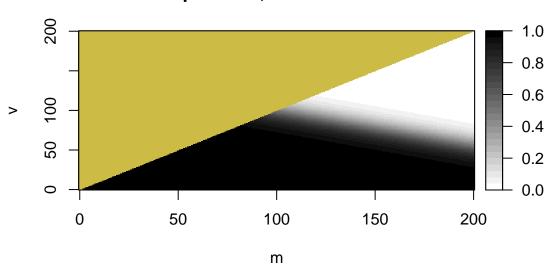
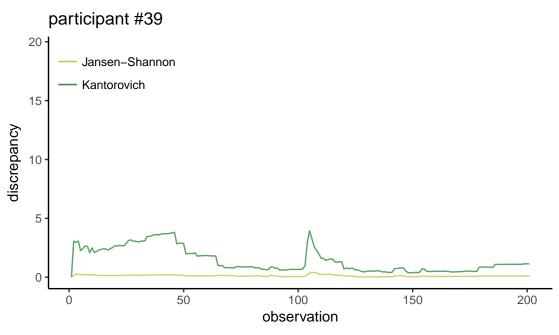


h for part. #39, stubbornness = 0.989





participant #39, sqrt(robot-participant)

