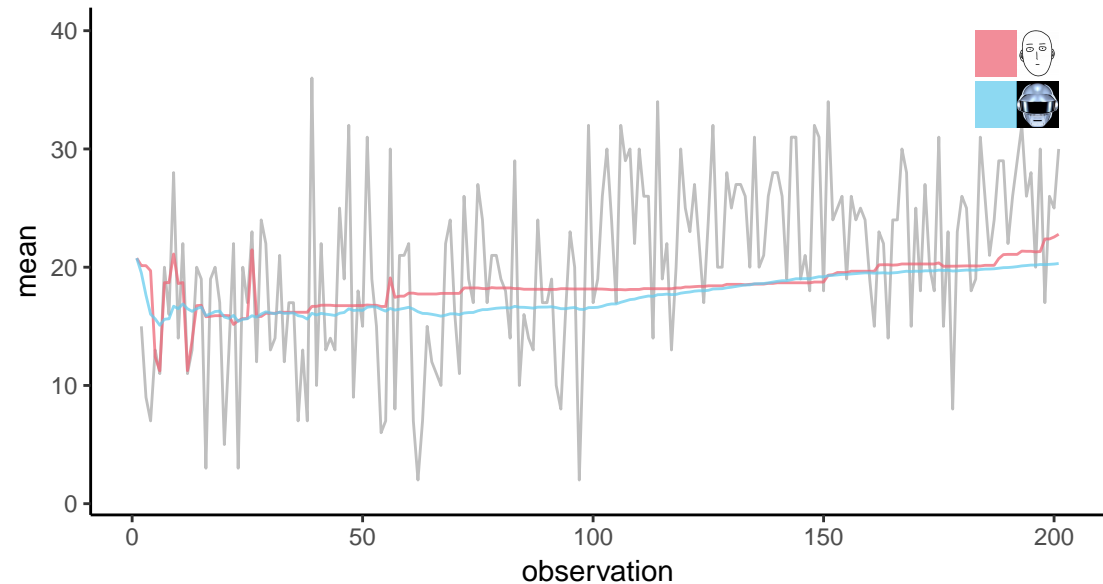
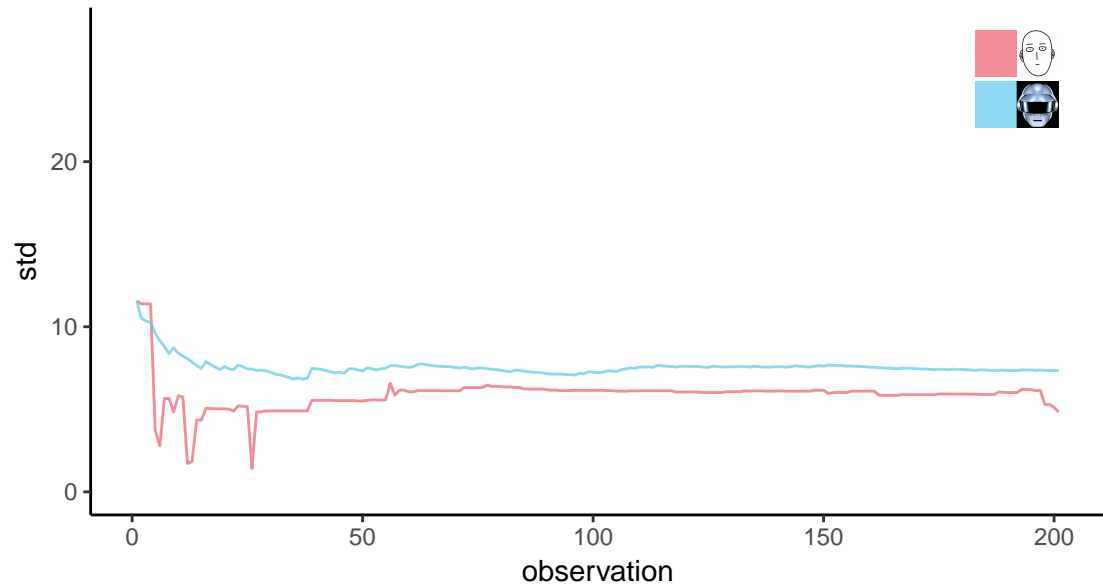


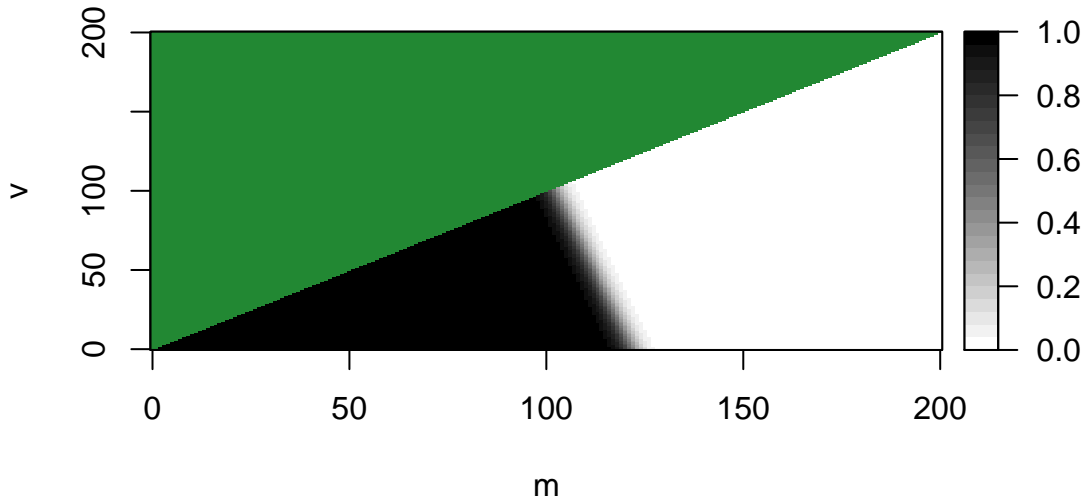
participant #1, means (black: plinko outcomes)



