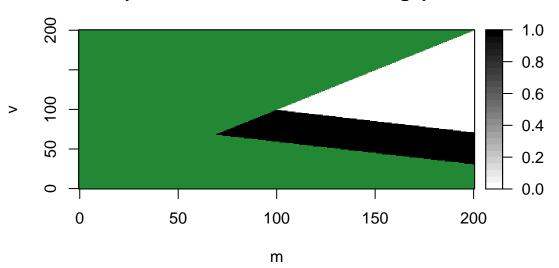
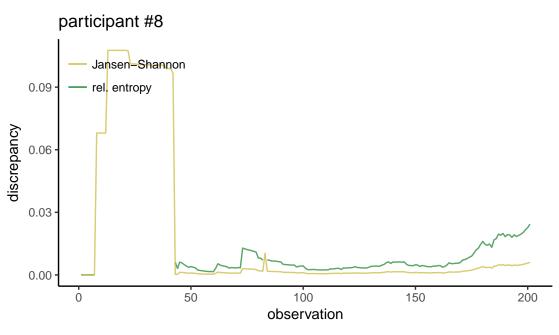
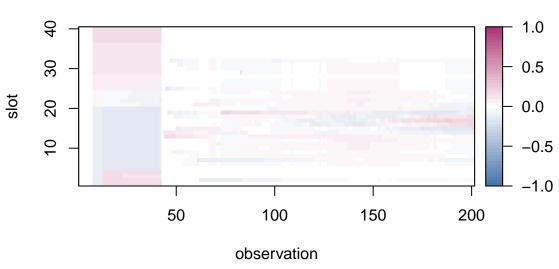


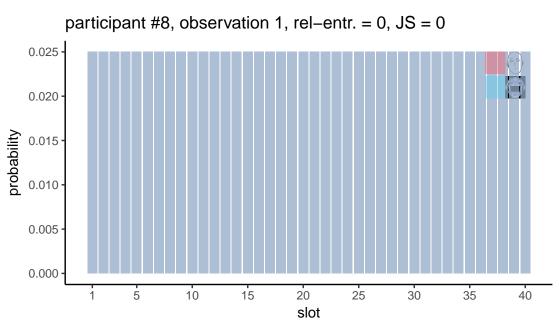
part. #8, stub. = 0.000871, changepoint:



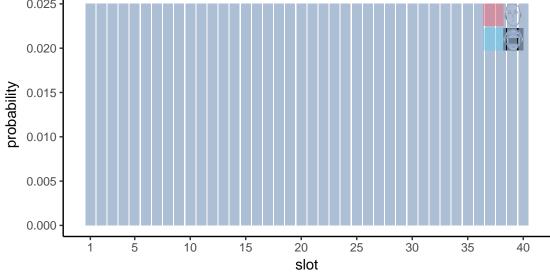


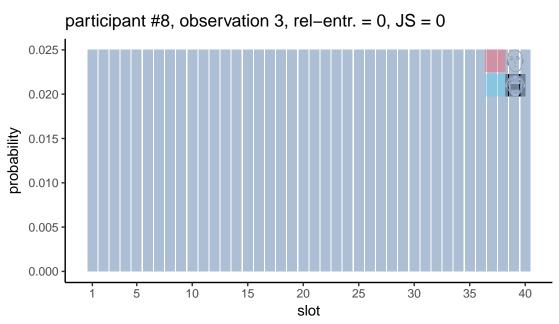
participant #8, sqrt(robot-participant)



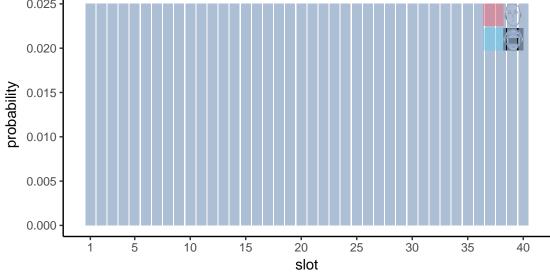


participant #8, observation 2, rel-entr. = 2.2e-16, JS = 1.1e-16

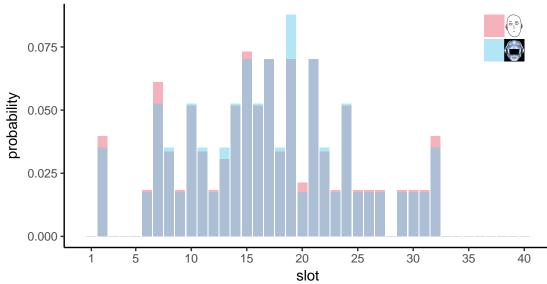




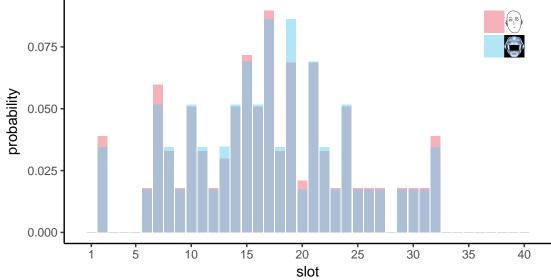
participant #8, observation 4, rel-entr. = 2.2e-16, JS = 1.1e-16



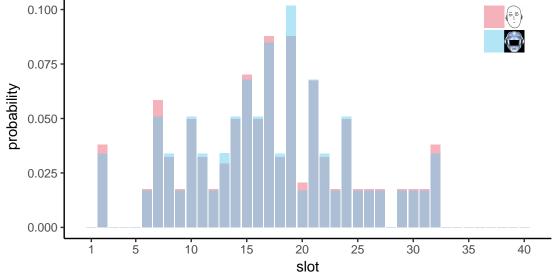
participant #8, observation 99, rel-entr. = 0.0043, JS = 0.0011



participant #8, observation 100, rel-entr. = 0.0043, JS = 0.0011

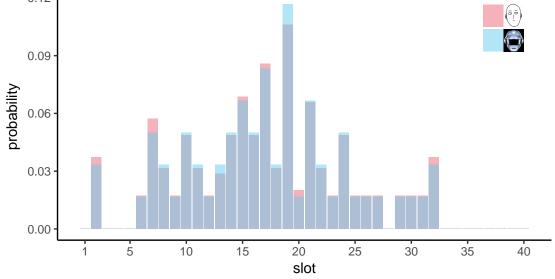


participant #8, observation 101, rel-entr. = 0.0032, JS = 0.00079

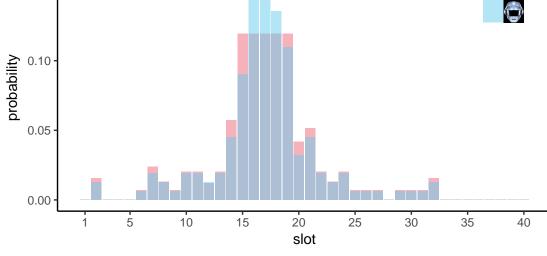


0.12 -

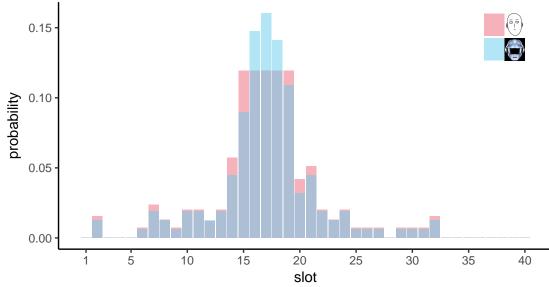
participant #8, observation 102, rel-entr. = 0.0026, JS = 0.00064



participant #8, observation 197, rel-entr. = 0.02, JS = 0.0048 0.15 0.10



participant #8, observation 198, rel-entr. = 0.02, JS = 0.0051



participant #8, observation 199, rel-entr. = 0.022, JS = 0.0054 0.15 probability 0.10 0.05 0.00 15 25 30 5 10 20 35 40

slot

participant #8, observation 200, rel-entr. = 0.023, JS = 0.0056 0.15 probability 0.10 0.05 0.00 15 25 30 35 5 10 20 40 slot