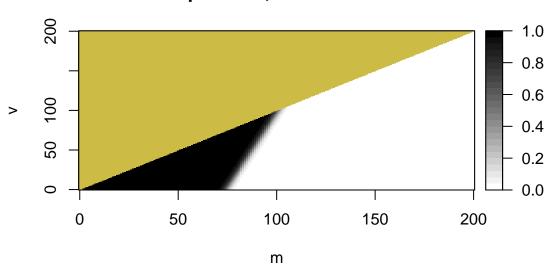
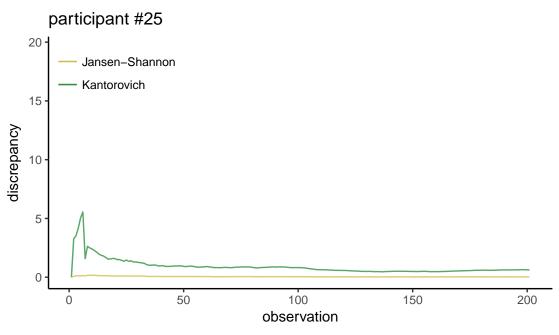
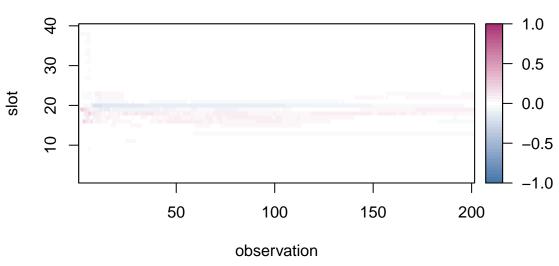


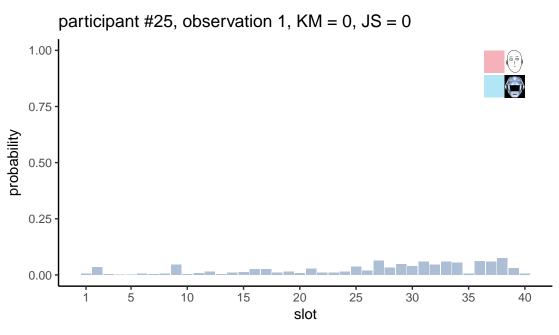
h for part. #25, stubbornness = 2.21

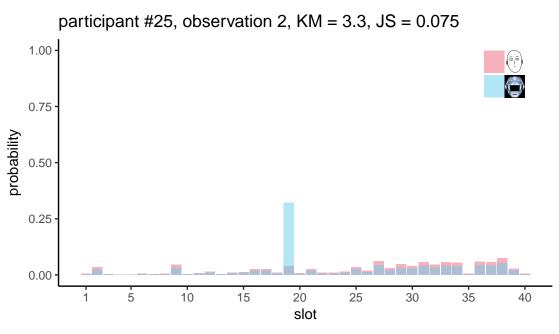


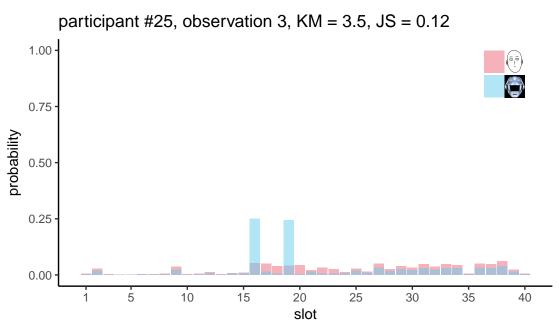


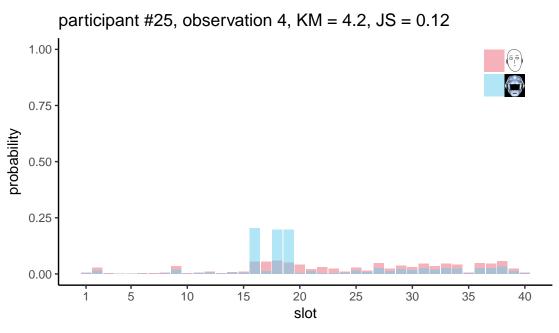
participant #25, sqrt(robot-participant)

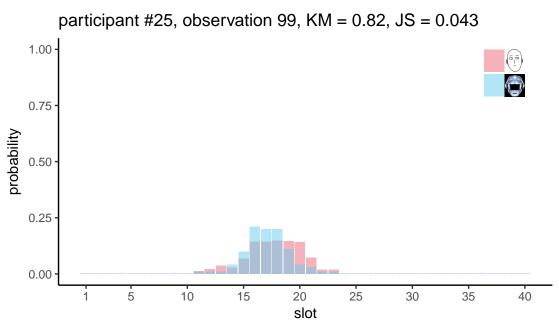


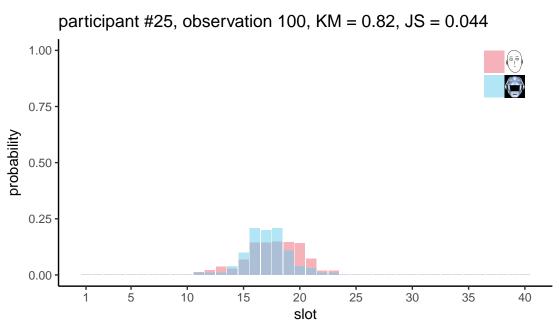


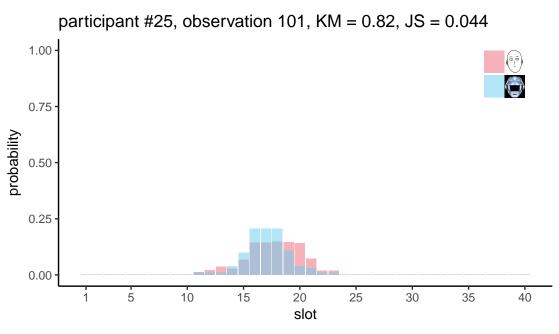


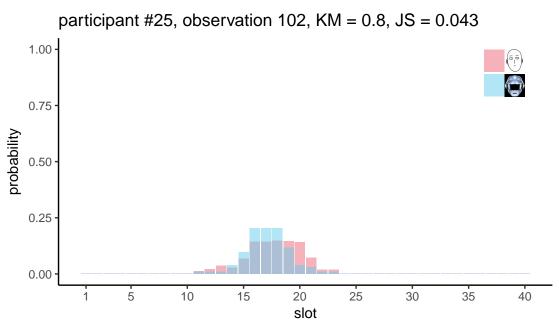












participant #25, observation 197, KM = 0.64, JS = 0.027 1.00 0.75 probability 0.25 0.00 10 15 25 30 35 5 20 40 slot

