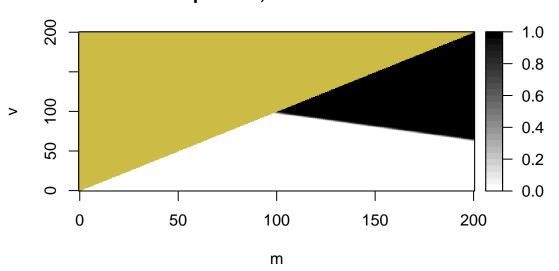
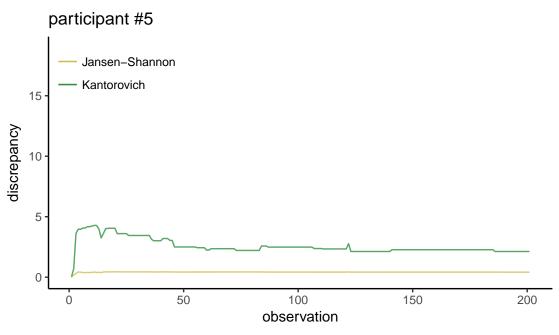
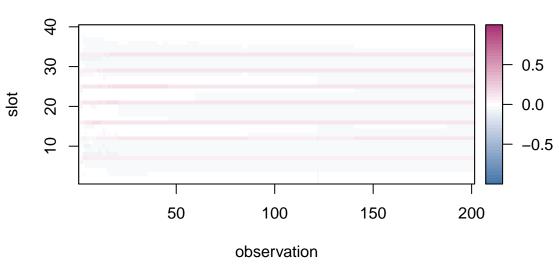


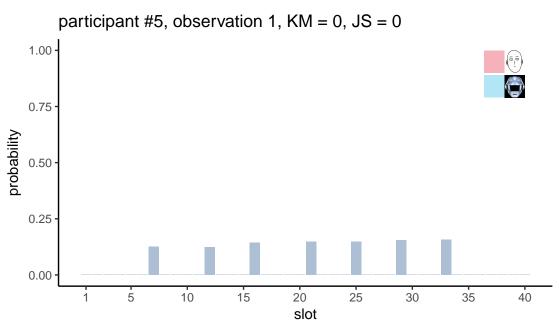
h for part. #5, stubbornness = 17.4





participant #5, sqrt(robot-participant)





participant #5, observation 2, KM = 0.71, JS = 0.18 1.00 0.75 probability 0.25 0.00 15 25 5 10 20 30 35 40 slot

