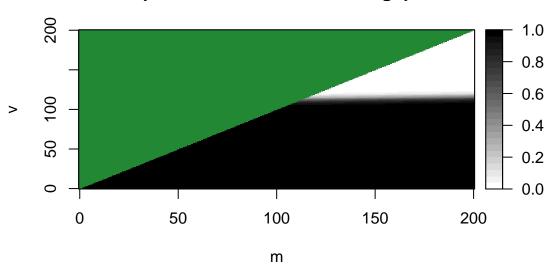
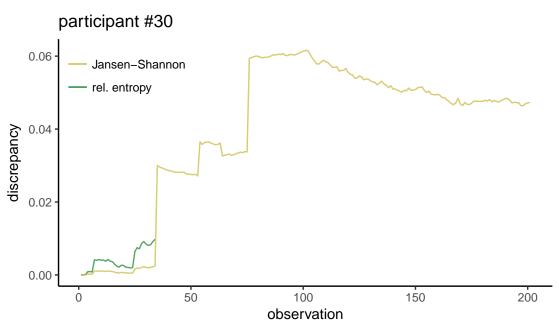
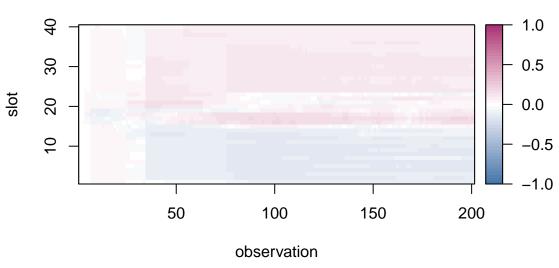


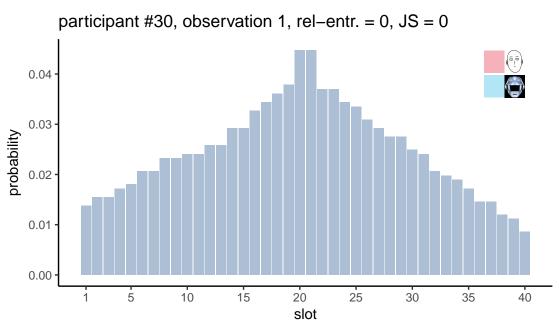
## part. #30, stub. = 211, changepoint:



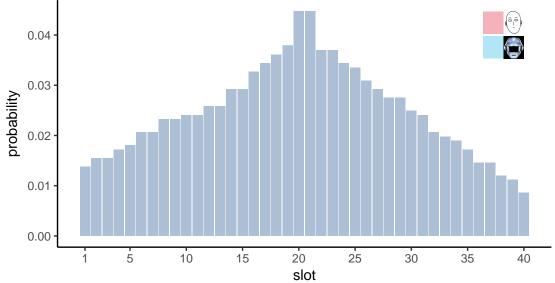


## participant #30, sqrt(robot-participant)

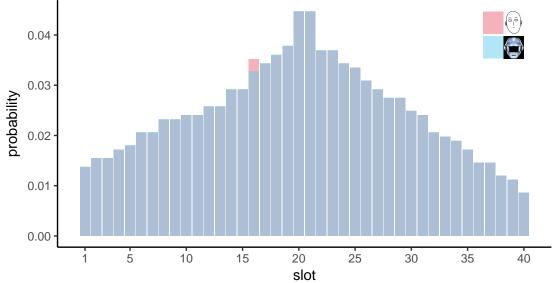




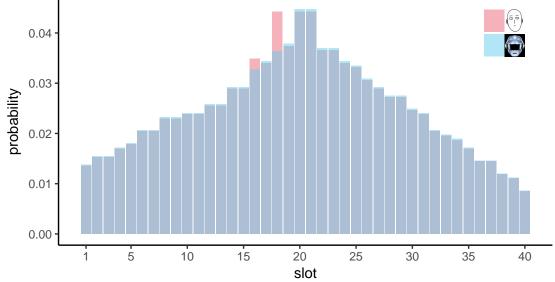
participant #30, observation 2, rel-entr. = 1.4e-07, JS = 3.4e-08



