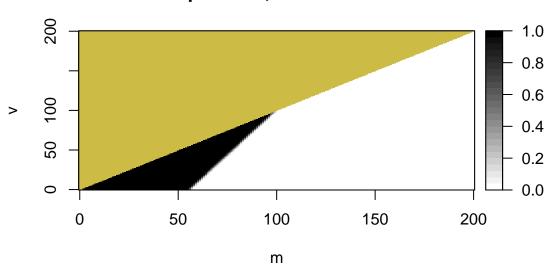
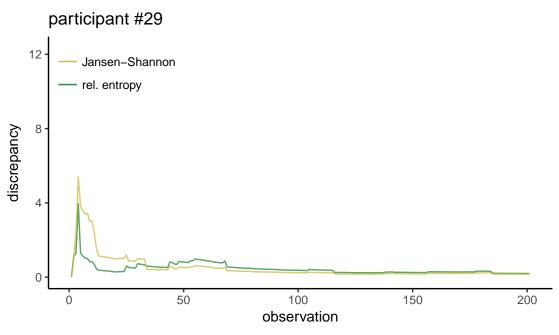
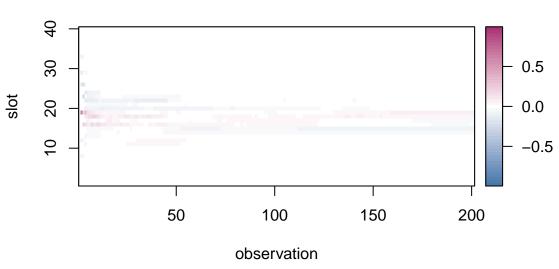


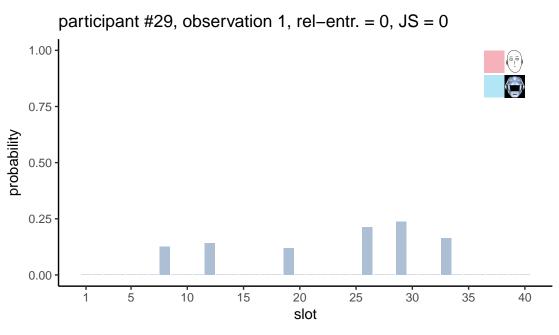
h for part. #29, stubbornness = 0.36

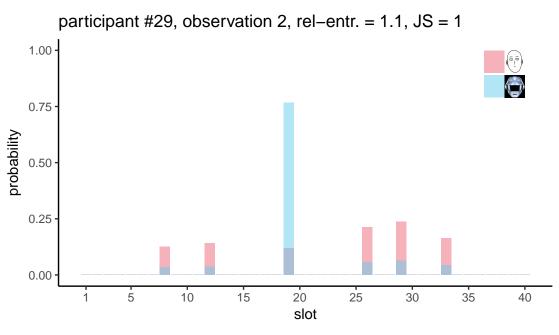




participant #29, sqrt(robot-participant)

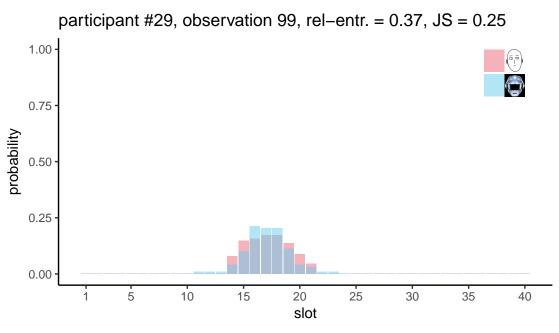






participant #29, observation 3, rel-entr. = 1.3, JS = 2.5 1.00 0.75 probability 0.25 0.00 10 15 25 30 5 20 35 40 slot

participant #29, observation 4, rel-entr. = 4, JS = 5.4 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot



participant #29, observation 100, rel-entr. = 0.37, JS = 0.25 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 101, rel-entr. = 0.37, JS = 0.25 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 102, rel-entr. = 0.36, JS = 0.24 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 197, rel-entr. = 0.2, JS = 0.16 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 198, rel-entr. = 0.2, JS = 0.16 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 199, rel-entr. = 0.2, JS = 0.16 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 200, rel-entr. = 0.2, JS = 0.16 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot