Networking

Chapter 5
Network Layer: Control Plane

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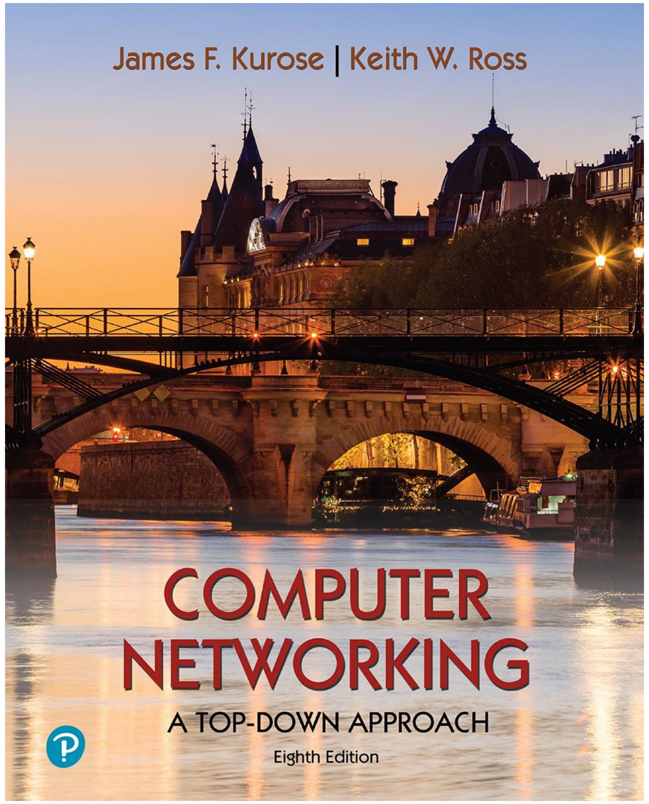


Computer Networking: A Top-Down Approach
8th edition
Jim Kurose, Keith Ross
Pearson, 2020

Network layer control plane: our goals

- understand principles behind network control plane:
  - traditional routing algorithms
  - SDN controllers
  - network management, configuration

- instantiation, implementation in the Internet:
  - OSPF, BGP
  - OpenFlow, ODL and ONOS controllers
  - Internet Control Message Protocol: ICMP
  - SNMP, YANG/NETCONF

Network layer: “control plane” roadmap

- introduction
- routing protocols
  - link state
  - distance vector
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- SDN control plane
- Internet Control Message Protocol

- network management, configuration
  - SNMP
  - NETCONF/YANG

Network-layer functions

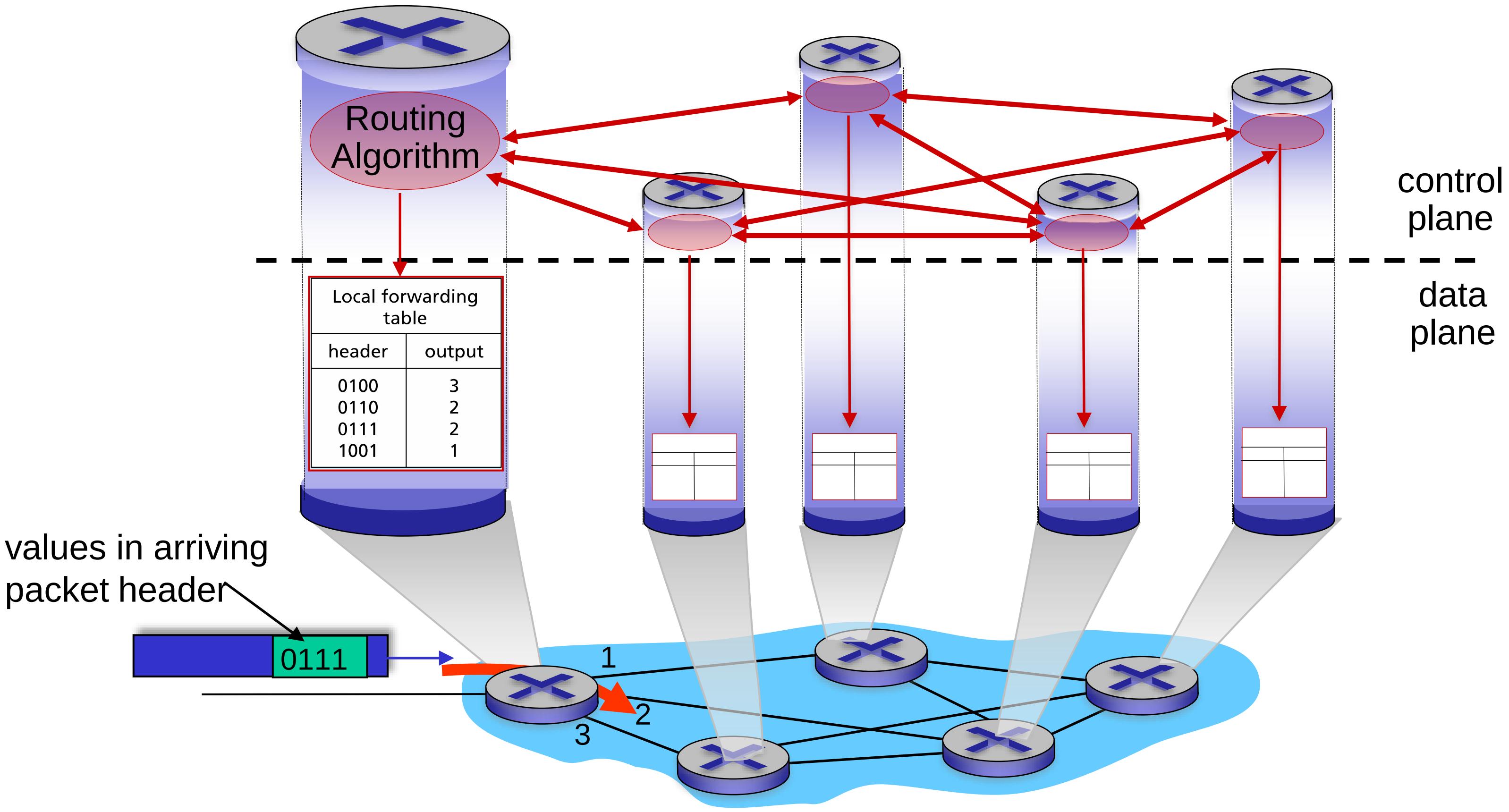
- forwarding: move packets from router's input to appropriate router output — *data plane*
- routing: determine route taken by packets from source to destination — *control plane*

Two approaches to structuring network control plane:

- per-router control (traditional)
- logically centralized control (software defined networking)

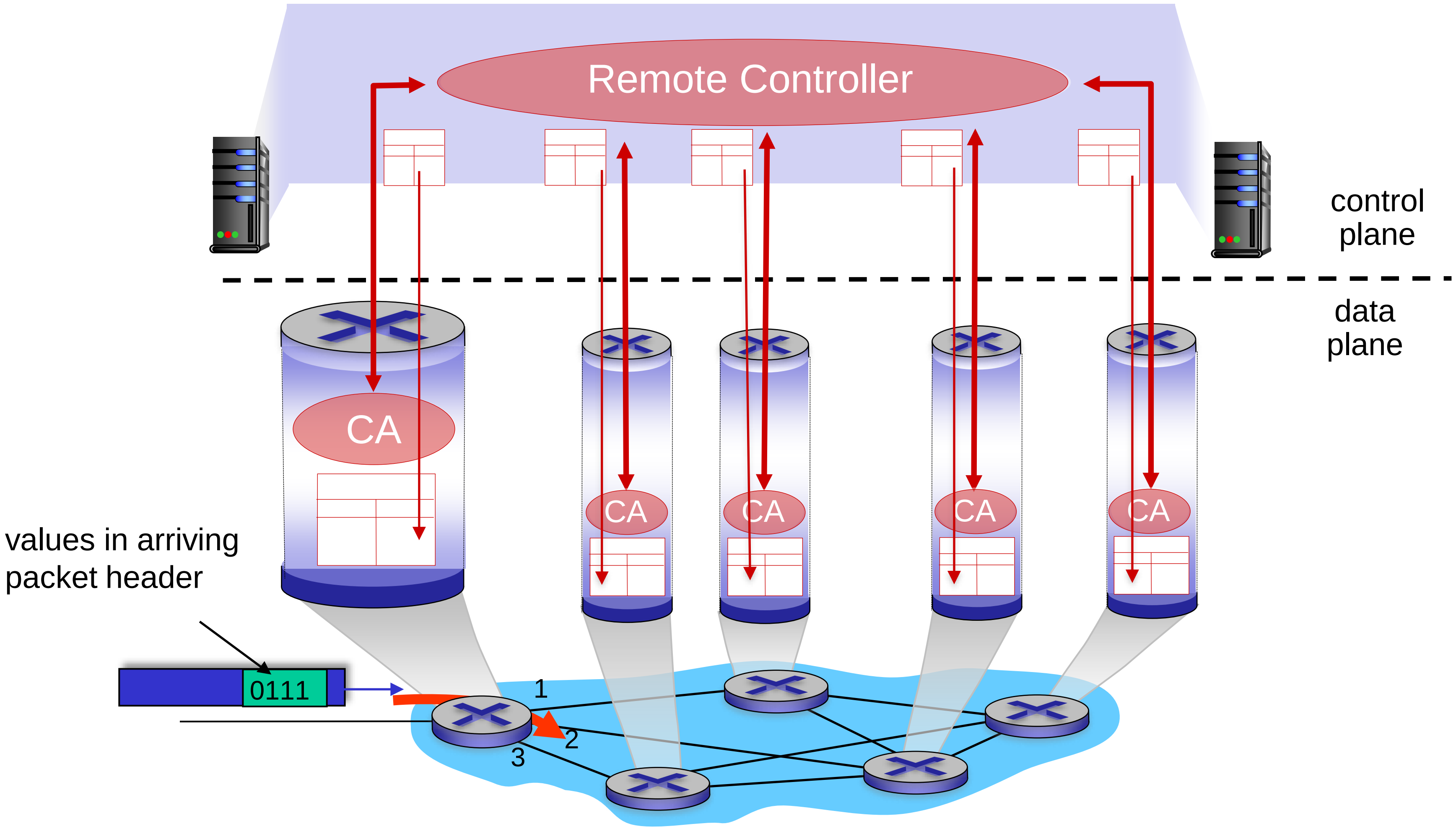
Per-router control plane

Individual routing algorithm components *in each and every router* interact in the control plane



Software-Defined Networking (SDN) control plane

Remote controller computes, installs forwarding tables in routers



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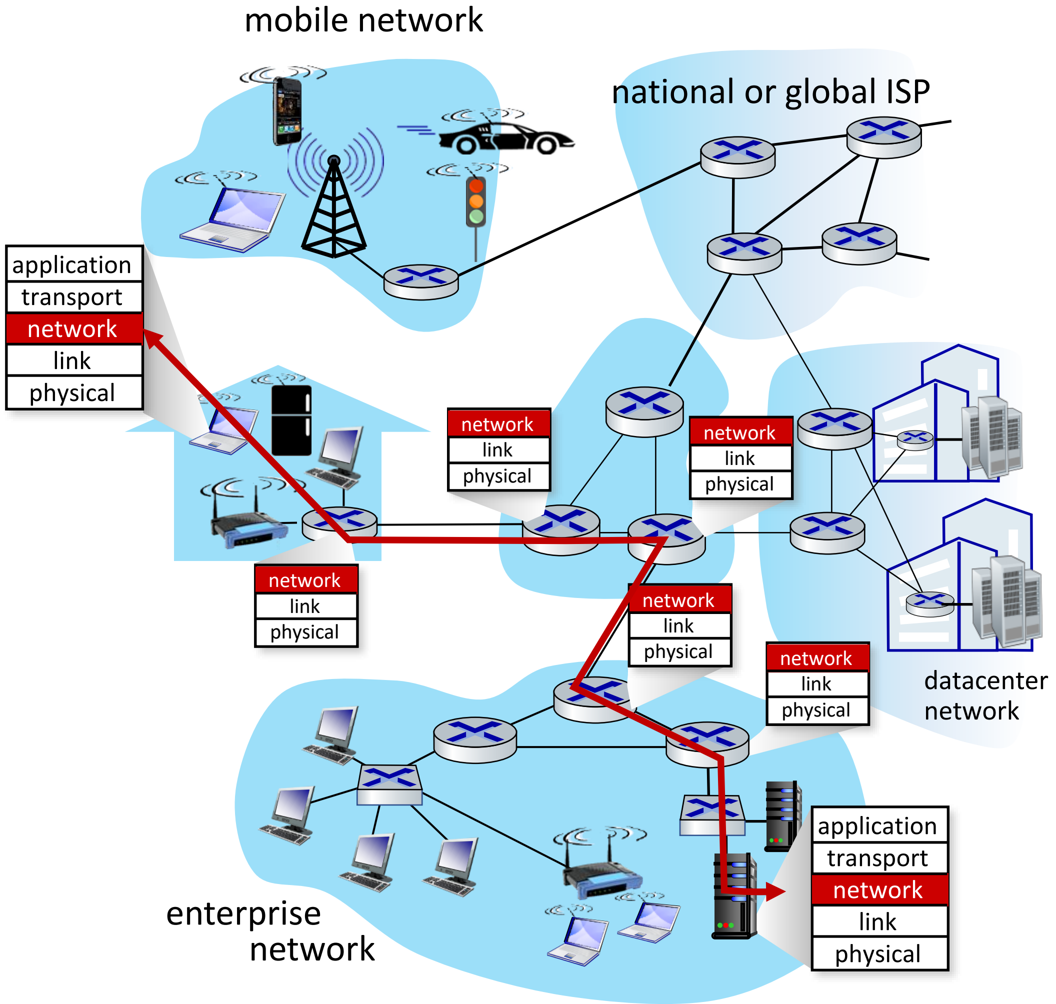
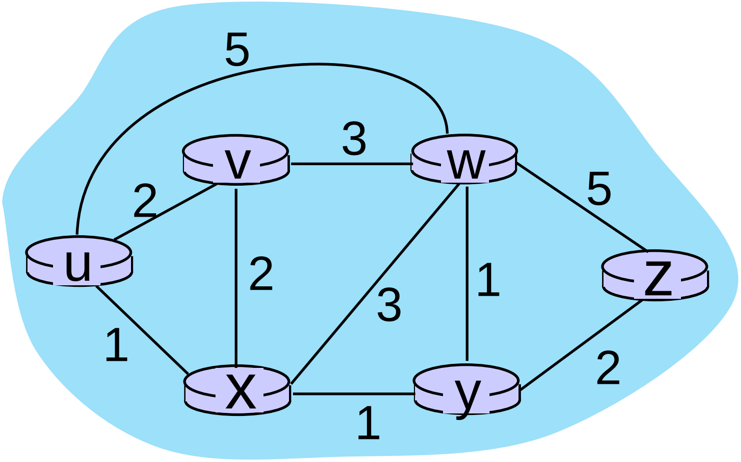
Routing protocols

Routing protocol goal: determine "good" paths (equivalently, routes), from sending hosts to receiving host, through network of routers

- path: sequence of routers packets traverse from given initial source host to final destination host
- "good": least "cost", "fastest", "least congested"
- routing: a "top-10" networking challenge!



Graph abstraction: link costs



$c_{a,b}$: cost of *direct* link connecting *a* and *b*

e.g., $c_{w,z} = 5$, $c_{u,z} = \infty$

cost defined by network operator: could always be 1, or inversely related to bandwidth, or inversely related to congestion

graph: $G = (N,E)$

N: set of routers = { *u, v, w, x, y, z* }

E: set of links ={ *(u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z)* }

Routing algorithm classification

global: all routers have *complete* topology, link cost info
- "link state" algorithms

How fast do routes change?

static: routes change slowly over time

dynamic: routes change more quickly
- periodic updates or in response to link cost changes

decentralized: iterative process of computation, exchange of info with neighbors
- routers initially only know link costs to attached neighbors
- "distance vector" algorithms

global or decentralized information?

