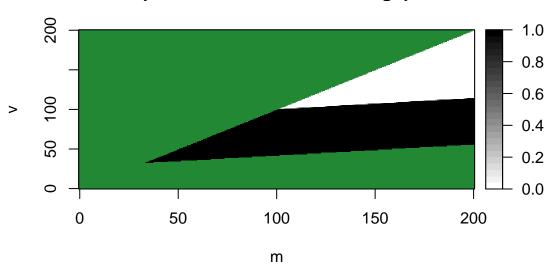
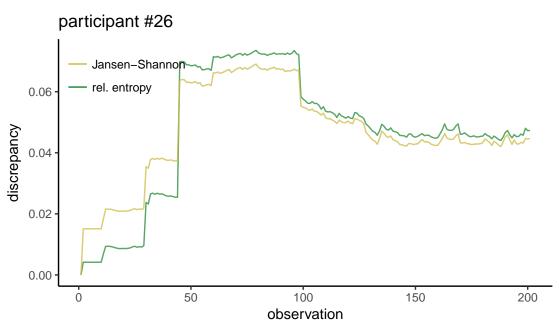
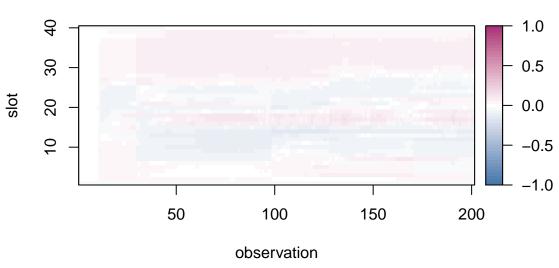


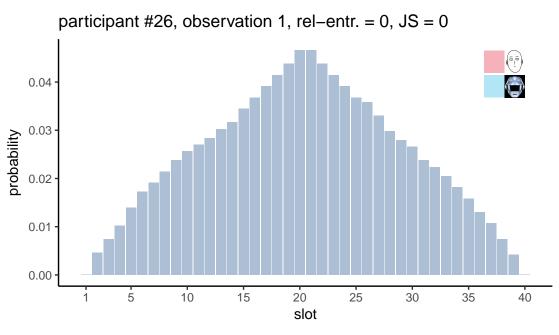
part. #26, stub. = 315, changepoint:



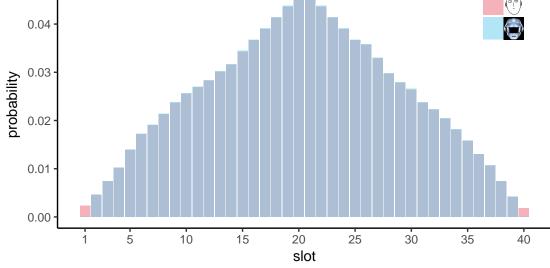


participant #26, sqrt(robot-participant)

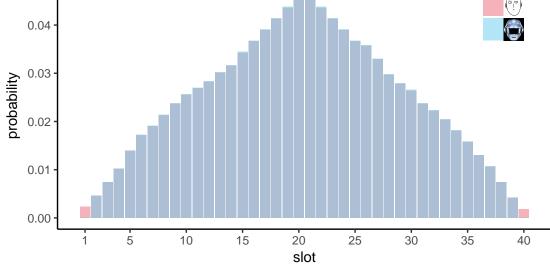




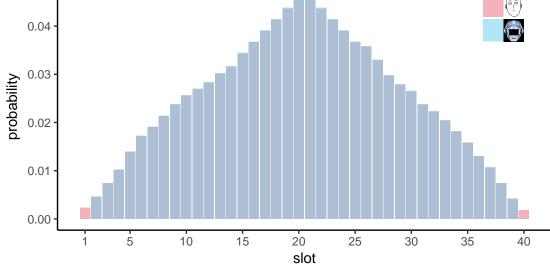
participant #26, observation 2, rel-entr. = 0.0042, JS = 0.015 0.04 0.03



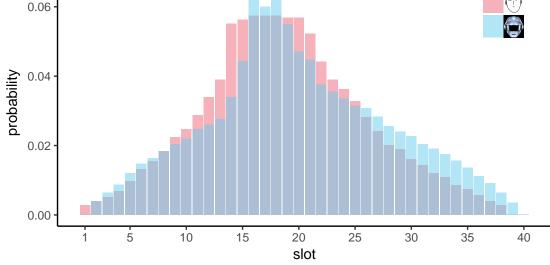
participant #26, observation 3, rel-entr. = 0.0042, JS = 0.015 0.04 0.03



participant #26, observation 4, rel-entr. = 0.0042, JS = 0.015 0.04 0.03



participant #26, observation 99, rel-entr. = 0.058, JS = 0.055 0.06 0.04



participant #26, observation 100, rel-entr. = 0.058, JS = 0.055 0.06 probability 0.02 0.00 15 25 30 5 10 20 35 40

slot

participant #26, observation 101, rel-entr. = 0.057, JS = 0.055 0.06 probability 0.04 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #26, observation 102, rel-entr. = 0.056, JS = 0.054 0.06 probability 0.02

20

slot

25

30

35

40

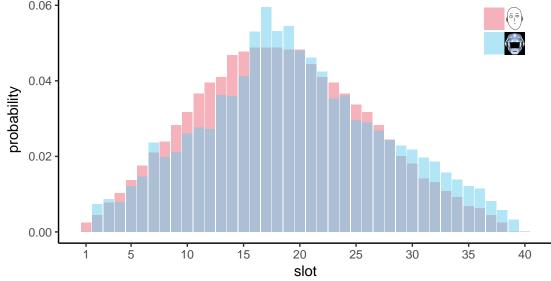
15

10

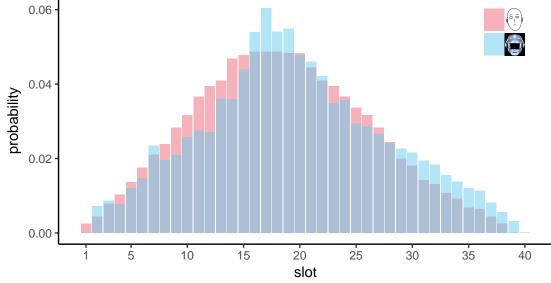
0.00

5

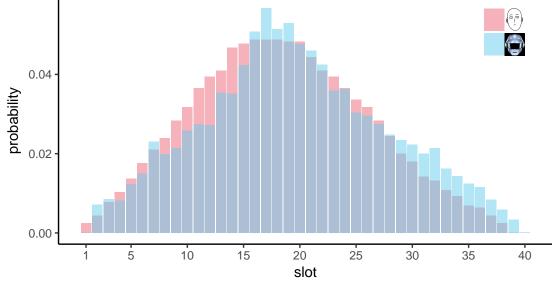
participant #26, observation 197, rel-entr. = 0.046, JS = 0.043



participant #26, observation 198, rel-entr. = 0.046, JS = 0.043



participant #26, observation 199, rel-entr. = 0.048, JS = 0.045



participant #26, observation 200, rel-entr. = 0.047, JS = 0.045

