

Prakhar Gupta

Curriculum Vitae

PhD Student
Clemson University
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🌐 **Prakhar's Website**
🐙 Github in LinkedIn



Education

2025 **Ph.D., Automotive Engineering**, *Clemson University ICAR*, Greenville.

Research topics: robotics controls and planning, reinforcement learning, off-road driving controls, optimal control, connected autonomous vehicles, sim2real

GPA: 3.97/4.0

Research Question "How can we leverage the individual strengths of model-based and learning-based methods to improve off-road driving controls and planning algorithms under unknown dynamics?"

2022 **MS, Automotive Engineering**, *Clemson University ICAR*, Greenville.

Capstone Project: Deep Orange 13 (Full scaled high speed autonomous off-road vehicle)

GPA: 3.97/4.0

2017 **B.Tech., Mechanical Engineering**, *Manipal University*, India.

Thesis topic: Vehicle dynamics simulation model and validation (Distinction)

Research & Development Experience

Graduate Research Assistant, *Clemson University*

2022-2025 **Learning augmented model based optimization controls.**

Advisor: **Dr. Yunyi Jia**, Associate Professor, Clemson University

Funding: Department of Defense through VIPR-GS.

- Formulated and investigated a residual reinforcement learning architecture to handle modeling mismatches and unmodeled system dynamics to improve driving performance
- Research aims to reduce data dependency by leveraging nominal models and increase generalization of controller across different driving conditions
- Offline and online learning to enable life-long adaptation on vehicle using vision foundation models
- Validating simulation results on a drive-by-wire vehicle on off-road terrains ([Off-road Autonomous Video](#))

2022-2025 **Energy efficient cooperative autonomous driving.**

Advisors: Dr. Yunyi Jia, **Dr. Ardalan Vahidi**, Clemson University

Funding: Department of Energy through Argonne National Laboratory.

- Controls and planning research to improve energy efficiency through V2V, V2I connectivity using optimal control and planning algorithms like Model Predictive Control (MPC) and Pontryagin's minimum principle.
- Experimental results on an in-house drive-by-wire Mazda CX7 showed up to 36% improvements with state-of-the-art lane switching and acceleration strategy on connected traffic corridors
- Expert skills for on-vehicle control deployment using MPC and other state-of-the-art controllers

2024 **Physics Informed Future Video Frame Prediction.**

Advisor: **Dr. Siyu Huang**, Assistant Professor, Clemson University

- Surveyed and analyzed existing physics informed video prediction methods in computer vision
- Surrounding agents' behavior prediction can improve AV planner robustness. In this work, we improve the future scene prediction performance of a Conditional Generative Adversarial Network (GAN)
- The GAN was conditioned using kinematic constraints was developed to improve blurring in long-term future frame prediction for autonomous driving planning
- Project webpage: [conditional-GAN for video prediction](#)

2025 **Denial of Service Attacks on Connected Automated Vehicles.**

Advisors: Dr. Yunyi Jia, Dr. Ardalan Vahidi, Clemson University

- Investigating effects of cyber-security attacks on connected autonomous vehicles in urban traffic scenarios.
- We show experimentally that intention sharing among connected vehicles can mitigate the impact of denial-of-service attacks on the platoon.
- Communications and vehicle networking using CAN, Ethernet, wireless short range communications for V2X.

2021-2022 **Deep Orange 13.**

Advisor: [Dr. Chris Paredis](#), Professor Emeritus, Clemson University

Funding: Department of Defense through VIPR-GS.

- Utilized systems engineering principles to arrive at engineering requirements for mission critical autonomy needs.
- Implemented fully autonomous navigation for offroad driving using cameras, lidars, GNSS over ROS (Robot Operating Software) on physical small and full scaled platforms
- Designed and developed vehicle controls systems and safety architecture using model based engineering for embedded platform
- H-i-L and S-i-L testing for vehicle autonomy
- Autonomous Driving: [Unmanned Autonomous Deep Orange 13-14](#), [Manned Autonomous](#)

2021-2022 **Collaborative monitoring of road conditions.**

Advisors: Dr. Yunyi Jia, Clemson University

Funding: Department of Transportation

- Research aims to utilize deep learning and cloud architecture to augment road condition monitoring
- Multi modal object detection neural networks were trained to identify road defects that need attention using just smartphone sensors like IMU and camera. [Research Poster](#), [Award](#)

[CAE and Multibody Dynamics Engineer, Mercedes Benz R&D India](#)

2017-2020 **Freightliner Chassis Engineering Simulation.**

- Designed and set up a new simulation process to evaluate K&C characteristics of Freightliner custom chassis suspensions using multi-body approach. Facilitated vehicle evaluation for FMVSS136 regulation by analyzing sensitivity to K&C data.
- Simulated entire vehicle on a digitalized rough road in Altair MotionSolve (multi-body) for dynamics and durability evaluations to reduce physical testing costs. This lowered simulation times by 80% as compared to existing FEA processes.
- Used FEA solvers (NASTRAN, Abaqus) to analyze and quantify durability performance of Freightliner motorhome chassis.

Selected Projects

2021 **Stability of Tractor-Trailer Systems.**

Course Instructor: [Dr. Beshah Ayalew](#), Professor, Clemson University

- Analysis of dynamics of tractor-trailer combinations, their stability issues and control solutions
- LQR based yaw control of vehicle system
- Report Link: [Stability Analysis Report](#), [Control Design Report](#)

2021 **Autonomous Driving Robot.**

Course Instructor: [Dr. Venkat Krovi](#), Professor, Clemson University

- Developed and implemented ROS python and C++ nodes to enable, on a Turtlebot3 robot: Obstacle avoidance, Navigation, Line following, Traffic sign detection, Object tracking
- Utilized pre-trained deep learning models for object recognition
- GitHub: [ProjectCode](#)

2021 **Parallel Robots: Hexapod Inverse Kinematics.**

Advisor: [Dr. Venkat Krovi](#), Professor, Clemson University

- Implemented a planar cable robot and designed controller using Quanser's Hexapod hardware in HiL simulation
- Formulated inverse and forward kinematics for the cable robot

Skills

Topics	Reinforcement Learning, Optimal Control, Optimization, Sim2real
Coding	Python, C++, PyTorch, Git
Robotics	Gazebo, ROS, ROS2, Autoware software stack, Systems integration
Simulation & Modeling	MATLAB, Simulink, CarSim, Project Chrono, Altair MotionSolve, Hyperworks, ANSA, Solidworks, Carla, Siemens NX
Solvers	Acados, Gurobi, NASTRAN
RT Control	Arduino, New Eagle Raptor and other Real-Time control modules
OS	Windows, Linux, Raspberry Pi
Certificates	Nanodegree: Intro to Self-Driving Cars, Udacity (view), DC201x: Dynamics and Control, Universidad Politecnica de Valencia (view), Machine Learning, Stanford University (view)

Fellowships & Awards

- 2024 **Best Paper Award**, TRB Road User Measurement and Evaluation Committee, in the 103rd TRB Annual Meeting
- 2023 **2nd Place, Best Paper Award** at IEEE IAVVC 2023 conference
- 2021 **First prize for research poster** in Centre for Connected Multimodal Mobility Annual Conference 2021
- 2020 Received TATA Fellowship (full tuition grant \$36,000) to pursue MS Automotive Engg. at CU-ICAR
- 2019 Won **Team Impact Award** at Daimler for rapid and efficient development projects in CAE.
- 2016 Overall 2nd place, Formula Bharat 2015 (national student competition) – winners in 7 categories.
- 2016 National record for best acceleration timing of an FSAE race-car in 2015.

Publications

Journal Articles

- 2025 **Prakhar Gupta**, Jonathon M Smereka, and Yunyi Jia. Reinforcement learning compensated model predictive control for off-road driving on unknown deformable terrain. *arXiv preprint [arXiv:2408.09253](#)*, Under Review at *IEEE Transactions on Intelligent Vehicles*, 2025.
- 2025 Tyler Ard, Jihun Han, **Prakhar Gupta**, Dominik Karbowski, Yunyi Jia, and Ardalan Vahidi. Energy-efficient automated driving for everyday maneuvers: Fundamentals to experimentation. *IEEE Control Systems Letters, American Control Conference*, 2025.

In Conference Proceedings

- 2025 **Prakhar Gupta**, Jonathon M Smereka, and Yunyi Jia. Actor-critic cooperative compensation to model predictive control for off-road autonomous vehicles under unknown dynamics. In *IEEE ICRA*, 2025. *Arxiv preprint*.
- 2025 Hannah Musau, Denis Ruganuzza, Debbie Indah, Arthur Mukwaya, Nana Kankam Gyimah, Ashish Patil, Mayuresh Bhosale, **Gupta, Prakhar**, Judith Mwakalonge, Yunyi Jia, Dariusz Mikulski, David Grabowsky, Jae Dong Hong, and Saidi Siuhi. A review of off-road datasets, sensor technologies and terrain traversability analysis. Technical Report 2025-01-8339, SAE Technical Paper, 2025.
- 2024 **Prakhar Gupta** and Yunyi Jia. Safety-regulated reinforcement learning compensated model predictive control for ground vehicles with unknown disturbances. Technical report, SAE Technical Paper, GVSETS, 2024.
- 2024 Jihun Han, Tyler Ard, **Prakhar Gupta**, Rongyao Wang, Ardalan Vahidi, Yunyi Jia, and Dominik Karbowski. Human driver interaction with an eco-speed advisory system in connected vehicles: Simulation and experimental results. In *Proceeding of Transportation Research Board*, 2024. **Winner, Best Paper Award**.
- 2024 Mayuresh Bhosale, **Prakhar Gupta**, Rahul Prasanna Kumar, and Yunyi Jia. Ai-enhanced proactive model predictive control for off-road autonomous vehicles. Technical report, SAE Technical Paper, GVSETS, 2024.
- 2023 **Prakhar Gupta**, Rongyao Wang, Tyler Ard, Jihun Han, Dominik Karbowski, Ardalan Vahidi, and Yunyi Jia. An x-in-the-loop (xil) testing framework for validation of connected and autonomous vehicles. In *2023 IEEE International Automated Vehicle Validation Conference (IAVVC)*, pages 1–6. IEEE, 2023. **2nd Place, Best Paper Award**.

Leadership Positions

- 2021-2022 **Lead Autonomy and Controls Engineer**, Deep Orange 13, Clemson University.
- 2014-2016 **Lead Vehicle Dynamics Engineer**, FSAE Team, Manipal University.

Teaching Assistantship

- 2022-2024 **AuE8350: Automotive Electronics Integration**, Dr. Yunyi Jia, Clemson University.
- 2024-2025 **AuE8240: Autonomous Driving Technologies**, Dr. Yunyi Jia, Clemson University.

Community Engagement

- 2023 **Robotics for kids**, *Taught kids the basics of robotics using visual block programming and drawing robots as a STEAM initiative at Artishpere Greenville festival.*
- 2019 **Formula Student**, *Design Judged undergraduate students' engineering skills and race-cars; conducted feedback sessions to mentor them.*
- 2019 **Habitat for Humanity**, *Volunteered to paint homes in underprivileged neighborhoods. Initiative was to recondition their homes for the festive season. Cleaning drive for the city lake.*
- 2018 **Mobile Kids, a Daimler Initiative**, *Worked in a team of 20 members to impart traffic education events to over 100 school children. Identified traffic hazards and missing traffic management infrastructure in school vicinity and fulfilled them with the help of an NGO called 'Pothole Raja'.*