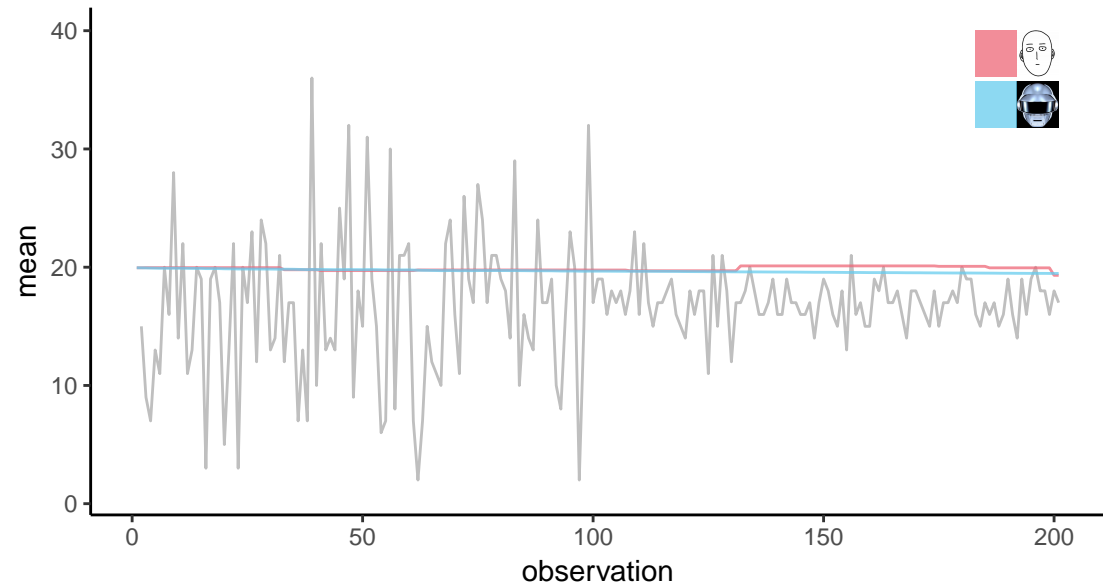
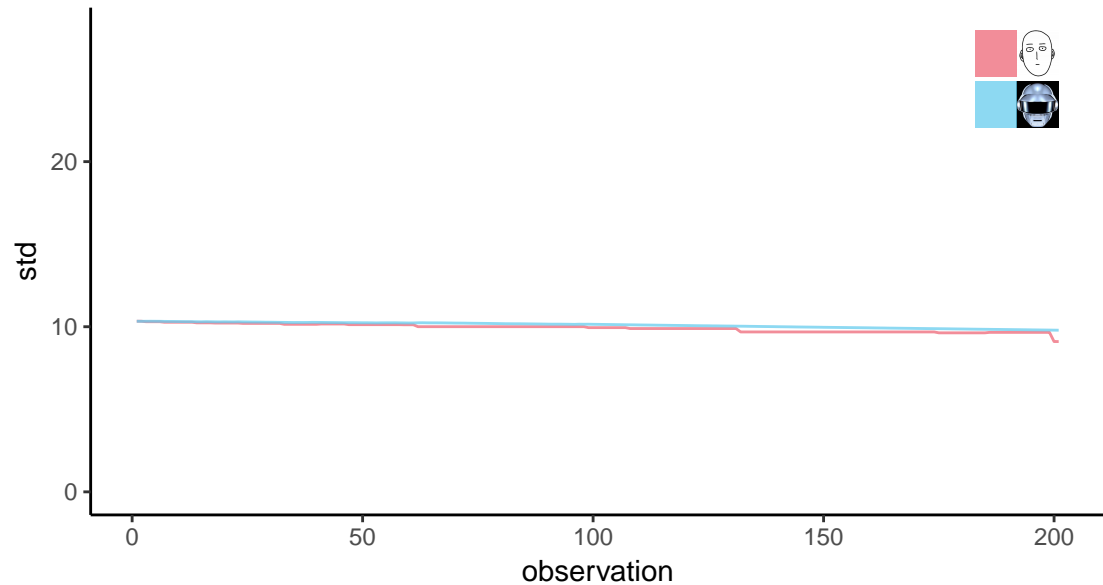


