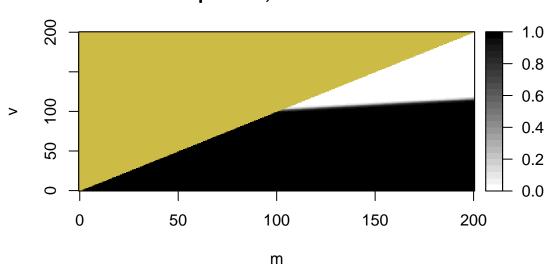
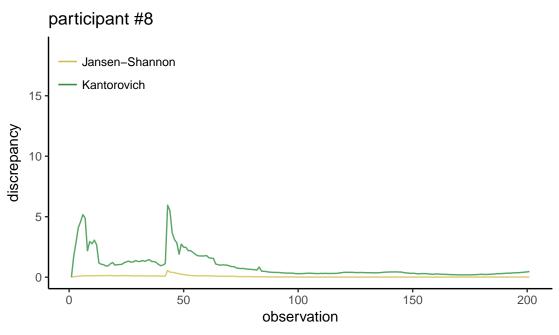


## h for part. #8, stubbornness = 5.2





## participant #8, sqrt(robot-participant)

