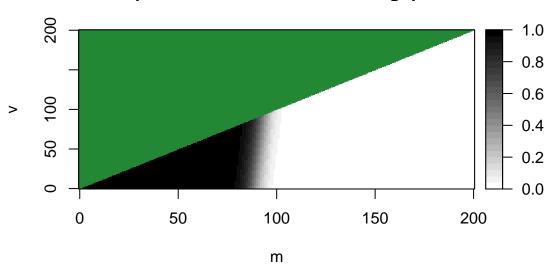
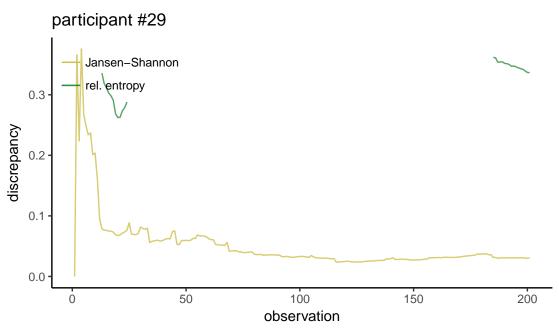
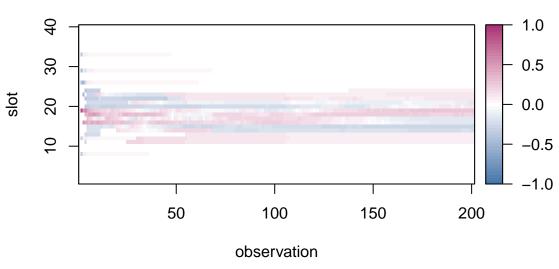


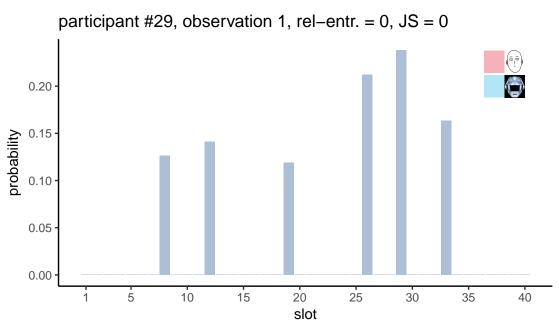
part. #29, stub. = 0.105, changepoint:

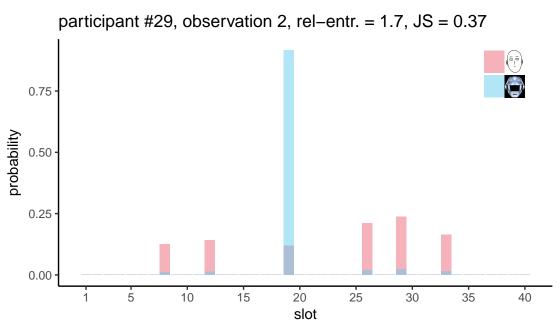


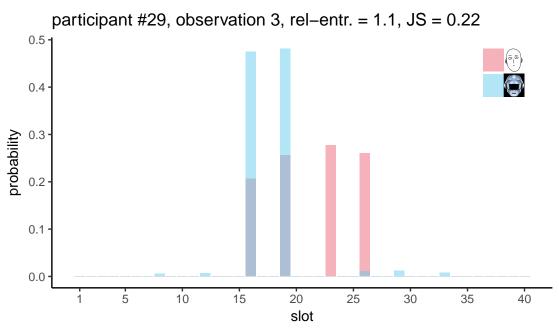


participant #29, sqrt(robot-participant)









participant #29, observation 4, rel-entr. = 6.3, JS = 0.38 0.3 probability 0.2 -0.1 0.0 10 30 35 15 20 25 40 slot

participant #29, observation 99, rel-entr. = 0.72, JS = 0.033 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 100, rel-entr. = 0.72, JS = 0.033 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 101, rel-entr. = 0.71, JS = 0.033 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40

slot

participant #29, observation 102, rel-entr. = 0.7, JS = 0.033 0.20 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #29, observation 197, rel-entr. = 0.34, JS = 0.031 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 198, rel-entr. = 0.34, JS = 0.031 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 199, rel-entr. = 0.34, JS = 0.03 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 200, rel-entr. = 0.34, JS = 0.03 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot