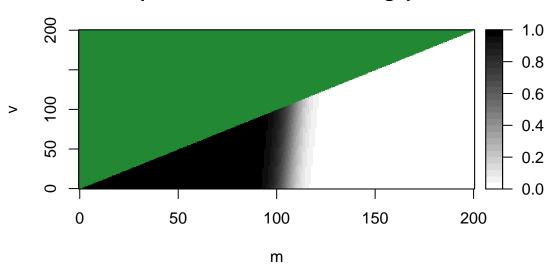
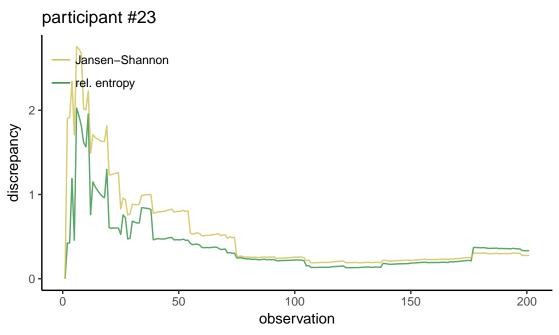
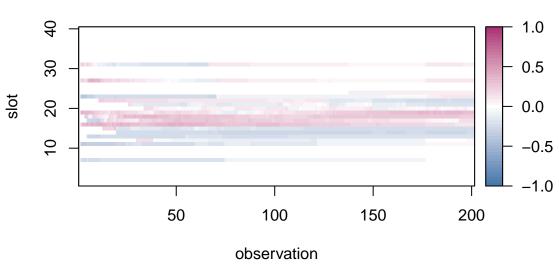


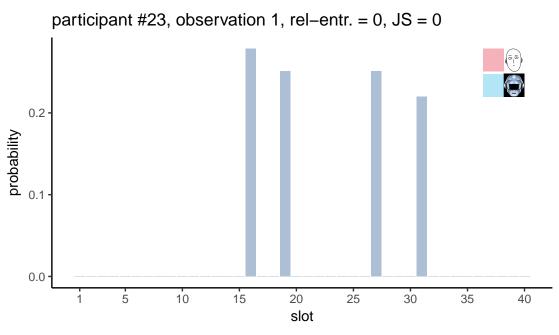
part. #23, stub. = 8.81, changepoint:





participant #23, sqrt(robot-participant)





participant #23, observation 2, rel-entr. = 0.42, JS = 1.9 0.3 probability 0.2 -0.1 0.0 10 15 30 25 20 35 40 slot

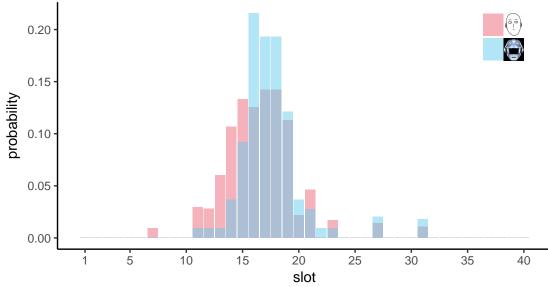
participant #23, observation 3, rel-entr. = 0.42, JS = 1.9 0.3 0.2 probability 0.1 0.0 10 15 30 20 25 35 40 slot

participant #23, observation 4, rel-entr. = 1.2, JS = 2.3 0.3 -0.2 probability 0.0 10 15 25 30 20 35 40 slot

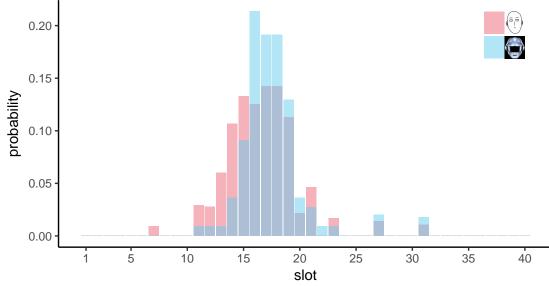
participant #23, observation 99, rel-entr. = 0.22, JS = 0.25 0.20 0.15 probability 0.05 0.00 15 25 35 5 10 20 30 40 slot

participant #23, observation 100, rel-entr. = 0.22, JS = 0.26 0.20 0.15 probability 0.05 0.00 15 25 35 5 10 20 30 40 slot

participant #23, observation 101, rel-entr. = 0.22, JS = 0.26

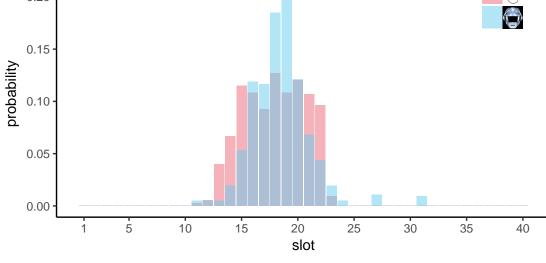


participant #23, observation 102, rel-entr. = 0.22, JS = 0.26

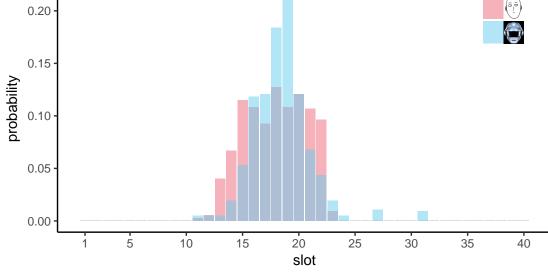


participant #23, observation 197, rel-entr. = 0.35, JS = 0.3 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 5 20 35 40 slot

participant #23, observation 198, rel-entr. = 0.33, JS = 0.28 0.20 0.15 probability



participant #23, observation 199, rel-entr. = 0.33, JS = 0.28 0.20 0.15 probability 0.10



participant #23, observation 200, rel-entr. = 0.33, JS = 0.28 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 5 20 35 40 slot