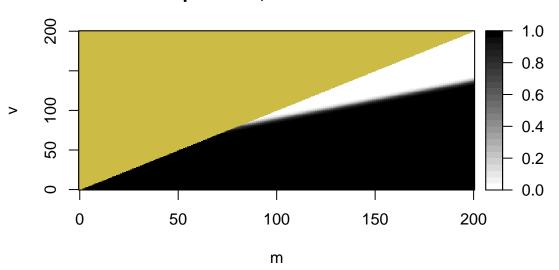
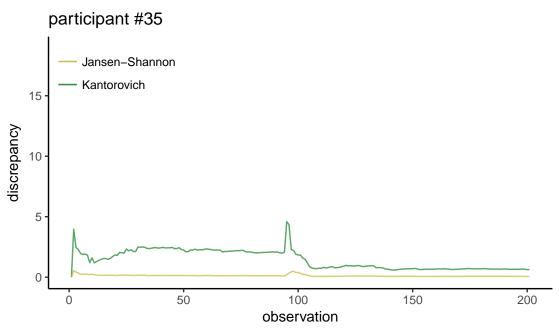
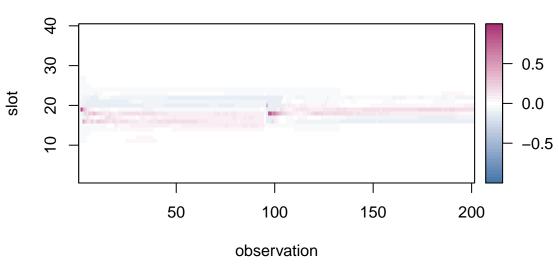


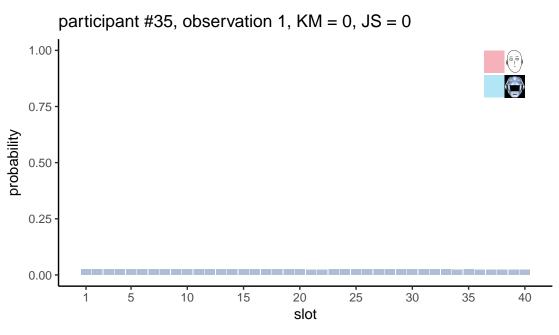
## h for part. #35, stubbornness = 0.001

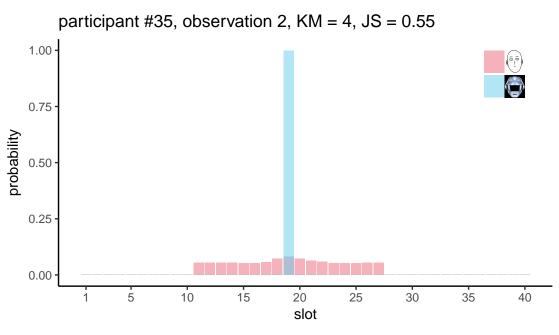


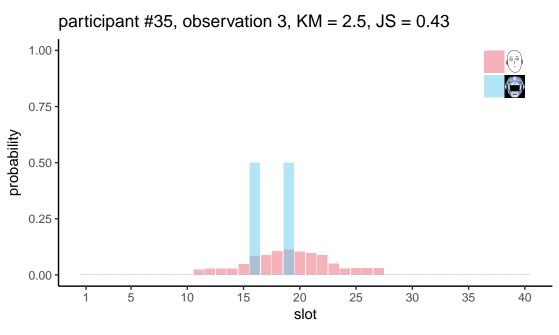


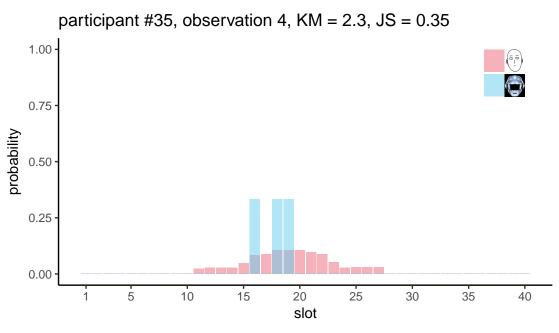
## participant #35, sqrt(robot-participant)

