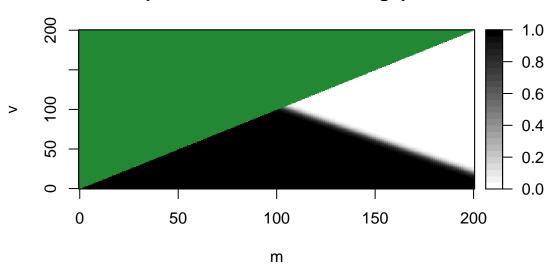
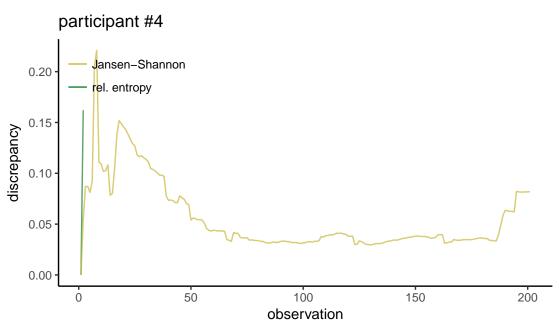
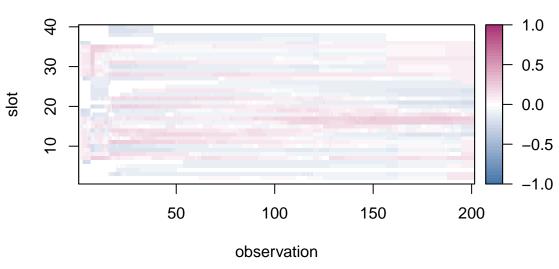


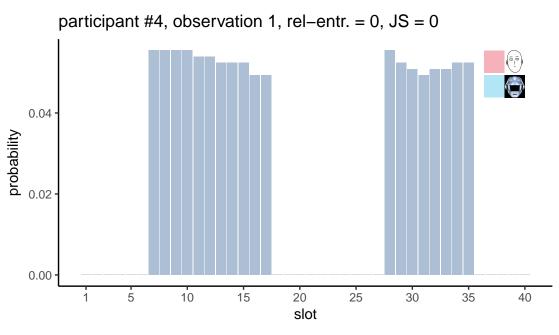
part. #4, stub. = 14.4, changepoint:

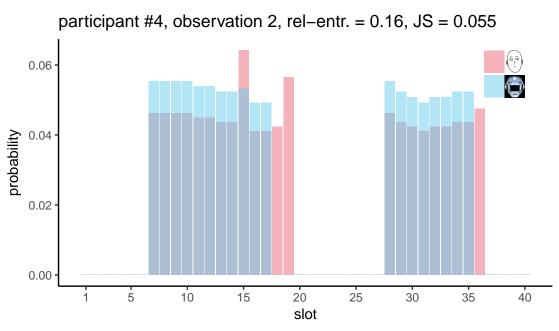


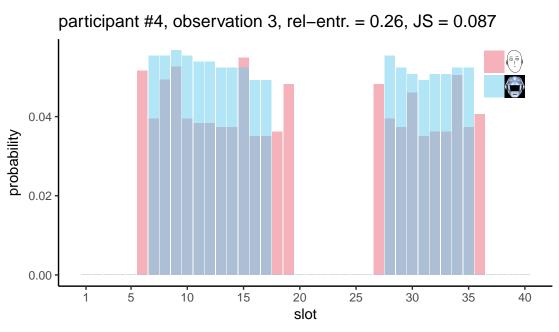


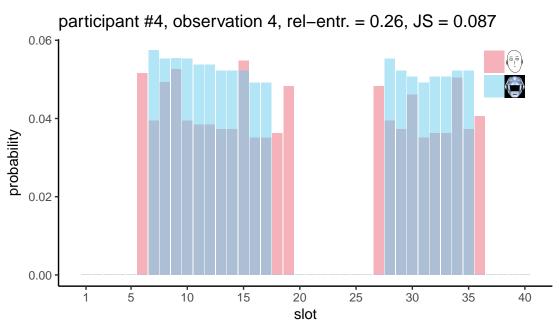
participant #4, sqrt(robot-participant)



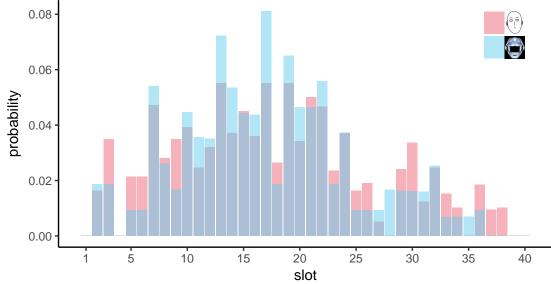




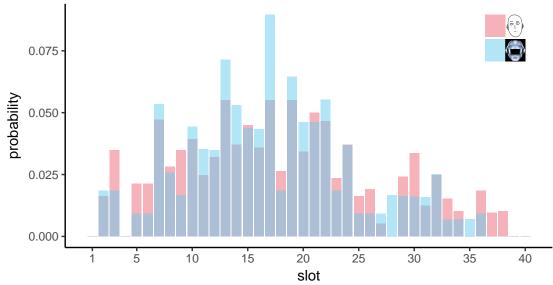




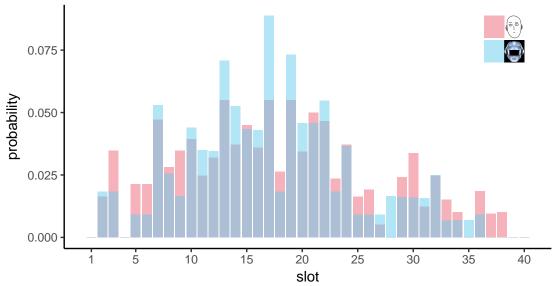
participant #4, observation 99, rel-entr. = 0.44, JS = 0.031



participant #4, observation 100, rel-entr. = 0.44, JS = 0.032



participant #4, observation 101, rel-entr. = 0.44, JS = 0.032



participant #4, observation 102, rel-entr. = 0.43, JS = 0.032

