SDIRK Time Integration and Variable Material Properties for Radiative Transfer

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August 21, 2014

1 Generic SDIRK

Consider a generic Butcher Tableaux:

Let ψ be our variable of interest. Then $\psi_{n+1} = \psi(t_n + \Delta t)$ is:

$$\psi_{n+1} = \psi_n + \Delta t \sum_{i=1}^s b_i k_i \tag{1}$$

where k_i is defined as:

$$k_i = f\left(t_n + c_i \Delta t, \ \psi_n + \Delta t \sum_{j=1}^i c_{ij} k_j\right)$$

and

$$f(t,\psi) = \frac{\partial \psi}{\partial t}$$

Eq. (1) can also be interpreted as meaning:

$$\psi_i = \psi_n + \Delta t \sum_{j=1}^i a_{ij} f(t_n + \Delta t c_j, \psi_j)$$
(2)

2 Grey Equations

We know that the 1D, mono-energetic (grey) radiative transfer equations are:

$$\frac{1}{c}\frac{\partial I}{\partial t} + \mu \frac{\partial}{\partial x}I + \sigma_t I = \frac{\sigma_s}{4\pi}\phi + \frac{\sigma_a}{4\pi}acT^4 + S_I$$
$$C_v \frac{\partial T}{\partial t} = \sigma_a \left(\phi - acT^4\right) + S_T$$

Solving for the time derivatives:

$$\frac{\partial I}{\partial t} = c \left[\frac{\sigma_s}{4\pi} \phi + \frac{\sigma_a}{4\pi} acT^4 - \mu \frac{\partial I}{\partial x} - \sigma_t I + S_I \right]$$
$$\frac{\partial T}{\partial t} = \frac{1}{C_v} \left[\sigma_a \left(\phi - acT^4 \right) + S_T \right]$$

Before going any further, we spatially discretize our equations, expanding in an arbitrary order Lagrangian basis. First, transforming to a generic reference element:

$$x = x_{i} + \frac{\Delta x_{i}}{2} s$$

$$s \in [-1, 1]$$

$$\Delta x_{i} = x_{i+1/2} - x_{i-1/2}$$

$$x_{i} = \frac{x_{i+1/2} + x_{i-1/2}}{2}$$

For generality, let \widetilde{x} and \widetilde{y} be unknowns represented using our finite element representation:

$$\widetilde{x}(s) = \vec{B}(s) \cdot \vec{x} = B_1(s)x_1 + B_2x_2 + \dots + B_Nx_{N_P}$$

where

$$\vec{B} = \left[\begin{array}{c} B_1 \\ B_2 \\ \vdots \\ B_N \end{array} \right],$$

$$B_i(s) = \prod_{\substack{k=1\\k\neq j}}^{N_P} \frac{s_k - s}{s_k - s_i},$$

and $N_P = P + 1$ where P is the DFEM trial space degree. Further suppose we wish to take integrals of the form:

$$\int_{-1}^{1} \vec{B} \psi ds$$

we represent this result as

$$\mathbf{M}\vec{\psi}$$

where

$$\mathbf{M}_{ij} = \frac{\Delta x_c}{2} \int_{-1}^{1} B_i(s) B_j(s) ds \approx \frac{\Delta x_i}{2} \sum_{q=1}^{N_q} w_q B_i(s_q) B_j(s_q),$$

 $\{s_q,q_q\}_{q=1}^{N_q}$ is a quadrature set, and

$$\psi \approx \widetilde{\psi} = \sum_{j=1}^{N_P} B_j(s) \psi_j$$
.

If we want to calculate the integral:

$$\int_{-1}^{1} \vec{B} \widetilde{\psi}(s) \sigma(s) ds$$

we denote the result as:

$$\mathbf{R}_{\sigma}\vec{\psi}$$
,

where

$$\mathbf{R}_{\sigma,ij} = \frac{\Delta x_c}{2} \int_{-1}^{1} \sigma(s) B_i(s) B_j(s) ds \approx \frac{\Delta x_c}{2} \sum_{q=1}^{N_q} w_q B_i(s_q) B_j(s_q) \sigma(s_q).$$

Our fundamental unknowns will be expressed as:

$$I(s) = \vec{B}(s) \cdot \vec{I}$$

 $T(s) = \vec{B}(s) \cdot \vec{T}$.

