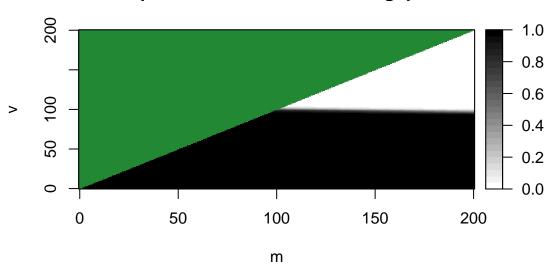
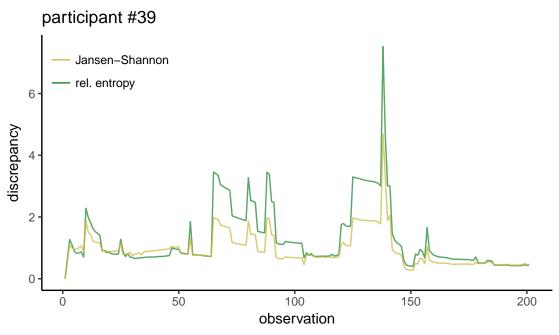
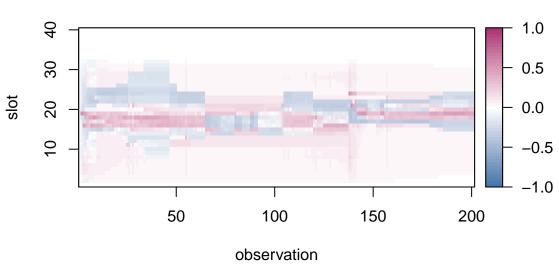


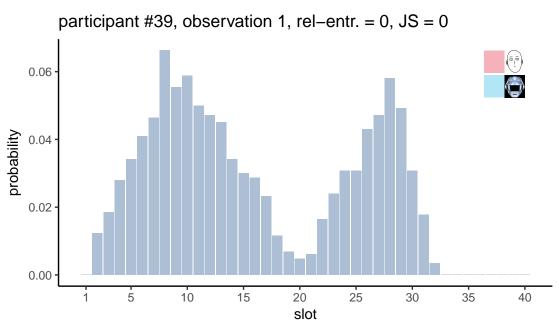
part. #39, stub. = 1.69, changepoint:

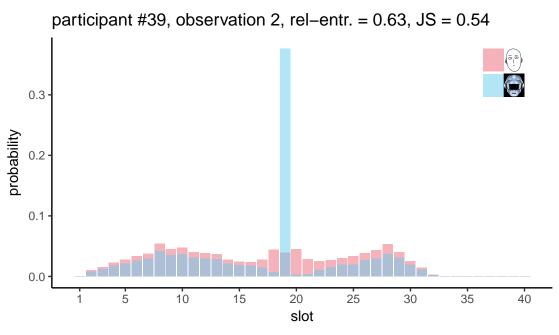


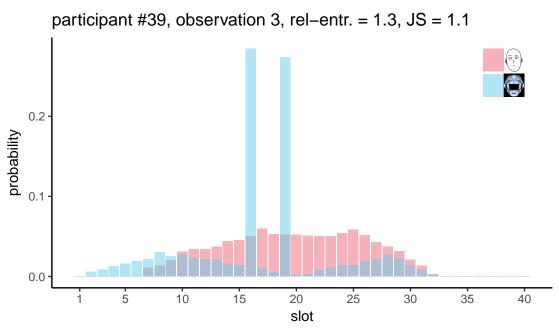


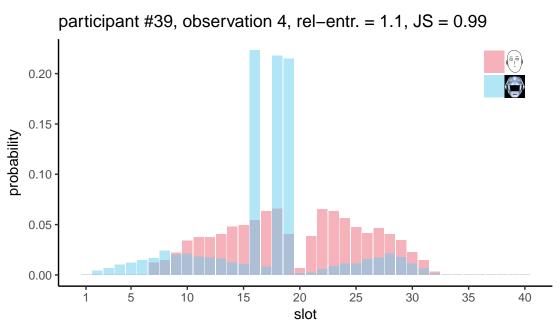
participant #39, sqrt(robot-participant)











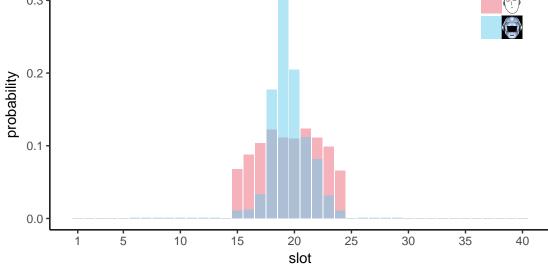
participant #39, observation 99, rel-entr. = 1.2, JS = 0.69 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #39, observation 100, rel-entr. = 1.2, JS = 0.68 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

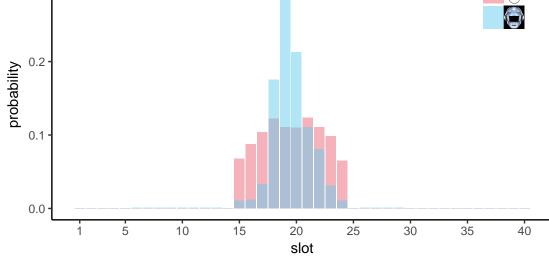
participant #39, observation 101, rel-entr. = 1.2, JS = 0.68 0.20 0.15 probability 0.05 0.00 30 10 15 25 35 5 20 40 slot

participant #39, observation 102, rel-entr. = 1.2, JS = 0.68 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #39, observation 197, rel-entr. = 0.42, JS = 0.45 0.3



participant #39, observation 198, rel-entr. = 0.43, JS = 0.45 0.3



participant #39, observation 199, rel-entr. = 0.46, JS = 0.49 0.3 probability 0.1

20

slot

25

30

35

. 40

10

15

0.0

participant #39, observation 200, rel-entr. = 0.43, JS = 0.46 0.3

