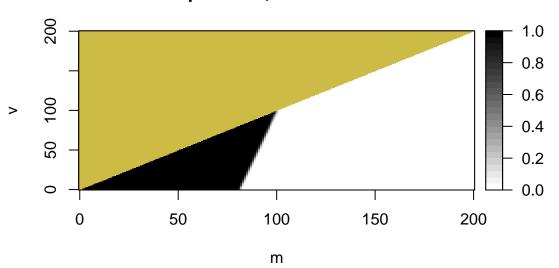
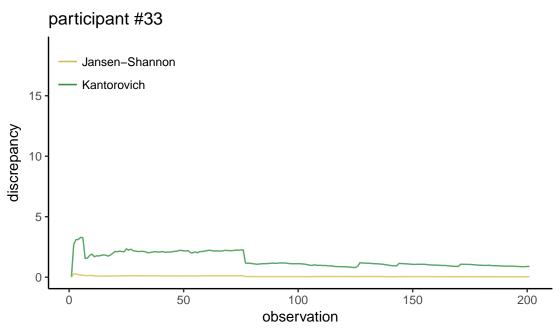


h for part. #33, stubbornness = 1.81





participant #33, sqrt(robot-participant)

