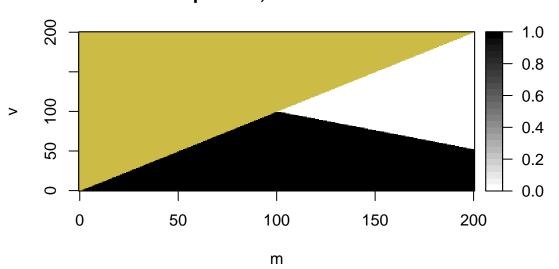
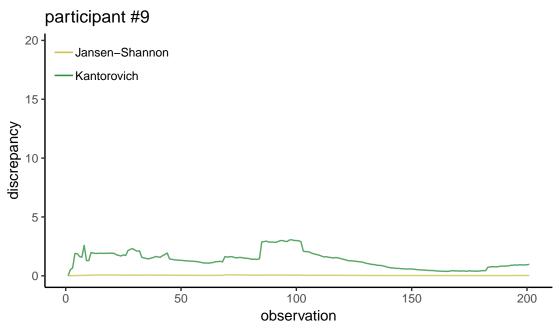
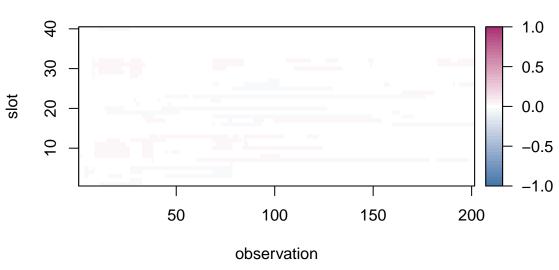


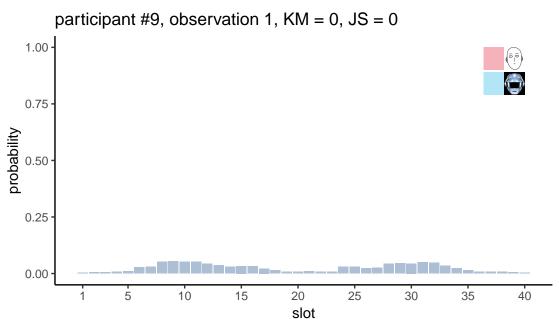
h for part. #9, stubbornness = 31.7

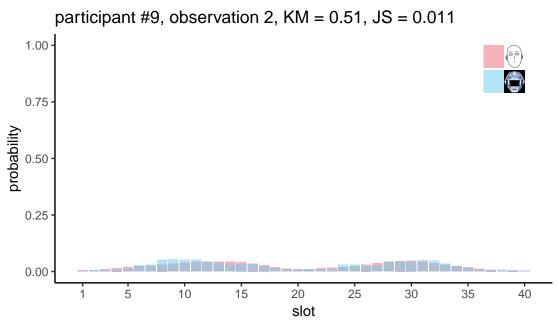


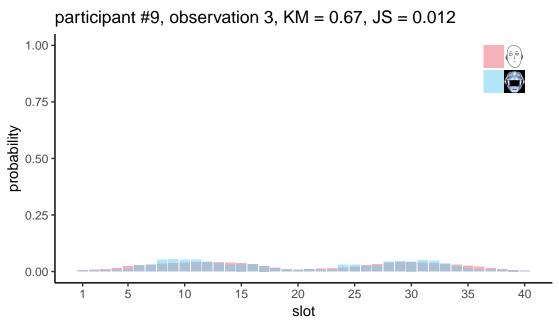


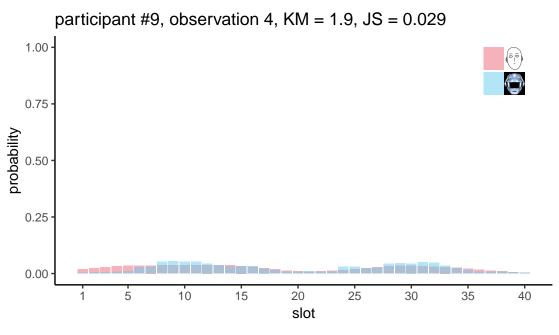
participant #9, sqrt(robot-participant)

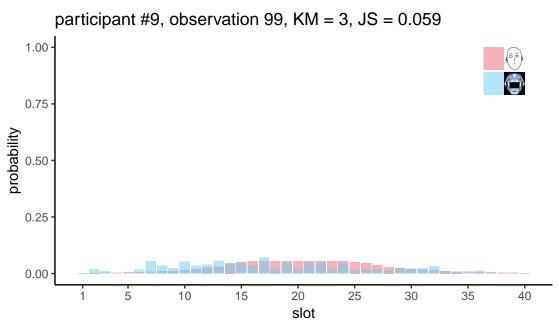


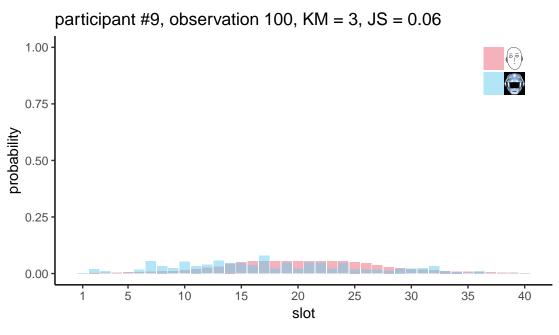


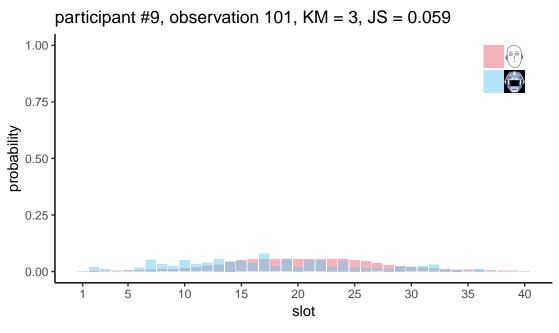


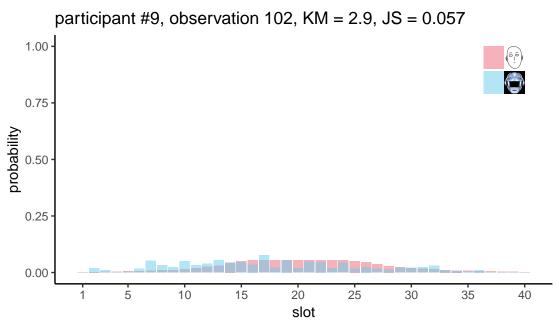


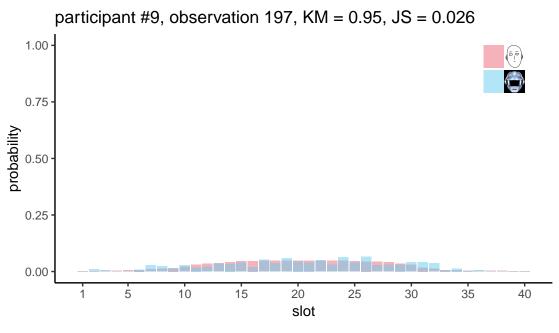


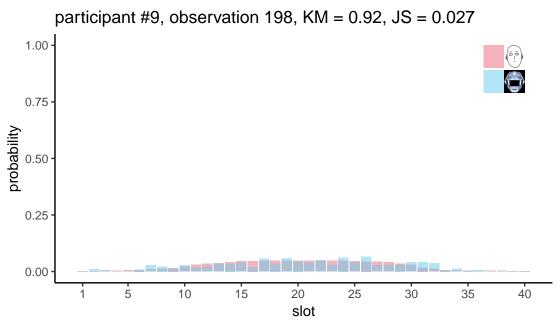












participant #9, observation 199, KM = 0.93, JS = 0.027 1.00 0.75 probability 0.25 0.00 5 10 15 20 25 30 35 40 slot

participant #9, observation 200, KM = 0.94, JS = 0.027 1.00 0.75 probability 0.25 0.00 5 10 15 20 25 30 35 40 slot