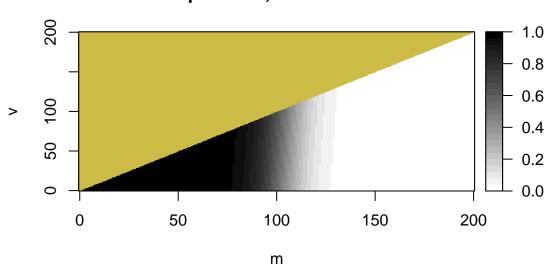
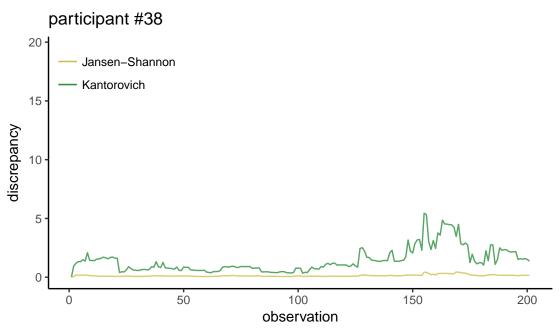


h for part. #38, stubbornness = 1.87





participant #38, sqrt(robot-participant)