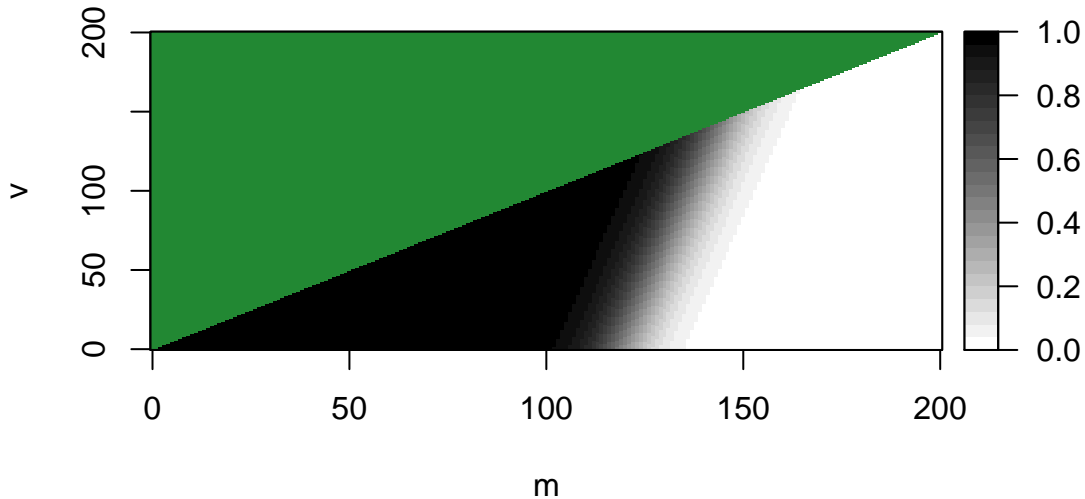
participant #2, means (black: plinko outcomes)