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Dijkstra's link-state routing algorithm

- centralized: network topology, link costs known to *all* nodes
  - accomplished via "link state broadcast"
  - all nodes have same info
- computes least cost paths from one node ("source") to all other nodes
  - gives *forwarding table* for that node
- iterative: after *k* iterations, know least cost path to *k* destinations

notation

- $c_{x,y}$: direct link cost from node *x* to *y*; $= \infty$ if not direct neighbors
- *D(v)*: *current* estimate of cost of least-cost-path from source to destination *v*
- *p(v)*: predecessor node along path from source to *v*
- *N'*: set of nodes whose least-cost-path *definitively* known

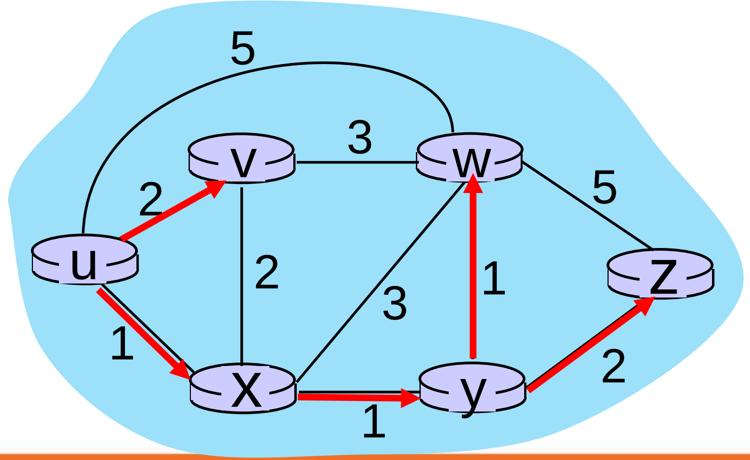
Dijkstra's link-state routing algorithm

Initialization:
$N' = \{u\}$ /* compute least cost path from u to all other nodes */
for all nodes v
if v adjacent to u /* u initially knows direct-path-cost only to direct neighbors */
then $D(v) = c_{u,v}$ /* but may not be *minimum* cost! */
else $D(v) = \infty$

Loop
find w not in N' such that $D(w)$ is a minimum
add w to N'
update $D(v)$ for all v adjacent to w and not in N' :
$D(v) = \min(D(v), D(w) + c_{w,v})$
/* new least-path-cost to v is either old least-cost-path to v or known
least-cost-path to w plus direct-cost from w to v */
until all nodes in N'

Dijkstra's algorithm: an example

Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5	uxyvwz					

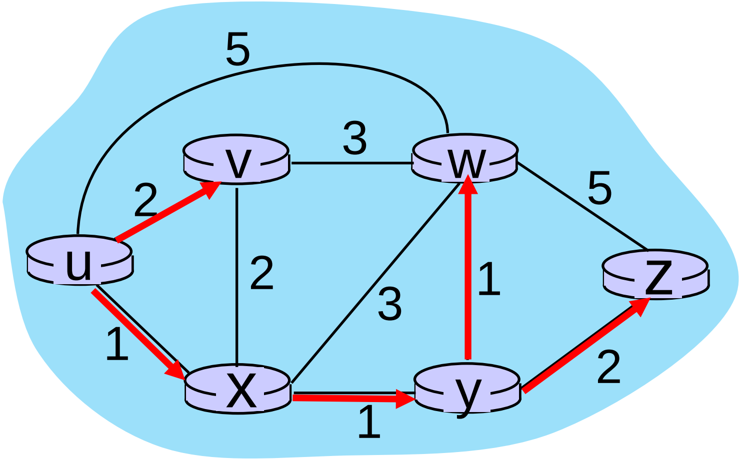


Initialization (step 0): For all a: if *a* adjacent to then *D(a)* = $c_{u,a}$

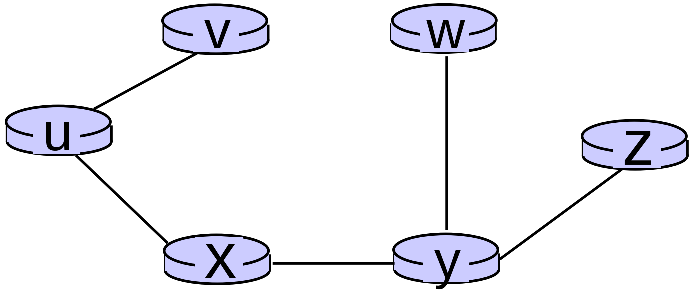
find *a* not in *N'* such that *D(a)* is a minimum
add *a* to *N'*
update *D(b)* for all *b* adjacent to *a* and not in *N'* :

$D(b) = \min(D(b), D(a) + c_{a,b})$

Dijkstra's algorithm: an example



resulting least-cost-path tree from u:



resulting forwarding table in u:

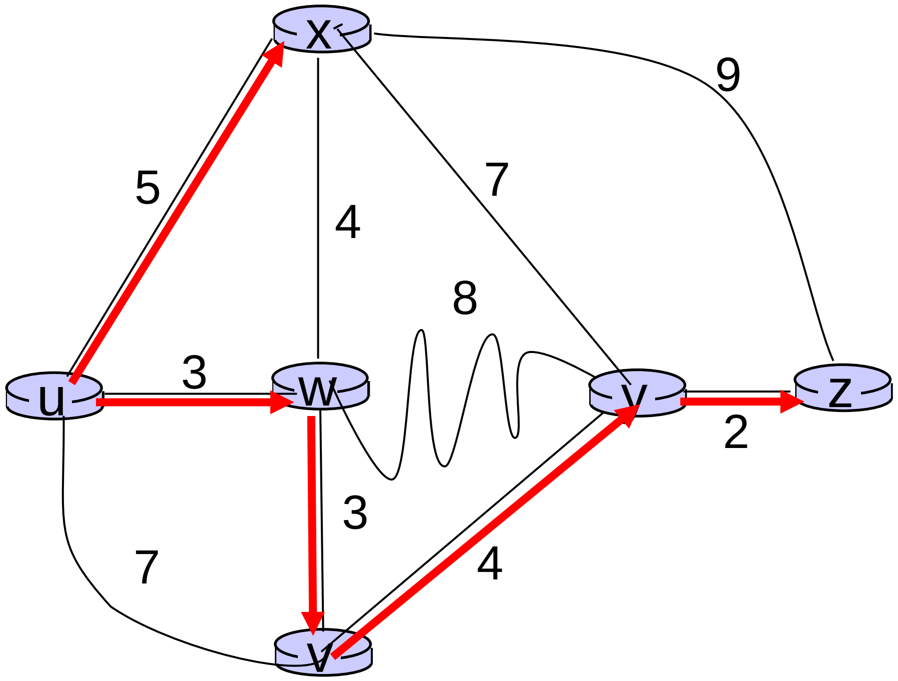
destination	outgoing link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
x	(u,x)

route from *u* to *v* directly

route from u to all other destinations via *x*

Dijkstra's algorithm: another example

Step	N'	D(v), p(v)	D(w), p(w)	D(x), p(x)	D(y), p(y)	D(z), p(z)
0	u	7,u	3,u	5,u	∞	∞
1	uw	6,w		5,u	11,w	∞
2	uwx	6,w			11,w	14,x
3	uwxv				10,v	14,x
4	uwxvy					12,y
5	uwxvyz					



notes:

- construct least-cost-path tree by tracing predecessor nodes
- ties can exist (can be broken arbitrarily)

Dijkstra's algorithm: discussion

algorithm complexity: *n* nodes

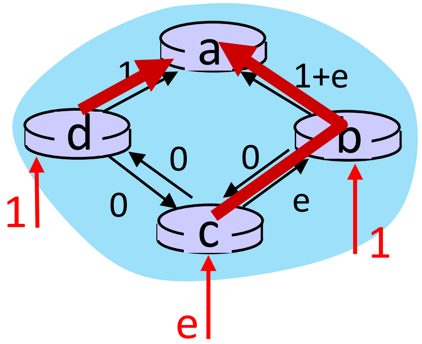
- each of *n* iteration: need to check all nodes, *w*, not in *N*
- $n(n+1)/2$ comparisons: $O(n^2)$ complexity
- more efficient implementations possible: $O(n\log n)$

message complexity:

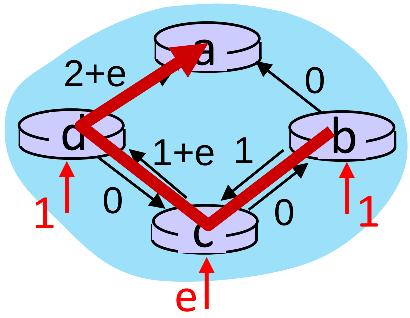
- each router must *broadcast* its link state information to other *n* routers
- efficient (and interesting!) broadcast algorithms: $O(n)$ link crossings to disseminate a broadcast message from one source
- each router's message crosses $O(n)$ links: overall message complexity: $O(n^2)$

Dijkstra's algorithm: oscillations possible

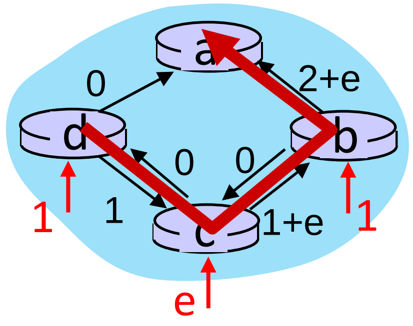
- when link costs depend on traffic volume, route oscillations possible
- sample scenario:
  - routing to destination a, traffic entering at d, c, e with rates 1, e (<1), 1
  - link costs are directional, and volume-dependent



initially



given these costs, find new routing…. resulting in new costs



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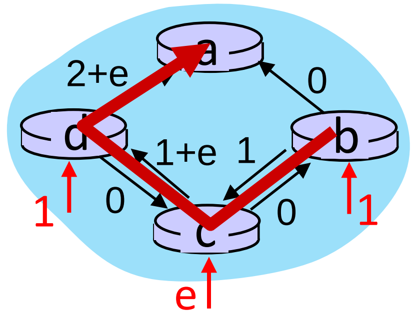

given these costs, find new routing…. resulting in new costs

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Distance vector algorithm

Based on *Bellman-Ford* (BF) equation (dynamic programming):

Bellman-Ford equation

Let $D_x(y)$: cost of least-cost path from x to y.

Then:

$$D_x(y) = \min_v \{ c_{x,v} + D_v(y) \}$$

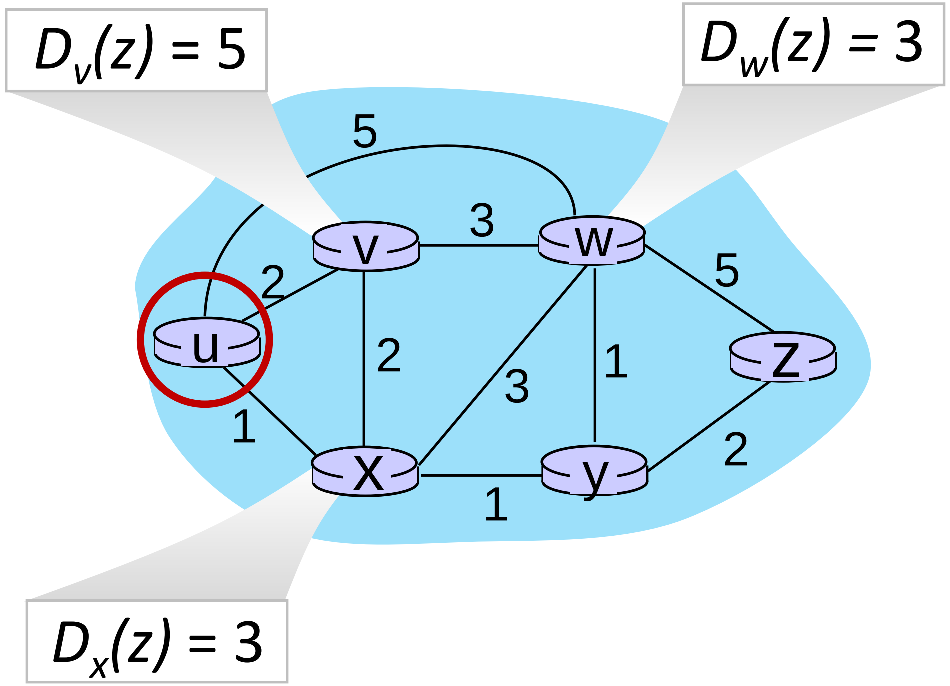
v's estimated least-cost-path cost to y

min taken over all neighbors v of x

direct cost of link from x to v

Bellman-Ford Example

Suppose that *u*'s neighboring nodes, *x,v,w,* know that for destination *z*:



Bellman-Ford equation says:

$$D_u(z) = \min \{ c_{u,v} + D_v(z), \; c_{u,x} + D_x(z), \; c_{u,w} + D_w(z) \}$$

$$= \min \{2 + 5, \; 1 + 3, \; 5 + 3\} = 4$$

node achieving minimum (x) is next hop on estimated least-cost path to destination (z)

Distance vector algorithm

key idea:

- from time-to-time, each node sends its own distance vector estimate to neighbors
- when *x* receives new DV estimate from any neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_v\{c_{x,v} + D_v(y)\} \quad \text{for each node } y \in N$$

- under minor, natural conditions, the estimate *$D_x(y)$ converge to the actual least cost* $d_x(y)$

Distance vector algorithm:

each node:

wait for (change in local link cost or msg from neighbor)

↓

recompute DV estimates using DV received from neighbor

↓

if DV to any destination has changed, *notify* neighbors

iterative, asynchronous: each local iteration caused by:

- local link cost change
- DV update message from neighbor

distributed, self-stopping: each node notifies neighbors *only* when its DV changes

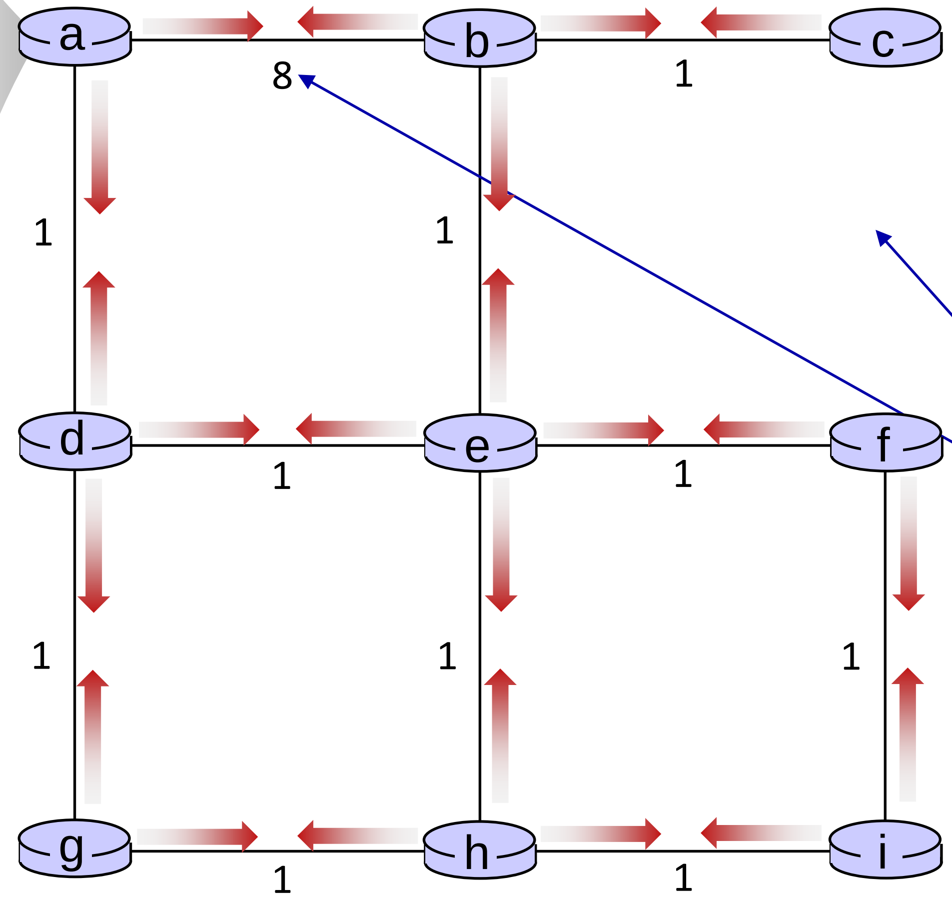
- neighbors then notify their neighbors – *only if necessary*
- no notification received, no actions taken!

Distance vector: example

DV in a:
$D_a(a)=0$
$D_a(b) = 8$
$D_a(c) = \infty$
$D_a(d) = 1$
$D_a(e) = \infty$
$D_a(f) = \infty$
$D_a(g) = \infty$
$D_a(h) = \infty$
$D_a(i) = \infty$

t=0

- All nodes have distance estimates to nearest neighbors (only)
- All nodes send their local distance vector to their neighbors



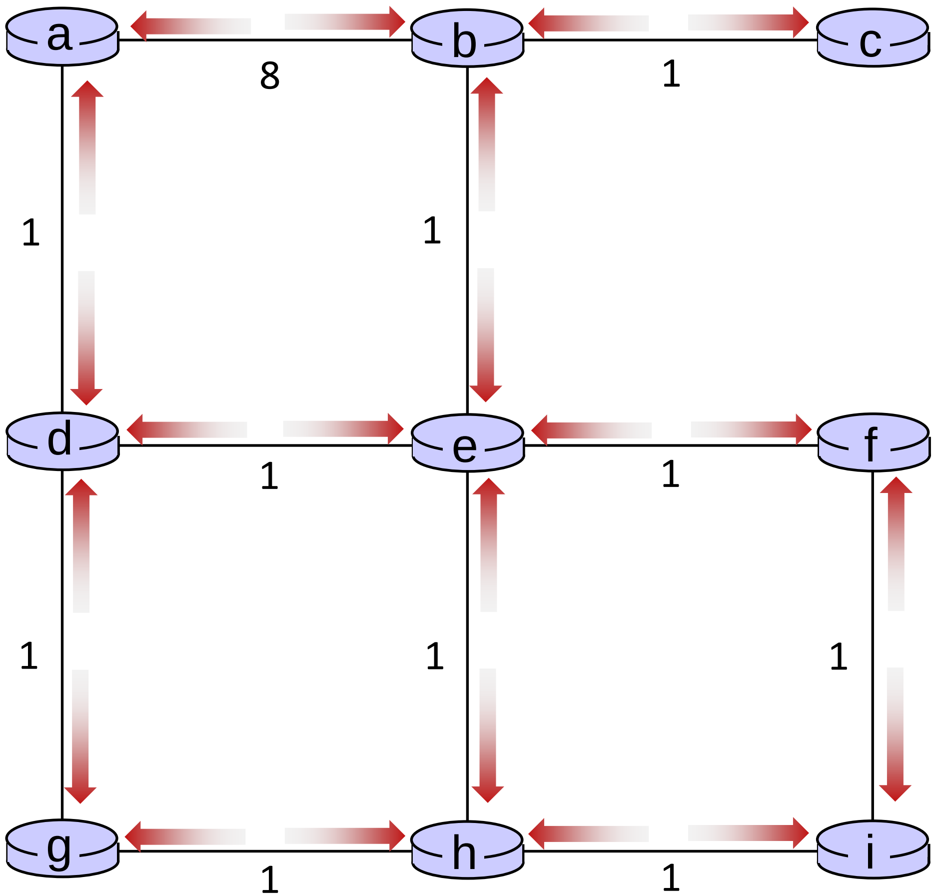
A few asymmetries:

- missing link
- larger cost

Distance vector example: iteration

t=1

All nodes:
- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors

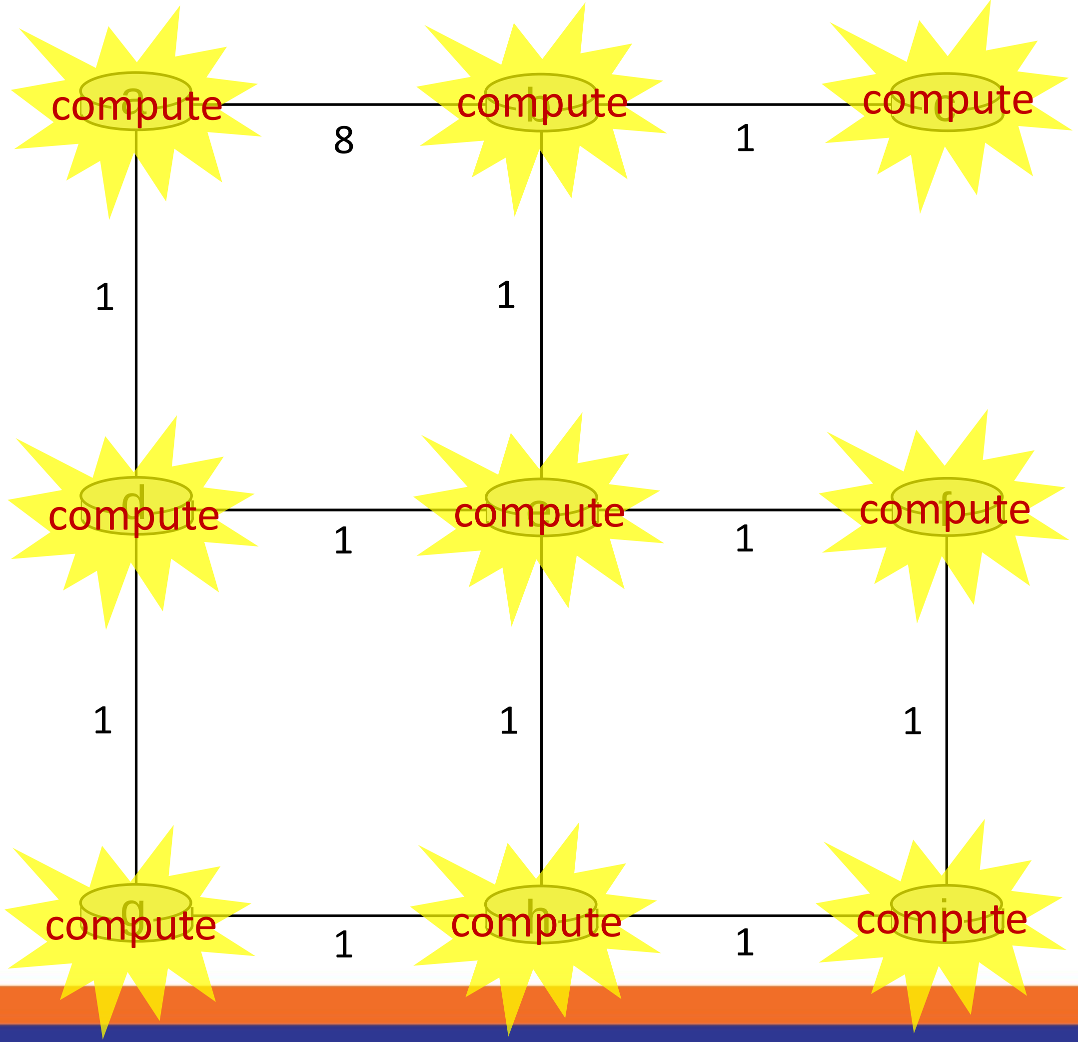


Distance vector example: iteration

t=1

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



Distance vector example: iteration

t=1

All nodes:
- receive distance vectors from neighbors
- compute their new local distance vector
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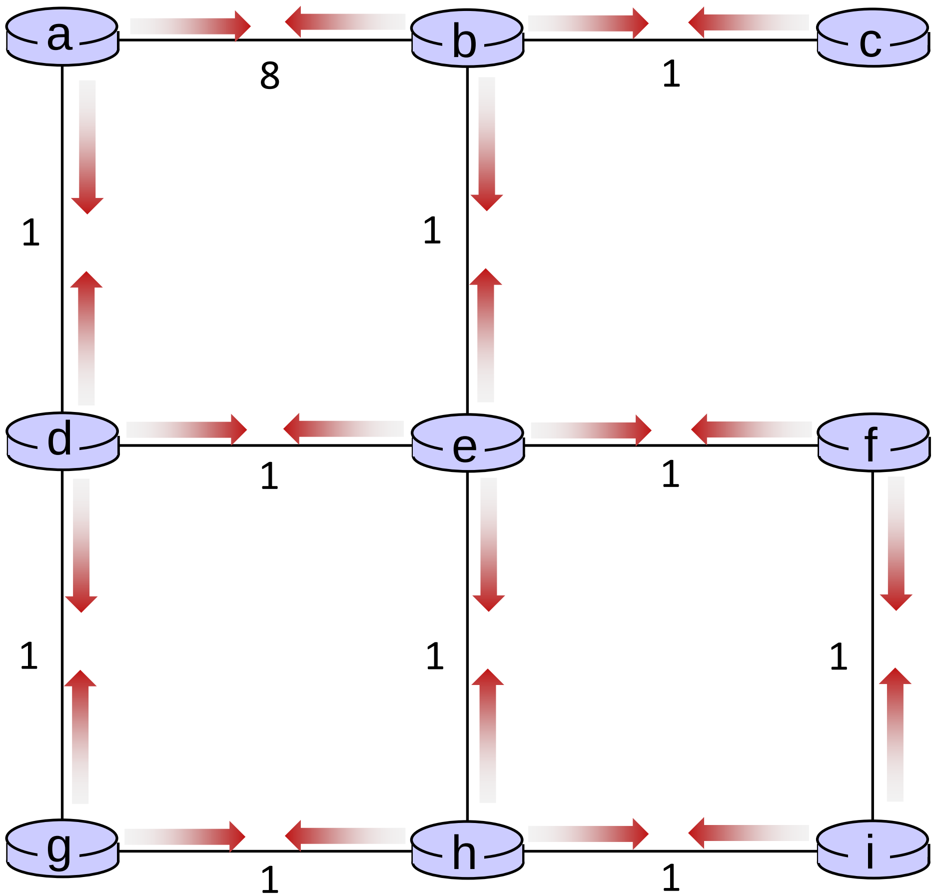
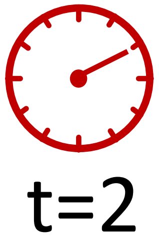
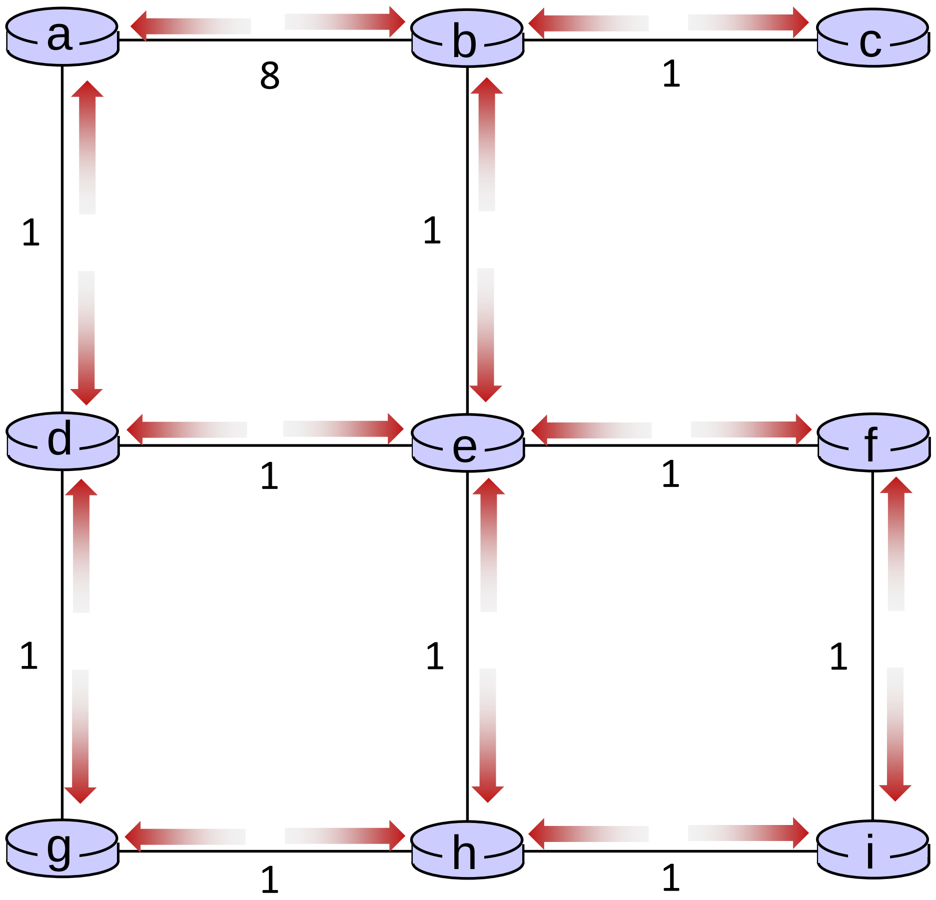


Distance vector example: iteration



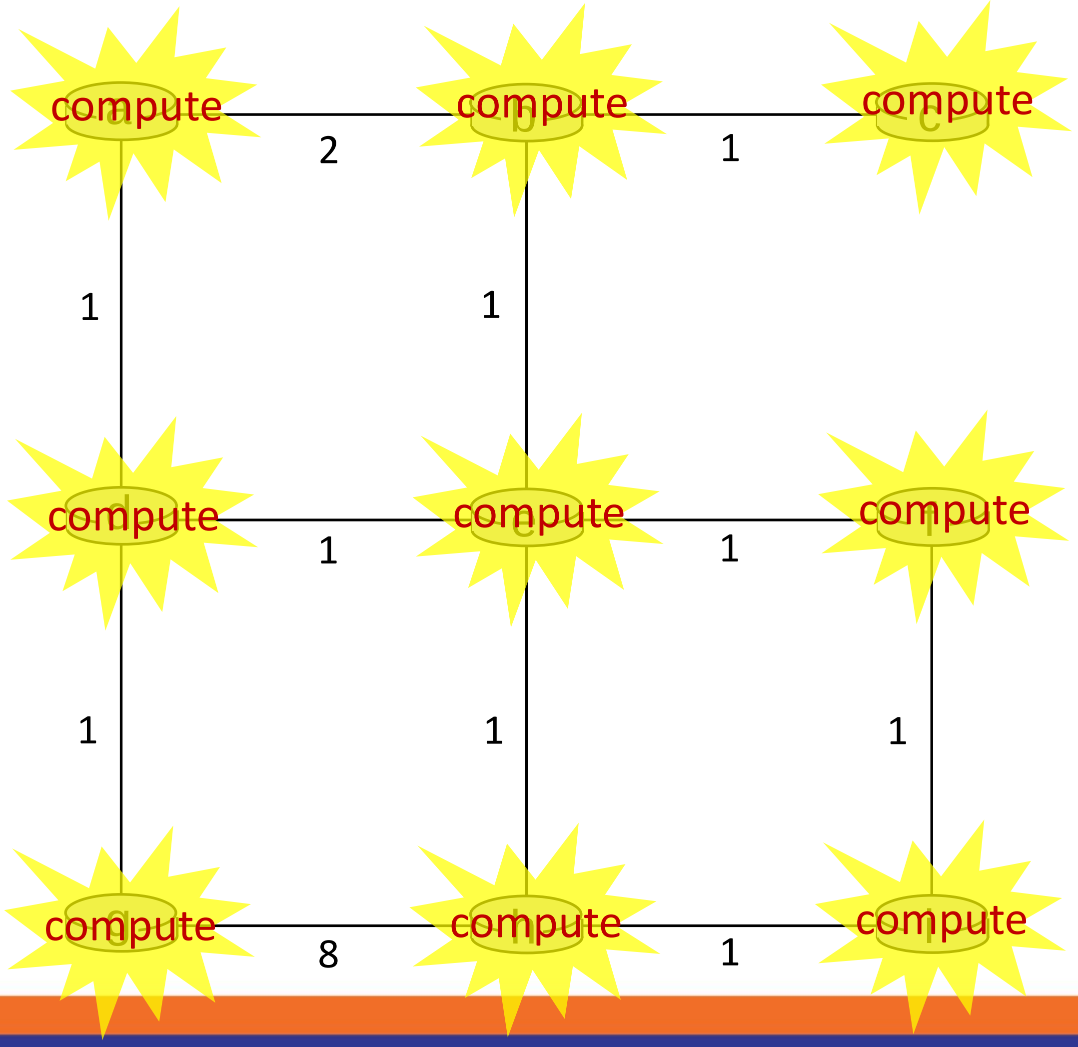
All nodes:
- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



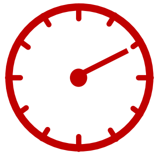
Distance vector example: iteration

t=2

All nodes:
- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



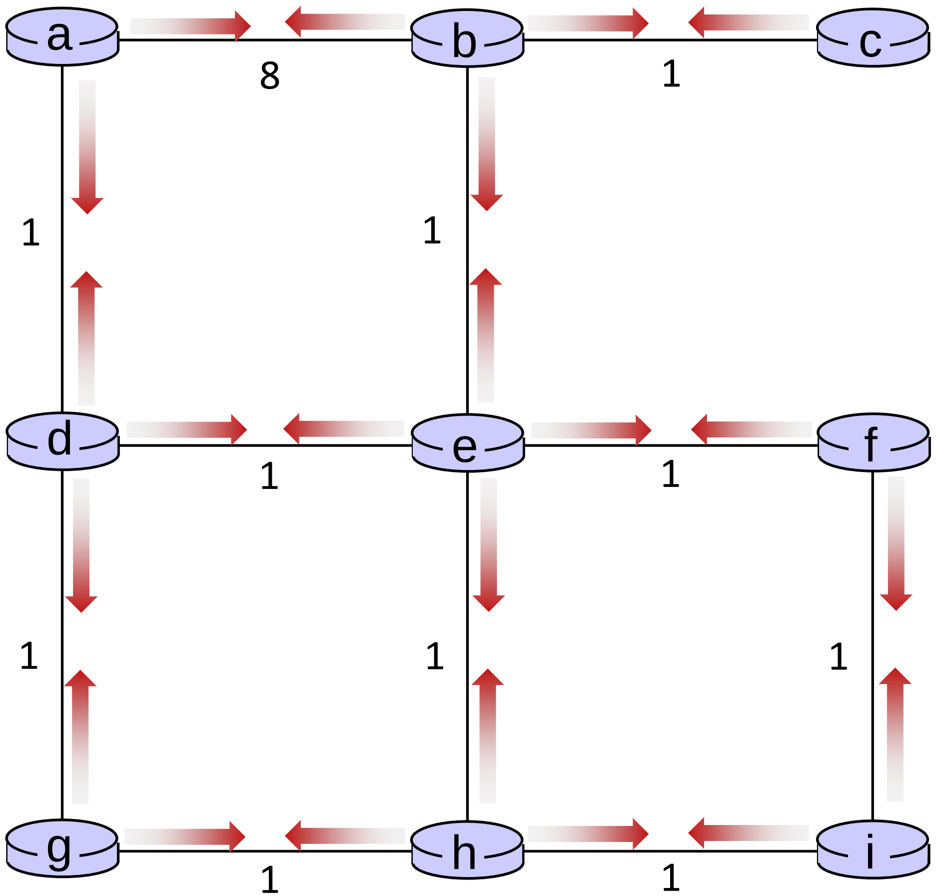
Distance vector example: iteration



t=2

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



Distance vector example: iteration

…. and so on

Let's next take a look at the iterative *computations* at nodes

Distance vector example: computation

t=1

- b receives DVs from a, c, e

DV in a:

$D_a(a)=0$
$D_a(b) = 8$
$D_a(c) = \infty$
$D_a(d) = 1$
$D_a(e) = \infty$
$D_a(f) = \infty$
$D_a(g) = \infty$
$D_a(h) = \infty$
$D_a(i) = \infty$

DV in b:

$D_b(a) = 8$	$D_b(f) = \infty$
$D_b(c) = 1$	$D_b(g) = \infty$
$D_b(d) = \infty$	$D_b(h) = \infty$
$D_b(e) = 1$	$D_b(i) = \infty$

DV in c:

$D_c(a) = \infty$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = \infty$
$D_c(e) = \infty$
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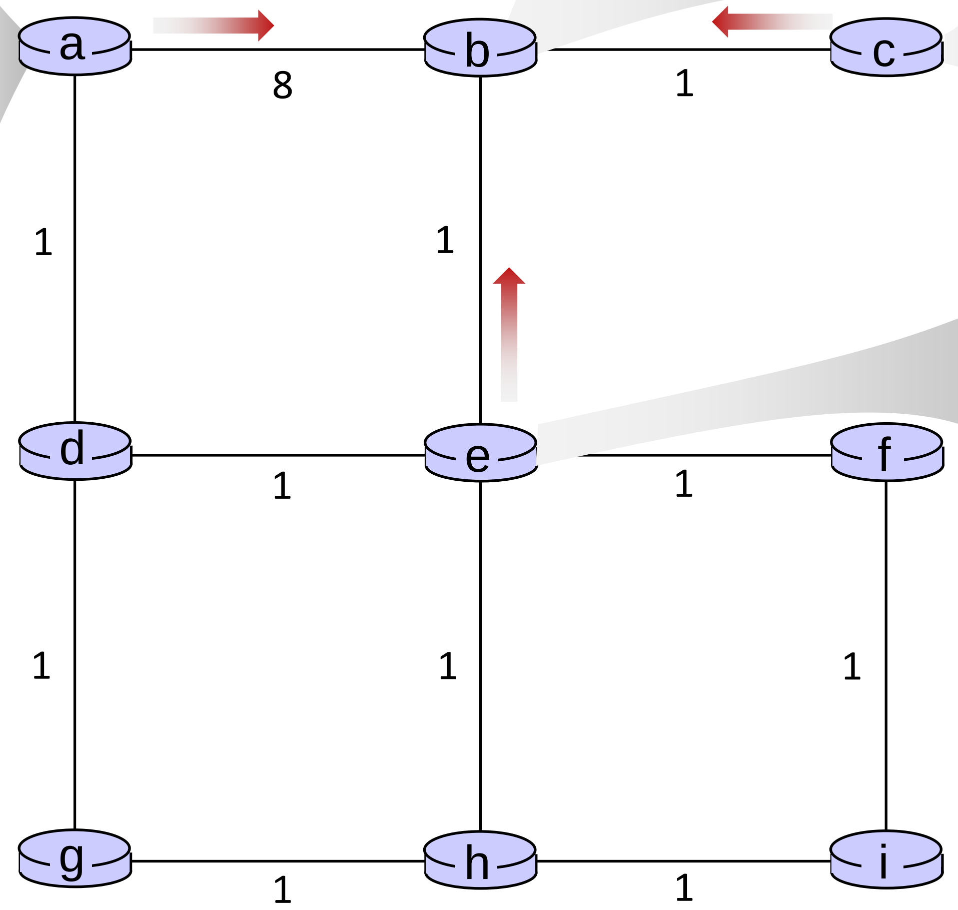

