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	Introduction

1. Introduction

1.1 Problem That I am Solving:

As part of this project I developed a web based tool which will generate a .ROBOT script for testing various Negative triggers. The script generated by this tool is readily executable without any additional changes or efforts.

1.2 Background Information:

In my current job as part of functional test team, my primary responsibilities includes testing of various new L2 and L3 routing functionality.

Typical tasks involved our day to day job are:

- a) Designing test network topology.
- b) Write FTP (Functional Test Plan).
- c) Build the testbed.
- d) Automate all the TCs (test cases) in FTP.
- e) Perform Testing using scripts developed.

Each FTP contains good amount (approximately 30%) of Negative TCs. In our company we use ROBOT frame work for our automation.

Typical Steps involved in a Negative TC are:

- a) Load Initial Configuration on all the devices in the testbed.
- b) Perform Checks in Steady state Check that all primary protocols are UP and control and Forwarding Plane entries exists as expected.
- c) Perform Negative Trigger on DUT (Device Under Test)
- d) Check again all primary protocols are UP and control and Forwarding Plane entries exists as expected (after negative trigger)
- e) Perform core functionality check, to ensure DUT is recovered after Negative trigger.

Typically testers will write KW (Keywords – Equivalent to Functions/Subroutines in other languages) for functional TCs (which covers steps# a, b, d and e mentioned above). For Negative Triggers, the only additional step is #c. This tool reuses the KWs already developed by the tester for any kind of Checks and only adds script snippet related to Negative triggers and any common checks.

Here are the typical Negative Triggers we use:

- a) Flap Protocols Protocols like OSPF, ISIS, BGP, MPLS, etc.
- b) Restart Daemons Daemons like RPD, L2ALD, Chassisd, etc.
- c) Links Flap Core links, access links, etc.
- d) High Availability Tests GR, NSR, ISSU, etc.

Advantages of this tool:

1. Saves time. Though the time saved per user is just few hours, it will be huge if we consider the total time saved for the whole team.

- 2. Include Common Checks like CPU Hogs, memory leaks, errors in log files, etc Typically testers focus on the checks related to their functionality and tend to ignore common check (due to lck of knowledge or lack of time) and this tool covers such checks by adding KW related to common checks automatically.
- 3. This approach can be extended for other kind of tasks.

2. Requirements

Here is the list of all the Python modules that need to be installed to run my program:

import re

from flask import Flask, render_template, request, url_for, redirect, send_file from werkzeug.datastructures import CombinedMultiDict, MultiDict

3. Description of my Python program

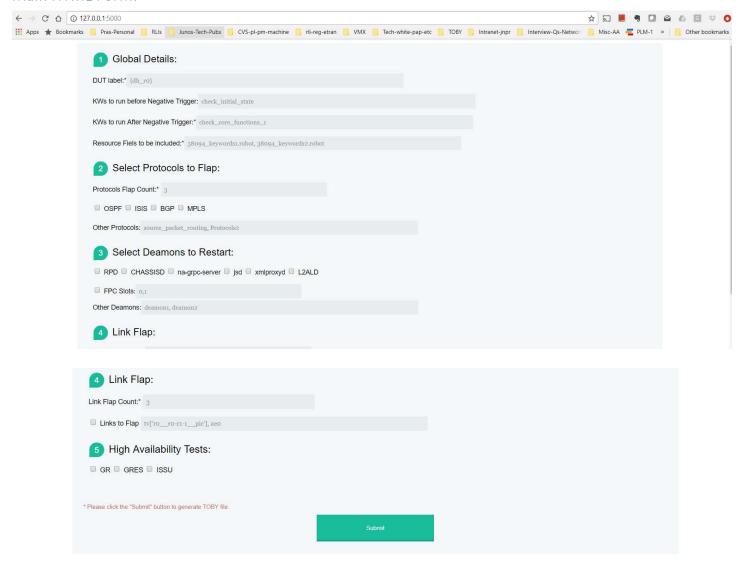
The program starts a webserver (using FLASK) and when users access the root HTML page, it will show a HTML form. Users will enter required fields and clicks on the SUBMIT button. Next the program takes to a different page where the user has option to download the automatically generated .ROBOT file or to go back to the main page to re-submit the form.

Steps involved in my python program execution:

- 1) Start Web server and users can access the main HTML form from http://127.0.0.1:5000/.
- 2) Users will enter the appropriate fields in the form and click on Submit.
- 3) Python program receives the data from HTML page and saves it into a python dictionary.
- 4) Python program reads each key in the dictionary and generates code for corresponding TC and writes it into a .ROBOT file.
- 5) After reading the whole Dictionary and generating and writing all the corresponding TCs, the file is closed and a 2nd HTML page is displayed to the user.
- 6) User has option to download the automatically generated .ROBOT file or to go back to the main page to re-submit the form.

4. Screenshots of the program output

Main HTML Form:



Results Download Page:



Click on the Download Robot File option:



Click on Go to Main Page:

Control goes to the the Main HTML Page, shown above.

5. Conclusion

Using my program a .ROBOT file shown below is generated:

```
*** Test Cases ***
     [Setup] NONE
[Tags] Negative
    59
60
          R····${var}···in·range···1····3
Config-Engine···device_list=r0···cmd_list=deactivate-protocols-ospf·····commit=1
        \ Sleep 2s
\ Config Engine device_list=r0 cmd_list=activate protocols ospf commit=1
          -Sleep
       Run Keyword And Continue On Failure .... check_core_functions_1
   69
70
     [Documentation] Deacitave then activate protocols ISIS \{\} multiple times [Setup] ... NONE ... [Tags] ... Negative ...
    :FOR····${var}···in·range···1····3
·\··Config·Engine···device_list=r0···cmd_list=deactivate·protocols·isis·····commit=1
·\··Sleep···2s
79
80
           Config Engine device_list=r0 cmd_list=activate protocols isis commit=1
          Sleep
       Run Keyword And Continue On Failure .... check_core_functions_1
```

```
[Setup] NONE
[Tags] Negative
  :FOR····${var}···in·range···1····3
·\··Config Engine···device_list=r0···cmd_list=deactivate protocols bgp·····commit=1
·\·Sleep···2s
      \ Config Engine device_list=r0 cmd_list=activate protocols bgp commit=1
        Sleep
      Run Keyword And Continue On Failure .... check_core_functions_1
  [Setup] NONE
[Tags] Negative
109
110
   ${test} = - Execute Cli Command On Device - - device={dh_r0} - command=restart routing
Run Keyword And Continue On Failure - - - - check_core_functions_1
     Run Keyword And Continue On Failure
  [Setup] NONE
[Tags] Negative
   S{test} = Execute Cli Command On Device device={dh_r0} command=restart chassisd Run Keyword And Continue On Failure check_core_functions_1
```

6. Python program

```
import os, re
from flask import Flask, render_template, request, url for, redirect, json, send file
from werkzeug.datastructures import CombinedMultiDict, MultiDict
app = Flask(__name__)
@app.route('/',methods=['GET', 'POST'])
def form1():
    if request.method == "POST":
       create_toby_file(request.values)
        #return render template('download toby file.html')
       return render template('download toby file2.html')
       return render template('toby script generator-v1.html')
@app.route('/return file')
def return file():
   return send file('toby file 1.robot')
@app.route('/results', methods=['GET', 'POST'])
def form1results():
   if request.method == "POST":
       return render template('form1result.html')
    else:
       return render template('form1result.html')
def create toby file(data from form):
   print ("inside create_toby_file")
form_dict = data_from_form.to_dict()
   print(form dict)
    patterns = [',']
    dut_handle = form_dict.get('dut_handle', 'dh_none')
    kw0 = form_dict.get('kw0')
    if (kw0):
       if re.search(',', kw0):
           kw0 = kw0.split(',')
           kw0 = [x.strip() for x in kw0]
       else:
           kw0 = kw0.strip()
    kw1 = form dict.get('kw1')
    if (kw1):
        if re.search(',', kw1):
           kw1 = kw1.split(',')
           kw1 = [x.strip() for x in kw1]
       else:
           kw1 = kw1.strip()
    fr = open("C:\\Users\\pgudipati\\Me-Pras-Cloud\\Technical-Docs\\Python-UCSC\\Project\\toby file 1.robot",
' w')
    fr.write('''#=======\n''')
    fr.write('''*** Settings ***\n''')
    fr.write('''#=======\n''')
    fr.write('''Documentation\n''')
   fr.write('''
                                                          : \n''')
                                   Author
                                                        : \n''')
   fr.write('''
                                   JTMS DESCRIPTION
                   . . .
   fr.write('''
                                   RLI
                                                          : \n''')
                   . . .
    fr.write('''
                                                           : \n''')
                                   DESCRIPTION
                   . . .
                                                          : \n''')
   fr.write('''
                                   TECHNOLOGY AREA
                    . . .
   fr.write('''
                                  MIN SUPPORT VERSION : \n''')
                   . . .
                                                          : \n''')
                                  FEATURE
SUB-AREA
    fr.write('''
                   . . .
                                                           : \n''')
   fr.write('''
                   . . .
   fr.write('''
                                                          : \n''')
                                  MPC/FPC TYPE
                   . . .
                                                          : \n''')
   fr.write('''
                                   CUSTOMER PR
PLATFORM
                   . . .
    fr.write('''
                                                           : \n''')
                   . . .
   fr.write('''
                                  VIRTUALIZATION SUPPORT : \n''')
                    . . .
   fr.write('''
                                                           : \n''')
                                   DOMAIN
                   . . .
```

```
fr.write(''' ...
fr.write(''' ...
fr.write(''' ...
fr.write(''' ...
                                                 : \n''')
                            TESTER
                         JPG : \n''')

MARKET USE CASES : \n''')
                             Supporting files to run script - \n''')
   fr.write('''\n''')
   fr.write('''Library
                       BuiltIn\n''')
   fr.write('''Library
                      Collections\n''')
   fr.write('''Library
                      String\n''')
                     inpr/toby/system/jvision/jvision.py\n''')
jnpr/toby/init/init.py\n''')
   fr.write('''Library
   fr.write('''Library
   fr.write('''Resource
                      jnpr/toby/Master.robot\n''')
   fr.write('''Resource
                       jnpr/toby/toby.robot\n''')
   fr.write('''Resource
                       jnpr/toby/engines/verification/verification.robot\n''')
   fr.write('''Resource jnpr/toby/engines/verification/verification jvision.robot\n''')
   resource files = form dict.get('resource files')
   if resource files:
      if re.search(',', resource files):
         resource files = resource files.split(',')
         resource files = [x.strip() for x in resource files]
      else:
         resource files = resource files.strip()
   if isinstance(resource files, list):
      for i in resource files:
         fr.write('''Resource
                             '''+i+'''\n''')
     fr.write('''Resource '''+resource files+'''\n''')
   fr.write('''\n''')
   fr.write('''Suite Setup Run Keywords\n''')
                ... Toby Suite Setup\n''')
   fr.write('''
   fr.write('''\n''')
   fr.write('''Suite Teardown Run Keywords\n''')
   fr.write(''' ...
                         Toby Suite Teardown\n''')
   fr.write('''\n''')
   fr.write('''Test Setup Run Keywords\n''')
   fr.write(''' ...
                         Toby Test Setup\n''')
   fr.write('''\n''')
   fr.write('''Test Teardown Run Keywords\n''')
   fr.write('''
                         Toby Test Teardown\n''')
   fr.write(''' \n''')
   fr.write('''#======\n''')
   fr.write('''*** Test Cases ***\n''')
   fr.write('''#=======\n''')
   fr.write(''' \n''')
# TCs for Protocols Flapping:
   proto flap count = form dict.get('prot flap count')
   ospf flag = form dict.get('ospf', 'No')
   if (ospf flag == "yes"):
      fr.write('''#########\n''')
      fr.write('''Tc Flap OSPF\n''')
      fr.write('''######## \n''')
      fr.write(''' [Documentation] Deacitave then activate protocols ospf \{\} multiple times \n''')
fr.write(''' [Setup] NONE \n''')
      fr.write(''' :FOR ${var} in range 1 ''' + str(proto flap_count) + '''\n''')
      fr.write('''
                      \\ Config Engine device list=r0 cmd list=deactivate protocols ospf
commit=1\n''')
      commit=1\n''')
      fr.write('''
                                 2s\n''')
                   \\ Sleep 2s\n''')
Run Keyword And Continue On Failure ''' + kw1 + '''\n\n''')
      # isis
   isis flag = form dict.get('isis', 'No')
   if (isis flag == "yes"):
      fr.write('''#########\n''')
```

```
fr.write('''Tc Flap isis\n''')
   fr.write('''######### \n''')
   commit=1\n''')
   fr.write(''' \\ Sleep 2s\n''')
fr.write(''' \\ Config Engine device_list=r0 cmd_list=activate protocols isis
commit=1\n''')
   fr.write('''
            \\ Sleep
                  2s\n''')
          Run Keyword And Continue On Failure
   # bgp
  bgp_flag = form_dict.get('bgp', 'No')
  if (bgp flag == "yes"):
   fr.write('''#########\n''')
   fr.write('''Tc Flap bgp\n''')
   fr.write('''######## \n''')
    fr.write(''') \quad [Documentation] \quad Deacitave \ then \ activate \ protocols \ bgp \ \{\} \ multiple \ times \ \n''') 
   fr.write(''' [Setup] NONE \n''')
commit=1\n''')
   fr.write('''
commit=1\n''')
          \\ Sleep 2s\n''')
Run Keyword And Continue On Failure ''' + kwl + '''\n\n''')
   fr.write('''
   # mpls
 mpls flag = form dict.get('mpls', 'No')
  if (mpls flag == "yes"):
   fr.write('''########\n''')
   fr.write('''Tc Flap mpls\n''')
   fr.write('''######## \n''')
commit=1\n''')
   fr.write('''
commit=1\n''')
   fr.write('''
   fr.write('''
# TCs for Deamons Restart:
  # RPD restart
  rpd flag = form dict.get('rpd', 'No')
  if (rpd_flag == "yes"):
   fr.write('''#########\n''')
   fr.write('''Tc RPD restart\n''')
   fr.write('''######## \n''')
   fr.write(''' ${test} = Execute Cli Command On Device device=''' + dut handle + '''
command=restart routing\n''')
```

```
#chassisd
  chassisd_flag = form_dict.get('chassisd', 'No')
if (chassisd flag == "yes"):
    fr.write('''#########\n''')
    fr.write('''Tc chassisd restart\n''')
     fr.write('''######## \n''')
fr.write(''' ${test} = Execute Cli Command On Device device=''' + dut_handle + '''
command=restart chassisd\n''')
    # TCs for Links Flap:
  fr.close()
  return True
if __name__ == "__main__":
  #host = os.getenv('IP', '127.0.0.1')
  #port = int(os.getenv('PORT', 5000))
  #print (host, port)
  app.run()
```