The Planck function, $\widehat{B}(T)$ will be similarly expanded:

$$\widehat{B}(s) \approx \vec{B}(s) \cdot \vec{\widehat{B}}$$

where for the grey case:

$$\vec{\hat{B}} = \frac{1}{4\pi} \begin{bmatrix} acT_1^4 \\ \vdots \\ acT_j^4 \\ \vdots \\ acT_N^4 \end{bmatrix}$$

Since the Planck function is a highly nonlinear function of T, we elect to linearize it about an arbitrary temperature, T^* :

$$\widehat{B}(T) \approx \widehat{B}(T^*) + \frac{\partial}{\partial T} \left[\widehat{B}(T^*) \right] (T - T^*)$$

Expressing in vector/matrix form:

$$\vec{\hat{B}} \approx \vec{\hat{B}}^* + \hat{\mathbf{D}}^* \left(\vec{T} - \vec{T}^* \right) \tag{3}$$

where: $\widehat{\mathbf{D}}^*$ is a $N \times N$ diagonal matrix with non zero elements, d_{jj} :

$$d_{jj} = \frac{\partial \widehat{B}(T_j^*)}{\partial T}$$

Driving/manufactured solution sources are likely not to be polynomials, so we define the following source moments rather than expand S_I or S_T in the DFEM trial space:

$$\vec{S}_{I,j} = \int_{-1}^{1} B_{j} S_{I}(s) ds$$

 $\vec{S}_{T,j} = \int_{-1}^{1} B_{j} S_{T}(s) ds$.

Having defined all this notation, we give the spatially discretized equations for cell i:

$$\frac{\partial}{\partial t} \left[\mathbf{M} \vec{I} \right] = c \left[\frac{1}{4\pi} \mathbf{R}_{\sigma_s} \vec{\phi} + \mathbf{R}_{\sigma_a} \left(\vec{B}^* + \widehat{\mathbf{D}}^* \left(\vec{T} - \vec{T}^* \right) \right) - \mathbf{R}_{\sigma_t} \vec{I} - \mathbf{L} \vec{I} + \vec{f} I_{in} + \vec{S}_I \right]$$
(4)

$$\frac{\partial}{\partial t} \left[\mathbf{R}_{C_v^*} \vec{T} \right] = \mathbf{R}_{\sigma_a} \left[\vec{\phi} - 4\pi \vec{B}^* - 4\pi \mathbf{D}^* \left(\vec{T} - \vec{T}^* \right) \right] + \vec{S}_T \tag{5}$$

Solving for k_I and k_T we have:

$$k_{I} = c\mathbf{M}^{-1} \left[\frac{1}{4\pi} \mathbf{R}_{\sigma_{s}} \vec{\phi} + \mathbf{R}_{\sigma_{a}} \left(\vec{B}^{*} + \widehat{\mathbf{D}}^{*} \left(\vec{T} - \vec{T}^{*} \right) \right) - \mathbf{R}_{\sigma_{t}} \vec{I} - \mathbf{L} \vec{I} + \vec{f} I_{in} + \vec{S}_{I} \right]$$
(6)

$$k_T = \mathbf{R}_{C_v}^{-1} \left[\mathbf{R}_{\sigma_a} \left(\vec{\phi} - 4\pi \vec{B}^* - 4\pi \mathbf{D}^* \left(\vec{T} - \vec{T}^* \right) \right) + \vec{S}_T \right]$$
 (7)

2.1 First RK step

We now look at Eq. (2) for step 1 of an arbitrary, diagonally implicit RK scheme:

$$\vec{I}_{1} = \vec{I}_{n} + c\Delta t a_{11} \mathbf{M}^{-1} \left[\frac{1}{4\pi} \mathbf{R}_{\sigma_{s},*} \vec{\phi}_{1} + \mathbf{R}_{\sigma_{a},*} \left(\vec{B}^{*} + \widehat{\mathbf{D}}^{*} \left(\vec{T}_{1} - \vec{T}^{*} \right) \right) - \mathbf{R}_{\sigma_{t},*} \vec{I}_{1} - \widehat{\mathbf{L}} \vec{I}_{1} + \vec{f} I_{in,1} + \vec{S}_{I} \right]$$

$$(8)$$

$$\vec{T}_{1} = \vec{T}_{n} + \Delta t a_{11} \mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a}} \left(\vec{\phi}_{1} - 4\pi \vec{B}^{*} - 4\pi \mathbf{D}^{*} \left(\vec{T}_{1} - \vec{T}^{*} \right) \right) + \vec{S}_{T} \right]$$
(9)

