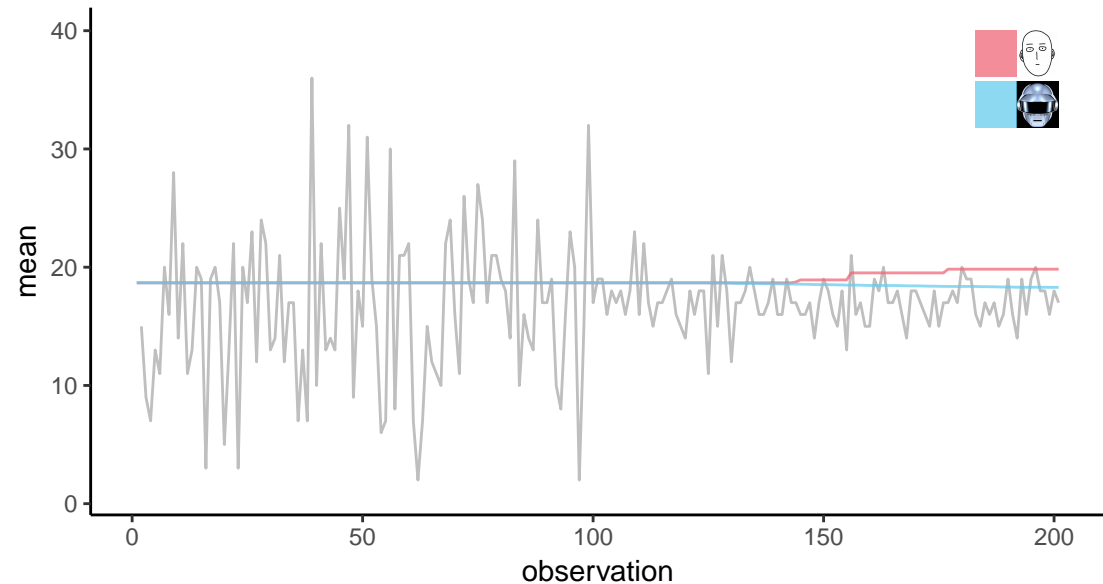
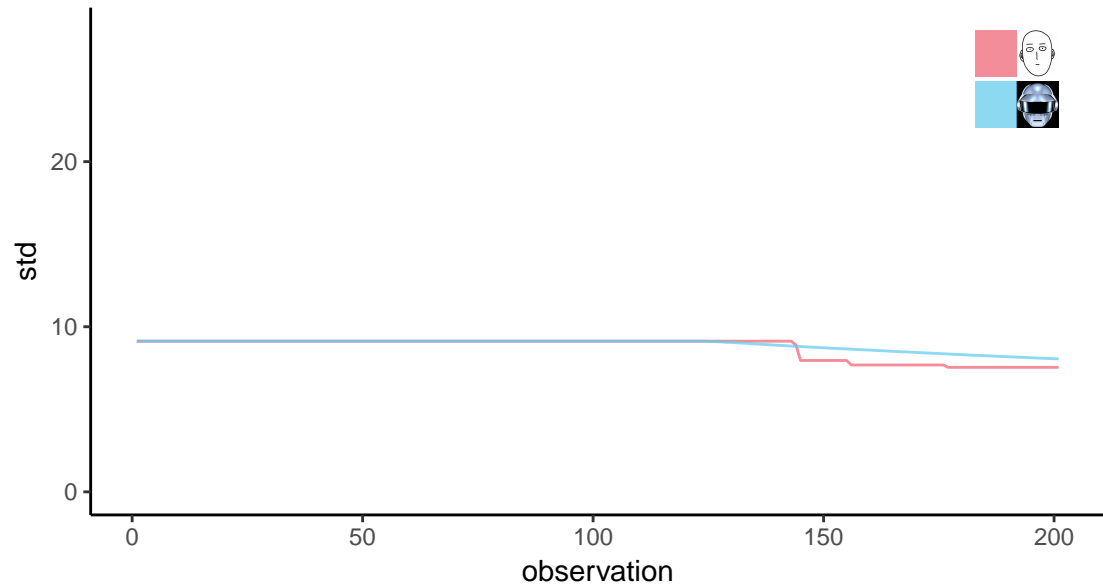


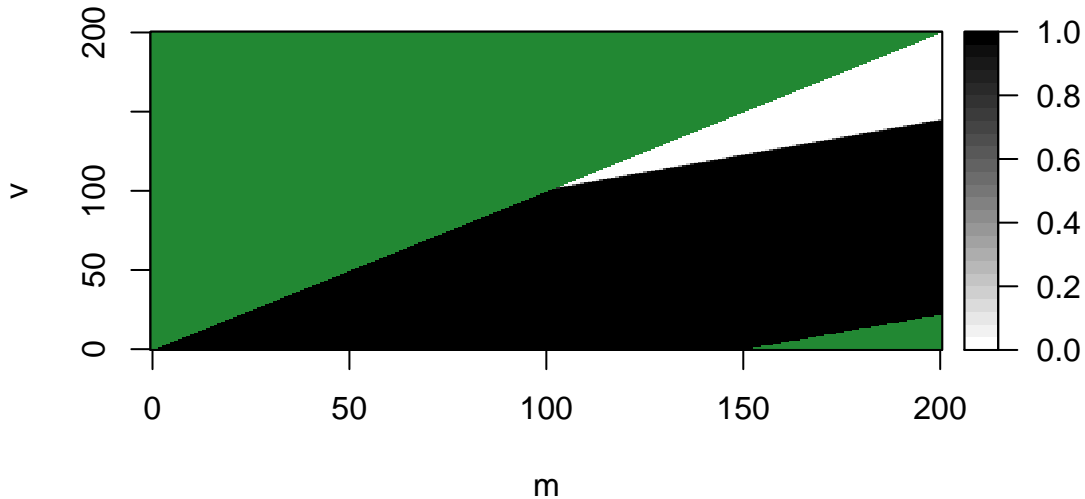
participant #14, means (black: plinko outcomes)



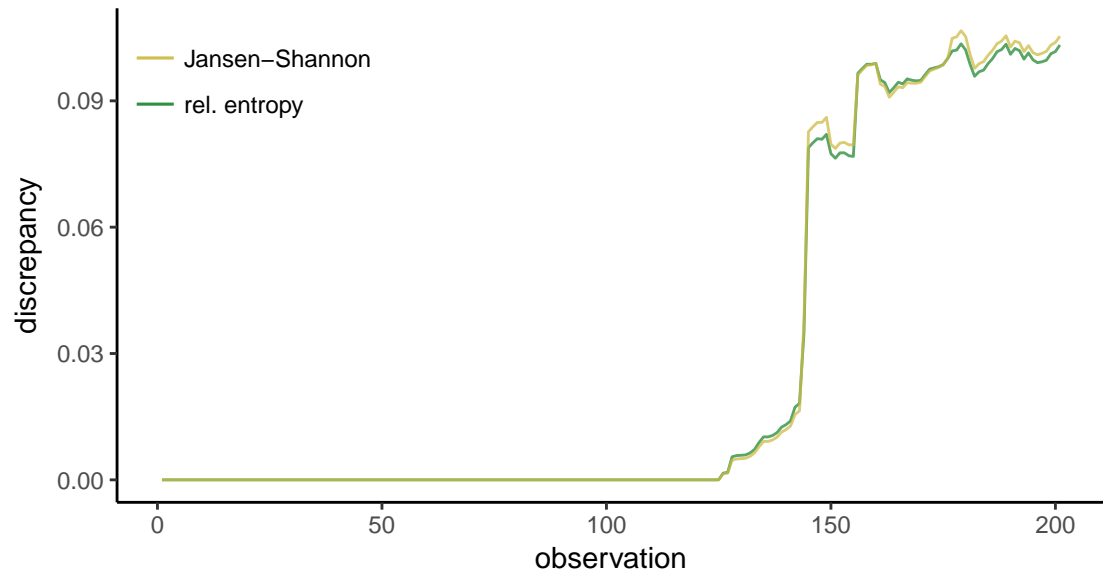
participant #14, st. deviations



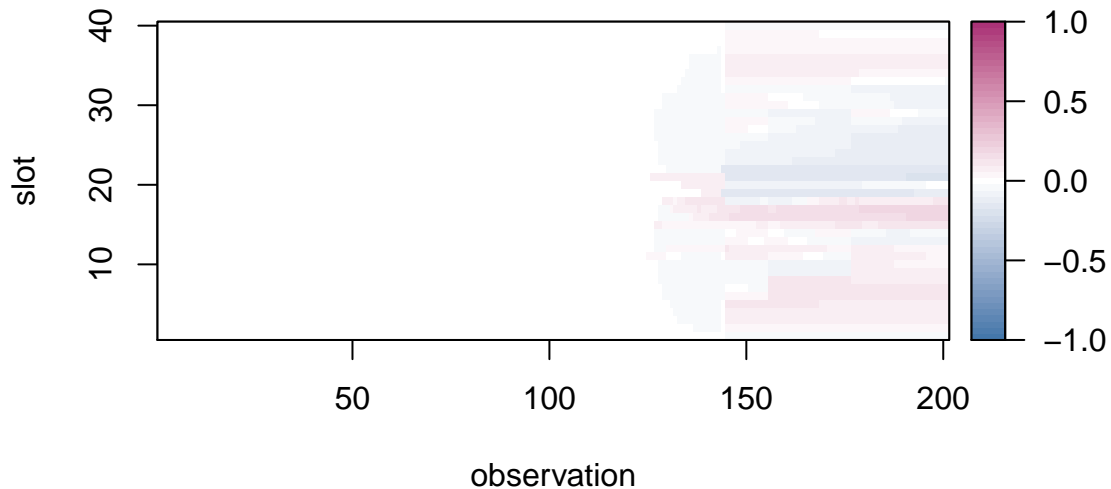
part. #14, stub. = 245, changepoint:



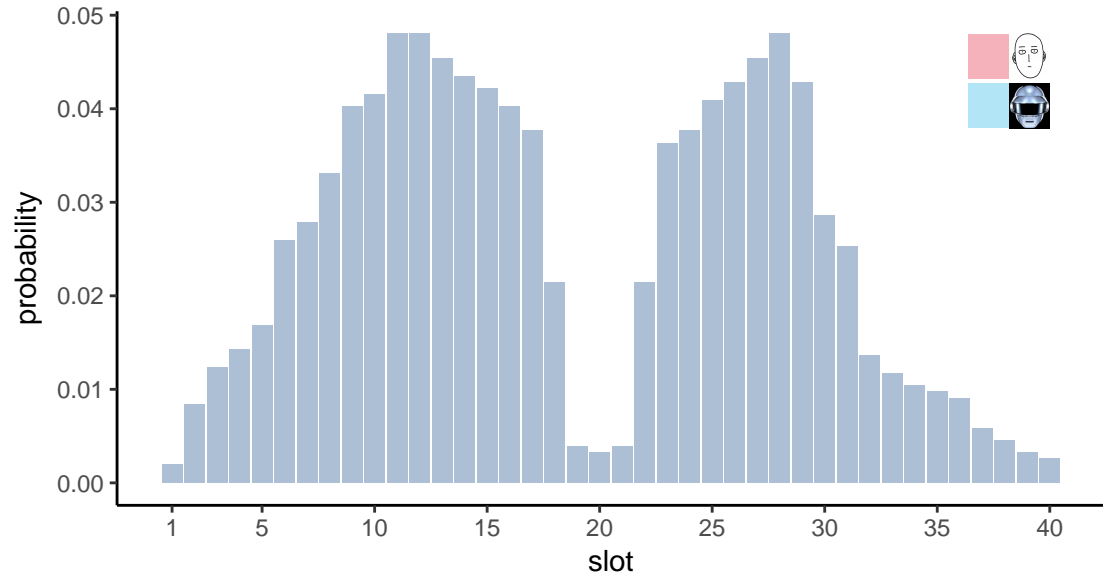
participant #14



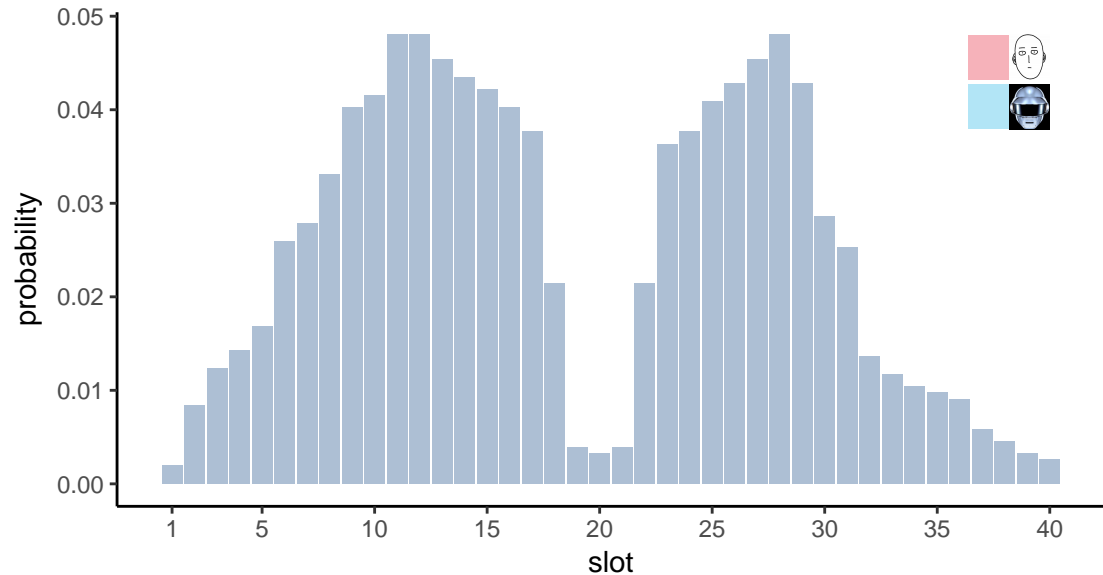
participant #14, sqrt(robot-participant)



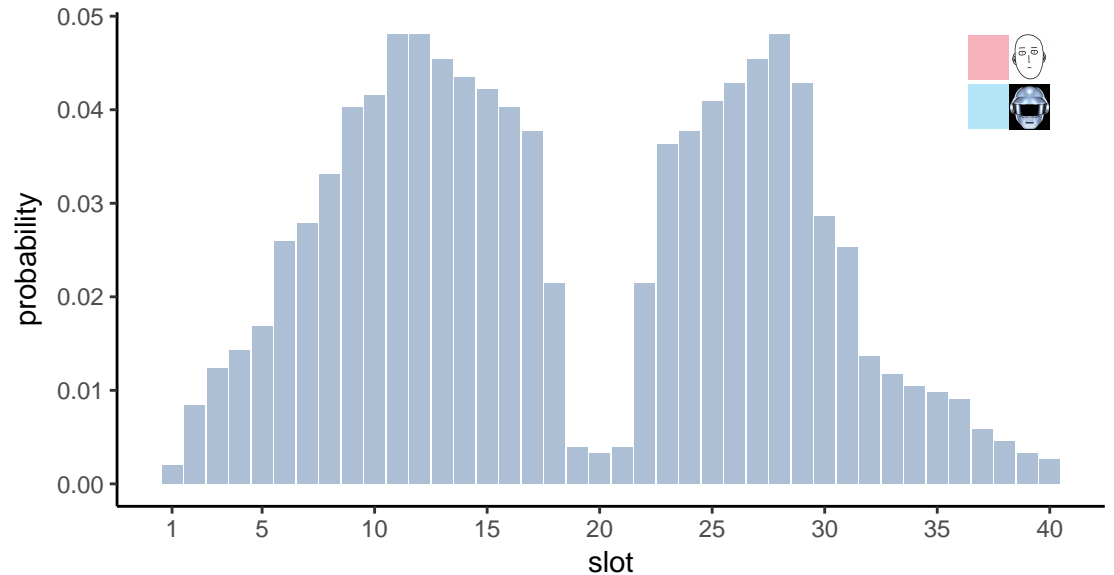
participant #14, observation 1, rel-entr. = 0, JS = 0



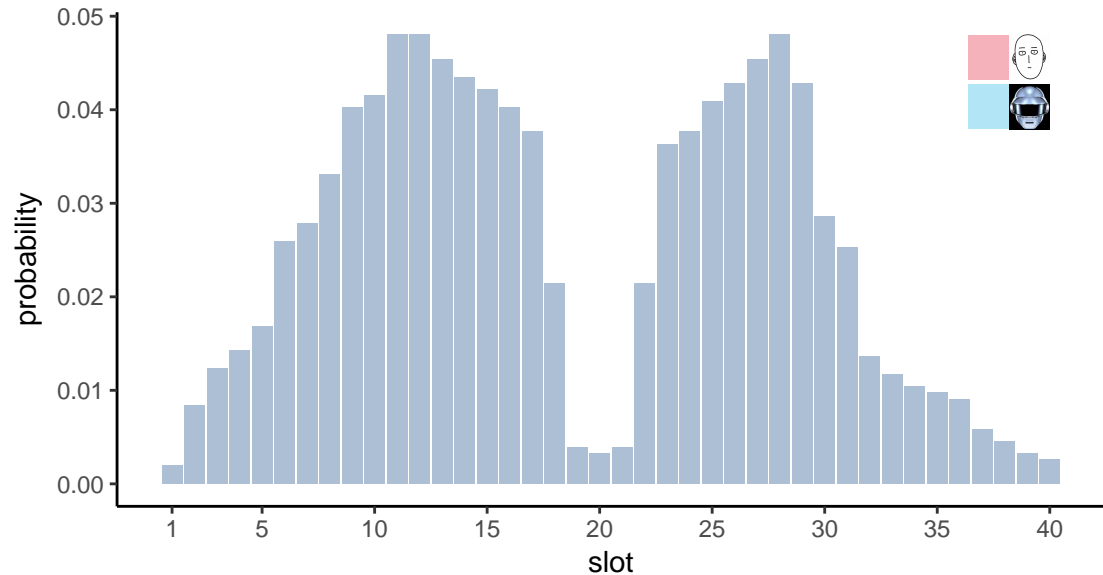
participant #14, observation 2, rel-entr. = $-1.6e-18$, JS = $2.7e-18$



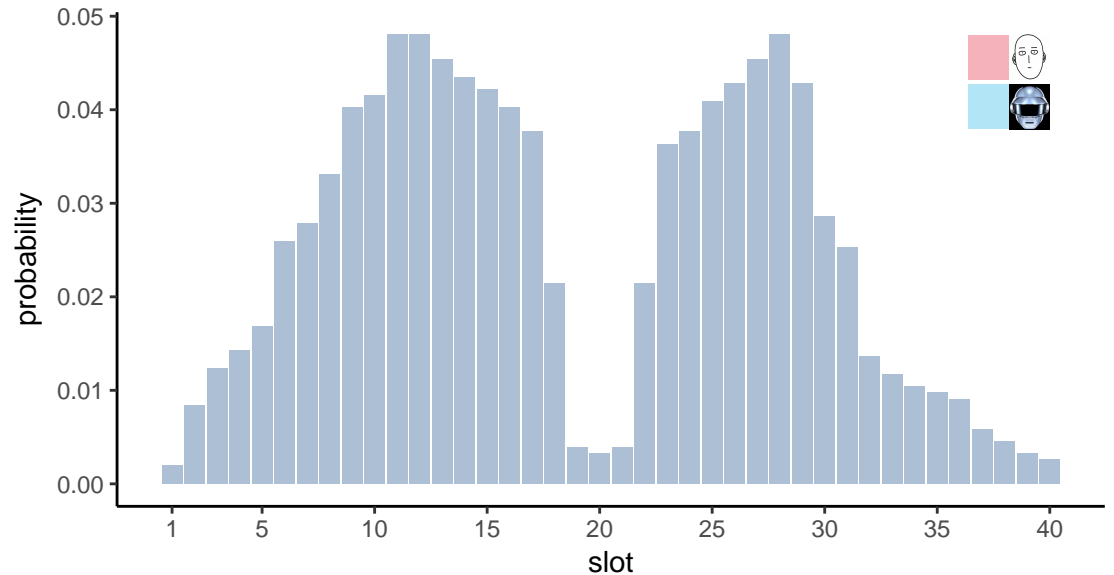
participant #14, observation 3, rel-entr. = $-5.2\text{e-}18$, JS = $-1.4\text{e-}1$