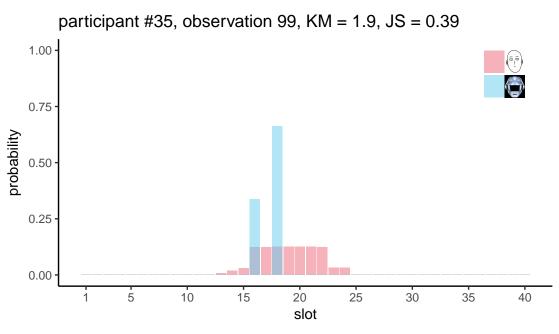


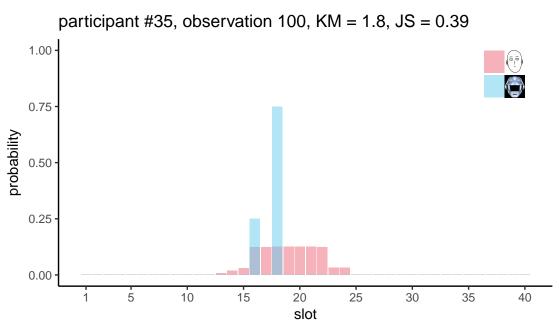


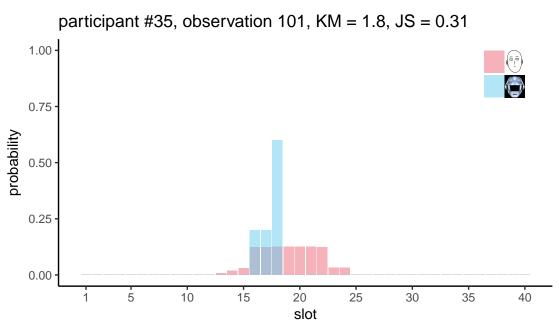


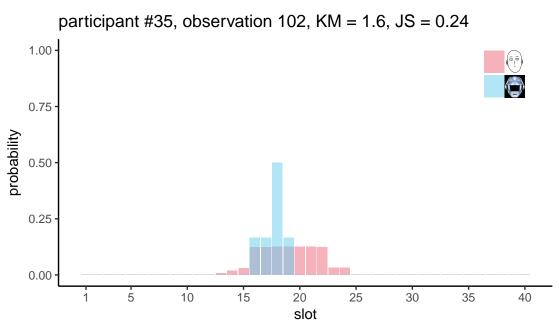


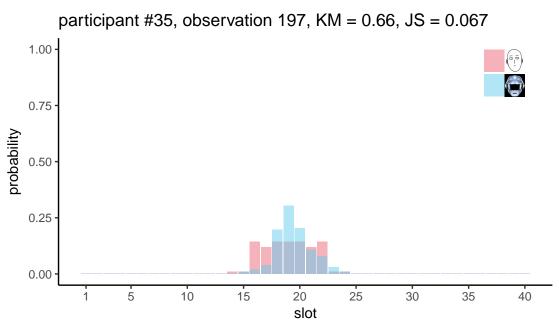


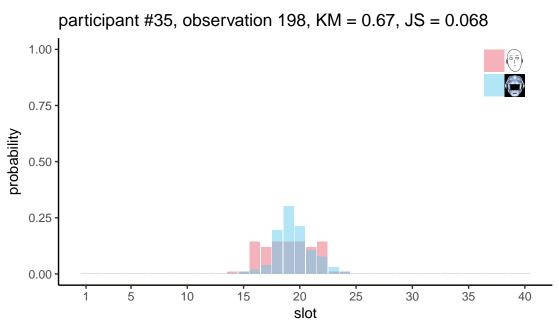


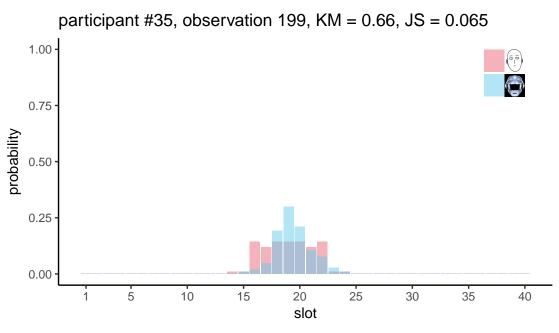












participant #35, observation 200, KM = 0.63, JS = 0.058 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot