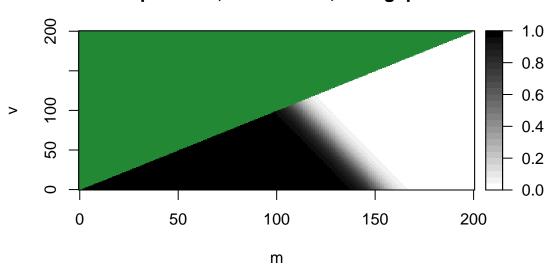
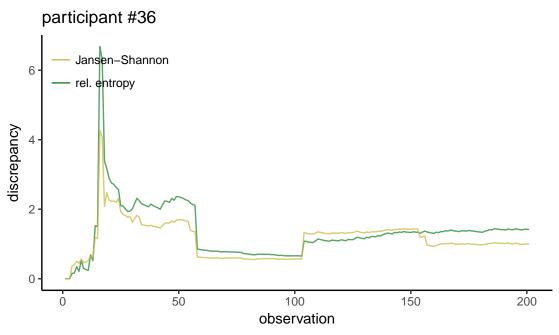
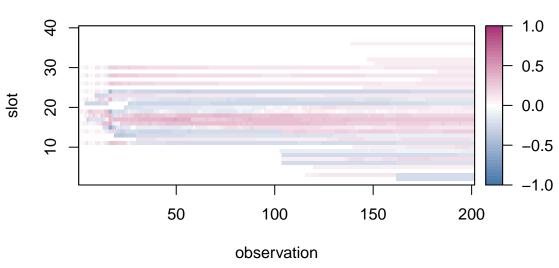


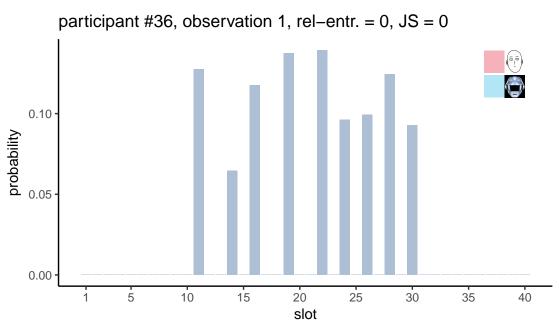
part. #36, stub. = 16.2, changepoint:



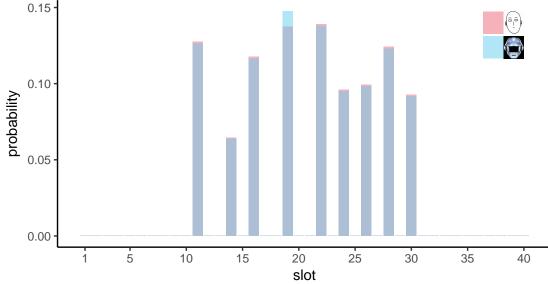


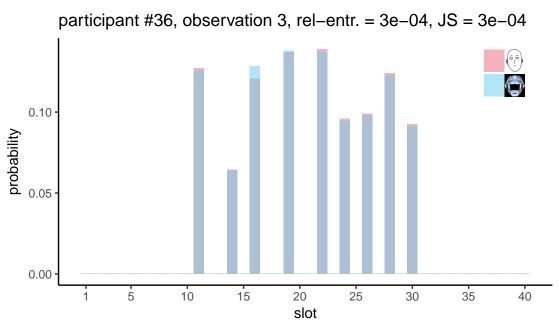
participant #36, sqrt(robot-participant)

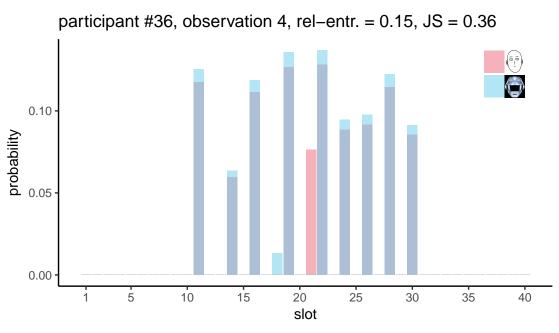




participant #36, observation 2, rel-entr. = 0.00041, JS = 4e-04

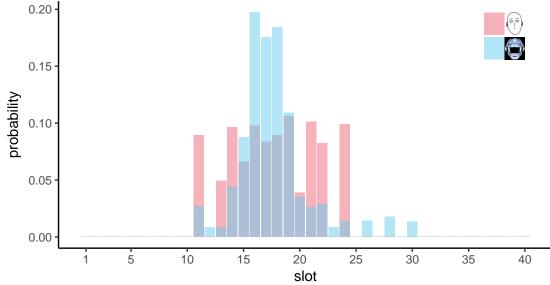




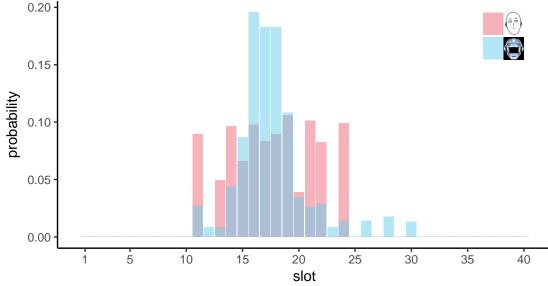


participant #36, observation 99, rel-entr. = 0.66, JS = 0.56 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #36, observation 100, rel-entr. = 0.66, JS = 0.57



participant #36, observation 101, rel-entr. = 0.66, JS = 0.57



participant #36, observation 102, rel-entr. = 0.66, JS = 0.57 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40

slot

participant #36, observation 197, rel-entr. = 1.4, JS = 0.99 0.10 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #36, observation 198, rel-entr. = 1.4, JS = 0.99 0.10 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

