Succinct Vector Commitments from Lattices

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Vector Commitment

Formally defined by Dario Catalano and Dario Fiore [CF13].

Syntax:

- Setup($1^{\lambda}, 1^{\ell}$): Output *crs*.
- Commit(\vec{x} , crs): Output commitment \vec{c} to \vec{x} and state st.
- Open(crs, \vec{c} , \vec{x} , i): Output opening π_i at index i.
- Verify($crs, \vec{c}, i, x_i, \pi$): Check (x_i, π) is valid opening at index i.

Vector Commitment

Properties:

- Correctness. If $\vec{c} = Com(\vec{x}, crs)$ and $\pi = Open(crs, \vec{c}, \vec{x}, i)$ then $Verify(crs, \vec{c}, i, x_i, \pi) = 1$.
- Binding. Hard to find $x \neq x', \pi, \pi'$ s.t Verify(crs, \vec{c} , i, x_i , π) = Verify(crs, \vec{c} , i, x_i' , π') = 1.
- <u>Hiding.</u> Commitments and openings do not reveal anything about the vector.

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crs:
$$A_1, A_2, ..., A_\ell \in \mathbb{Z}_q^{m \times n}$$
 and $\vec{t}_1, \vec{t}_2, ..., \vec{t}_\ell \in \mathbb{Z}_q^n$ and $\{A_i^{-1}(\vec{t}_j)\}_{j \neq i}$.

<u>Commit</u>: For $\vec{x} = (x_1, x_2, ..., x_\ell)$, commitment is $\vec{c} = \sum_{i \in [\ell]} x_i \vec{t}_i$.

Opening at index i: A short vector $\vec{v_i}$ s.t $\vec{c} = A_i \vec{v_i} + x_i \vec{t_i}$

where $\vec{v}_i = \sum_{j \neq i} x_j A_i^{-1}(\vec{t}_j)$.

<u>Verification</u>: Check $\|\vec{v}_i\|$ is small and $\vec{c} = A_i \vec{v}_i + x_i \vec{t}_i$.

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Previous works ([PPS21], [ACL+22]):

- Can only commit $\vec{x} \in \{0,1\}^{\ell}$.
- In addition, the hiding property of [PPS21] is not proven.

This work [WW22]:

- Can commit any $\vec{x} \in \mathbb{Z}_q^{\ell}$.
- Hiding property is formally proven.

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SIS Assumption. Given $A \xleftarrow{\$} \mathbb{Z}_q^{m \times n}$, find $\vec{u} \in \mathbb{Z}_q^m$ s.t

$$\begin{cases} A\vec{u} = \vec{0}, \\ \|\vec{u}\| \text{ is small.} \end{cases}$$

 $\underline{\mathsf{ISIS}} \ \mathsf{Assumption}. \ \mathsf{Given} \ A \overset{\$}{\leftarrow} \mathbb{Z}_q^{m \times n} \ \mathsf{and} \ \vec{t} \overset{\$}{\leftarrow} \mathbb{Z}_q^n, \ \mathsf{find} \ \vec{u} \in \mathbb{Z}_q^m \ \mathsf{s.t}$

$$\begin{cases} A\vec{u} = \vec{t}, \\ \|\vec{u}\| \text{ is small.} \end{cases}$$

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Gadget Matrices

For integers n and q,

$$G_n = I_n \otimes \vec{g}^T = \begin{bmatrix} \vec{g} & & \\ & \vec{g} & \\ & & \ddots & \\ & & \vec{g} \end{bmatrix} \in \mathbb{Z}_q^{n \times m'} \text{ is the gadget matrix,}$$
 where $\vec{g} = (1, 2, 4, ..., 2^{\lceil log(q) \rceil})$ and $m' = n(\lceil log(q) \rceil + 1)$.

Gadget Trapdoors

There are efficient algorithms with the following syntax [MP12]:

- TrapGen(1ⁿ, q, m): Output (A, R) s.t AR = G and ||R|| is small. The distribution of A is statistically close to the uniform distribution.
- SamplePre (A, R, \vec{v}, s) : Output \vec{u} s.t $A\vec{u} = \vec{v}$. If AR = G, the distribution of \vec{u} is statistically close to $A^{-1}(\vec{v})$.

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The Basis-Augmented SIS (BASIS) Assumption

Sample($1^{\lambda}, A$):

Sample
$$i^* \stackrel{\$}{\leftarrow} [\ell], A_i \stackrel{\$}{\leftarrow} \mathbb{Z}_q^{(n+1) \times m} \ \forall i \neq i^*, \vec{a} \stackrel{\$}{\leftarrow} \mathbb{Z}_q^m \ \text{and} \ A_{i^*} = \begin{bmatrix} \vec{a}^T \\ A \end{bmatrix}$$
.

Output
$$B=egin{bmatrix} A_1 & & -G_{n+1} \\ & A_2 & & -G_{n+1} \\ & & \ddots & & \vdots \\ & & A_n & -G_{n+1} \end{bmatrix}$$
 and $aux=i^*.$

BASIS Assumption:

Given A, $B \leftarrow \mathsf{Sample}(1^{\lambda}, A)$ and the trapdoor $T \leftarrow B^{-1}(G)$, the SIS problem w.r.t A is still hard to solve.

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From previous works for binary vectors:

For binding at position 1, expect $\vec{c}=x_1\vec{t}_1+\vec{a}_1$ for public non-zero \vec{t}_1 and \vec{a}_1 .

Suppose there are $\vec{a_1},\vec{a_1}$ s.t $\vec{c}=1\cdot\vec{t_1}+\vec{a_1}=0\cdot\vec{t_1}+\vec{a_1}$. Then, we have $\vec{t_1}=\vec{a_1}-\vec{a_1}$.

If $\vec{a}_1=A_1\vec{v}_1$ and $\vec{a}_1'=A_1\vec{v}_1'$ for some vector \vec{v}_1 and \vec{v}_1' , then we have $\vec{t}_1=A_1(\vec{v}_1'-\vec{v}_1)$.

Restricting \vec{v}_1 and \vec{v}_1' to have small norm, then we have the ISIS solution, which is hard to find.

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Replacing \vec{t}_1 with $\vec{e}_1 = (1, 0, ..., 0)$, then $(x_1 - x_1')\vec{e}_1 = A_1(\vec{v}_1 - \vec{v}_1')$.

This becomes the SIS problem by removing the first row of A

 \Rightarrow Can commit for any $\vec{x} \in \mathbb{Z}_q^\ell$.

Generalizing for all i, we require $\vec{c} = x_i \vec{e}_1 + A_i \vec{v}_i$ for all $i \in [\ell]$.

In their work, the authors want $\vec{c} = G\vec{c}'$ where \vec{c}' has small norm for security analysis.

These relations can be expressed by a linear system:

$$\begin{bmatrix} A_1 & & -G \\ & A_2 & & -G \\ & & \ddots & & \vdots \\ & & A_{\ell} & -G \end{bmatrix} \cdot \begin{bmatrix} \vec{v}_1 \\ \vec{v}_2 \\ \vdots \\ \vec{v}_{\ell} \\ \vec{c}' \end{bmatrix} = \begin{bmatrix} -x_1 \vec{e}_1 \\ -x_2 \vec{e}_1 \\ \vdots \\ -x_{\ell} \vec{e}_1 \end{bmatrix}$$
(1

Intuition

To commit
$$\vec{x} = (x_1, x_2, ..., x_\ell)$$
, let $B_\ell = \begin{bmatrix} A_1 & & -G \\ & A_2 & & -G \\ & & \ddots & \vdots \\ & & & A_\ell & -G \end{bmatrix}$.

Sample a vector
$$\begin{vmatrix} \vec{v}_1 \\ \vec{v}_2 \\ \vdots \\ \vec{v}_\ell \\ \vec{c}' \end{vmatrix}$$
 of small norm that satisfies (1).

This yields a commitment $\vec{c} = G\vec{c}'$ and openings $\vec{v}_1, \vec{v}_2, ..., \vec{v}_\ell$.

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$\mathsf{Setup}(1^\lambda, 1^\ell)$:

Sample $(A_i, R_i) \leftarrow \mathsf{TrapGen}(1^{\lambda}, q, m)$ for all $i \in [\ell]$.

Let
$$B = \begin{bmatrix} A_1 & & & -G \\ & A_2 & & -G \\ & & \ddots & & \vdots \\ & & A_\ell & -G \end{bmatrix} \in \mathbb{Z}_q^{n\ell \times (\ell m + m')}$$

and
$$R = \begin{bmatrix} \operatorname{diag}(R_1, R_2, \dots, R_\ell) \\ 0^{m' \times \ell m'} \end{bmatrix} \in \mathbb{Z}_q^{(\ell m + m') \times \ell m'}$$

Sample $T \leftarrow SamplePre(B_{\ell}, R, G_{n\ell}, s_0)$.

Output $crs = (A_1, A_2, \ldots, A_\ell, T)$.

Vector Commitment from SIS

$$\begin{aligned} & \underbrace{\mathsf{Com}(\vec{x},\mathit{crs} = (A_1,A_2,\ldots,A_\ell,T)):}_{\vec{V_1}} \\ & \mathsf{Sample} \begin{bmatrix} \vec{v}_1 \\ \vec{v}_2 \\ \vdots \\ \vec{v}_\ell \\ \vec{c}' \end{bmatrix} = \mathsf{SamplePre}(B_\ell,T,-\vec{x}\otimes\vec{e}_1,s_1) \\ & \mathsf{where} \ \vec{e}_1 = (1,0,...,0) \in \mathbb{Z}_q^\ell. \\ & \mathsf{Output} \ \mathsf{commitment} \ \vec{c} = G\vec{c}' \in \mathbb{Z}_q^n \ \mathsf{and} \ \mathsf{state} \ st = (\vec{v}_1,\vec{v}_2,...,\vec{v}_\ell). \\ & \underbrace{\mathsf{Open}(\mathit{crs},\vec{c},\vec{x},i):}_{\mathsf{Verify}} \ \mathsf{Output} \ \vec{v}_i. \\ & \underbrace{\mathsf{Verify}(\mathit{crs},\vec{c},i,x_i,\pi):}_{\mathsf{Check}} \ \|\vec{v}_i\| \leq B \ \mathsf{and} \ \vec{c} = A_i\vec{v}_i + x_ie_1 \end{aligned}$$

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Linear Homomorphism

For \vec{x} and \vec{z}' with commitments \vec{c} and \vec{c}' , observe that for all i:

$$\vec{c} + \vec{c}' = A_i(\vec{v}_i + \vec{v}_i') + (x_i + x_i')e_1.$$

Thus, the commitment to $\vec{x} + \vec{x}'$ is equal to $\vec{c} + \vec{c}'$, and the opening at index i is equal to $\vec{v}_i + \vec{v}'_i$.

Notice that the norm of the openings is increased (from B to 2B).

 \Rightarrow Can only support a bounded number of additions.

Updatability

Given (\vec{x}, \vec{c}) , suppose we want to update to (\vec{x}', \vec{c}') s.t \vec{x}' differ from \vec{x} at exactly one position i.

Let $\vec{x}^* = \vec{x}' - \vec{x}$ and \vec{c}^* be the commitment to \vec{x}^* , then $\vec{c} + \vec{c}^*$ is the commitment to \vec{x}' and $\vec{v}_i + \vec{v}_i^*$ is the opening at position i of \vec{x}' .

We know that $\vec{x}^* = (0, 0, ..., x_i' - x_i, 0, ..., 0)$.

Hence, the update step can be done without knowing the other positions of \vec{x} .

Once again, because of norm bound, we can only update a bounded number of times.

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Application: Verkle Tree

Verkle Tree

- Introduced by John Kuszmaul [Kus18].
- Use commitment scheme instead of hashing.
- Recommended using KZG by Vitalik [But21].
 - \Rightarrow Not quantum secure.

Application: Verkle Tree

<u>Idea worth trying:</u> Replacing KZG with a lattice-based vector commitment for post-quantum security.

<u>Limitations</u>: Many restrictions for lattice based construction,

e.g., bounded norm forbids many updates,...

Thank You

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