We now use Eq. (9) to eliminate the unknown temperature, \vec{T}_1 from Eq. (8). Solving Eq. (9) for \vec{T}_1 :

$$\vec{T}_{1} + 4\pi \Delta t a_{11} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}} \mathbf{D}^{*} \vec{T}_{1} = \vec{T}_{n} + \Delta t a_{11} \mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a}*} \left(\vec{\phi}_{1} - 4\pi \vec{B}^{*} + 4\pi \mathbf{D}^{*} \vec{T}^{*} \right) + \vec{S}_{T} \right]$$

$$\vec{T}_{1} = \left[\mathbf{I} + 4\pi\Delta t a_{11}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a}}\mathbf{D}^{*}\right]^{-1} \left[\vec{T}_{n} + \Delta t a_{11}\mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a}} \left(\vec{\phi}_{1} - 4\pi\vec{B}^{*} + 4\pi\mathbf{D}^{*}\vec{T}^{*}\right) + \vec{S}_{T}\right]\right] \dots + \left[\mathbf{I} + 4\pi\Delta t a_{11}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a}}\mathbf{D}^{*}\right]^{-1} \left[\vec{T}^{*} - \vec{T}^{*}\right]$$

$$\vec{T}_{1} = \left[\mathbf{I} + 4\pi\Delta t a_{11}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a}}\mathbf{D}^{*}\right]^{-1} \left[\vec{T}_{n} + \Delta t a_{11}\mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a}*}\left(\vec{\phi}_{1} - 4\pi\vec{B}^{*}\right) + \vec{S}_{T}\right]\right] \dots$$

$$+ \left[\mathbf{I} + 4\pi\Delta t a_{11}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a}}\mathbf{D}^{*}\right]^{-1} \left[\mathbf{I} + 4\pi\Delta t a_{11}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a}}\mathbf{D}^{*}\right] \vec{T}^{*} \dots$$

$$- \left[\mathbf{I} + 4\pi\Delta t a_{11}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a}}\mathbf{D}^{*}\right]^{-1} \vec{T}^{*}$$

The "Temperature Update" for the first RK stage is the following:

$$\vec{T}_{1} = \vec{T}^{*} + \left[\mathbf{I} + 4\pi \Delta t a_{11} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}} \mathbf{D}^{*} \right]^{-1} \left[\vec{T}_{n} - \vec{T}^{*} + \Delta t a_{11} \mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a}*} \left(\vec{\phi}_{1} - 4\pi \vec{B}^{*} \right) + \vec{S}_{T} \right] \right]$$
(10)

Inserting Eq. (10) into Eq. (8):

$$\vec{I}_{1} = \vec{I}_{n} + c\Delta t a_{11} \mathbf{M}^{-1} \left[\frac{1}{4\pi} \mathbf{R}_{\sigma_{s},*} \vec{\phi}_{1} + \mathbf{R}_{\sigma_{a},*} \vec{B}^{*} - \mathbf{R}_{\sigma_{t},*} \vec{I}_{1} - \mathbf{L} \vec{I}_{1} + \vec{f} I_{in,1} + \vec{S}_{I} \right] \dots$$

$$+ c\Delta t a_{11} \mathbf{M}^{-1} \mathbf{R}_{\sigma_{a},*} \widehat{\mathbf{D}}^{*} \left[\mathbf{I} + 4\pi \Delta t a_{11} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}} \mathbf{D}^{*} \right]^{-1} \left[\vec{T}_{n} - \vec{T}^{*} + \Delta t a_{11} \mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a},*} \left(\vec{\phi}_{1} - 4\pi \vec{B}^{*} \right) + \vec{S}_{T} \right] \right]$$

Multiply by $\frac{1}{c\Delta t a_{11}} \mathbf{M}$

$$\frac{1}{c\Delta t a_{11}} \mathbf{M} \vec{I}_{1} = \frac{1}{c\Delta t a_{11}} \mathbf{M} \vec{I}_{n} + \left[\frac{1}{4\pi} \mathbf{R}_{\sigma_{s},*} \vec{\phi}_{1} + \mathbf{R}_{\sigma_{a},*} \vec{B}^{*} - \mathbf{R}_{\sigma_{t},*} \vec{I}_{1} - \mathbf{L} \vec{I}_{1} + \vec{f} I_{in,1} + \vec{S}_{I} \right] \dots \\
+ \mathbf{R}_{\sigma_{a},*} \widehat{\mathbf{D}}^{*} \left[\mathbf{I} + 4\pi \Delta t a_{11} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}*} \mathbf{D}^{*} \right]^{-1} \left[\vec{T}_{n} - \vec{T}^{*} + \Delta t a_{11} \mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a}*} \left(\vec{\phi}_{1} - 4\pi \vec{B}^{*} \right) + \vec{S}_{T} \right] \right] .$$