DV in e:

$D_e(a) = \infty$
$D_e(b) = 1$
$D_e(c) = \infty$
$D_e(d) = 1$
$D_e(e) = 0$
$D_e(f) = 1$
$D_e(g) = \infty$
$D_e(h) = 1$
$D_e(i) = \infty$

Distance vector example: computation

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DV in a:

$D_a(a)=0$
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$D_a(g) = \infty$
$D_a(h) = \infty$
$D_a(i) = \infty$

DV in b:

$D_b(a) = 8$	$D_b(f) = \infty$
$D_b(c) = 1$	$D_b(g) = \infty$
$D_b(d) = \infty$	$D_b(h) = \infty$
$D_b(e) = 1$	$D_b(i) = \infty$

DV in c:

$D_c(a) = \infty$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = \infty$
$D_c(e) = \infty$
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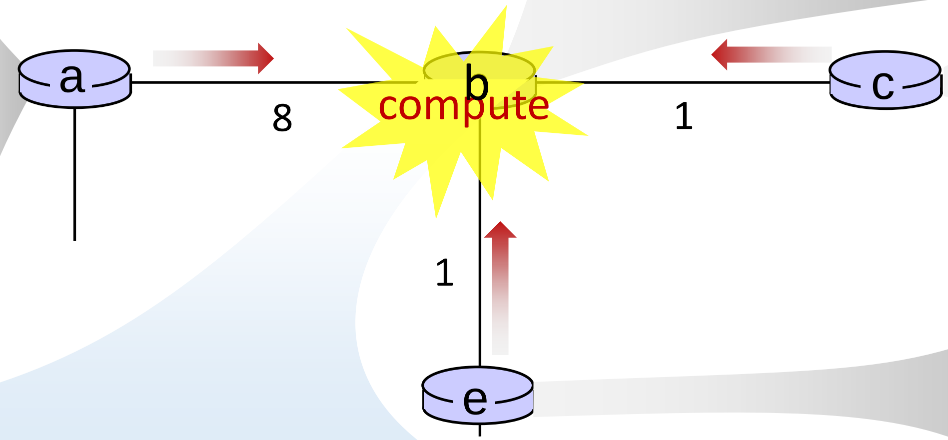

DV in e:

$D_e(a) = \infty$
$D_e(b) = 1$
$D_e(c) = \infty$
$D_e(d) = 1$
$D_e(e) = 0$
$D_e(f) = 1$
$D_e(g) = \infty$
$D_e(h) = 1$
$D_e(i) = \infty$

t=1

- b receives DVs from a, c, e, computes:

$D_b(a) = \min\{c_{b,a}+D_a(a),\ c_{b,c}+D_c(a),\ c_{b,e}+D_e(a)\} = \min\{8,\infty,\infty\} = 8$

$D_b(c) = \min\{c_{b,a}+D_a(c),\ c_{b,c}+D_c(c),\ c_{b,e}+D_e(c)\} = \min\{\infty,1,\infty\} = 1$

$D_b(d) = \min\{c_{b,a}+D_a(d),\ c_{b,c}+D_c(d),\ c_{b,e}+D_e(d)\} = \min\{9,2,\infty\} = 2$

$D_b(e) = \min\{c_{b,a}+D_a(e),\ c_{b,c}+D_c(e),\ c_{b,e}+D_e(e)\} = \min\{\infty,\infty,1\} = 1$

$D_b(f) = \min\{c_{b,a}+D_a(f),\ c_{b,c}+D_c(f),\ c_{b,e}+D_e(f)\} = \min\{\infty,\infty,2\} = 2$

$D_b(g) = \min\{c_{b,a}+D_a(g),\ c_{b,c}+D_c(g),\ c_{b,e}+D_e(g)\} = \min\{\infty, \infty, \infty\} = \infty$

$D_b(h) = \min\{c_{b,a}+D_a(h),\ c_{b,c}+D_c(h),\ c_{b,e}+D_e(h)\} = \min\{\infty, \infty, 2\} = 2$

$D_b(i) = \min\{c_{b,a}+D_a(i),\ c_{b,c}+D_c(i),\ c_{b,e}+D_e(i)\} = \min\{\infty, \infty, \infty\} = \infty$

DV in b:

$D_b(a) = 8$	$D_b(f) =2$
$D_b(c) = 1$	$D_b(g) = \infty$
$D_b(d) = 2$	$D_b(h) = 2$
$D_b(e) = 1$	$D_b(i) = \infty$

Distance vector example: computation

t=1

- c receives DVs from b

DV in a:

$D_a(a)=0$
$D_a(b) = 8$
$D_a(c) = \infty$
$D_a(d) = 1$
$D_a(e) = \infty$
$D_a(f) = \infty$
$D_a(g) = \infty$
$D_a(h) = \infty$
$D_a(i) = \infty$

DV in b:

$D_b(a) = 8$
$D_b(c) = 1$
$D_b(d) = \infty$
$D_b(e) = 1$
$D_b(f) = \infty$
$D_b(g) = \infty$
$D_b(h) = \infty$
$D_b(i) = \infty$

DV in c:

$D_c(a) = \infty$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = \infty$
$D_c(e) = \infty$
$D_c(f) = \infty$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = \infty$

DV in e:

$D_e(a) = \infty$
$D_e(b) = 1$
$D_e(c) = \infty$
$D_e(d) = 1$
$D_e(e) = 0$
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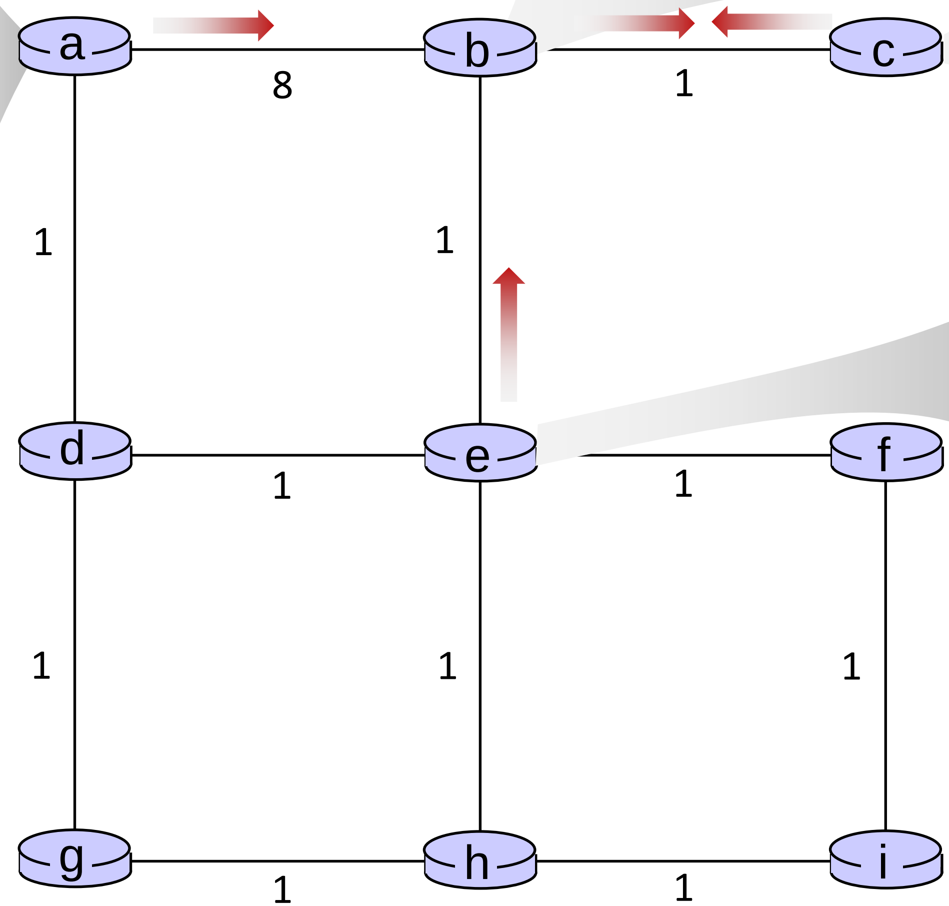

Distance vector example: computation

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t=1

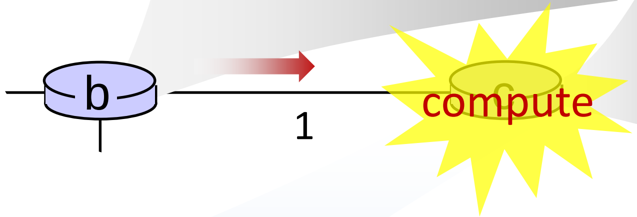
- c receives DVs from b computes:

DV in b:

$D_b(a) = 8$	$D_b(f) = \infty$
$D_b(c) = 1$	$D_b(g) = \infty$
$D_b(d) = \infty$	$D_b(h) = \infty$
$D_b(e) = 1$	$D_b(i) = \infty$

DV in c:

$D_c(a) = \infty$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = \infty$
$D_c(e) = \infty$
$D_c(f) = \infty$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = \infty$



$D_c(a) = \min\{c_{c,b}+D_b(a)\} = 1 + 8 = 9$

$D_c(b) = \min\{c_{c,b}+D_b(b)\} = 1 + 0 = 1$

$D_c(d) = \min\{c_{c,b}+D_b(d)\} = 1+ \infty = \infty$

$D_c(e) = \min\{c_{c,b}+D_b(e)\} = 1 + 1 = 2$

$D_c(f) = \min\{c_{c,b}+D_b(f)\} = 1+ \infty = \infty$

$D_c(g) = \min\{c_{c,b}+D_b(g)\} = 1+ \infty = \infty$

$D_c(h) = \min\{c_{bc,b}+D_b(h)\} = 1+ \infty = \infty$

$D_c(i) = \min\{c_{c,b}+D_b(i)\} = 1+ \infty = \infty$

DV in c:

$D_c(a) = 9$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = 2$
$D_c(e) = \infty$
$D_c(f) = \infty$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = \infty$

* Check out the online interactive exercises for more examples: http://gaia.cs.umass.edu/kurose_ross/interactive/

Distance vector example: computation

t=1

- e receives DVs from b, d, f, h

DV in d:

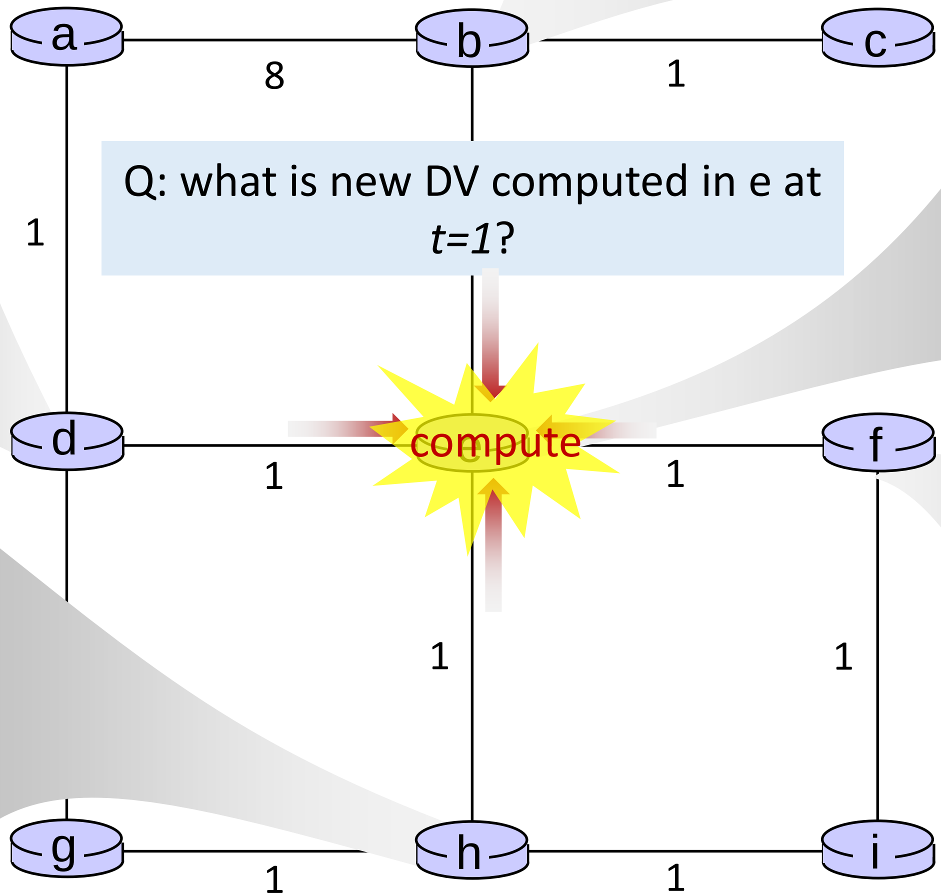
$D_c(a) = 1$
$D_c(b) = \infty$
$D_c(c) = \infty$
$D_c(d) = 0$
$D_c(e) = 1$
$D_c(f) = \infty$
$D_c(g) = 1$
$D_c(h) = \infty$
$D_c(i) = \infty$

DV in b:

$D_b(a) = 8$ $D_b(f) = \infty$
$D_b(c) = 1$ $D_b(g) = \infty$
$D_b(d) = \infty$ $D_b(h) = \infty$
$D_b(e) = 1$ $D_b(i) = \infty$

DV in e:

$D_e(a) = \infty$
$D_e(b) = 1$
$D_e(c) = \infty$
$D_e(d) = 1$
$D_e(e) = 0$
$D_e(f) = 1$
$D_e(g) = \infty$
$D_e(h) = 1$
$D_e(i) = \infty$



DV in h:

$D_c(a) = \infty$
$D_c(b) = \infty$
$D_c(c) = \infty$
$D_c(d) = \infty$
$D_c(e) = 1$
$D_c(f) = \infty$
$D_c(g) = 1$
$D_c(h) = 0$
$D_c(i) = 1$

DV in f:

$D_c(a) = \infty$
$D_c(b) = \infty$
$D_c(c) = \infty$
$D_c(d) = \infty$
$D_c(e) = 1$
$D_c(f) = 0$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = 1$

Distance vector: state information diffusion

Iterative communication, computation steps diffuses information through network:

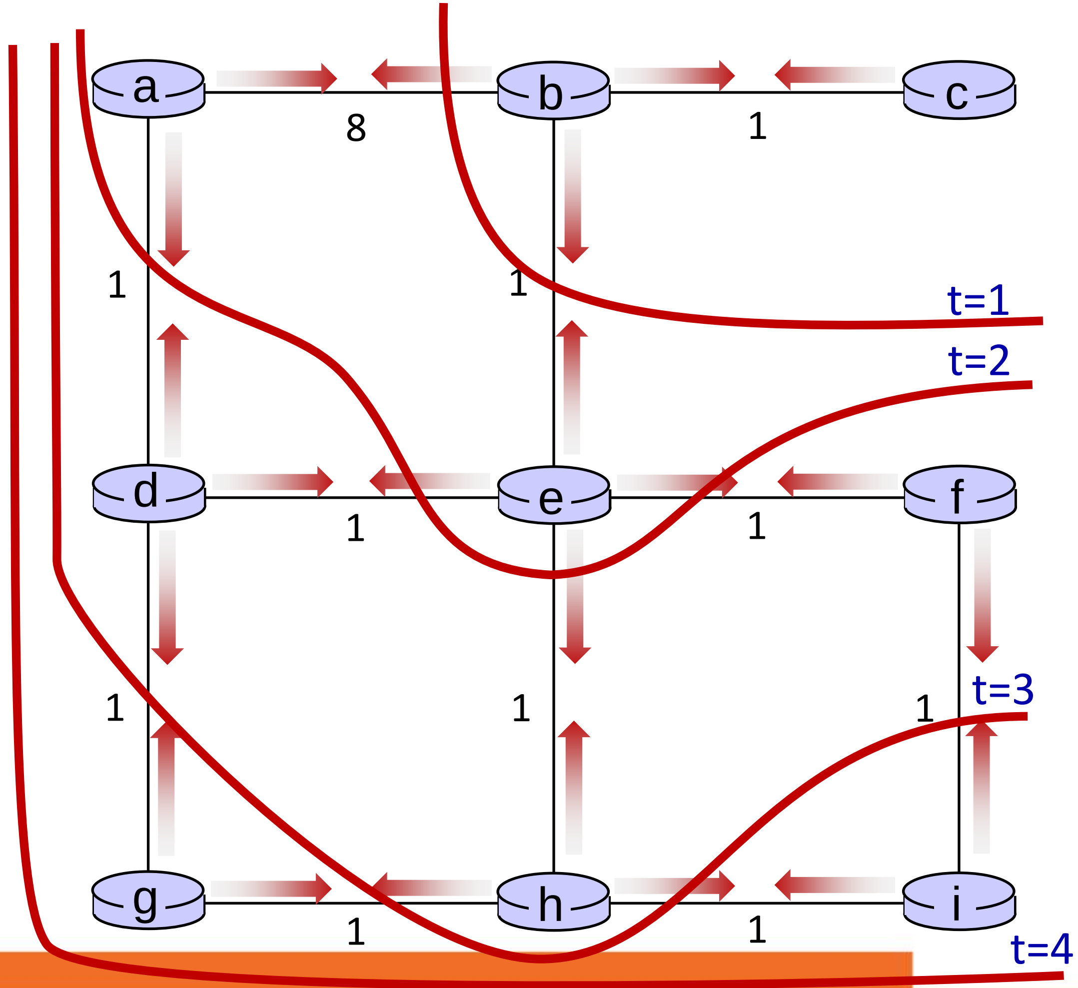
t=0 c's state at t=0 is at c only

t=1 c's state at t=0 has propagated to b, and may influence distance vector computations up to **1** hop away, i.e., at b

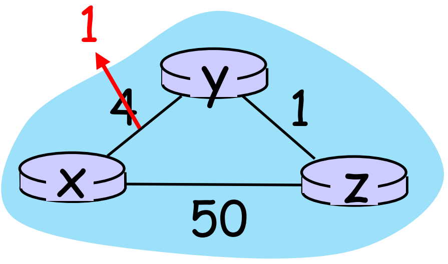
t=2 c's state at t=0 may now influence distance vector computations up to **2** hops away, i.e., at b and now at a, e as well

t=3 c's state at t=0 may influence distance vector computations up to **3** hops away, i.e., at b,a,e and now at c,f,h as well

t=4 c's state at t=0 may influence distance vector computations up to **4** hops away, i.e., at b,a,e, c, f, h and now at g,i as well



Distance vector: link cost changes



link cost changes:

- node detects local link cost change
- updates routing info, recalculates local DV
- if DV changes, notify neighbors

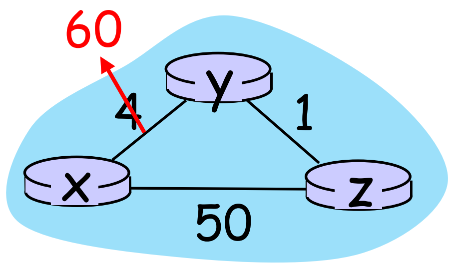
"good news travels fast"

t_0 : *y* detects link-cost change, updates its DV, informs its neighbors.

t_1 : *z* receives update from *y*, updates its table, computes new least cost to *x* , sends its neighbors its DV.

t_2 : *y* receives *z*'s update, updates its distance table. *y*'s least costs do *not* change, so *y* does *not* send a message to *z*.

