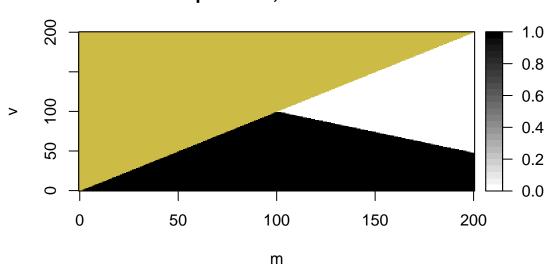
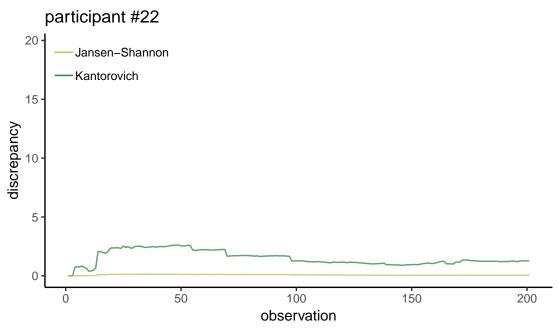


h for part. #22, stubbornness = 14





participant #22, sqrt(robot-participant)

