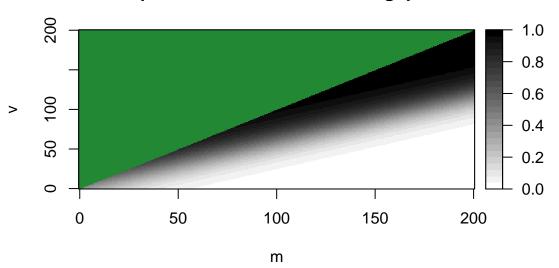
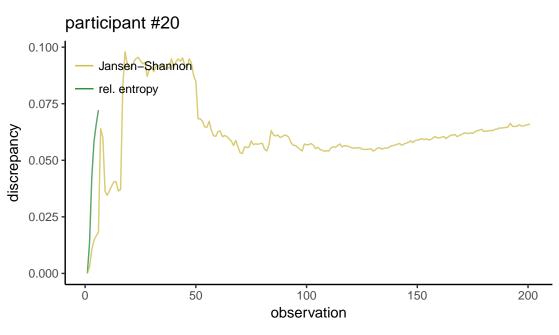
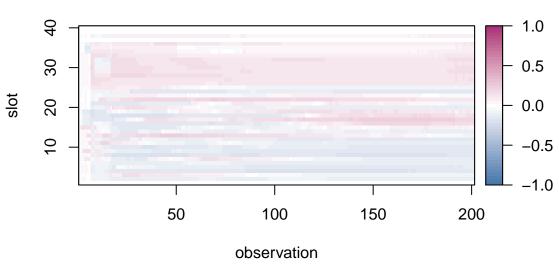


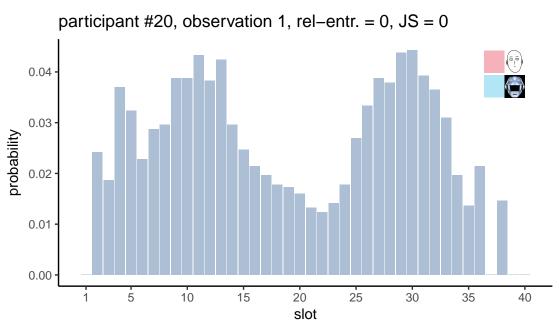
part. #20, stub. = 31.9, changepoint:



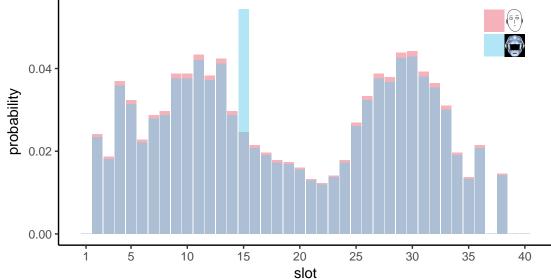


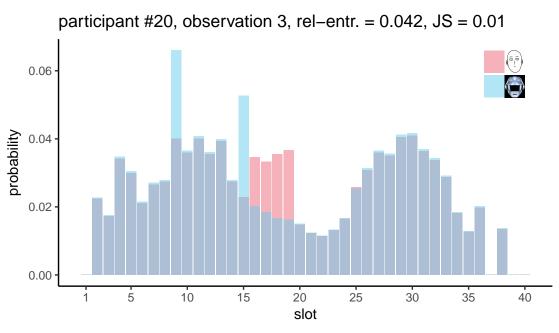
participant #20, sqrt(robot-participant)



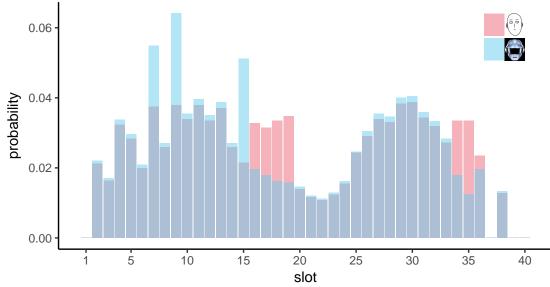


participant #20, observation 2, rel-entr. = 0.014, JS = 0.003



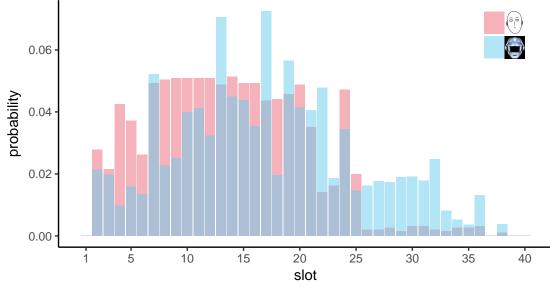


participant #20, observation 4, rel-entr. = 0.058, JS = 0.015

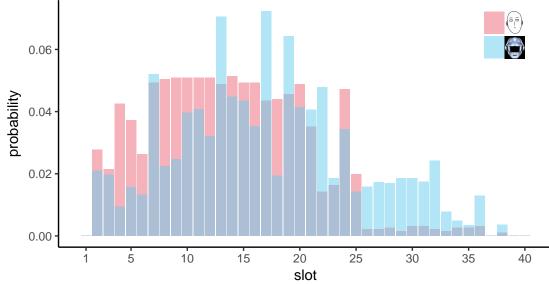


participant #20, observation 99, rel-entr. = 0.3, JS = 0.057 0.06 probability 0.04 0.02 0.00 15 25 30 5 10 20 35 40 slot

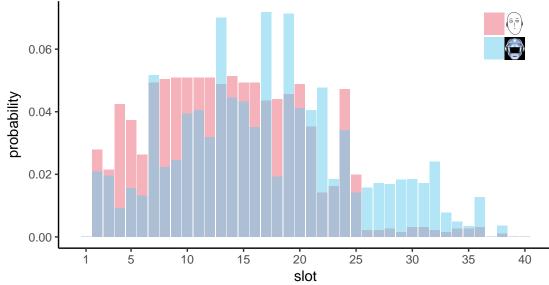
participant #20, observation 100, rel-entr. = 0.29, JS = 0.057



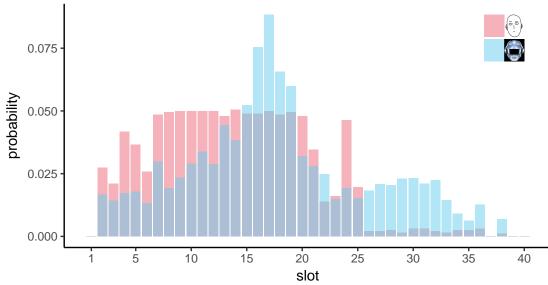
participant #20, observation 101, rel-entr. = 0.29, JS = 0.057



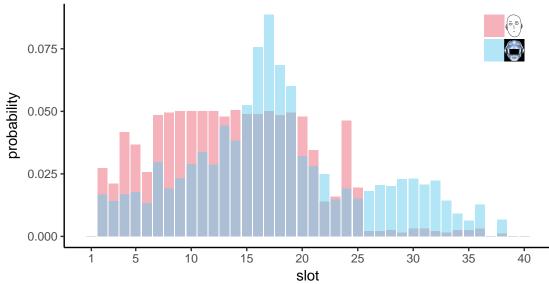
participant #20, observation 102, rel-entr. = 0.29, JS = 0.057



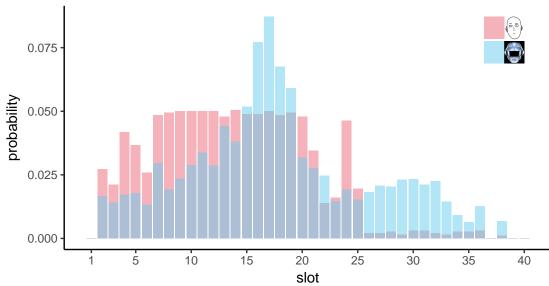
participant #20, observation 197, rel-entr. = 0.34, JS = 0.065



participant #20, observation 198, rel-entr. = 0.34, JS = 0.065



participant #20, observation 199, rel-entr. = 0.35, JS = 0.066



participant #20, observation 200, rel-entr. = 0.35, JS = 0.066

