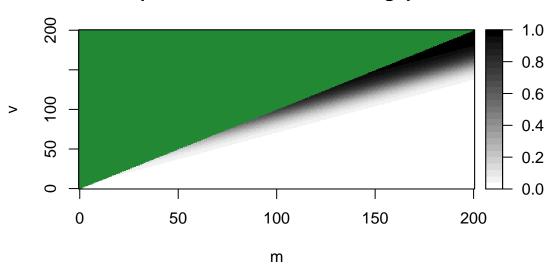
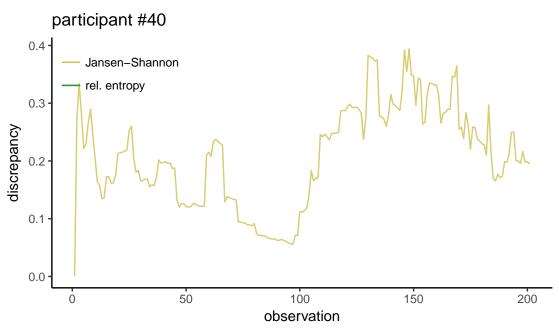
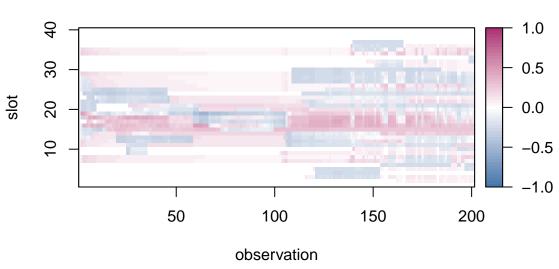


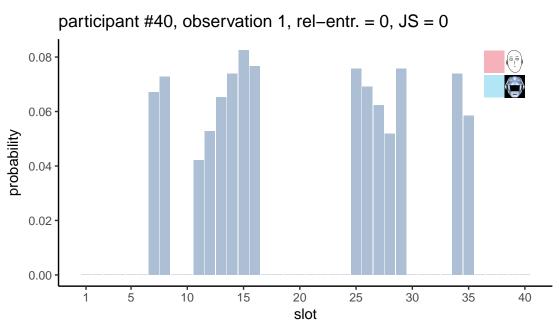
part. #40, stub. = 3.11, changepoint:

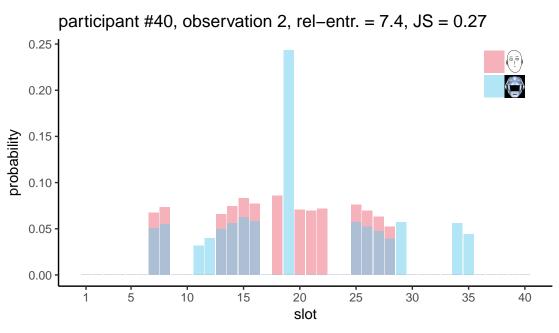




participant #40, sqrt(robot-participant)

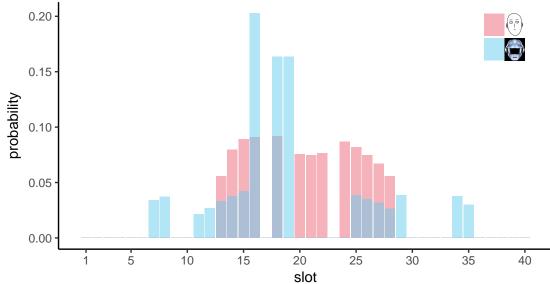




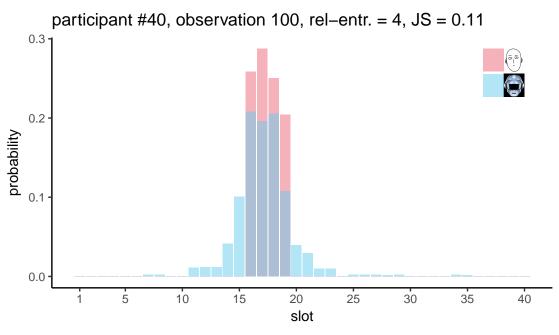


participant #40, observation 3, rel-entr. = 7.3, JS = 0.33 0.25 -0.20 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

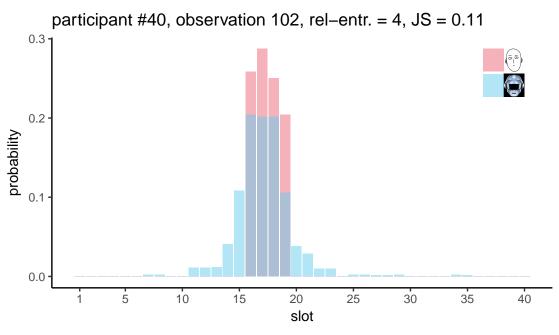
participant #40, observation 4, rel-entr. = 6.1, JS = 0.28



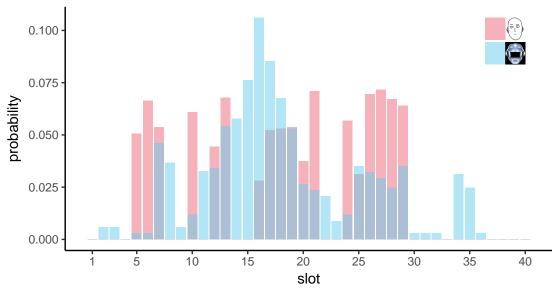
participant #40, observation 99, rel-entr. = 2.5, JS = 0.071 0.25 0.20 probability 0.15 0.05 0.00 10 15 25 30 5 20 35 40 slot



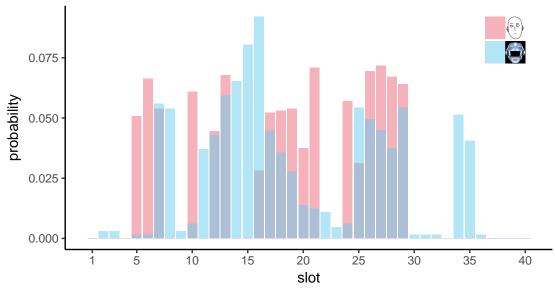
participant #40, observation 101, rel-entr. = 3.9, JS = 0.11 0.3 probability 0.0 10 20 30 15 25 40 35 slot



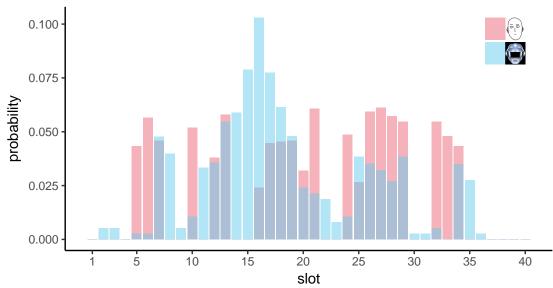
participant #40, observation 197, rel-entr. = 4.7, JS = 0.2



participant #40, observation 198, rel-entr. = 5.4, JS = 0.22



participant #40, observation 199, rel-entr. = 4.4, JS = 0.2



participant #40, observation 200, rel-entr. = 4.4, JS = 0.2

