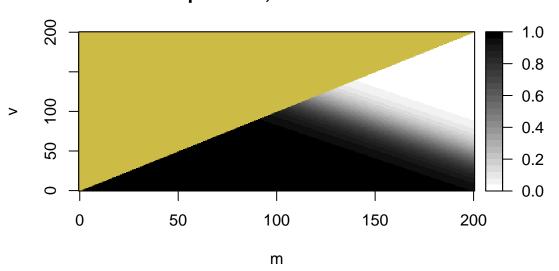
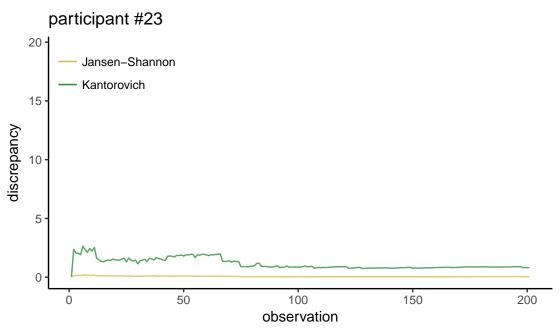
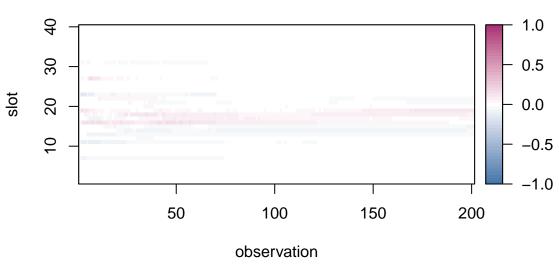


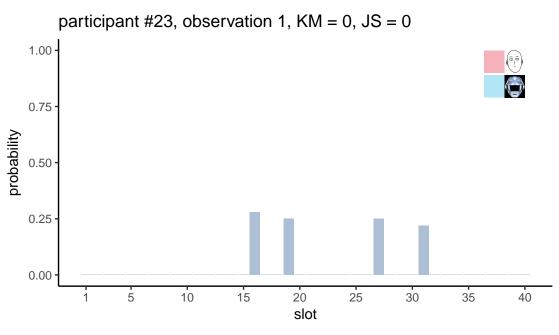
h for part. #23, stubbornness = 7.11

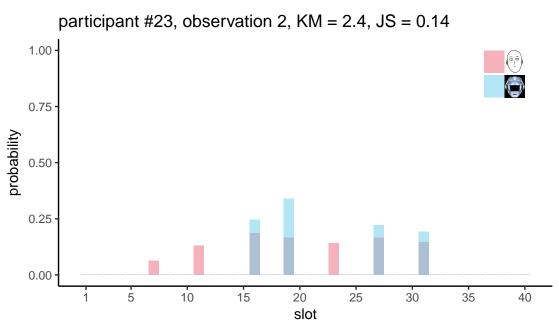


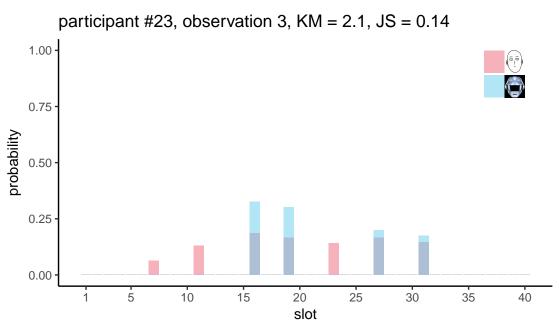


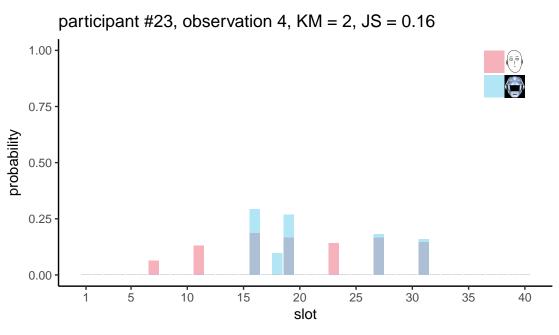
participant #23, sqrt(robot-participant)

