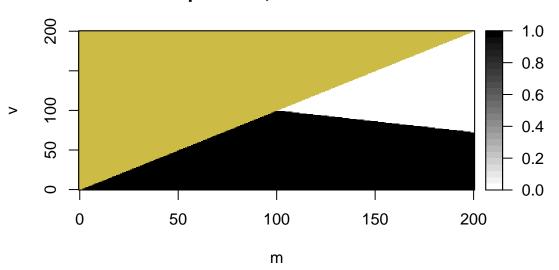
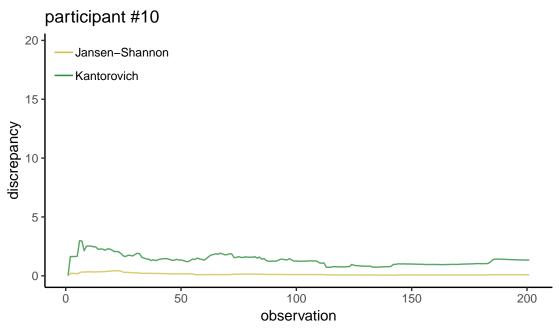


h for part. #10, stubbornness = 36.6





participant #10, sqrt(robot-participant)

