



Universidade Federal de Pernambuco

las4s e pelados

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- 1 Contest
- 2 Mathematics
- 3 Number theory
- 4 Combinatorial
- 5 Various

Contest (1)

template.cpp14 lines

```
#include <bits/stdc++.h>
using namespace std;

#define rep(i, a, b) for(int i = a; i < (b); ++i)
#define all(x) begin(x), end(x)
#define sz(x) (int)(x).size()
typedef long long ll;
typedef pair<int, int> pii;
typedef vector<int> vi;

int main() {
    cin.tie(0)->sync_with_stdio(0);
    cin.exceptions(cin.failbit);
}
```

.bashrc2 lines

```
alias c='g++ -Wall -Wconversion -Wfatal-errors -g -std=c++17 \
-fsanitize=undefined,address'
```

hash.sh2 lines

```
# bash hash.sh file.cpp 11 12
sed -n $2', '$3' p' $1 | sed '/^#w/d' | cpp -dD -P -
fpreprocessed | tr -d '[:space:]' | md5sum |cut -c-6
```

troubleshoot.txt52 lines

```
Pre-submit:
Write a few simple test cases if sample is not enough.
Are time limits close? If so, generate max cases.
Is the memory usage fine?
Could anything overflow?
Make sure to submit the right file.
```

```
Wrong answer:
Print your solution! Print debug output, as well.
Are you clearing all data structures between test cases?
Can your algorithm handle the whole range of input?
Read the full problem statement again.
Do you handle all corner cases correctly?
Have you understood the problem correctly?
Any uninitialized variables?
Any overflows?
Confusing N and M, i and j, etc.?
Are you sure your algorithm works?
What special cases have you not thought of?
Are you sure the STL functions you use work as you think?
Add some assertions, maybe resubmit.
Create some testcases to run your algorithm on.
Go through the algorithm for a simple case.
Go through this list again.
```

1 Explain your algorithm to a teammate.
Ask the teammate to look at your code.
Go for a small walk, e.g. to the toilet.
1 Is your output format correct? (including whitespace)
Rewrite your solution from the start or let a teammate do it.
3 Runtime error:
Have you tested all corner cases locally?
Any uninitialized variables?
Are you reading or writing outside the range of any vector?
5 Any assertions that might fail?
Any possible division by 0? (mod 0 for example)
6 Any possible infinite recursion?
Invalidated pointers or iterators?
Are you using too much memory?
Debug with resubmits (e.g. remapped signals, see Various).

Time limit exceeded:
Do you have any possible infinite loops?
What is the complexity of your algorithm?
Are you copying a lot of unnecessary data? (References)
How big is the input and output? (consider scanf)
Avoid vector, map. (use arrays/unordered_map)
What do your teammates think about your algorithm?

Memory limit exceeded:
What is the max amount of memory your algorithm should need?
Are you clearing all data structures between test cases?

Mathematics (2)

2.1 Equations

$$ax^2 + bx + c = 0 \Rightarrow x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

The extremum is given by $x = -b/2a$.

$$\begin{matrix} ax + by = e \\ cx + dy = f \end{matrix} \Rightarrow \begin{matrix} x = \frac{ed - bf}{ad - bc} \\ y = \frac{af - ec}{ad - bc} \end{matrix}$$

In general, given an equation $Ax = b$, the solution to a variable x_i is given by

$$x_i = \frac{\det A'_i}{\det A}$$

where A'_i is A with the i 'th column replaced by b .

2.2 Recurrences

If $a_n = c_1a_{n-1} + \dots + c_ka_{n-k}$, and r_1, \dots, r_k are distinct roots of $x^k - c_1x^{k-1} - \dots - c_k$, there are d_1, \dots, d_k s.t.

$$a_n = d_1r_1^n + \dots + d_kr_k^n.$$

Non-distinct roots r become polynomial factors, e.g.
 $a_n = (d_1n + d_2)r^n$.

2.3 Trigonometry

$$\begin{aligned} \sin(v + w) &= \sin v \cos w + \cos v \sin w \\ \cos(v + w) &= \cos v \cos w - \sin v \sin w \end{aligned}$$

$$\begin{aligned} \tan(v + w) &= \frac{\tan v + \tan w}{1 - \tan v \tan w} \\ \sin v + \sin w &= 2 \sin \frac{v + w}{2} \cos \frac{v - w}{2} \\ \cos v + \cos w &= 2 \cos \frac{v + w}{2} \cos \frac{v - w}{2} \end{aligned}$$

$$(V + W) \tan(v - w)/2 = (V - W) \tan(v + w)/2$$

where V, W are lengths of sides opposite angles v, w .

$$\begin{aligned} a \cos x + b \sin x &= r \cos(x - \phi) \\ a \sin x + b \cos x &= r \sin(x + \phi) \end{aligned}$$

where $r = \sqrt{a^2 + b^2}, \phi = \text{atan2}(b, a)$.

2.4 Geometry

2.4.1 Triangles

Side lengths: a, b, c

Semiperimeter: $p = \frac{a + b + c}{2}$

Area: $A = \sqrt{p(p - a)(p - b)(p - c)}$

Circumradius: $R = \frac{abc}{4A}$

Inradius: $r = \frac{A}{p}$

Length of median (divides triangle into two equal-area triangles):
 $m_a = \frac{1}{2}\sqrt{2b^2 + 2c^2 - a^2}$

Length of bisector (divides angles in two):

$$s_a = \sqrt{bc \left[1 - \left(\frac{a}{b + c} \right)^2 \right]}$$

Law of sines: $\frac{\sin \alpha}{a} = \frac{\sin \beta}{b} = \frac{\sin \gamma}{c} = \frac{1}{2R}$

Law of cosines: $a^2 = b^2 + c^2 - 2bc \cos \alpha$

Law of tangents: $\frac{a + b}{a - b} = \frac{\tan \frac{\alpha + \beta}{2}}{\tan \frac{\alpha - \beta}{2}}$

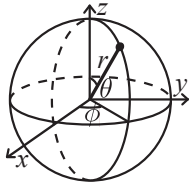
2.4.2 Quadrilaterals

With side lengths a, b, c, d , diagonals e, f , diagonals angle θ , area A and magic flux $F = b^2 + d^2 - a^2 - c^2$:

$$4A = 2ef \cdot \sin \theta = F \tan \theta = \sqrt{4e^2f^2 - F^2}$$

For cyclic quadrilaterals the sum of opposite angles is 180° ,
 $ef = ac + bd$, and $A = \sqrt{(p - a)(p - b)(p - c)(p - d)}$.

2.4.3 Spherical coordinates



$$\begin{aligned} x &= r \sin \theta \cos \phi & r &= \sqrt{x^2 + y^2 + z^2} \\ y &= r \sin \theta \sin \phi & \theta &= \arccos(z / \sqrt{x^2 + y^2 + z^2}) \\ z &= r \cos \theta & \phi &= \operatorname{atan2}(y, x) \end{aligned}$$

2.4.4 Pick’s Theorem

The area of a simple polygon whose vertices have integer coordinates is:

$$A = I + \frac{B}{2} - 1$$

where I is the number of interior integer points, and B is the number of integer points in the border of the polygon.

2.4.5 Centroid of a polygon

The coordites of the centroid of a non-self-intersecting closed polygon is:

$$\frac{1}{3A} \left(\sum_{i=0}^{n-1} (x_i + x_{i+1})(x_i y_{i+1} - x_{i+1} y_i), \sum_{i=0}^{n-1} (y_i + y_{i+1})(x_i y_{i+1} - x_{i+1} y_i) \right),$$

where A is twice the signed area of the polygon.

2.4.6 Two Ears Theorem

Every simple polygon with more than 3 vertices has at least two non-overlapping ears (a ear is a vertex whose diagonal induced by its neighbors which lies strictly inside the polygon). Equivalently, every simple polygon can be triangulated.

2.5 Derivatives/Integrals

$$\begin{aligned} \frac{d}{dx} \arcsin x &= \frac{1}{\sqrt{1-x^2}} & \frac{d}{dx} \arccos x &= -\frac{1}{\sqrt{1-x^2}} \\ \frac{d}{dx} \tan x &= 1 + \tan^2 x & \frac{d}{dx} \arctan x &= \frac{1}{1+x^2} \\ \int \tan ax &= -\frac{\ln |\cos ax|}{a} & \int x \sin ax &= \frac{\sin ax - ax \cos ax}{a^2} \\ \int e^{-x^2} &= \frac{\sqrt{\pi}}{2} \operatorname{erf}(x) & \int x e^{ax} dx &= \frac{e^{ax}}{a^2} (ax - 1) \end{aligned}$$

Integration by parts:

$$\int_a^b f(x)g(x)dx = [F(x)g(x)]_a^b - \int_a^b F(x)g'(x)dx$$

2.6 Sums

$$c^a + c^{a+1} + \cdots + c^b = \frac{c^{b+1} - c^a}{c - 1}, \quad c \neq 1$$

$$\begin{aligned} 1^2 + 2^2 + \cdots + n^2 &= \frac{n(2n+1)(n+1)}{6} \\ 1^3 + 2^3 + \cdots + n^3 &= \frac{n^2(n+1)^2}{4} \\ 1^4 + 2^4 + \cdots + n^4 &= \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30} \end{aligned}$$

$$\sum_{i=0}^n ic^i = \frac{nc^{n+2} - (n+1)c^{n+1} + c}{(c-1)^2}, \quad c \neq 1$$

2.7 Series

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots, \quad (-\infty < x < \infty)$$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots, \quad (-1 < x \leq 1)$$

$$\sqrt{1+x} = 1 + \frac{x}{2} - \frac{x^2}{8} + \frac{2x^3}{32} - \frac{5x^4}{128} + \dots, \quad (-1 \leq x \leq 1)$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots, \quad (-\infty < x < \infty)$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots, \quad (-\infty < x < \infty)$$

$$\sum_{i=0}^{\infty} ic^i = \frac{c}{(1-c)^2}, \quad |c| < 1$$

2.8 Probability theory

Let X be a discrete random variable with probability $p_X(x)$ of assuming the value x . It will then have an expected value (mean) $\mu = \mathbb{E}(X) = \sum_x x p_X(x)$ and variance $\sigma^2 = V(X) = \mathbb{E}(X^2) - (\mathbb{E}(X))^2 = \sum_x (x - \mathbb{E}(X))^2 p_X(x)$ where σ is the standard deviation. If X is instead continuous it will have a probability density function $f_X(x)$ and the sums above will instead be integrals with $p_X(x)$ replaced by $f_X(x)$.

Expectation is linear:

$$\mathbb{E}(aX + bY) = a\mathbb{E}(X) + b\mathbb{E}(Y)$$

For independent X and Y ,

$$V(aX + bY) = a^2V(X) + b^2V(Y).$$

2.8.1 Discrete distributions

Binomial distribution

The number of successes in n independent yes/no experiments, each which yields success with probability p is $\operatorname{Bin}(n, p)$, $n = 1, 2, \dots$, $0 \leq p \leq 1$.

$$p(k) = \binom{n}{k} p^k (1-p)^{n-k}$$

$$\mu = np, \sigma^2 = np(1-p)$$

$\operatorname{Bin}(n, p)$ is approximately $\operatorname{Po}(np)$ for small p .

First success distribution

The number of trials needed to get the first success in independent yes/no experiments, each which yields success with probability p is $\operatorname{Fs}(p)$, $0 \leq p \leq 1$.

$$p(k) = p(1-p)^{k-1}, \quad k = 1, 2, \dots$$

$$\mu = \frac{1}{p}, \sigma^2 = \frac{1-p}{p^2}$$

Poisson distribution

The number of events occurring in a fixed period of time t if these events occur with a known average rate κ and independently of the time since the last event is $\operatorname{Po}(\lambda)$, $\lambda = t\kappa$.

$$p(k) = e^{-\lambda} \frac{\lambda^k}{k!}, \quad k = 0, 1, 2, \dots$$

$$\mu = \lambda, \sigma^2 = \lambda$$

2.8.2 Continuous distributions

Uniform distribution

If the probability density function is constant between a and b and 0 elsewhere it is $\operatorname{U}(a, b)$, $a < b$.

$$f(x) = \begin{cases} \frac{1}{b-a} & a < x < b \\ 0 & \text{otherwise} \end{cases}$$

$$\mu = \frac{a+b}{2}, \sigma^2 = \frac{(b-a)^2}{12}$$

Exponential distribution

The time between events in a Poisson process is $\operatorname{Exp}(\lambda)$, $\lambda > 0$.

$$f(x) = \begin{cases} \lambda e^{-\lambda x} & x \geq 0 \\ 0 & x < 0 \end{cases}$$

$$\mu = \frac{1}{\lambda}, \sigma^2 = \frac{1}{\lambda^2}$$

Normal distribution

Most real random values with mean μ and variance σ^2 are well described by $\mathcal{N}(\mu, \sigma^2)$, $\sigma > 0$.

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}}e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

If $X_1 \sim \mathcal{N}(\mu_1, \sigma_1^2)$ and $X_2 \sim \mathcal{N}(\mu_2, \sigma_2^2)$ then

$$aX_1 + bX_2 + c \sim \mathcal{N}(\mu_1 + \mu_2 + c, a^2\sigma_1^2 + b^2\sigma_2^2)$$

2.9 Markov chains

A *Markov chain* is a discrete random process with the property that the next state depends only on the current state. Let X_1, X_2, \dots be a sequence of random variables generated by the Markov process. Then there is a transition matrix $\mathbf{P} = (p_{ij})$, with $p_{ij} = \Pr(X_n = i | X_{n-1} = j)$, and $\mathbf{p}^{(n)} = \mathbf{P}^n \mathbf{p}^{(0)}$ is the probability distribution for X_n (i.e., $p_i^{(n)} = \Pr(X_n = i)$), where $\mathbf{p}^{(0)}$ is the initial distribution.

π is a stationary distribution if $\pi = \pi \mathbf{P}$. If the Markov chain is *irreducible* (it is possible to get to any state from any state), then $\pi_i = \frac{1}{\mathbb{E}(T_i)}$ where $\mathbb{E}(T_i)$ is the expected time between two visits in state i . π_j / π_i is the expected number of visits in state j between two visits in state i .

For a connected, undirected and non-bipartite graph, where the transition probability is uniform among all neighbors, π_i is proportional to node i 's degree.

