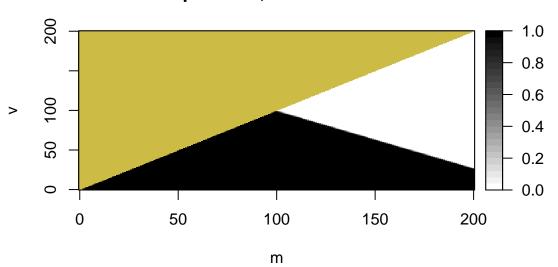
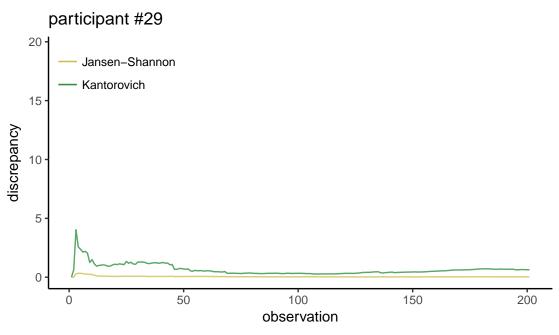


h for part. #29, stubbornness = 0.253





participant #29, sqrt(robot-participant)

