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**Education** 

**Master of Computer Science** 

Fredericton, NB, Canada

UNIVERSITY OF NEW BRUNSWICK

Bachelor of Computer Engineering SHAHID BEHESHTI UNIVERSITY

Tehran, Iran

**Experience** 

**Human-Robot Interaction Laboratory** 

UNB, Fredericton, Canada

**RESEARCH ASSOCIATE**September 2023 - Present

Applied UI/UX principles to Teleoperation interfaces, in order to achieve better user performance and experience. Implemented automation for robot network configuration.

Used ROS and tkinter along with Python3 to develope the interface and operate the robot

**Robotics Laboratory** 

SBU, Tehran, Iran

RESEARCH ASSOCIATE

July 2021 - Present

Applied Reinforcement Learning, and Data Mining principles to Soccer Simulation 2D League for RoboCup Competitions to analyze and improve team performance

Applied the same principles in addition to Obstacle avoidance, and Navigation algorithms to develope A.I. for SBU Omni-Directional Robot, and resolved sensor inaccuracies to enhance high-precision mapping capabilities.

Worked with C++, Pandas, TensorFlow, ROS, Webots, Docker, and Catkin

**Introduction to Game Developement** 

UNB, Fredericton, Canada

January 2024 - April 2024

Instructor: Daniel J. Rea; Responsible for marking and reviewing the lab assignments

Used Godot Engine.

**TEACHING ASSISTANT** 

**Introduction to Robotics** 

SBU, Tehran, Iran

INSTRUCTOR June 2023 - August 2023

Instructed for summer workshops, in order to recruit new passionate individuals for the lab.

Taught Fandamentals of Robotics, Machine Learning, A.I. Algorithms, and Simulation concepts

**Concealand Game Studio** 

SBU, Tehran, Iran

**GAME DEVELOPER INTERN** February 2023 - April 2023

Applied Reinforcement Learning, Imitation Learning, and Curriculum Learning for Procedural Content Generation (PCG, procedural animation for a humanoid character) to reduce the animation state complexity for artists.

Worked with Unity3D IK frameworks, animation rigging package, and ML model training.

**Introduction to Algorithms Design** 

SBU, Tehran, Iran

**TEACHING ASSISTANT** 

September 2022 - December 2022

Instructor: Ramak Ghavamizadeh; Responsible for teaching labs and designing lab assignment problemsets.

Used C++ and bash scripts to automate the test units for marking.

**Introduction to Robotics** 

SBU, Tehran, Iran

INSTRUCTOR

June 2022 - September 2022

Instructed for summer workshops, in order to recruit new passionate individuals for the lab.

Taught Fandamentals of Robotics, Machine Learning, A.I. Algorithms, and Simulation concepts

**NAO Research and Development Group** 

SBU, Tehran, Iran

ROBOTICS ENGINEER INTERN

July 2021 - September 2021

Responsible for Robot motion and A.I.

The project was implementing an autonomous control system for SBU omni-directional robot. Applied Localization and Mapping algorithms using ROS2 slam libraries with LIDAR sensors.

Applied using Python3.

Fixing the 3D Model in Webots which was causing a dynamic motion failure and getting familiar with robot 3D models, URDF and Proto, and the SBU omni-robot structure in Webots.

Setting Up the ROS2 platform for the robot and getting familiar with the ROS2 networking protocols and architectures.

Digital Logic Circuits SBU, Tehran, Iran

TEACHING ASSISTANT February 2019 - June 2019

Instructor: Hamidreza Mahdiani; Responsible for marking concept assignments.