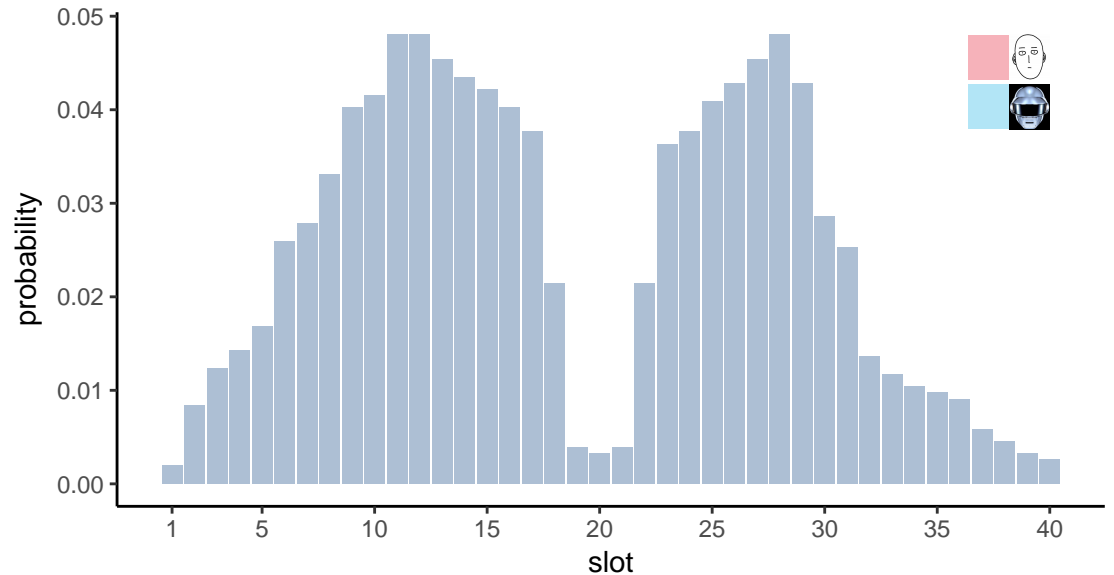
participant #14, observation 4, rel-entr. = $1.9\text{e}-17$, JS = $5.7\text{e}-18$



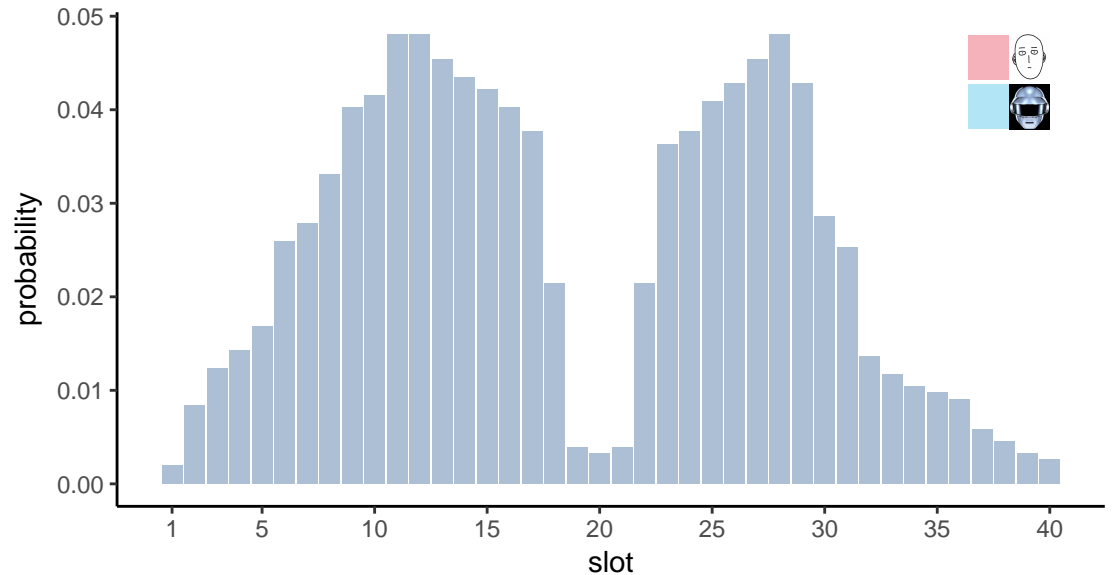
participant #14, observation 99, rel-entr. = $-5.8e-18$, JS = $2.4e-1$



