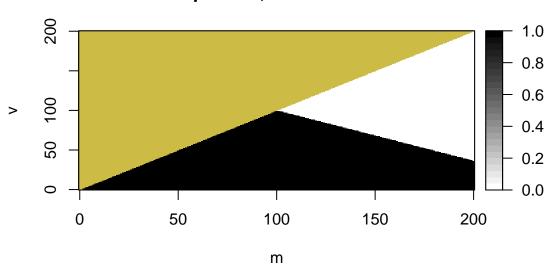
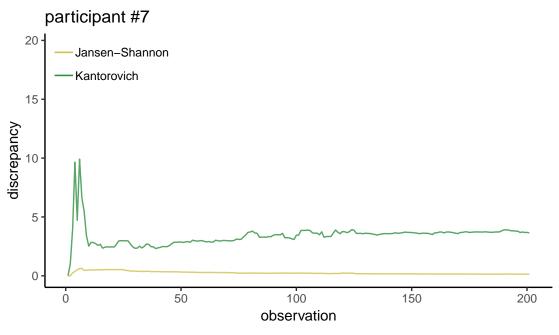


h for part. #7, stubbornness = 81.2





participant #7, sqrt(robot-participant)

