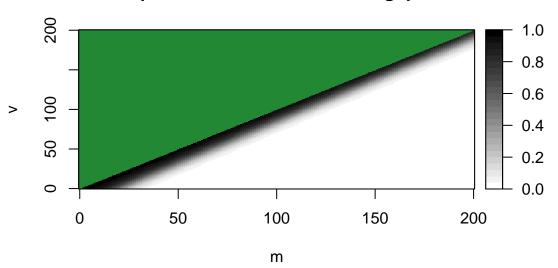
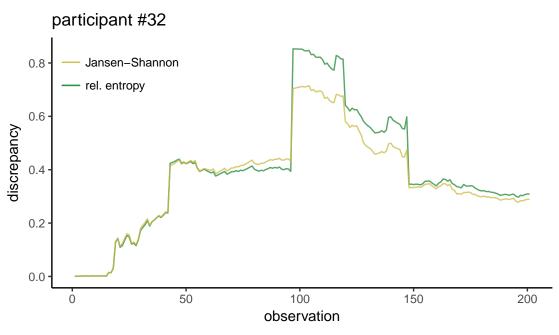
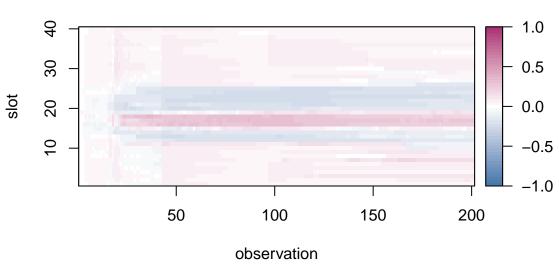


part. #32, stub. = 26.9, changepoint:



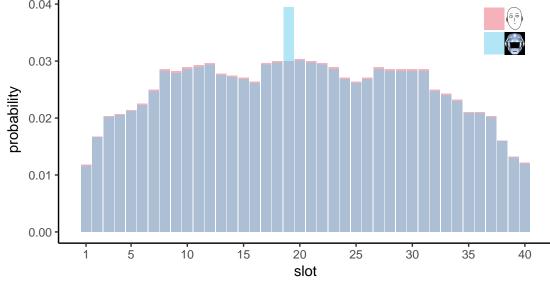


participant #32, sqrt(robot-participant)

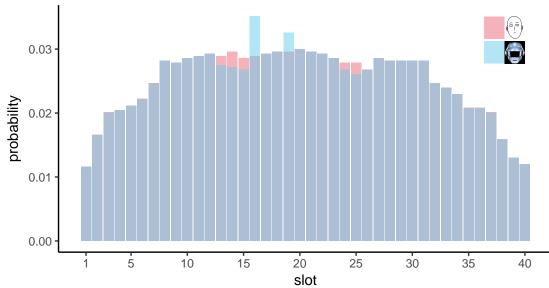


participant #32, observation 1, rel-entr. = 0, JS = 0 0.03 0.02 probability 0.01 0.00 15 25 30 5 10 20 35 40 slot

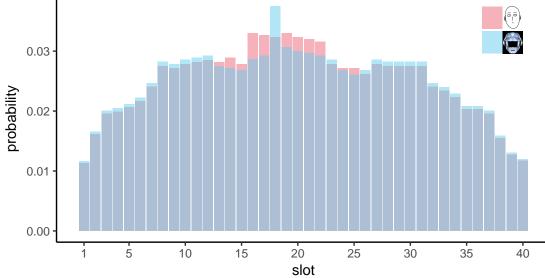
participant #32, observation 2, rel-entr. = 0.0014, JS = 0.0013



participant #32, observation 3, rel-entr. = 0.001, JS = 0.001



participant #32, observation 4, rel-entr. = 0.0015, JS = 0.0015



participant #32, observation 99, rel-entr. = 0.85, JS = 0.71 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #32, observation 100, rel-entr. = 0.85, JS = 0.71 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #32, observation 101, rel-entr. = 0.85, JS = 0.71 0.15 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #32, observation 102, rel-entr. = 0.85, JS = 0.71 0.15 probability 0.10 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #32, observation 197, rel-entr. = 0.3, JS = 0.28 0.10 probability 0.00 slot

participant #32, observation 198, rel-entr. = 0.3, JS = 0.28 0.10 probability 0.00 slot

participant #32, observation 199, rel-entr. = 0.31, JS = 0.29 0.10 probability 0.00 slot

participant #32, observation 200, rel-entr. = 0.31, JS = 0.29 0.10 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot