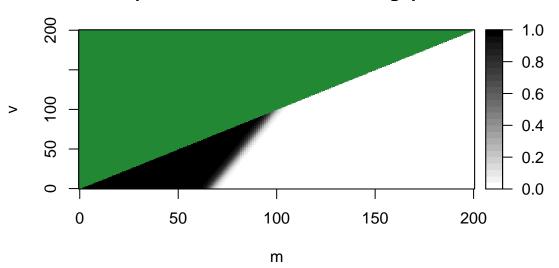
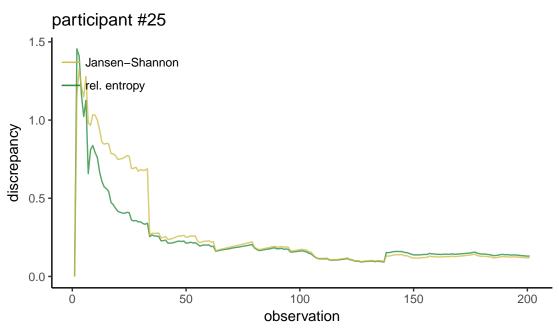
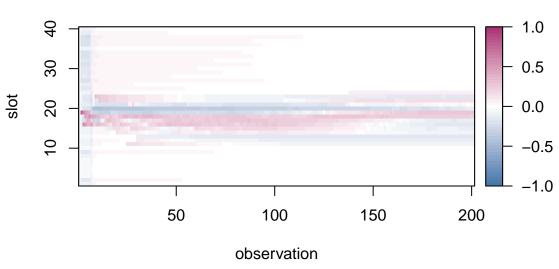


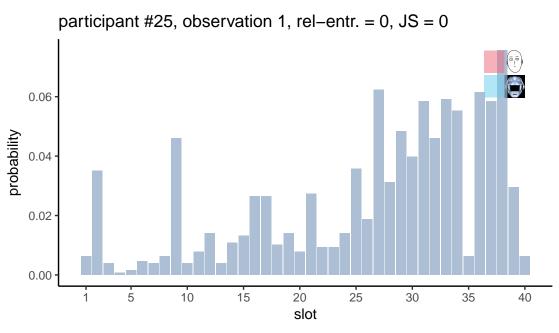
part. #25, stub. = 0.558, changepoint:





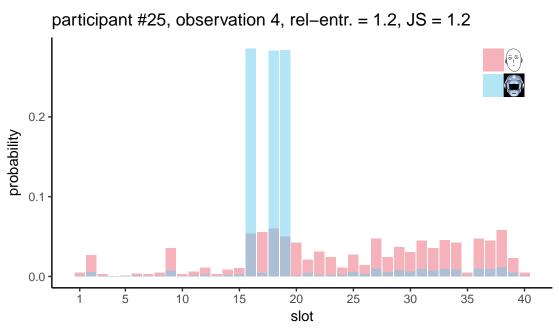
participant #25, sqrt(robot-participant)





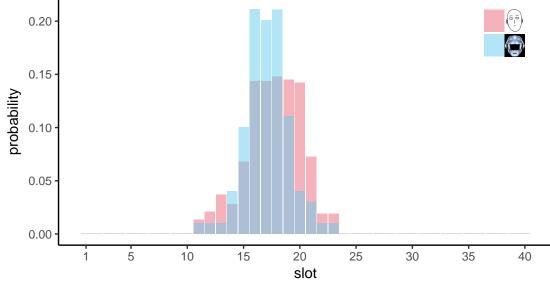
participant #25, observation 2, rel-entr. = 1.5, JS = 1.2 0.6 probability 0.4 0.2 0.0 30 35 10 25 15 20 40 slot

participant #25, observation 3, rel-entr. = 1.4, JS = 1.3 0.4 -0.3 probability 0.1 0.0 10 25 30 35 20 15 40 slot

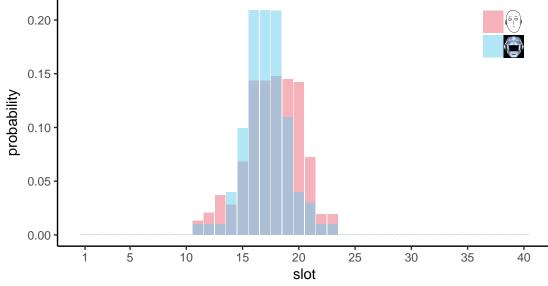


participant #25, observation 99, rel-entr. = 0.16, JS = 0.17 0.20 0.15 probability 0.10 0.05 0.00 15 25 30 35 5 10 20 40 slot

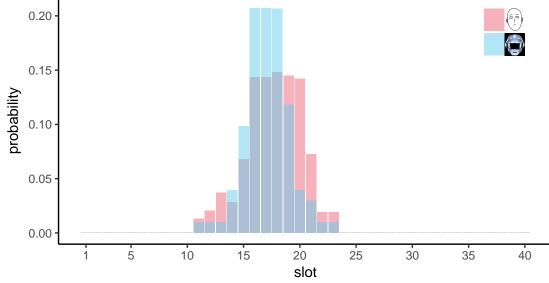
participant #25, observation 100, rel-entr. = 0.16, JS = 0.17



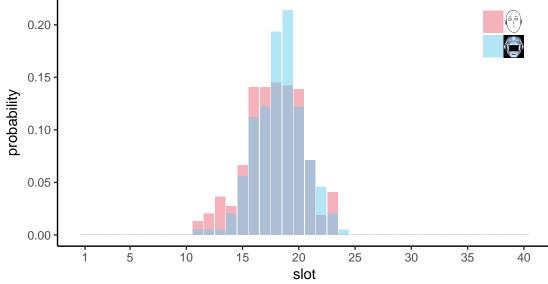
participant #25, observation 101, rel-entr. = 0.16, JS = 0.17



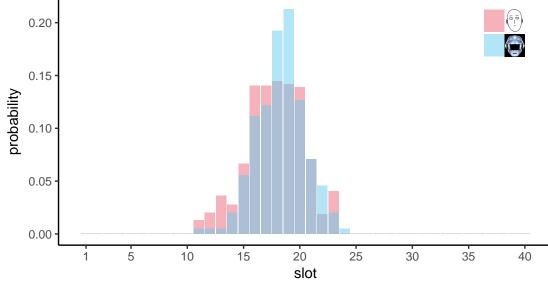
participant #25, observation 102, rel-entr. = 0.16, JS = 0.17



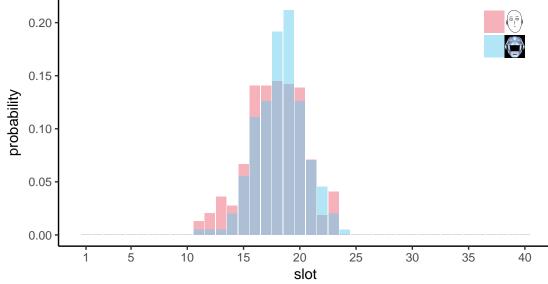
participant #25, observation 197, rel-entr. = 0.13, JS = 0.12



participant #25, observation 198, rel-entr. = 0.13, JS = 0.12



participant #25, observation 199, rel-entr. = 0.13, JS = 0.12



participant #25, observation 200, rel-entr. = 0.13, JS = 0.12

