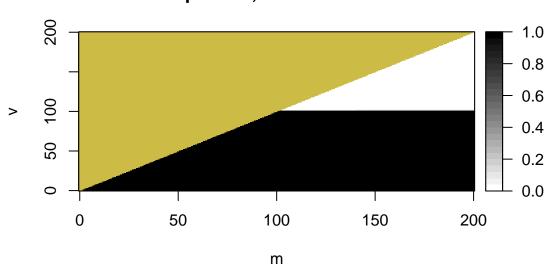
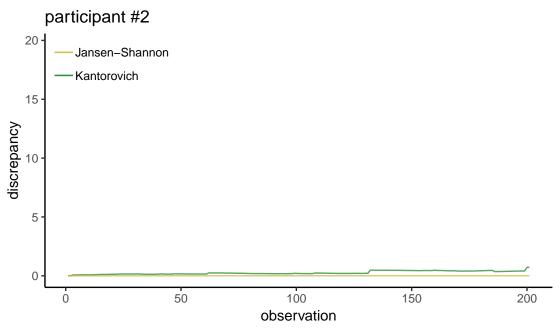
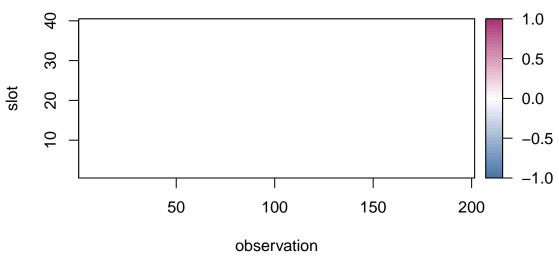


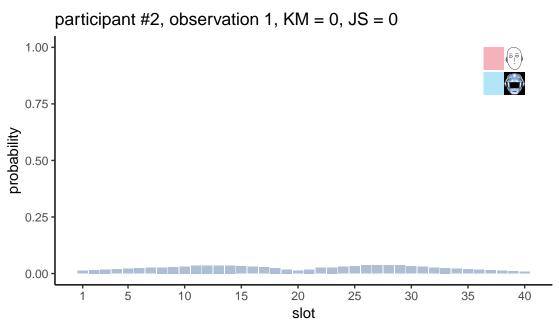
## h for part. #2, stubbornness = 1e+03

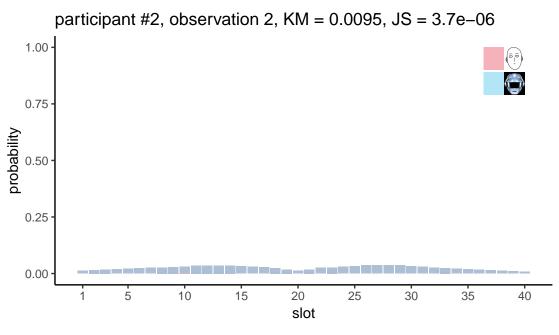


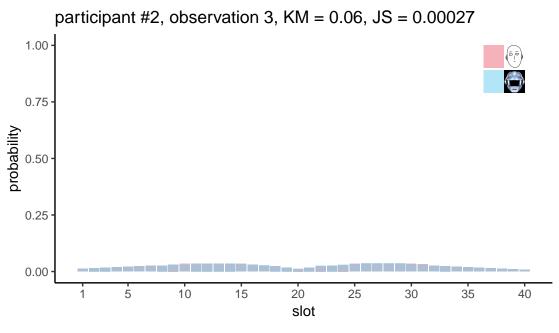


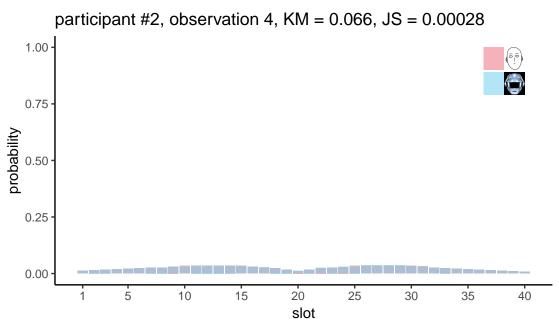
## participant #2, sqrt(robot-participant)

