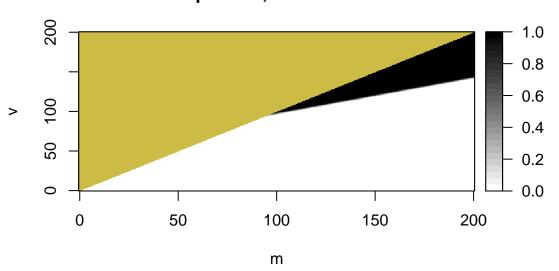
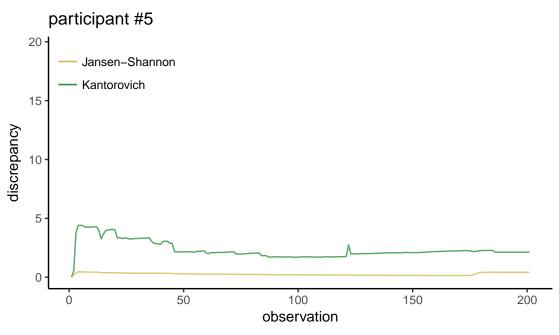


h for part. #5, stubbornness = 195





participant #5, sqrt(robot-participant)

