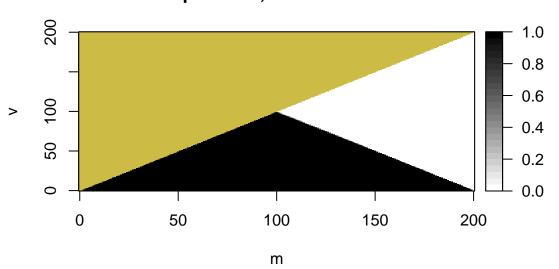
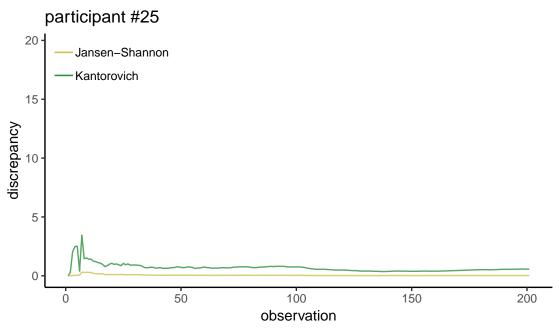


## h for part. #25, stubbornness = 0.244





## participant #25, sqrt(robot-participant)

