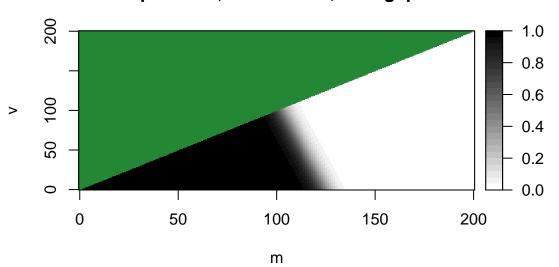
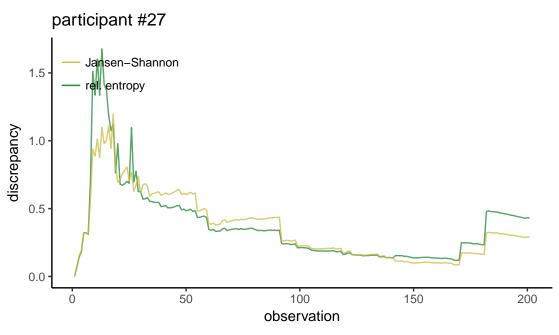
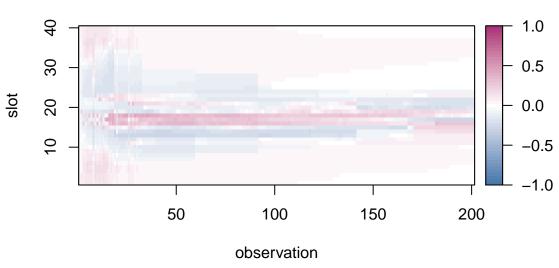


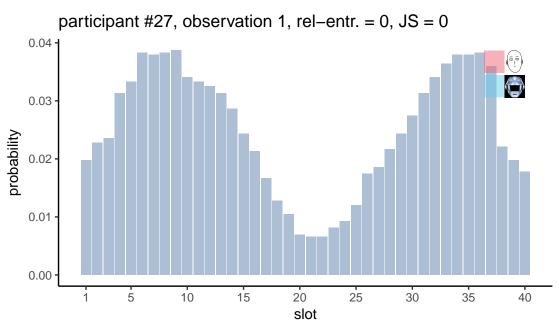
part. #27, stub. = 2.12, changepoint:



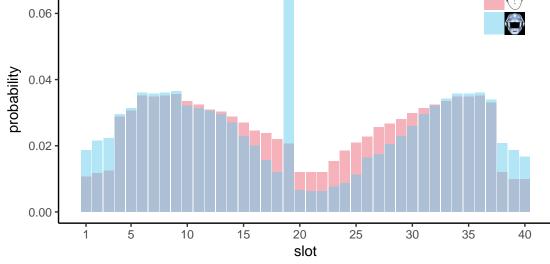


## participant #27, sqrt(robot-participant)

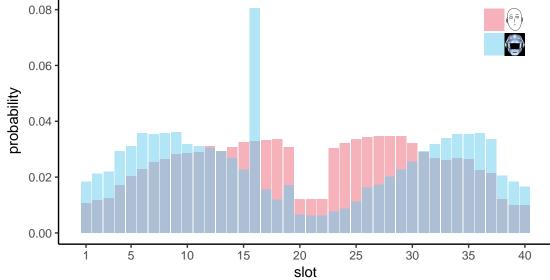




participant #27, observation 2, rel-entr. = 0.072, JS = 0.068 0.06 0.04



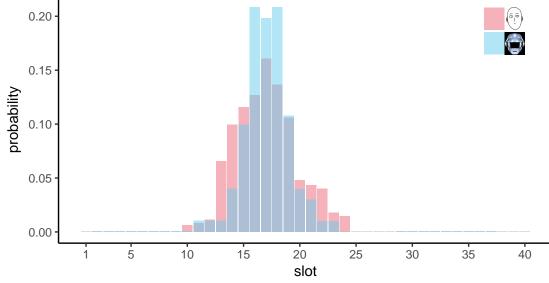
participant #27, observation 3, rel-entr. = 0.14, JS = 0.15



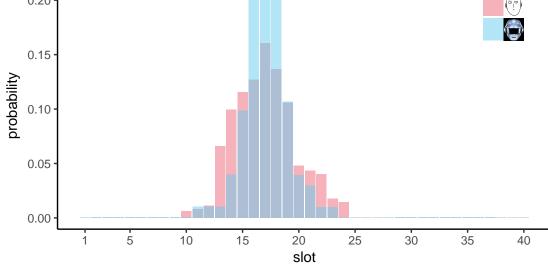
participant #27, observation 4, rel-entr. = 0.19, JS = 0.19 0.06 probability 0.04 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #27, observation 99, rel-entr. = 0.21, JS = 0.22 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

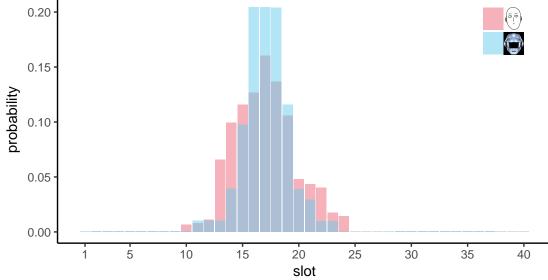
participant #27, observation 100, rel-entr. = 0.21, JS = 0.22



participant #27, observation 101, rel-entr. = 0.21, JS = 0.23 0.20 0.15

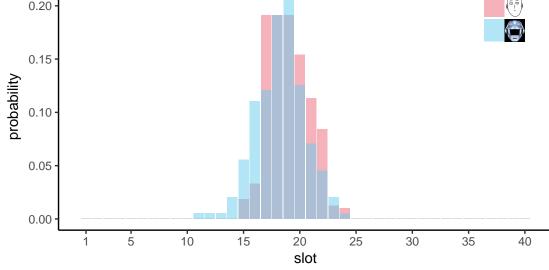


participant #27, observation 102, rel-entr. = 0.21, JS = 0.23

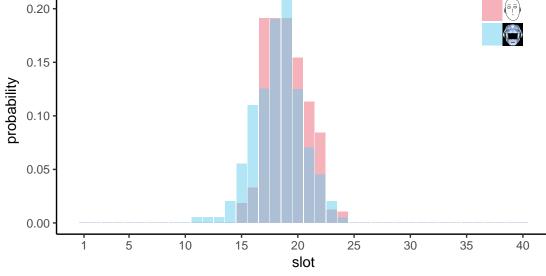


participant #27, observation 197, rel-entr. = 0.44, JS = 0.29 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #27, observation 198, rel-entr. = 0.43, JS = 0.29 0.20



participant #27, observation 199, rel-entr. = 0.43, JS = 0.29 0.20 0.15 probability



participant #27, observation 200, rel-entr. = 0.43, JS = 0.29

