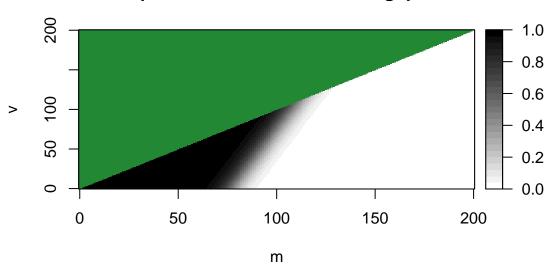
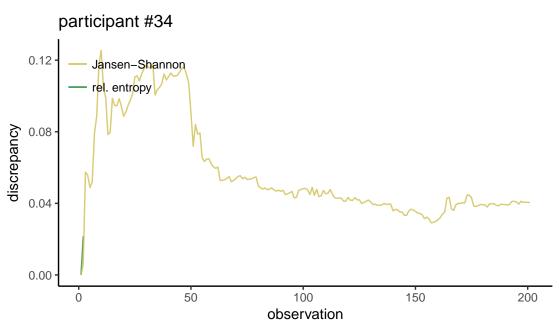
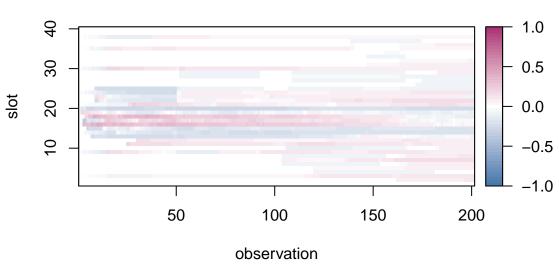


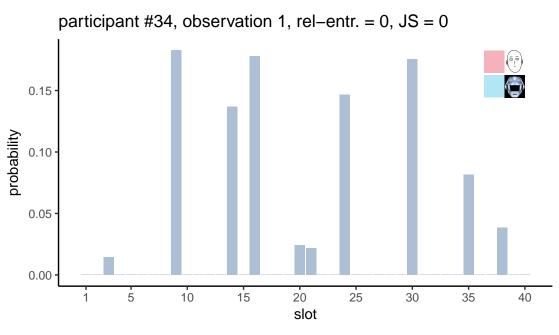
part. #34, stub. = 6.44, changepoint:



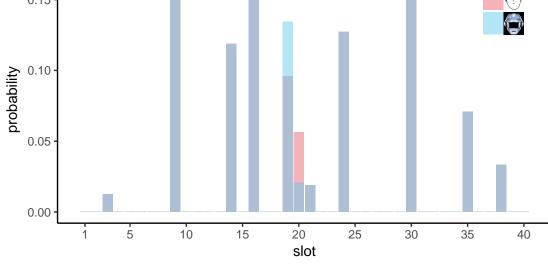


## participant #34, sqrt(robot-participant)

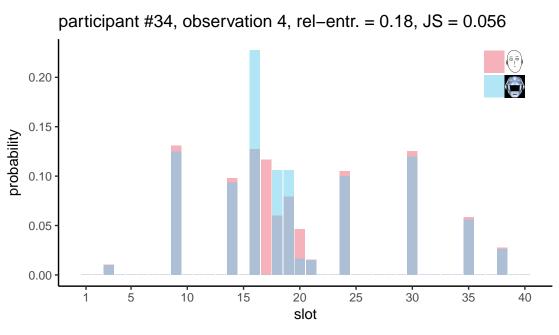




participant #34, observation 2, rel-entr. = 0.022, JS = 0.0059 0.15 0.10



participant #34, observation 3, rel-entr. = 0.18, JS = 0.057 0.2 probability 0.0 10 15 20 30 25 35 40 slot

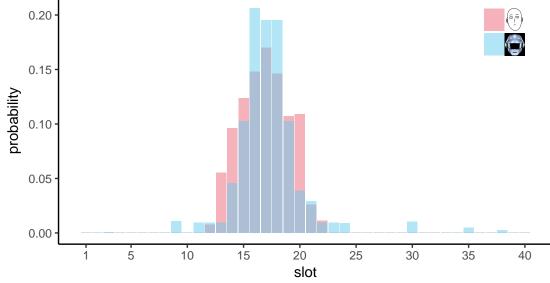


participant #34, observation 99, rel-entr. = 0.91, JS = 0.048 0.20 0.15 probability 0.10 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #34, observation 100, rel-entr. = 0.9, JS = 0.048 0.20 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #34, observation 101, rel-entr. = 0.9, JS = 0.048 0.20 0.15 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #34, observation 102, rel-entr. = 0.88, JS = 0.048



participant #34, observation 197, rel-entr. = 0.88, JS = 0.041 0.15 0.10 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #34, observation 198, rel-entr. = 0.88, JS = 0.041 0.15 0.10 probability 0.05 0.00 15 25 30 35 5 10 20 40 slot

participant #34, observation 199, rel-entr. = 0.87, JS = 0.041 0.15 0.10 probability 0.05 0.00 15 25 30 5 10 20 35 40 slot

participant #34, observation 200, rel-entr. = 0.87, JS = 0.041