participant #30, observation 3, rel-entr. = 8.2e-05, JS = 2.1e-05



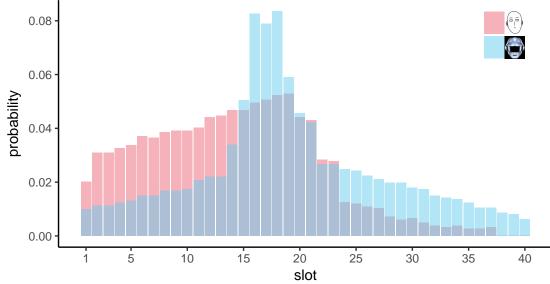
participant #30, observation 4, rel-entr. = 0.00087, JS = 0.00022



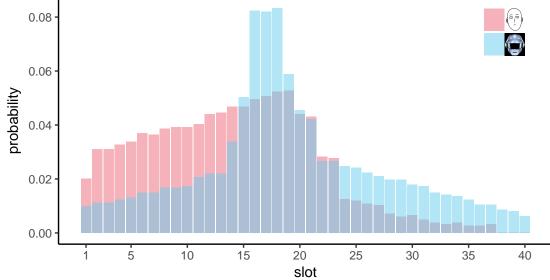
participant #30, observation 99, rel-entr. = 0.54, JS = 0.061 0.08 0.06 probability 0.04 0.02 0.00 15 25 30 5 10 20 35 40

slot

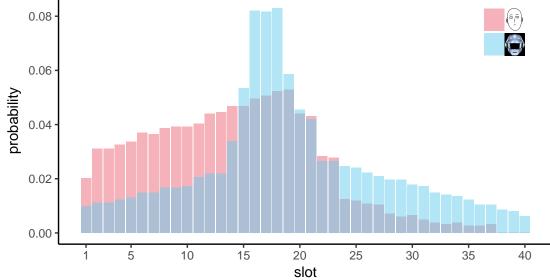
participant #30, observation 100, rel-entr. = 0.54, JS = 0.061



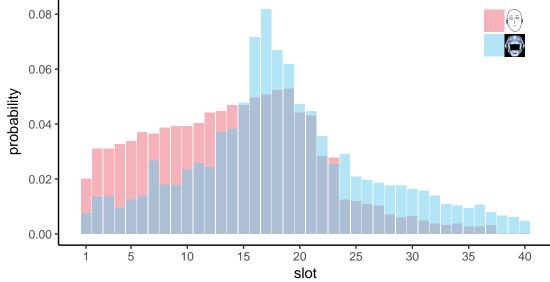
participant #30, observation 101, rel-entr. = 0.54, JS = 0.062



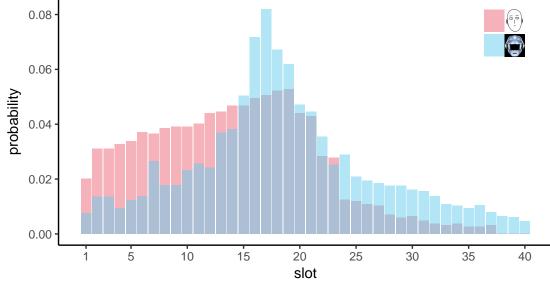
participant #30, observation 102, rel-entr. = 0.54, JS = 0.062



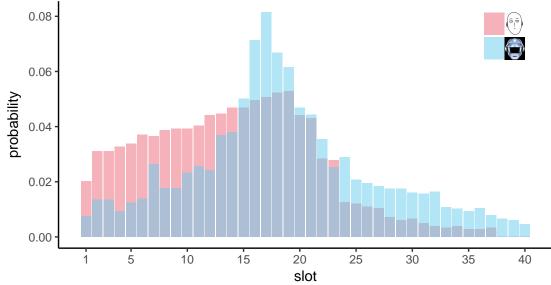
participant #30, observation 197, rel-entr. = 0.4, JS = 0.046



participant #30, observation 198, rel-entr. = 0.4, JS = 0.046



participant #30, observation 199, rel-entr. = 0.4, JS = 0.047



participant #30, observation 200, rel-entr. = 0.4, JS = 0.047

