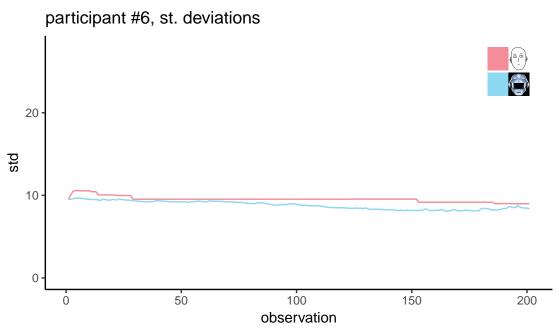
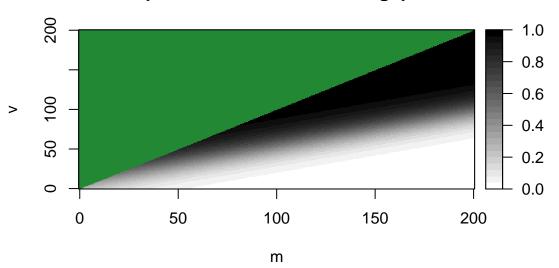
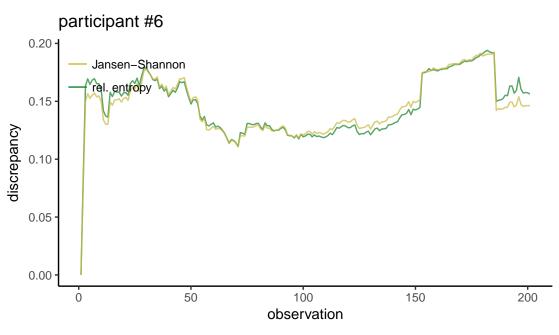


observation

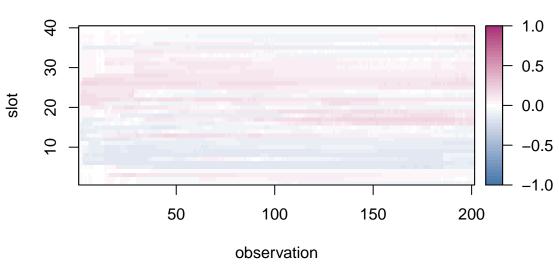


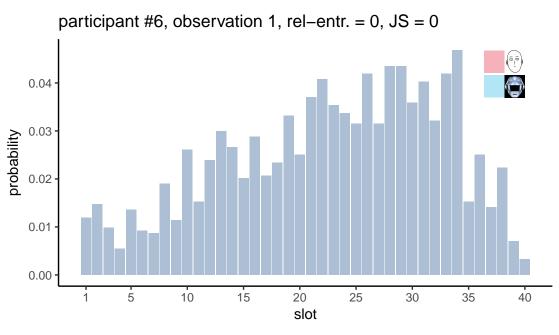
part. #6, stub. = 75.7, changepoint:

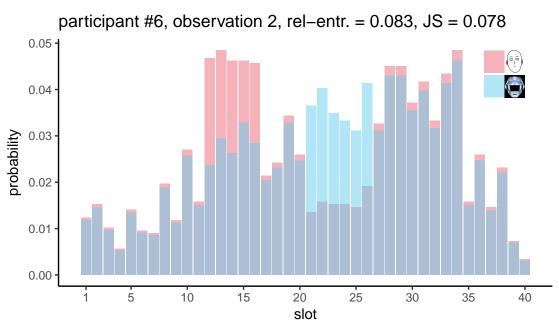


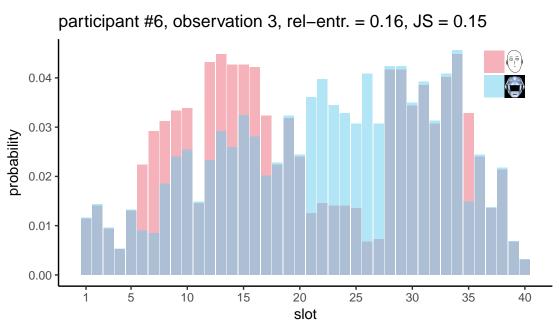


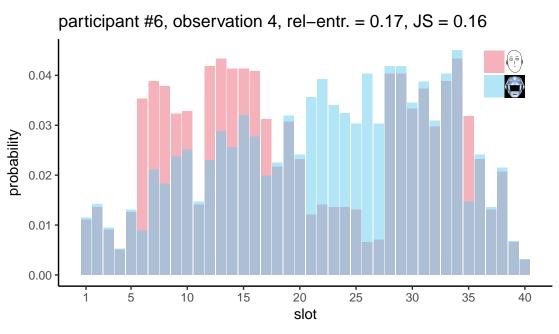
participant #6, sqrt(robot-participant)











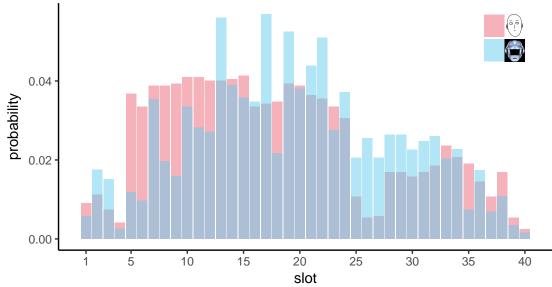
participant #6, observation 99, rel-entr. = 0.12, JS = 0.12 0.04

slot

probability

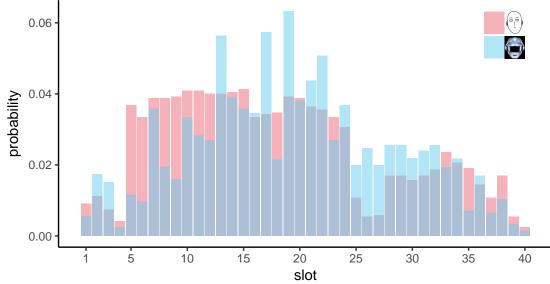
0.00

participant #6, observation 100, rel-entr. = 0.12, JS = 0.12



participant #6, observation 101, rel-entr. = 0.12, JS = 0.12 0.06 -0.04 probability 0.02 0.00 15 25 30 35 5 10 20 40 slot

participant #6, observation 102, rel-entr. = 0.12, JS = 0.12



participant #6, observation 197, rel-entr. = 0.16, JS = 0.15 0.06 probability 0.02 0.00 15 25 30 35 5 10 20 40 slot

participant #6, observation 198, rel-entr. = 0.16, JS = 0.15 0.06 probability 0.04 0.02 0.00 15 25 30 35 5 10 20 40 slot

participant #6, observation 199, rel-entr. = 0.16, JS = 0.15 0.06 probability 0.04 0.02 0.00 15 25 30 35 5 10 20 40 slot

participant #6, observation 200, rel-entr. = 0.16, JS = 0.15 0.06 probability 0.04 0.02 0.00 15 25 30 35 5 10 20 40 slot