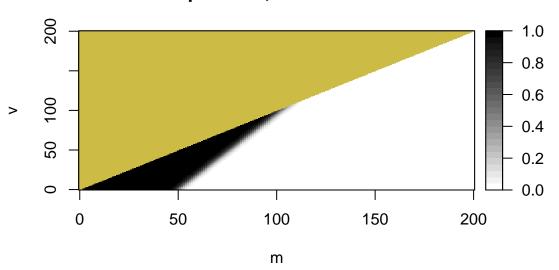
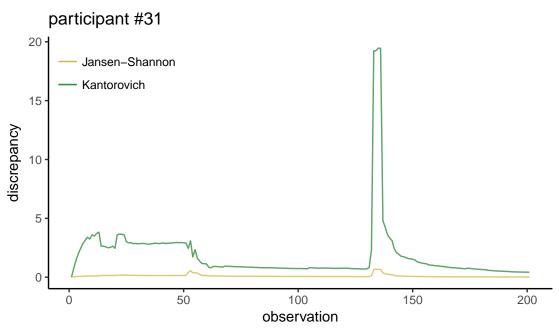
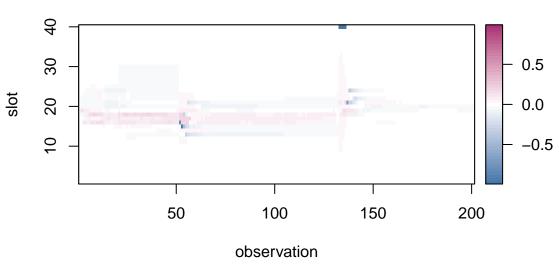


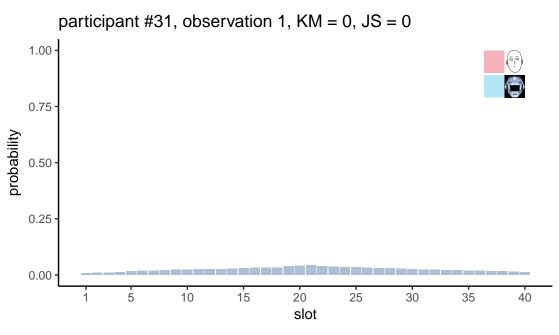
h for part. #31, stubbornness = 5.23

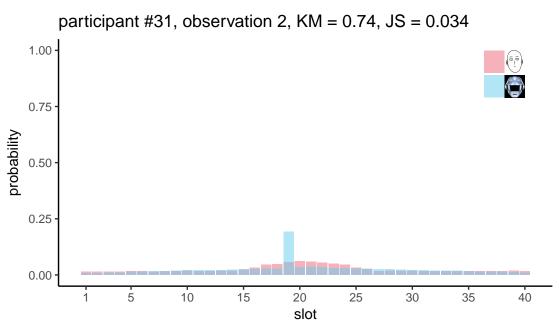


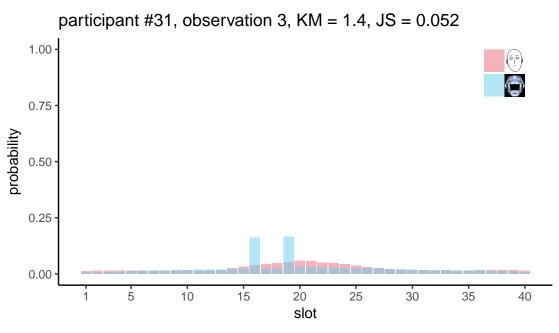


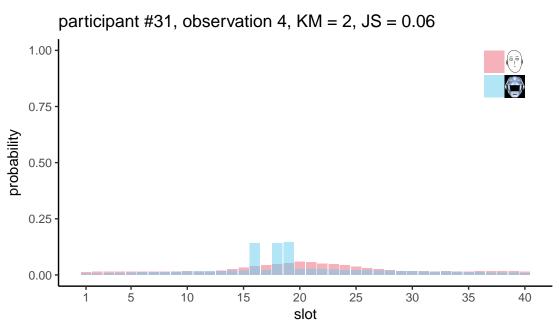
participant #31, sqrt(robot-participant)

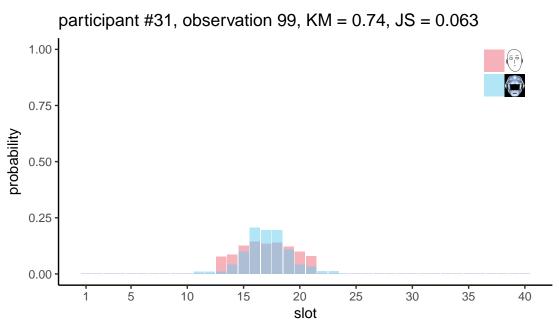


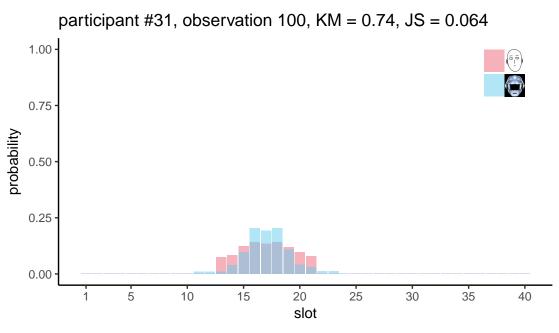


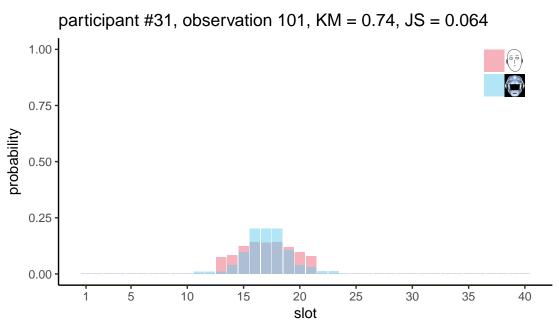


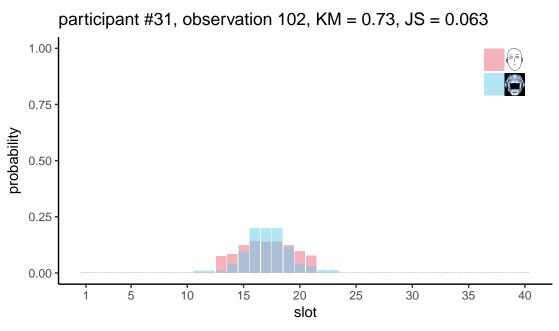


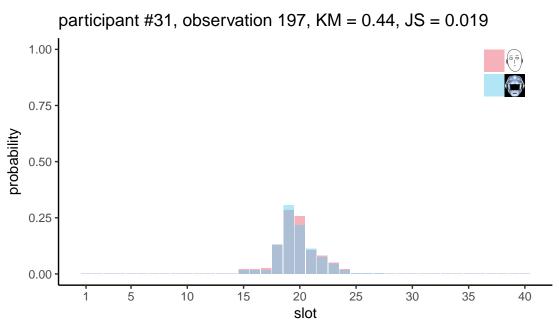












participant #31, observation 198, KM = 0.43, JS = 0.018 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