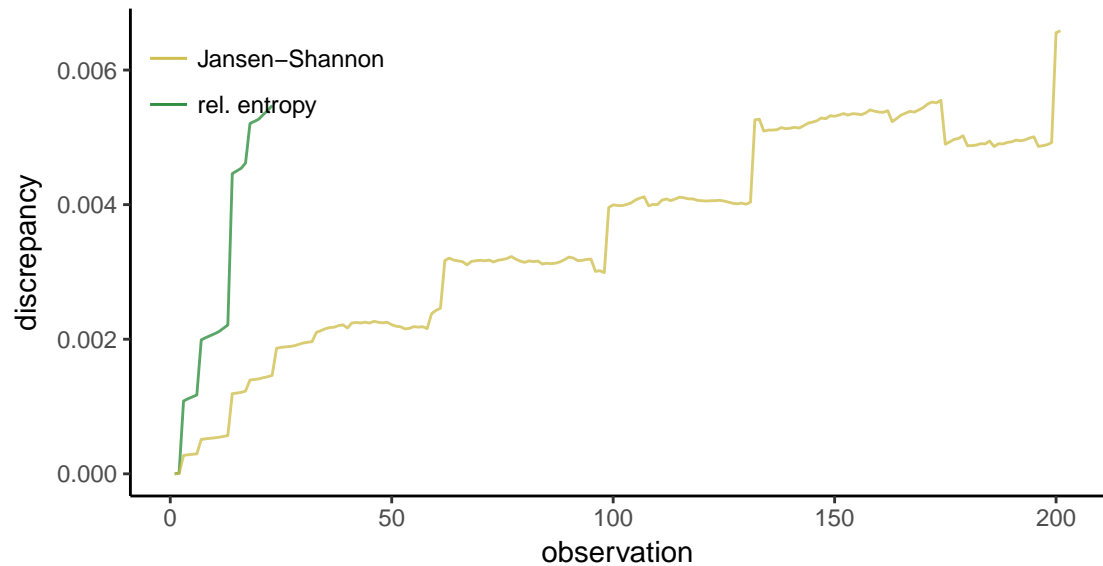
participant #2, st. deviations



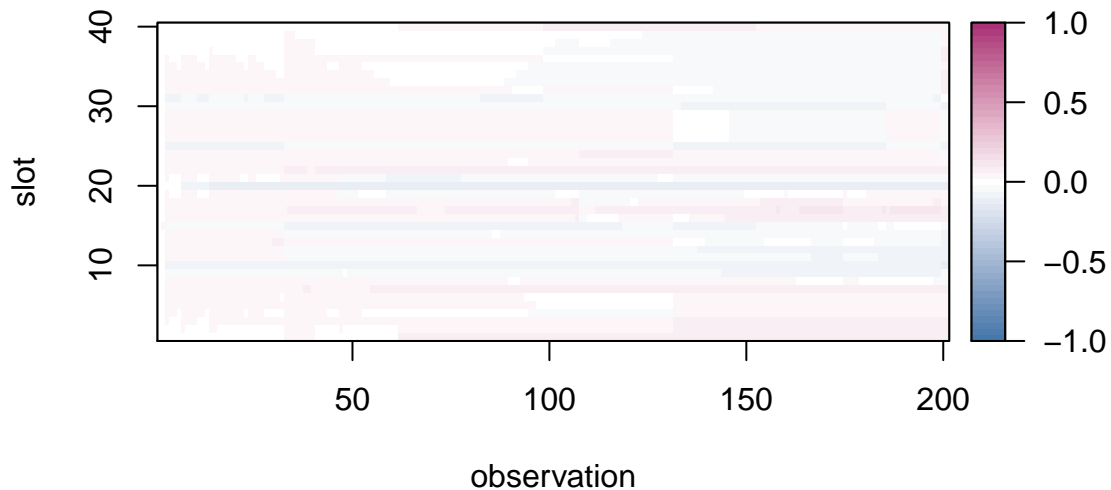
**part. #2, stub. = 1.12e+03, changepoint:**



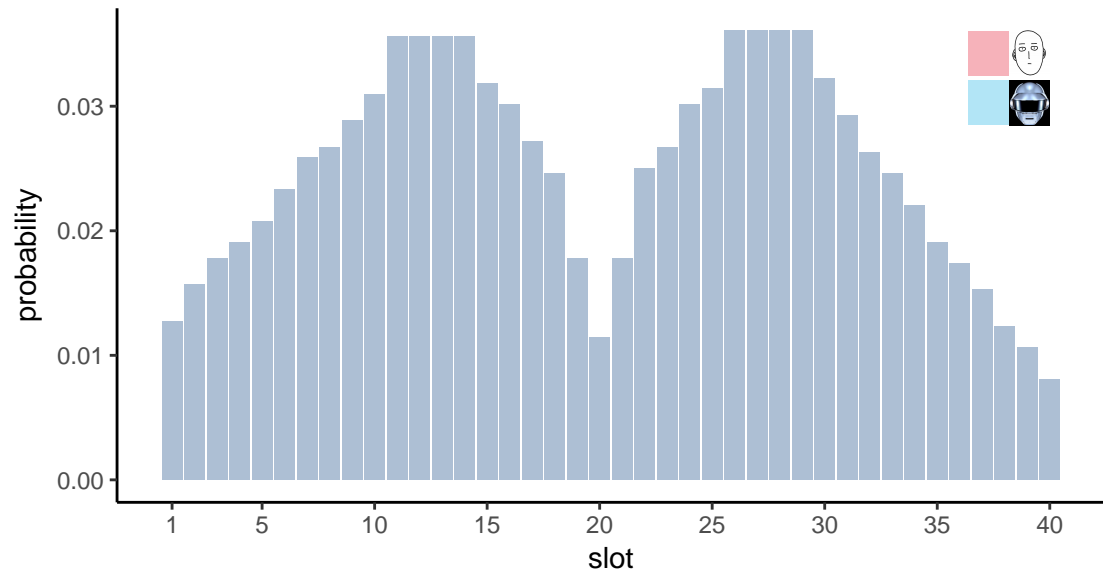
## participant #2



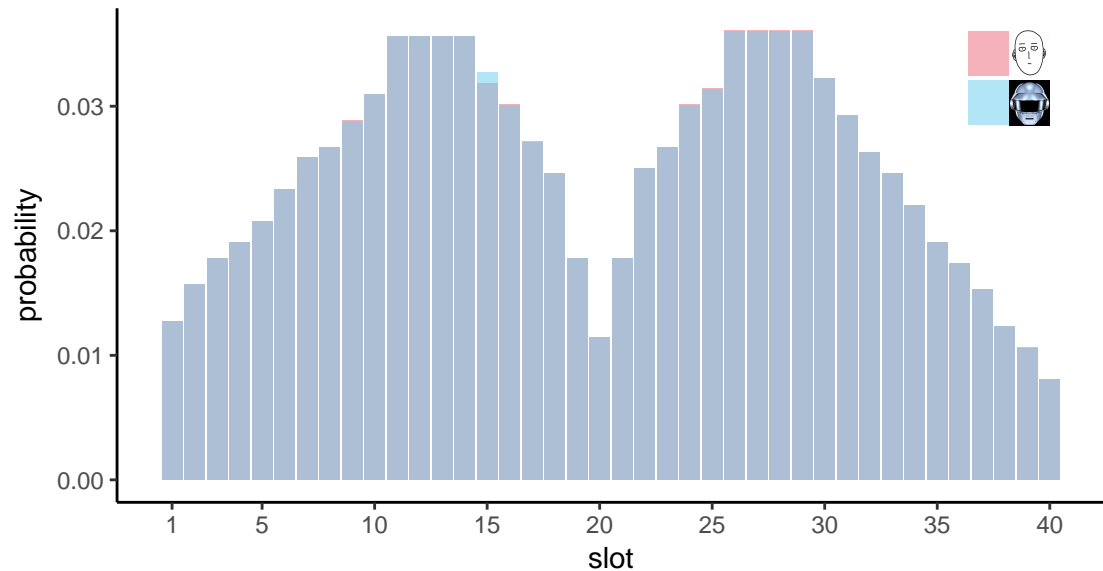
## participant #2, $\sqrt{\text{robot-participant}}$



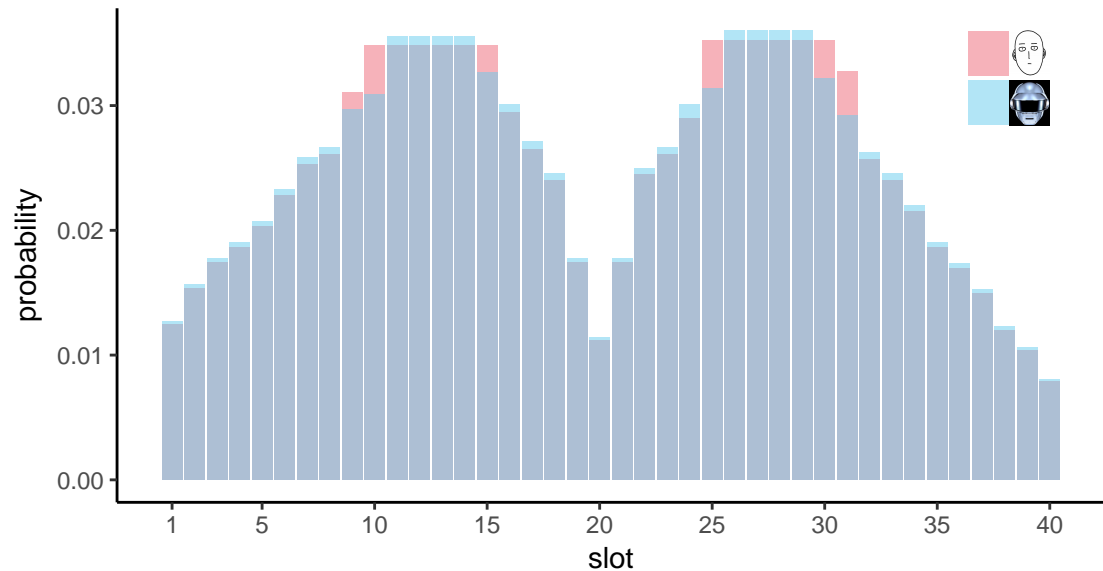
participant #2, observation 1, rel-entr. = 0, JS = 0



participant #2, observation 2, rel-entr. =  $1.2\text{e-}05$ , JS =  $3\text{e-}06$

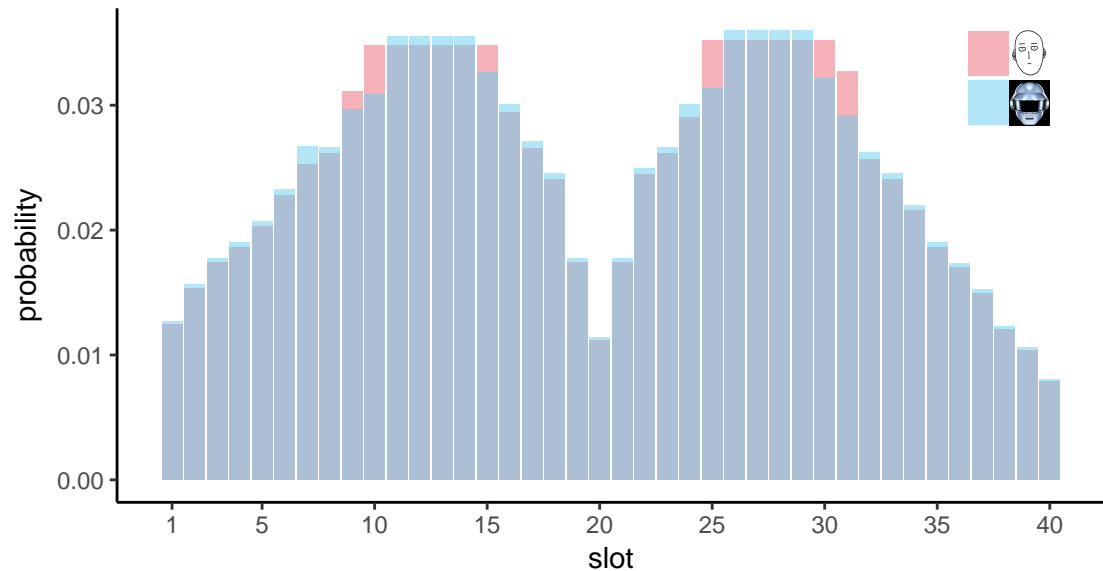


participant #2, observation 3, rel-entr. = 0.0011, JS = 0.00027

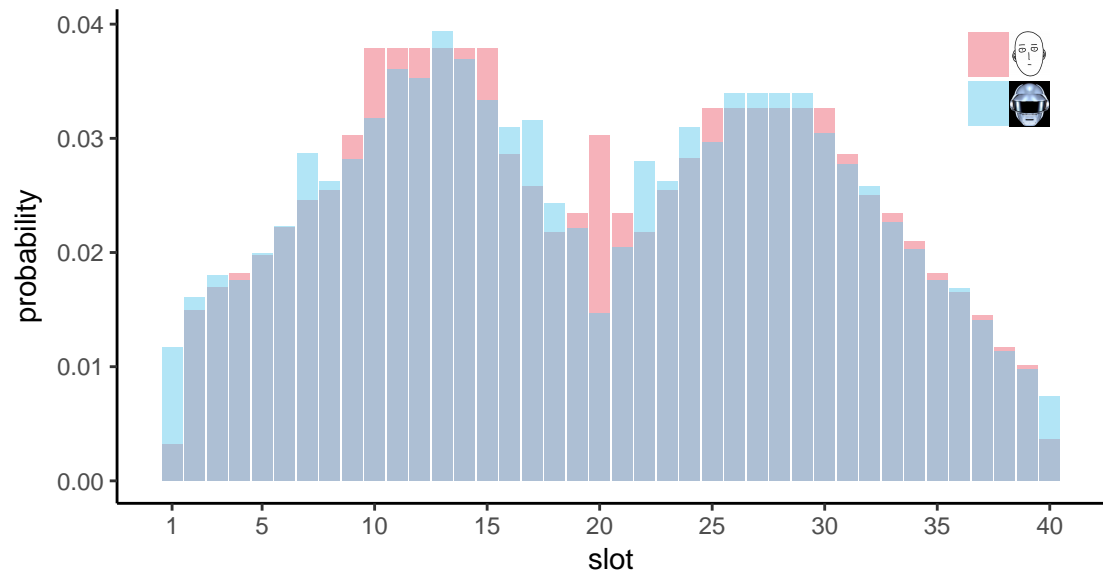




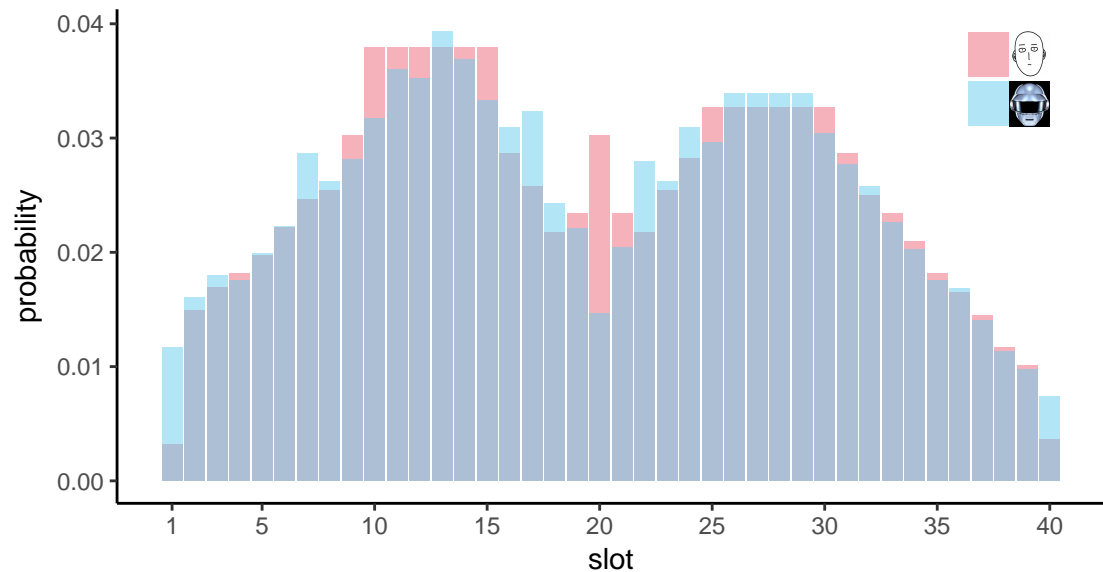
participant #2, observation 4, rel-entr. = 0.0011, JS = 0.00028



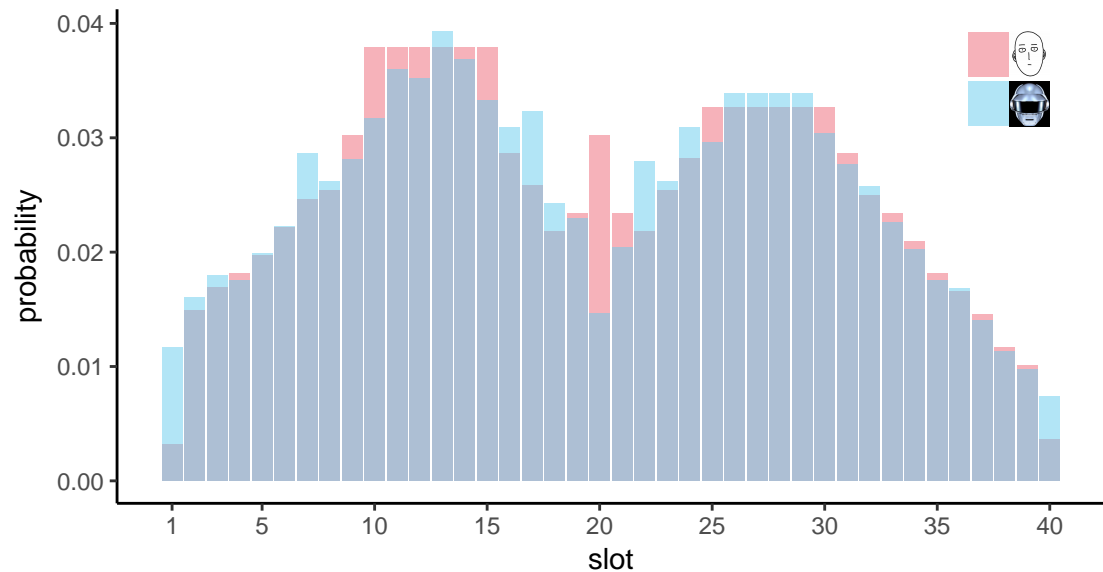
participant #2, observation 99, rel-entr. = 0.017, JS = 0.004



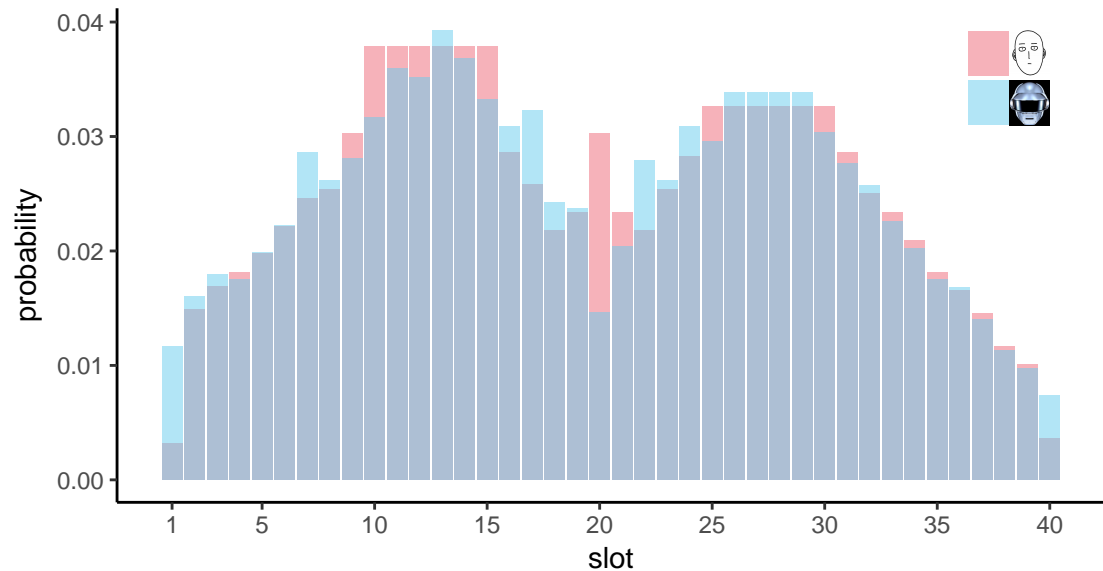
participant #2, observation 100, rel-entr. = 0.017, JS = 0.004



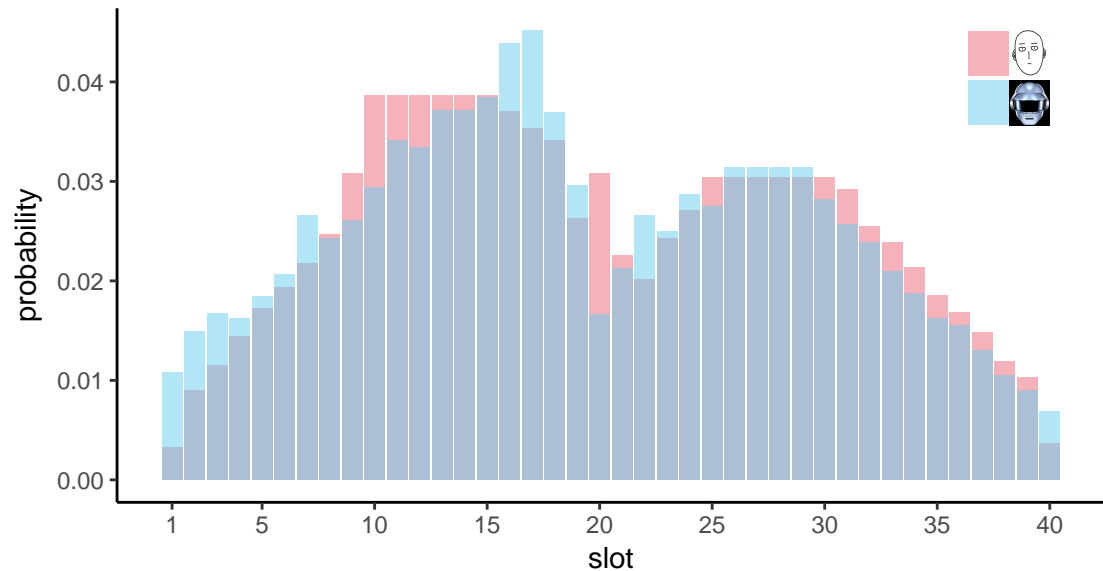
participant #2, observation 101, rel-entr. = 0.017, JS = 0.004



