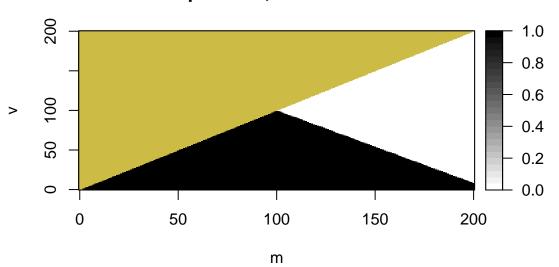
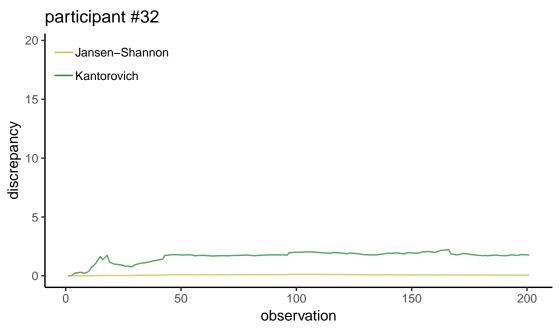


h for part. #32, stubbornness = 19.3





participant #32, sqrt(robot-participant)

