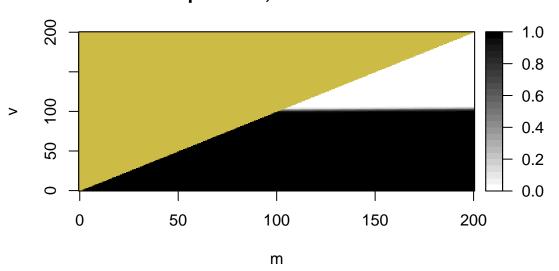
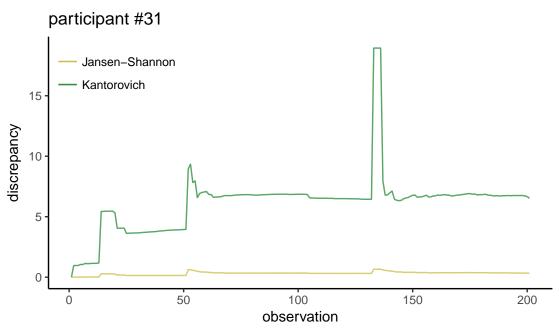


h for part. #31, stubbornness = 5.27





participant #31, sqrt(robot-participant)