Move some terms over to the LHS:

$$\mathbf{L}\vec{I}_{1} + \left(\frac{1}{c\Delta t a_{11}}\mathbf{M} + \mathbf{R}_{\sigma_{t},*}\right)\vec{I}_{1} = \frac{1}{c\Delta t a_{11}}\mathbf{M}\vec{I}_{n} + \frac{1}{4\pi}\mathbf{R}_{\sigma_{s},*}\vec{\phi}_{1} + \mathbf{R}_{\sigma_{a},*}\vec{B}^{*} + \vec{f}I_{in,1} + \vec{S}_{I} \dots + \mathbf{R}_{\sigma_{a},*}\hat{\mathbf{D}}^{*}\left[\mathbf{I} + 4\pi\Delta t a_{11}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a}*}\mathbf{D}^{*}\right]^{-1}\left[\vec{T}_{n} - \vec{T}^{*} + \Delta t a_{11}\mathbf{R}_{C_{v}}^{-1}\left[\mathbf{R}_{\sigma_{a}*}\left(\vec{\phi}_{1} - 4\pi\vec{B}^{*}\right) + \vec{S}_{T}\right]\right]$$

Further manipulating to pull all of the $\vec{\phi}_1$ terms together:

$$\mathbf{L}\vec{I}_{1} + \left(\frac{1}{c\Delta t a_{11}}\mathbf{M} + \mathbf{R}_{\sigma_{t},*}\right)\vec{I}_{1} = \dots$$

$$\frac{1}{4\pi}\mathbf{R}_{\sigma_{s},*}\vec{\phi}_{1} + \Delta t a_{11}\mathbf{R}_{\sigma_{a},*}\widehat{\mathbf{D}}^{*}\left[\mathbf{I} + 4\pi\Delta t a_{11}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a}*}\mathbf{D}^{*}\right]^{-1}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a}*}\vec{\phi}_{1}\dots$$

$$+ \frac{1}{c\Delta t a_{11}}\mathbf{M}\vec{I}_{n} + \mathbf{R}_{\sigma_{a},*}\vec{B}^{*} + \vec{f}I_{in,1}\vec{S}_{I}\dots$$

$$+ \mathbf{R}_{\sigma_{a},*}\widehat{\mathbf{D}}^{*}\left[\mathbf{I} + 4\pi\Delta t a_{11}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a}*}\mathbf{D}^{*}\right]^{-1}\left[\vec{T}_{n} - \vec{T}^{*} + \Delta t a_{11}\mathbf{R}_{C_{v}}^{-1}\left[\vec{S}_{T} - 4\pi\mathbf{R}_{\sigma_{a}*}\vec{B}^{*}\right]\right] \quad (11)$$

Though it does not look that familiar, Eq. (11) can be made to resemble the canonical monoenergetic neutron fission equation. Let us define the following terms:

$$\bar{\bar{\nu}} = 4\pi \Delta t a_{11} \mathbf{R}_{\sigma_a,*} \hat{\mathbf{D}}^* \left[\mathbf{I} + 4\pi \Delta t a_{11} \mathbf{R}_{C_v}^{-1} \mathbf{R}_{\sigma_a,*} \mathbf{D}^* \right]^{-1} \mathbf{R}_{C_v}^{-1}$$
(12a)

$$\bar{\xi}_{d} = \frac{1}{c\Delta t a_{11}} \mathbf{M} \vec{I}_{n} + \mathbf{R}_{\sigma_{a},*} \vec{B}^{*} + \vec{S}_{I} \dots
+ \mathbf{R}_{\sigma_{a},*} \hat{\mathbf{D}}^{*} \left[\mathbf{I} + 4\pi \Delta t a_{11} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}*} \mathbf{D}^{*} \right]^{-1} \left[\vec{T}_{n} - \vec{T}^{*} + \Delta t a_{11} \mathbf{R}_{C_{v}}^{-1} \left[\vec{S}_{T} - 4\pi \mathbf{R}_{\sigma_{a}} \vec{B}^{*} \right] \right]$$
(12b)

$$\bar{\bar{\mathbf{R}}}_{\sigma_t} = \frac{1}{c\Delta t a_{11}} \mathbf{M} + \mathbf{R}_{\sigma_t,*} \tag{12c}$$

Inserting Eqs. (12) into Eq. (11) gives our final form:

$$\mathbf{L}\vec{I}_{1} + \bar{\bar{\mathbf{R}}}_{\sigma_{t}}\vec{I}_{1} = \frac{1}{4\pi}\mathbf{R}_{\sigma_{s},*}\vec{\phi}_{1} + \frac{1}{4\pi}\bar{\bar{\nu}}\mathbf{R}_{\sigma_{a}*}\vec{\phi}_{1} + \vec{f}I_{in,1} + \bar{\bar{\xi}}_{d}$$
(13)

