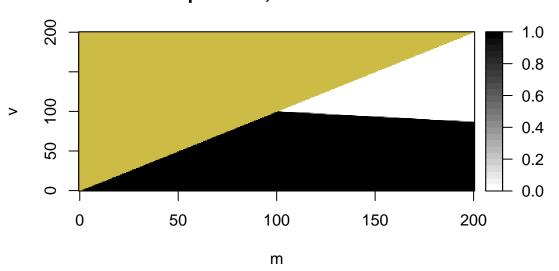
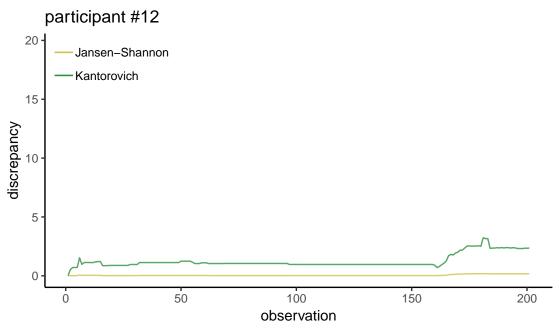


h for part. #12, stubbornness = 17.7





participant #12, sqrt(robot-participant)

