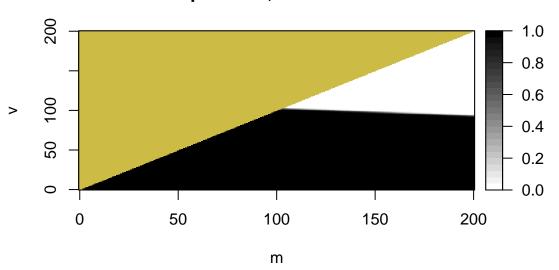
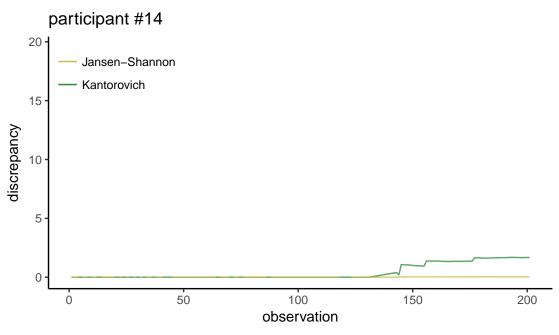
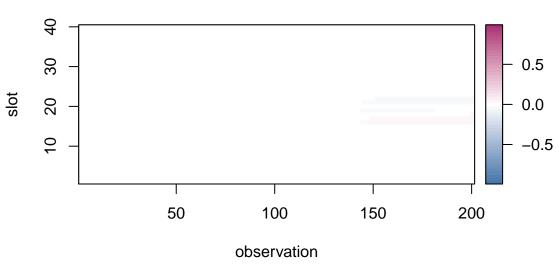


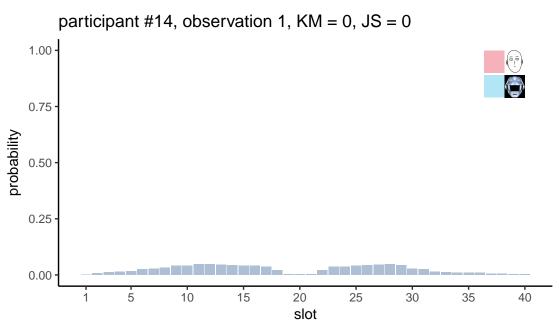
h for part. #14, stubbornness = 189

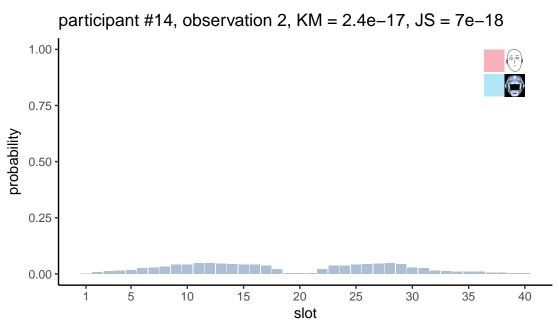


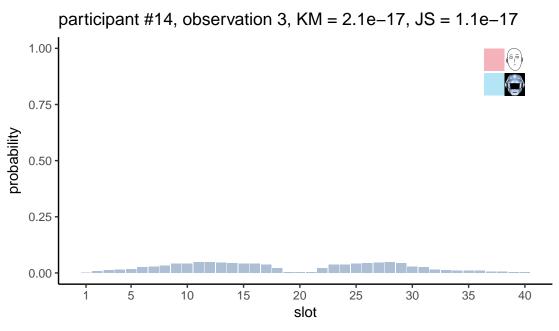


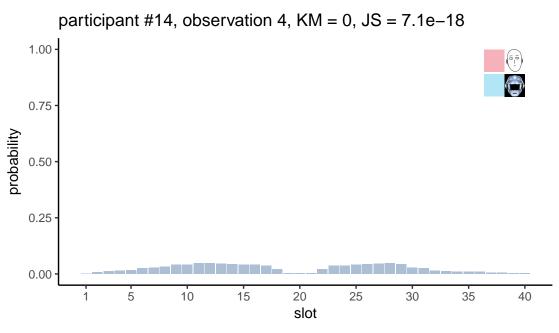
participant #14, sqrt(robot-participant)

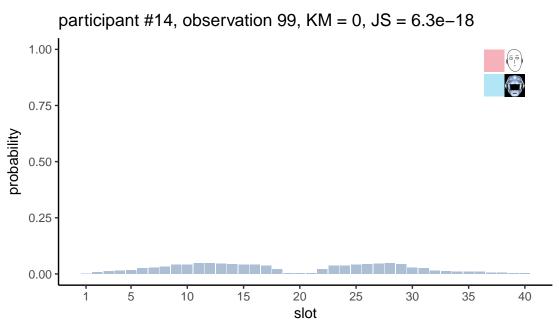












participant #14, observation 100, KM = 2.2e-19, JS = 9.6e-18 1.00 0.75 probability 0.25 0.00 5 10 15 25 20 30 35 40 slot

