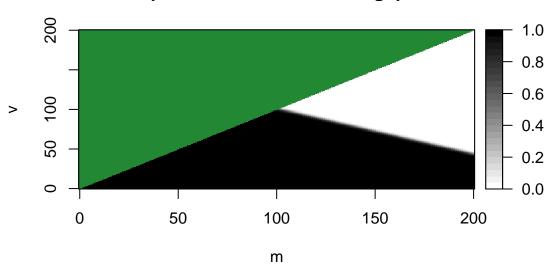
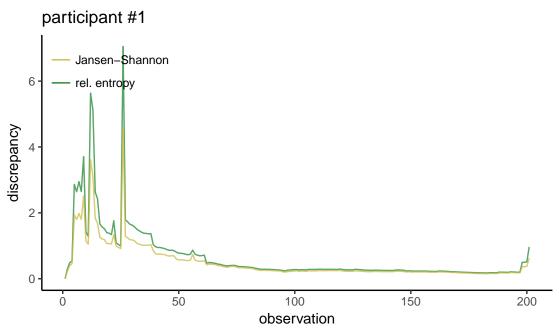
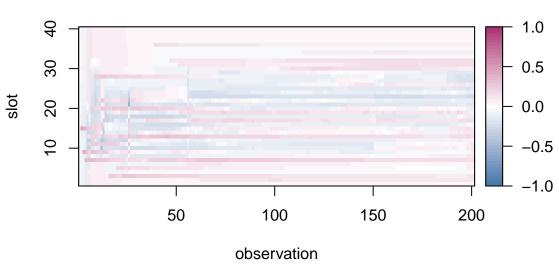


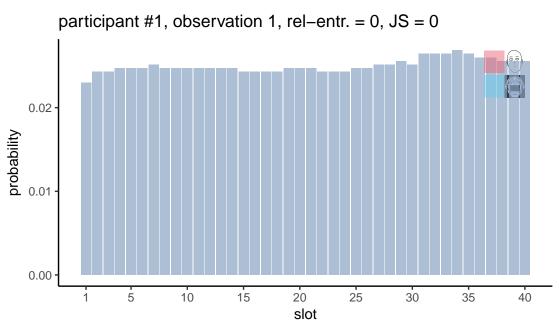
## part. #1, stub. = 3.6, changepoint:

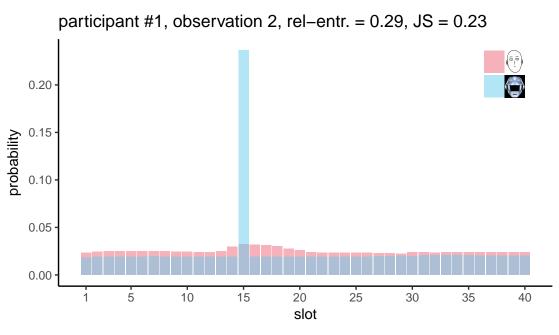


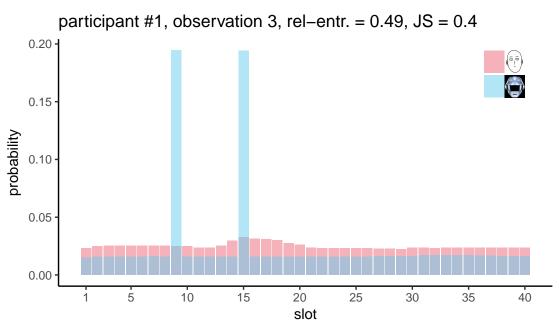


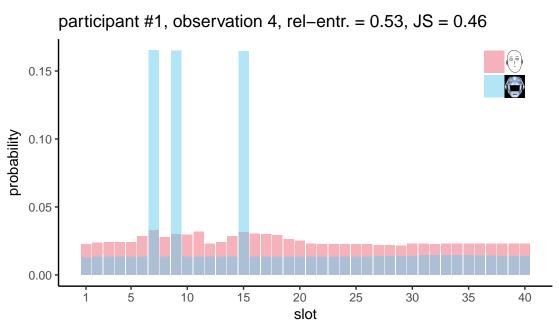
## participant #1, sqrt(robot-participant)



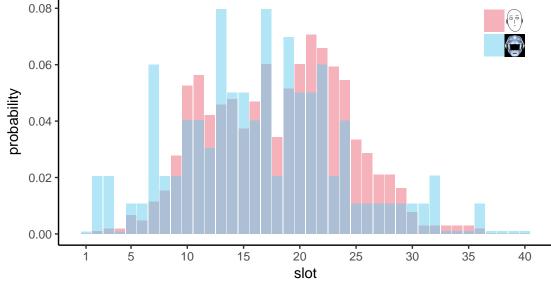




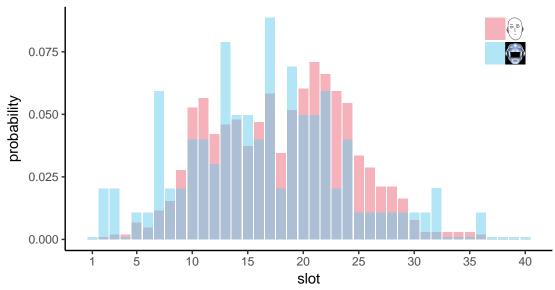




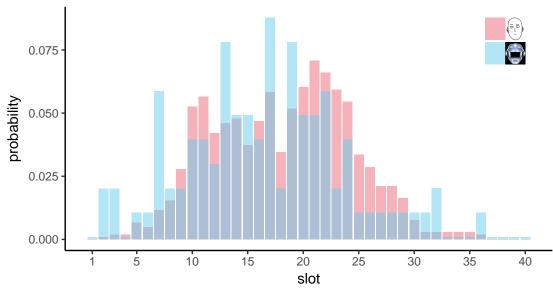
participant #1, observation 99, rel-entr. = 0.28, JS = 0.23



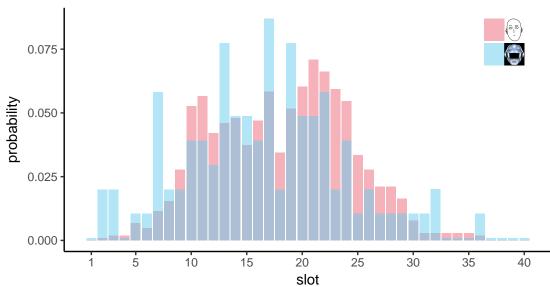
participant #1, observation 100, rel-entr. = 0.28, JS = 0.23

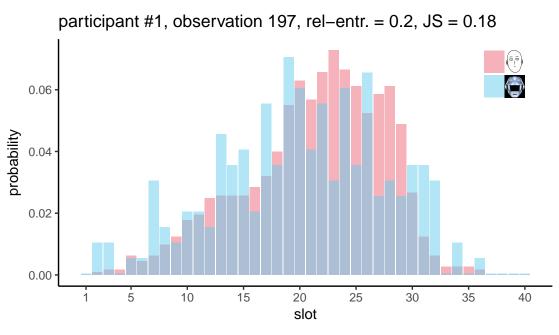


participant #1, observation 101, rel-entr. = 0.28, JS = 0.24



participant #1, observation 102, rel-entr. = 0.27, JS = 0.23





participant #1, observation 198, rel-entr. = 0.5, JS = 0.36 0.08 0.06 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #1, observation 199, rel-entr. = 0.5, JS = 0.36 0.08 0.06 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #1, observation 200, rel-entr. = 0.51, JS = 0.38 0.08 0.06 probability 0.04 0.02 0.00 15 25 30 5 10 20 35 40

slot