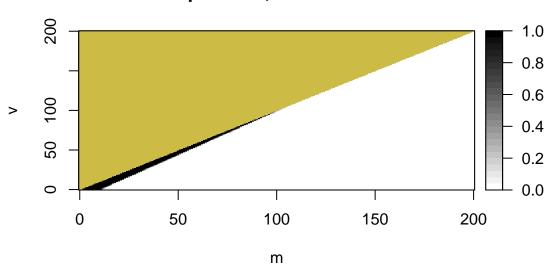
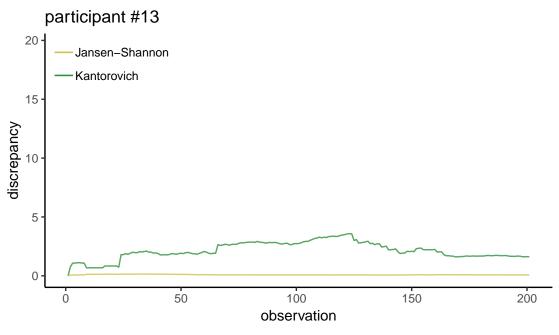


h for part. #13, stubbornness = 42.9





participant #13, sqrt(robot-participant)

