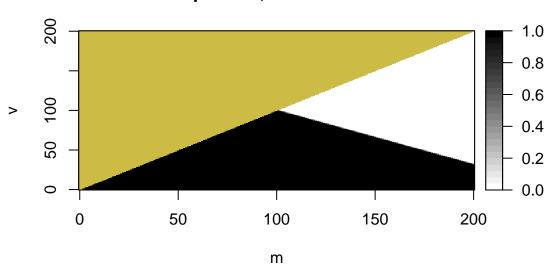
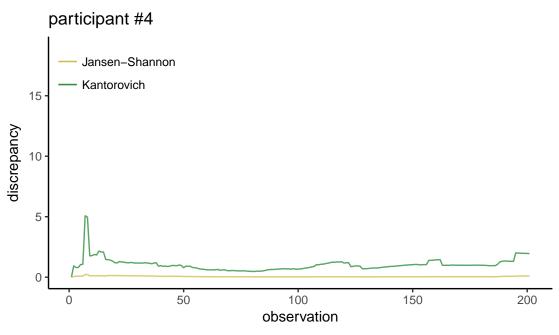
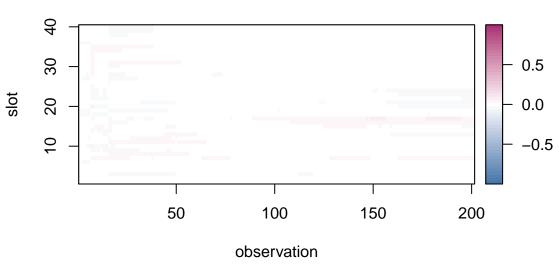


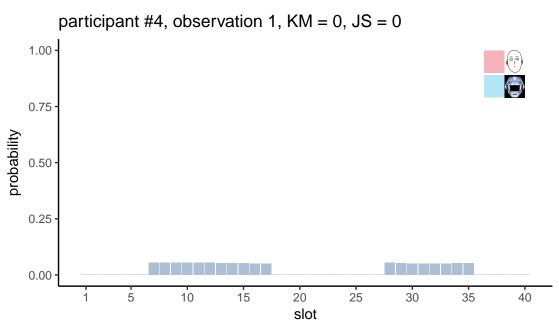
## h for part. #4, stubbornness = 32.1





## participant #4, sqrt(robot-participant)





participant #4, observation 2, KM = 0.94, JS = 0.055 1.00 0.75 probability 0.50 0.25 0.00 15 25 30 5 10 35 20 40 slot