Having found \vec{I}_1 by solving Eq. (13), we use Eq. (10) to find \vec{T}_1 . This is like an outre Newton iteration loop, with the update defined in Eq. (10). The following assume we have converged the outer Newton iteration loop:

$$k_{I,1} = c\mathbf{M}^{-1} \left[\frac{1}{4\pi} \mathbf{R}_{\sigma_s,1} \vec{\phi}_1 + \mathbf{R}_{\sigma_a,1} \hat{\mathbf{B}}_1 - \mathbf{R}_{\sigma_t,1} \vec{I}_1 - \mathbf{L} \vec{I}_1 + \vec{f} I_{in,1} + \vec{S}_I \right]$$
$$k_{T,1} = \mathbf{R}_{C_v}^{-1} \left[\mathbf{R}_{\sigma_a} \left(\vec{\phi}_1 - 4\pi \hat{\mathbf{B}}_1 \right) + \vec{S}_T \right]$$

2.2 i-th RK step

Moving on to the *i*-th RK step, we first write the equation for \vec{I}_i and \vec{T}_i :

$$\vec{I}_{i} = \vec{I}_{n} + \Delta t \sum_{j=1}^{i-1} a_{ij} k_{I,j} + \Delta t a_{ii} c \mathbf{M}^{-1} \left[\frac{1}{4\pi} \mathbf{R}_{\sigma_{s},*} \vec{\phi}_{i} + \mathbf{R}_{\sigma_{a},*} \left(\vec{B}^{*} + \widehat{\mathbf{D}}^{*} \left(\vec{T}_{i} - \vec{T}^{*} \right) \right) - \mathbf{R}_{\sigma_{t},*} \vec{I}_{i} - \mathbf{L} \vec{I}_{i} + \vec{f} I_{in,i} + \vec{S}_{I} \right]$$

$$(14)$$

$$\vec{T}_{i} = \vec{T}_{n} + \Delta t \sum_{i=1}^{i-1} a_{ij} k_{T,j} + \Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a}*} \left(\vec{\phi}_{i} - 4\pi \vec{B}^{*} - 4\pi \mathbf{D}^{*} \left(\vec{T}_{i} - \vec{T}^{*} \right) \right) + \vec{S}_{T} \right]$$
(15)

Proceeding in a similar fashion as before, we solve Eq. (15) for \vec{T}_i .

$$\vec{T}_{i} + 4\pi \Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}*} \mathbf{D}^{*} \vec{T}_{i} = \vec{T}_{n} + \Delta t \sum_{j=1}^{i-1} a_{ij} k_{T,j} + \Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a}*} \left(\vec{\phi}_{i} - 4\pi \vec{B}^{*} + 4\pi \mathbf{D}^{*} \vec{T}^{*} \right) + \vec{S}_{T} \right]$$

$$\left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_v}^{-1} \mathbf{R}_{\sigma_a} \mathbf{D}^*\right] \vec{T}_i = \vec{T}_n + \Delta t \sum_{i=1}^{i-1} a_{ij} k_{T,j} + \Delta t a_{ii} \mathbf{R}_{C_v}^{-1} \left[\mathbf{R}_{\sigma_a *} \left(\vec{\phi}_i - 4\pi \vec{B}^* + 4\pi \mathbf{D}^* \vec{T}^*\right) + \vec{S}_T\right]$$

$$\vec{T}_{i} = \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}*} \mathbf{D}^{*}\right]^{-1} \left[\vec{T}_{n} + \Delta t \sum_{j=1}^{i-1} a_{ij} k_{T,j}\right] \dots$$

$$+ \Delta t a_{ii} \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}*} \mathbf{D}^{*}\right]^{-1} \mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a}*} \left(\vec{\phi}_{i} - 4\pi\vec{B}^{*} + 4\pi\mathbf{D}^{*}\vec{T}^{*}\right) + \vec{S}_{T}\right]$$

$$\vec{T}_{i} = \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a*}} \mathbf{D}^{*}\right]^{-1} \left[\vec{T}_{n} + \Delta t \sum_{j=1}^{i-1} a_{ij} k_{T,j}\right] \dots$$

$$+ \Delta t a_{ii} \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a*}} \mathbf{D}^{*}\right]^{-1} \mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a*}} \left(\vec{\phi}_{i} - 4\pi\vec{B}^{*}\right) + \vec{S}_{T}\right] \dots$$

$$+ 4\pi\Delta t a_{ii} \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a*}} \mathbf{D}^{*}\right]^{-1} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a*}} \mathbf{D}^{*} \vec{T}^{*}$$