Distance vector: link cost changes



link cost changes:

- node detects local link cost change
- "bad news travels slow" – count-to-infinity problem:
  - *y* sees direct link to *x* has new cost 60, but z has said it has a path at cost of 5. So *y* computes "my new cost to x will be 6, via z); notifies *z* of new cost of 6 to *x*.
  - *z* learns that path to *x* via *y* has new cost 6, so *z* computes "my new cost to *x* will be 7 via y), notifies *y* of new cost of 7 to *x*.
  - *y* learns that path to *x* via *z* has new cost 7, so *y* computes "my new cost to *x* will be 8 via y), notifies *z* of new cost of 8 to *x*.
  - *z* learns that path to *x* via *y* has new cost 8, so *z* computes "my new cost to *x* will be 9 via y), notifies *y* of new cost of 9 to *x*.

  …
- see text for solutions. *Distributed algorithms are tricky!*

Comparison of LS and DV algorithms

message complexity

- LS: n routers, $O(n^2)$ messages sent
- DV: exchange between neighbors; convergence time varies

speed of convergence

- LS: $O(n^2)$ algorithm, $O(n^2)$ messages
  - may have oscillations
- DV: convergence time varies
  - may have routing loops
  - count-to-infinity problem

robustness: what happens if router malfunctions, or is compromised?

LS:
- router can advertise incorrect *link* cost
- each router computes only its *own* table

DV:
- DV router can advertise incorrect *path* cost ("I have a *really* low cost path to everywhere"): black-holing
- each router's table used by others: error propagate thru network

Network layer: “control plane” roadmap

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  - SNMP
  - NETCONF/YANG

Making routing scalable

our routing study thus far - idealized

- all routers identical
- network "flat"

… not true in practice

scale: billions of destinations:

- can't store all destinations in routing tables!
- routing table exchange would swamp links!

administrative autonomy:

- Internet: a network of networks
- each network admin may want to control routing in its own network

Internet approach to scalable routing

aggregate routers into regions known as "autonomous systems" (AS) (a.k.a. "domains")

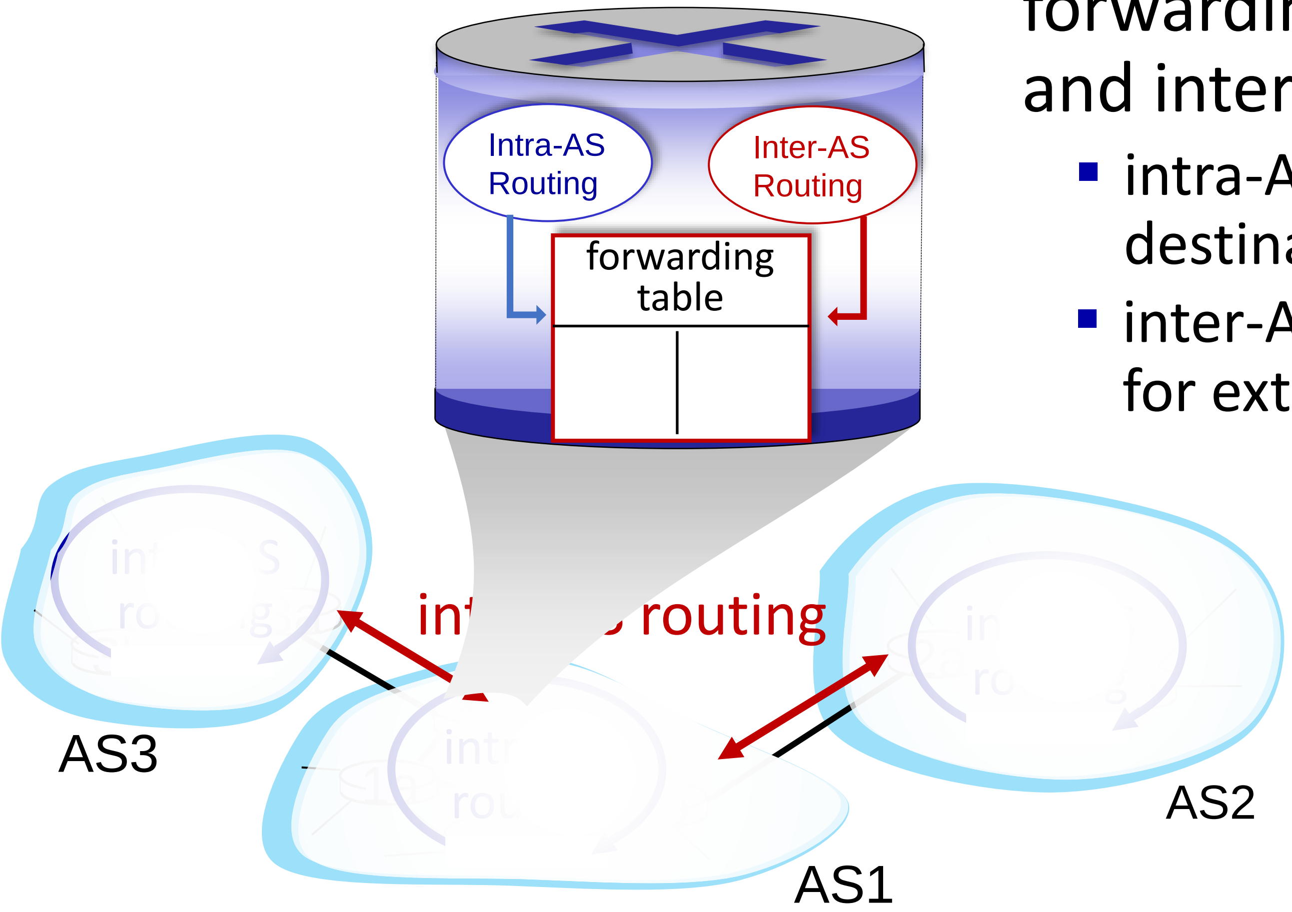
intra-AS (aka "intra-domain"): routing among *within same AS ("network")*

- all routers in AS must run same intra-domain protocol
- routers in different AS can run different intra-domain routing protocols
- gateway router: at "edge" of its own AS, has link(s) to router(s) in other AS'es

inter-AS (aka "inter-domain"): routing *among* AS'es

- gateways perform inter-domain routing (as well as intra-domain routing)

Interconnected ASes



forwarding table configured by intra- and inter-AS routing algorithms

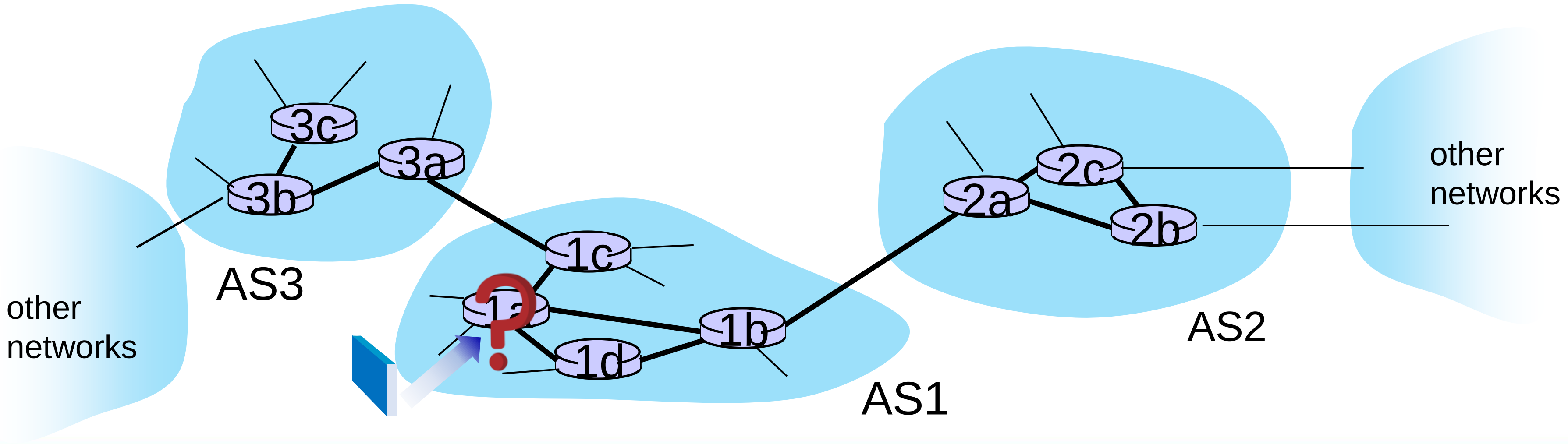
- intra-AS routing determine entries for destinations within AS
- inter-AS & intra-AS determine entries for external destinations

Inter-AS routing: a role in intradomain forwarding

- suppose router in AS1 receives datagram destined outside of AS1:
  - router should forward packet to gateway router in AS1, but which one?

AS1 inter-domain routing must:

1. learn which destinations reachable through AS2, which through AS3
2. propagate this reachability info to all routers in AS1



Inter-AS routing: routing within an AS

most common intra-AS routing protocols:

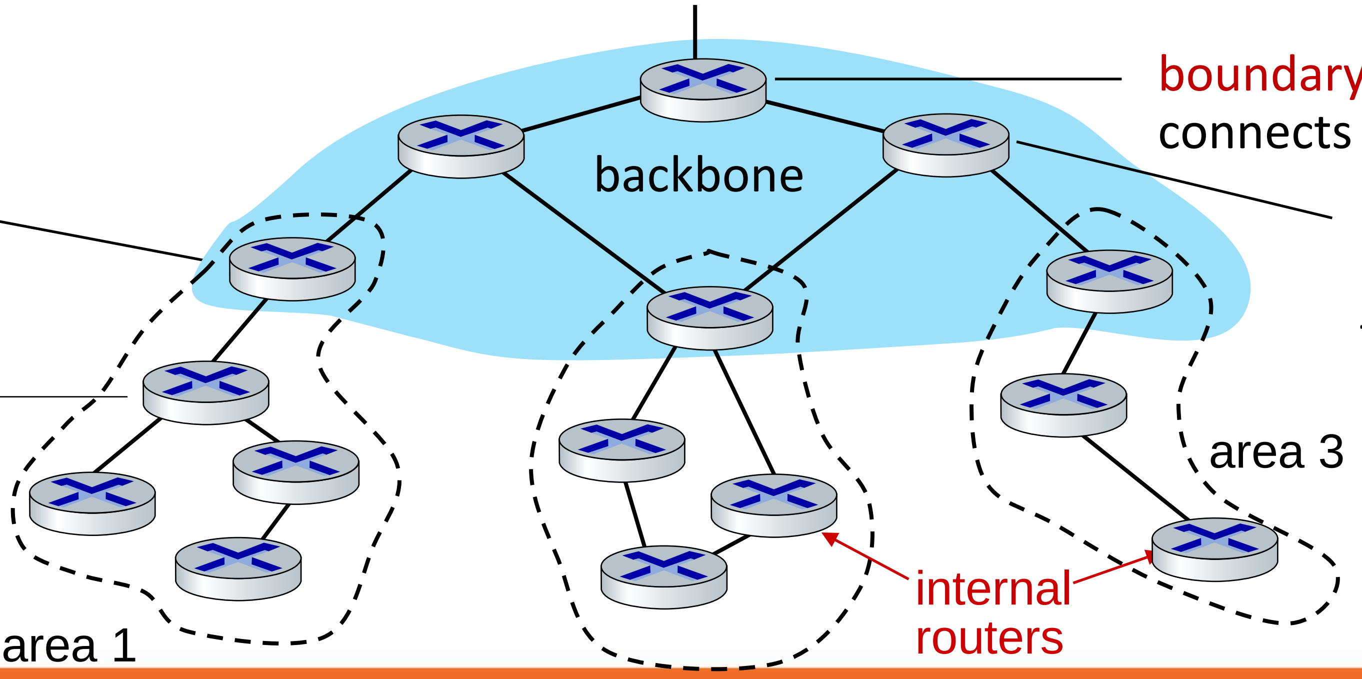
- RIP: Routing Information Protocol [RFC 1723]
  - classic DV: DVs exchanged every 30 secs
  - no longer widely used
- EIGRP: Enhanced Interior Gateway Routing Protocol
  - DV based
  - formerly Cisco-proprietary for decades (became open in 2013 [RFC 7868])
- OSPF: Open Shortest Path First [RFC 2328]
  - link-state routing
  - IS-IS protocol (ISO standard, not RFC standard) essentially same as OSPF

OSPF (Open Shortest Path First) routing

- "open": publicly available
- classic link-state
  - each router floods OSPF link-state advertisements (directly over IP rather than using TCP/UDP) to all other routers in entire AS
  - multiple link costs metrics possible: bandwidth, delay
  - each router has full topology, uses Dijkstra's algorithm to compute forwarding table
- *security:* all OSPF messages authenticated (to prevent malicious intrusion)

Hierarchical OSPF

- two-level hierarchy: local area, backbone.
  - link-state advertisements flooded only in area, or backbone
  - each node has detailed area topology; only knows direction to reach other destinations



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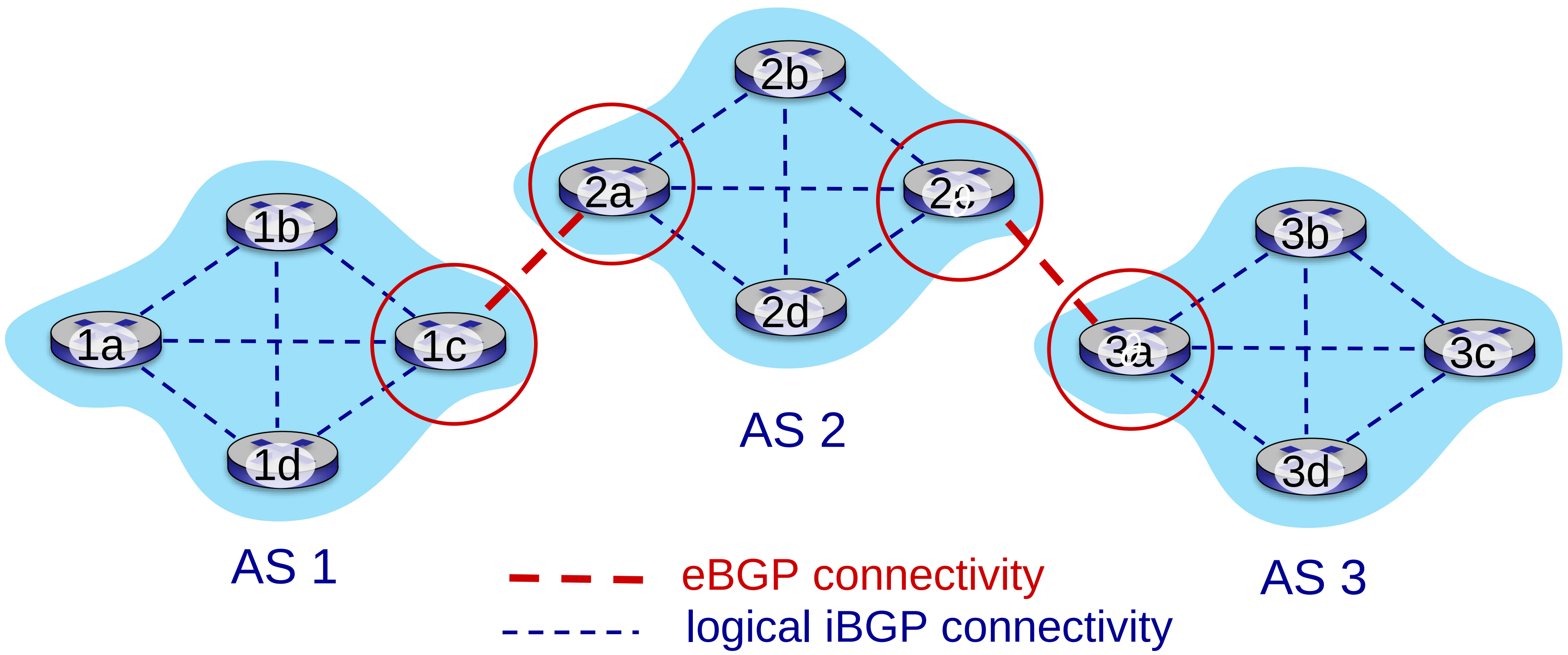
Internet inter-AS routing: BGP

- BGP (Border Gateway Protocol): *the* de facto inter-domain routing protocol
  - "glue that holds the Internet together"
- allows subnet to advertise its existence, and the destinations it can reach, to rest of Internet: *"I am here, here is who I can reach, and how"*
- BGP provides each AS a means to:
  - eBGP: obtain subnet reachability information from neighboring ASes
  - iBGP: propagate reachability information to all AS-internal routers.
  - determine "good" routes to other networks based on reachability information and *policy*

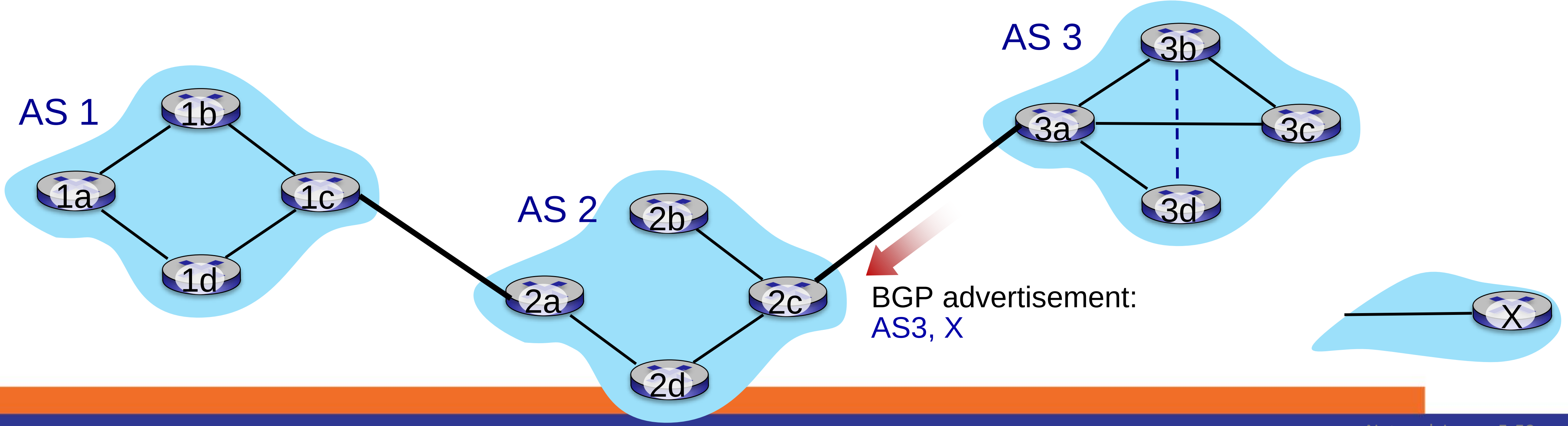
eBGP, iBGP connections



gateway routers run both eBGP and iBGP protocols

BGP basics

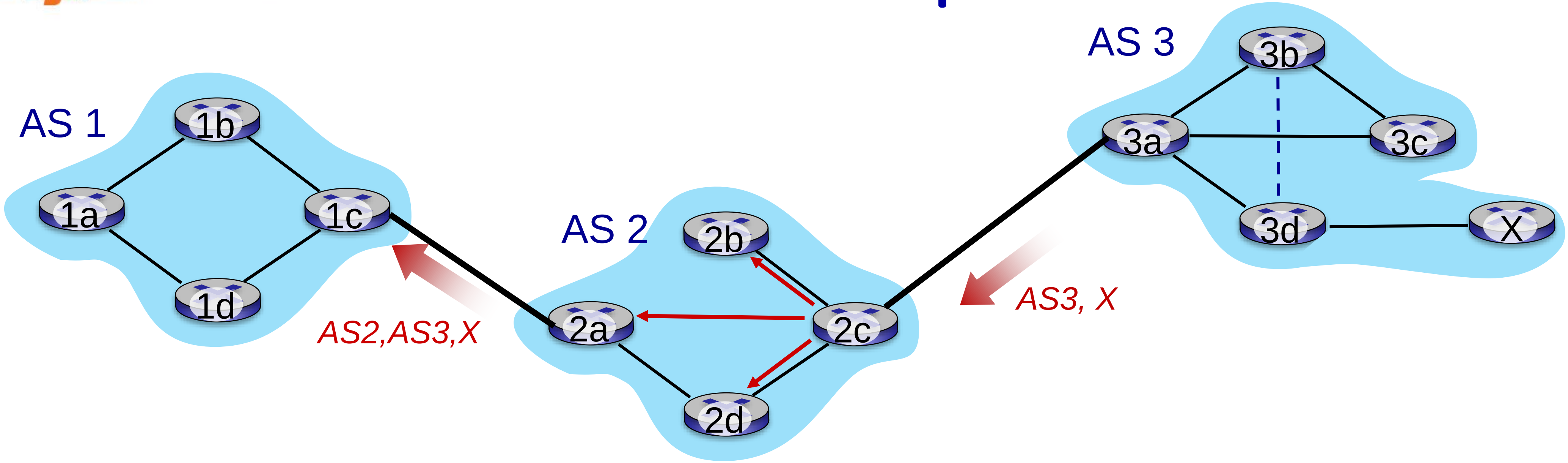
- BGP session: two BGP routers ("peers") exchange BGP messages over semi-permanent TCP connection:
  - advertising *paths* to different destination network prefixes (BGP is a "path vector" protocol)
- when AS3 gateway 3a advertises path AS3,X to AS2 gateway 2c:
  - AS3 *promises* to AS2 it will forward datagrams towards X



Path attributes and BGP routes

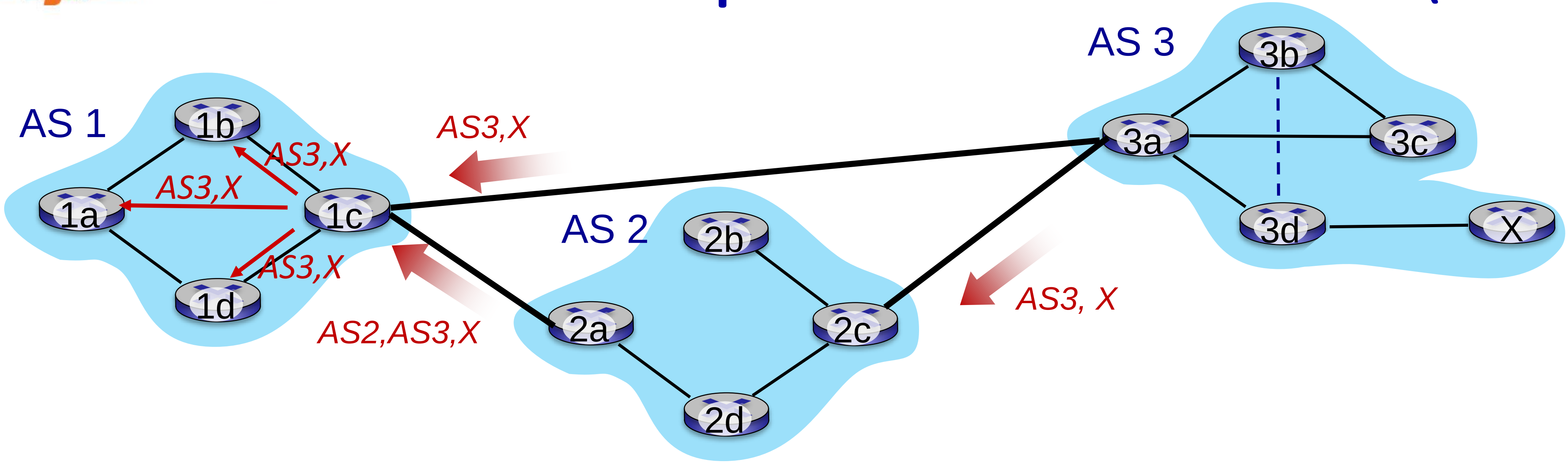
- BGP advertised route: prefix + attributes
  - prefix: destination being advertised
  - two important attributes:
    - AS-PATH: list of ASes through which prefix advertisement has passed
    - NEXT-HOP: indicates specific internal-AS router to next-hop AS
- policy-based routing:
  - gateway receiving route advertisement uses *import policy* to accept/decline path (e.g., never route through AS Y).
  - AS policy also determines whether to *advertise* path to other other neighboring ASes

BGP path advertisement



- AS2 router 2c receives path advertisement AS3,X (via eBGP) from AS3 router 3a
- based on AS2 policy, AS2 router 2c accepts path AS3,X, propagates (via iBGP) to all AS2 routers
- based on AS2 policy, AS2 router 2a advertises (via eBGP) path AS2, AS3, X to AS1 router 1c

BGP path advertisement (more)



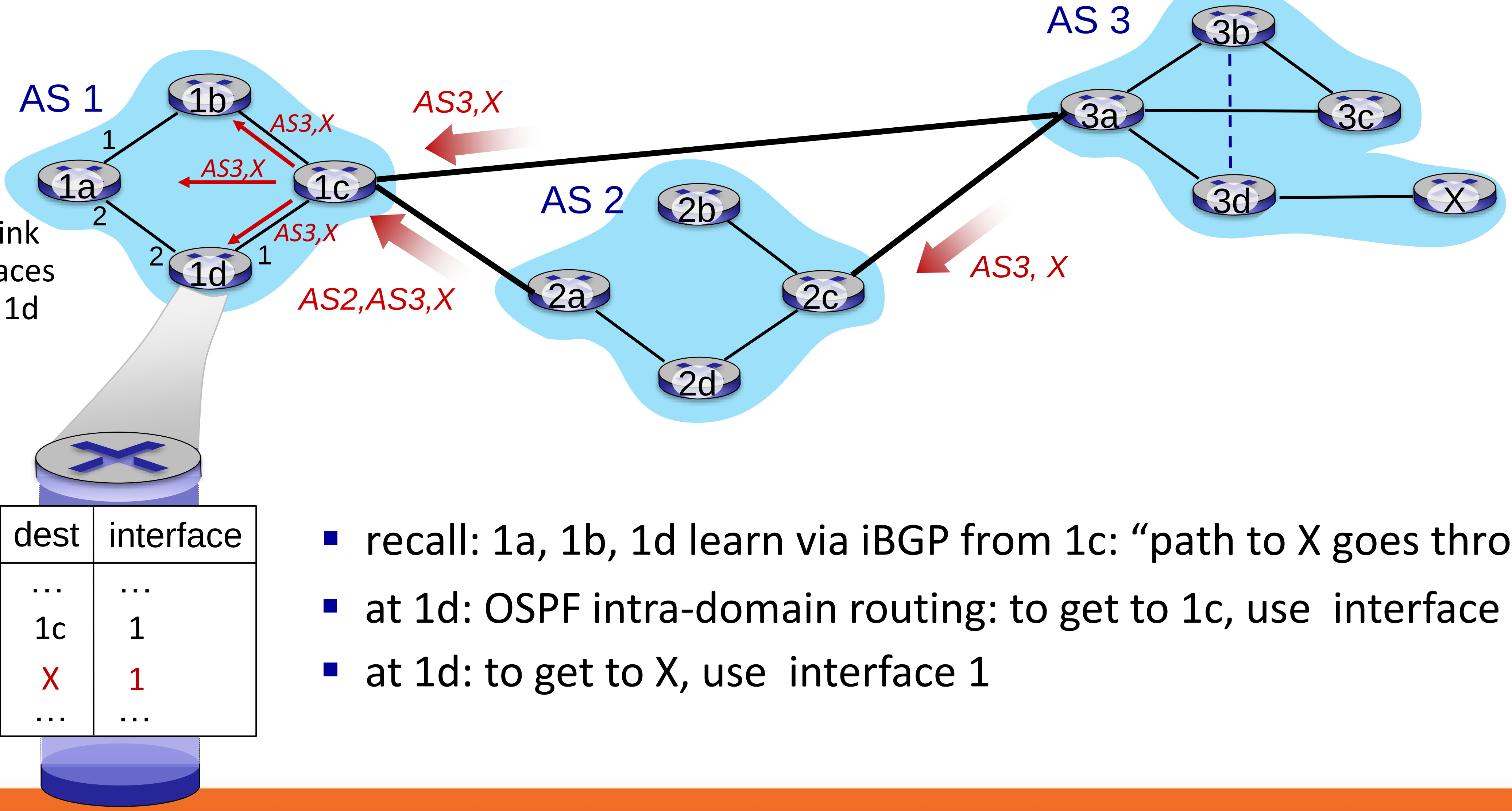
gateway router may learn about multiple paths to destination:

- AS1 gateway router 1c learns path *AS2,AS3,X* from 2a
- AS1 gateway router 1c learns path *AS3,X* from 3a
- based on *policy,* AS1 gateway router 1c chooses path *AS3,X* and advertises path within AS1 via iBGP

BGP messages

- BGP messages exchanged between peers over TCP connection
- BGP messages:
  - OPEN: opens TCP connection to remote BGP peer and authenticates sending BGP peer
  - UPDATE: advertises new path (or withdraws old)
  - KEEPALIVE: keeps connection alive in absence of UPDATES; also ACKs OPEN request
  - NOTIFICATION: reports errors in previous msg; also used to close connection

BGP path advertisement

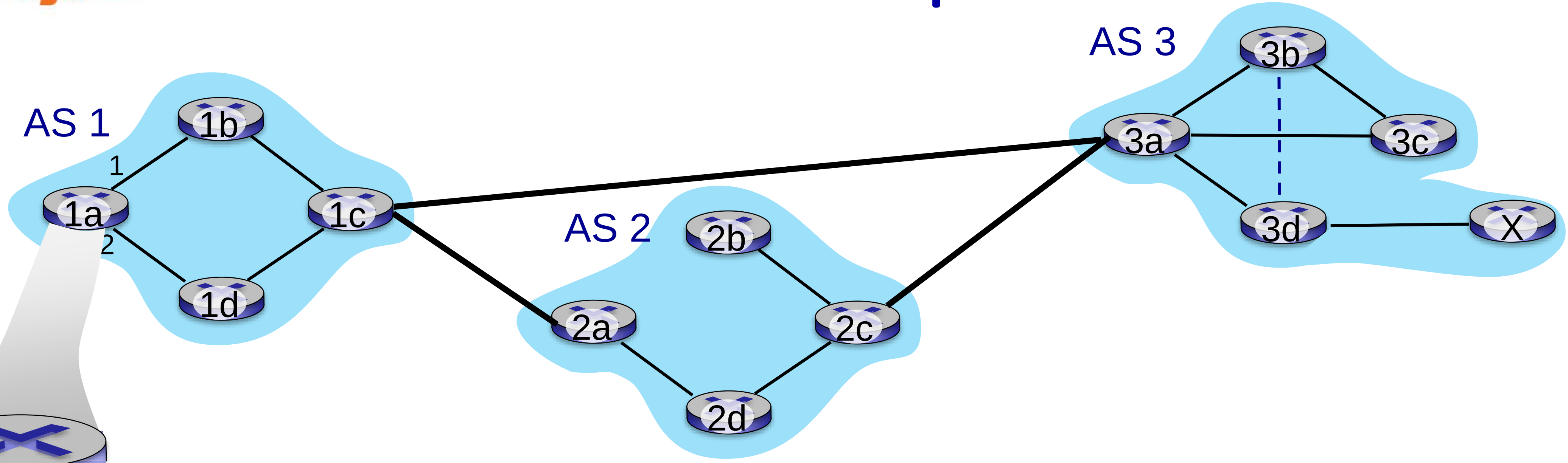


local link interfaces at 1a, 1d

dest	interface
…	…
1c	1
X	1
…	…

- recall: 1a, 1b, 1d learn via iBGP from 1c: “path to X goes through 1c”
- at 1d: OSPF intra-domain routing: to get to 1c, use interface 1
- at 1d: to get to X, use interface 1

BGP path advertisement



dest	interface
…	…
1c	2
X	2
…	…

- recall: 1a, 1b, 1d learn via iBGP from 1c: "path to X goes through 1c"
- at 1d: OSPF intra-domain routing: to get to 1c, use interface 1
- at 1d: to get to X, use interface 1
- at 1a: OSPF intra-domain routing: to get to 1c, use interface 2
- at 1a: to get to X, use interface 2

Why different Intra-, Inter-AS routing ?

policy:

- inter-AS: admin wants control over how its traffic routed, who routes through its network
- intra-AS: single admin, so policy less of an issue

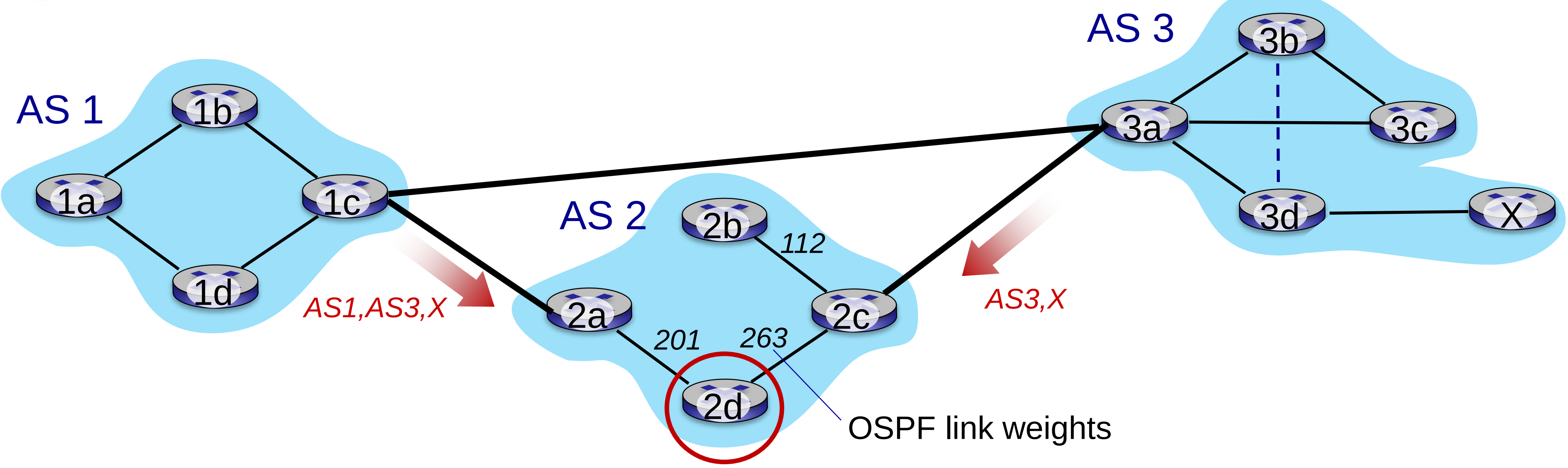
scale:

- hierarchical routing saves table size, reduced update traffic

performance:

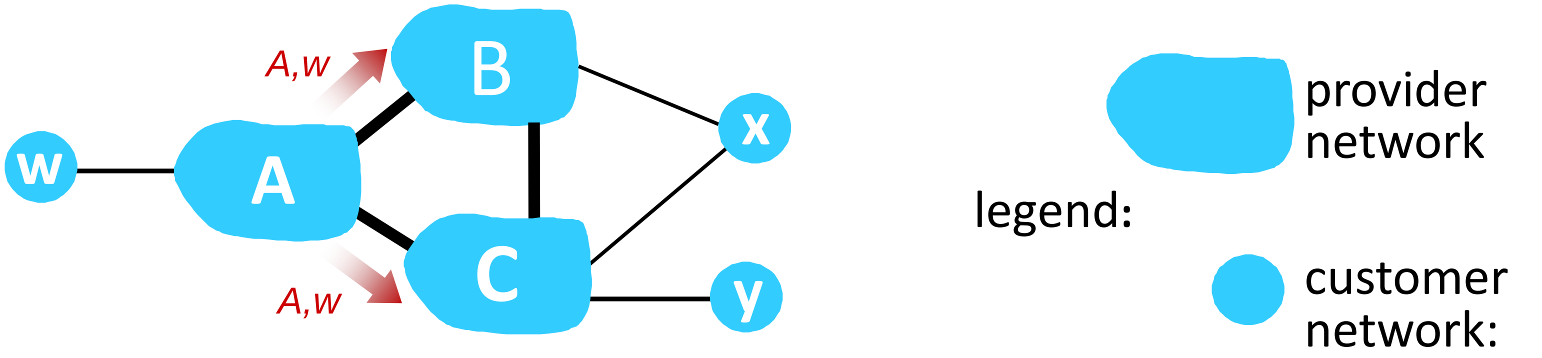
- intra-AS: can focus on performance
- inter-AS: policy dominates over performance

Hot potato routing



- 2d learns (via iBGP) it can route to X via 2a or 2c
- hot potato routing: choose local gateway that has least *intra-domain* cost (e.g., 2d chooses 2a, even though more AS hops to *X*): don't worry about inter-domain cost!

