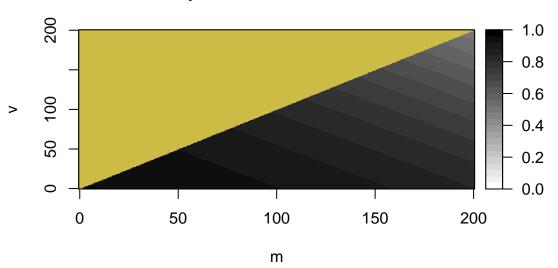
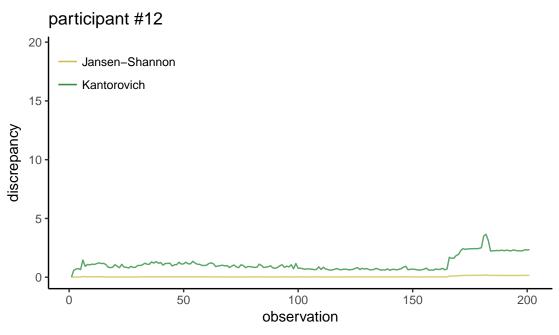
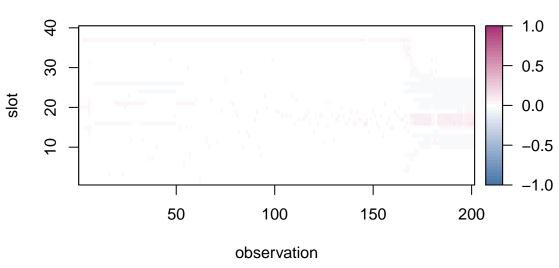


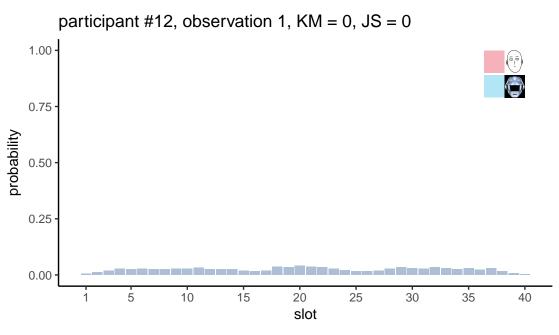
h for part. #12, stubbornness = 5.02

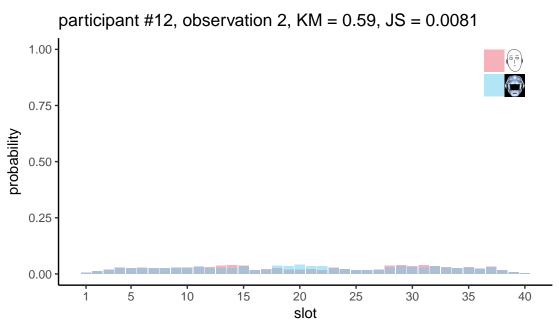


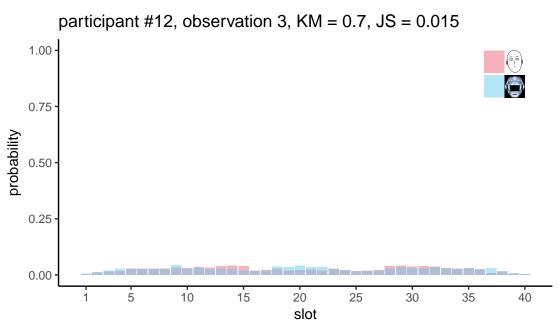


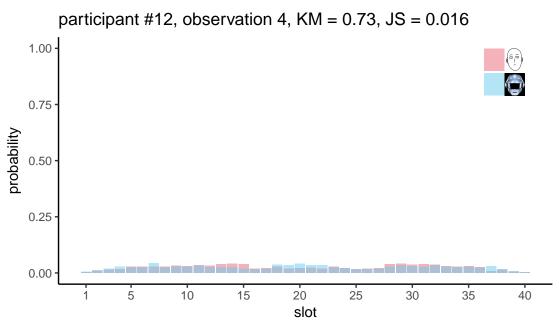
participant #12, sqrt(robot-participant)

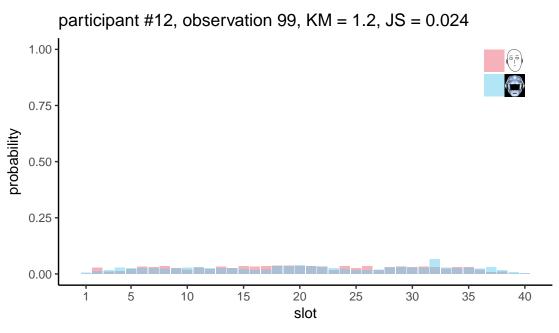












participant #12, observation 100, KM = 0.76, JS = 0.0221.00 0.75 probability 0.25 0.00 10 15 25 5 20 30 35 40 slot

