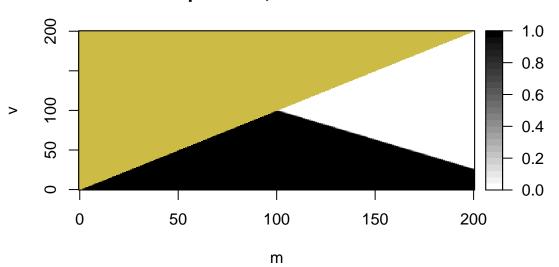
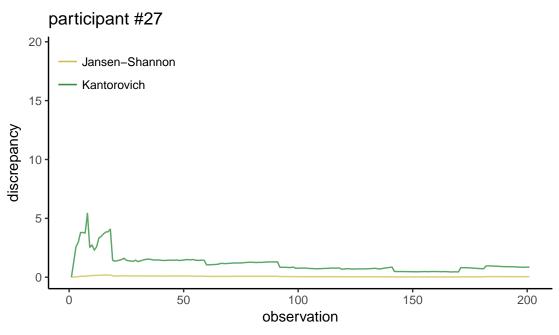


h for part. #27, stubbornness = 4.88





participant #27, sqrt(robot-participant)