Adding nothing:

$$\vec{T}_{i} = \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}*} \mathbf{D}^{*}\right]^{-1} \left[\vec{T}_{n} + \Delta t \sum_{j=1}^{i-1} a_{ij} k_{T,j}\right] \dots$$

$$+ \Delta t a_{ii} \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}*} \mathbf{D}^{*}\right]^{-1} \mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a}*} \left(\vec{\phi}_{i} - 4\pi\vec{B}^{*}\right) + \vec{S}_{T}\right] \dots$$

$$+ \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}*} \mathbf{D}^{*}\right]^{-1} \left[4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}*} \mathbf{D}^{*}\vec{T}^{*}\right] \dots$$

$$+ \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}*} \mathbf{D}^{*}\right]^{-1} \left(\vec{T}^{*} - \vec{T}^{*}\right)$$

simplifying

$$\vec{T}_{i} = \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a*}} \mathbf{D}^{*}\right]^{-1} \left[\vec{T}_{n} + \Delta t \sum_{j=1}^{i-1} a_{ij} k_{T,j}\right] \dots$$

$$+ \Delta t a_{ii} \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a*}} \mathbf{D}^{*}\right]^{-1} \mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a*}} \left(\vec{\phi}_{i} - 4\pi\vec{B}^{*}\right) + \vec{S}_{T}\right] \dots$$

$$+ \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a*}} \mathbf{D}^{*}\right]^{-1} \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a*}} \mathbf{D}^{*}\right] \vec{T}^{*} \dots$$

$$- \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a*}} \mathbf{D}^{*}\right]^{-1} \vec{T}^{*}$$

$$\vec{T}_{i} = \vec{T}^{*} + \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}*} \mathbf{D}^{*}\right]^{-1} \left[\vec{T}_{n} - \vec{T}^{*} + \Delta t \sum_{j=1}^{i-1} a_{ij} k_{T,j}\right] \dots$$

$$+ \Delta t a_{ii} \left[\mathbf{I} + 4\pi\Delta t a_{ii} \mathbf{R}_{C_{v}}^{-1} \mathbf{R}_{\sigma_{a}*} \mathbf{D}^{*}\right]^{-1} \mathbf{R}_{C_{v}}^{-1} \left[\mathbf{R}_{\sigma_{a}*} \left(\vec{\phi}_{i} - 4\pi\vec{B}^{*}\right) + \vec{S}_{T}\right]$$
(16)

Multiplying Eq. (14) by $\frac{1}{c\Delta t a_{ii}}\mathbf{M}$:

$$\frac{1}{c\Delta t a_{ii}} \mathbf{M} \vec{I}_{i} = \frac{1}{c\Delta t a_{ii}} \mathbf{M} \vec{I}_{n} + \frac{1}{ca_{ii}} \mathbf{M} \sum_{j=1}^{i-1} a_{ij} k_{I,j} \dots
+ \frac{1}{4\pi} \widehat{\mathbf{M}}_{\sigma_{s,*}} \vec{\phi}_{i} + \widehat{\mathbf{M}}_{\sigma_{a,*}} \left(\vec{B}^{*} + \widehat{\mathbf{D}}^{*} \left(\vec{T}_{i} - \vec{T}^{*} \right) \right) - \widehat{\mathbf{M}}_{\sigma_{t,*}} \vec{I}_{i} - \widehat{\mathbf{L}} \vec{I}_{i} + \vec{S}_{I} \quad (17)$$

Inserting Eq. (16) into Eq. (17):

$$\widehat{\mathbf{L}}\vec{I}_{i} + \left(\frac{1}{c\Delta t a_{ii}}\mathbf{M} + \mathbf{R}_{\sigma_{t},*}\right)\vec{I}_{i} = \frac{1}{c\Delta t a_{ii}}\mathbf{M}\vec{I}_{n} + \frac{1}{ca_{ii}}\mathbf{M}\sum_{j=1}^{i-1}a_{ij}k_{I,j} + \frac{1}{4\pi}\mathbf{R}_{\sigma_{s},*}\vec{\phi}_{i} + \mathbf{R}_{\sigma_{a},*}\vec{B}^{*} \dots
+ \mathbf{R}_{\sigma_{a},*}\widehat{\mathbf{D}}^{*}\left\{\left[\mathbf{I} + 4\pi\Delta t a_{ii}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a}*}\mathbf{D}^{*}\right]^{-1}\left[\vec{T}_{n} - \vec{T}^{*} + \Delta t\sum_{j=1}^{i-1}a_{ij}k_{T,j}\right]\dots
+ \Delta t a_{ii}\left[\mathbf{I} + 4\pi\Delta t a_{ii}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a}*}\mathbf{D}^{*}\right]^{-1}\mathbf{R}_{C_{v}}^{-1}\left[\mathbf{R}_{\sigma_{a}*}\left(\vec{\phi}_{i} - 4\pi\vec{B}^{*}\right) + \vec{S}_{T}\right]\right\}$$

Re-arranging to isolate $\vec{\phi}_i$:

$$\widehat{\mathbf{L}}\vec{I}_{i} + \left(\frac{1}{c\Delta t a_{ii}}\mathbf{M} + \mathbf{R}_{\sigma_{t},*}\right)\vec{I}_{i} = \frac{1}{4\pi}\mathbf{R}_{\sigma_{s},*}\vec{\phi}_{i}\dots$$

$$+ \Delta t a_{ii}\widehat{\mathbf{M}}_{\sigma_{a},*}\widehat{\mathbf{D}}^{*} \left[\mathbf{I} + 4\pi\Delta t a_{ii}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a},*}\mathbf{D}^{*}\right]^{-1}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a},*}\vec{\phi}_{i}\dots$$

$$+ \frac{1}{c\Delta t a_{ii}}\mathbf{M}\vec{I}_{n} + \frac{1}{ca_{ii}}\mathbf{M}\sum_{j=1}^{i-1}a_{ij}k_{I,j} + \mathbf{R}_{\sigma_{a},*}\vec{B}^{*}\dots$$

$$+ \widehat{\mathbf{M}}_{\sigma_{a},*}\widehat{\mathbf{D}}^{*} \left[\mathbf{I} + 4\pi\Delta t a_{ii}\mathbf{R}_{C_{v}}^{-1}\mathbf{R}_{\sigma_{a},*}\widehat{\mathbf{D}}^{*}\right]^{-1} \left[\vec{T}_{n} - \vec{T}^{*} + \Delta t\sum_{j=1}^{i-1}a_{ij}k_{T,j} + \Delta t a_{ii}\mathbf{R}_{C_{v}}^{-1}\left[\vec{S}_{T} - 4\pi\mathbf{R}_{\sigma_{a},*}\mathbf{B}^{*}\right]\right]$$

$$(18)$$

Make the following definitions:

$$\bar{\bar{\xi}}_{i,d} = \frac{1}{c\Delta t a_{ii}} \mathbf{M} \vec{I}_n + \frac{1}{c a_{ii}} \mathbf{M} \sum_{j=1}^{i-1} a_{ij} k_{I,j} + \widehat{\mathbf{M}}_{\sigma_a,*} \vec{B}^* \dots$$

$$+ \mathbf{R}_{\sigma_a,*} \widehat{\mathbf{D}}^* \left[\mathbf{I} + 4\pi \Delta t a_{ii} \mathbf{R}_{C_v}^{-1} \mathbf{R}_{\sigma_a,*} \widehat{\mathbf{D}}^* \right]^{-1} \left[\vec{T}_n - \vec{T}^* + \Delta t \sum_{j=1}^{i-1} a_{ij} k_{T,j} + \Delta t a_{ii} \mathbf{R}_{C_v}^{-1} \left[\vec{S}_T - 4\pi \mathbf{R}_{\sigma_a,*} \mathbf{B}^* \right] \right]$$
(19a)

$$\bar{\bar{\nu}}_i = 4\pi \Delta t a_{ii} \widehat{\mathbf{M}}_{\sigma_a,*} \widehat{\mathbf{D}}^* \left[\mathbf{I} + 4\pi \Delta t a_{ii} \mathbf{R}_{C_n}^{-1} \mathbf{R}_{\sigma_a,*} \mathbf{D}^* \right]^{-1} \mathbf{R}_{C_n}^{-1}$$
(19b)

$$\bar{\bar{\mathbf{M}}}_{\sigma_t,i} = \mathbf{M}_{\sigma_t,*} + \frac{1}{c\Delta t a_{ii}} \mathbf{M}$$
 (19c)

This then gives us our final equation for the radiation intensity:

$$\widehat{\mathbf{L}}\vec{I}_i + \bar{\bar{\mathbf{M}}}_{\sigma_t,i}\vec{I}_i = \frac{1}{4\pi}\mathbf{M}_{\sigma_s,*}\vec{\phi}_i + \frac{1}{4\pi}\bar{\bar{\nu}}_i\widehat{\mathbf{M}}_{\sigma_a*}\vec{\phi}_i + \bar{\bar{\xi}}_{i,d}$$
(20)

Having found \vec{I} for the *i*-th RK time step, we solve for $\vec{T_i}$ using Eq. (16). At this point, we again have the option to either iterate on $\vec{T_i}$, or we only solve for $\vec{T_i}$ once. Regardless of whether we iterate for $\vec{T_i}$ or not, we evaluate all material properties at the final value of $\vec{T_i}$, and apply the definitions of $k_{T,i}$ and $k_{I,i}$:

$$k_{I,i} = c\mathbf{M}^{-1} \left[\frac{1}{4\pi} \widehat{\mathbf{M}}_{\sigma_s,i} \vec{\phi}_i + \widehat{\mathbf{M}}_{\sigma_a,i} \widehat{\mathbf{B}}_i - \widehat{\mathbf{M}}_{\sigma_t} \vec{I}_i - \widehat{\mathbf{L}} \vec{I}_i + \vec{S}_I \right]$$
(21)

$$k_{T,i} = \mathbf{R}_{C_v}^{-1} \left[\mathbf{R}_{\sigma_a,i} \left(\vec{\phi}_i - 4\pi \hat{\mathbf{B}}_i \right) + \vec{S}_T \right]$$
 (22)

