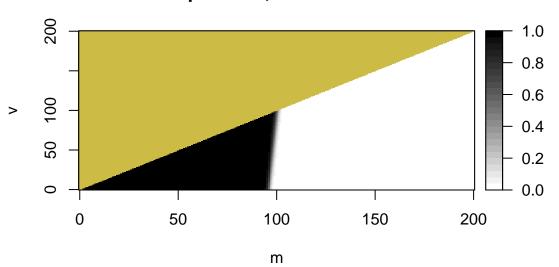
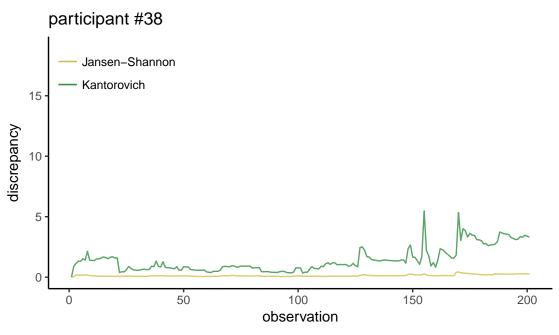


h for part. #38, stubbornness = 2.07





participant #38, sqrt(robot-participant)

