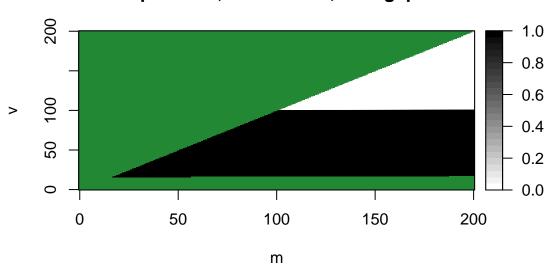
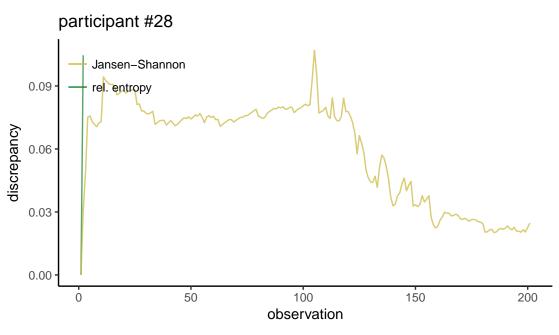
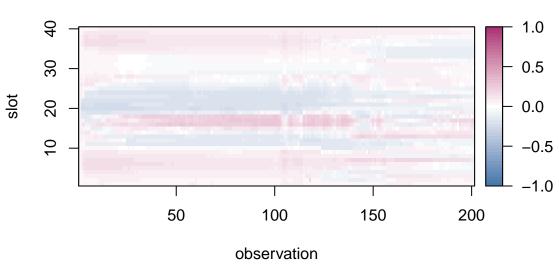


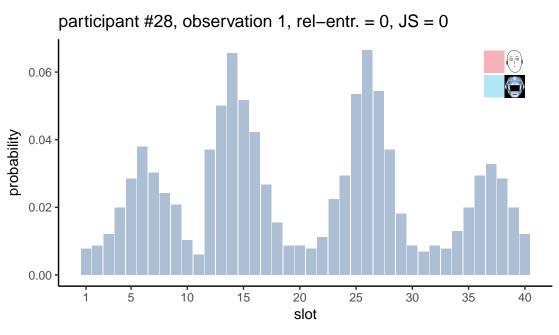
part. #28, stub. = 53.9, changepoint:





participant #28, sqrt(robot-participant)

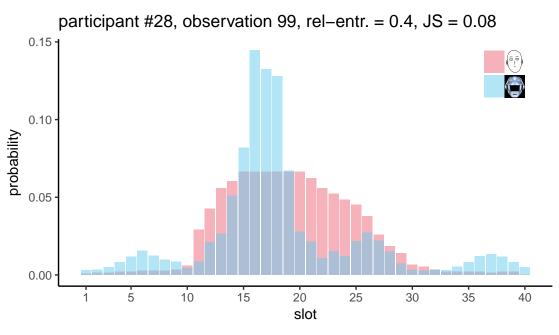




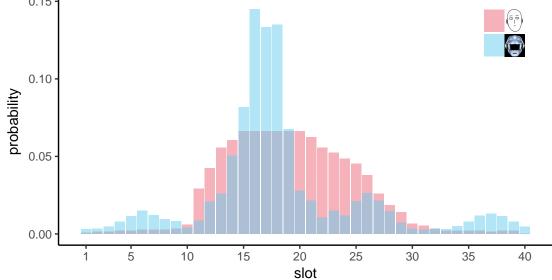
participant #28, observation 2, rel-entr. = 0.1, JS = 0.031 0.06 probability 0.04 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #28, observation 3, rel-entr. = 0.18, JS = 0.048 0.06 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #28, observation 4, rel-entr. = 0.31, JS = 0.075 0.06 0.04 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

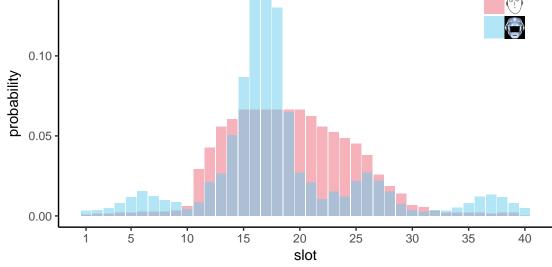


participant #28, observation 100, rel-entr. = 0.41, JS = 0.081 0.15

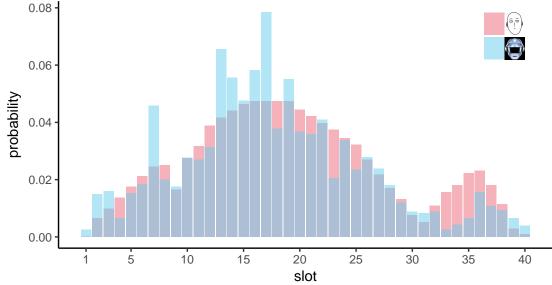


participant #28, observation 101, rel-entr. = 0.41, JS = 0.081 0.15 0.10 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

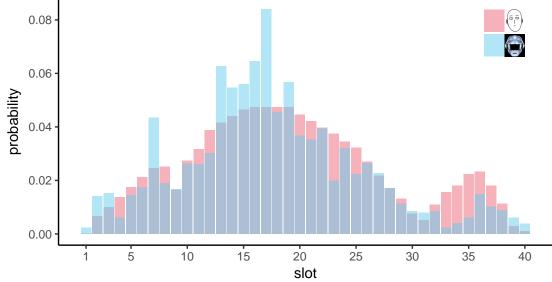
participant #28, observation 102, rel-entr. = 0.41, JS = 0.081

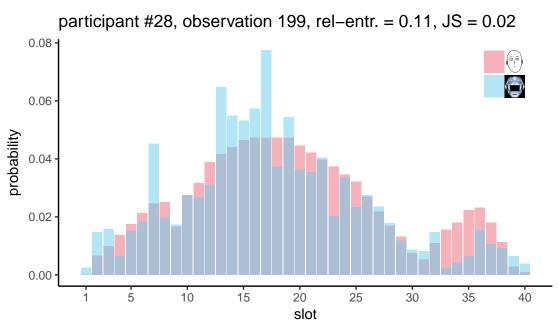


participant #28, observation 197, rel-entr. = 0.11, JS = 0.02



participant #28, observation 198, rel-entr. = 0.11, JS = 0.022





participant #28, observation 200, rel-entr. = 0.12, JS = 0.023