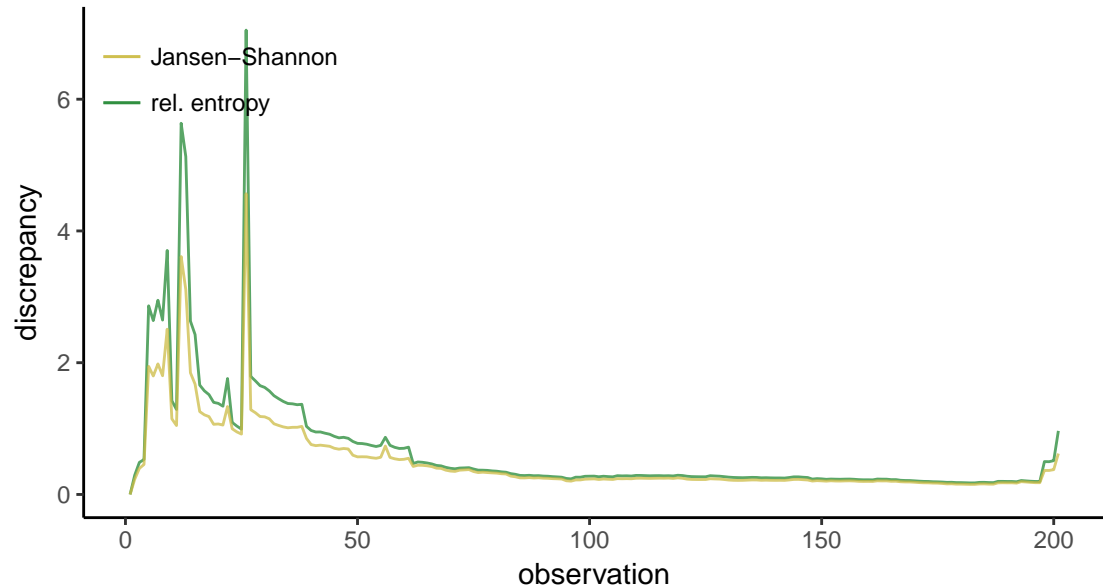
participant #1, st. deviations



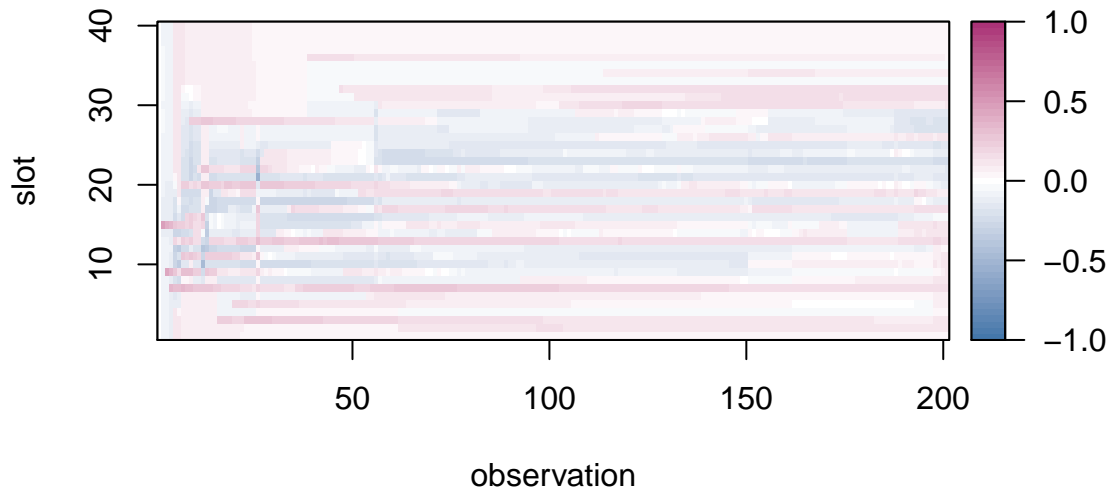
part. #1, stub. = 3.6, changepoint:



