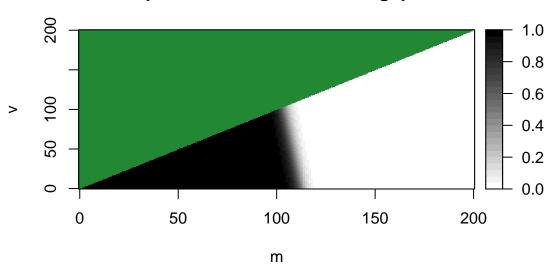
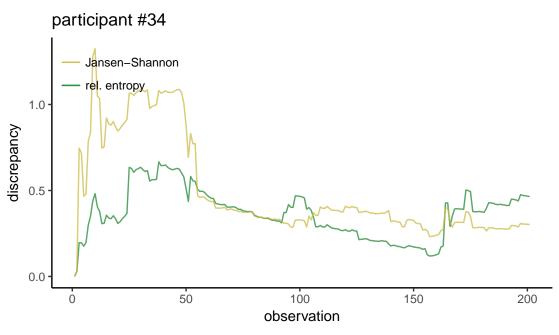
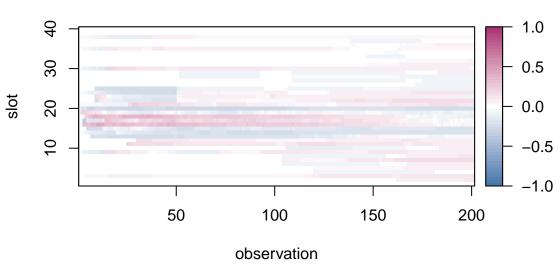


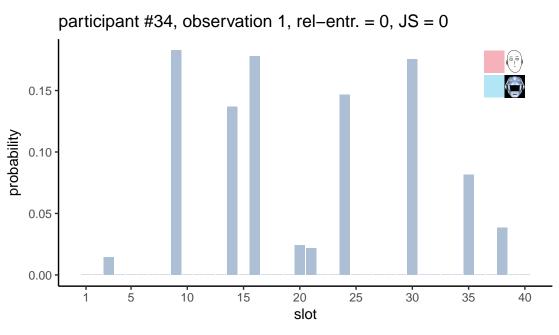
part. #34, stub. = 5.6, changepoint:



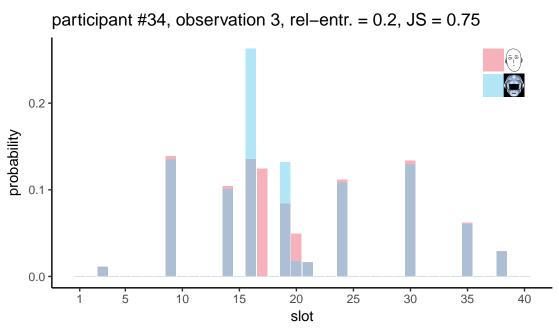


## participant #34, sqrt(robot-participant)

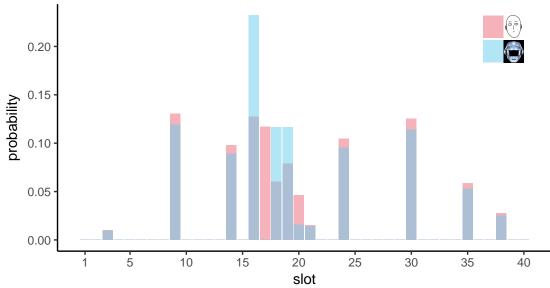




participant #34, observation 2, rel-entr. = 0.029, JS = 0.031 0.15 0.10 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

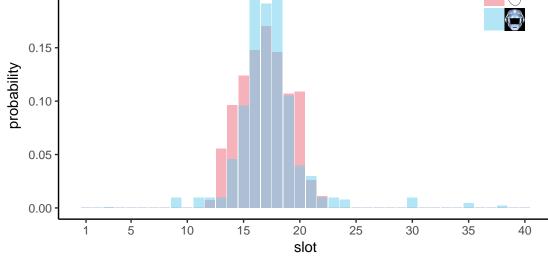


participant #34, observation 4, rel-entr. = 0.2, JS = 0.72

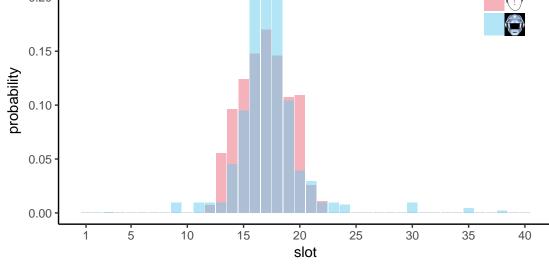


participant #34, observation 99, rel-entr. = 0.47, JS = 0.33 0.20 0.15 probability 0.10 0.05 0.00 15 25 30 35 5 10 20 40 slot

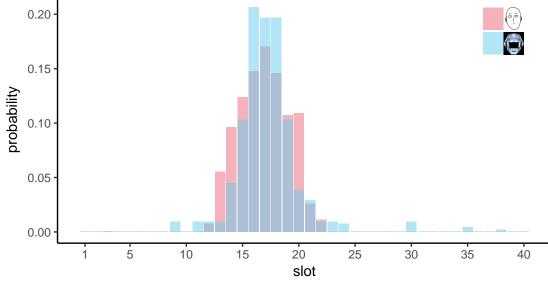
participant #34, observation 100, rel-entr. = 0.47, JS = 0.33 0.20 0.15



participant #34, observation 101, rel-entr. = 0.46, JS = 0.33 0.20 0.15



participant #34, observation 102, rel-entr. = 0.46, JS = 0.32



participant #34, observation 197, rel-entr. = 0.48, JS = 0.31 0.15 0.10 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #34, observation 198, rel-entr. = 0.47, JS = 0.3 0.15 0.10 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #34, observation 199, rel-entr. = 0.47, JS = 0.3 0.15 0.10 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #34, observation 200, rel-entr. = 0.47, JS = 0.3 0.15 0.10 probability

