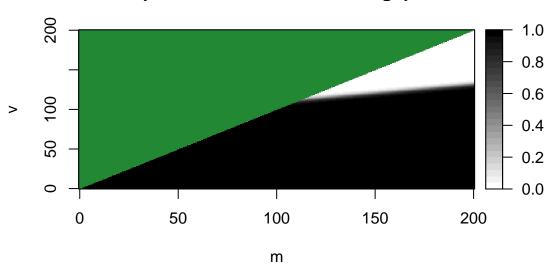
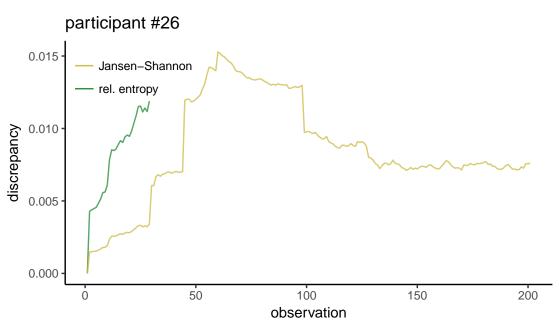
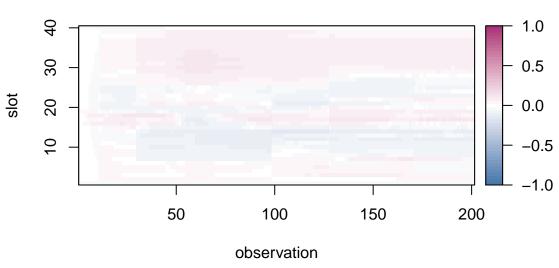


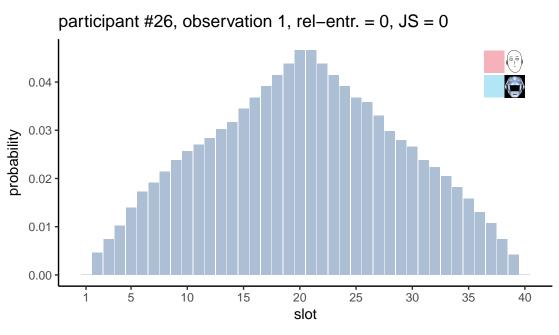
part. #26, stub. = 327, changepoint:



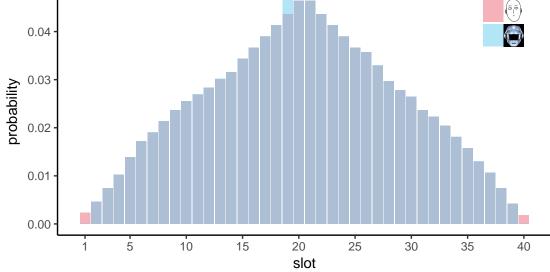


## participant #26, sqrt(robot-participant)

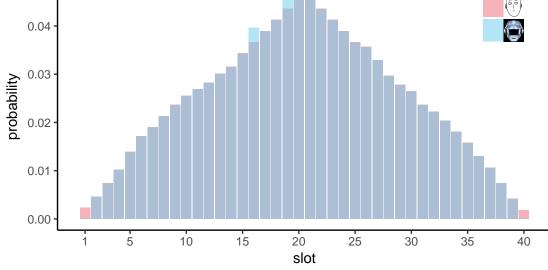




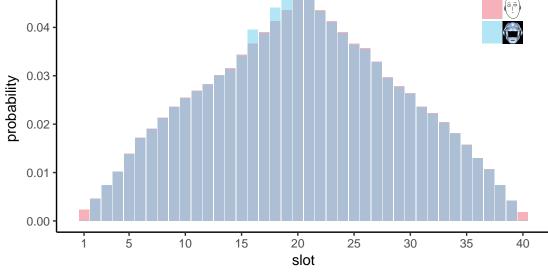
participant #26, observation 2, rel-entr. = 0.0043, JS = 0.0015 0.04



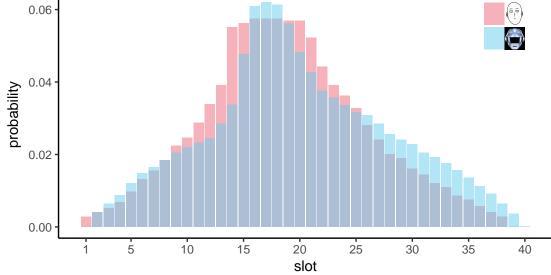
participant #26, observation 3, rel-entr. = 0.0044, JS = 0.0015 0.04 0.03 0.02



participant #26, observation 4, rel-entr. = 0.0045, JS = 0.0015 0.04 0.03 probability 0.02

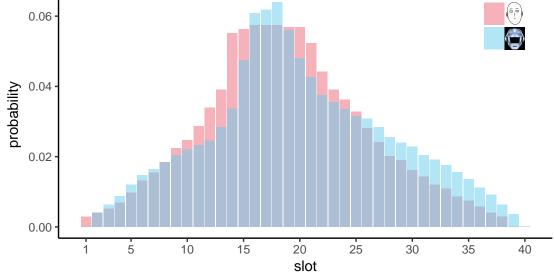


participant #26, observation 99, rel-entr. = 0.083, JS = 0.0097 0.06



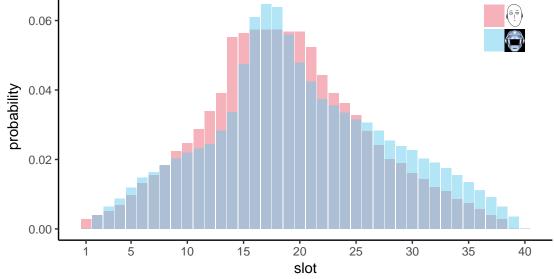
0.06

participant #26, observation 100, rel-entr. = 0.083, JS = 0.0098



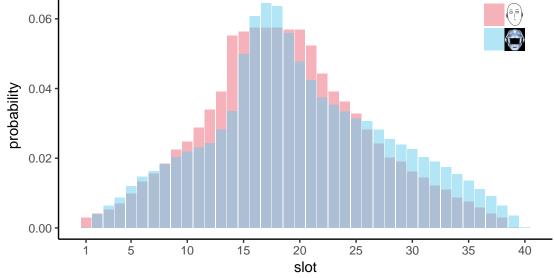
0.06

participant #26, observation 101, rel-entr. = 0.083, JS = 0.0098



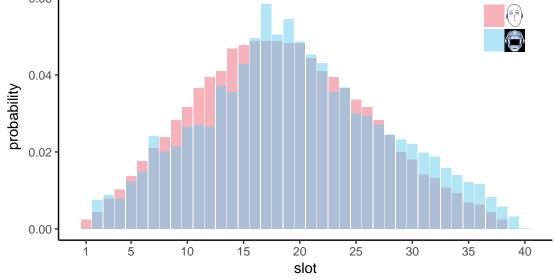
0.06

participant #26, observation 102, rel-entr. = 0.083, JS = 0.0097



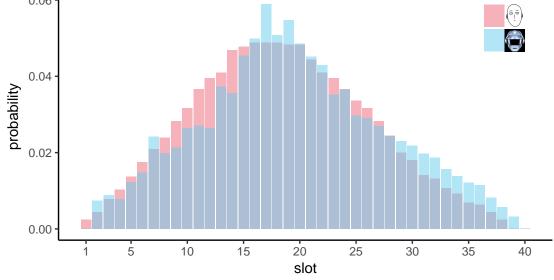
0.06 -

participant #26, observation 197, rel-entr. = 0.069, JS = 0.0073

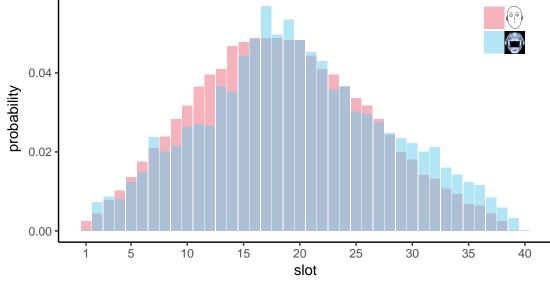


0.06 -

participant #26, observation 198, rel-entr. = 0.068, JS = 0.0073



participant #26, observation 199, rel-entr. = 0.07, JS = 0.0076 0.04



participant #26, observation 200, rel-entr. = 0.069, JS = 0.0076 0.06

