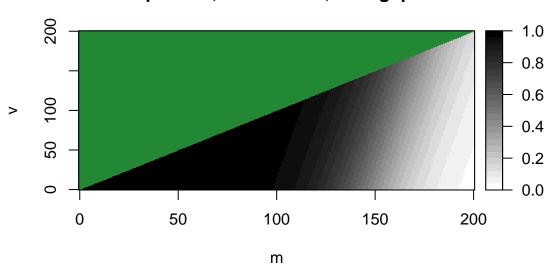
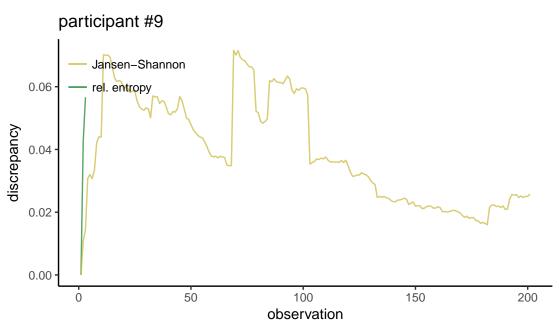
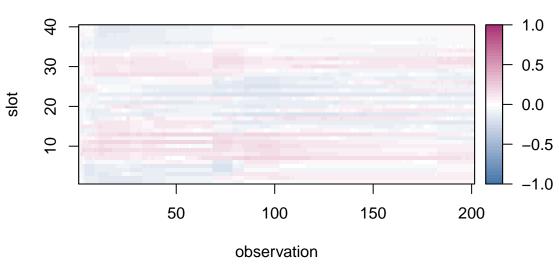


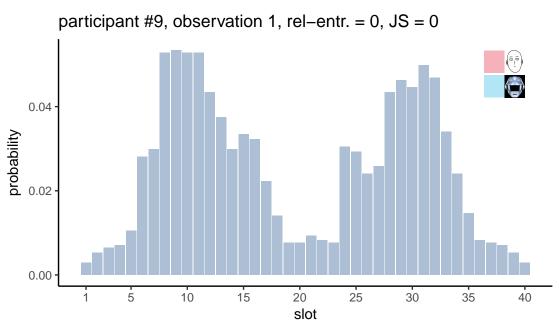
part. #9, stub. = 54.5, changepoint:



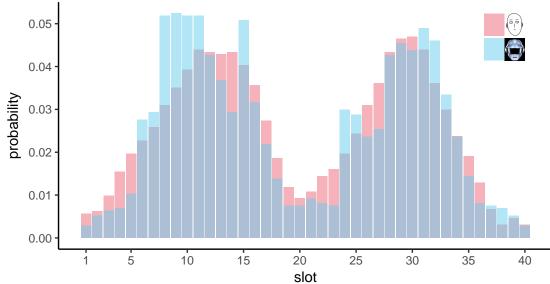


participant #9, sqrt(robot-participant)

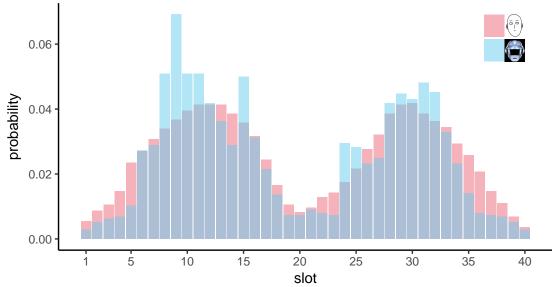


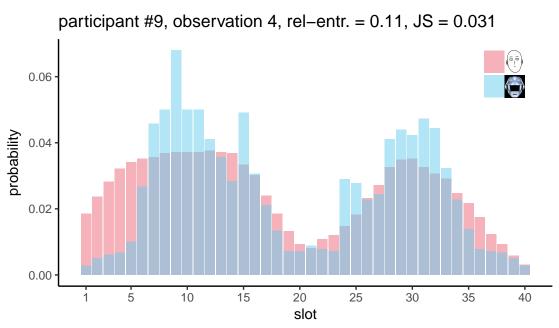


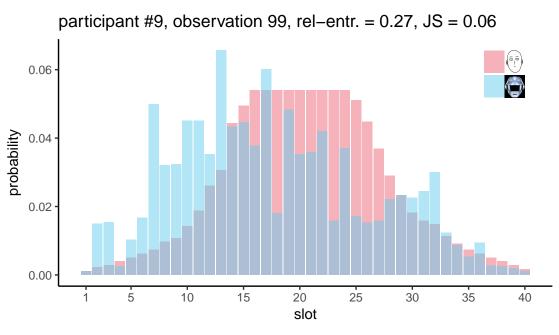
participant #9, observation 2, rel-entr. = 0.042, JS = 0.011