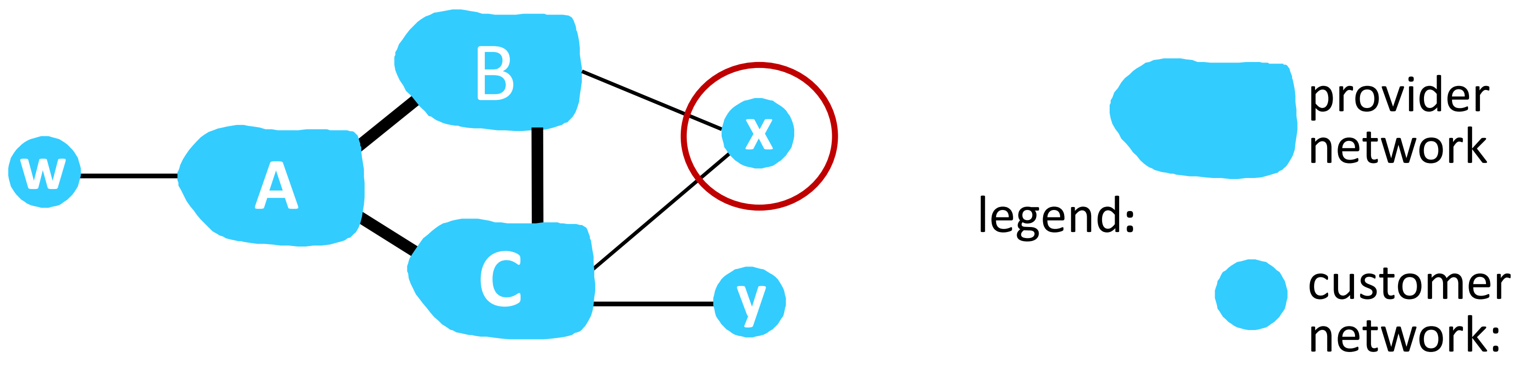
BGP: achieving policy via advertisements



ISP only wants to route traffic to/from its customer networks (does not want to carry transit traffic between other ISPs – a typical "real world" policy)

- A advertises path Aw to B and to C
- B *chooses not to advertise* BAw to C!
  - B gets no "revenue" for routing CBAw, since none of C, A, w are B's customers
  - C does *not* learn about CBAw path
- C will route CAw (not using B) to get to w

BGP: achieving policy via advertisements (more)



ISP only wants to route traffic to/from its customer networks (does not want to carry transit traffic between other ISPs – a typical “real world” policy)

- A,B,C are provider networks
- x,w,y are customer (of provider networks)
- x is dual-homed: attached to two networks
- *policy to enforce:* x does not want to route from B to C via x
  - .. so x will not advertise to B a route to C

BGP route selection

- router may learn about more than one route to destination AS, selects route based on:
  1. local preference value attribute: policy decision
  2. shortest AS-PATH
  3. closest NEXT-HOP router: hot potato routing
  4. additional criteria

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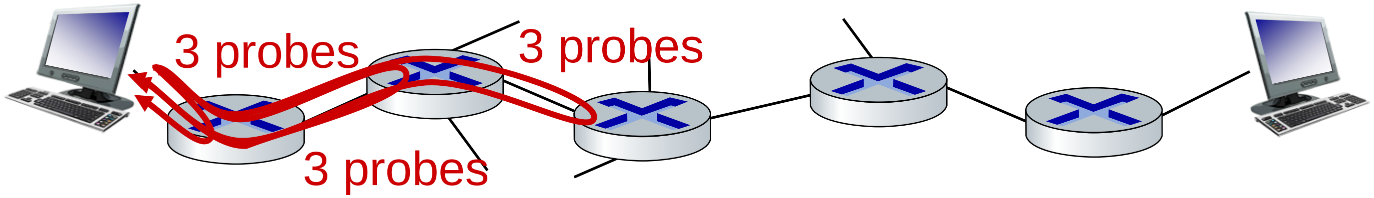
ICMP: internet control message protocol

- used by hosts and routers to communicate network-level information
  - error reporting: unreachable host, network, port, protocol
  - echo request/reply (used by ping)
- network-layer "above" IP:
  - ICMP messages carried in IP datagrams
- *ICMP message:* type, code plus first 8 bytes of IP datagram causing error

Type	Code	description
0	0	echo reply (ping)
3	0	dest. network unreachable
3	1	dest host unreachable
3	2	dest protocol unreachable
3	3	dest port unreachable
3	6	dest network unknown
3	7	dest host unknown
4	0	source quench (congestion control - not used)
8	0	echo request (ping)
9	0	route advertisement
10	0	router discovery
11	0	TTL expired
12	0	bad IP header

Traceroute and ICMP



- source sends sets of UDP segments to destination
  - 1st set has TTL =1, 2nd set has TTL=2, etc.
- datagram in *n*th set arrives to nth router:
  - router discards datagram and sends source ICMP message (type 11, code 0)
  - ICMP message possibly includes name of router & IP address
- when ICMP message arrives at source: record RTTs

stopping criteria:

- UDP segment eventually arrives at destination host
- destination returns ICMP "port unreachable" message (type 3, code 3)
- source stops

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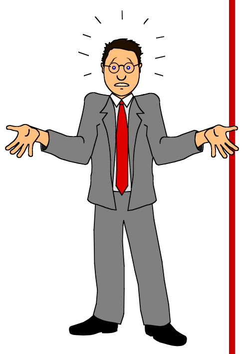
What is network management?

- autonomous systems (aka “network”): 1000s of interacting hardware/software components
- other complex systems requiring monitoring, configuration, control:
  - jet airplane, nuclear power plant, others?

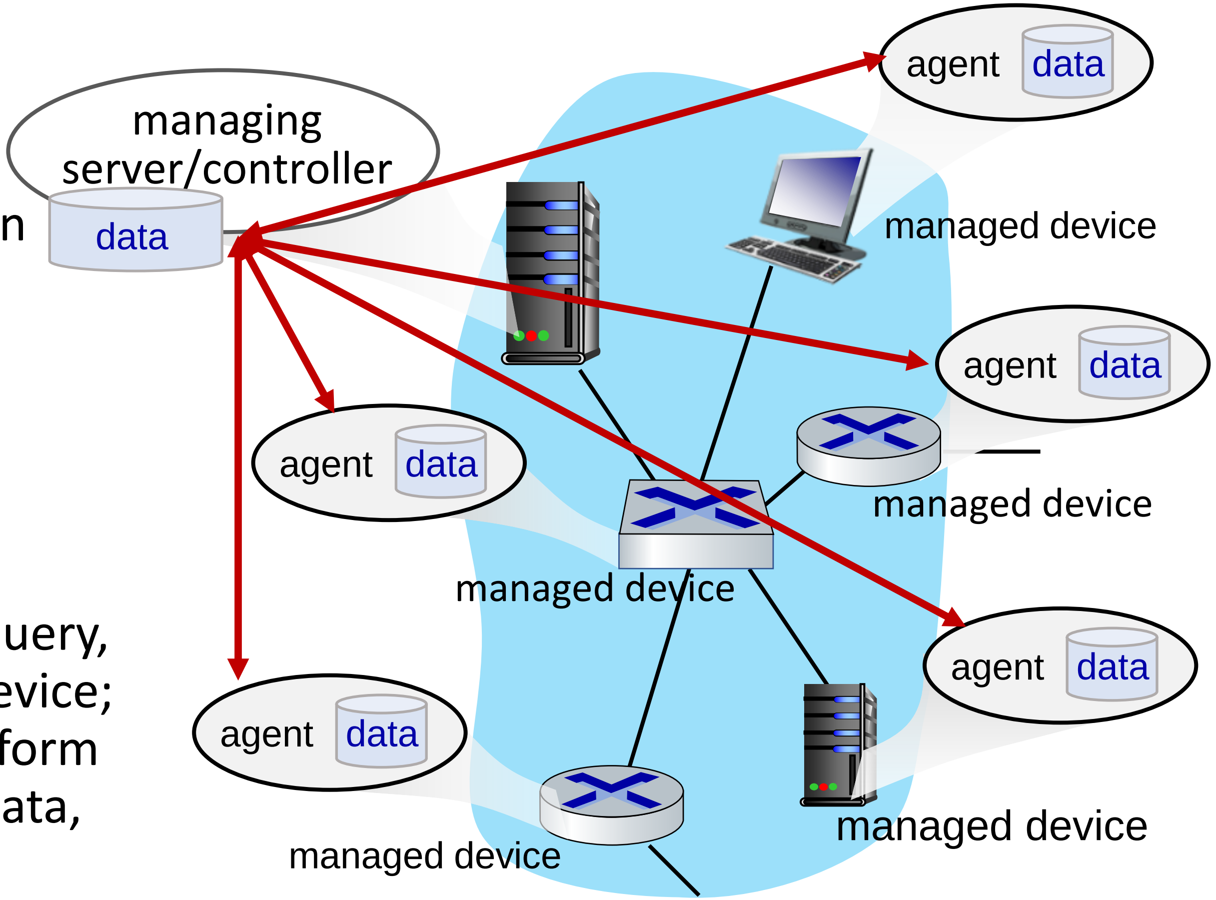


"Network management includes the deployment, integration and coordination of the hardware, software, and human elements to monitor, test, poll, configure, analyze, evaluate, and control the network and element resources to meet the real-time, operational performance, and Quality of Service requirements at a reasonable cost."

Components of network management

Managing server:
application, typically with network managers (humans) in the loop

Network management protocol:
used by managing server to query, configure, manage device; used by devices to inform managing server of data, events.



Managed device:
equipment with manageable, configurable hardware, software components

Data: device "state" configuration data, operational data, device statistics

Network operator approaches to management

CLI (Command Line Interface)

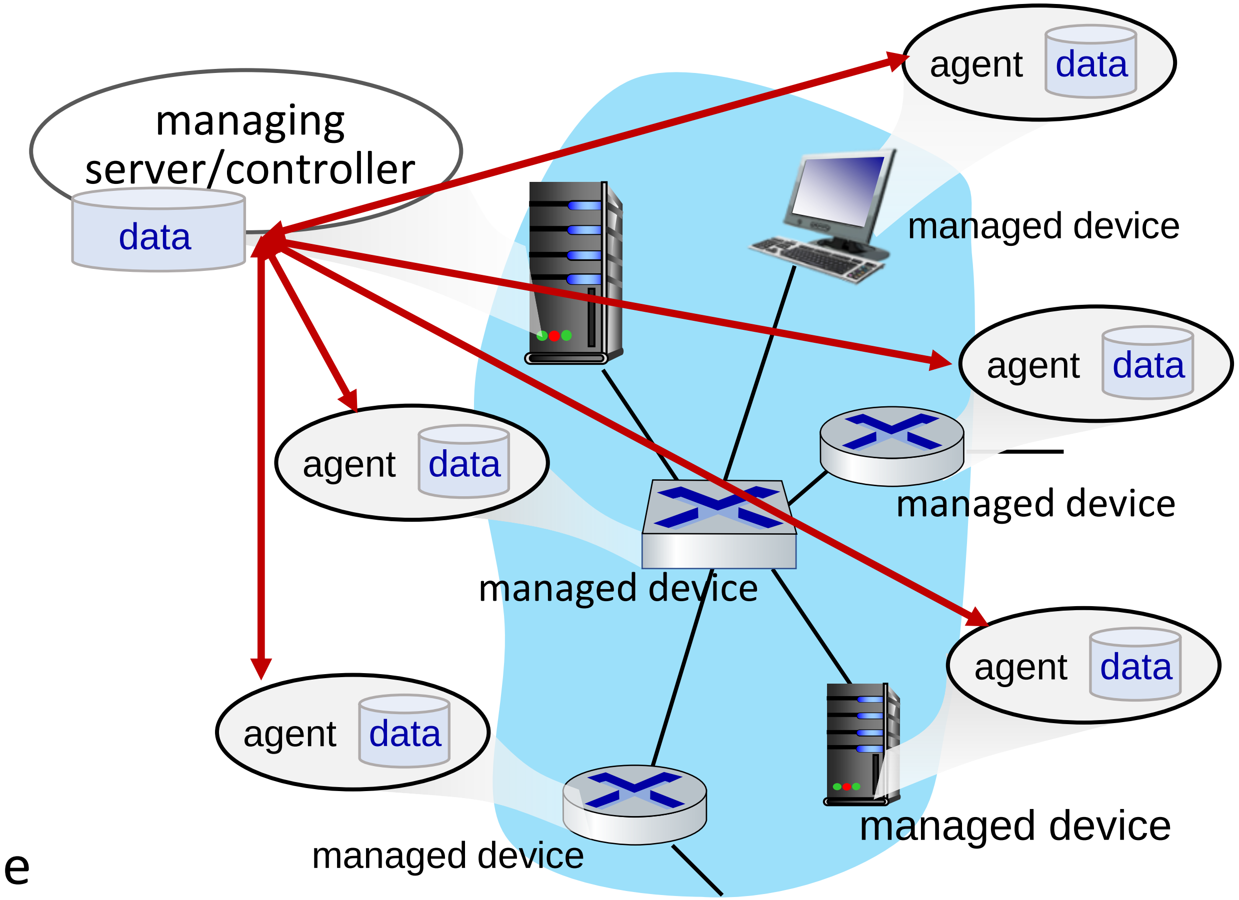
- operator issues (types, scripts) direct to individual devices (e.g., vis ssh)

SNMP/MIB

- operator queries/sets devices data (MIB) using Simple Network Management Protocol (SNMP)

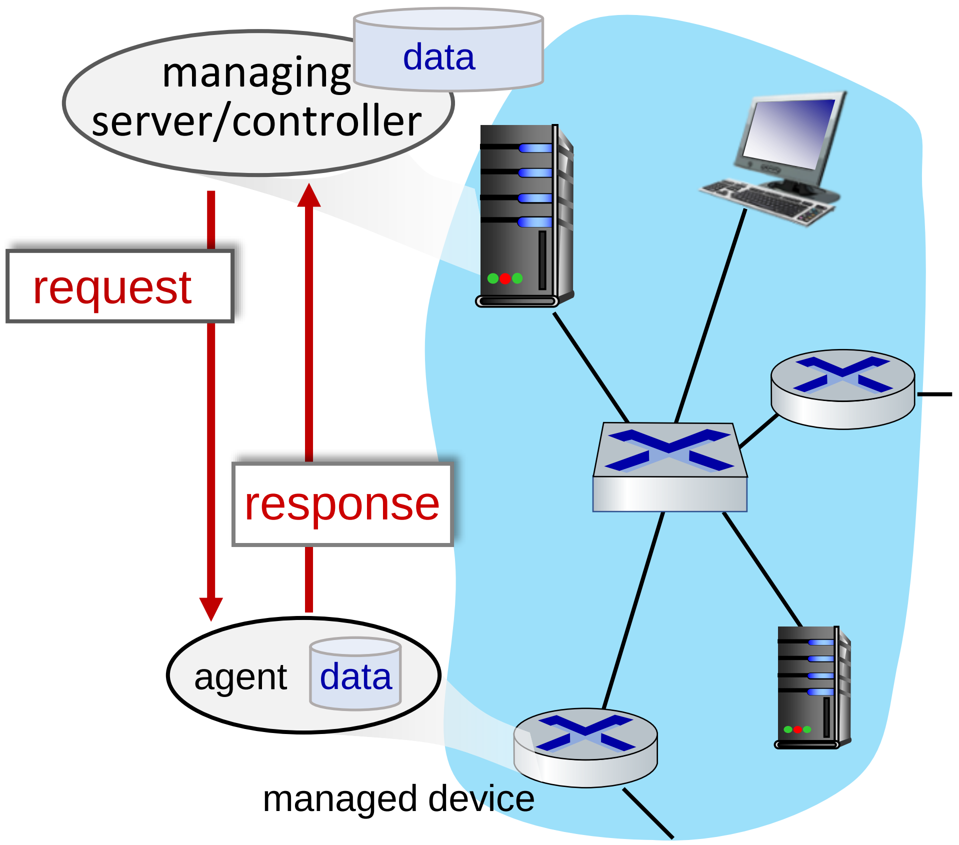
NETCONF/YANG

- more abstract, network-wide, holistic
- emphasis on multi-device configuration management.
- YANG: data modeling language
- NETCONF: communicate YANG-compatible actions/data to/from/among remote devices

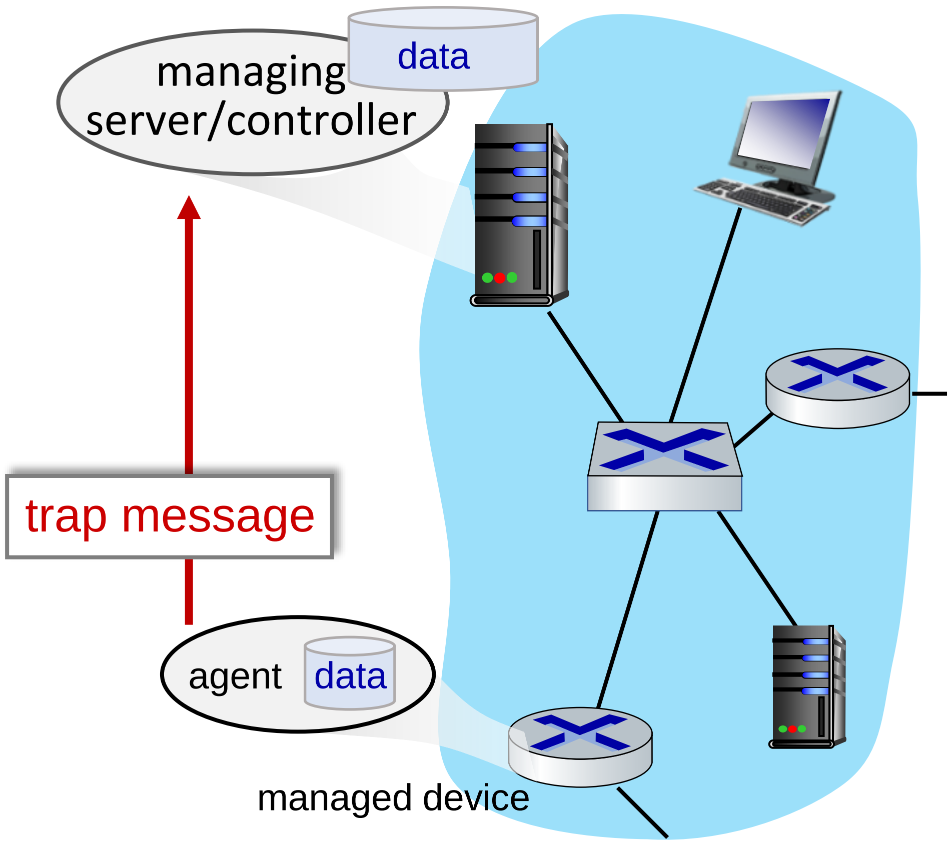


SNMP protocol

Two ways to convey MIB info, commands:



request/response mode

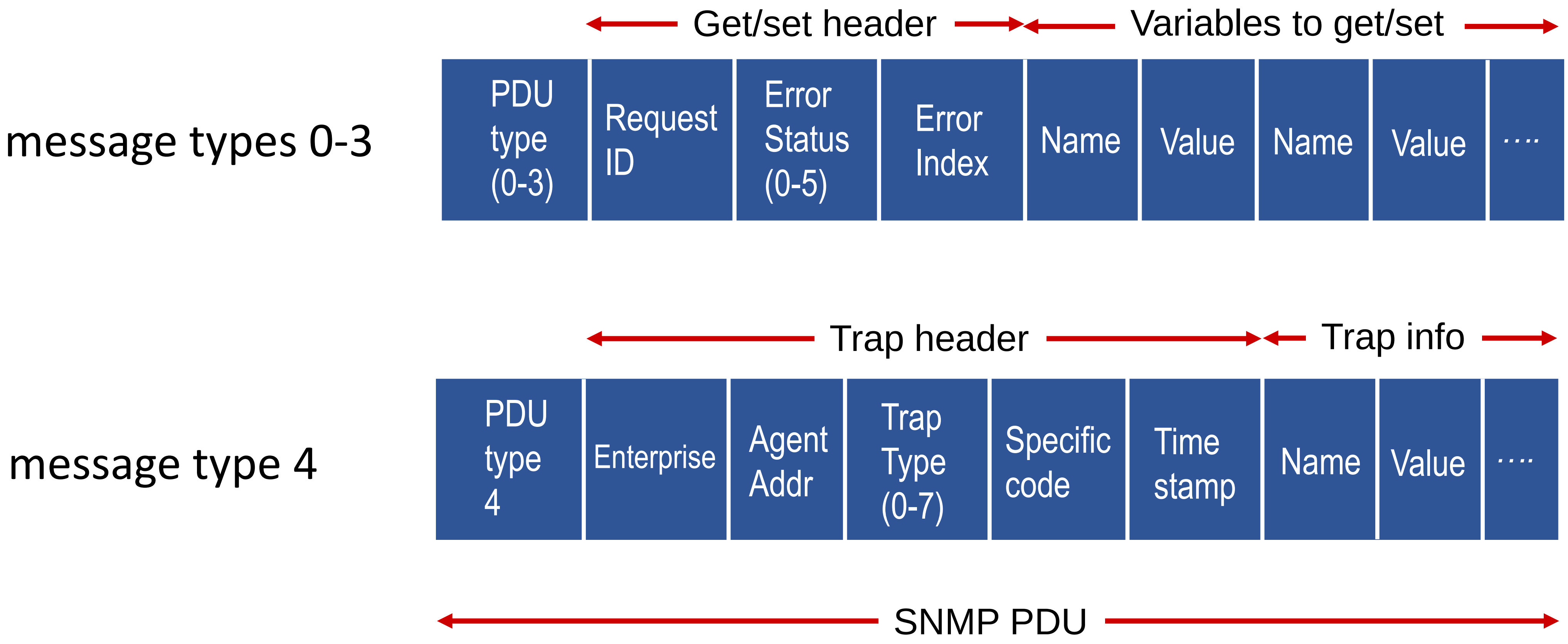


trap mode

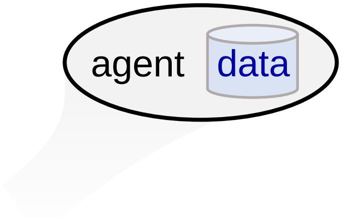
SNMP protocol: message types

Message type	Function
GetRequest GetNextRequest GetBulkRequest	manager-to-agent: "get me data" (data instance, next data in list, block of data).
SetRequest	manager-to-agent: set MIB value
Response	Agent-to-manager: value, response to Request
Trap	Agent-to-manager: inform manager of exceptional event

SNMP protocol: message formats



SNMP: Management Information Base (MIB)



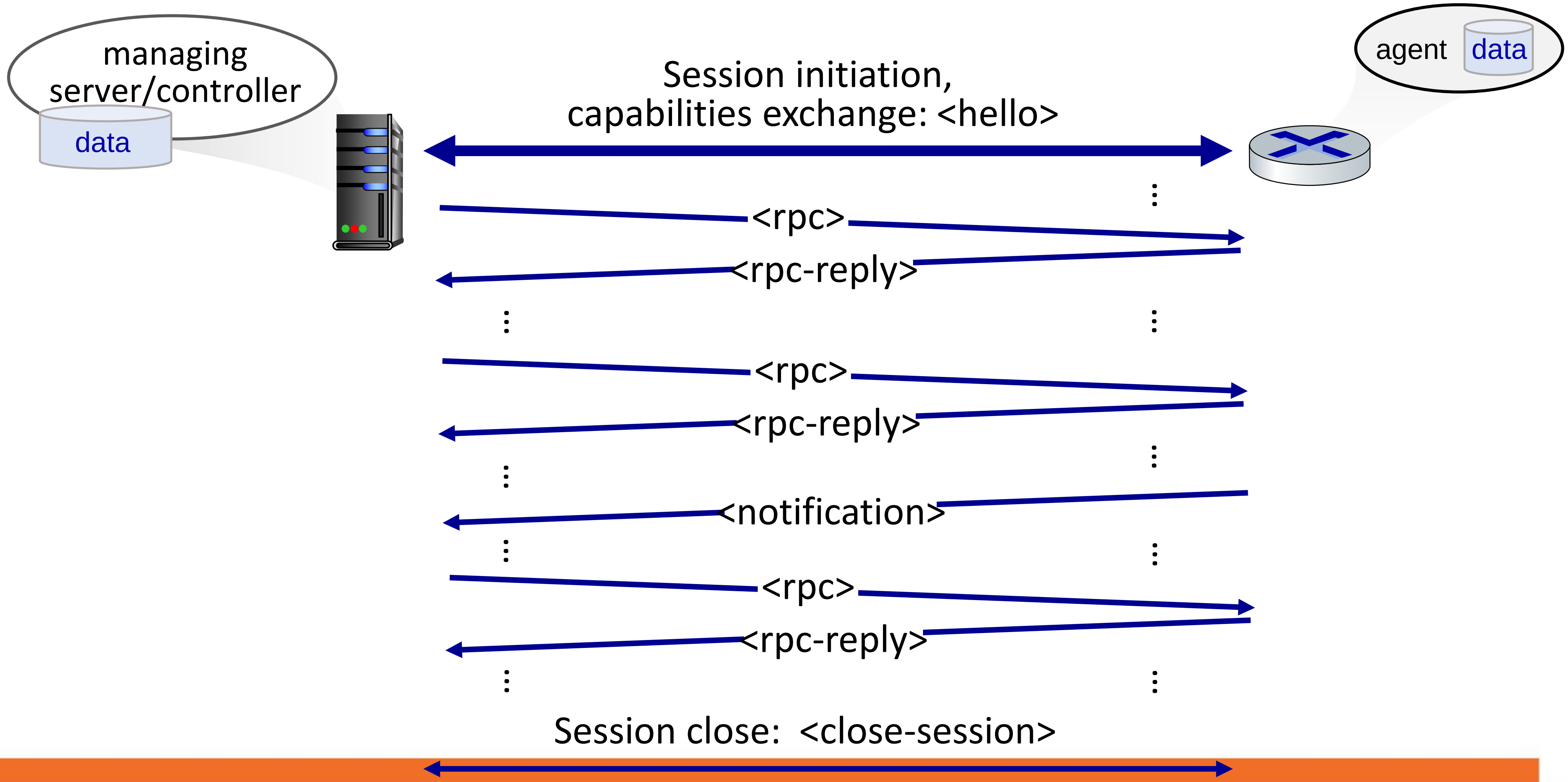
- managed device's operational (and some configuration) data
- gathered into device MIB module
  - 400 MIB modules defined in RFC's; many more vendor-specific MIBs
- Structure of Management Information (SMI): data definition language
- example MIB variables for UDP protocol:

Object ID	Name	Type	Comments
1.3.6.1.2.1.7.1	UDPInDatagrams	32-bit counter	total # datagrams delivered
1.3.6.1.2.1.7.2	UDPNoPorts	32-bit counter	# undeliverable datagrams (no application at port)
1.3.6.1.2.1.7.3	UDInErrors	32-bit counter	# undeliverable datagrams (all other reasons)
1.3.6.1.2.1.7.4	UDPOutDatagrams	32-bit counter	total # datagrams sent
1.3.6.1.2.1.7.5	udpTable	SEQUENCE	one entry for each port currently in use

NETCONF overview

- goal: actively manage/configure devices network-wide
- operates between managing server and managed network devices
  - actions: retrieve, set, modify, activate configurations
  - atomic-commit actions over multiple devices
  - query operational data and statistics
  - subscribe to notifications from devices
- remote procedure call (RPC) paradigm
  - NETCONF protocol messages encoded in XML
  - exchanged over secure, reliable transport (e.g., TLS) protocol

NETCONF initialization, exchange, close



Selected NETCONF Operations

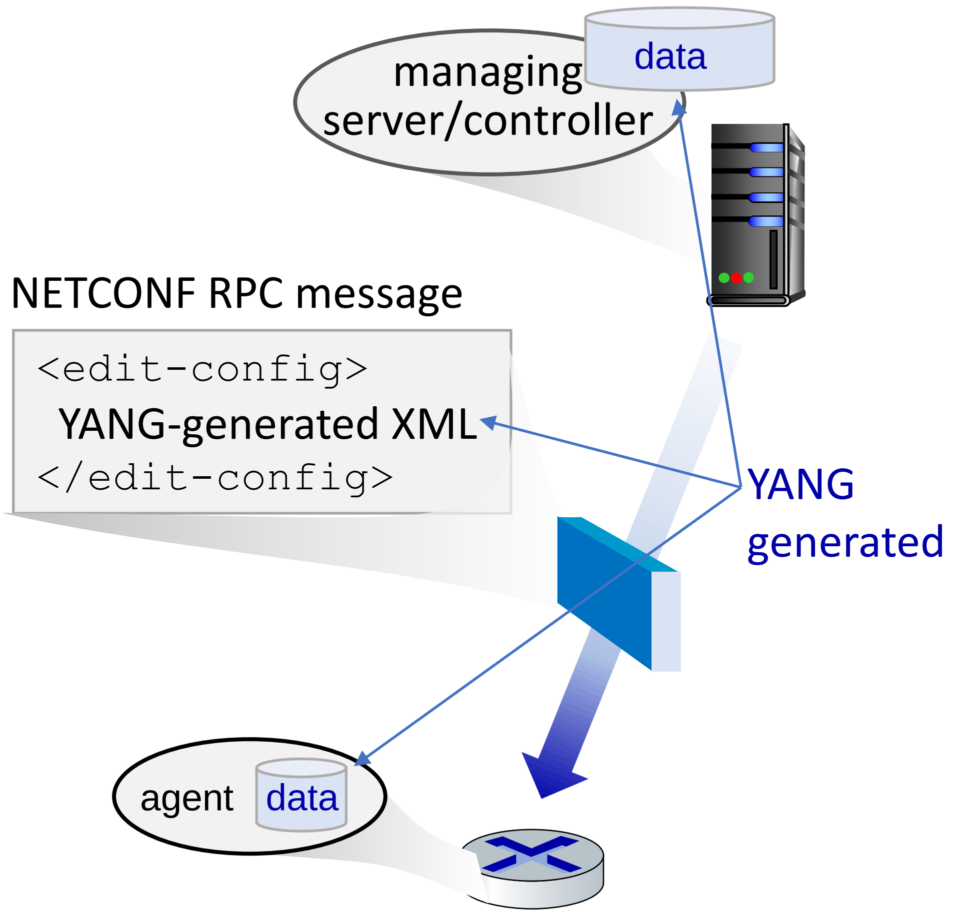
NETCONF	Operation Description
<get-config>	Retrieve all or part of a given configuration. A device may have multiple configurations.
<get>	Retrieve all or part of both configuration state and operational state data.
<edit-config>	Change specified (possibly running) configuration at managed device. Managed device <rpc-reply> contains <ok> or <rpcerror> with rollback.
<lock>, <unlock>	Lock (unlock) configuration datastore at managed device (to lock out NETCONF, SNMP, or CLIs commands from other sources).
<create-subscription>, <notification>	Enable event notification subscription from managed device

Sample NETCONF RPC message

```
<?xml version="1.0" encoding="UTF-8"?>
<rpc message-id="101"  note message id
  xmlns="urn:ietf:params:xml:ns:netconf:base:1.0">
  <edit-config>        change a configuration
    <target>
      <running/>  change the running configuration
    </target>
    <config>
      <top xmlns="http://example.com/schema/
      1.2/config">
        <interface>
          <name>Ethernet0/0</name>  change MTU of Ethernet 0/0 interface to 1500
          <mtu>1500</mtu>
        </interface>
      </top>
    </config>
  </edit-config>
</rpc>
```

YANG

- data modeling language used to specify structure, syntax, semantics of NETCONF network management data
  - built-in data types, like SMI
- XML document describing device, capabilities can be generated from YANG description
- can express constraints among data that must be satisfied by a valid NETCONF configuration
  - ensure NETCONF configurations satisfy correctness, consistency constraints



Network layer: Summary

we've learned a lot!

- approaches to network control plane
  - per-router control (traditional)
  - logically centralized control (software defined networking)
- traditional routing algorithms
  - implementation in Internet: OSPF , BGP
- SDN controllers
  - implementation in practice: ODL, ONOS
- Internet Control Message Protocol
- network management

next stop: link layer!

Network layer, control plane: Done!

- introduction
- routing protocols
  - link state
  - distance vector
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- SDN control plane
- Internet Control Message Protocol

- network management, configuration
  - SNMP
  - NETCONF/YANG

Additional Chapter 5 slides

Distance vector: another example

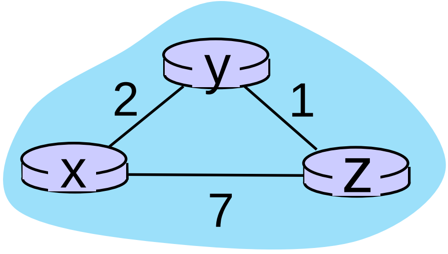
$D_x()$

from \ cost to	x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

$D_x(z) = \min\{c_{x,y} + D_y(z),\ c_{x,z} + D_z(z)\}$
$= \min\{2+1\ ,\ 7+0\} = 3$

$D_x(y) = \min\{c_{x,y} + D_y(y),\ c_{x,z} + D_z(y)\}$
$= \min\{2+0\ ,\ 7+1\} = 2$



$D_y()$

from \ cost to	x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

$D_z()$

from \ cost to	x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0

time

Distance vector: another example

$D_x()$

from \ cost to	x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

$D_y()$

from \ cost to	x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

from \ cost to	x	y	z
x	0	2	7
y	2	0	1
z	7	1	0

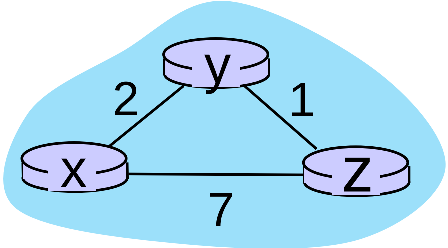
from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

$D_z()$

from \ cost to	x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0

from \ cost to	x	y	z
x	0	2	7
y	2	0	1
z	3	1	0

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0



time