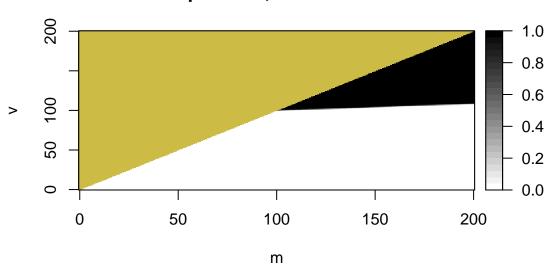
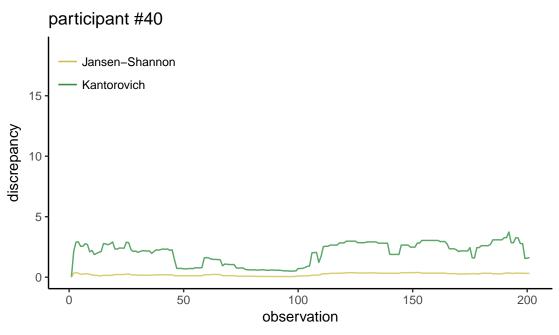


## h for part. #40, stubbornness = 1.27





## participant #40, sqrt(robot-participant)