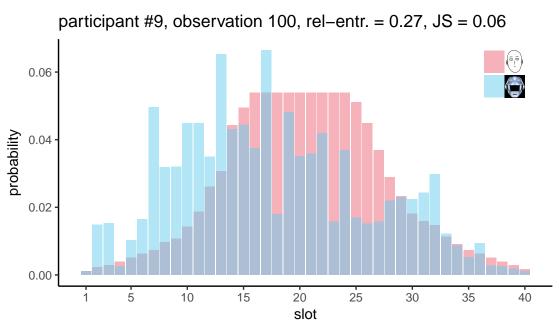


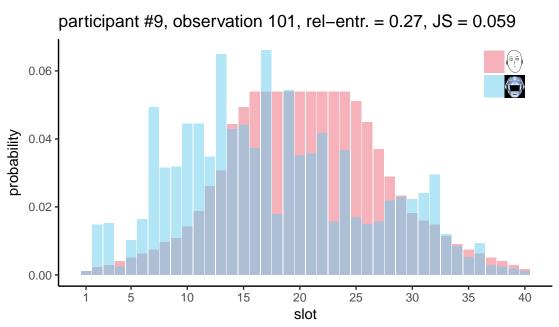
participant #9, observation 3, rel-entr. = 0.057, JS = 0.014



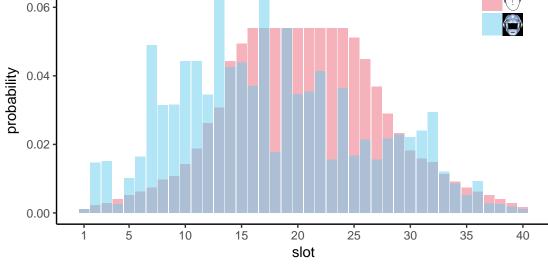




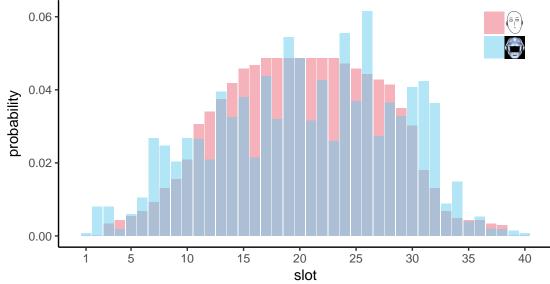




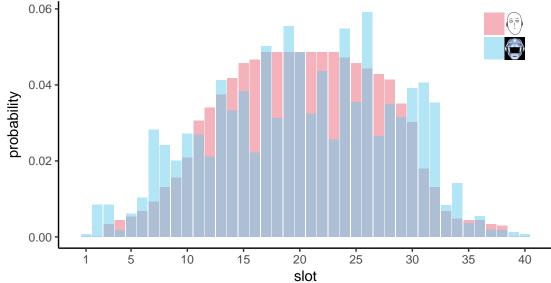
participant #9, observation 102, rel-entr. = 0.26, JS = 0.057 0.06 probability 0.04



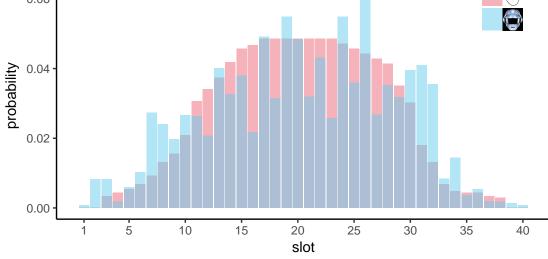
participant #9, observation 197, rel-entr. = 0.25, JS = 0.025



participant #9, observation 198, rel-entr. = 0.25, JS = 0.025



participant #9, observation 199, rel-entr. = 0.25, JS = 0.025 0.06 probability 0.04



participant #9, observation 200, rel-entr. = 0.24, JS = 0.025

