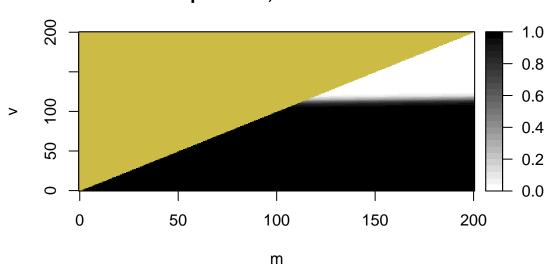
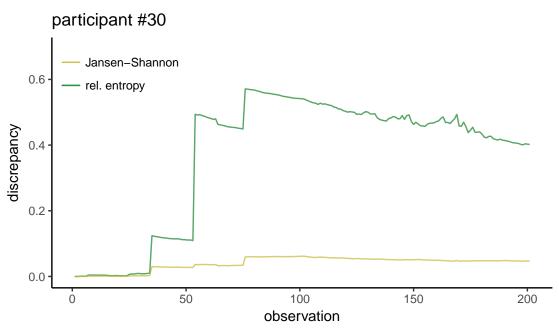
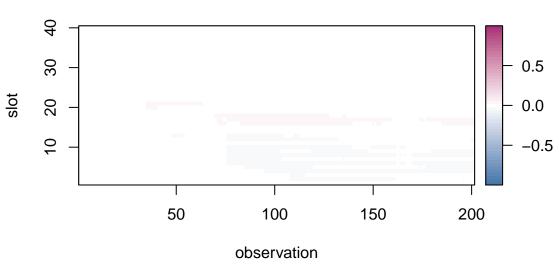


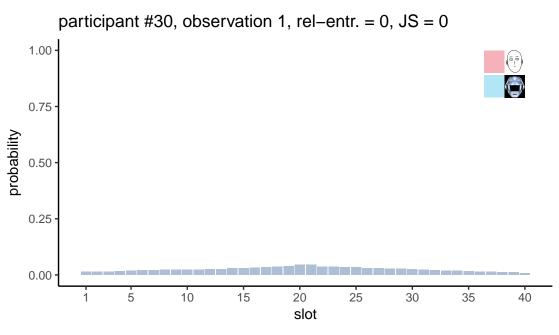
h for part. #30, stubbornness = 211





participant #30, sqrt(robot-participant)

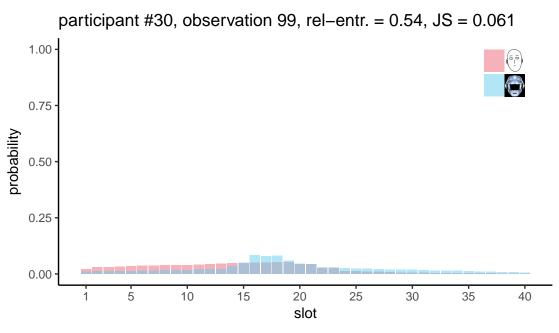




participant #30, observation 2, rel-entr. = 1.4e-07, JS = 3.4e-08 1.00 0.75 probability 0.25 0.00 5 10 15 25 20 30 35 40 slot

participant #30, observation 3, rel-entr. = 8.2e-05, JS = 2.1e-05 1.00 0.75 probability 0.25 0.00 5 10 15 25 20 30 35 40 slot

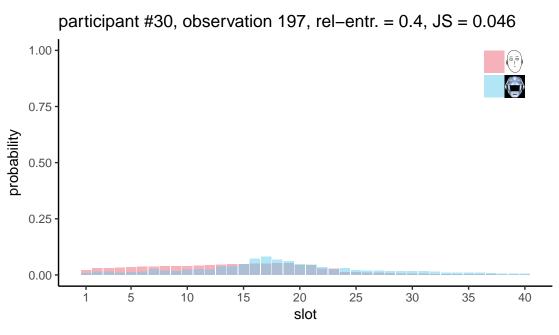
participant #30, observation 4, rel-entr. = 0.00087, JS = 0.00022 1.00 0.75 probability 0.25 0.00 5 10 15 25 20 30 35 40 slot

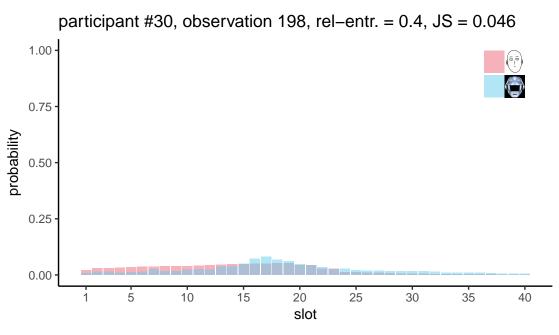


participant #30, observation 100, rel-entr. = 0.54, JS = 0.061 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 35 30 40 slot

participant #30, observation 101, rel-entr. = 0.54, JS = 0.062 1.00 0.75 probability 0.25 0.00 5 10 15 20 25 30 35 40 slot

participant #30, observation 102, rel-entr. = 0.54, JS = 0.062 1.00 0.75 probability 0.25 0.00 5 10 15 20 25 30 35 40 slot





participant #30, observation 199, rel-entr. = 0.4, JS = 0.047 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 35 30 40 slot

participant #30, observation 200, rel-entr. = 0.4, JS = 0.047 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 30 35 40 slot