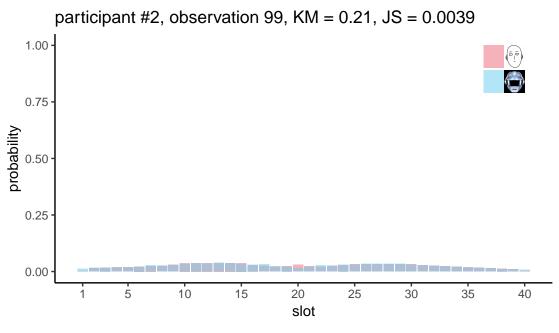


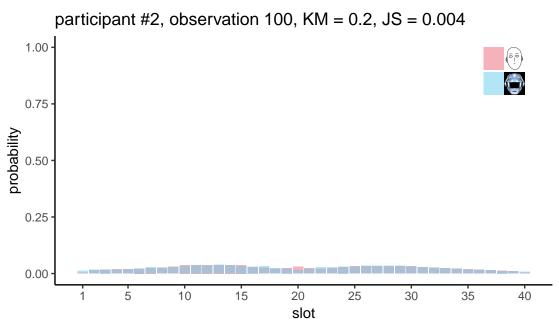


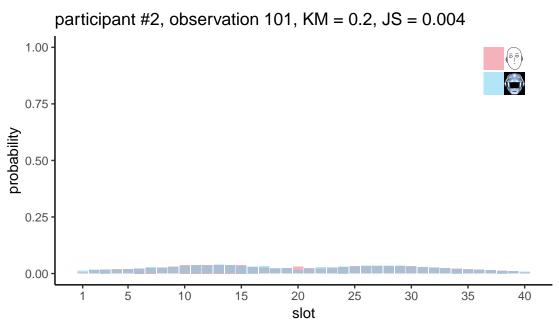


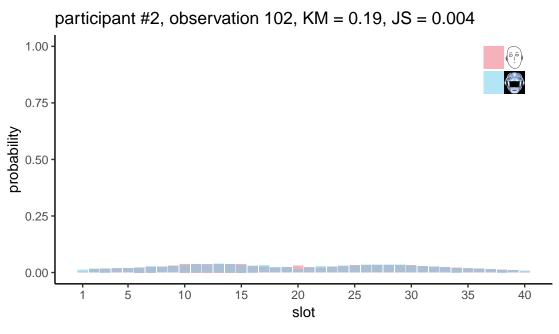


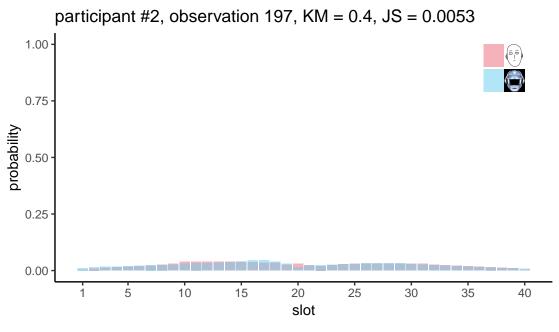


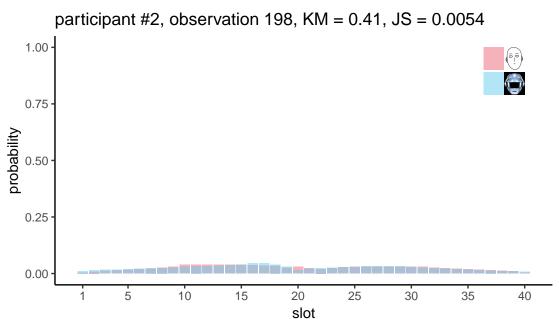


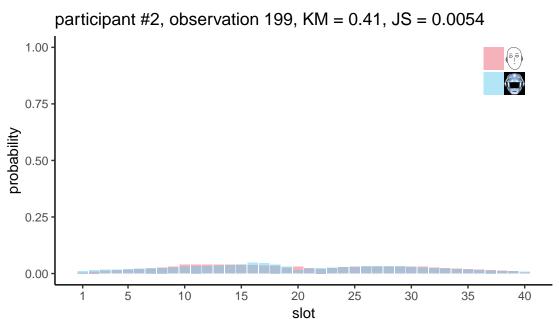












participant #2, observation 200, KM = 0.72, JS = 0.0073 1.00 0.75 probability 05.0 0.25 0.00 10 15 20 25 30 35 40 5 slot