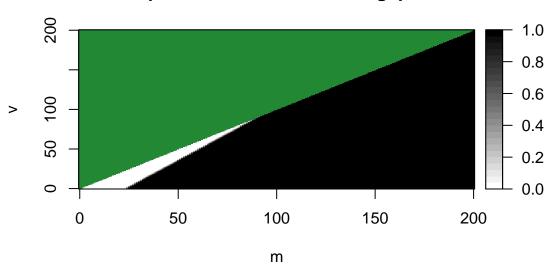
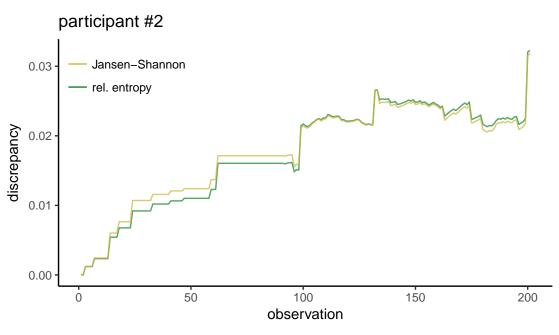
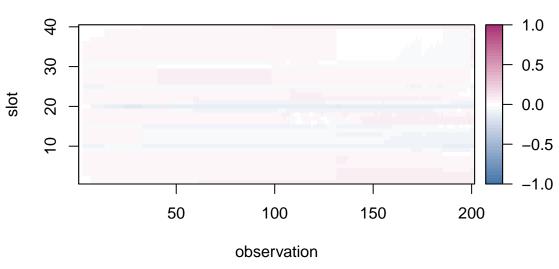


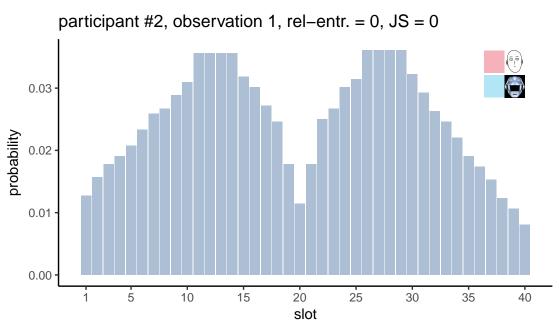
part. #2, stub. = 592, changepoint:



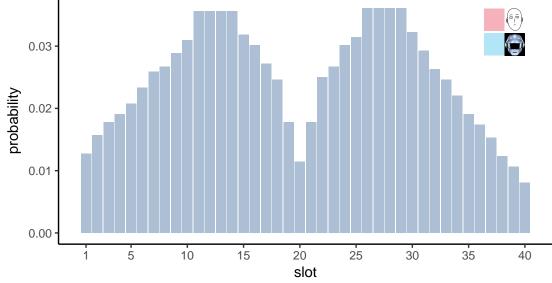


participant #2, sqrt(robot-participant)

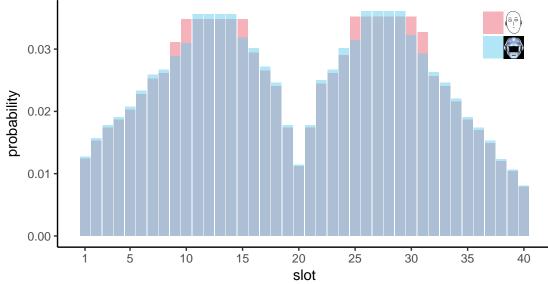




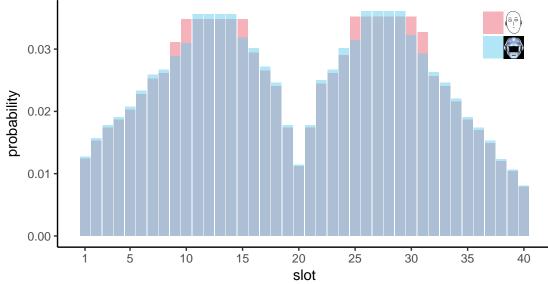
participant #2, observation 2, rel-entr. = 6.6e-19, JS = 3.1e-18



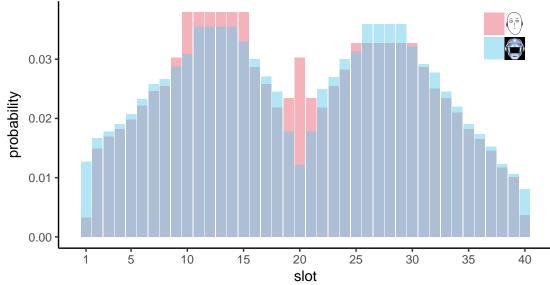
participant #2, observation 3, rel-entr. = 0.0012, JS = 0.0012



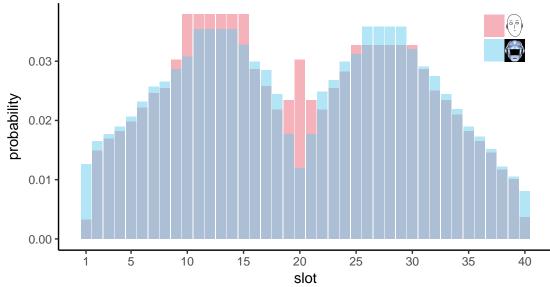
participant #2, observation 4, rel-entr. = 0.0012, JS = 0.0012



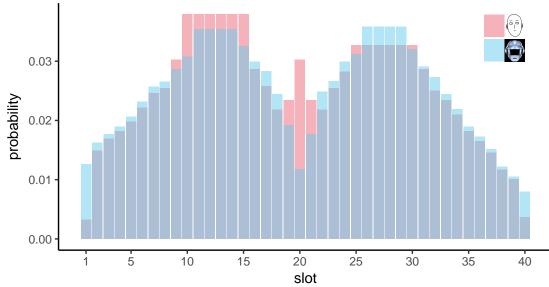
participant #2, observation 99, rel-entr. = 0.021, JS = 0.021



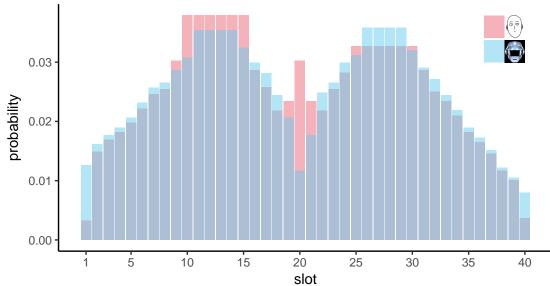
participant #2, observation 100, rel-entr. = 0.022, JS = 0.021



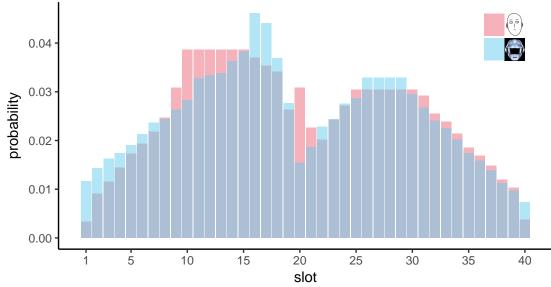
participant #2, observation 101, rel-entr. = 0.021, JS = 0.021



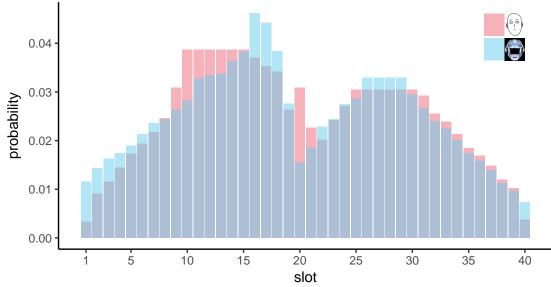
participant #2, observation 102, rel-entr. = 0.021, JS = 0.021



participant #2, observation 197, rel-entr. = 0.022, JS = 0.021



participant #2, observation 198, rel-entr. = 0.022, JS = 0.021



participant #2, observation 199, rel-entr. = 0.022, JS = 0.022 0.05 -0.04 probability 0.03 0.02 0.01 0.00 15 25 30 5 10 20 35 40 slot

participant #2, observation 200, rel-entr. = 0.032, JS = 0.032 0.05 -0.04 probability 0.03 0.02 0.01 0.00 15 25 30 5 10 20 35 40 slot