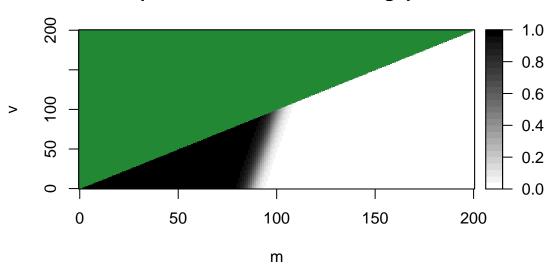
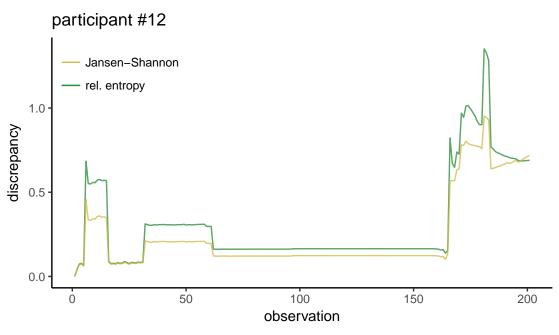
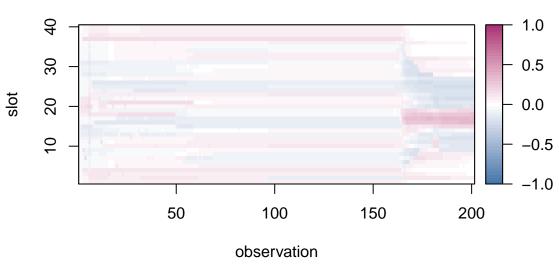


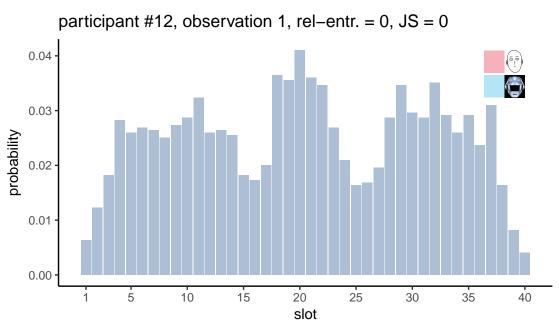
part. #12, stub. = 1.12, changepoint:



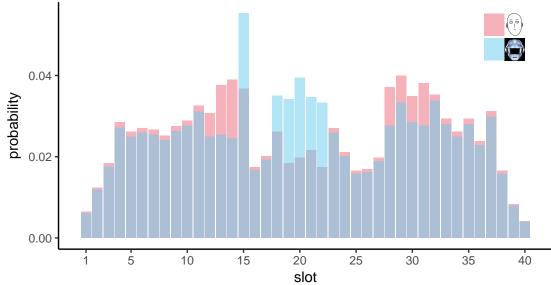


participant #12, sqrt(robot-participant)

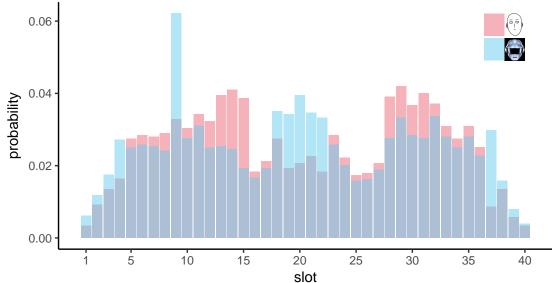




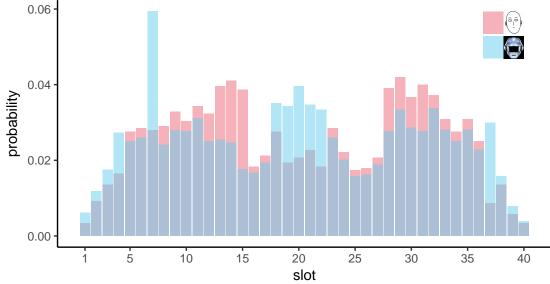
participant #12, observation 2, rel-entr. = 0.038, JS = 0.036



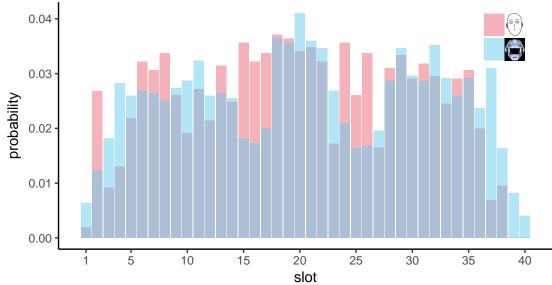
participant #12, observation 3, rel-entr. = 0.073, JS = 0.069



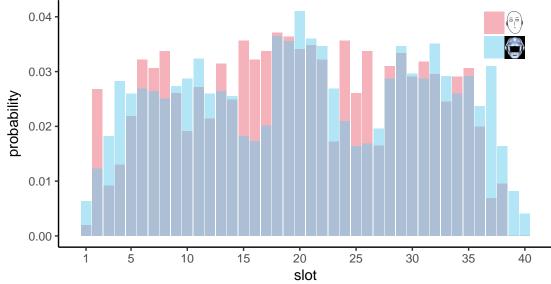
participant #12, observation 4, rel-entr. = 0.078, JS = 0.074



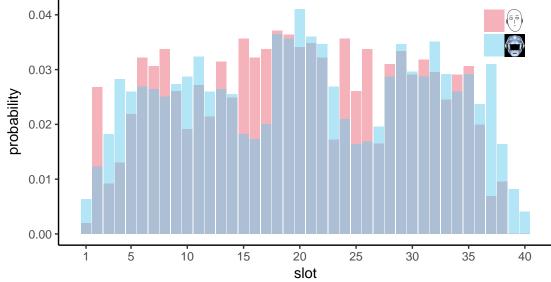
participant #12, observation 99, rel-entr. = 0.16, JS = 0.12



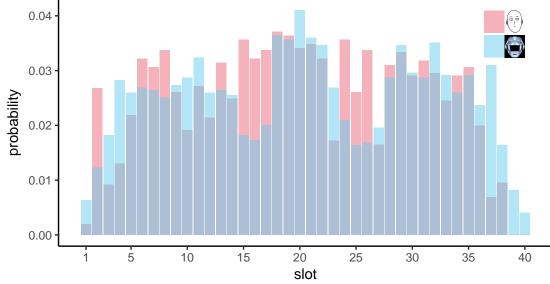
participant #12, observation 100, rel-entr. = 0.16, JS = 0.12



participant #12, observation 101, rel-entr. = 0.16, JS = 0.12



participant #12, observation 102, rel-entr. = 0.16, JS = 0.12



participant #12, observation 197, rel-entr. = 0.69, JS = 0.69 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #12, observation 198, rel-entr. = 0.69, JS = 0.7 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #12, observation 199, rel-entr. = 0.69, JS = 0.7 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #12, observation 200, rel-entr. = 0.69, JS = 0.71 0.15 probability 0.10 0.05 0.00 15 25 30 35 5 10 20 40 slot