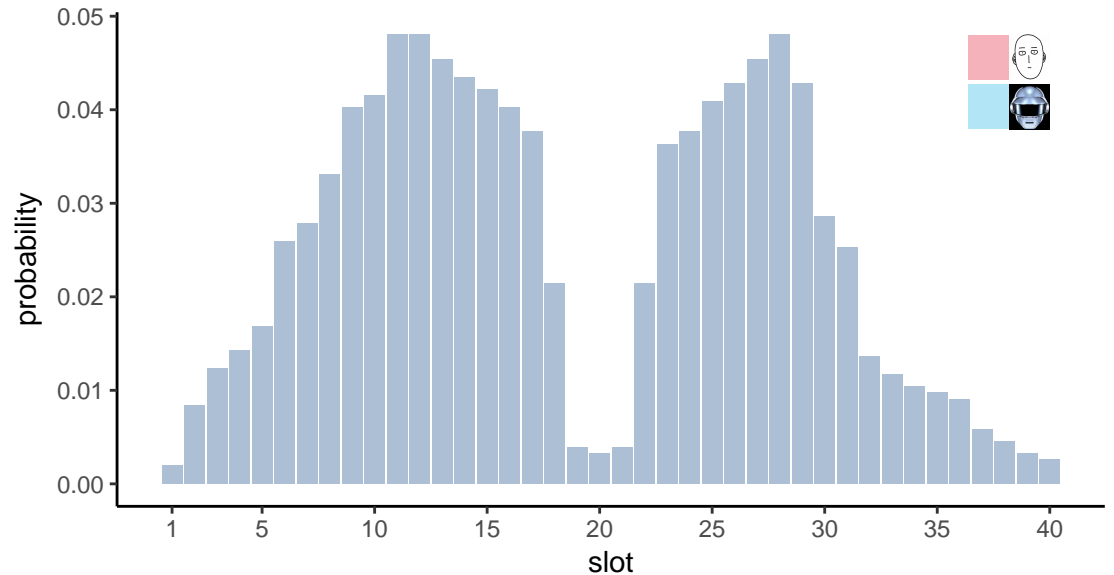
participant #14, observation 100, rel-entr. = $3.7\text{e-}18$, JS = $2.8\text{e-}1$



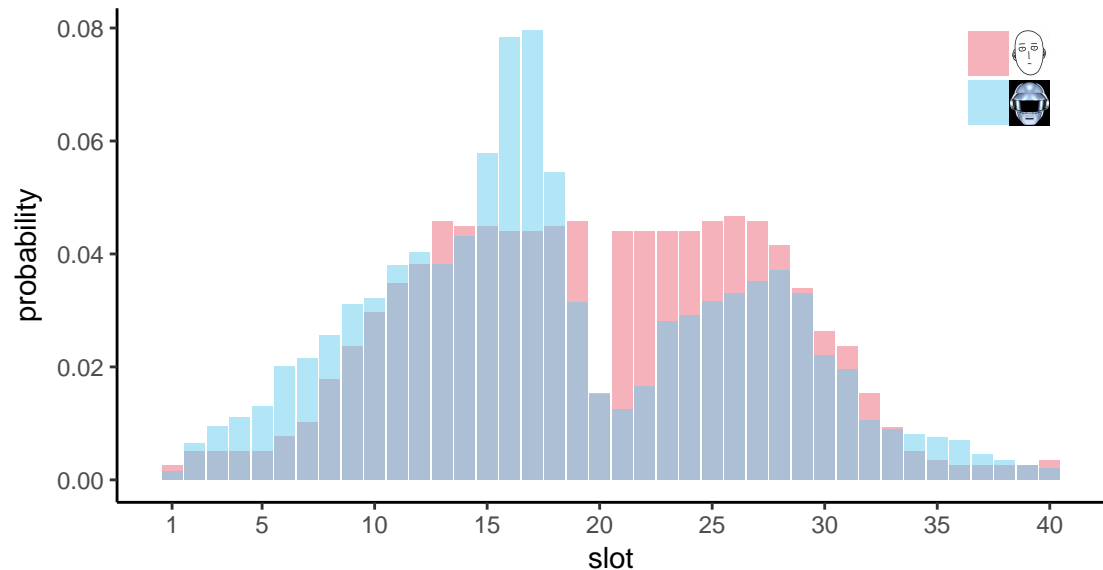
participant #14, observation 101, rel-entr. = $-1.4\text{e}-18$, JS = $6.8\text{e}-$



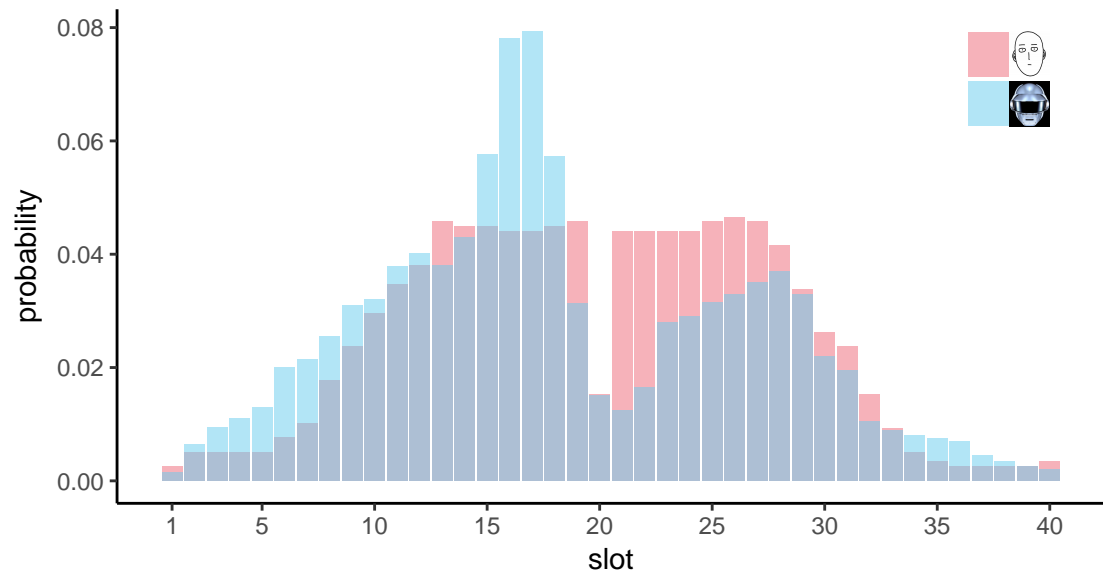
participant #14, observation 102, rel-entr. = $-1.4\text{e}-18$, JS = $6.8\text{e}-$



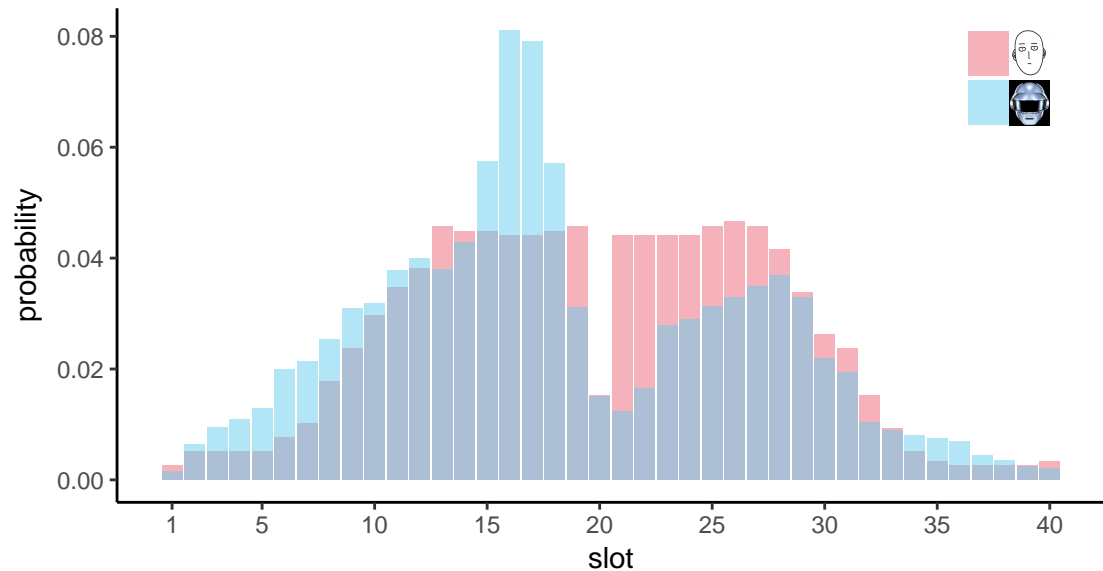
participant #14, observation 197, rel-entr. = 0.099, JS = 0.1



participant #14, observation 198, rel-entr. = 0.1, JS = 0.1



participant #14, observation 199, rel-entr. = 0.1, JS = 0.1



participant #14, observation 200, rel-entr. = 0.1, JS = 0.1

