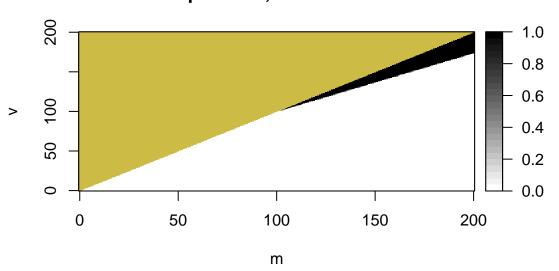
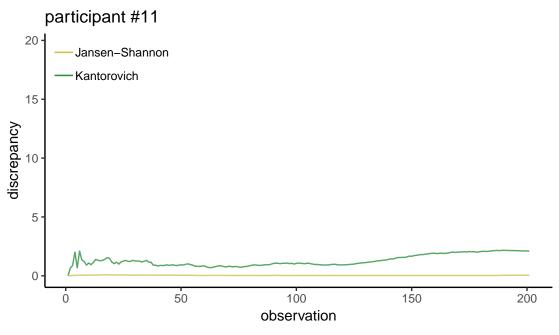


h for part. #11, stubbornness = 8.72





participant #11, sqrt(robot-participant)

