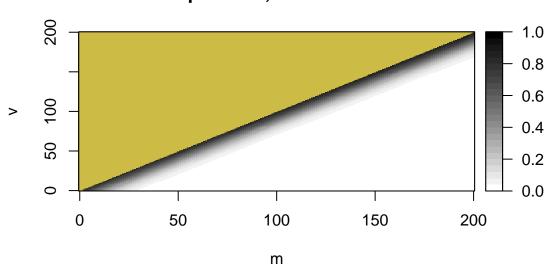
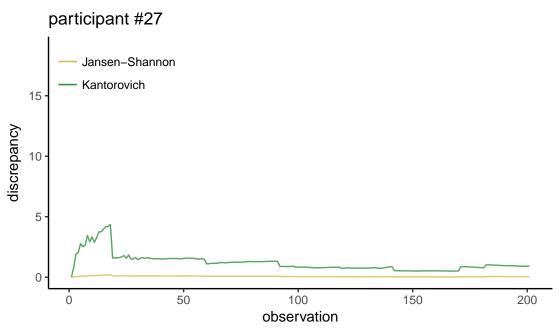
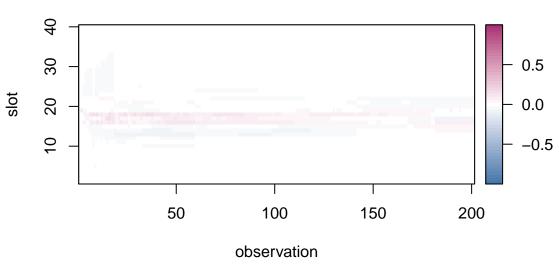


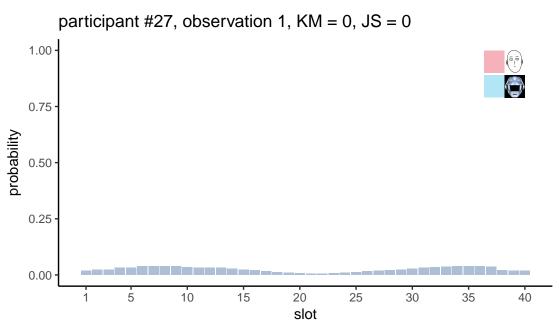
## h for part. #27, stubbornness = 5.91

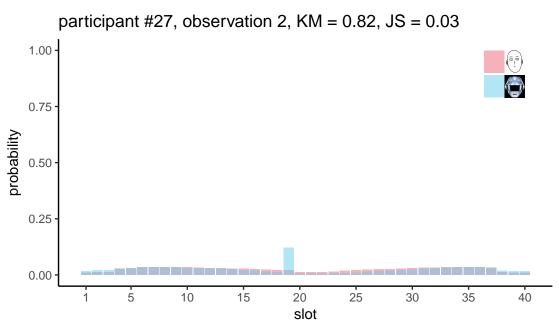


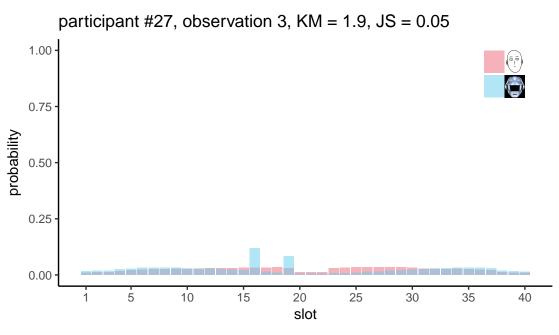


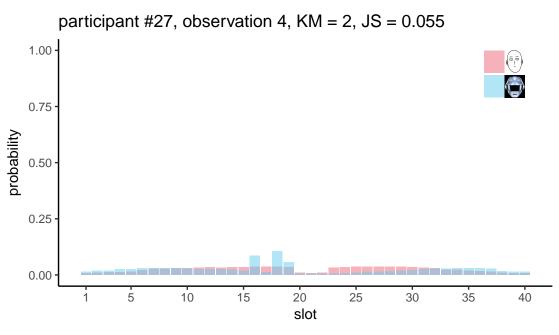
## participant #27, sqrt(robot-participant)

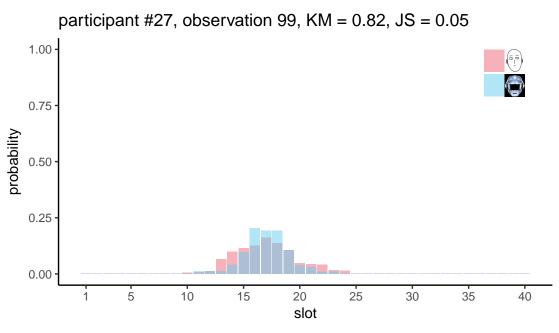


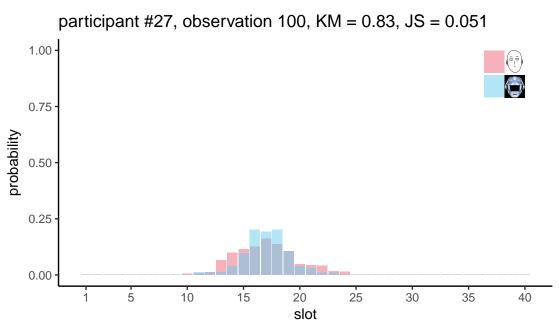












participant #27, observation 101, KM = 0.83, JS = 0.051 1.00 0.75 probability 0.25 0.00 15 25 30 35 5 20 10 40 slot