Honors and Awards		
RoboCup 2024 Internationa	l Competitions, Soccer 2D Simula	ation League
RANKED 5TH - AS A MEMBER OF R2	Summer - 2024	
Scholarship from School of BOARD OF GOVERNORS MERIT AWA	<b>New Brunswick</b> Fall - 2023	
	ernational Competitions, Soccer	
League		
RANKED 3RD - AS A MEMBER OF R3	Spring - 2023	
The Best Bachelor Thesis Pr	Summer - 2022	
	e Follower league, Isfahan univer	
RANKED 1ST		Fall - 2021
Konkour, National Universit		
I UITION WAIVED ADMISSION TO SH	ahid Beheshti University - Ranked to	DP 4% Fall - 2017
Skills		
PostgreSQL, Pandas, Redis <b>Simul</b> OpenAl Gym, <b>Knowledge</b> : Comp (Simultaneous Localization and M	lators: Webots Simulator, Unity Game E outer Vision, Image Processing, Signal Pr lapping), Planning, Optimal Control, Evo Operating System(ROS), GIT, Docker, CU	v, Node.JS, React, OpenCV, PyTorch, <b>Databases</b> : SQL, Engine, Robocup Soccer Simulator, Gazebo Robot Simulator, rocessing, ML, ANNs, Reinforcement Learning, SLAM olutionary Algorithms <b>Operating Systems</b> : Windows, JDA
• English : Fluent	• Persian : Native	• Japanese : Intermediate
Publications		
	RENCE ON COMPUTER AND KNOWLEDGE E	
TEAM DESCRIPTION PAPER FOR RO	27 Nov 2023	
Projects (Chronologica	l Order)	
Avatar Robots to Mitigate So		
RESEARCH PROJECT - PROFESSOR	Summer 2024	
[more info]	d of Integrating Social Interfaces	to releoperation
MASTER THESIS - SUPERVISOR: PR	ofessor Daniel J. Rea	Winter 2024
Overcoming Phobias Through	gh Virtual Reality Exposure	
HOBBY PROJECT  Implementation and Analys	is of Binary Index Trees for Histo	Winter 2024
Databases [more info]	is of Billary mack frees for misco	Treat Stockenam
BIG DATA SYSTEMS - PROFESSOR S		Winter 2024
	ntrol Schemes with Mouse and Co	ontroller with Aim
Assistance Techniques and O	•	Fall 2023
	-Decoder LSTM Network Towards	
Summarized Titles From Inc	dian News Reports	
NATURAL LANGUAGES PROCESSING		Fall 2023
Machine Learning and Data Min	tudent Success Based on Preprep	pared Dataset Fall 2023
	t Patterns Using Robotic Arms [m	
BACHELOR THESIS - SUPERVISOR:		
SHEKOFTEH		Summer 2022
Heater/Cooler Control System  EMBEDDED AND REAL-TIME SYSTEM	e <b>m</b> 1s - Professor Seyed-Hosein Attarzai	DEH-NIAKI Fall 2021
Classification of Different Co	7 UII 2021	
FUNDAMENTALS OF COMPUTATION	AL INTELLIGENCE - PROFESSOR HAMED M	ALEK Fall 2021

Simple Bitcoin Estimator Using Regression	
Fundamentals of Computational Intelligence - Professor Hamed Malek	Fall 2021
Survivability Likelihood of Titanic Passengers Data Analysis	
Fundamentals of Computational Intelligence - Professor Hamed Malek	Fall 2021
E-Puck Robot Wall Following and Obstacle Avoidance	
Principles of Robotics - Professor Armin Salimi-Badr	Spring 2021
Analysis and Optimization of the Shazam Algorithm	
MATLAB PROGRAMMING WORKSHOP - PROFESSOR YASER SHEKOFTEH	Fall 2020
A Clone of Skype's Background Blurring on Webcams	
COMPUTER VISION - PROFESSOR ALIREZA TALEBPOUR	Fall 2020
An Implementation of Decaf Compiler	
Compiler Design - Professor Mohammad Reza Bahrami	Fall 2020
Automated Scheduling and Course Selection for Students	
ARTIFICIAL INTELLIGENCE - PROFESSOR MEHRNOUSH SHAMSFARD	Fall 2019
Eight Puzzle Platform and Solver	
ARTIFICIAL INTELLIGENCE - PROFESSOR MEHRNOUSH SHAMSFARD	Fall 2019

## References \_\_\_

Available upon request