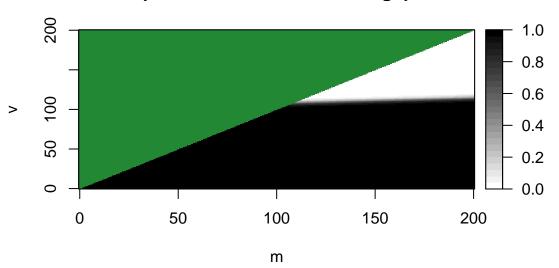
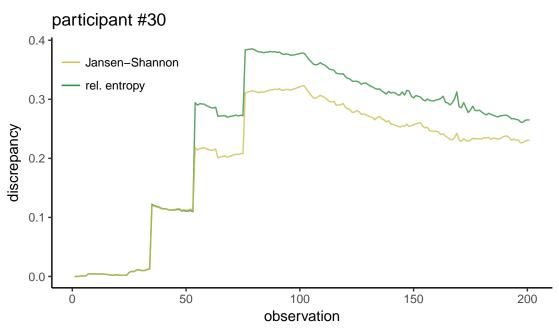
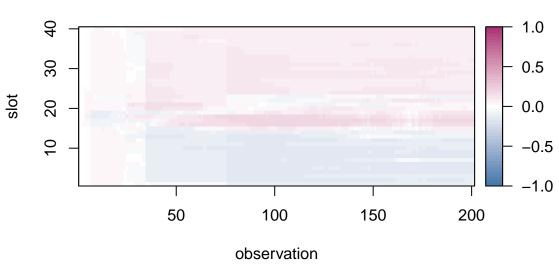


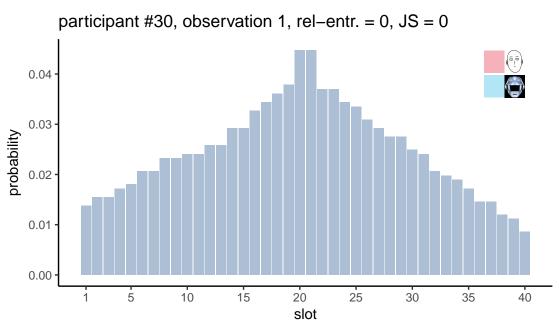
part. #30, stub. = 157, changepoint:



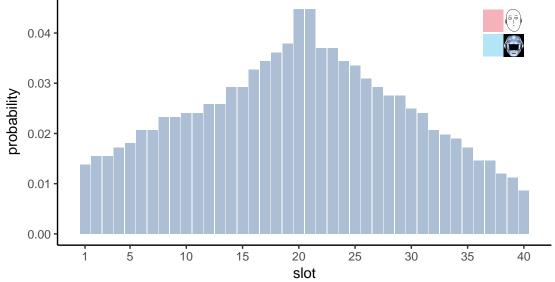


participant #30, sqrt(robot-participant)

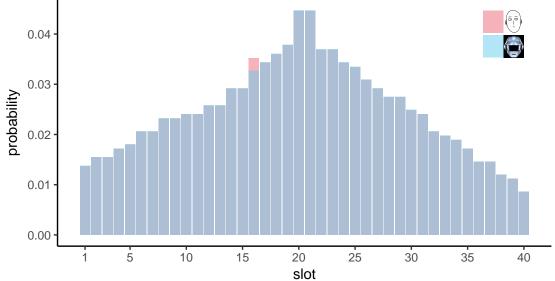




participant #30, observation 2, rel-entr. = 2.6e-10, JS = 2.6e-10

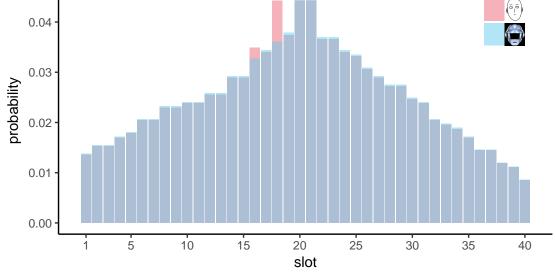


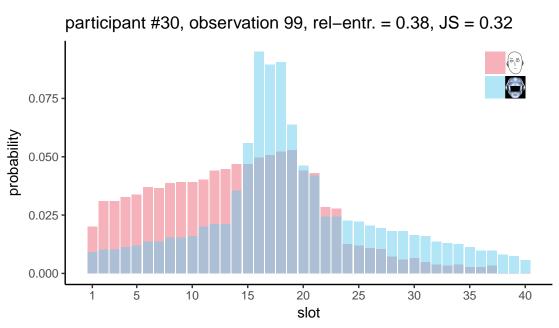
participant #30, observation 3, rel-entr. = 9.3e-05, JS = 9.4e-05