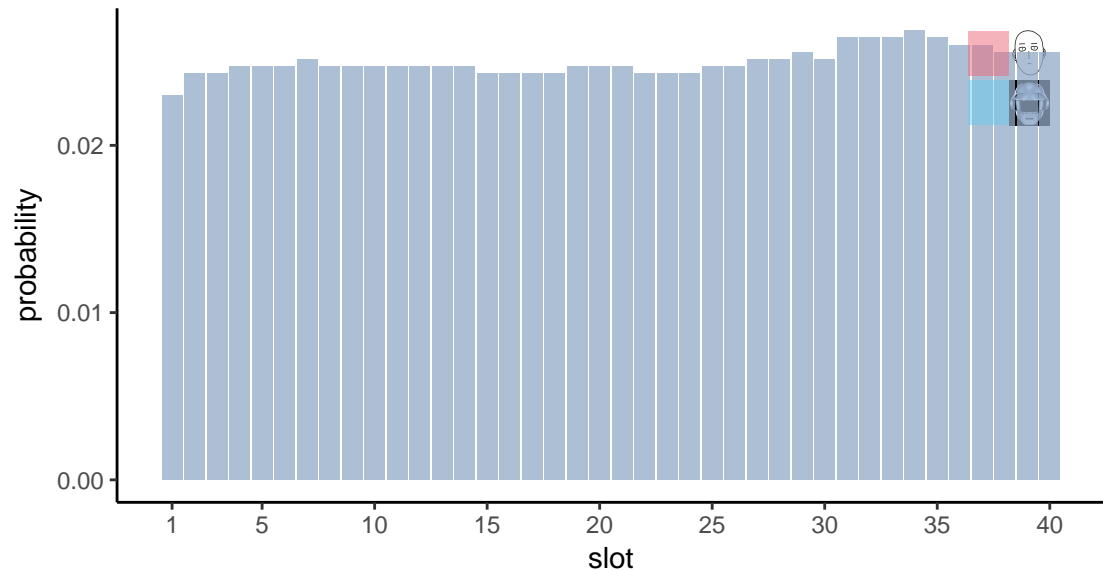
participant #1



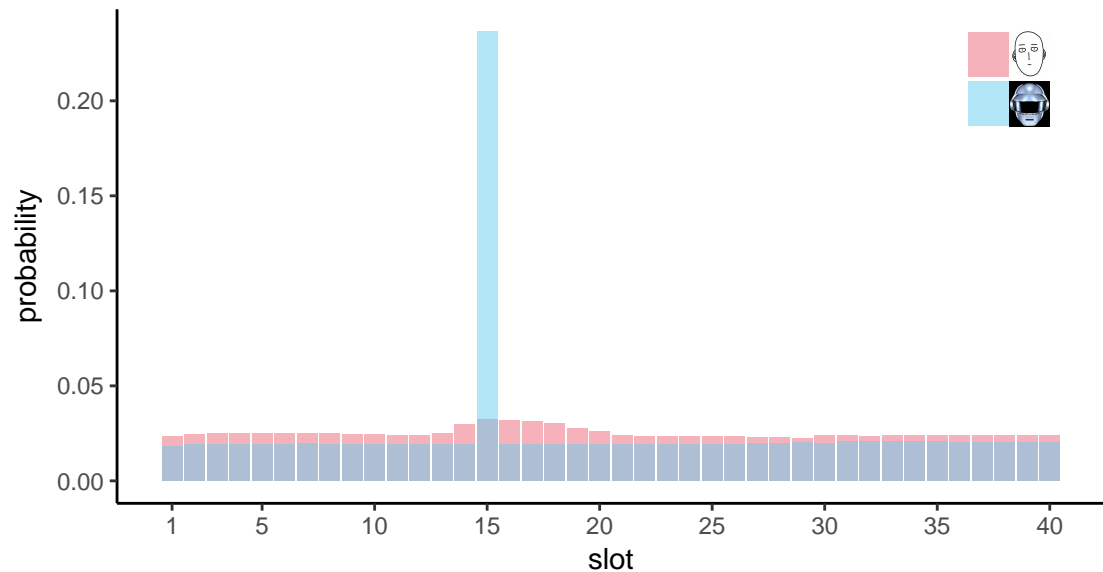
participant #1, $\sqrt{\text{robot-participant}}$



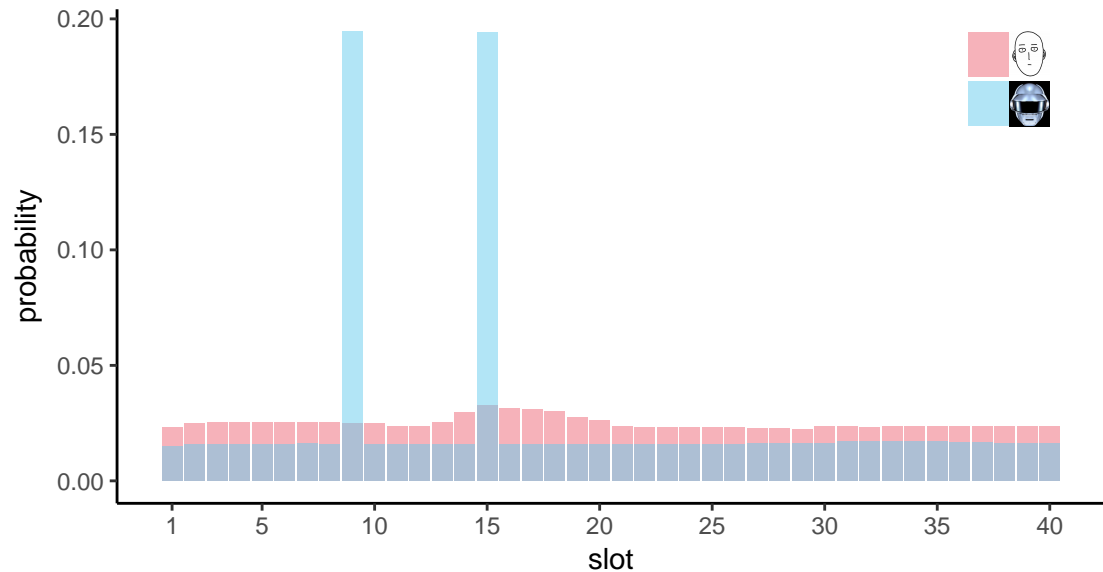
participant #1, observation 1, rel-entr. = 0, JS = 0



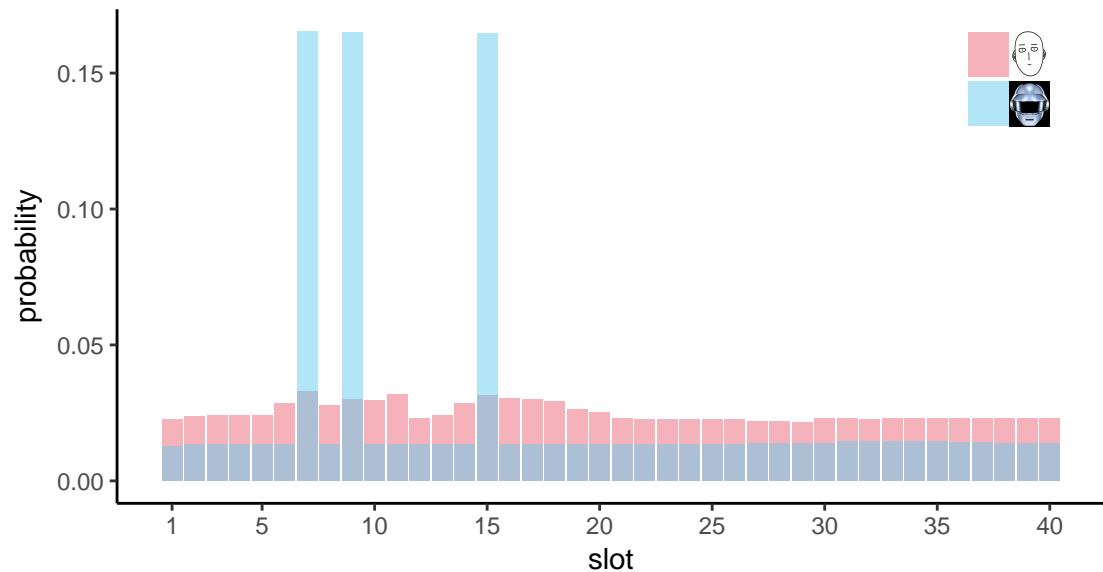
participant #1, observation 2, rel-entr. = 0.29, JS = 0.23



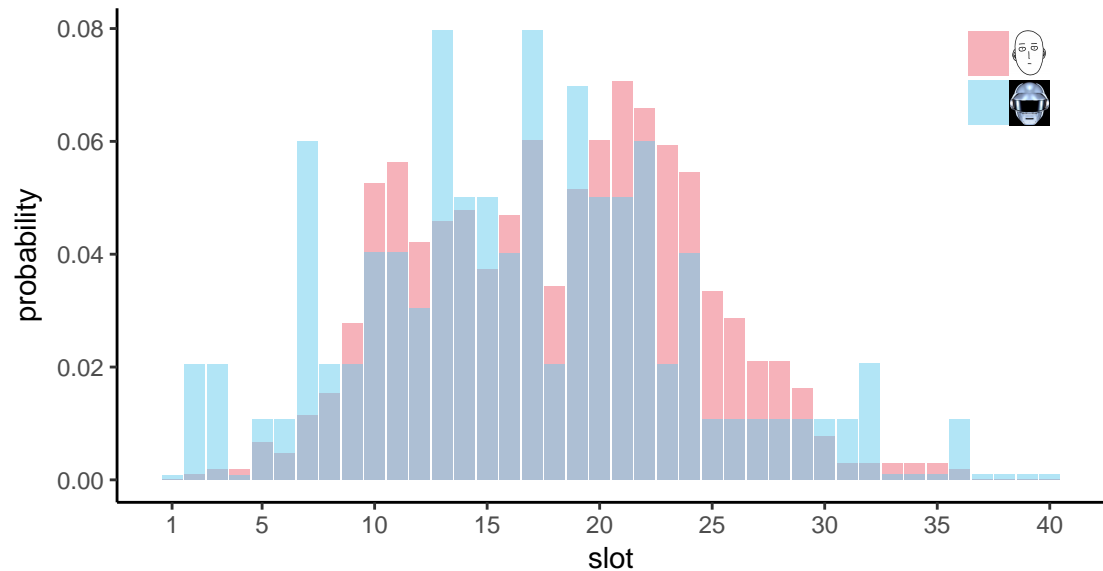
participant #1, observation 3, rel-entr. = 0.49, JS = 0.4



