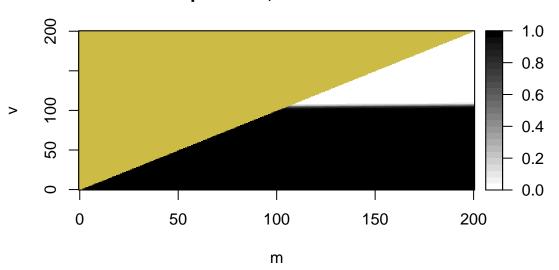
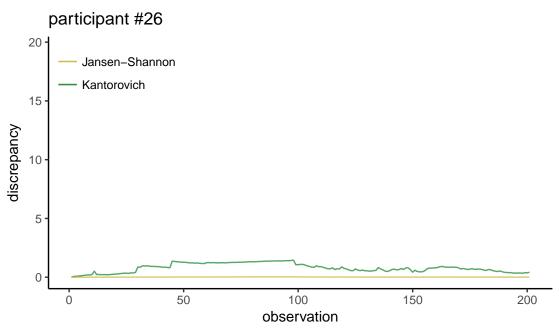


h for part. #26, stubbornness = 120





participant #26, sqrt(robot-participant)

