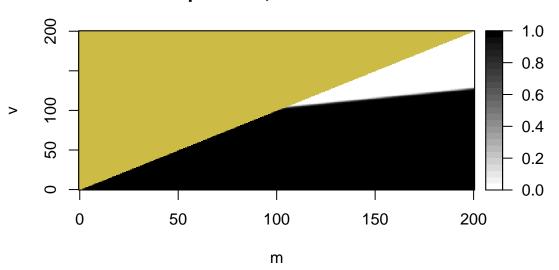
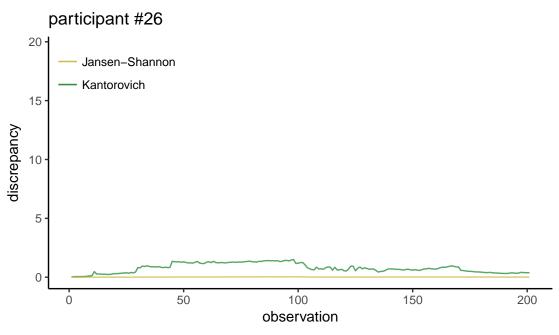
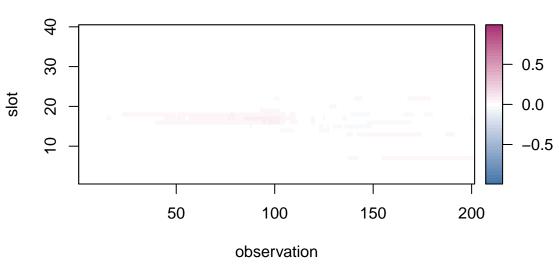


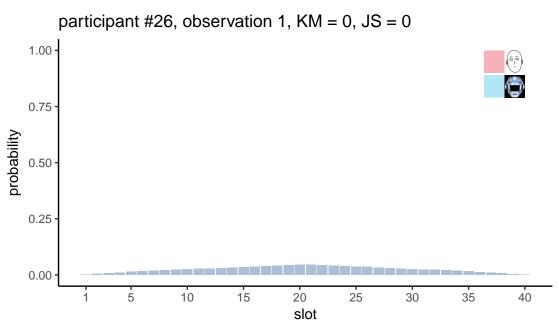
h for part. #26, stubbornness = 77.5

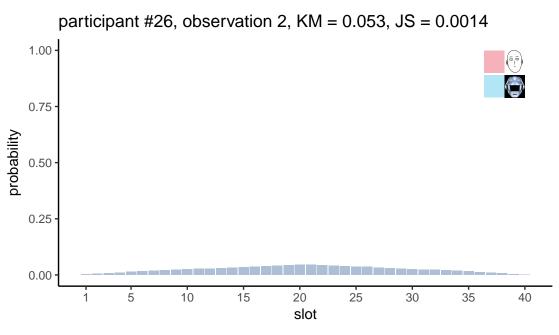


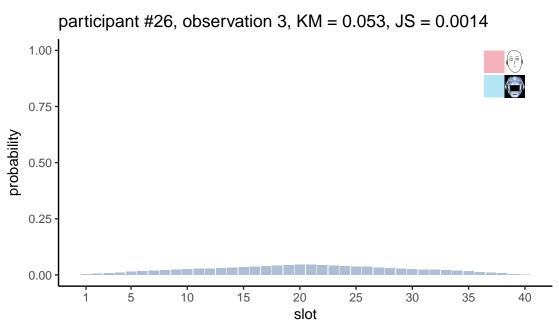


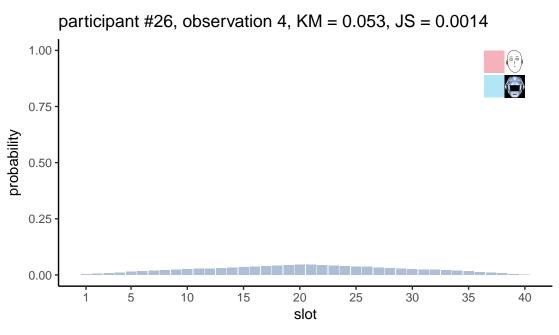
participant #26, sqrt(robot-participant)

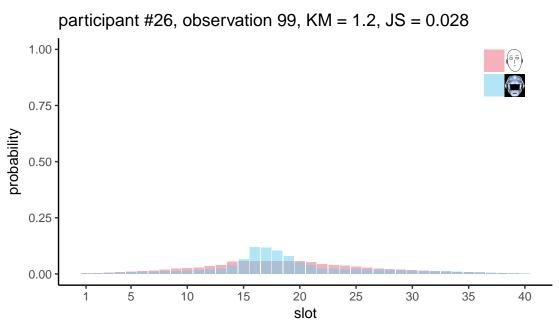


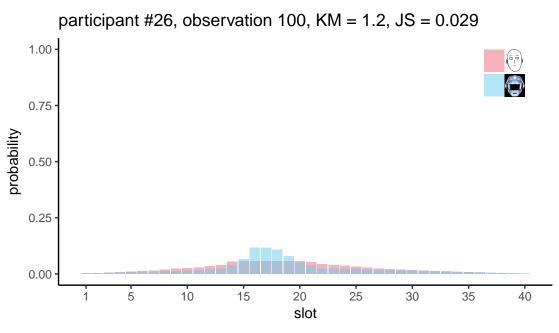


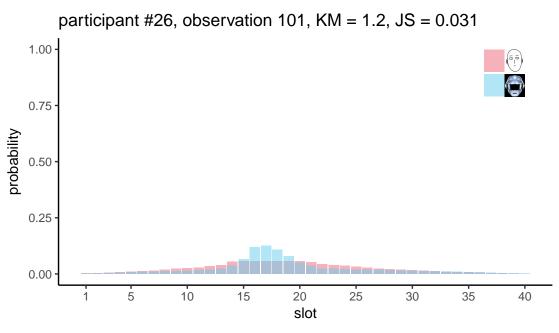


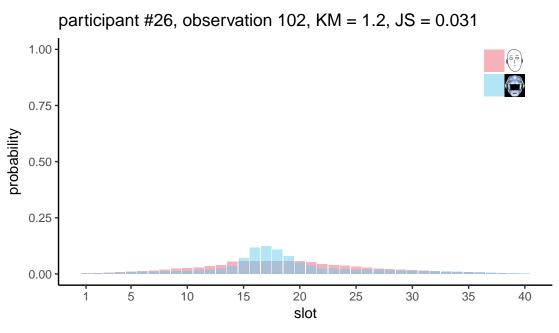












participant #26, observation 197, KM = 0.4, JS = 0.013 1.00 0.75 probability 0.25 0.00 10 15 25 5 20 35 30 40 slot