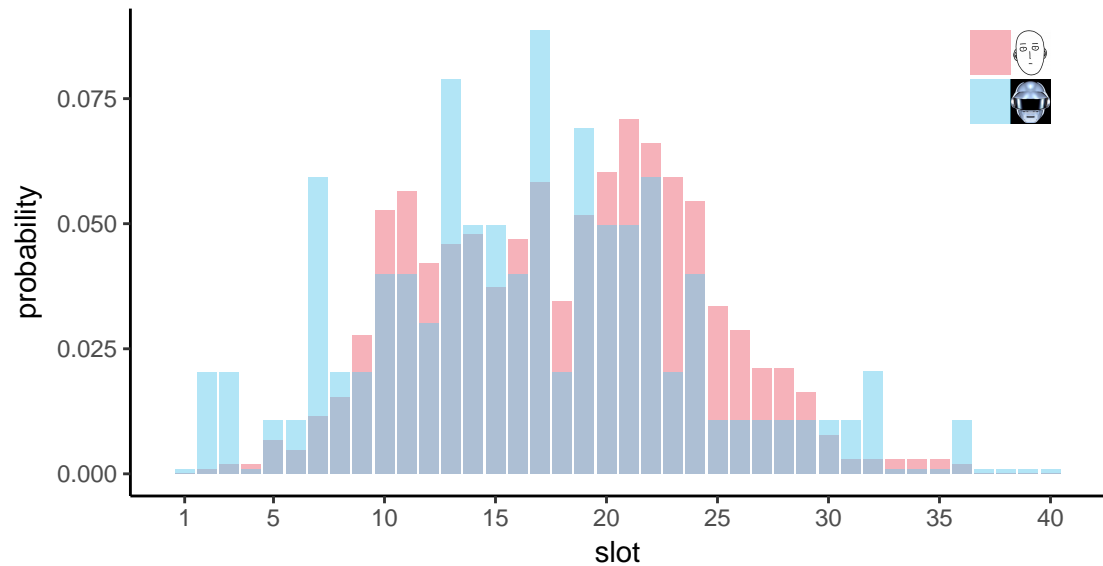
participant #1, observation 4, rel-entr. = 0.53, JS = 0.46



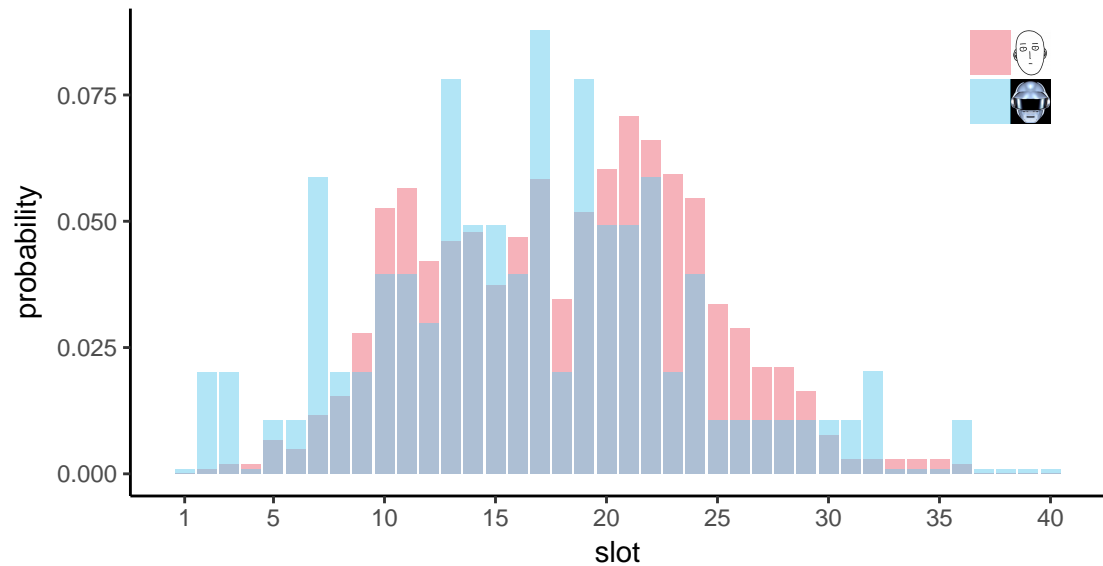
participant #1, observation 99, rel-entr. = 0.28, JS = 0.23



