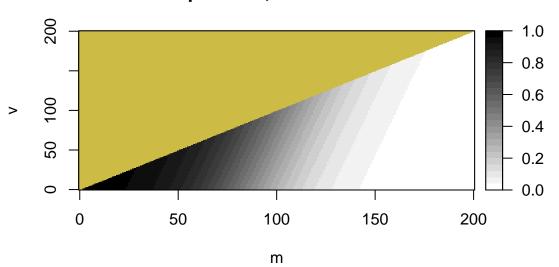
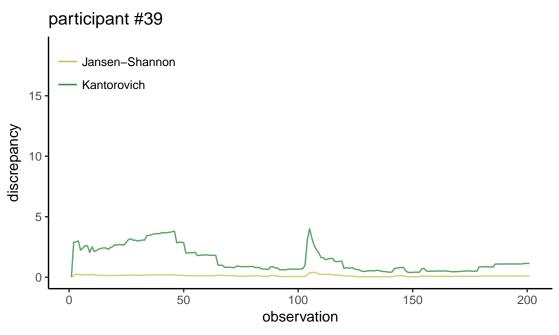


h for part. #39, stubbornness = 1.08





participant #39, sqrt(robot-participant)

