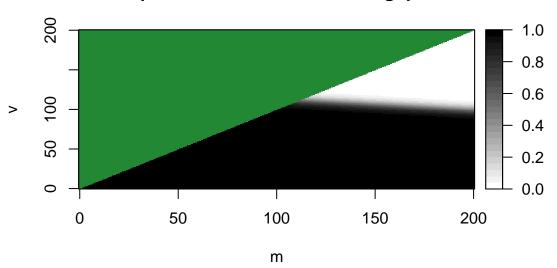
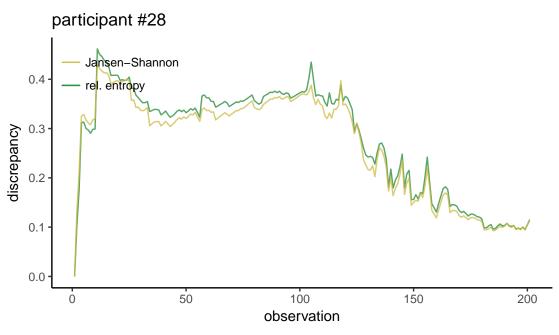
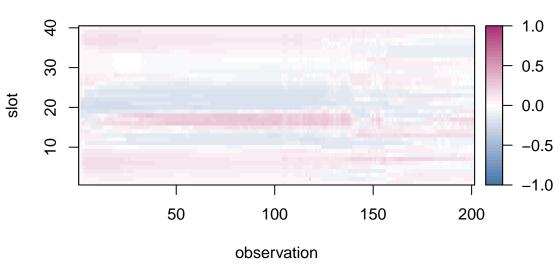


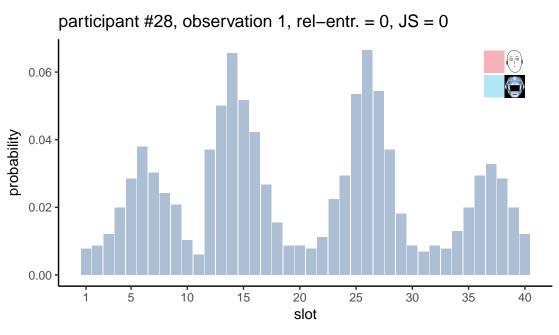
part. #28, stub. = 49.5, changepoint:





participant #28, sqrt(robot-participant)





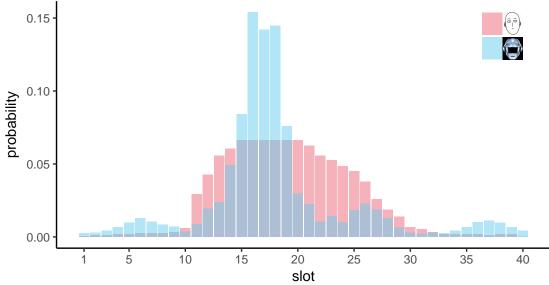
participant #28, observation 2, rel-entr. = 0.1, JS = 0.13 0.06 probability 0.04 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #28, observation 3, rel-entr. = 0.18, JS = 0.21 0.06 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

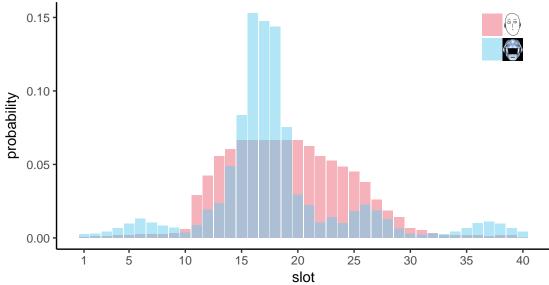
participant #28, observation 4, rel-entr. = 0.31, JS = 0.33 0.06 0.04 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #28, observation 99, rel-entr. = 0.37, JS = 0.36 0.15 0.10 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

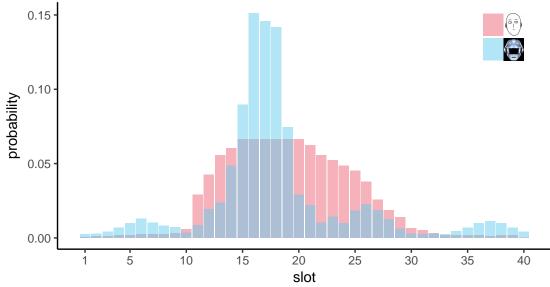
participant #28, observation 100, rel-entr. = 0.37, JS = 0.37



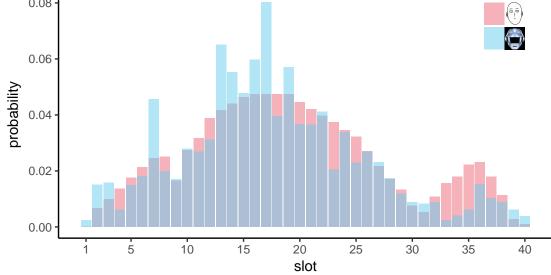
participant #28, observation 101, rel-entr. = 0.37, JS = 0.37



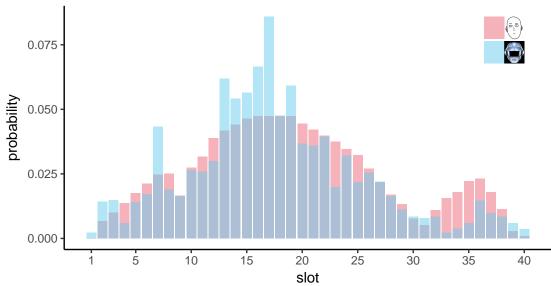
participant #28, observation 102, rel-entr. = 0.37, JS = 0.37



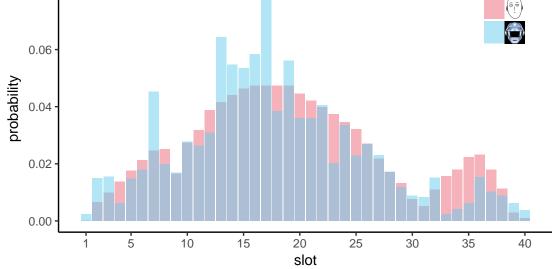
participant #28, observation 197, rel-entr. = 0.096, JS = 0.095



participant #28, observation 198, rel-entr. = 0.1, JS = 0.1



participant #28, observation 199, rel-entr. = 0.095, JS = 0.094 0.08 -



participant #28, observation 200, rel-entr. = 0.1, JS = 0.11

