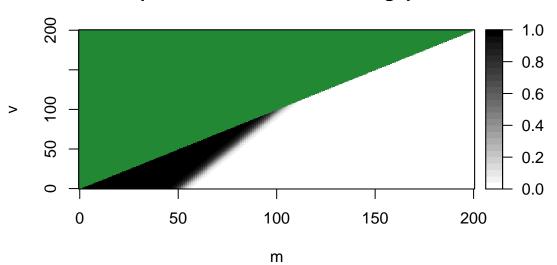
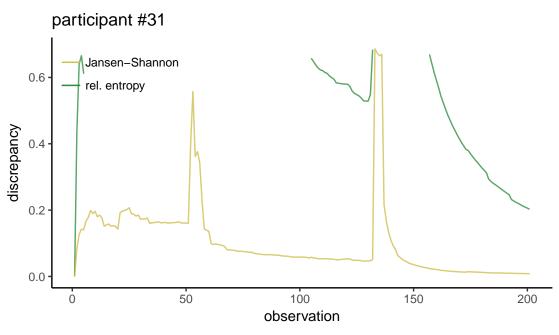
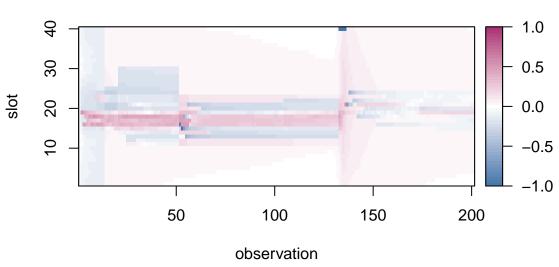


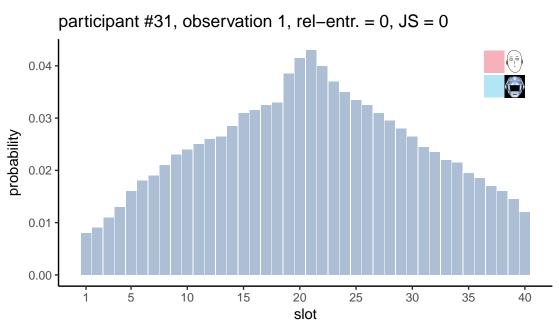
part. #31, stub. = 2.05, changepoint:

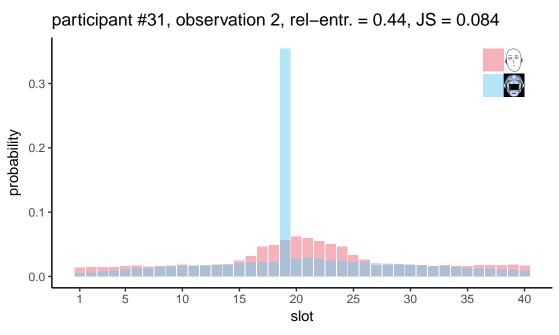


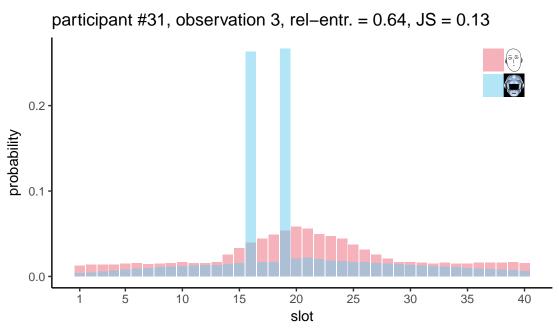


participant #31, sqrt(robot-participant)





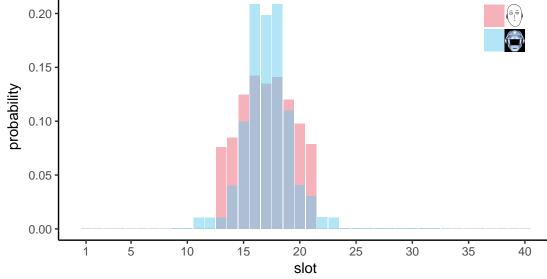




participant #31, observation 4, rel-entr. = 0.67, JS = 0.14 0.20 0.15 probability 0.10 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #31, observation 99, rel-entr. = 0.82, JS = 0.058 0.20 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #31, observation 100, rel-entr. = 0.81, JS = 0.058



participant #31, observation 101, rel-entr. = 0.8, JS = 0.058 0.20 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #31, observation 102, rel-entr. = 0.8, JS = 0.058 0.20 0.15 probability 0.05

15

20

slot

10

25

30

35

40

0.00

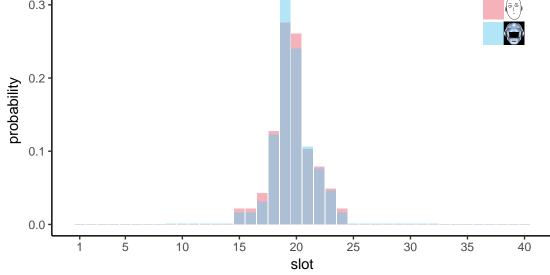
5

participant #31, observation 197, rel-entr. = 0.22, JS = 0.0089 0.3 probability 0.2 -0.1 0.0 10 15 25 30 20 35 40

slot

participant #31, observation 198, rel-entr. = 0.21, JS = 0.0087 0.3 0.2 probability 0.1 0.0 10 15 25 30 20 35 40 slot

participant #31, observation 199, rel-entr. = 0.21, JS = 0.0086



participant #31, observation 200, rel-entr. = 0.21, JS = 0.0085

