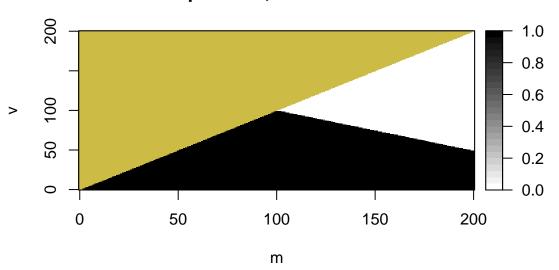
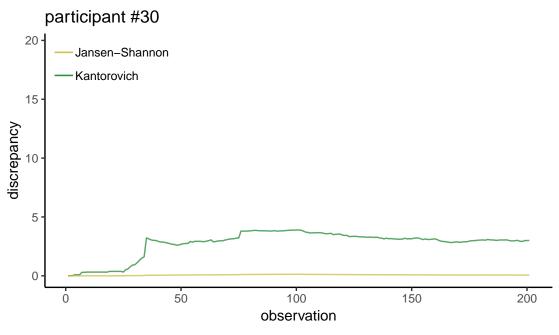


h for part. #30, stubbornness = 25.5





participant #30, sqrt(robot-participant)

