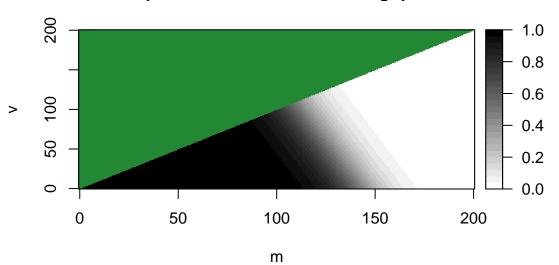
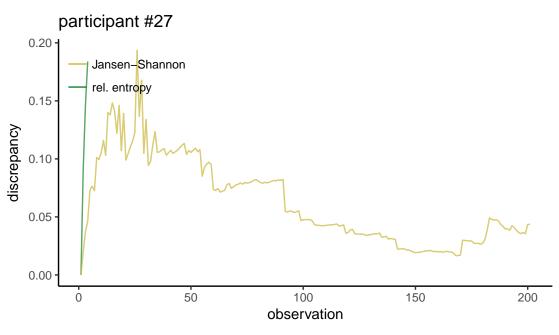
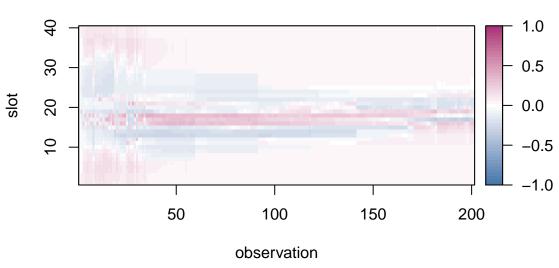


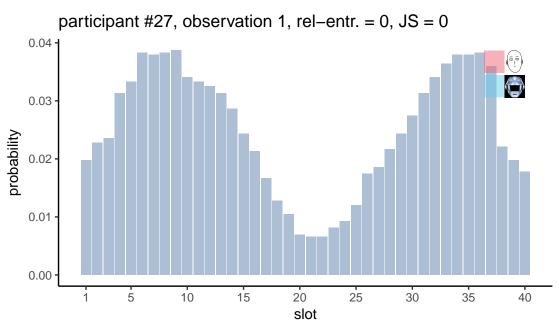
part. #27, stub. = 3.7, changepoint:



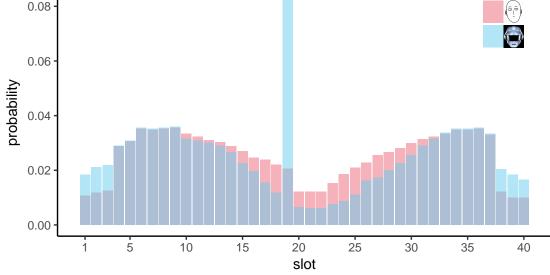


participant #27, sqrt(robot-participant)





participant #27, observation 2, rel-entr. = 0.091, JS = 0.02 0.08 0.06



participant #27, observation 3, rel-entr. = 0.15, JS = 0.037 0.075 probability 0.050 0.025 0.000 10 5 15 20 25 30 35 40

slot

participant #27, observation 4, rel-entr. = 0.18, JS = 0.046 0.08 0.06 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #27, observation 99, rel-entr. = 0.45, JS = 0.047 0.20 0.15 probability 0.05

10

5

15

20

slot

25

30

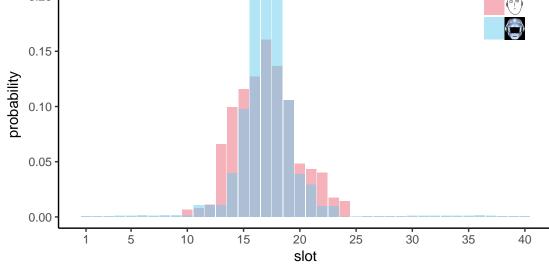
35

40

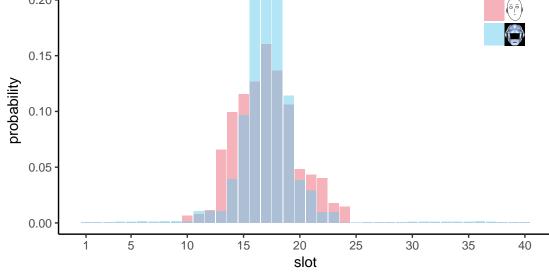
0.00

participant #27, observation 100, rel-entr. = 0.45, JS = 0.047 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #27, observation 101, rel-entr. = 0.45, JS = 0.048 0.20 0.15



participant #27, observation 102, rel-entr. = 0.45, JS = 0.048 0.20



participant #27, observation 197, rel-entr. = 0.63, JS = 0.036 0.2 probability 0.0 20 25 10 15 30 35 40 slot

participant #27, observation 198, rel-entr. = 0.59, JS = 0.037 0.2 probability 0.0 10 20 25 15 30 35 40

slot

participant #27, observation 199, rel-entr. = 0.68, JS = 0.035 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #27, observation 200, rel-entr. = 0.79, JS = 0.044 0.20 0.15 probability 0.10 0.05 0.00

20

slot

25

30

35

40

10

5

15