Pham Minh Duc

Master 2 Student

+33 745 744 383

Email: Ducphamminh10082002@gmail.com

Personal Page: phamminhducH.github.io

Google Scholar: scholar.google.com/minhducpham

Education

- **Université Évry Paris-Saclay - France** *9/2025 - present*
  Master's degree in ***M2-Mechatronics, Machine Vision and Artificial Intelligence***
  Granted IDEX International Masters Scholarship of Université Paris-Saclay

- **Hanoi University of Science and Technology (HUST) - Vietnam** *10/2020 - 8/2024*
  Excellent Bachelor's Degree in ***Talented Program of Control Engineering and Automation***
  CPA: 3.8/4.0

Academic Experience

- **Motion Control and Applied Robotics Laboratory (MoCAR)** *11/2021 - 12/2024*
  University: ***Hanoi University of Science and Technology, Vietnam***
  Research orientation: ***Advanced controls for ballbot system***

- **TEEP Internship in Computational Intelligence and Robotics Lab (CIR)** *2/2025 - 5/2025*
  University: ***National Taiwan Normal University, Taiwan***
  Research orientation: ***Robot navigation system using deep reinforcement learning***

Research Publications

- **M. D. Pham**, D. C. Vu, T. T. H. Nguyen, T. V. A. Nguyen, and T. L. Nguyen, "CBFs-based Model Predictive Control for obstacles avoidance with tilt angle limitation for ball-balancing robots," *IEEE Access*, 2025.doi: 10.1109/ACCESS.2025.3567474
- D. C. Vu, **M. D. Pham**, T. T. H. Nguyen, T. V. A. Nguyen, and T. L. Nguyen, "Time-optimal trajectory generation and observer-based hierarchical sliding mode control for ballbots with system constraints," *International Journal of Robust and Nonlinear Control*, 2024. doi: 10.1002/rnc.7358
- Nguyen, P. N., Vu, D. C., **Pham, M. D.**, Nguyen, T. L., "Artificial Intelligence-Based Control: A Case Study for Balancing BallBots." *International Conference on Material, Machines and Methods for Sustainable Development.* Cham: Springer Nature Switzerland, 2024.doi: 10.1007/978-3-031-96126-7_16
- **Pham Minh Duc**, Vu Duc Cuong, Nguyen Thi Thuy Hang, Nguyen Danh Huy, Nguyen Thi Van Anh, Nguyen Tung Lam, "Dynamic Obstacle Avoidance Using Nonlinear Model Predictive Control and Control Barrier Function for Ballbot Systems," *Journal of Science and Technology: Smart Systems and Devices*, Hanoi University of Science and Technology, 2024, pp. 35-42. doi: 10.51316/jst.176.ssad.2024.34.3.5
- **M. D. Pham**, D. C. Vu, T. T. H. Nguyen, T. -V. -A. Nguyen, H. B. Dang and T. L. Nguyen, "Adaptive Mechanism Hierarchical Sliding Mode Control for Ballbot Systems," *2024 International Conference on Advanced Technologies for Communications (ATC)*, Ho Chi Minh City, Vietnam, 2024, pp. 797-802. doi: 10.1109/ATC63255.2024.10908289
- **M. D. Pham**, D. C. Vu, T. T. H. Nguyen, T. -V. -A. Nguyen, D. D. Vu and T. L. Nguyen, "Nonlinear Model Predictive Control for Ballbot systems: A benchmark with Hierarchical Sliding Mode and Linear Quadratic controls," *2023 12th International Conference on Control, Automation and Information Sciences (ICCAIS)*, Hanoi, Vietnam, 2023, pp. 411-416. doi: 10.1109/ICCAIS59597.2023.10382349
- **M. D. Pham**, C. M. Pham, T. G. Do, P. T. Dao, T. D. Van, Q. D. Hoang, and T. L. Nguyen, "Auto-balancing ballbot systems: A fractional- order sliding mode based radial-basis neural network approach," in *Advances in Engineering Research and Application: Proceedings of the International Conference on Engineering Research and Applications, ICERA 2022.* Springer, 2022, pp. 270–280. doi: 10.1007/978-3-031-22200-9_29

Achievements

- **Second Prize at Science and Technology Award for Students in Higher Education Institutions organized by Vietnamese Ministry of Education and Training** *11/2024*
- **Highest score in Bachelor Defense of Control Engineering and Automation** *7/2024*

- **First prize of the 41st HUST Conference of Student Scientific Research** *5/2024*
- **Three times received HUST Academic Incentive Scholarship for excellent students** *2022-2024*
- **Salutatorian in Entrance for Talent Program of Control Engineering and Automation** *10/2020*

Related Skills

- **Languages**: English - IELTS 7.0
- **Working with Programming**(MATLAB, Python, C++)/**Simulation**(MATLAB-Simulink, ROS2, LabVIEW) /**Hardware/Real Systems in Robotics and Control Engineering**
- **Reviewing and analyzing scientific articles**
- **Researching and team-working with foreign partners**

References

Assoc.Prof. Tung Lam Nguyen
Main Supervisor
Hanoi University of Science and Technology
lam.nguyentung@hust.edu.vn

Dr. Thi-Van-Anh Nguyen
Research Instructor
Hanoi University of Science and Technology
anh.nguyenthivan1@hust.edu.vn

Prof. Chen-Chien James Hsu
TEEF Internship Supervisor
National Taiwan Normal University, Taiwan
jhsu@ntnu.edu.tw