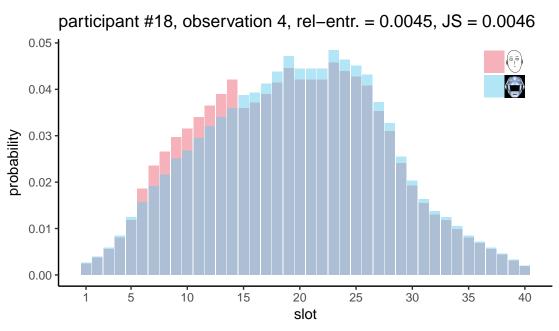


participant #18, observation 2, rel-entr. = 9.2e-06, JS = 9.1e-06 0.05



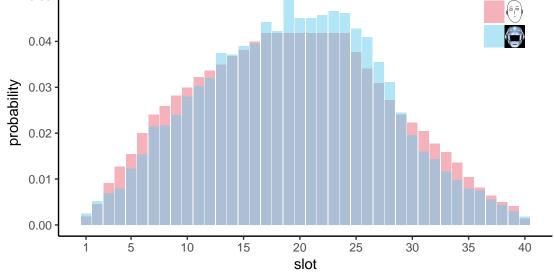
participant #18, observation 3, rel-entr. = 2.3e-05, JS = 2.3e-05 0.05



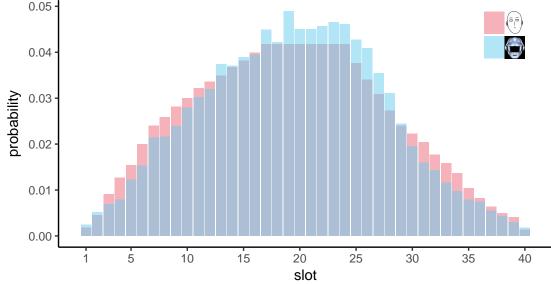


0.05 -0.04

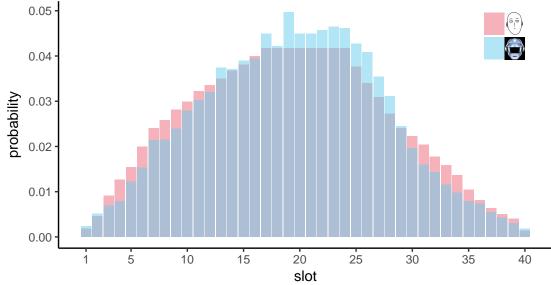
participant #18, observation 99, rel-entr. = 0.0097, JS = 0.0099



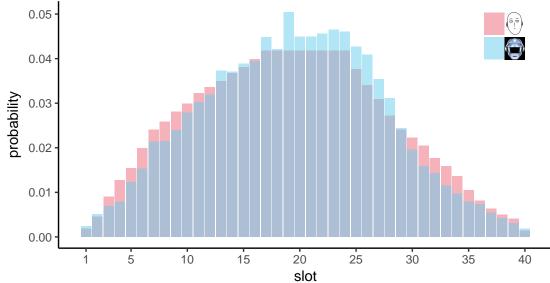
participant #18, observation 100, rel-entr. = 0.0097, JS = 0.01



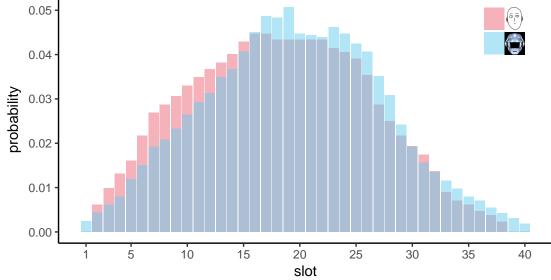
participant #18, observation 101, rel-entr. = 0.0099, JS = 0.01 0.05 -



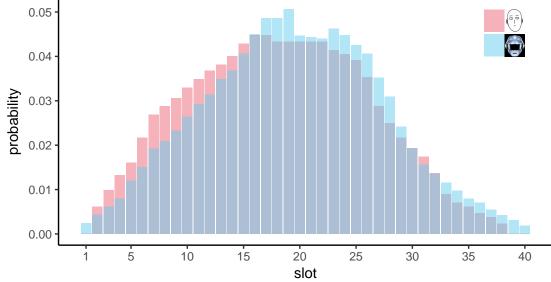
participant #18, observation 102, rel-entr. = 0.01, JS = 0.01



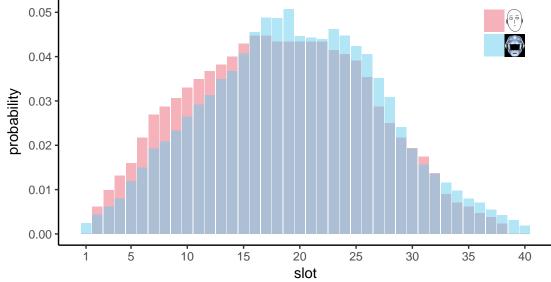
participant #18, observation 197, rel-entr. = 0.063, JS = 0.043 $0.05 \frac{1}{2}$



participant #18, observation 198, rel-entr. = 0.063, JS = 0.043



participant #18, observation 199, rel-entr. = 0.063, JS = 0.043



participant #18, observation 200, rel-entr. = 0.063, JS = 0.043 $0.05 - \frac{1}{100}$

