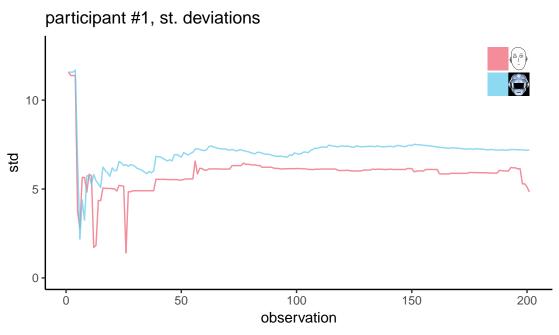
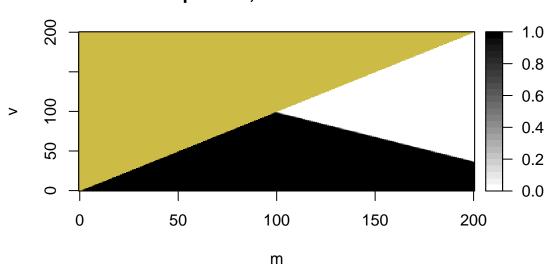
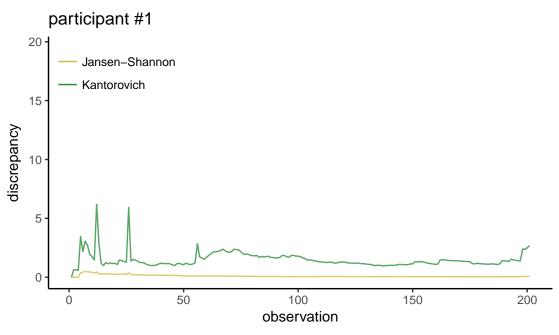


observation



## h for part. #1, stubbornness = 0.0143





## participant #1, sqrt(robot-participant)