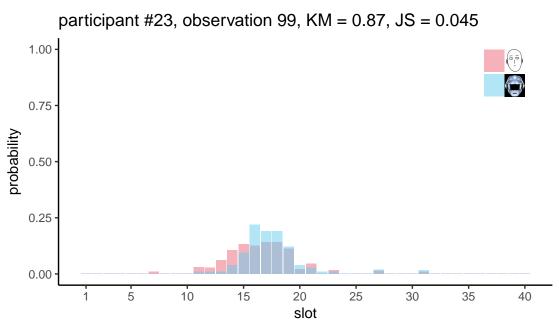


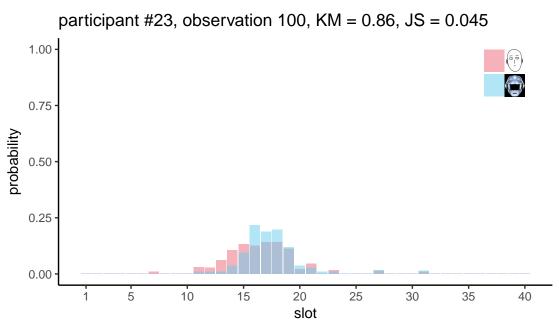


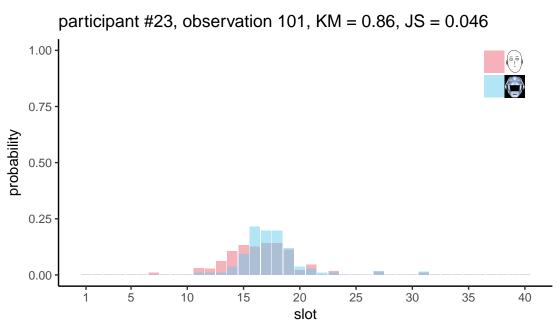


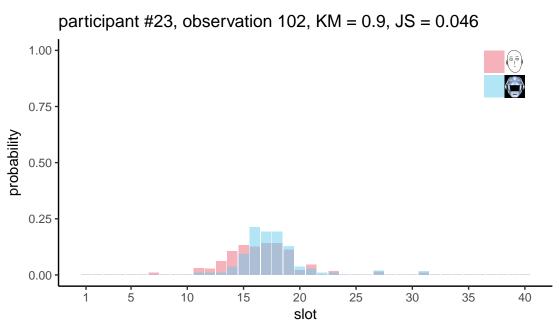


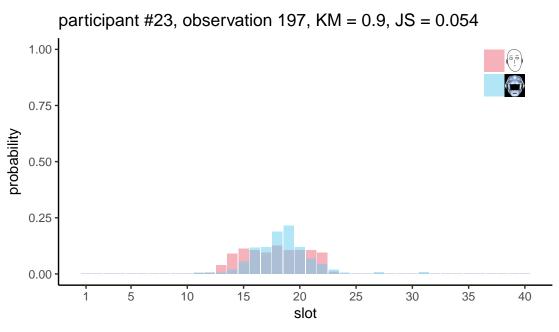


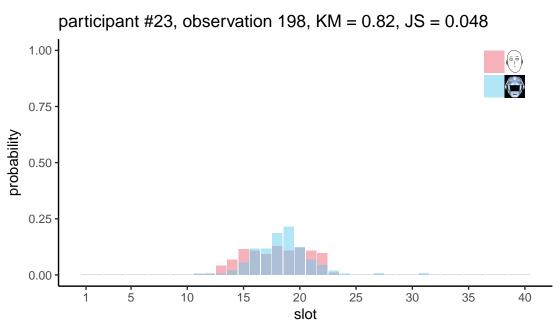


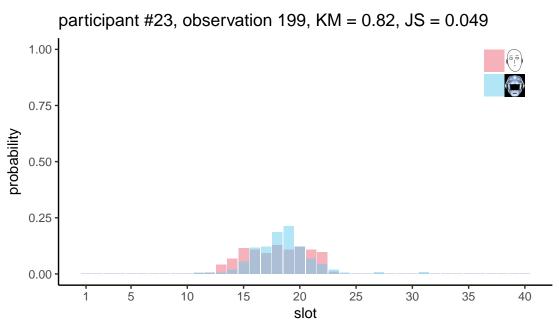












participant #23, observation 200, KM = 0.81, JS = 0.049 1.00 0.75 probability 0.25 0.00 10 15 25 30 5 20 35 40 slot