

# Resolving Full Motion in Presence of Micromotion

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The equation of motion we are interested in solving is:

$$v_p''(\tau) = -\frac{(2\pi)^2}{\beta^2} \left( a_p - 2q_x \cos\left(\frac{4\pi\tau}{\beta}\right) \right) v_p(\tau) \quad (1)$$

Or, if the substitution  $\xi = \frac{2\pi\tau}{\beta}$  (which is equivalent to  $\xi = \frac{\omega_{RF}}{2}t$ , as  $\tau = \frac{\beta\omega_{RF}}{4\pi}t$ ) is made:

$$v_p''(\xi) = -(a_p - 2q_x \cos(2\xi)) v_p(\xi) \quad (2)$$

The stable solutions of the Mathieu Equation can be found from Floquet's Theorem, which states that the Mathieu Equation admits a complex-valued solution of the form:

$$F(a_p, q_x, \xi) = e^{i\beta_p\xi} P(2\xi) + e^{-i\beta_p\xi} P(-2\xi) \quad (3)$$

Here,  $\beta_p$  is some complex number (which we have not yet defined), denoted as the Floquet exponent.  $P(2\xi)$  is a complex-valued function of the same period as the periodic function in our differential equation, which is given in (2) (hence the dependency on  $2\xi$ ). That is,  $P(2\xi)$  is a periodic function with  $\pi$ , which allows us to generate a general Fourier series for  $P(2\xi)$ :

$$P(2\xi) = \sum_{n=-\infty}^{\infty} C_n e^{i2n\xi} \quad (4)$$

Ultimately, this gives the stable solutions of the Mathieu Equation as:

$$v_p(\xi) = A e^{i\beta_p\xi} \sum_{n=-\infty}^{\infty} C_n e^{i2n\xi} + B e^{-i\beta_p\xi} \sum_{n=-\infty}^{\infty} C_n e^{-i2n\xi} \quad (5)$$

$\beta_p$ , the Floquet exponent, is a mode-specific value that is defined from the recurrence relations, and  $\beta$  is chosen as  $\beta := \beta_1$  (see 'Secular Limit of Micromotion' document). If we now convert back to the non-dimensionalised time  $\tau$  (which is related to  $\xi$  via  $\xi = \frac{2\pi}{\beta}\tau$ ), this becomes:

$$v_p(\tau) = A e^{i2\pi\frac{\beta_p}{\beta}\tau} \sum_{n=-\infty}^{\infty} C_n e^{in\frac{4\pi\tau}{\beta}} + B e^{-i2\pi\frac{\beta_p}{\beta}\tau} \sum_{n=-\infty}^{\infty} C_n e^{-in\frac{4\pi\tau}{\beta}} \quad (6)$$

By modifying  $A$  and  $B$ , this can be shifted to:

$$v_p(\tau) = A' e^{i2\pi\frac{\beta_p}{\beta}(\tau-\tau_0)} \sum_{n=-\infty}^{\infty} C_n e^{in\frac{4\pi\tau}{\beta}} + B' e^{-i2\pi\frac{\beta_p}{\beta}(\tau-\tau_0)} \sum_{n=-\infty}^{\infty} C_n e^{-in\frac{4\pi\tau}{\beta}} \quad (7)$$

Its corresponding time derivative is given by:

$$\begin{aligned} v_p'(\tau) &= A' \left( i2\pi\frac{\beta_p}{\beta} \right) e^{i2\pi\frac{\beta_p}{\beta}(\tau-\tau_0)} \sum_{n=-\infty}^{\infty} C_n e^{in\frac{4\pi\tau}{\beta}} + B' \left( -i2\pi\frac{\beta_p}{\beta} \right) e^{-i2\pi\frac{\beta_p}{\beta}(\tau-\tau_0)} \sum_{n=-\infty}^{\infty} C_n e^{-in\frac{4\pi\tau}{\beta}} \\ &+ A' e^{i2\pi\frac{\beta_p}{\beta}(\tau-\tau_0)} \sum_{n=-\infty}^{\infty} C_n \left( \frac{4\pi in}{\beta} \right) e^{in\frac{4\pi\tau}{\beta}} + B' e^{-i2\pi\frac{\beta_p}{\beta}(\tau-\tau_0)} \sum_{n=-\infty}^{\infty} C_n \left( -\frac{4\pi in}{\beta} \right) e^{-in\frac{4\pi\tau}{\beta}} \end{aligned} \quad (8)$$

We can solve for  $A'$  and  $B'$  by equating the motion to initial conditions. Note that  $A'$  and  $B'$  will need to be complex coefficients in order for the motion as a whole,  $v_p(\tau)$ , to be purely real. If we impose the initial condition  $v_p(\tau_0) = x_0$ , then this generates:

$$x_0 = A' \sum_{n=-\infty}^{\infty} C_n e^{in\frac{4\pi\tau_0}{\beta}} + B' \sum_{n=-\infty}^{\infty} C_n e^{-in\frac{4\pi\tau_0}{\beta}} \quad (9)$$

$$= (A'_r + iA'_i)(f_c(\tau_0) + if_s(\tau_0)) + (B'_r + iB'_i)(f_c(\tau_0) - if_s(\tau_0)) \quad (10)$$

where:

$$f_c(\tau) = \sum_{n=-\infty}^{\infty} C_n \cos\left(\frac{4n\pi\tau}{\beta}\right) \quad (11)$$

$$f_s(\tau) = \sum_{n=-\infty}^{\infty} C_n \sin\left(\frac{4n\pi\tau}{\beta}\right) \quad (12)$$

If this is explicitly broken up into its real and imaginary parts, we generate:

$$x_0 = (A'_r + B'_r)f_c(\tau_0) + (B'_i - A'_i)f_s(\tau_0) \quad (13)$$

$$0 = (A'_i + B'_i)f_c(\tau_0) + (A'_r - B'_r)f_s(\tau_0) \quad (14)$$

If we also impose the initial condition  $v'_p(\tau_0) = v_0$ , then this generates:

$$\begin{aligned} v_0 &= A' \left( i2\pi \frac{\beta_p}{\beta} \right) \sum_{n=-\infty}^{\infty} C_n e^{in \frac{4\pi\tau_0}{\beta}} + B' \left( -i2\pi \frac{\beta_p}{\beta} \right) \sum_{n=-\infty}^{\infty} C_n e^{-in \frac{4\pi\tau_0}{\beta}} \\ &+ A' \sum_{n=-\infty}^{\infty} C_n \left( \frac{4\pi in}{\beta} \right) e^{in \frac{4\pi\tau_0}{\beta}} + B' \sum_{n=-\infty}^{\infty} C_n \left( -\frac{4\pi in}{\beta} \right) e^{-in \frac{4\pi\tau_0}{\beta}} \end{aligned} \quad (15)$$

$$\begin{aligned} &= (A'_r + iA'_i) \left( 2\pi \frac{\beta_p}{\beta} \right) (if_c(\tau_0) - f_s(\tau_0)) + (B'_r + iB'_i) \left( 2\pi \frac{\beta_p}{\beta} \right) (-if_c(\tau_0) - f_s(\tau_0)) \\ &+ (A'_r + iA'_i)(if'_s(\tau_0) + f'_c(\tau_0)) + (B'_r + iB'_i)(-if'_s(\tau_0) + f'_c(\tau_0)) \end{aligned} \quad (16)$$

If this is explicitly broken up into its real and imaginary parts, we generate:

$$v_0 = \frac{2\pi\beta_p}{\beta} [-(A'_r + B'_r)f_s(\tau_0) + (B'_i - A'_i)f_c(\tau_0)] + (A'_r + B'_r)f'_c(\tau_0) + (B'_i - A'_i)f'_s(\tau_0) \quad (17)$$

$$0 = \frac{2\pi\beta_p}{\beta} [-(A'_i + B'_i)f_s(\tau_0) + (A'_r - B'_r)f_c(\tau_0)] + (A'_i + B'_i)f'_c(\tau_0) + (A'_r - B'_r)f'_s(\tau_0) \quad (18)$$

Equations (13), (14), (17) and (18) now fully define  $A'$  and  $B'$ . The components of  $A'$  and  $B'$  can accordingly be solved as:

$$A'_r = -\frac{1}{2} \frac{f_s(\tau_0)v_0 - x_0 \left( \frac{2\pi\beta_p}{\beta} f_c(\tau_0) + f'_s(\tau_0) \right)}{f_c(\tau_0)f'_s(\tau_0) - f'_c(\tau_0)f_s(\tau_0) + \frac{2\pi\beta_p}{\beta} (f_c(\tau_0)^2 + f_s(\tau_0)^2)} \quad (19)$$

$$B'_r = -\frac{1}{2} \frac{f_s(\tau_0)v_0 - x_0 \left( \frac{2\pi\beta_p}{\beta} f_c(\tau_0) + f'_s(\tau_0) \right)}{f_c(\tau_0)f'_s(\tau_0) - f'_c(\tau_0)f_s(\tau_0) + \frac{2\pi\beta_p}{\beta} (f_c(\tau_0)^2 + f_s(\tau_0)^2)} \quad (20)$$

$$A'_i = -\frac{1}{2} \frac{f_c(\tau_0)v_0 - x_0 \left( -\frac{2\pi\beta_p}{\beta} f_s(\tau_0) + f'_c(\tau_0) \right)}{f_c(\tau_0)f'_s(\tau_0) - f'_c(\tau_0)f_s(\tau_0) + \frac{2\pi\beta_p}{\beta} (f_c(\tau_0)^2 + f_s(\tau_0)^2)} \quad (21)$$

$$B'_i = \frac{1}{2} \frac{f_c(\tau_0)v_0 - x_0 \left( -\frac{2\pi\beta_p}{\beta} f_s(\tau_0) + f'_c(\tau_0) \right)}{f_c(\tau_0)f'_s(\tau_0) - f'_c(\tau_0)f_s(\tau_0) + \frac{2\pi\beta_p}{\beta} (f_c(\tau_0)^2 + f_s(\tau_0)^2)} \quad (22)$$

We can see that  $A$  and  $B$  are complex conjugates of one another, which ensures that our motion is indeed real. Substituting  $A' = A'_r + iA'_i$  and  $B' = A'_r - iA'_i$  (for simplicity) into (7), the motion becomes:

$$v_p(\tau) = 2(A'_r f_c(\tau) - A'_i f_s(\tau)) \cos\left(2\pi \frac{\beta_p}{\beta} (\tau - \tau_0)\right) - 2(A'_i f_c(\tau) + A'_r f_s(\tau)) \sin\left(2\pi \frac{\beta_p}{\beta} (\tau - \tau_0)\right) \quad (23)$$

Accordingly, by substituting the form of  $A'_r$  and  $A'_i$  from (19) and (21) respectively, we generate the motion:

$$\begin{aligned} v_p(\tau) &= \frac{1}{f'_c(\tau_0)f_s(\tau_0) - f_c(\tau_0)f'_s(\tau_0) - \frac{2\pi\beta_p}{\beta} (f_c(\tau_0)^2 + f_s(\tau_0)^2)} \left( \cos\left(2\pi \frac{\beta_p}{\beta} (\tau - \tau_0)\right) \left( (f_s(\tau_0)v_0 - f'_s(\tau_0)x_0)f_c(\tau) \right. \right. \\ &+ (f'_c(\tau_0)x_0 - f_c(\tau_0)v_0)f_s(\tau) - \frac{2\pi\beta_p}{\beta} x_0(f_c(\tau_0)f_c(\tau) + f_s(\tau_0)f_s(\tau)) \Big) + \sin\left(2\pi \frac{\beta_p}{\beta} (\tau - \tau_0)\right) \left( f_s(\tau)(f'_s(\tau_0)x_0 \right. \\ &- f_s(\tau_0)v_0 + \frac{2\pi\beta_p}{\beta} f_c(\tau_0)x_0) + f_c(\tau)(f'_c(\tau_0)x_0 - f_c(\tau)v_0 - \frac{2\pi\beta_p}{\beta} x_0f_s(\tau)) \Big) \Big) \end{aligned} \quad (24)$$

To provide a more convenient form of the motion, we can introduce the following constants:

$$\sigma_c = f_c(\tau_0) = \sum_{n=-\infty}^{\infty} C_n \cos\left(\frac{4n\pi\tau_0}{\beta}\right) \quad (25)$$

$$\sigma_s = f_s(\tau_0) = \sum_{n=-\infty}^{\infty} C_n \sin\left(\frac{4n\pi\tau_0}{\beta}\right) \quad (26)$$

$$\zeta_c = \frac{\beta}{4\pi} f'_s(\tau_0) = \sum_{n=-\infty}^{\infty} n C_n \cos\left(\frac{4n\pi\tau_0}{\beta}\right) \quad (27)$$

$$\zeta_s = -\frac{\beta}{4\pi} f'_c(\tau_0) = \sum_{n=-\infty}^{\infty} n C_n \sin\left(\frac{4n\pi\tau_0}{\beta}\right) \quad (28)$$

$$\rho = 4\pi \left( \sigma_c \left( \sigma_c + \frac{2}{\beta_p} \zeta_c \right) + \sigma_s \left( \sigma_s + \frac{2}{\beta_p} \zeta_s \right) \right) \quad (29)$$

This allows the motion to be written as:

$$\begin{aligned} v_p(\tau) = & \frac{2\beta}{\rho\beta_p} v_0 \sin\left(2\pi\frac{\beta_p}{\beta}(\tau - \tau_0)\right) (\sigma_c f_c(\tau - \tau_0) + \sigma_s f_s(\tau - \tau_0)) \\ & + \frac{2\beta}{\rho\beta_p} v_0 \cos\left(2\pi\frac{\beta_p}{\beta}(\tau - \tau_0)\right) (\sigma_c f_s(\tau - \tau_0) - \sigma_s f_c(\tau - \tau_0)) \\ & + \frac{2}{\rho\beta_p} 2\pi x_0 \sin\left(2\pi\frac{\beta_p}{\beta}(\tau - \tau_0)\right) ((\beta_p \sigma_s + 2\zeta_s) f_c(\tau - \tau_0) - (\beta \sigma_c + 2\zeta_c) f_s(\tau - \tau_0)) \\ & + \frac{2}{\rho\beta_p} 2\pi x_0 \cos\left(2\pi\frac{\beta_p}{\beta}(\tau - \tau_0)\right) ((\beta_p \sigma_c + 2\zeta_c) f_c(\tau - \tau_0) + (\beta \sigma_s + 2\zeta_s) f_s(\tau - \tau_0)) \end{aligned} \quad (30)$$