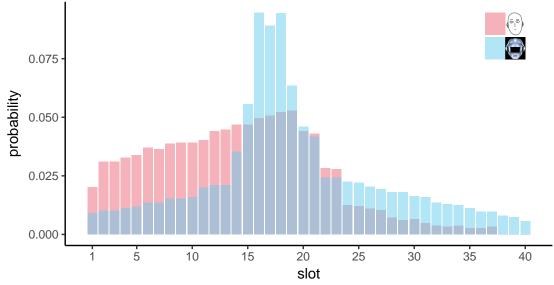
0.04

participant #30, observation 4, rel-entr. = 0.00092, JS = 0.00095

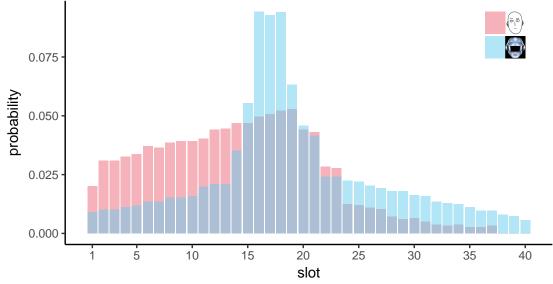




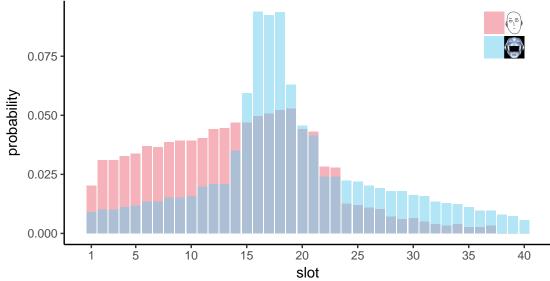
participant #30, observation 100, rel-entr. = 0.38, JS = 0.32



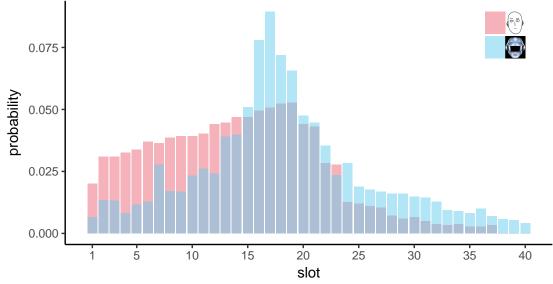
participant #30, observation 101, rel-entr. = 0.38, JS = 0.32



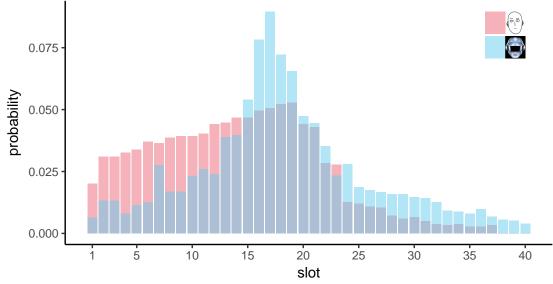
participant #30, observation 102, rel-entr. = 0.38, JS = 0.32



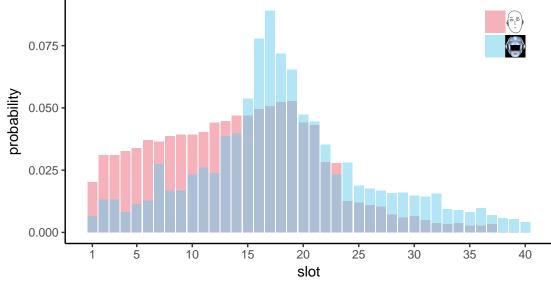
participant #30, observation 197, rel-entr. = 0.26, JS = 0.23



participant #30, observation 198, rel-entr. = 0.26, JS = 0.23



participant #30, observation 199, rel-entr. = 0.26, JS = 0.23



participant #30, observation 200, rel-entr. = 0.27, JS = 0.23