A Markov chain is *ergodic* if the asymptotic distribution is independent of the initial distribution. A finite Markov chain is ergodic iff it is irreducible and *aperiodic* (i.e., the gcd of cycle lengths is 1). $\lim_{k \rightarrow \infty} \mathbf{P}^k = \mathbf{1P}$.

A Markov chain is an A-chain if the states can be partitioned into two sets **A** and **G**, such that all states in **A** are absorbing ($p_{ii} = 1$), and all states in **G** leads to an absorbing state in **A**. The probability for absorption in state $i \in \mathbf{A}$, when the initial state is j , is $a_{ij} = p_{ij} + \sum_{k \in \mathbf{G}} a_{ik} p_{kj}$. The expected time until absorption, when the initial state is i , is $t_i = 1 + \sum_{k \in \mathbf{G}} p_{ki} t_k$.

Number theory (3)

3.1 Modular arithmetic

ModularArithmetic.h

Description: Operators for modular arithmetic. You need to set mod to some number first and then you can use the structure.

"euclid.h"	d41d8c, 19 lines
d41	const ll mod = 17; // change to something else
d41	struct Mod {
d41	ll x;
d41	Mod(ll xx) : x(xx) {}
d41	Mod operator+(Mod b) { return Mod((x + b.x) % mod); }

d41	Mod operator-(Mod b) { return Mod((x - b.x + mod) % mod); }
d41	Mod operator*(Mod b) { return Mod((x * b.x) % mod); }
d41	Mod operator/(Mod b) { return *this * invert(b); }
d41	Mod invert(Mod a) {
d41	ll x, y, g = euclid(a.x, mod, x, y);
d41	assert(g == 1); return Mod((x + mod) % mod);
d41	}
d41	Mod operator^(ll e) {
d41	if (!e) return Mod(1);
d41	Mod r = *this ^ (e / 2); r = r * r;
d41	return e&1 ? *this * r : r;
d41	}
d41	};

ModInverse.h

Description: Pre-computation of modular inverses. Assumes LIM ≤ mod and that mod is a prime.

d41	const ll mod = 1000000007, LIM = 200000;
d41	ll* inv = new ll[LIM] - 1; inv[1] = 1;
d41	rep(i,2,LIM) inv[i] = mod - (mod / i) * inv[mod % i] % mod;

ModPow.h

d41	const ll mod = 1000000007; // faster if const
d41	ll modpow(ll b, ll e) {
d41	ll ans = 1;
d41	for (; e; b = b * b % mod, e /= 2)
d41	if (e & 1) ans = ans * b % mod;
d41	return ans;
d41	}

ModLog.h

Description: Returns the smallest $x > 0$ s.t. $a^x = b \pmod m$, or -1 if no such x exists. modLog(a,l,m) can be used to calculate the order of a .

	Time: $\mathcal{O}(\sqrt{m})$	d41d8c, 12 lines
d41	ll modLog(ll a, ll b, ll m) {	
d41	ll n = (ll) sqrt(m) + 1, e = 1, f = 1, j = 1;	
d41	unordered_map<ll, ll> A;	
d41	while (j <= n && (e = f = e * a % m) != b % m)	
d41	A[e * b % m] = j++;	
d41	if (e == b % m) return j;	
d41	if (__gcd(m, e) == __gcd(m, b))	
d41	rep(i,2,n+2) if (A.count(e = e * f % m))	
d41	return n * i - A[e];	
d41	return -1;	
d41	}	

ModSum.h

Description: Sums of mod'ed arithmetic progressions. modsum(to, c, k, m) = $\sum_{i=0}^{to-1} (ki + c) \% m$. divsum is similar but for floored division.

Time: log(m), with a large constant.

d41	typedef unsigned long long ull;
d41	ull sumsq(ull to) { return to / 2 * ((to-1) 1); }
d41	ull divsum(ull to, ull c, ull k, ull m) {
d41	ull res = k / m * sumsq(to) + c / m * to;
d41	k %= m; c %= m;
d41	if (!k) return res;
d41	ull to2 = (to * k + c) / m;
d41	return res + (to - 1) * to2 - divsum(to2, m-1 - c, m, k);
d41	}

d41	ll modsum(ull to, ll c, ll k, ll m) {
d41	c = ((c % m) + m) % m;
d41	k = ((k % m) + m) % m;
d41	return to * c + k * sumsq(to) - m * divsum(to, c, k, m);
d41	}

ModMulLL.h

Description: Calculate $a \cdot b \pmod c$ (or $a^b \pmod c$) for $0 \leq a, b \leq c \leq 7.2 \cdot 10^{18}$. **Time:** $\mathcal{O}(1)$ for modmul, $\mathcal{O}(\log b)$ for modpow

d41	typedef unsigned long long ull;
d41	ull modmul(ull a, ull b, ull M) {
d41	ll ret = a * b - M * ull(1.L / M * a * b);
d41	return ret + M * (ret < 0) - M * (ret >= (1l)M);
d41	}
d41	ull modpow(ull b, ull e, ull mod) {
d41	ull ans = 1;
d41	for (; e; b = modmul(b, b, mod), e /= 2)
d41	if (e & 1) ans = modmul(ans, b, mod);
d41	return ans;
d41	}

ModSqrt.h

Description: Tonelli-Shanks algorithm for modular square roots. Finds x s.t. $x^2 = a \pmod p$ ($-x$ gives the other solution).

Time: $\mathcal{O}(\log^2 p)$ worst case, $\mathcal{O}(\log p)$ for most p

	"ModPow.h"	d41d8c, 25 lines
d41	ll sqrt(ll a, ll p) {	
d41	a %= p; if (a < 0) a += p;	
d41	if (a == 0) return 0;	
d41	assert(modpow(a, (p-1)/2, p) == 1); // else no solution	
d41	if (p % 4 == 3) return modpow(a, (p+1)/4, p);	
	// a^(n+3)/8 or 2^(n+3)/8 * 2^(n-1)/4 works if p % 8 == 5	
d41	ll s = p - 1, n = 2;	
d41	int r = 0, m;	
d41	while (s % 2 == 0)	
d41	++r, s /= 2;	
d41	while (modpow(n, (p - 1) / 2, p) != p - 1) ++n;	
d41	ll x = modpow(a, (s + 1) / 2, p);	
d41	ll b = modpow(a, s, p), g = modpow(n, s, p);	
d41	for (;;) r = m) {	
d41	ll t = b;	
d41	for (m = 0; m < r && t != 1; ++m)	
d41	t = t * t % p;	
d41	if (m == 0) return x;	
d41	ll gs = modpow(g, 1LL << (r - m - 1), p);	
d41	g = gs * gs % p;	
d41	x = x * gs % p;	
d41	b = b * g % p;	
d41	}	
d41	}	

3.2 Primality

FastEratosthenes.h

Description: Prime sieve for generating all primes smaller than LIM. **Time:** LIM=1e9 ≈ 1.5s

d41	const int LIM = 1e6;	d41d8c, 21 lines
d41	bitset<LIM> isPrime;	
d41	vi eratosthenes() {	
d41	const int S = (int)round(sqrt(LIM)), R = LIM / 2;	
d41	vi pr = {2}, sieve(S+1); pr.reserve(int(LIM/log(LIM)*1.1)	
);	
d41	vector<pii> cp;	
d41	for (int i = 3; i <= S; i += 2) if (!sieve[i]) {	
d41	cp.push_back({i, i * i / 2});	
d41	for (int j = i * i; j <= S; j += 2 * i) sieve[j] = 1;	
d41	}	

```
d41 for (int L = 1; L <= R; L += S) {
d41     array<bool, S> block{};
d41     for (auto &p, idx] : cp)
d41         for (int i=idx; i < S+L; idx = (i+=p)) block[i-L] =
1;
d41     rep(i,0,min(S, R - L))
d41         if (!block[i]) pr.push_back((L + i) * 2 + 1);
d41 }
d41 for (int i : pr) isPrime[i] = 1;
d41 return pr;
d41 }
```

MillerRabin.h

Description: Deterministic Miller-Rabin primality test. Guaranteed to work for numbers up to $7 \cdot 10^{18}$; for larger numbers, use Python and extend A randomly.

Time: 7 times the complexity of $a^b \bmod c$.

"ModMuLL.h"	d41d8c, 13 lines
d41 bool isPrime(ull n) {	
d41 if (n < 2 n % 6 % 4 != 1) return (n 1) == 3;	
d41 ull A[] = {2, 325, 9375, 28178, 450775, 9780504,	
1795265022},	
d41 s = __builtin_ctzll(n-1), d = n >> s;	
d41 for (ull a : A) { // ^ count trailing zeroes	
d41 ull p = modpow(a%n, d, n), i = s;	
d41 while (p != 1 && p != n-1 && a % n && i--)	
d41 p = modmul(p, p, n);	
d41 if (p != n-1 && i != s) return 0;	
d41 }	
d41 return 1;	
d41 }	

Factor.h

Description: Pollard-rho randomized factorization algorithm. Returns prime factors of a number, in arbitrary order (e.g. 2299 -> {11, 19, 11}).

Time: $\mathcal{O}(n^{1/4})$, less for numbers with small factors.

"ModMuLL.h", "MillerRabin.h"	d41d8c, 19 lines
d41 ull pollard(ull n) {	
d41 ull x = 0, y = 0, t = 30, prd = 2, i = 1, q;	
d41 auto f = [&](ull x) { return modmul(x, x, n) + i; };	
d41 while (t++ % 40 __gcd(prd, n) == 1) {	
d41 if (x == y) x = ++i, y = f(x);	
d41 if ((q = modmul(prd, max(x,y) - min(x,y), n))) prd = q;	
d41 x = f(x), y = f(f(y));	
d41 }	
d41 return __gcd(prd, n);	
d41 }	
d41 vector<ull> factor(ull n) {	
d41 if (n == 1) return {};	
d41 if (isPrime(n)) return {n};	
d41 ull x = pollard(n);	
d41 auto l = factor(x), r = factor(n / x);	
d41 l.insert(l.end(), all(r));	
d41 return l;	
d41 }	

3.3 Divisibility

euclid.h

Description: Finds two integers x and y , such that $ax + by = \gcd(a, b)$. If you just need gcd, use the built in __gcd instead. If a and b are coprime, then x is the inverse of $a \pmod b$.

	d41d8c, 6 lines
d41 ll euclid(ll a, ll b, ll &x, ll &y) {	
d41 if (!b) return x = 1, y = 0, a;	
d41 ll d = euclid(b, a % b, y, x);	
d41 return y -= a/b * x, d;	
d41 }	

CRT.h

Description: Chinese Remainder Theorem.

crt(a, m, b, n) computes x such that $x \equiv a \pmod m, x \equiv b \pmod n$. If $|a| < m$ and $|b| < n$, x will obey $0 \leq x < \text{lcm}(m, n)$. Assumes $mn < 2^{62}$.

Time: $\log(n)$

"euclid.h"	d41d8c, 8 lines
d41 ll crt(ll a, ll m, ll b, ll n) {	
d41 if (n > m) swap(a, b), swap(m, n);	
d41 ll x, y, g = euclid(m, n, x, y);	
d41 assert((a - b) % g == 0); // else no solution	
d41 x = (b - a) % n * x % n / g * m + a;	
d41 return x < 0 ? x + m*n/g : x;	
d41 }	

3.3.1 Bézout’s identity

For $a \neq, b \neq 0$, then $d = \gcd(a, b)$ is the smallest positive integer for which there are integer solutions to

$$ax + by = d$$

If (x, y) is one solution, then all solutions are given by

$$\left(x + \frac{kb}{\gcd(a,b)}, y - \frac{ka}{\gcd(a,b)}\right), \quad k \in \mathbb{Z}$$

phiFunction.h

Description: Euler’s ϕ function is defined as $\phi(n) := \#$ of positive integers $\leq n$ that are coprime with n . $\phi(1) = 1, p \text{ prime} \Rightarrow \phi(p^k) = (p - 1)p^{k-1}$, m, n coprime $\Rightarrow \phi(mn) = \phi(m)\phi(n)$. If $n = p_1^{k_1}p_2^{k_2}...p_r^{k_r}$ then $\phi(n) = (p_1 - 1)p_1^{k_1-1}...(p_r - 1)p_r^{k_r-1}$. $\phi(n) = n \cdot \prod_{p|n} (1 - 1/p)$. $\sum_{d|n} \phi(d) = n, \sum_{1 \leq k \leq n, \gcd(k,n)=1} k = n\phi(n)/2, n > 1$.

Euler’s thm: a, n coprime $\Rightarrow a^{\phi(n)} \equiv 1 \pmod n$.

Fermat’s little thm: p prime $\Rightarrow a^{p-1} \equiv 1 \pmod p \forall a$.

	d41d8c, 9 lines
d41 const int LIM = 5000000;	
d41 int phi[LIM];	
d41 void calculatePhi() {	
d41 rep(i,0,LIM) phi[i] = i&1 ? i : i/2;	
d41 for (int i = 3; i < LIM; i += 2) if(phi[i] == i)	
d41 for (int j = i; j < LIM; j += i) phi[j] -= phi[j] / i;	
d41 }	

3.4 Fractions

ContinuedFractions.h

Description: Given N and a real number $x \geq 0$, finds the closest rational approximation p/q with $p, q \leq N$. It will obey $|p/q - x| \leq 1/qN$.

For consecutive convergents, $p_{k+1}q_k - q_{k+1}p_k = (-1)^k$. (p_k/q_k alternates between $> x$ and $< x$.) If x is rational, y eventually becomes ∞ ; if x is the root of a degree 2 polynomial the a ’s eventually become cyclic.

Time: $\mathcal{O}(\log N)$

	d41d8c, 22 lines
d41 typedef double d; // for N ~ 1e7; long double for N ~ 1e9	
d41 pair<ll, ll> approximate(d x, ll N) {	
d41 ll LP = 0, LQ = 1, P = 1, Q = 0, inf = LLONG_MAX; d y = x	
;	
d41 for (;;) {	
d41 ll lim = min(P ? (N-LP) / P : inf, Q ? (N-LQ) / Q : inf	
),	
d41 a = (ll)floor(y), b = min(a, lim),	
d41 NP = b*P + LP, NQ = b*Q + LQ;	
d41 if (a > b) {	
// If b > a/2, we have a semi-convergent that gives	
us a	

```
// better approximation; if b = a/2, we *may* have
one.
// Return {P, Q} here for a more canonical
approximation.
d41 return (abs(x - (d)NP / (d)NQ) < abs(x - (d)P / (d)Q)
) ?
d41     make_pair(NP, NQ) : make_pair(P, Q);
d41 }
d41 if (abs(y = 1/(y - (d)a)) > 3*N) {
d41     return {NP, NQ};
d41 }
d41 LP = P; P = NP;
d41 LQ = Q; Q = NQ;
d41 }
d41 }
```

FracBinarySearch.h

Description: Given f and N , finds the smallest fraction $p/q \in [0, 1]$ such that $f(p/q)$ is true, and $p, q \leq N$. You may want to throw an exception from f if it finds an exact solution, in which case N can be removed.

Usage: fracBS([f](Frac f) { return f.p>=3*f.q; }, 10); // {1,3}

	d41d8c, 26 lines
d41 struct Frac { ll p, q; };	
d41 template<class F>	
d41 Frac fracBS(F f, ll N) {	
d41 bool dir = 1, A = 1, B = 1;	
d41 Frac lo{0, 1}, hi{1, 1}; // Set hi to 1/0 to search (0, N	
]	
d41 if (f(lo)) return lo;	
d41 assert(f(hi));	
d41 while (A B) {	
d41 ll adv = 0, step = 1; // move hi if dir, else lo	
d41 for (int si = 0; step; (step *= 2) >= si) {	
d41 adv += step;	
d41 Frac mid{lo.p * adv + hi.p, lo.q * adv + hi.q};	
d41 if (abs(mid.p) > N mid.q > N dir == !f(mid)) {	
d41 adv -= step; si = 2;	
d41 }	
d41 }	
d41 hi.p += lo.p * adv;	
d41 hi.q += lo.q * adv;	
d41 dir = !dir;	
d41 swap(lo, hi);	
d41 A = B; B = !adv;	
d41 }	
d41 return dir ? hi : lo;	
d41 }	

3.5 Primes

$p = 962592769$ is such that $2^{21} \mid p - 1$, which may be useful. For hashing use 970592641 (31-bit number), 31443539979727 (45-bit), 3006703054056749 (52-bit). There are 78498 primes less than 1 000 000.

Primitive roots exist modulo any prime power p^a , except for $p = 2, a > 2$, and there are $\phi(\phi(p^a))$ many. For $p = 2, a > 2$, the group $\mathbb{Z}_{2^a}^\times$ is instead isomorphic to $\mathbb{Z}_2 \times \mathbb{Z}_{2^{a-2}}$.

3.6 Estimates

$$\sum_{d|n} d = O(n \log \log n).$$

The number of divisors of n is at most around 100 for $n < 5e4$, 500 for $n < 1e7$, 2000 for $n < 1e10$, 200 000 for $n < 1e19$.

3.7 Mobius Function

μ(n) = { 0 if n is not square free, 1 if n has even number of prime factors, -1 if n has odd number of prime factors

Mobius Inversion:

g(n) = Σ_{d|n} f(d) ⇔ f(n) = Σ_{d|n} μ(d)g(n/d)

Other useful formulas/forms:

Σ_{d|n} μ(d) = [n = 1] (very useful)
g(n) = Σ_{n|d} f(d) ⇔ f(n) = Σ_{n|d} μ(d/n)g(d)
g(n) = Σ_{1≤m≤n} f(⌊n/m⌋) ⇔ f(n) = Σ_{1≤m≤n} μ(m)g(⌊n/m⌋)

3.8 Theorems

Goldbach’s conjecture: Every even integer n > 2 can be written as n = a + b with a, b prime.
Legendre’s conjecture: There is always at least one prime between n^2 and (n + 1)^2.
Lagrange’s four-square theorem: Every positive integer can be written as

n = a^2 + b^2 + c^2 + d^2.

Zeckendorf’s theorem: Every integer n ≥ 1 has a unique representation as a sum of non-consecutive Fibonacci numbers:

n = F_{i_1} + F_{i_2} + ... + F_{i_k}, i_j - i_{j+1} ≥ 2.

Euclid’s formula (primitive Pythagorean triples): The Pythagorean triples are uniquely generated by

a = k · (m^2 - n^2), b = k · (2mn), c = k · (m^2 + n^2),

with m > n > 0, k > 0, m ⊥ n, and either m or n even.

Wilson’s theorem: n is prime iff

(n - 1)! ≡ -1 (mod n).

Chicken McNugget theorem: For coprime n, m, the largest integer not representable as an + bm (with a, b ≥ 0) is

nm - n - m.

There are (n-1)(m-1)/2 non-representable integers, and for each pair (k, nm - n - m - k) exactly one is representable.

Combinatorial (4)

4.1 Binomial Identities

Binomial identities including Pascal's rule, binomial theorem, and combinatorial identities like Σ k^2 * C(n, k) = (n + n^2) 2^{n-2}.

4.2 Permutations

4.2.1 Factorial

Table with 2 rows of headers and 10 data columns showing factorial values from 1! to 10! and their decimal representations.

IntPerm.h
Description: Permutation -> integer conversion. (Not order preserving.)
Integer -> permutation can use a lookup table.
Time: O(n)
d41d8c, 7 lines
d41 int permToInt(vi& v) {
d41 int use = 0, i = 0, r = 0;
d41 for(int x:v) r = r * ++i + __builtin_popcount(use & -(1<<x)),
d41 use |= 1 << x; // (note: minus, not ~!)
d41 return r;
d41 }

4.2.2 Cycles

Let g_S(n) be the number of n-permutations whose cycle lengths all belong to the set S. Then

Σ_{n=0}^∞ g_S(n) x^n / n! = exp (Σ_{n∈S} x^n / n)

4.2.3 Derangements

Permutations of a set such that none of the elements appear in their original position.

D(n) = (n - 1)(D(n - 1) + D(n - 2)) = nD(n - 1) + (-1)^n = ⌊ n! / e ⌋

4.2.4 Burnside’s lemma

Counts the number of distinct colorings of an object under symmetry.

1/|G| Σ_{g∈G} k^{cyc(g)},

where G is the symmetry group, k the number of colors, and cyc(g) the number of cycles induced by g.

Example: number of ways to color a necklace with n beads using k colors (rotations only):

g(n) = 1/n Σ_{i=0}^{n-1} k^{gcd(n,i)}

where rotation i shifts the necklace by i positions.

4.3 Partitions and subsets

4.3.1 Partition function

Number of ways of writing n as a sum of positive integers, disregarding the order of the summands.

p(0) = 1, p(n) = Σ_{k∈Z\{0}} (-1)^{k+1} p(n - k(3k - 1)/2)

p(n) ~ 0.145/n · exp(2.56√n)

Table with 2 rows of headers and 15 data columns showing partition values from 0! to 100!.

4.3.2 Lucas’ Theorem

Let n, m be non-negative integers and p a prime. Write n = n_k p^k + ... + n_1 p + n_0 and m = m_k p^k + ... + m_1 p + m_0. Then (n choose m) ≡ Π_{i=0}^k (n_i choose m_i) (mod p).

4.3.3 Binomials

multinomial.h
Description: Computes (k_1 + ... + k_n choose k_1, k_2, ..., k_n) = (Σ k_i)! / (k_1! k_2! ... k_n!).
d41d8c, 6 lines
d41 ll multinomial(vi& v) {
d41 ll c = 1, m = v.empty() ? 1 : v[0];
d41 rep(i,1,sz(v)) rep(j,0,v[i]) c = c * ++m / (j+1);
d41 return c;
d41 }

4.4 General purpose numbers

4.4.1 Stirling numbers of the first kind

Number of permutations on n items with k cycles.

c(n, k) = c(n - 1, k - 1) + (n - 1)c(n - 1, k), c(0, 0) = 1
Σ_{k=0}^n c(n, k) x^k = x(x + 1) ... (x + n - 1)

c(8, k) = 8, 0, 5040, 13068, 13132, 6769, 1960, 322, 28, 1
c(n, 2) = 0, 0, 1, 3, 11, 50, 274, 1764, 13068, 109584, ...

4.4.2 Eulerian numbers

Number of permutations $\pi \in S_n$ in which exactly k elements are greater than the previous element. k j :s s.t. $\pi(j) > \pi(j + 1)$, $k + 1$ j :s s.t. $\pi(j) \geq j$, k j :s s.t. $\pi(j) > j$.

$$E(n, k) = (n - k)E(n - 1, k - 1) + (k + 1)E(n - 1, k)$$

$$E(n, 0) = E(n, n - 1) = 1$$

$$E(n, k) = \sum_{j=0}^k (-1)^j \binom{n+1}{j} (k+1-j)^n$$

4.4.3 Stirling numbers of the second kind

Partitions of n distinct elements into exactly k groups.

$$S(n, k) = S(n - 1, k - 1) + kS(n - 1, k)$$

$$S(n, 1) = S(n, n) = 1$$

$$S(n, k) = \frac{1}{k!} \sum_{j=0}^k (-1)^{k-j} \binom{k}{j} j^n$$

4.4.4 Bell numbers

Total number of partitions of n distinct elements. $B(n) = 1, 1, 2, 5, 15, 52, 203, 877, 4140, 21147, \dots$. For p prime,

$$B(p^m + n) \equiv mB(n) + B(n + 1) \pmod{p}$$

4.4.5 Labeled unrooted trees

- on n vertices: n^{n-2}
- on k existing trees of size n_i : $n_1 n_2 \cdots n_k n^{k-2}$
- with degrees d_i : $(n - 2)! / ((d_1 - 1)! \cdots (d_n - 1)!)$

4.4.6 Catalan numbers

$$C_n = \frac{1}{n + 1} \binom{2n}{n} = \binom{2n}{n} - \binom{2n}{n + 1} = \frac{(2n)!}{(n + 1)!n!}$$

$$C_0 = 1, C_{n+1} = \frac{2(2n + 1)}{n + 2} C_n, C_{n+1} = \sum C_i C_{n-i}$$

$$C_n = 1, 1, 2, 5, 14, 42, 132, 429, 1430, 4862, 16796, 58786, \dots$$

- sub-diagonal monotone paths in an $n \times n$ grid.
- strings with n pairs of parenthesis, correctly nested.
- binary trees with with $n + 1$ leaves (0 or 2 children).
- ordered trees with $n + 1$ vertices.
- ways a convex polygon with $n + 2$ sides can be cut into triangles by connecting vertices with straight lines.
- permutations of $[n]$ with no 3-term increasing subseq.

Various (5)

5.1 Intervals

IntervalContainer.h

Description: Add and remove intervals from a set of disjoint intervals. Will merge the added interval with any overlapping intervals in the set when adding. Intervals are [inclusive, exclusive).

Time: $\mathcal{O}(\log N)$

```
d41d8c, 24 lines
d41 set<pii>::iterator addInterval(set<pii>& is, int L, int R)
d41 {
d41     if (L == R) return is.end();
d41     auto it = is.lower_bound({L, R}), before = it;
d41     while (it != is.end() && it->first <= R) {
d41         R = max(R, it->second);
d41         before = it = is.erase(it);
d41     }
d41     if (it != is.begin() && (--it)->second >= L) {
d41         L = min(L, it->first);
d41         R = max(R, it->second);
d41         is.erase(it);
d41     }
d41     return is.insert(before, {L,R});
d41 }
```

```
d41 void removeInterval(set<pii>& is, int L, int R) {
d41     if (L == R) return;
d41     auto it = addInterval(is, L, R);
d41     auto r2 = it->second;
d41     if (it->first == L) is.erase(it);
d41     else (int&)it->second = L;
d41     if (R != r2) is.emplace(R, r2);
d41 }
```

IntervalCover.h

Description: Compute indices of smallest set of intervals covering another interval. Intervals should be [inclusive, exclusive). To support [inclusive, inclusive], change (A) to add || R.empty(). Returns empty set on failure (or if G is empty).

Time: $\mathcal{O}(N \log N)$

```
d41d8c, 20 lines
d41 template<class T>
d41 vi cover(pair<T, T> G, vector<pair<T, T>> I) {
d41     vi S(sz(I)), R;
d41     iota(all(S), 0);
d41     sort(all(S), [&](int a, int b) { return I[a] < I[b]; });
d41     T cur = G.first;
d41     int at = 0;
d41     while (cur < G.second) { // (A)
d41         pair<T, int> mx = make_pair(cur, -1);
d41         while (at < sz(I) && I[S[at]].first <= cur) {
d41             mx = max(mx, make_pair(I[S[at]].second, S[at]));
d41             at++;
d41         }
d41         if (mx.second == -1) return {};
d41         cur = mx.first;
d41         R.push_back(mx.second);
d41     }
d41     return R;
d41 }
```

ConstantIntervals.h

Description: Split a monotone function on [from, to) into a minimal set of half-open intervals on which it has the same value. Runs a callback g for each such interval.

Usage: constantIntervals(0, sz(v), [&](int x){return v[x];}, [&](int lo, int hi, T val){...});

Time: $\mathcal{O}(k \log \frac{n}{k})$

d41d8c, 20 lines

```
d41 template<class F, class G, class T>
d41 void rec(int from, int to, F& f, G& g, int& i, T& p, T q)
d41 {
d41     if (p == q) return;
d41     if (from == to) {
d41         g(i, to, p);
d41         i = to; p = q;
d41     } else {
d41         int mid = (from + to) >> 1;
d41         rec(from, mid, f, g, i, p, f(mid));
d41         rec(mid+1, to, f, g, i, p, q);
d41     }
d41 }
d41 template<class F, class G>
d41 void constantIntervals(int from, int to, F f, G g) {
d41     if (to <= from) return;
d41     int i = from; auto p = f(i), q = f(to-1);
d41     rec(from, to-1, f, g, i, p, q);
d41     g(i, to, q);
d41 }
```

5.2 Misc. algorithms

TernarySearch.h

Description: Find the smallest i in $[a, b]$ that maximizes $f(i)$, assuming that $f(a) < \dots < f(i) \geq \dots \geq f(b)$. To reverse which of the sides allows non-strict inequalities, change the $<$ marked with (A) to $<=$, and reverse the loop at (B). To minimize f , change it to $>$, also at (B).

Usage: int ind = ternSearch(0,n-1,[&](int i){return a[i];});

Time: $\mathcal{O}(\log(b - a))$

d41d8c, 12 lines

```
d41 template<class F>
d41 int ternSearch(int a, int b, F f) {
d41     assert(a <= b);
d41     while (b - a >= 5) {
d41         int mid = (a + b) / 2;
d41         if (f(mid) < f(mid+1)) a = mid; // (A)
d41         else b = mid+1;
d41     }
d41     rep(i,a+1,b+1) if (f(a) < f(i)) a = i; // (B)
d41     return a;
d41 }
```

LIS.h

Description: Compute indices for the longest increasing subsequence.

Time: $\mathcal{O}(N \log N)$

d41d8c, 18 lines

```
d41 template<class I> vi lis(const vector<I>& S) {
d41     if (S.empty()) return {};
d41     vi prev(sz(S));
d41     typedef pair<I, int> p;
d41     vector<p> res;
d41     rep(i,0,sz(S)) {
d41         // change 0 -> i for longest non-decreasing subsequence
d41         auto it = lower_bound(all(res), p{S[i], 0});
d41         if (it == res.end()) res.emplace_back(), it = res.end()
d41         -1;
d41         *it = {S[i], i};
d41         prev[i] = it == res.begin() ? 0 : (it-1)->second;
d41     }
d41     int L = sz(res), cur = res.back().second;
d41     vi ans(L);
d41     while (L-->) ans[L] = cur, cur = prev[cur];
d41     return ans;
d41 }
```

FastKnapsack.h

Description: Given N non-negative integer weights w and a non-negative target t, computes the maximum S <= t such that S is the sum of some subset of the weights.
Time: $\mathcal{O}(N \max(w_i))$

```
d41d8c, 17 lines
```

```
d41 int knapsack(vi w, int t) {
d41     int a = 0, b = 0, x;
d41     while (b < sz(w) && a + w[b] <= t) a += w[b++];
d41     if (b == sz(w)) return a;
d41     int m = *max_element(all(w));
d41     vi u, v(2*m, -1);
d41     v[a+m-t] = b;
d41     rep(i,b,sz(w)) {
d41         u = v;
d41         rep(x,0,m) v[x+w[i]] = max(v[x+w[i]], u[x]);
d41         for (x = 2*m; --x > m;) rep(j, max(0,u[x]), v[x])
d41             v[x-w[j]] = max(v[x-w[j]], j);
d41     }
d41     for (a = t; v[a+m-t] < 0; a--);
d41     return a;
d41 }
```

BumpAllocator.h

Description: When you need to dynamically allocate many objects and don't care about freeing them. "new X" otherwise has an overhead of something like 0.05us + 16 bytes per allocation.

```
d41d8c, 9 lines
```

```
// Either globally or in a single class:
d41 static char buf[450 << 20];
d41 void* operator new(size_t s) {
d41     static size_t i = sizeof buf;
d41     assert(s < i);
d41     return (void*)&buf[i -= s];
d41 }
d41 void operator delete(void*) {}
```

SmallPtr.h

Description: A 32-bit pointer that points into BumpAllocator memory.

```
"BumpAllocator.h" d41d8c, 11 lines
```

```
d41 template<class T> struct ptr {
d41     unsigned ind;
d41     ptr(T* p = 0) : ind(p ? unsigned((char*)p - buf) : 0) {
d41         assert(ind < sizeof buf);
d41     }
d41     T& operator*() const { return *(T*)(buf + ind); }
d41     T* operator->() const { return &*this; }
d41     T& operator[](int a) const { return (&this)[a]; }
d41     explicit operator bool() const { return ind; }
d41 };
```

BumpAllocatorSTL.h

Description: BumpAllocator for STL containers.
Usage: vector<vector<int, small<int>>>> ed(N);

```
d41d8c, 15 lines
```

```
d41 char buf[450 << 20] alignas(16);
d41 size_t buf_ind = sizeof buf;
```

FastMod.h

Description: Compute $a \% b$ about 5 times faster than usual, where b is constant but not known at compile time. Returns a value congruent to a (mod b) in the range [0, 2b).

```
d41d8c, 9 lines
```

```
d41 typedef unsigned long long ull;
d41 struct FastMod {
d41     ull b, m;
d41     FastMod(ull b) : b(b), m(-1ULL / b) {}
d41     ull reduce(ull a) { // a % b + (0 or b)
d41         return a - (ull)((__uint128_t(m) * a) >> 64) * b;
d41     }
d41 };
```

FastInput.h

Description: Read an integer from stdin. Usage requires your program to pipe in input from file.
Usage: ./a.out < input.txt
Time: About 5x as fast as cin/scanf.

```
d41d8c, 18 lines
```

```
d41 inline char gc() { // like getchar()
d41     static char buf[1 << 16];
d41     static size_t bc, be;
d41     if (bc >= be) {
d41         buf[0] = 0, bc = 0;
d41         be = fread(buf, 1, sizeof(buf), stdin);
d41     }
d41     return buf[bc++]; // returns 0 on EOF
d41 }
```

__builtin_ia32_ldmxcsr(40896); disables denormals (which make floats 20x slower near their minimum value).

5.5 Optimization tricks

5.5.1 Bit hacks

- x & -x is the least bit in x.
- for (int x = m; x;) { --x &= m; ... } loops over all subset masks of m (except m itself).
- c = x&-x, r = x+c; (((r^x) >> 2)/c) | r is the next number after x with the same number of bits set.
- rep(b,0,K) rep(i,0,(1 << K)) if (i & 1 << b) D[i] += D[i^(1 << b)]; computes all sums of subsets.

5.5.2 Pragmas

- #pragma GCC optimize ("Ofast") will make GCC auto-vectorize loops and optimizes floating points better.
- #pragma GCC target ("avx2") can double performance of vectorized code, but causes crashes on old machines.
- #pragma GCC optimize ("trapv") kills the program on integer overflows (but is really slow).

5.3 Dynamic programming

KnuthDP.h

Description: When doing DP on intervals: $a[i][j] = \min_{i < k < j} (a[i][k] + a[k][j]) + f(i, j)$, where the (minimal) optimal k increases with both i and j, one can solve intervals in increasing order of length, and search $k = p[i][j]$ for $a[i][j]$ only between $p[i][j - 1]$ and $p[i + 1][j]$. This is known as Knuth DP. Sufficient criteria for this are if $f(b, c) \leq f(a, d)$ and $f(a, c) + f(b, d) \leq f(a, d) + f(b, c)$ for all $a \leq b \leq c \leq d$. Consider also: LineContainer (ch. Data structures), monotone queues, ternary search.

Time: $\mathcal{O}(N^2)$

```
d41d8c, 2 lines
```

DivideAndConquerDP.h

Description: Given $a[i] = \min_{l \circ(i) \leq k < h \circ(i)} (f(i, k))$ where the (minimal) optimal k increases with i, computes $a[i]$ for $i = L..R - 1$.
Time: $\mathcal{O}((N + (hi - lo)) \log N)$

```
d41d8c, 19 lines
```

```
d41 struct DP { // Modify at will:
d41     int lo(int ind) { return 0; }
d41     int hi(int ind) { return ind; }
d41     ll f(int ind, int k) { return dp[ind][k]; }
d41     void store(int ind, int k, ll v) { res[ind] = pii(k, v); }
d41 }
d41 void rec(int L, int R, int LO, int HI) {
d41     if (L >= R) return;
d41     int mid = (L + R) >> 1;
d41     pair<ll, int> best(LLONG_MAX, LO);
d41     rep(k, max(LO, lo(mid)), min(HI, hi(mid)))
d41         best = min(best, make_pair(f(mid, k), k));
d41     store(mid, best.second, best.first);
d41     rec(L, mid, LO, best.second+1);
d41     rec(mid+1, R, best.second, HI);
d41 }
d41 void solve(int L, int R) { rec(L, R, INT_MIN, INT_MAX); }
d41 };
```

5.4 Debugging tricks

- signal(SIGSEGV, [](int) { _Exit(0); }); converts segfaults into Wrong Answers. Similarly one can catch SIGABRT (assertion failures) and SIGFPE (zero divisions). _GLIBCXX_DEBUG failures generate SIGABRT (or SIGSEGV on gcc 5.4.0 apparently).


```

// High-level/specific methods:
// load(u)?_si256, store(u)?_si256, setzero_si256,
// _mm_malloc
// blendv_(epi8|ps|pd) (z?y:x), movemask_epi8 (hibits of
// bytes)
// i32gather_epi32(addr, x, 4): map addr[] over 32-b parts
// of x
// sad_epu8: sum of absolute differences of u8, outputs 4
// xi64
// maddubs_epi16: dot product of unsigned i7's, outputs 16
// xi15
// madd_epi16: dot product of signed i16's, outputs 8xi32
// extractf128_si256(, i) (256->128), cvtsi128_si32 (128->
// lo32)
// permute2f128_si256(x,x,1) swaps 128-bit lanes
// shuffle_epi32(x, 3*64+2*16+1*4+0) == x for each lane
// shuffle_epi8(x, y) takes a vector instead of an imm

// Methods that work with most data types (append e.g.
// _epi32):
// set1, blend (i8?x:y), add, adds (sat.), mullo, sub, and
// /or,
// andnot, abs, min, max, sign(1,x), cmp(gt|eq), unpack(lo
// |hi)

d41 int sumi32(mi m) { union {int v[8]; mi m;} u; u.m = m;
d41 int ret = 0; rep(i,0,8) ret += u.v[i]; return ret; }
d41 mi zero() { return _mm256_setzero_si256(); }
d41 mi one() { return _mm256_set1_epi32(-1); }
d41 bool all_zero(mi m) { return _mm256_testz_si256(m, m); }
d41 bool all_one(mi m) { return _mm256_testc_si256(m, one()); }
}

d41 ll example_filteredDotProduct(int n, short* a, short* b) {
d41 int i = 0; ll r = 0;
d41 mi zero = _mm256_setzero_si256(), acc = zero;
d41 while (i + 16 <= n) {
d41     mi va = L(a[i]), vb = L(b[i]); i += 16;
d41     va = _mm256_and_si256(_mm256_cmpgt_epi16(vb, va), va);
d41     mi vp = _mm256_madd_epi16(va, vb);
d41     acc = _mm256_add_epi64(_mm256_unpacklo_epi32(vp, zero),
d41     _mm256_add_epi64(acc, _mm256_unpackhi_epi32(vp, zero)
d41 ));
d41 }
d41 union {ll v[4]; mi m;} u; u.m = acc; rep(i,0,4) r += u.v[
d41 i];
d41 for (;i<n;++i) if (a[i] < b[i]) r += a[i]*b[i]; // <-
d41 equiv
d41 return r;
d41 }

```

Techniques (A)

techniques.txt	159 lines
Recursion	
Divide and conquer	
Finding interesting points in N log N	
Algorithm analysis	
Master theorem	
Amortized time complexity	
Greedy algorithm	
Scheduling	
Max contiguous subvector sum	
Invariants	
Huffman encoding	
Graph theory	
Dynamic graphs (extra book-keeping)	
Breadth first search	
Depth first search	
* Normal trees / DFS trees	
Dijkstra's algorithm	
MST: Prim's algorithm	
Bellman-Ford	
Konig's theorem and vertex cover	
Min-cost max flow	
Lovasz toggle	
Matrix tree theorem	
Maximal matching, general graphs	
Hopcroft-Karp	
Hall's marriage theorem	
Graphical sequences	
Floyd-Warshall	
Euler cycles	
Flow networks	
* Augmenting paths	
* Edmonds-Karp	
Bipartite matching	
Min. path cover	
Topological sorting	
Strongly connected components	
2-SAT	
Cut vertices, cut-edges and biconnected components	
Edge coloring	
* Trees	
Vertex coloring	
* Bipartite graphs (=> trees)	
* 3^n (special case of set cover)	
Diameter and centroid	
K'th shortest path	
Shortest cycle	
Dynamic programming	
Knapsack	
Coin change	
Longest common subsequence	
Longest increasing subsequence	
Number of paths in a dag	
Shortest path in a dag	
Dynprog over intervals	
Dynprog over subsets	
Dynprog over probabilities	
Dynprog over trees	
3^n set cover	
Divide and conquer	
Knuth optimization	
Convex hull optimizations	
RMQ (sparse table a.k.a 2^k-jumps)	
Bitonic cycle	
Log partitioning (loop over most restricted)	
Combinatorics	

Computation of binomial coefficients
Pigeon-hole principle
Inclusion/exclusion
Catalan number
Pick's theorem
Number theory
Integer parts
Divisibility
Euclidean algorithm
Modular arithmetic
* Modular multiplication
* Modular inverses
* Modular exponentiation by squaring
Chinese remainder theorem
Fermat's little theorem
Euler's theorem
Phi function
Frobenius number
Quadratic reciprocity
Pollard-Rho
Miller-Rabin
Hensel lifting
Vieta root jumping
Game theory
Combinatorial games
Game trees
Mini-max
Nim
Games on graphs
Games on graphs with loops
Grundy numbers
Bipartite games without repetition
General games without repetition
Alpha-beta pruning
Probability theory
Optimization
Binary search
Ternary search
Unimodality and convex functions
Binary search on derivative
Numerical methods
Numeric integration
Newton's method
Root-finding with binary/ternary search
Golden section search
Matrices
Gaussian elimination
Exponentiation by squaring
Sorting
Radix sort
Geometry
Coordinates and vectors
* Cross product
* Scalar product
Convex hull
Polygon cut
Closest pair
Coordinate-compression
Quadtrees
KD-trees
All segment-segment intersection
Sweeping
Discretization (convert to events and sweep)
Angle sweeping
Line sweeping
Discrete second derivatives
Strings
Longest common substring
Palindrome subsequences

Knuth-Morris-Pratt
Tries
Rolling polynomial hashes
Suffix array
Suffix tree
Aho-Corasick
Manacher's algorithm
Letter position lists
Combinatorial search
Meet in the middle
Brute-force with pruning
Best-first (A*)
Bidirectional search
Iterative deepening DFS / A*
Data structures
LCA (2^k-jumps in trees in general)
Pull/push-technique on trees
Heavy-light decomposition
Centroid decomposition
Lazy propagation
Self-balancing trees
Convex hull trick (wcipeg.com/wiki/Convex_hull_trick)
Monotone queues / monotone stacks / sliding queues
Sliding queue using 2 stacks
Persistent segment tree