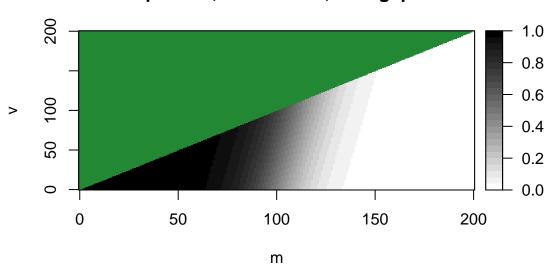
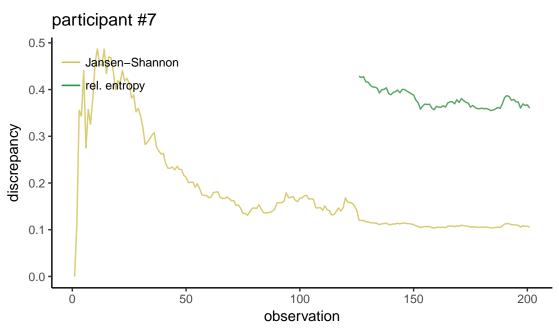
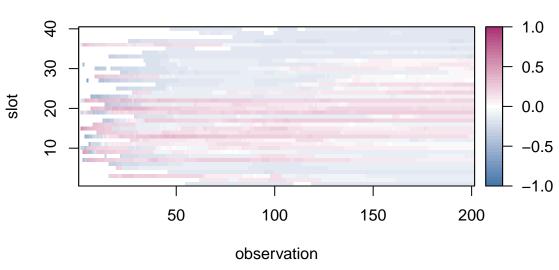


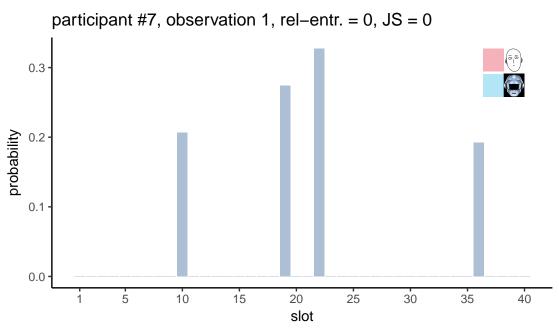
part. #7, stub. = 2.51, changepoint:



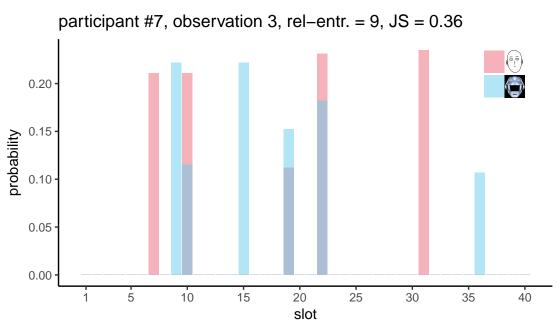


## participant #7, sqrt(robot-participant)





participant #7, observation 2, rel-entr. = 4.5, JS = 0.11 0.3 probability 0.0 10 15 30 20 25 35 40 slot



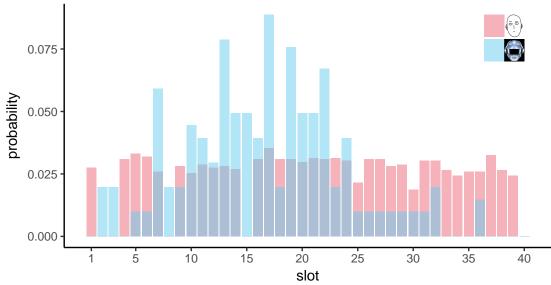
participant #7, observation 4, rel-entr. = 9.5, JS = 0.34 0.3 probability 0.1 0.0 10 15 30 20 25 35 40 slot

participant #7, observation 99, rel-entr. = 1.9, JS = 0.16 0.08 0.06 probability 0.02 0.00 15 25 30 5 10 20 35

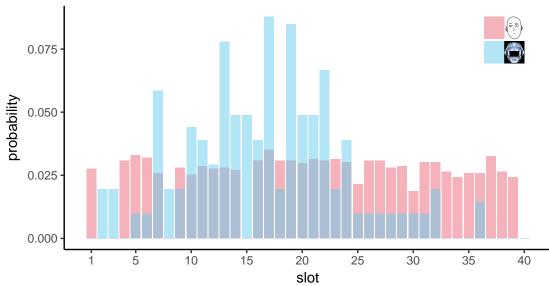
slot

40

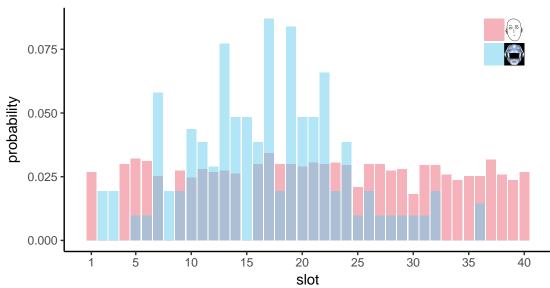
participant #7, observation 100, rel-entr. = 1.9, JS = 0.17



participant #7, observation 101, rel-entr. = 1.9, JS = 0.17



participant #7, observation 102, rel-entr. = 1.9, JS = 0.17



participant #7, observation 197, rel-entr. = 0.36, JS = 0.11 0.06 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #7, observation 198, rel-entr. = 0.37, JS = 0.11 0.06 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #7, observation 199, rel-entr. = 0.37, JS = 0.11 0.06 probability 0.04 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #7, observation 200, rel-entr. = 0.37, JS = 0.11 0.06 probability 0.04 0.02 0.00 15 25 30 5 10 20 35 40 slot