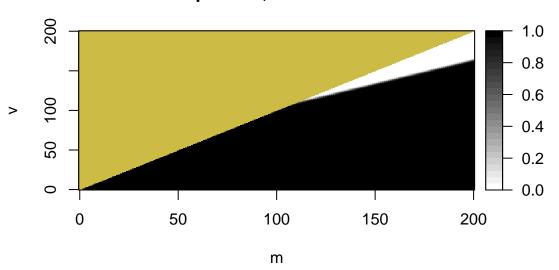
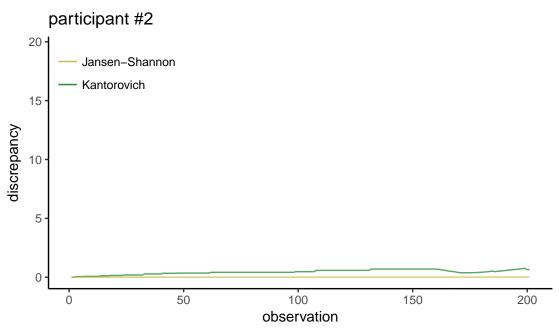


h for part. #2, stubbornness = 192





participant #2, sqrt(robot-participant)

