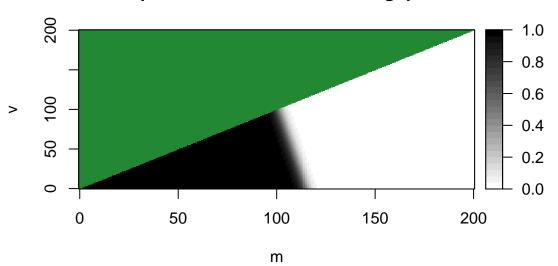
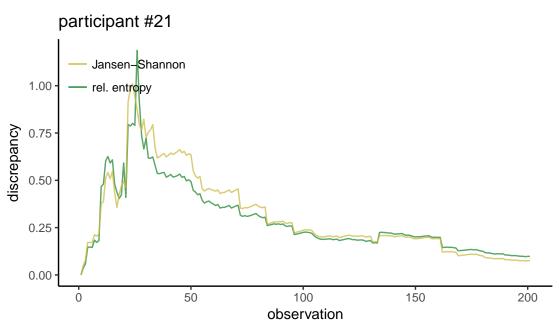
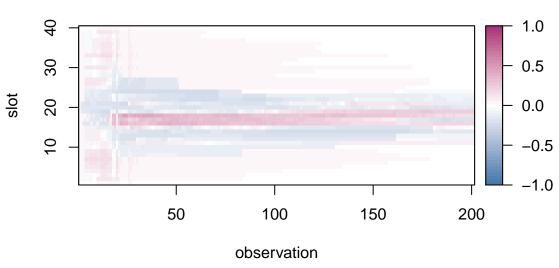


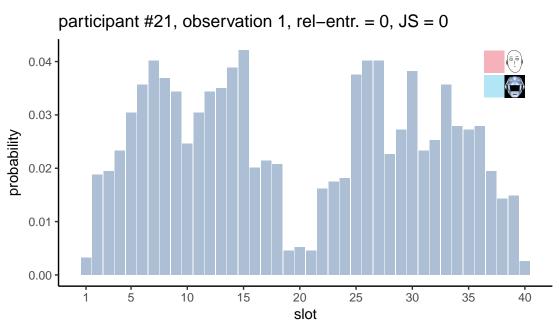
part. #21, stub. = 1.65, changepoint:



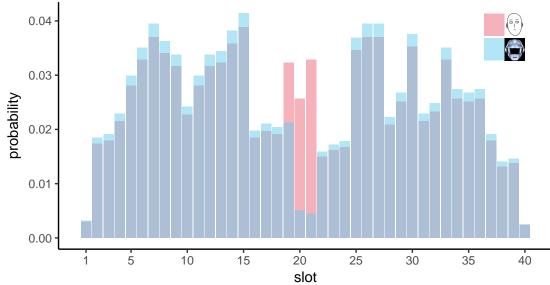


participant #21, sqrt(robot-participant)

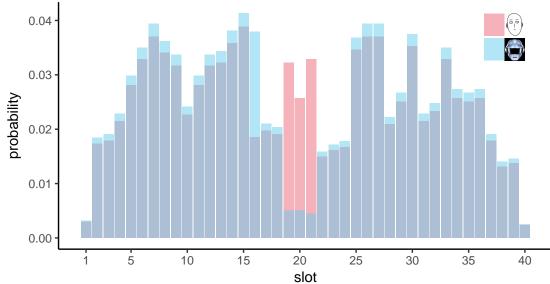




participant #21, observation 2, rel-entr. = 0.036, JS = 0.049



participant #21, observation 3, rel-entr. = 0.059, JS = 0.079

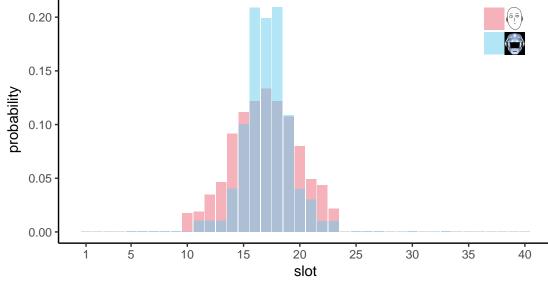


participant #21, observation 4, rel-entr. = 0.15, JS = 0.17 0.04 0.03 probability 0.02 0.01 0.00 15 25 30 5 10 20 35 40

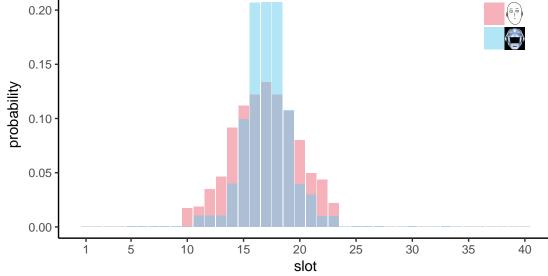
slot

participant #21, observation 99, rel-entr. = 0.22, JS = 0.23 0.20 0.15 probability 0.10 0.05 0.00 15 25 30 35 5 10 20 40 slot

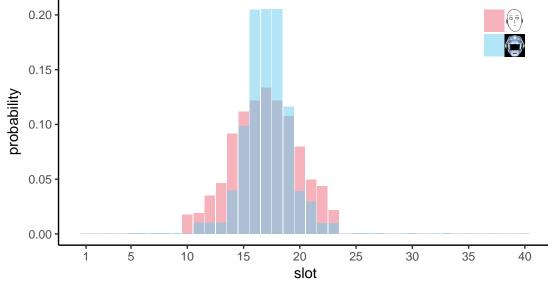
participant #21, observation 100, rel-entr. = 0.22, JS = 0.24



participant #21, observation 101, rel-entr. = 0.23, JS = 0.24



participant #21, observation 102, rel-entr. = 0.22, JS = 0.24



participant #21, observation 197, rel-entr. = 0.098, JS = 0.075 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #21, observation 198, rel-entr. = 0.098, JS = 0.075 0.20 0.15 probability 0.10 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #21, observation 199, rel-entr. = 0.097, JS = 0.073 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40

slot

participant #21, observation 200, rel-entr. = 0.098, JS = 0.075 0.20 0.15 probability 0.10 0.05 0.00 15 25 30 35 5 10 20 40

slot