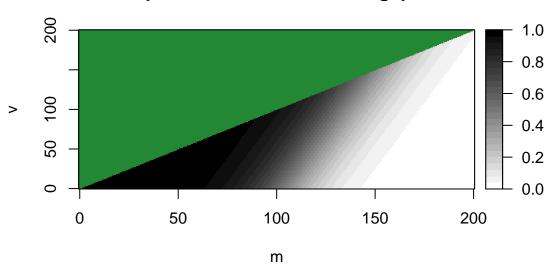
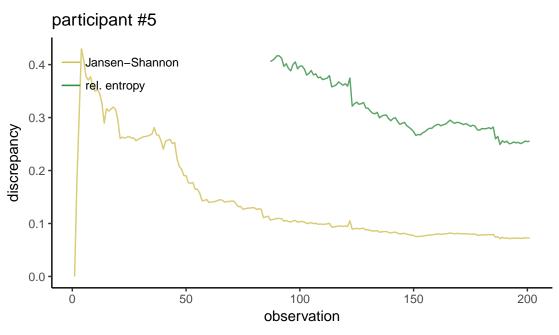
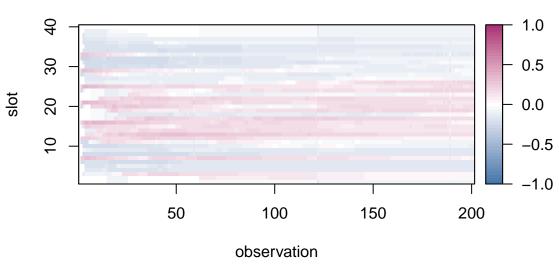


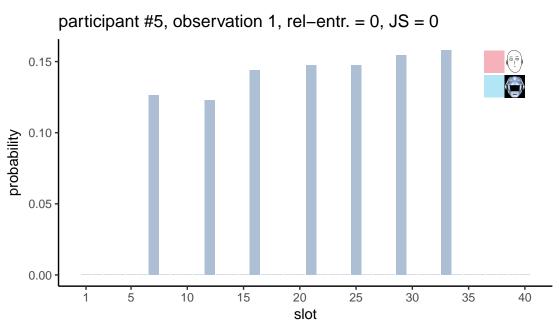
part. #5, stub. = 13.8, changepoint:



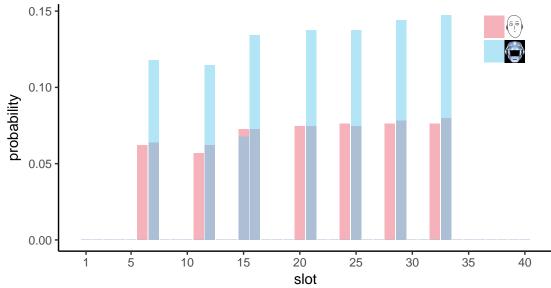


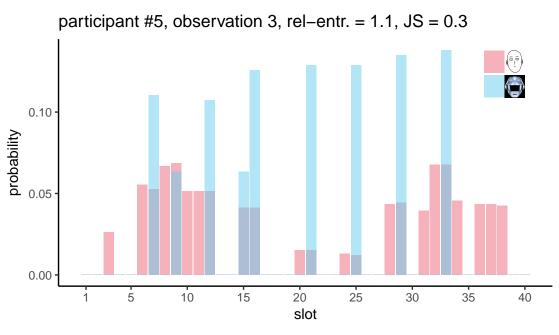
participant #5, sqrt(robot-participant)





