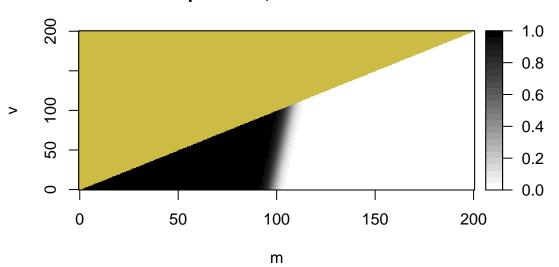
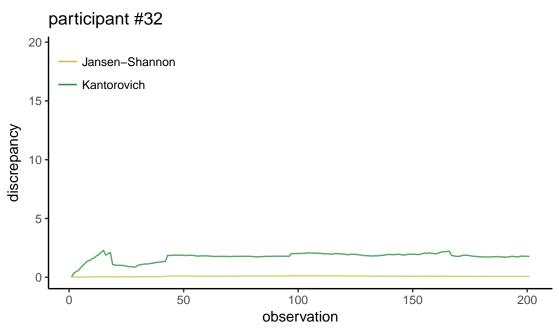


## h for part. #32, stubbornness = 27.5





## participant #32, sqrt(robot-participant)

