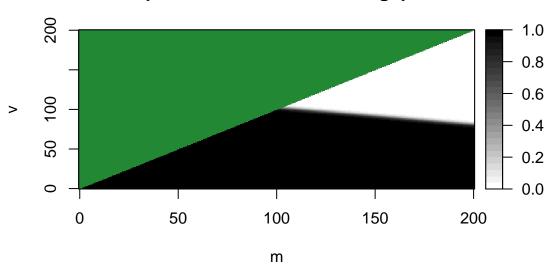
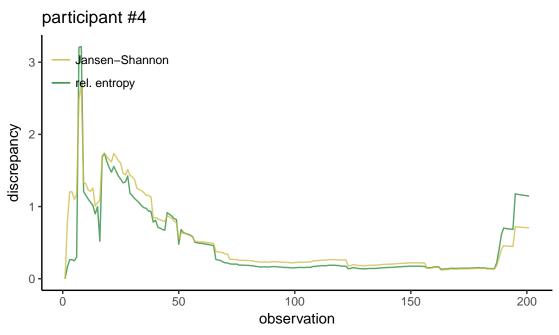
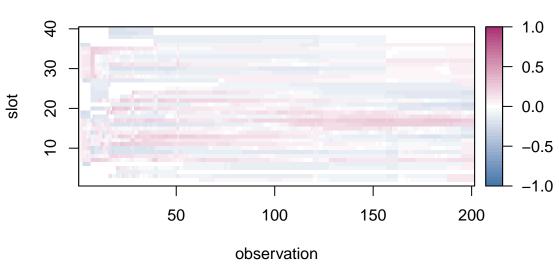


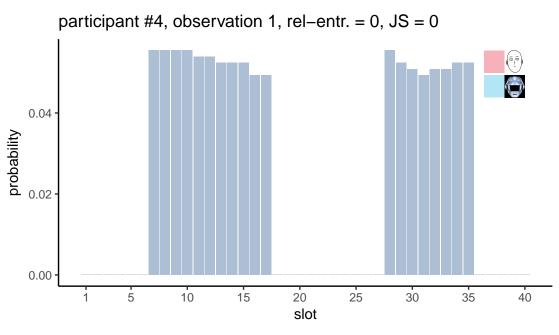
part. #4, stub. = 7.55, changepoint:



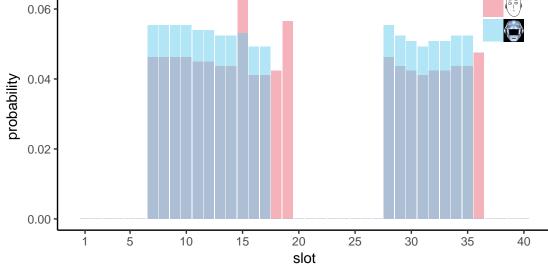


## participant #4, sqrt(robot-participant)



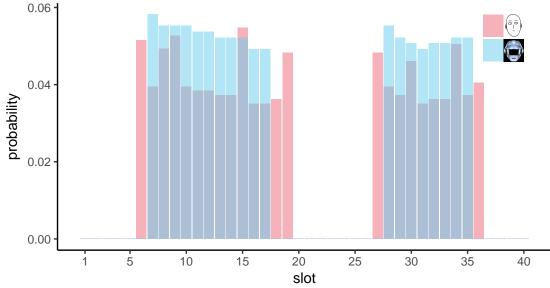


participant #4, observation 2, rel-entr. = 0.16, JS = 0.78 0.06

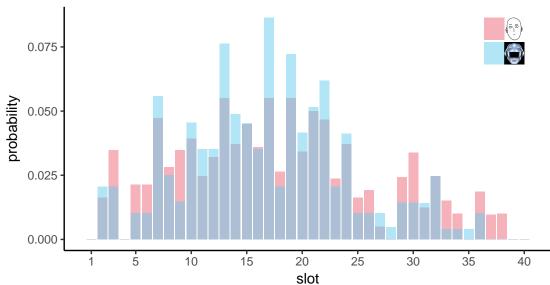


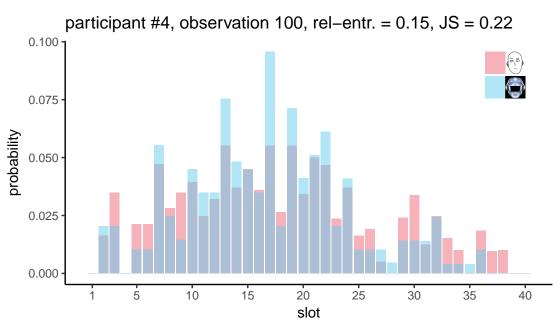
participant #4, observation 3, rel-entr. = 0.26, JS = 1.2 0.04 probability 0.00 slot

participant #4, observation 4, rel-entr. = 0.26, JS = 1.2

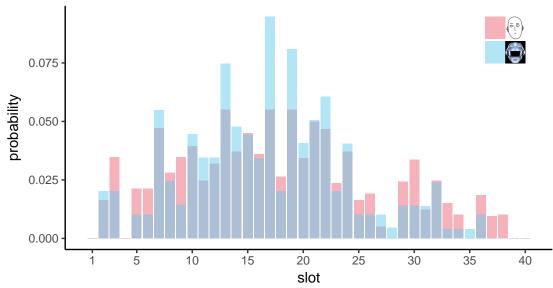


participant #4, observation 99, rel-entr. = 0.15, JS = 0.22

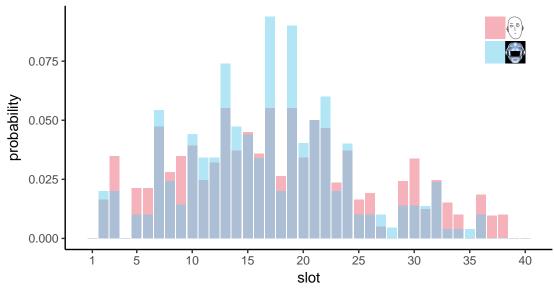




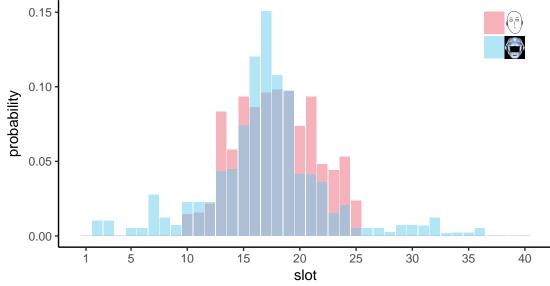
participant #4, observation 101, rel-entr. = 0.15, JS = 0.23



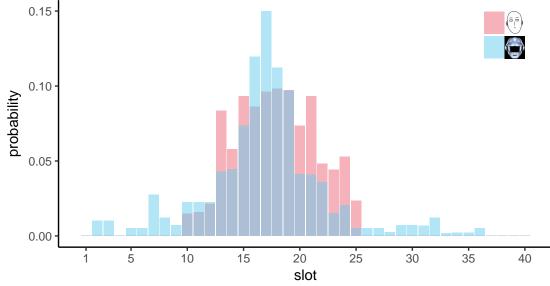
participant #4, observation 102, rel-entr. = 0.16, JS = 0.23



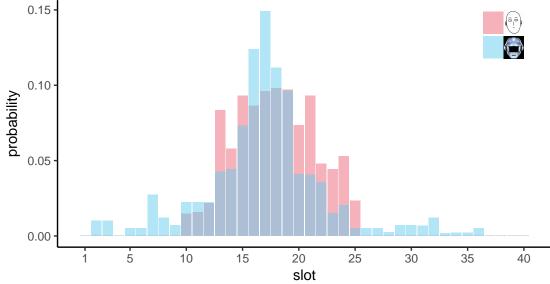
participant #4, observation 197, rel-entr. = 1.2, JS = 0.71



participant #4, observation 198, rel-entr. = 1.2, JS = 0.71



participant #4, observation 199, rel-entr. = 1.2, JS = 0.71



participant #4, observation 200, rel-entr. = 1.1, JS = 0.71 0.15 -0.10 probability 0.05 0.00

20

slot

25

30

35

40

15

10

5