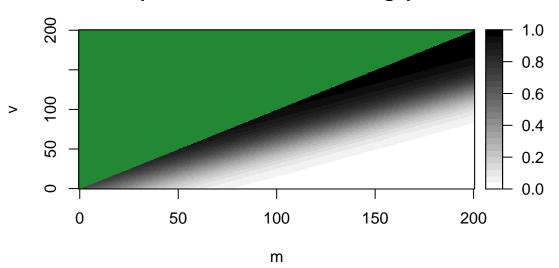
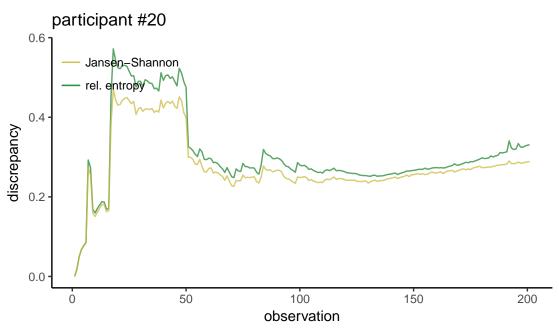
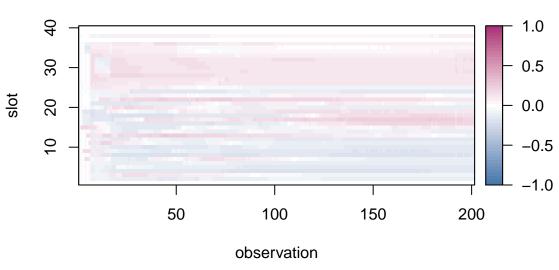


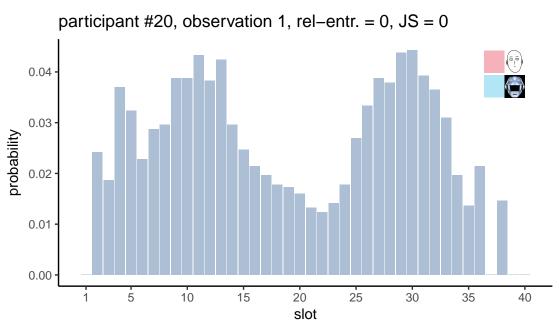
part. #20, stub. = 26.8, changepoint:



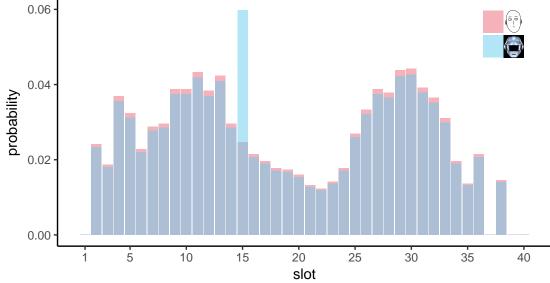


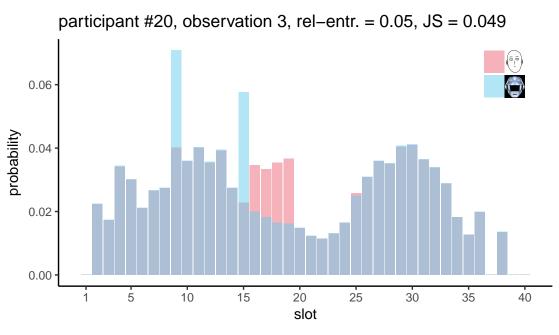
participant #20, sqrt(robot-participant)

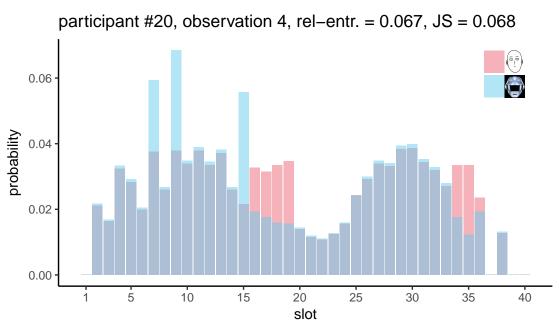




participant #20, observation 2, rel-entr. = 0.018, JS = 0.016

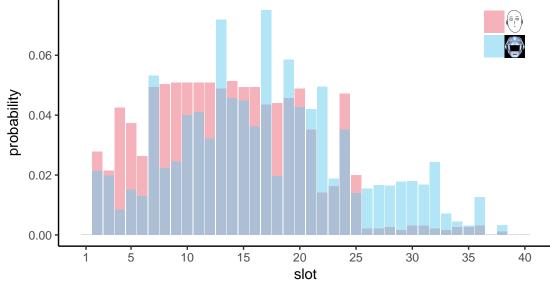




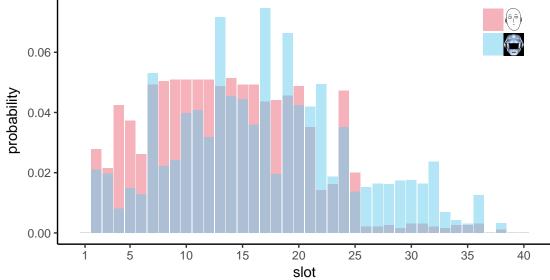


participant #20, observation 99, rel-entr. = 0.29, JS = 0.25 0.06 probability 0.04 0.02 0.00 15 25 30 5 10 20 35 40 slot

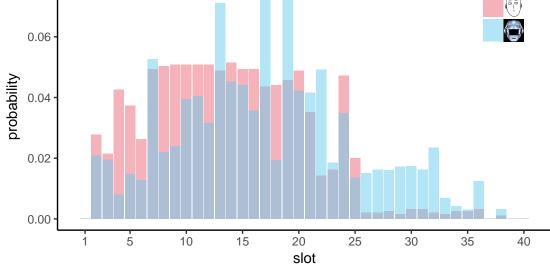
participant #20, observation 100, rel-entr. = 0.28, JS = 0.25



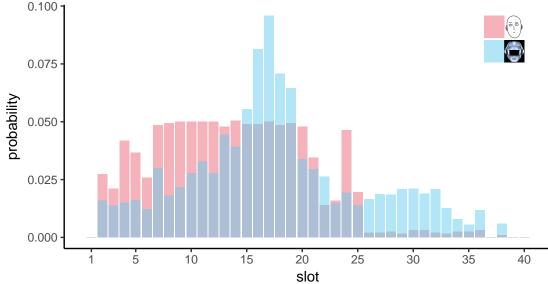
participant #20, observation 101, rel-entr. = 0.28, JS = 0.25



participant #20, observation 102, rel-entr. = 0.28, JS = 0.25 0.06 probability



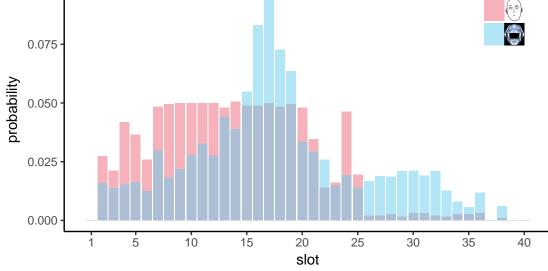
participant #20, observation 197, rel-entr. = 0.33, JS = 0.28 0.100



participant #20, observation 198, rel-entr. = 0.32, JS = 0.29 0.100 0.075 probability 0.050 0.025 0.000 10 5 15 20 25 30 35 40

slot

participant #20, observation 199, rel-entr. = 0.33, JS = 0.29



participant #20, observation 200, rel-entr. = 0.33, JS = 0.29

