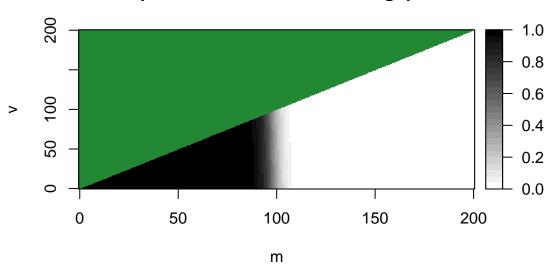
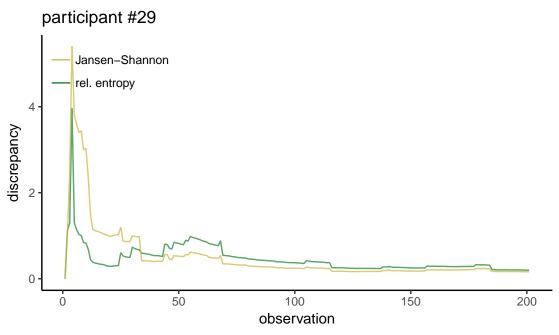
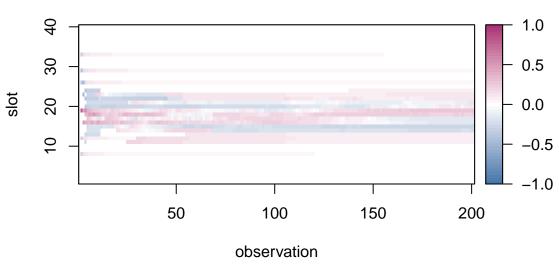


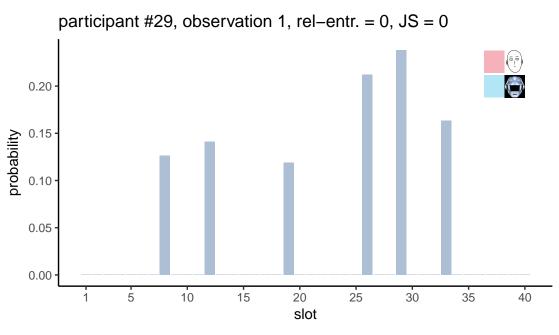
part. #29, stub. = 0.36, changepoint:

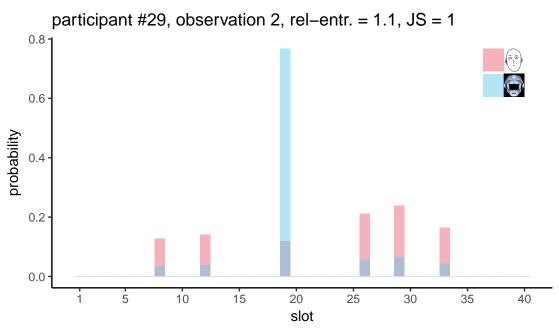




participant #29, sqrt(robot-participant)







participant #29, observation 3, rel-entr. = 1.3, JS = 2.5 0.4 0.3 probability 0.1 0.0 10 15 30 20 25 35 40 slot

participant #29, observation 4, rel-entr. = 4, JS = 5.4 0.3 probability 0.2. 0.1 0.0 10 30 15 20 25 35 40 slot

participant #29, observation 99, rel-entr. = 0.37, JS = 0.25 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 100, rel-entr. = 0.37, JS = 0.25 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 101, rel-entr. = 0.37, JS = 0.25 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 102, rel-entr. = 0.36, JS = 0.24 0.20 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #29, observation 197, rel-entr. = 0.2, JS = 0.16 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 198, rel-entr. = 0.2, JS = 0.16 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 199, rel-entr. = 0.2, JS = 0.16 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #29, observation 200, rel-entr. = 0.2, JS = 0.16 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot