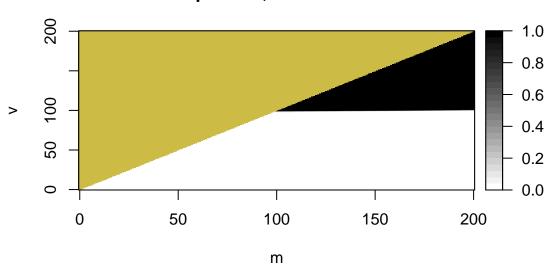
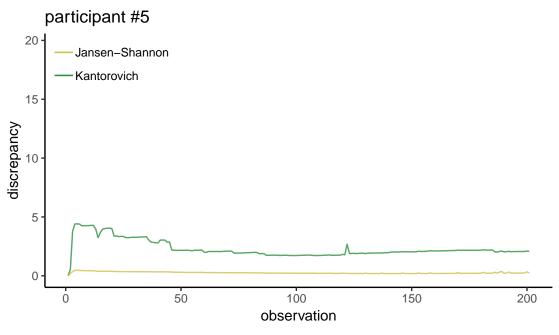
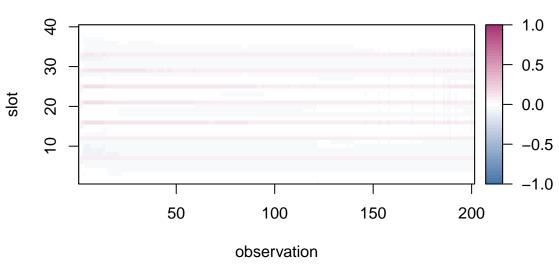


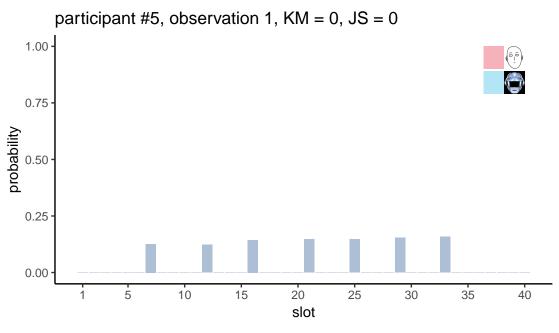
## h for part. #5, stubbornness = 229

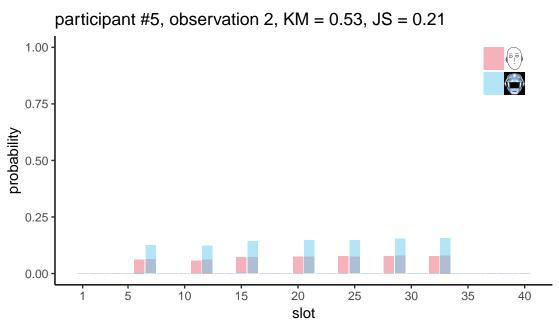


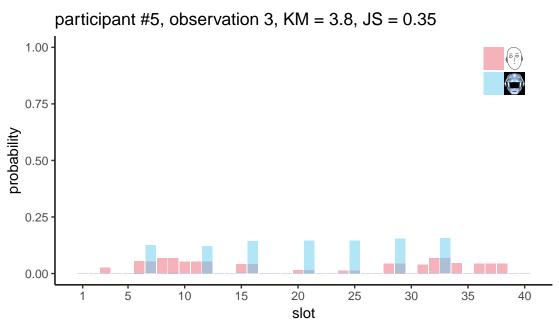


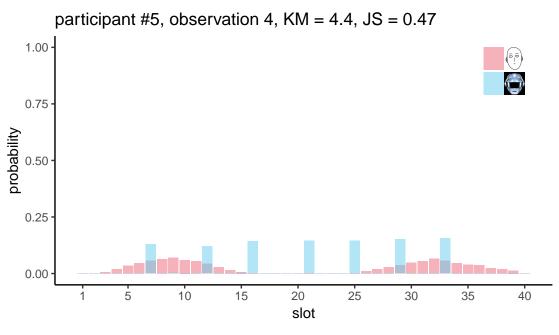
## participant #5, sqrt(robot-participant)

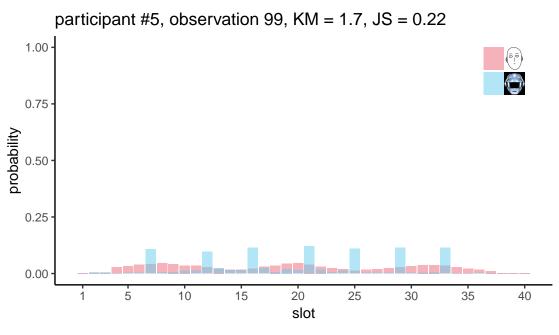


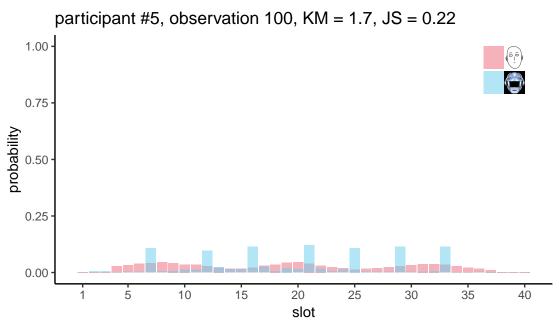












participant #5, observation 101, KM = 1.7, JS = 0.22 1.00 0.75 probability 0.25 0.00 5 10 15 20 25 30 35 40 slot

