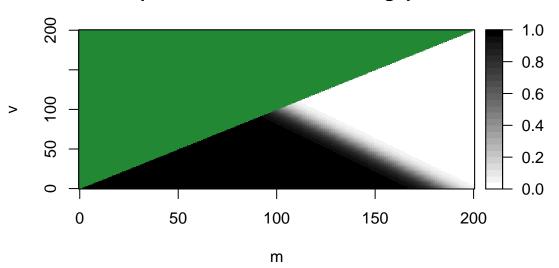
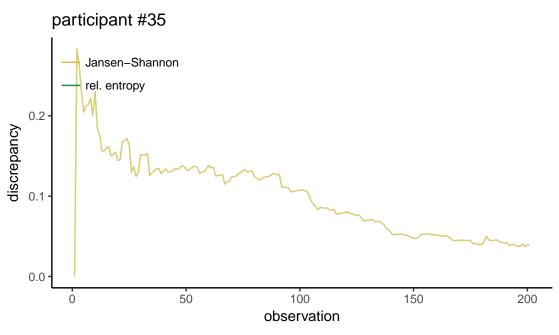
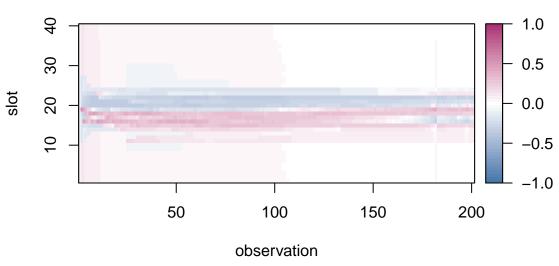


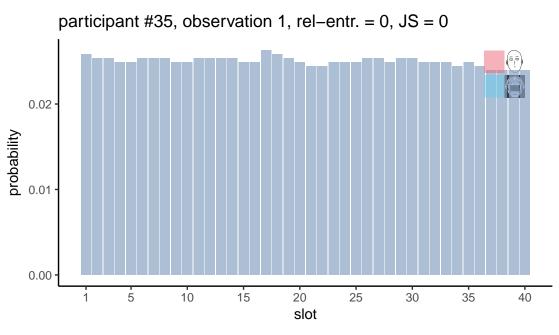
## part. #35, stub. = 1.55, changepoint:





## participant #35, sqrt(robot-participant)





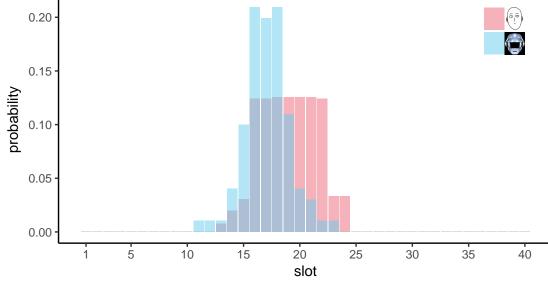
participant #35, observation 2, rel-entr. = 5.5, JS = 0.28 0.4 0.3 probability 0.1 0.0 30 10 15 25 20 35 40 slot

participant #35, observation 3, rel-entr. = 4.1, JS = 0.26 0.3 probability 0.0 15 25 30 10 20 35 40 slot

participant #35, observation 4, rel-entr. = 3.2, JS = 0.23 0.20 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

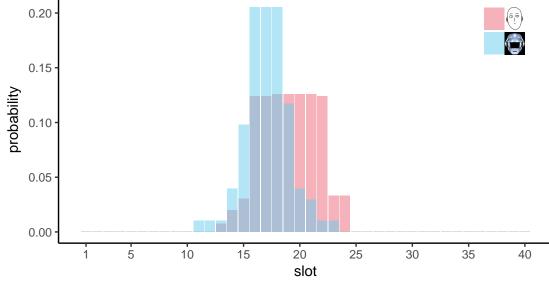
participant #35, observation 99, rel-entr. = 0.73, JS = 0.11 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #35, observation 100, rel-entr. = 0.73, JS = 0.11

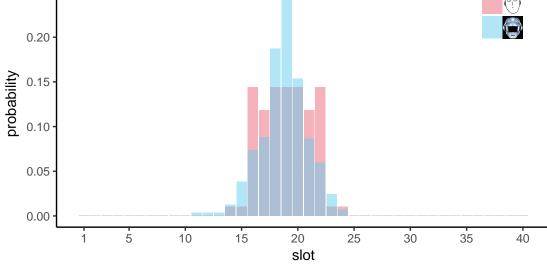


participant #35, observation 101, rel-entr. = 0.72, JS = 0.11 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #35, observation 102, rel-entr. = 0.72, JS = 0.11



participant #35, observation 197, rel-entr. = 0.32, JS = 0.038 0.25 0.20



participant #35, observation 198, rel-entr. = 0.32, JS = 0.041 0.2 probability 0.0 10 20 25 30 15 35 40 slot

participant #35, observation 199, rel-entr. = 0.34, JS = 0.037 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #35, observation 200, rel-entr. = 0.37, JS = 0.039 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot