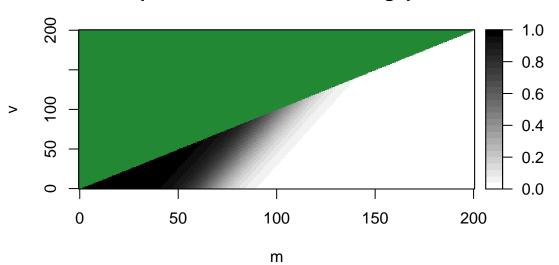
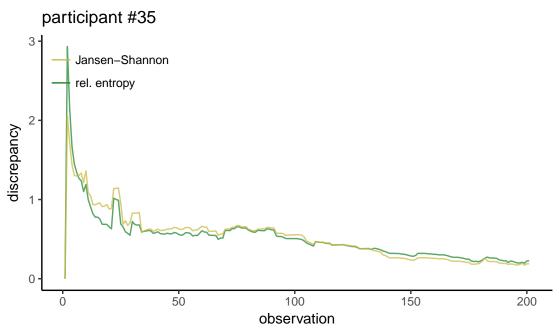
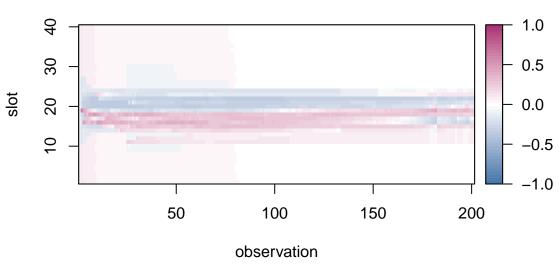


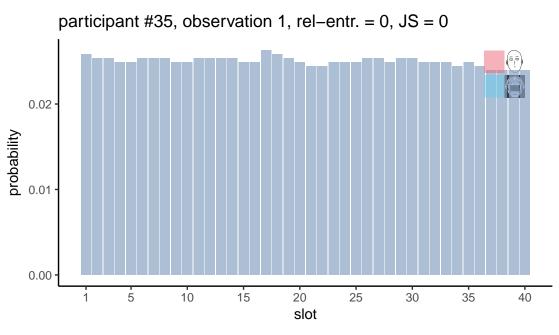
part. #35, stub. = 1.19, changepoint:

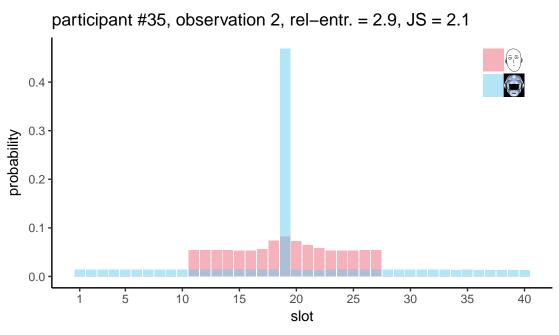




participant #35, sqrt(robot-participant)

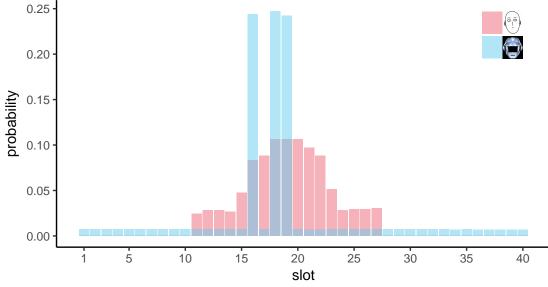






participant #35, observation 3, rel-entr. = 2.1, JS = 1.7 0.3 probability 0.2 0.1 0.0 15 20 25 30 10 40 35 slot

participant #35, observation 4, rel-entr. = 1.7, JS = 1.4



participant #35, observation 99, rel-entr. = 0.51, JS = 0.55 0.20 0.15 probability 0.10 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #35, observation 100, rel-entr. = 0.51, JS = 0.56 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #35, observation 101, rel-entr. = 0.51, JS = 0.56 0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #35, observation 102, rel-entr. = 0.5, JS = 0.55 0.20 0.15 probability 0.10 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #35, observation 197, rel-entr. = 0.2, JS = 0.18 0.2 probability 0.0 10 20 25 30 15 35 40 slot

participant #35, observation 198, rel-entr. = 0.21, JS = 0.2 0.2 probability 0.0 10 15 20 25 30 35 40 slot

participant #35, observation 199, rel-entr. = 0.2, JS = 0.17 0.25 -0.20 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #35, observation 200, rel-entr. = 0.22, JS = 0.19 0.20 0.15 probability 0.05 0.00

20

slot

25

30

35

40

10

5

15