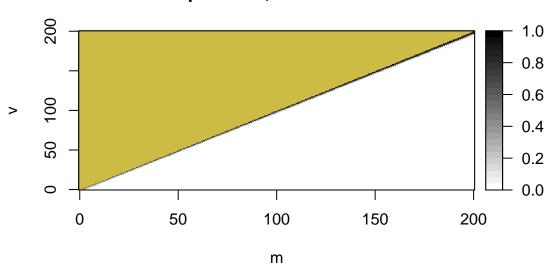
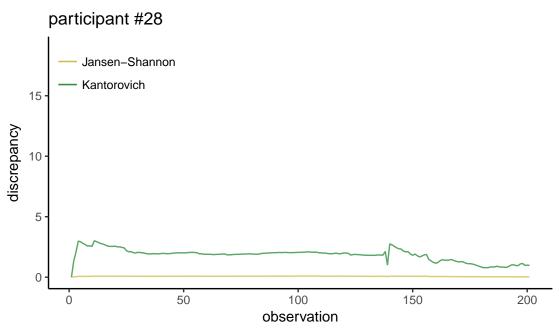


h for part. #28, stubbornness = 34.6





participant #28, sqrt(robot-participant)

