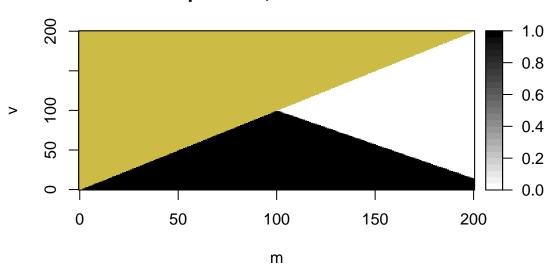
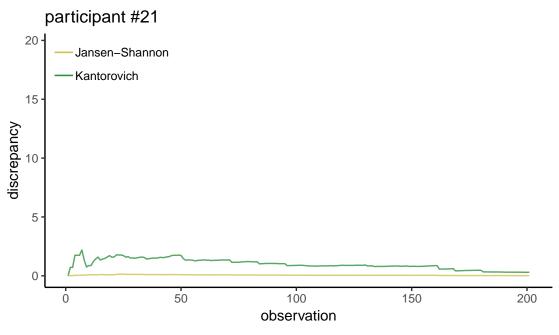


## h for part. #21, stubbornness = 5.43





## participant #21, sqrt(robot-participant)