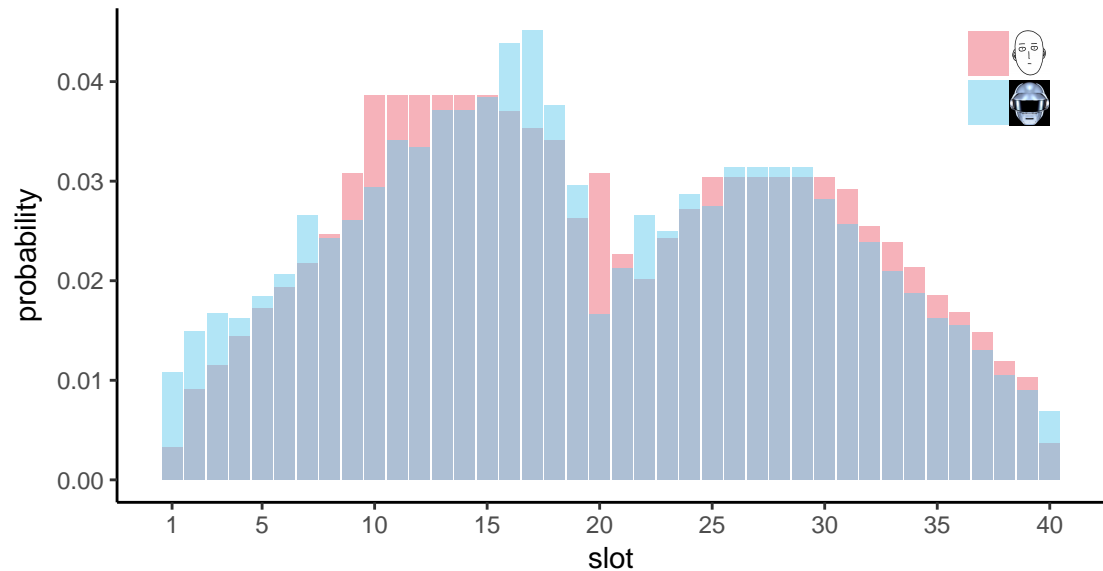
participant #2, observation 102, rel-entr. = 0.017, JS = 0.004



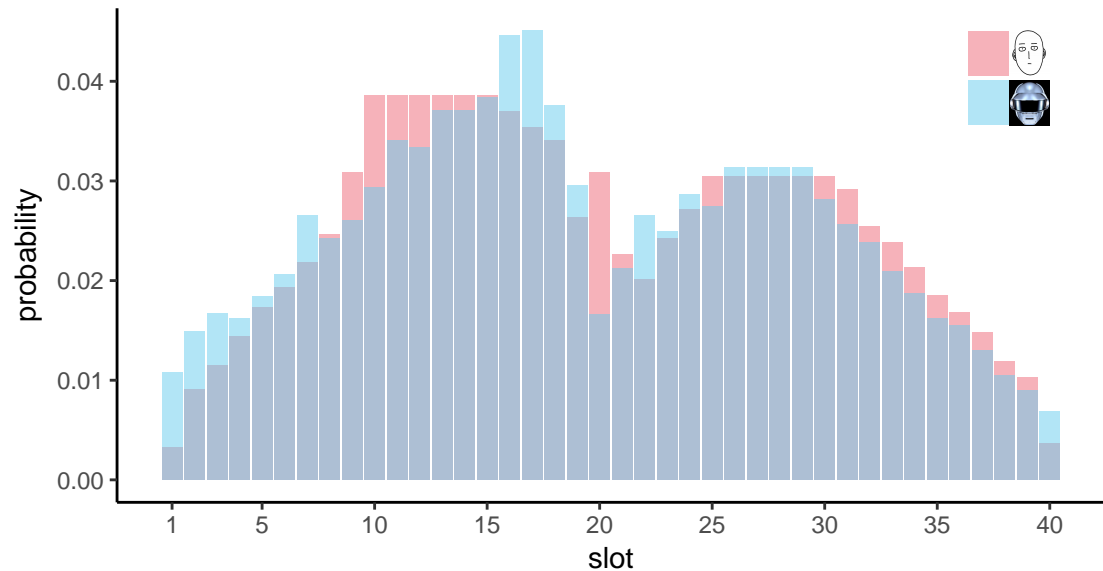
participant #2, observation 197, rel-entr. = 0.021, JS = 0.0049



participant #2, observation 198, rel-entr. = 0.021, JS = 0.0049



participant #2, observation 199, rel-entr. = 0.021, JS = 0.0049





participant #2, observation 200, rel-entr. = 0.027, JS = 0.0066

