

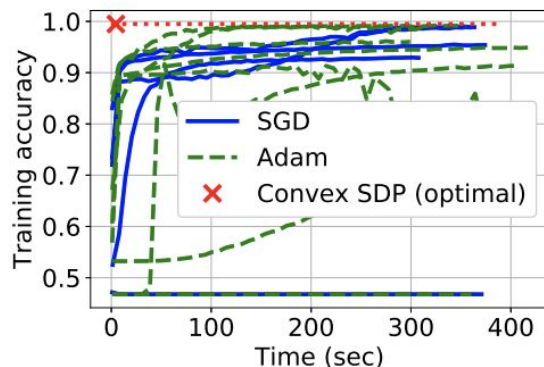
A Convex Approach to Two-Layer Convolutional Neural Network

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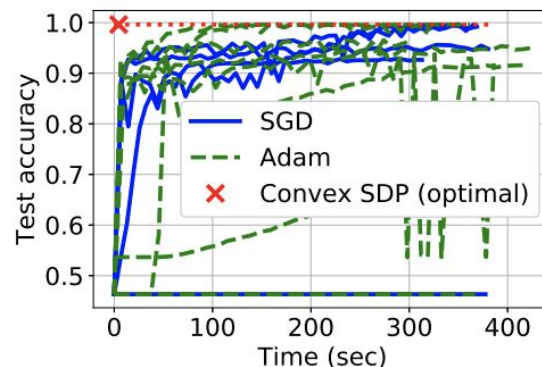
Project Mentor: Burak Bartan

Why convex optimization?

- Optimizer parameters have no influence on model performance
- Hyperparameter tuning becomes less important
- Locally optimal solutions are globally optimal



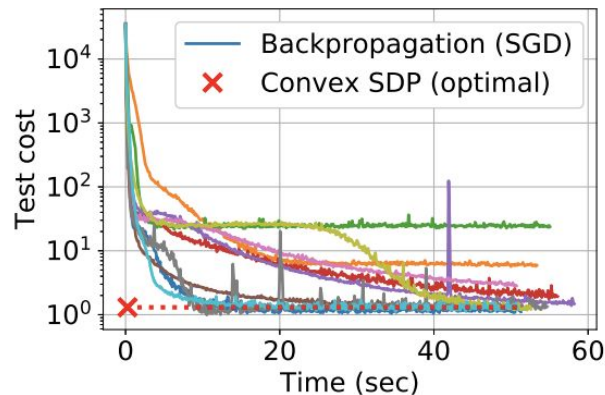
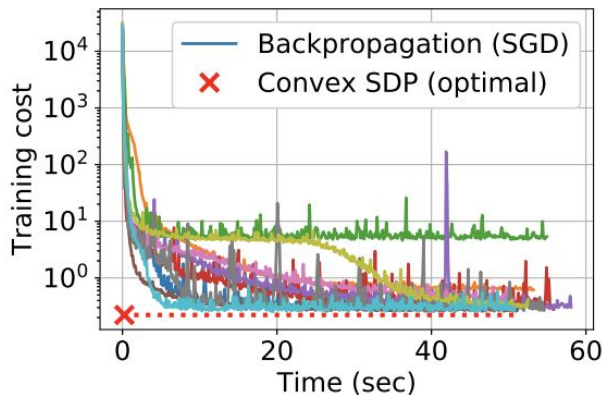
(a) CNN, MNIST, training accuracy