participant #5, observation 2, rel-entr. = 0.57, JS = 0.18

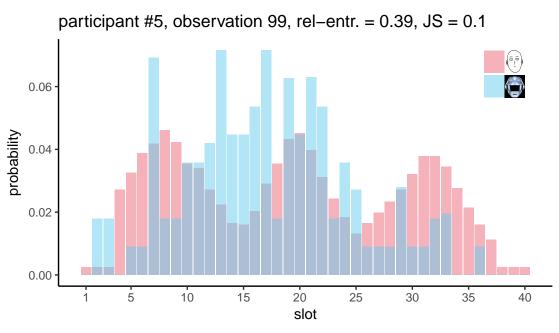




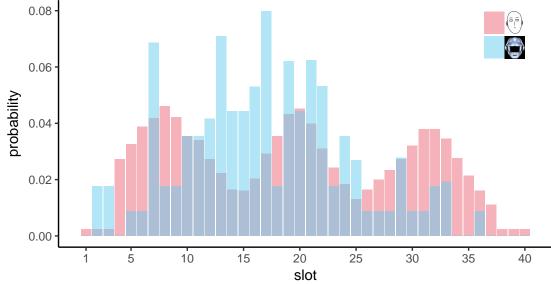
participant #5, observation 4, rel-entr. = 7.4, JS = 0.43 0.15 probability 0.10 0.05 0.00 15 20 25 30 5 10 35

slot

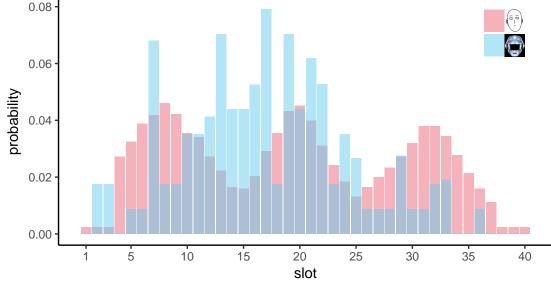
40



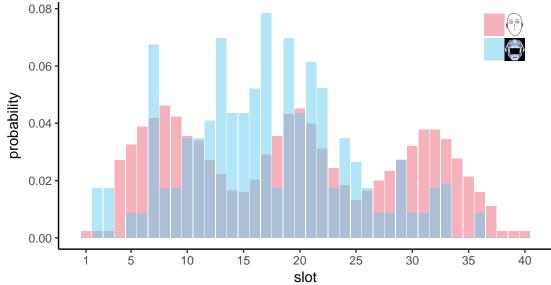
participant #5, observation 100, rel-entr. = 0.4, JS = 0.1



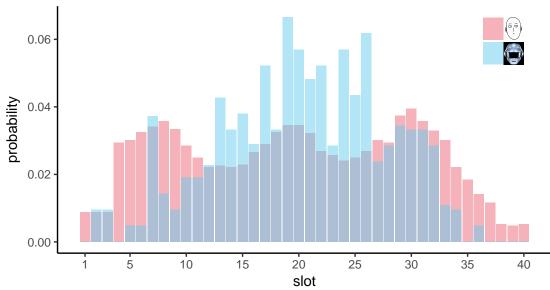
participant #5, observation 101, rel-entr. = 0.4, JS = 0.1



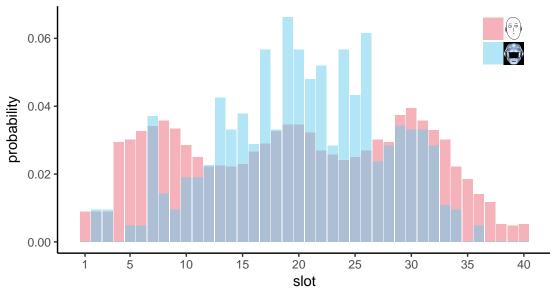
participant #5, observation 102, rel-entr. = 0.39, JS = 0.1



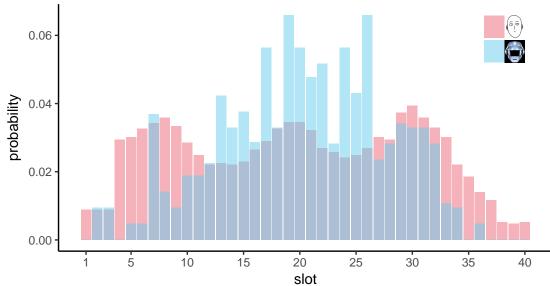
participant #5, observation 197, rel-entr. = 0.25, JS = 0.072



participant #5, observation 198, rel-entr. = 0.25, JS = 0.072



participant #5, observation 199, rel-entr. = 0.26, JS = 0.073



participant #5, observation 200, rel-entr. = 0.25, JS = 0.073

