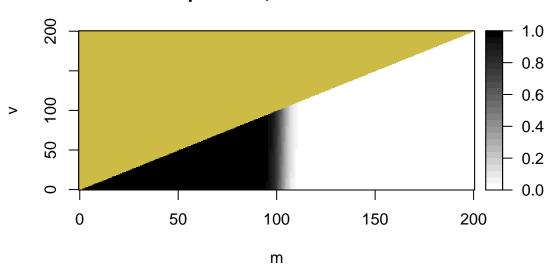
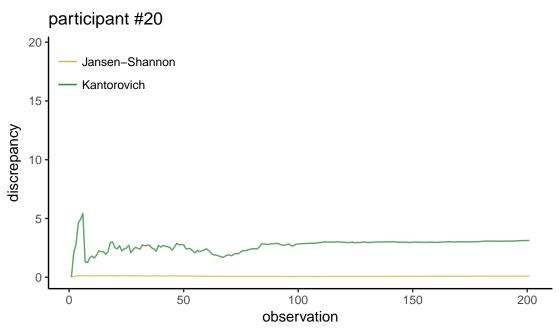


h for part. #20, stubbornness = 3.63





participant #20, sqrt(robot-participant)

