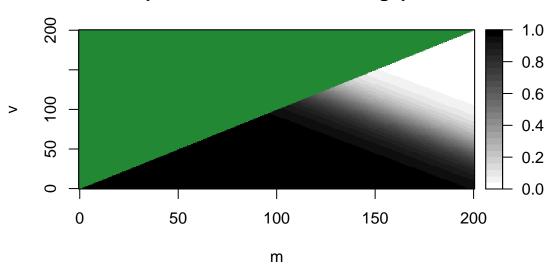
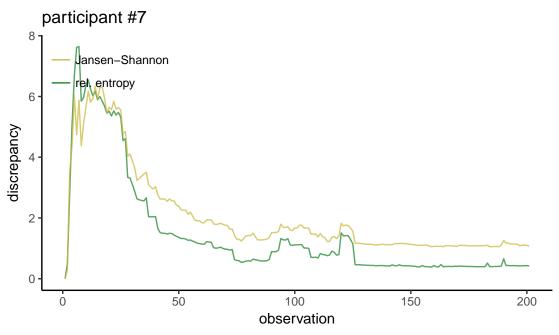
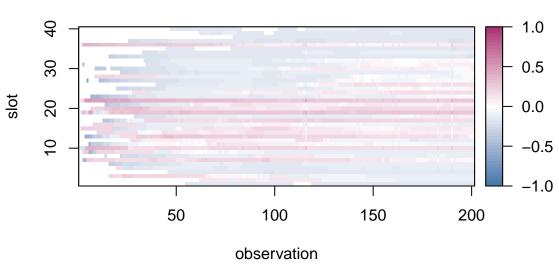


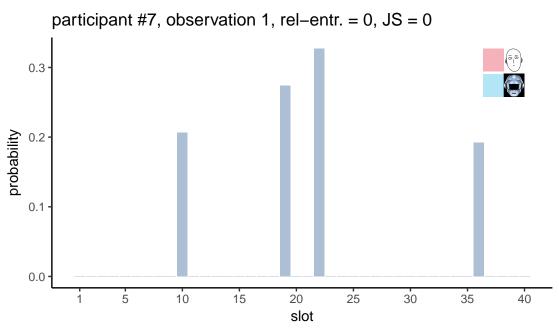
part. #7, stub. = 14.7, changepoint:



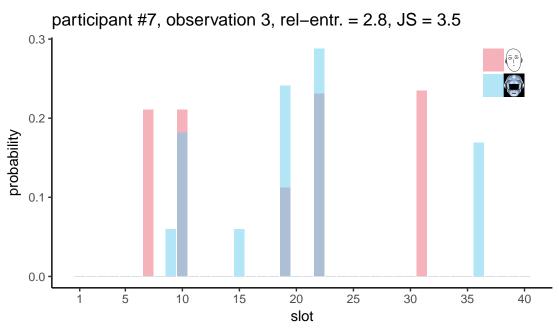


participant #7, sqrt(robot-participant)



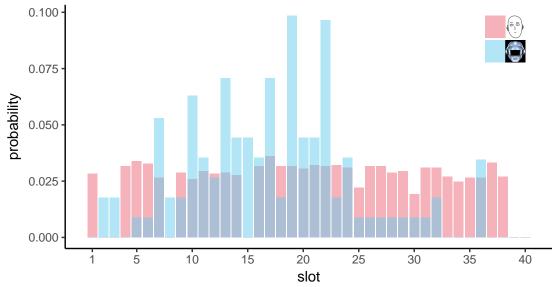


participant #7, observation 2, rel-entr. = 0.48, JS = 0.28 0.3 probability 0.1 0.0 10 15 30 25 20 35 40 slot

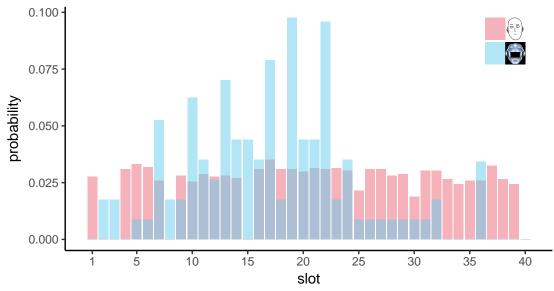


participant #7, observation 4, rel-entr. = 5, JS = 4.3 0.3 probability 0.1 0.0 10 15 30 20 25 35 40 slot

participant #7, observation 99, rel-entr. = 1.1, JS = 1.6

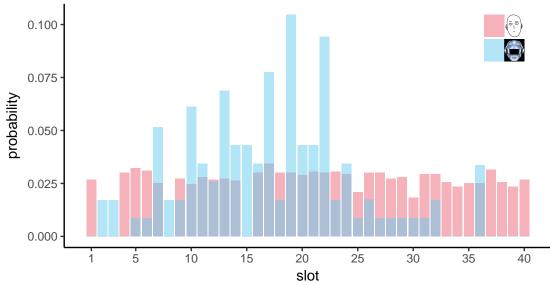


participant #7, observation 100, rel-entr. = 1.1, JS = 1.7

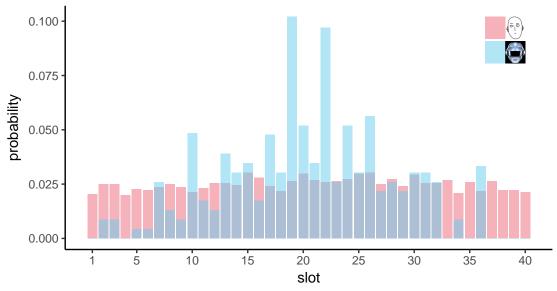


participant #7, observation 101, rel-entr. = 1.1, JS = 1.7 0.09 probability 0.06 0.03 0.00 15 25 30 5 10 20 35 40 slot

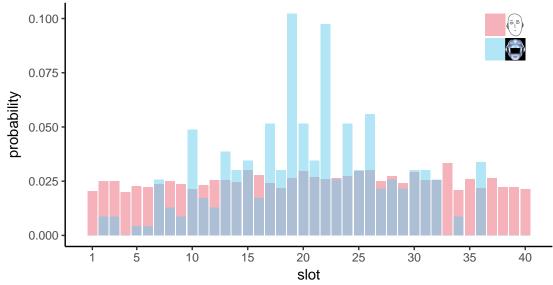
participant #7, observation 102, rel-entr. = 1.1, JS = 1.8



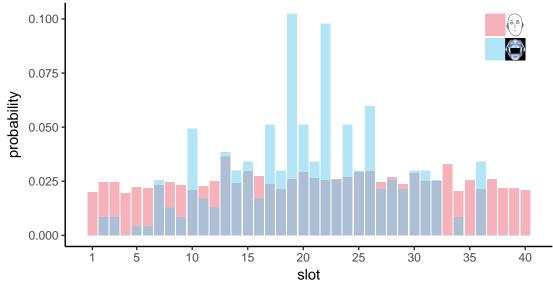
participant #7, observation 197, rel-entr. = 0.42, JS = 1.1



participant #7, observation 198, rel-entr. = 0.43, JS = 1.1



participant #7, observation 199, rel-entr. = 0.43, JS = 1.1



participant #7, observation 200, rel-entr. = 0.43, JS = 1.1

