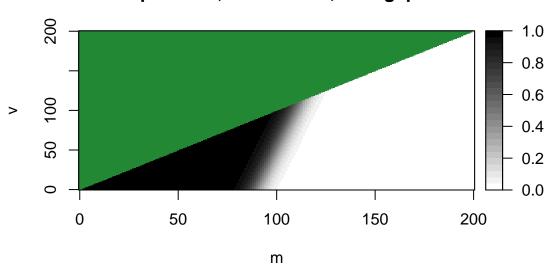
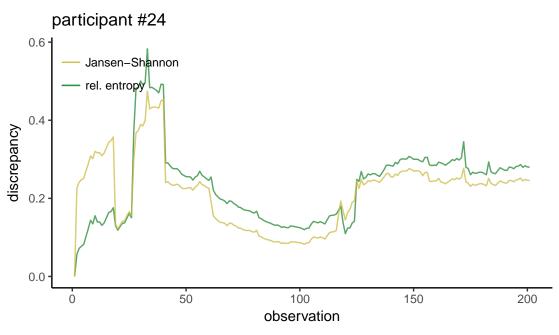
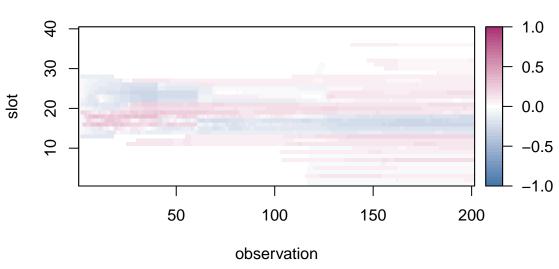


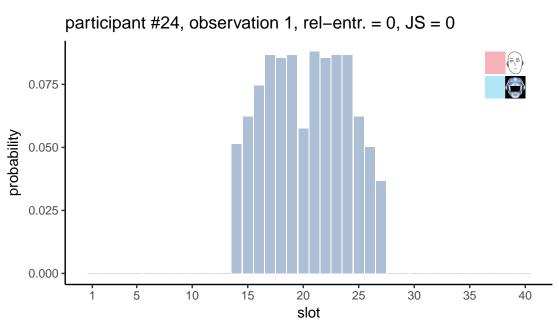
part. #24, stub. = 16.1, changepoint:

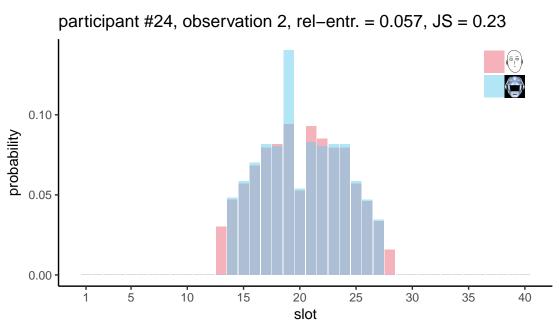




## participant #24, sqrt(robot-participant)

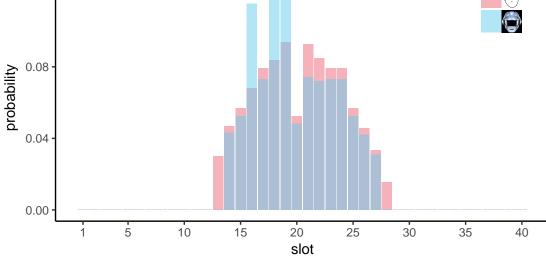






participant #24, observation 3, rel-entr. = 0.072, JS = 0.24 0.10 probability 0.00 slot

participant #24, observation 4, rel-entr. = 0.077, JS = 0.25 0.12 0.08 probability 0.04



participant #24, observation 99, rel-entr. = 0.13, JS = 0.087 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #24, observation 100, rel-entr. = 0.13, JS = 0.087 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #24, observation 101, rel-entr. = 0.12, JS = 0.085 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #24, observation 102, rel-entr. = 0.12, JS = 0.082 0.20 0.15 probability 0.05 0.00

20

slot

25

30

35

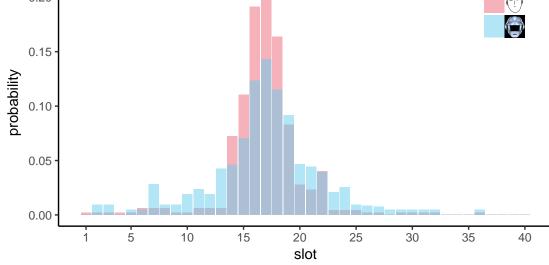
40

10

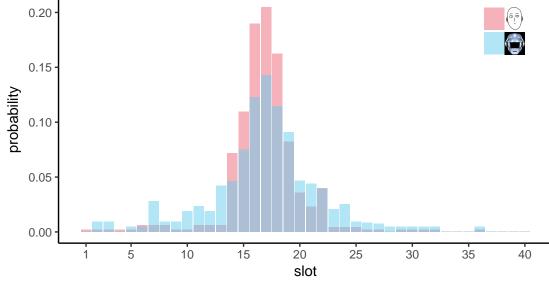
5

15

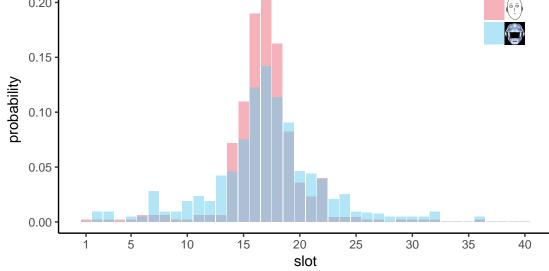
participant #24, observation 197, rel-entr. = 0.29, JS = 0.25



participant #24, observation 198, rel-entr. = 0.28, JS = 0.24



participant #24, observation 199, rel-entr. = 0.28, JS = 0.25 0.20



participant #24, observation 200, rel-entr. = 0.28, JS = 0.25

