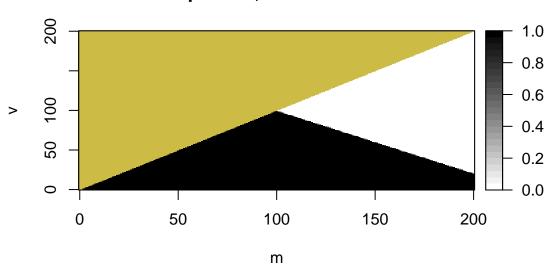
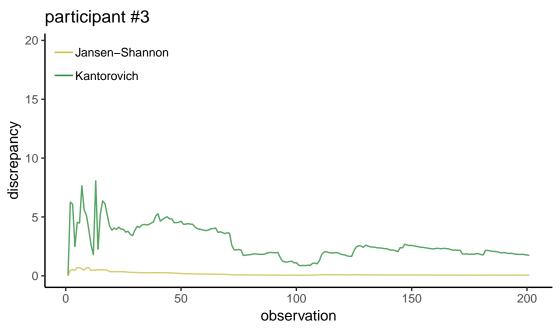


## h for part. #3, stubbornness = 0.001





## participant #3, sqrt(robot-participant)

