

## TWIP Measurements

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description	variable	value	units
length of track	$d$	0.161	m
length to COG	$l$	0.047	m
radius of a wheel	$r$	0.04	m
mass of platform	$M$	1.22	kg
mass of a wheel	$M_w$	[0.02, 0.021]	kg
mass of the pendulum	$m$	0	kg
moment of inertia of a wheel	$I_w$	[32e-6, 33.6e-6]	kg-m <sup>2</sup>
moment of inertia of the platform and pendulum about z-axis	$I_p$	[2.601e-3, 4.002e-3]	kg-m <sup>2</sup>
moment of inertia of platform about y-axis	$I_m$	[1.776e-3, 2.056e-3]	kg-m <sup>2</sup>
moment of inertia of motor output shaft	$J$	?	kg-m <sup>2</sup>
electromotive force constant	$K_e$	0.1893	V/rad/sec
motor torque constant	$K_t$	0.0993	N-m/A
motor friction	$b$	?	
motor resistance	$R$	11.1	$\Omega$
motor inductance	$L$	15.38e-3	H
motor deadzone	$d$	0.2	V

## Notes

- Mass of each battery  $\in [0.164 \text{ kg}, 0.165 \text{ kg}]$
- Mass of all panels = 0.369 kg
- Mass of fusebox = 0.078 kg
- Moment of inertia of platform/pendulum approximated using Parallel Axis Theorem