(b) CNN, MNIST, test accuracy

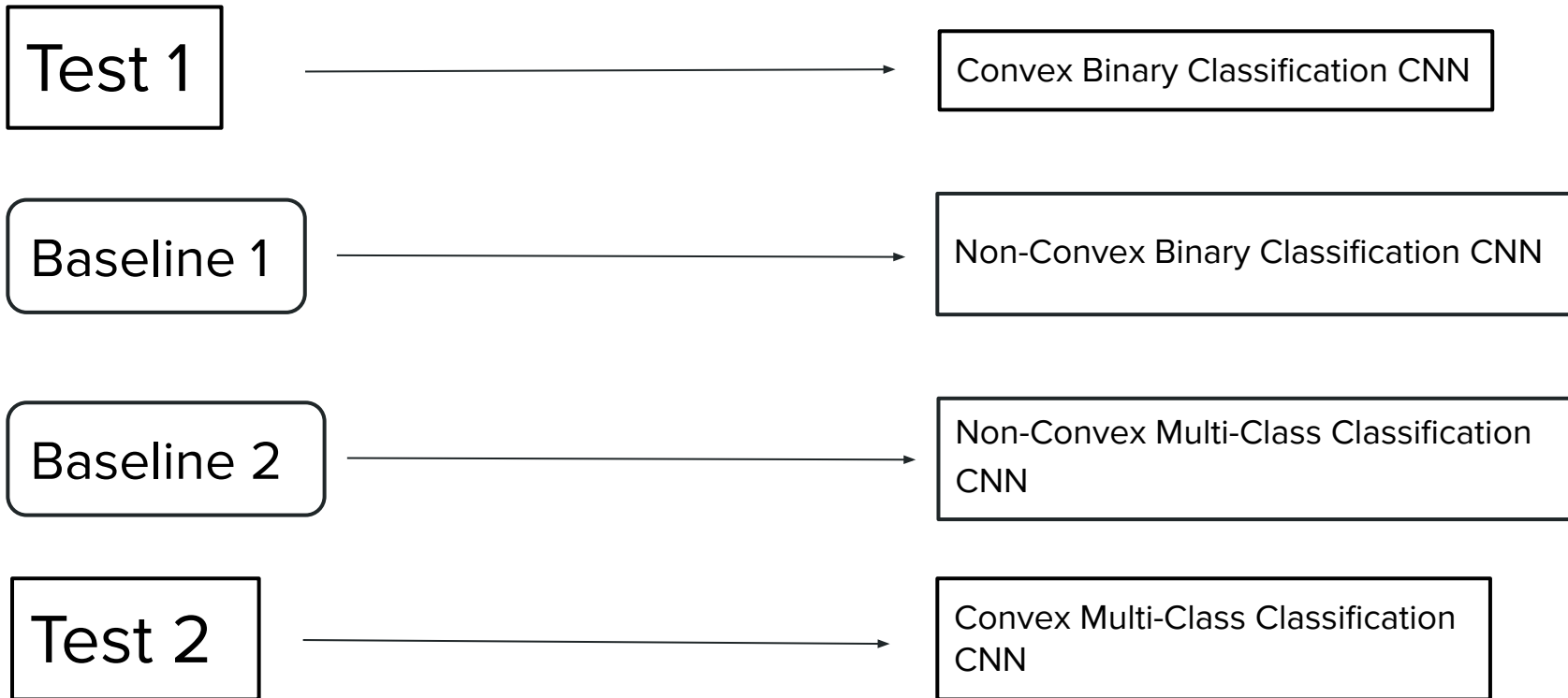
Convex Binary Convolutional Neural Network

- Binary classification accuracy performance on the CNN architecture with global average pooling on MNIST, Fashion MNIST, and Cifar-10 datasets
- Accuracy of stochastic gradient descent is slightly worse than convex Semidefinite Programming (SDP)
- Time that it takes for SGD to converge is consistently larger than the run time for convex SDP



Our Experiments

Datasets: CIFAR-2
CIFAR-10



Convex SDP (Scalar Output)

$$\begin{aligned}
 & \min_{\{Z_k=Z_k^T, Z'_k=Z'^T_k\}_{k=1}^{K/P}} \ell(\hat{y}, y) + \beta \sum_{k=1}^{K/P} (Z_{k,4} + Z'_{k,4}) \\
 & \text{s.t.} \quad \hat{y}_i = a \frac{1}{P} \sum_{k=1}^{K/P} \sum_{l=1}^P x_{i,(k-1)P+l}^T (Z_{k,1} - Z'_{k,1}) x_{i,(k-1)P+l} + b \frac{1}{P} \sum_{k=1}^{K/P} \sum_{l=1}^P x_{i,(k-1)P+l}^T (Z_{k,2} - Z'_{k,2}) + \\
 & \quad + c \sum_{k=1}^{K/P} (Z_{k,4} - Z'_{k,4}), \quad i \in [n] \\
 & \quad \text{tr}(Z_{k,1}) = Z_{k,4}, \quad \text{tr}(Z'_{k,1}) = Z'_{k,4}, \quad k = 1, \dots, K/P \\
 & \quad Z_k \succeq 0, \quad Z'_k \succeq 0, \quad k = 1, \dots, K/P.
 \end{aligned} \tag{95}$$

Convex SDP (Vector Output)

$$\begin{aligned}
 & \min_{Z_k^{(t)}, Z_k'^{(t)}} \ell(\hat{Y}, Y) + \beta \sum_{t=1}^C \sum_{k=1}^{K/P} (Z_{k,4}^{(t)} + Z_{k,4}'^{(t)}) \\
 \text{s.t. } & \hat{Y}_{it} = a \frac{1}{P} \sum_{k=1}^{K/P} \sum_{l=1}^P x_{i,(k-1)P+l}^T (Z_{k,1}^{(t)} - Z_{k,1}'^{(t)}) x_{i,(k-1)P+l} + b \frac{1}{P} \sum_{k=1}^{K/P} \sum_{l=1}^P x_{i,(k-1)P+l}^T (Z_{k,2}^{(t)} - Z_{k,2}'^{(t)}) + \\
 & + c \sum_{k=1}^{K/P} (Z_{k,4}^{(t)} - Z_{k,4}'^{(t)}), \quad i \in [n], t \in [C] \\
 & \text{tr}(Z_{k,1}^{(t)}) = Z_{k,4}^{(t)}, \quad \text{tr}(Z_{k,1}'^{(t)}) = Z_{k,4}'^{(t)}, \quad k \in [K/P], t \in [C] \\
 & Z_k^{(t)} \succeq 0, \quad Z_k'^{(t)} \succeq 0, \quad k \in [K/P], t \in [C],
 \end{aligned} \tag{1}$$

Dataset

Subset of CIFAR-10

- Binary Classification (First two classes)
- Multi-Class Classification (All Classes)

airplane



automobile



bird



cat



deer



dog



frog



horse



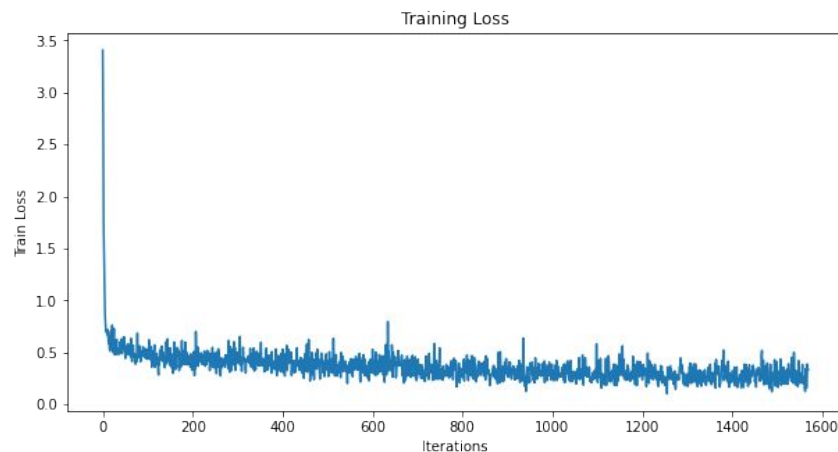
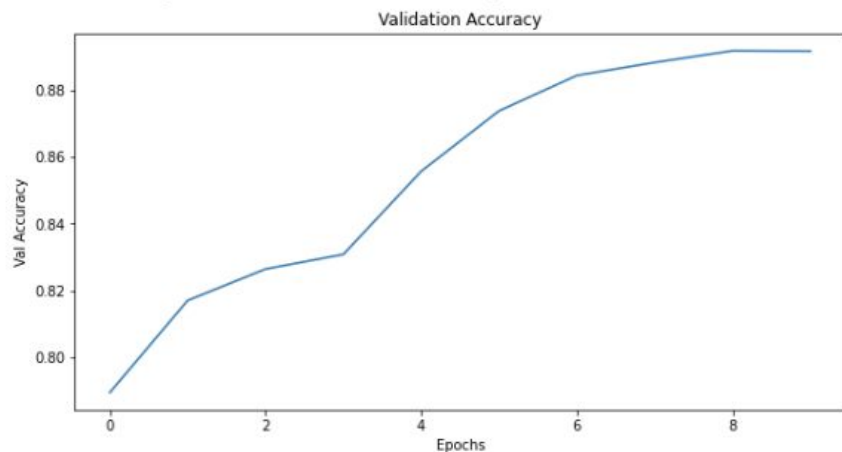
ship



truck



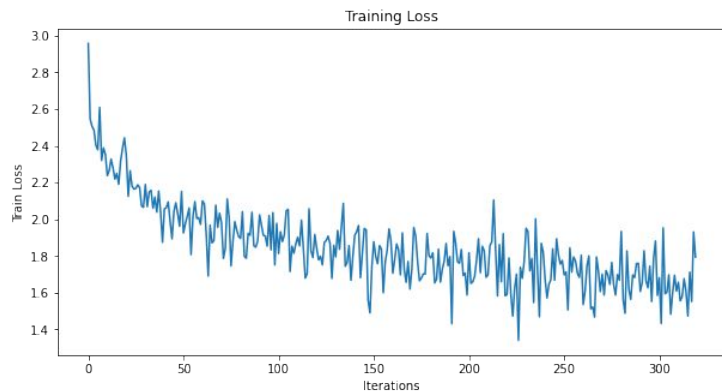
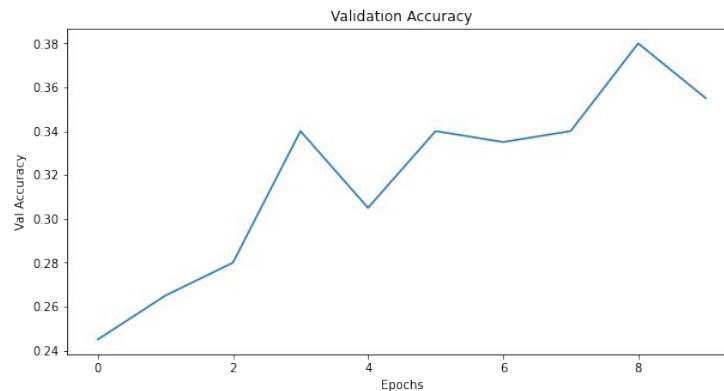
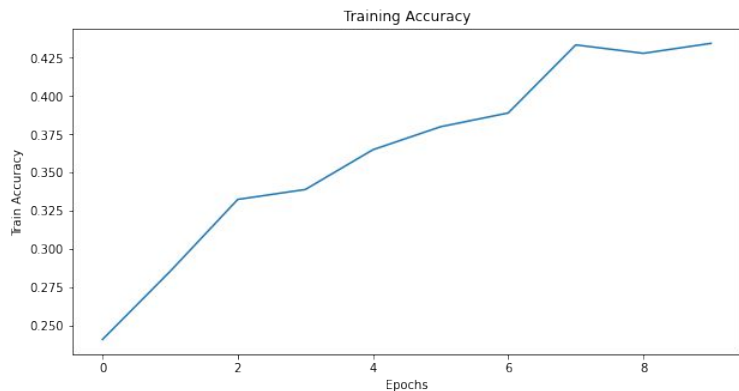
Comparison: Non-convex CIFAR-2 vs Convex Binary CIFAR-2



Non-convex CIFAR-2 Binary CNN Test Accuracy: 88.90%

Convex CIFAR-2 Binary CNN Test Accuracy: 84.05%

Baseline 2: Non-convex Multi-Class CNN



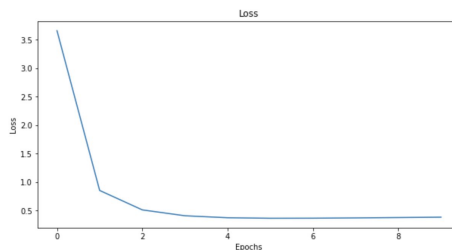
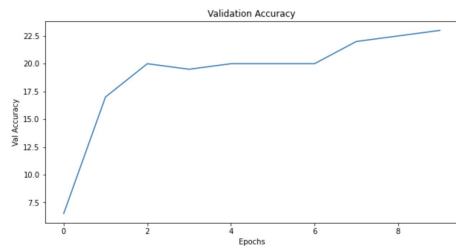
Non-Convex Multi-Class CNN Test

Accuracy: 36.50%

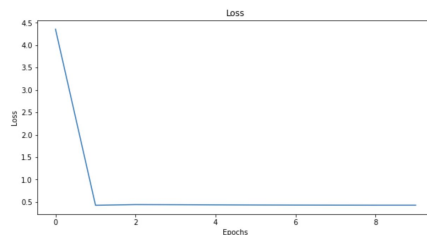
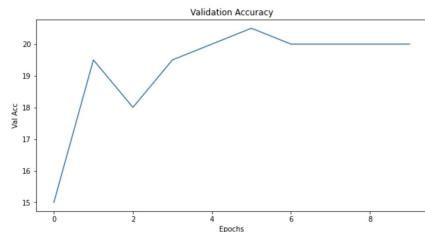
Convex Multi-Class CNN Test Accuracy:

28.55%

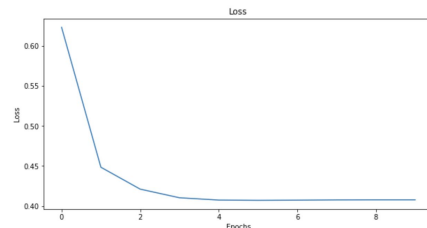
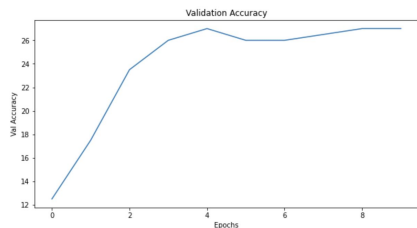
Convex Multi-Class CNN with Different Learning Rates



Learning Rate: 1e-4
Validation Accuracy: 23%



Learning Rate: 1e-2
Validation Accuracy: 20%



Learning Rate: 1e-3
Validation Accuracy: 28.5%

What do we see?

- Convex optimization CNNs have slightly lower but comparable accuracies
 - Pytorch version has a forward implementation built from scratch - not equipped for this
 - Non-controls which are positively skewing our baseline accuracies in comparison to our experiments
- For custom code with convex SDPs, the necessary optimizations were likely inadequate, and therefore the training was slow.

Validity of Using Convex Multi-Class CNNs

- More work needed to fully formulate convex optimization
- Convex methods still show great promise
- Next steps:
 - Layerwise learning
 - Deeper architectures
 - Expanding Dataset