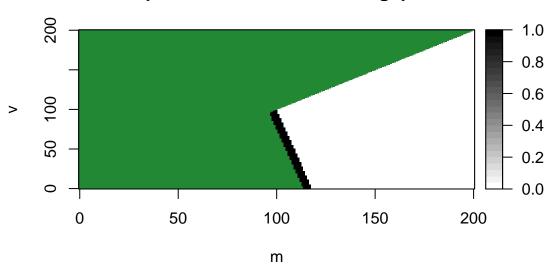
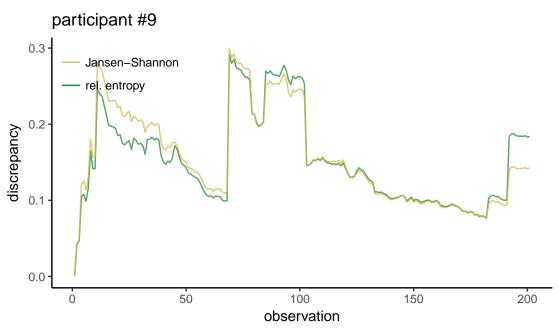
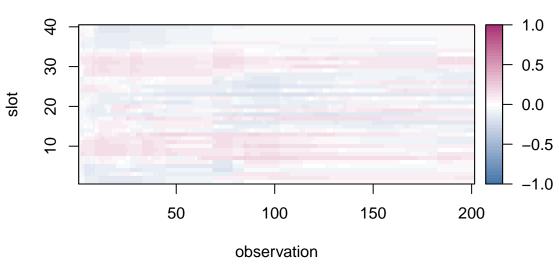


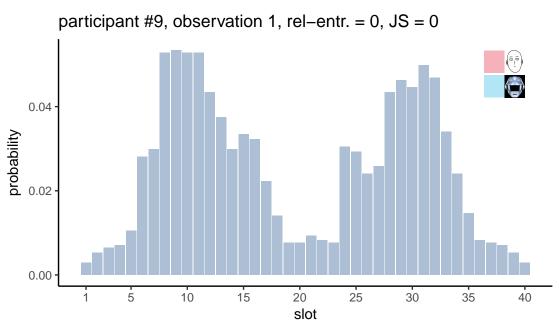
part. #9, stub. = 46.2, changepoint:



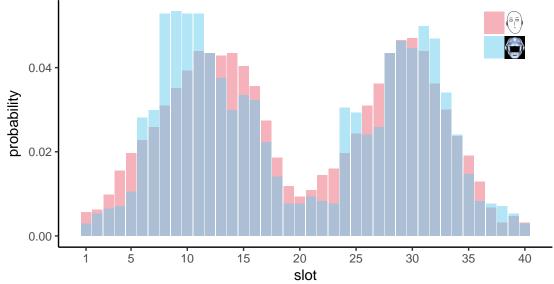


participant #9, sqrt(robot-participant)

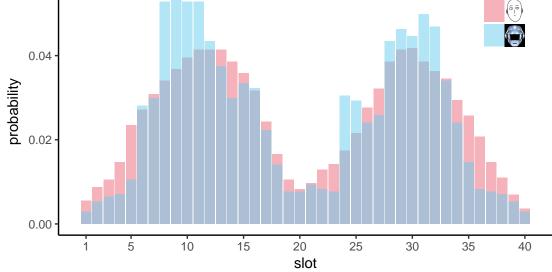




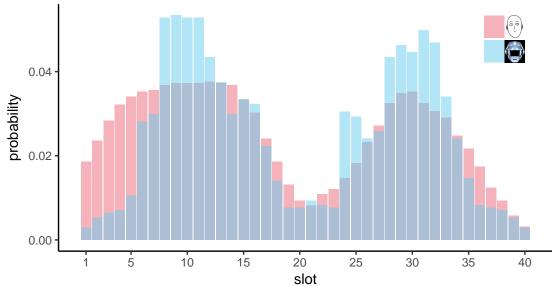
participant #9, observation 2, rel-entr. = 0.042, JS = 0.043

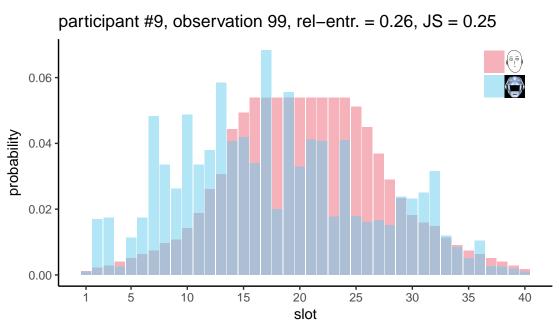


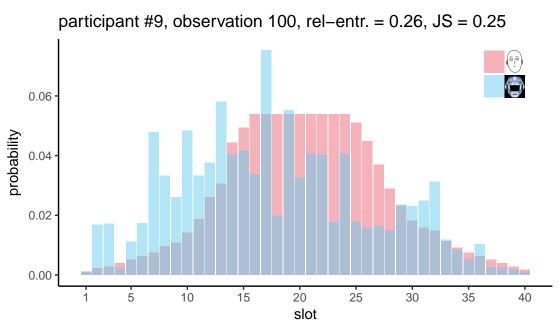
participant #9, observation 3, rel-entr. = 0.047, JS = 0.049



participant #9, observation 4, rel-entr. = 0.1, JS = 0.12







participant #9, observation 101, rel-entr. = 0.26, JS = 0.25 0.06 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #9, observation 102, rel-entr. = 0.25, JS = 0.24 0.06 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #9, observation 197, rel-entr. = 0.18, JS = 0.14 0.06 0.04 probability 0.02 0.00 15 25 30 5 10 20 35 40

slot

participant #9, observation 198, rel-entr. = 0.18, JS = 0.14 0.06 0.04 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #9, observation 199, rel-entr. = 0.18, JS = 0.14 0.06 probability 0.04 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #9, observation 200, rel-entr. = 0.18, JS = 0.14 0.06 probability 0.04 0.02 0.00 15 25 30 5 10 20 35 40 slot