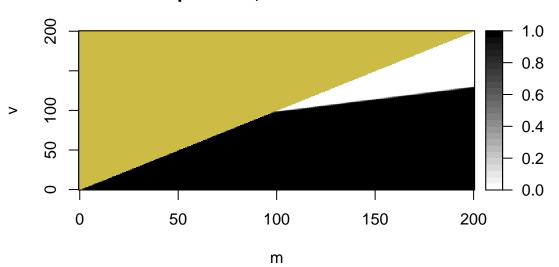
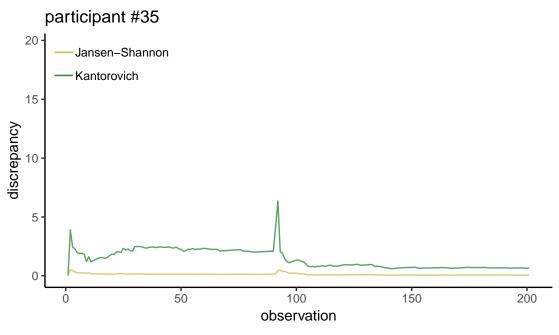


h for part. #35, stubbornness = 0.0219





participant #35, sqrt(robot-participant)