After completing all steps of the particular RK scheme, we advance $\vec{I}_n \to \vec{I}_{n+1}$ and $\vec{T}_n \to \vec{T}_{n+1}$:

$$\vec{I}_{n+1} = \vec{I}_n + \Delta t \sum_{i=1}^{s} b_i k_{I,i}$$

 $\vec{T}_{n+1} = \vec{T}_n + \Delta t \sum_{i=1}^{s} b_i k_{T,i}$

3 Multigroup Case

We previously considered the grey case, now we consider the spectrum of photon energies. We discretize the energy variable using the multigroup method. The multigroup method assumes a finite number of groups, G. Ideally, we would have:

$$I_g = \int_{E_{min}}^{E_{max}} I(E)dE$$

$$I_g \sigma_g = \int_{E_{min}}^{E_{max}} I(E)\sigma(E)dE$$

$$\int_0^\infty \sigma(E)I(E)dE = \sum_{g=1}^G \sigma_g I_g$$

where E_{min} and E_{max} are the minimum and maximum photon energy of each group, g. In practice though we are solving equations of the form:

$$\frac{1}{c}\frac{\partial I_g}{\partial t} + \mu \frac{\partial I_g}{\partial x} + \sigma_{t,g} I_g = \frac{\sigma_{s,g}}{4\pi} \phi_g + \sigma_{a,g} \widehat{B}_g$$
 (23)

$$C_v \frac{\partial T}{\partial t} = \sum_{g=1}^{G} \sigma_{a,g} \left(\phi_g - 4\pi \hat{B}_g \right)$$
 (24)

where the σ_g and C_v are evaluated a priori. Adjusting our Planck function expansion for multigroup use, we define:

$$\widehat{\mathbf{B}}_g = \int_{E_{min,g}}^{E_{max,g}} \widehat{B}(E,T) dE$$

and \mathbf{D}_{g}^{*} is a diagonal matrix with non-zero main diagonal elements $d_{i}i$:

$$d_{ii} = \int_{E_{min,g}}^{E_{max,g}} \frac{\partial \widehat{B}(E,T)}{\partial T} dE$$

giving our familiar linearization:

$$\mathbf{\widehat{B}}_{g}pprox\widehat{\mathbf{B}}_{g}^{st}+\widehat{\mathbf{D}}_{g}^{st}\left(ec{T}-ec{T}^{st}
ight)$$

with this notation, our spatially discretized, temporally analytic equations are:

$$\frac{1}{c}\frac{\partial}{\partial t}\mathbf{M}\vec{I}_{d,g} + \widehat{\mathbf{L}}\vec{I}_{d,g} + \mathbf{R}_{\sigma_{t,g}^*}\vec{I}_{d,g} = \frac{1}{4\pi}\mathbf{R}_{\sigma_{s,g}^*}\vec{\phi} + \mathbf{R}_{\sigma_{a,g}^*}\left[\widehat{\mathbf{B}}_g^* + \widehat{\mathbf{D}}_g^*\left(\vec{T} - \vec{T}^*\right)\right] + \vec{S}_{I,g}$$
(25)

$$\frac{\partial}{\partial t} \left[\mathbf{R}_{C_v^*} \vec{T} \right] = \sum_{g=1}^G \mathbf{R}_{\sigma_{a,g}^*} \left\{ \vec{\phi}_g - 4\pi \left[\widehat{\mathbf{B}}_g^* + \widehat{\mathbf{D}}_g^* \left(\vec{T} - \vec{T}^* \right) \right] \right\} + \vec{S}_T$$
 (26)

solving for $k_{I,g}$ and k_T we have:

$$k_{I,g} = c\mathbf{M}^{-1} \left[\frac{1}{4\pi} \mathbf{R}_{\sigma_{s,g}^*} \vec{\phi}_g + \mathbf{R}_{\sigma_{a,g}^*} \left[\widehat{\mathbf{B}}_g^* + \widehat{\mathbf{D}}_g^* \left(\vec{T} - \vec{T}^* \right) \right] - \widehat{\mathbf{L}} \vec{I}_{d,g} - \mathbf{R}_{\sigma_{t,g}^*} \vec{I}_{d,g} \right]$$
(27)

$$k_T = \mathbf{R}_{C_v^*}^{-1} \left[\sum_{g=1}^G \mathbf{R}_{\sigma_{a,g}^*} \left\{ \vec{\phi}_g - 4\pi \left[\widehat{\mathbf{B}}_g^* + \widehat{\mathbf{D}}_g^* \left(\vec{T} - \vec{T}^* \right) \right] \right\} \right]$$
 (28)