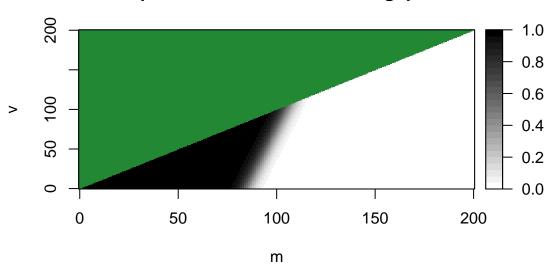
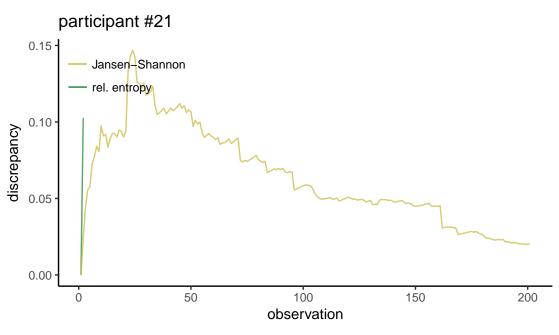
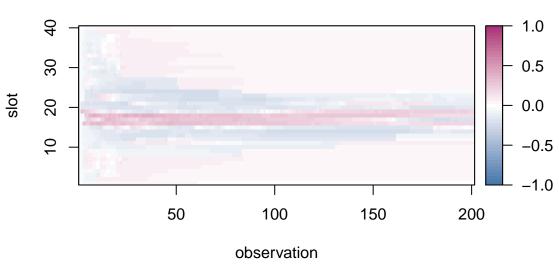


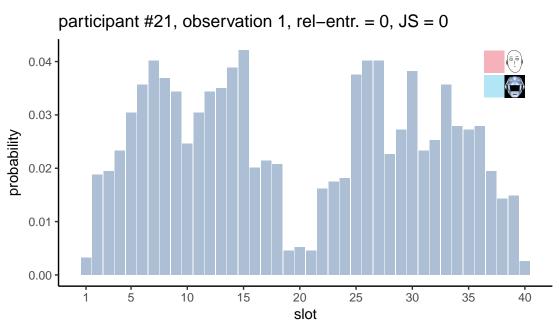
part. #21, stub. = 7.72, changepoint:

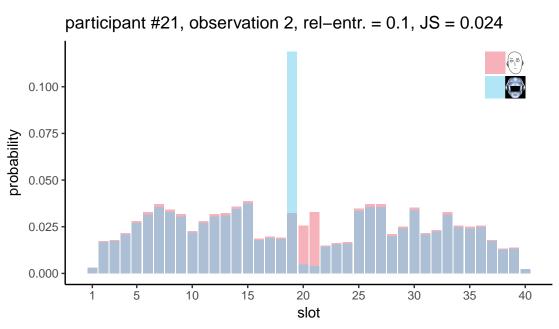




## participant #21, sqrt(robot-participant)







participant #21, observation 3, rel-entr. = 0.22, JS = 0.044 0.100 0.075 probability 0.050 0.025 0.000

10

15

20

slot

25

30

35

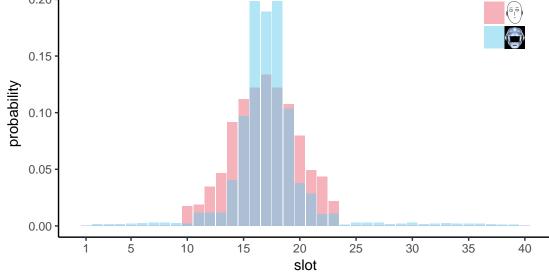
40

5

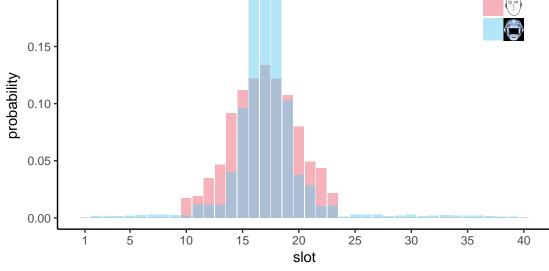
participant #21, observation 4, rel-entr. = 0.23, JS = 0.056 0.09 probability 0.06 0.03 0.00 15 25 30 5 10 20 35 40 slot

participant #21, observation 99, rel-entr. = 0.8, JS = 0.058 0.20 0.15 probability 0.05 0.00 10 15 25 5 20 30 35 40 slot

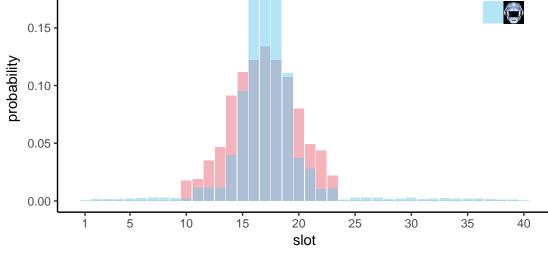
participant #21, observation 100, rel-entr. = 0.8, JS = 0.058 0.20



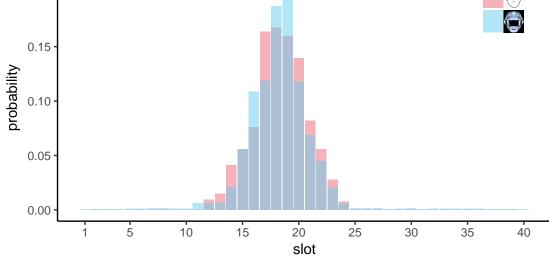
participant #21, observation 101, rel-entr. = 0.79, JS = 0.059 0.20 0.15



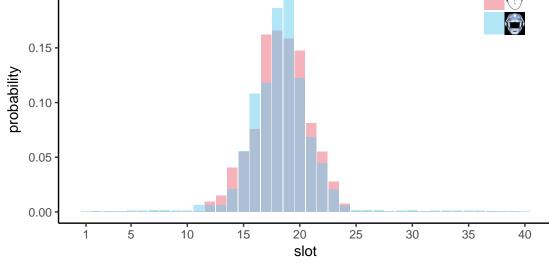
participant #21, observation 102, rel-entr. = 0.78, JS = 0.059 0.20 0.15



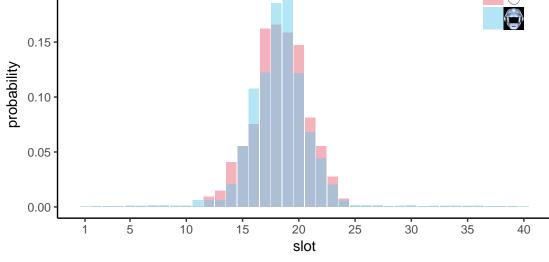
participant #21, observation 197, rel-entr. = 0.44, JS = 0.02 0.20 0.15



participant #21, observation 198, rel-entr. = 0.44, JS = 0.02 0.20 0.15



participant #21, observation 199, rel-entr. = 0.44, JS = 0.02 0.20 0.15



participant #21, observation 200, rel-entr. = 0.44, JS = 0.02

