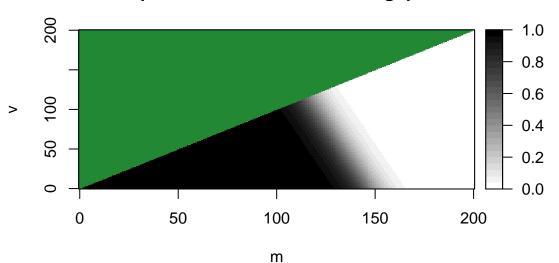
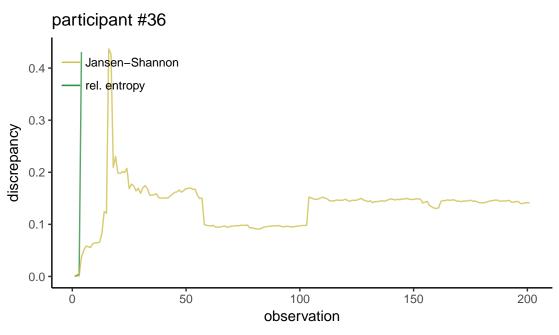
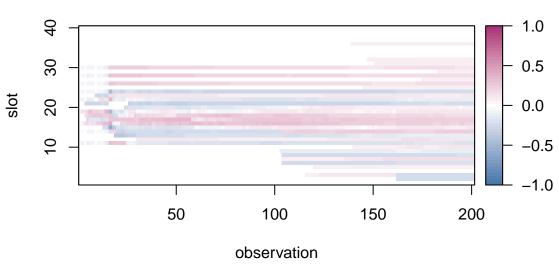


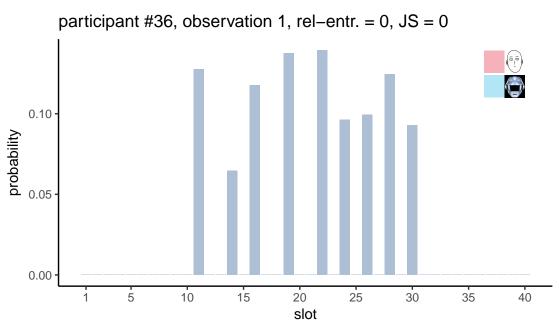
part. #36, stub. = 34.6, changepoint:





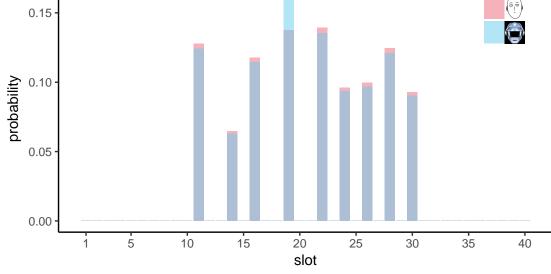
participant #36, sqrt(robot-participant)



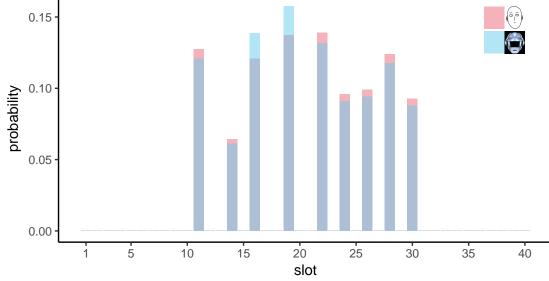


0.15

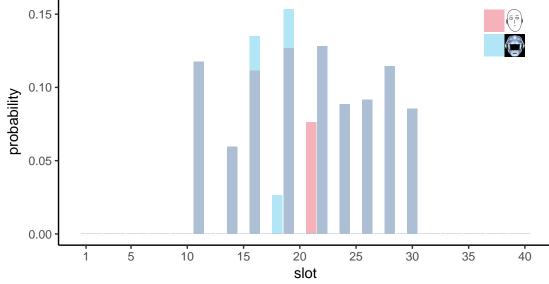
participant #36, observation 2, rel-entr. = 0.0024, JS = 0.00058



participant #36, observation 3, rel-entr. = 0.0037, JS = 0.00091

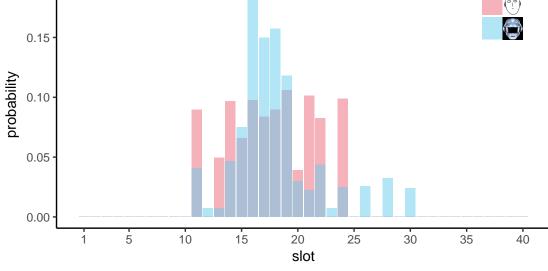


participant #36, observation 4, rel-entr. = 0.43, JS = 0.037



participant #36, observation 99, rel-entr. = 1.5, JS = 0.097 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #36, observation 100, rel-entr. = 1.5, JS = 0.097 0.15 probability 0.05



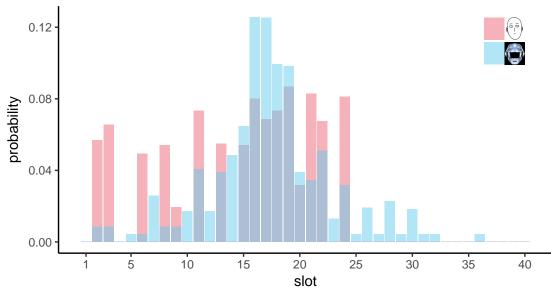
participant #36, observation 101, rel-entr. = 1.5, JS = 0.098 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40 slot

participant #36, observation 102, rel-entr. = 1.5, JS = 0.098 0.15 probability 0.05 0.00 10 15 25 30 35 5 20 40

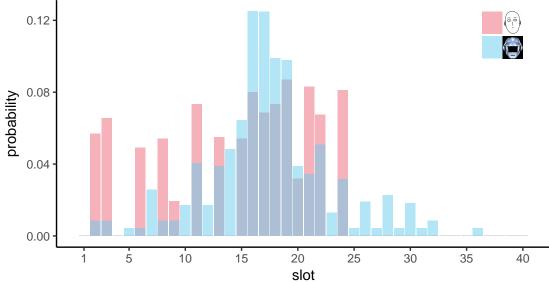
slot

participant #36, observation 197, rel-entr. = 3, JS = 0.14 0.10 probability 0.00 slot

participant #36, observation 198, rel-entr. = 2.9, JS = 0.14



participant #36, observation 199, rel-entr. = 3, JS = 0.14



participant #36, observation 200, rel-entr. = 3, JS = 0.14 0.10 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot