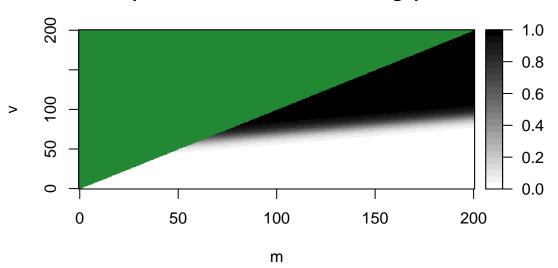
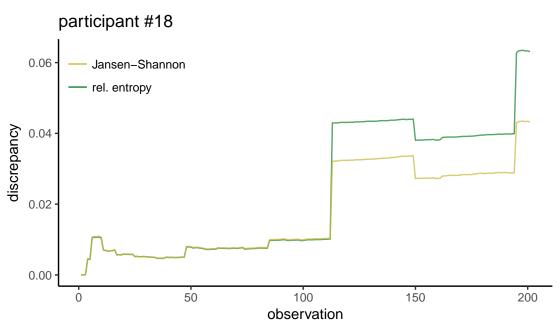
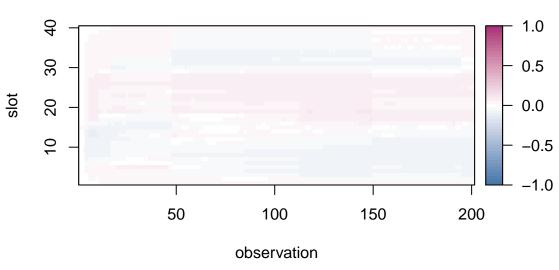


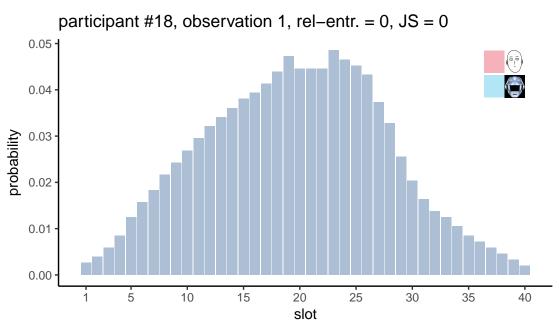
part. #18, stub. = 1e+03, changepoint:



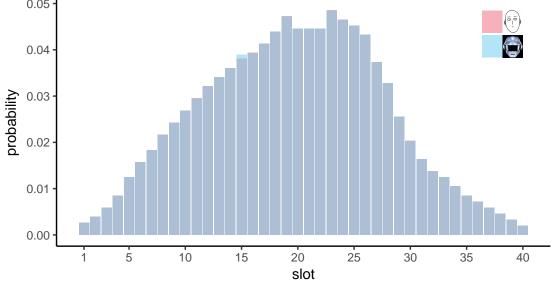


## participant #18, sqrt(robot-participant)

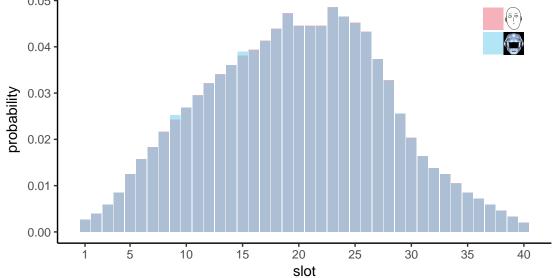


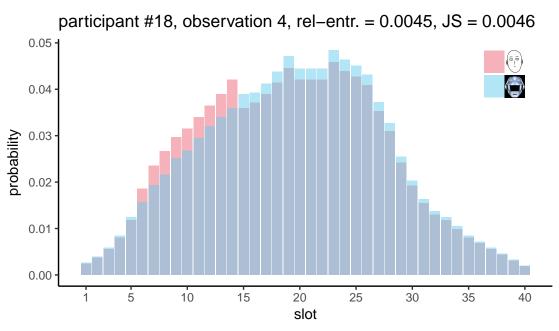


participant #18, observation 2, rel-entr. = 1.2e-05, JS = 1.2e-05

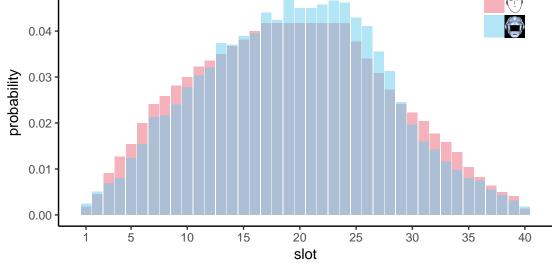


participant #18, observation 3, rel-entr. = 3.1e-05, JS = 3.1e-05 0.05

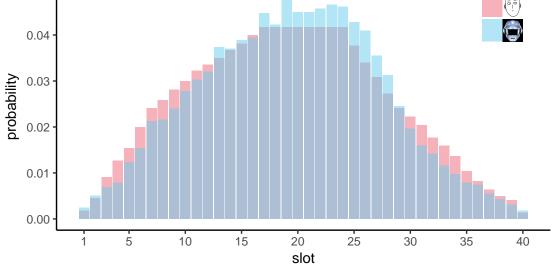




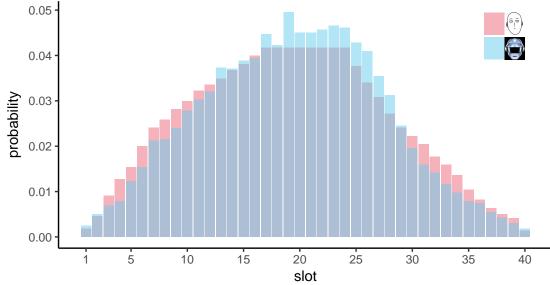
participant #18, observation 99, rel-entr. = 0.0097, JS = 0.0099 0.05 -0.04



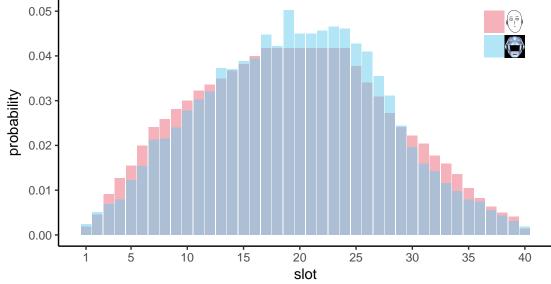
participant #18, observation 100, rel-entr. = 0.0097, JS = 0.0099 0.05 -0.04 0.03



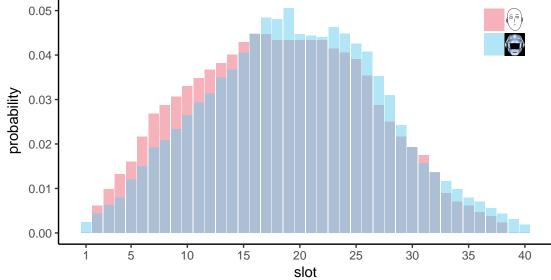
participant #18, observation 101, rel-entr. = 0.0098, JS = 0.01



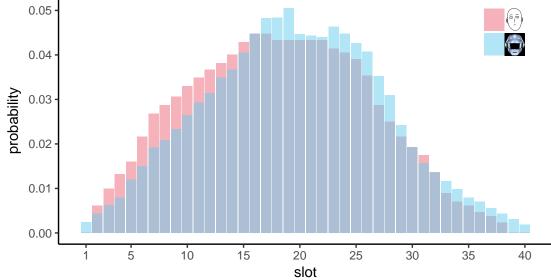
participant #18, observation 102, rel-entr. = 0.0099, JS = 0.01



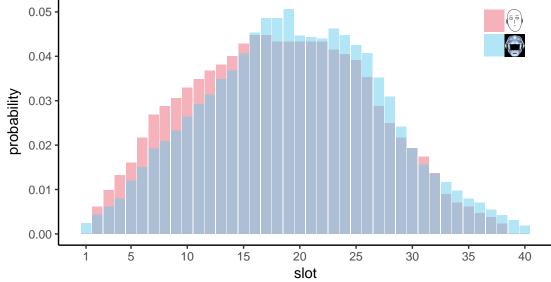
participant #18, observation 197, rel-entr. = 0.063, JS = 0.043



participant #18, observation 198, rel-entr. = 0.063, JS = 0.043



participant #18, observation 199, rel-entr. = 0.063, JS = 0.043



participant #18, observation 200, rel-entr. = 0.063, JS = 0.043

