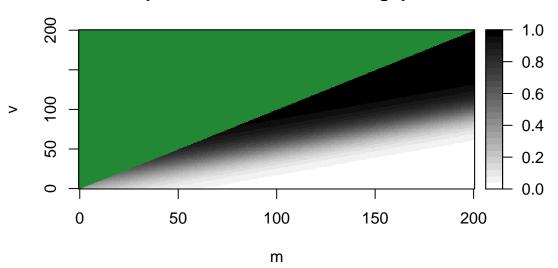
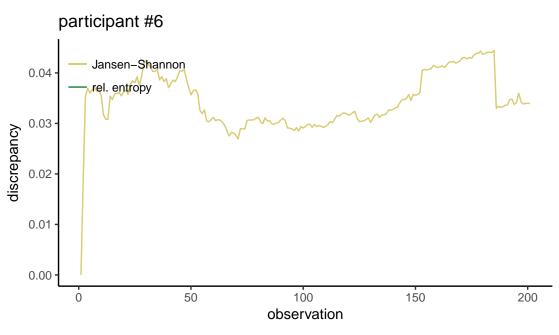
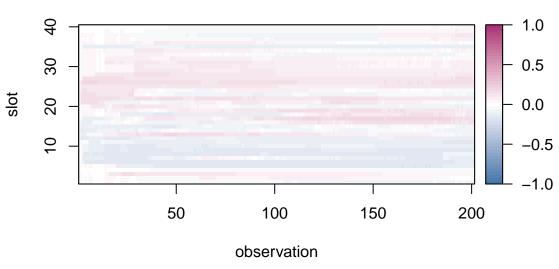


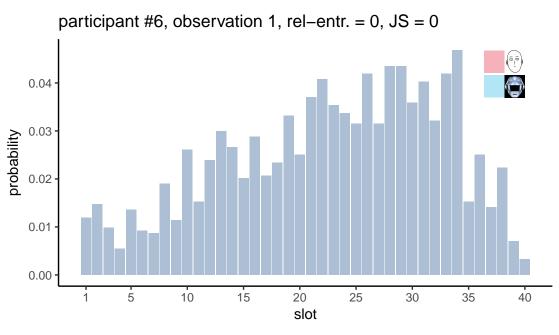
part. #6, stub. = 75.9, changepoint:

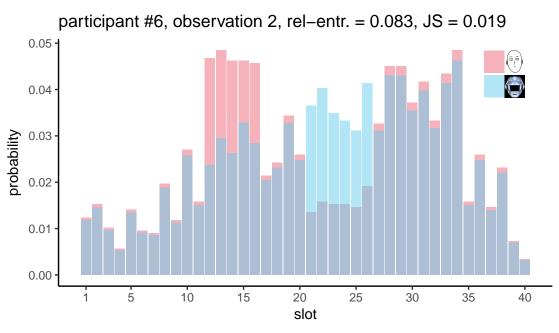


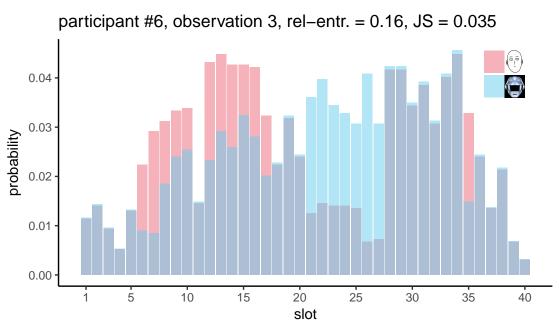


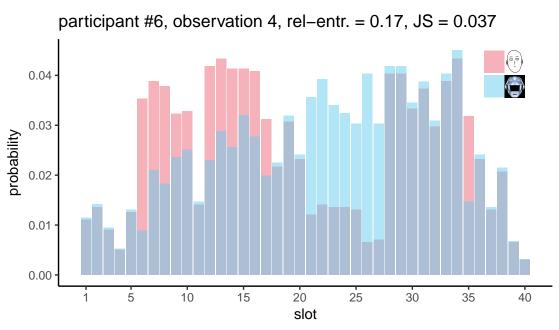
## participant #6, sqrt(robot-participant)

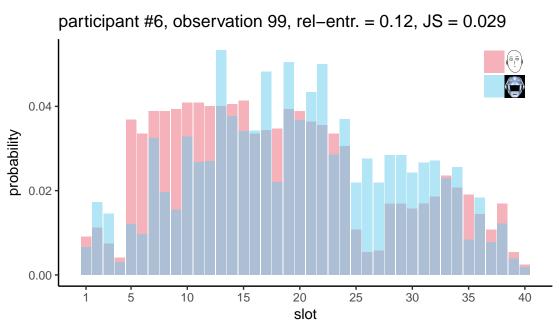




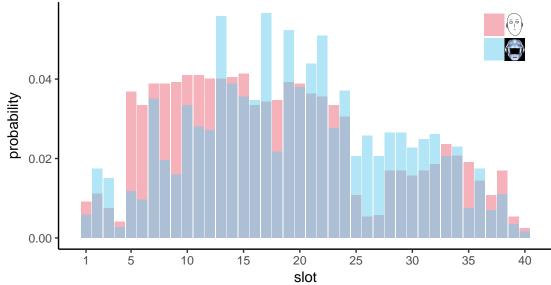








participant #6, observation 100, rel-entr. = 0.12, JS = 0.029



participant #6, observation 101, rel-entr. = 0.12, JS = 0.029 0.06 0.04 probability 0.02 0.00 15 25 30 5 10 20 35 40 slot

participant #6, observation 102, rel-entr. = 0.12, JS = 0.03 0.06 0.04 probability 0.02 0.00

20

slot

25

30

35

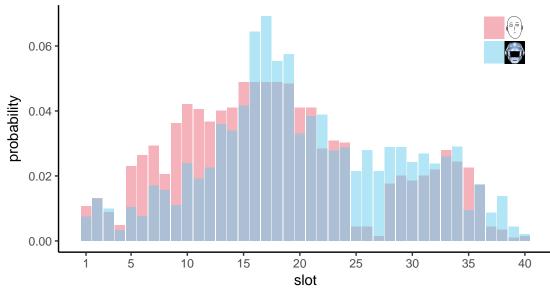
40

15

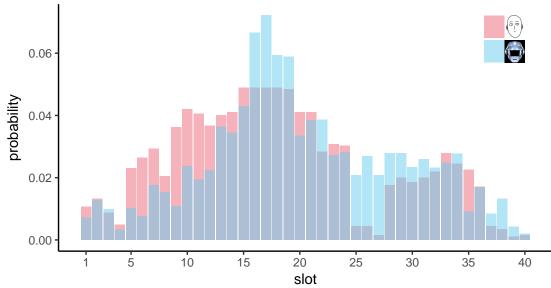
10

5

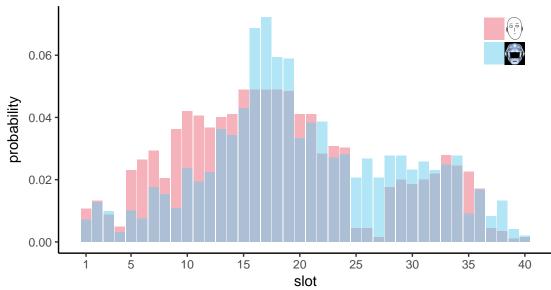
participant #6, observation 197, rel-entr. = 0.17, JS = 0.034



participant #6, observation 198, rel-entr. = 0.16, JS = 0.034



participant #6, observation 199, rel-entr. = 0.16, JS = 0.034



participant #6, observation 200, rel-entr. = 0.16, JS = 0.034