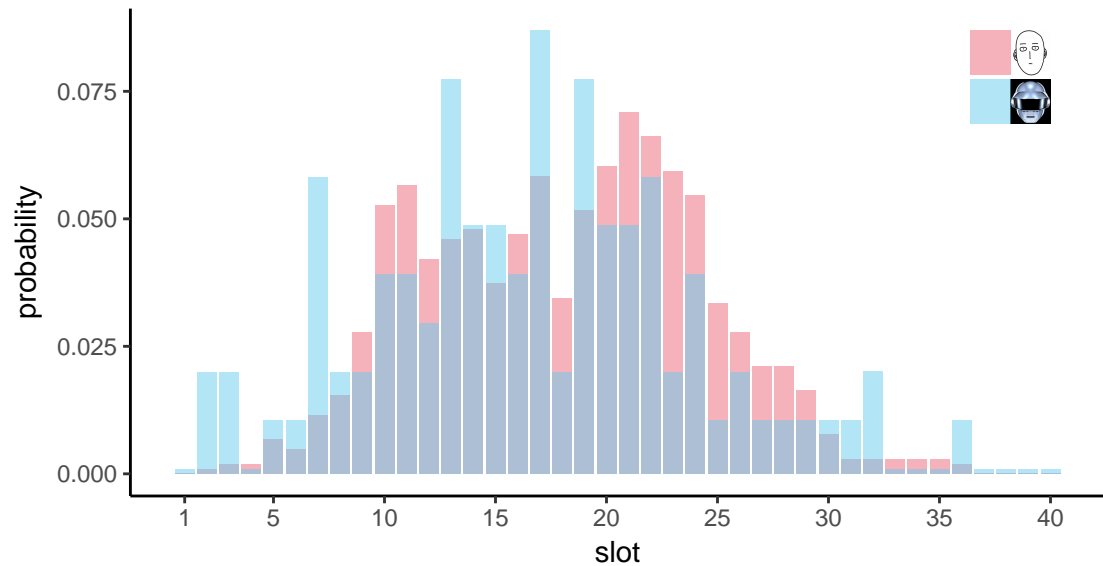
participant #1, observation 100, rel-entr. = 0.28, JS = 0.23



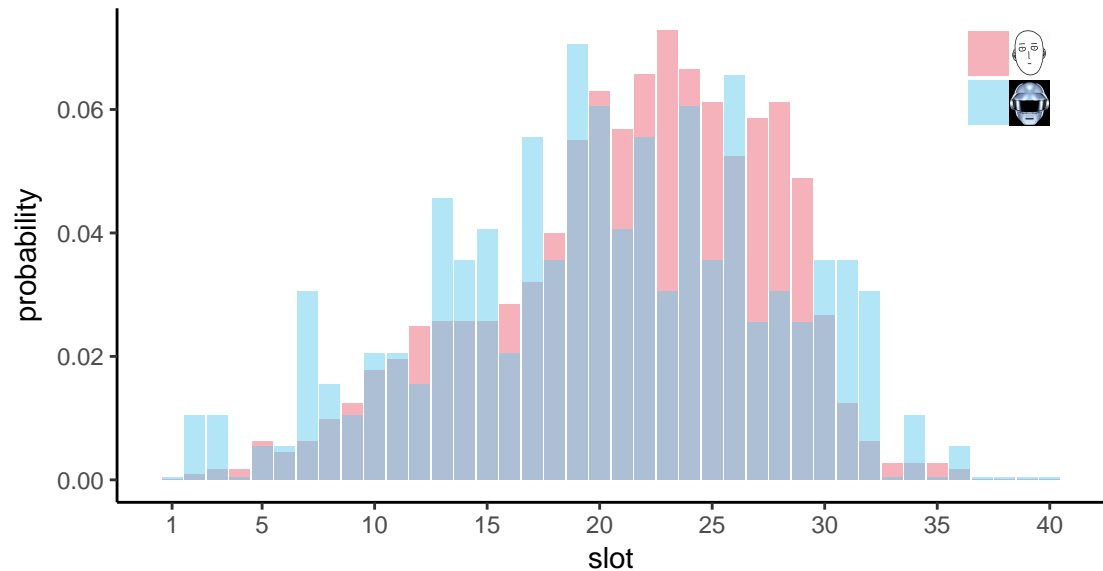
participant #1, observation 101, rel-entr. = 0.28, JS = 0.24



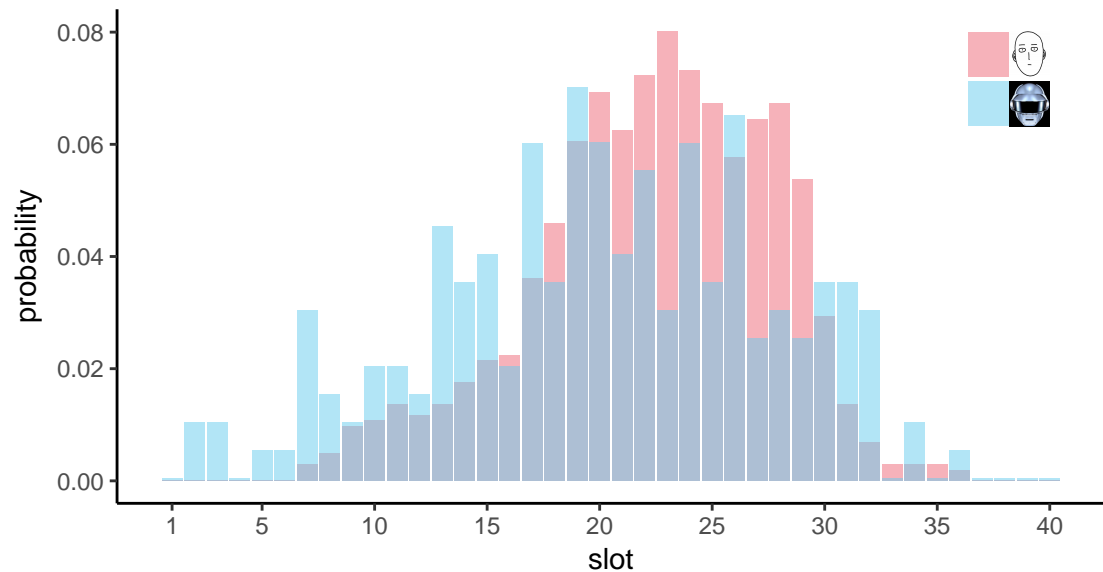
participant #1, observation 102, rel-entr. = 0.27, JS = 0.23



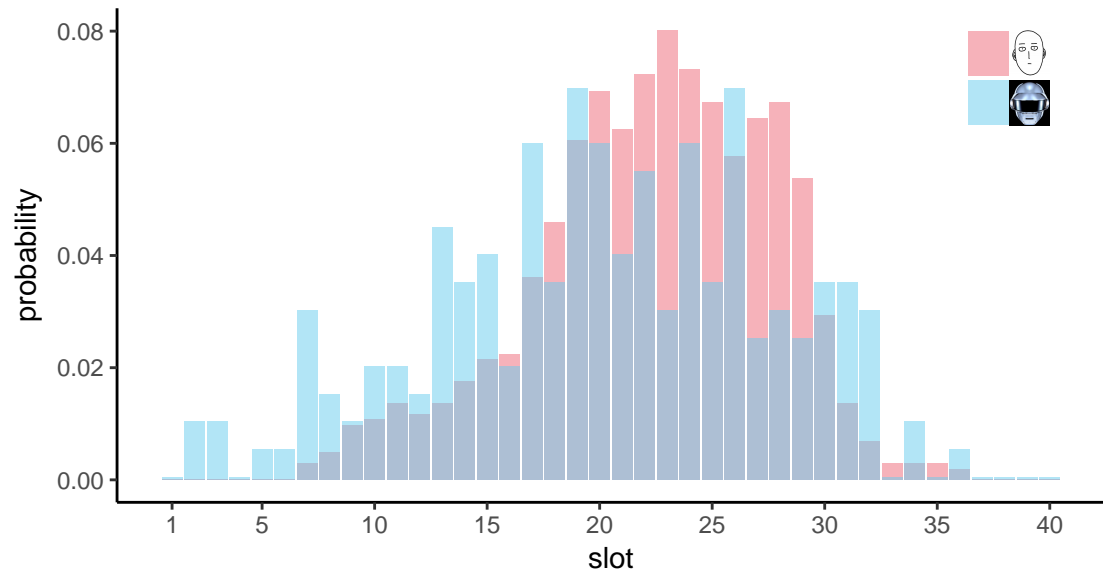
participant #1, observation 197, rel-entr. = 0.2, JS = 0.18



participant #1, observation 198, rel-entr. = 0.5, JS = 0.36



participant #1, observation 199, rel-entr. = 0.5, JS = 0.36



participant #1, observation 200, rel-entr. = 0.51, JS = 0.38

