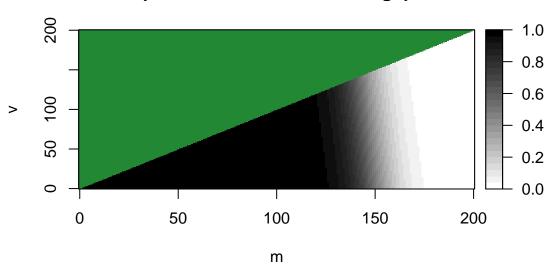
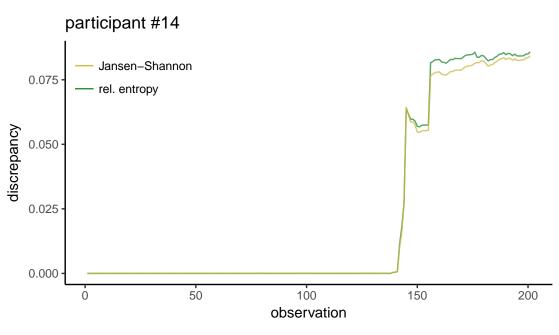
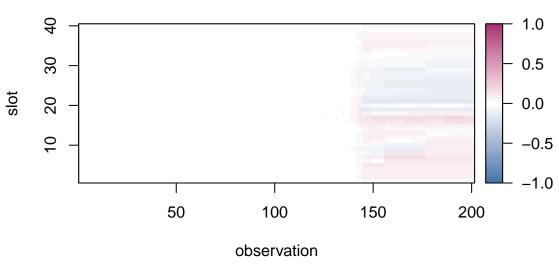


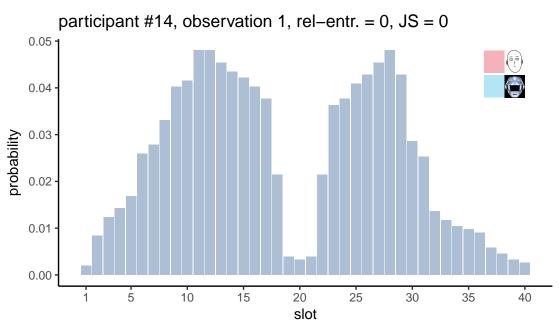
part. #14, stub. = 395, changepoint:





participant #14, sqrt(robot-participant)



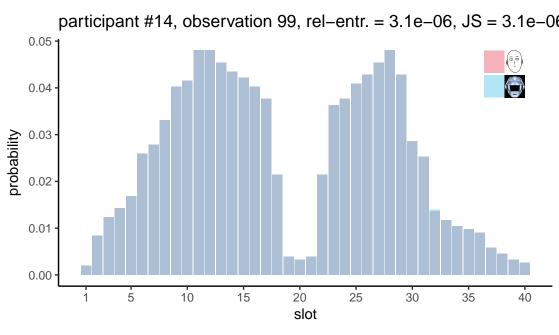


participant #14, observation 2, rel-entr. = 2.8e-07, JS = 2.8e-07 0.05 0.04 0.03 probability 0.02 0.01 0.00 15 25 30 5 10 20 35 40

slot

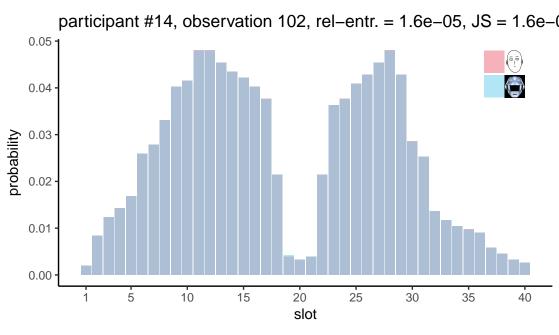
participant #14, observation 3, rel-entr. = 3e-07, JS = 3e-07 0.05 0.04 0.03 probability 0.02 0.01 0.00 15 25 30 5 10 20 35 40 slot

participant #14, observation 4, rel-entr. = 4.4e-07, JS = 4.4e-07 0.05 0.04 0.03 probability 0.02 0.01 0.00 15 25 30 5 10 20 35 40 slot

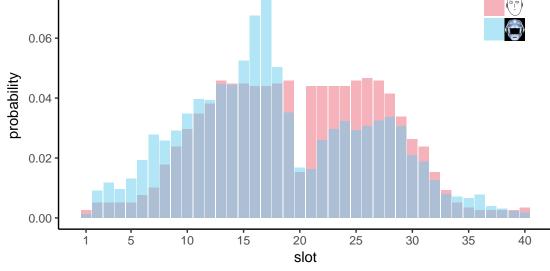


participant #14, observation 100, rel-entr. = 1.1e-06, JS = 1.1e-0 0.05 -0.04 0.03 probability 0.01 0.00 15 25 30 5 10 20 35 40 slot

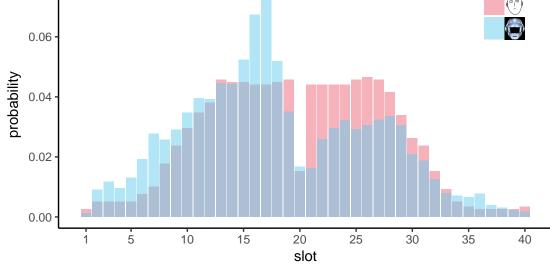
participant #14, observation 101, rel-entr. = 1.1e-05, JS = 1.1e-0 0.05 -0.04 0.03 probability 0.01 0.00 15 25 30 5 10 20 35 40 slot



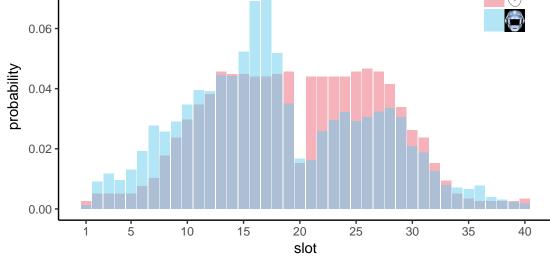
participant #14, observation 197, rel-entr. = 0.084, JS = 0.083 0.06 0.04



participant #14, observation 198, rel-entr. = 0.084, JS = 0.083 0.06



participant #14, observation 199, rel-entr. = 0.085, JS = 0.083 0.06



participant #14, observation 200, rel-entr. = 0.085, JS = 0.084 0.06

