

# Expanded 1-Month CFD Solver & MDO Project Plan

## 1) Overall scope & tech stack

- Language: C++17 (good perf, CGNS API, easy bindings).
- Libraries: CGNS C API (mesh IO), NLOpt or Pagmo (optim), Eigen (linear algebra for convenience), tinyyaml/CLI11 (config/CLI), matplotlib-cpp or CSV dump + Python for plots.
- Post: ParaView/Tecplot for contours; Python for  $C_p$  / objective history charts.
- Build: CMake; unit tests via Catch2 (lightweight).

## 2) Week 1 — Foundation setup (mesh, CGNS, baseline Euler solver)

**\*\*Goal:\*\*** Read a CGNS mesh, run a steady 2D compressible Euler solver, validate on an oblique shock over a wedge.

### ### 2.1 Mesh & geometry (CGNS)

- Create meshes in Gmsh (airfoil + combustor duct).
- Export to CGNS, keep boundary tags ('farfield', 'wall', 'inlet', 'outlet').
- CGNS reader: read coords, connectivity, BCs. Build cell-centered storage, compute metrics (area, normals, centroids).

### ### 2.2 Governing equations (Euler, 2D)

- State:  $U = [\rho, \rho u, \rho v, E]$ .
- Flux via Riemann solver.
- Numerics: HLLC Riemann, MUSCL+limiter, TVDRK3 time march, local dt by CFL.
- BCs: inflow/outflow, slip wall, farfield.
- Validation: Wedge shock angle vs oblique-shock theory.

**\*\*Deliverable:\*\*** residual plots, shock contours, pressure line probe.

## 3) Week 2 — Project 1: Non-reacting airfoil MDO

**\*\*Goal:\*\*** Black-box shape optimization: minimize drag with lift constraint.

### ### Geometry parameterization

- Bézier control points or Hicks–Henne bumps.
- Remesh each design in Gmsh to avoid mesh morphing.

### ### CFD black-box objective

- Inputs: design vector  $\rightarrow$  geometry  $\rightarrow$  mesh  $\rightarrow$  solver.
- Outputs: CL, CD.
- Objective:  $J = CD + \mu[\max(0, CL_{req} - CL)]^2$ .

### ### Optimizer

- NLOpt or Pagmo, 3–5 vars, derivative-free (COBYLA, ISRES, etc).
- Bounds on geometry.
- Cap ~50–100 evals.

### ### Deliverables

- $C_p$  curves, Mach/pressure contours, optimization history, report with drag reduction vs baseline.

## 4) Week 3 — Project 2 start: Reacting-flow extension

**Goal:** Extend solver to multi-species Euler + 1-step chemistry.

### Governing equations

- Species mass fractions  $Y_s$ , source terms from Arrhenius law.
- Thermo:  $cp(T)$ ,  $\gamma(T)$  from mixture.

### Numerics

- Operator splitting: Euler convection + chemistry ODE per cell.
- Integration: backward Euler or sub-cycled explicit.

### Validation case

- Supersonic duct with side injector.
- Expect shock/flame interaction,  $T$  rise, total pressure loss.

**Deliverable:** species/ $T$ /Mach fields, residual plots, physical sanity check.

## 5) Week 4 — Project 2 MDO (reacting combustor)

**Goal:** Optimize combustor design variables for efficiency/thrust.

### Design variables

- Wall divergence angle, injector location/angle, fuel rate, cavity length.

### Objective & constraints

- Maximize efficiency or thrust.
- Minimize total pressure loss (penalty).
- Constraints: max wall heat flux, static pressure limits.

### Optimization loop

- Budget: 5–10 evaluations.
- Reuse optimizer structure from Project 1.
- Deliverables: contours, efficiency history, comparison with baseline.

## 6) Code architecture

```
...  
/cfd  
/mesh // CGNS reader, BC maps  
/numerics // Riemann, reconstruction, time integrators  
/euler // non-reacting solver  
/reacting // multi-species + chemistry  
/io // CGNS writers, CSV/VTK exporters  
/mdo // optimizer bindings, geometry  
/utils // logging, timers  
main.cpp // CLI entry point  
...
```

Configs via YAML (flow inputs, CFL, chemistry, optimizer).

## 7) Implementation details & guardrails

#### ### Riemann + reconstruction

- HLLC robust for shocks, Roe optional.
- Limiters: Venkatakrishnan, ensure positivity.

#### ### Convergence & efficiency

- CFL ramping, restart/warm-start, coarse mesh to fine.

#### ### Robustness

- Enforce positive  $\rho$ ,  $p$ ,  $Y_s$ .
- Chemistry: cap T and enforce  $\sum(Y_s)=1$ .

## 8) Minimal day-by-day milestones

D1–2: CGNS reader, mesh/BC check.

D3–4: HLLC+MUSCL+RK3, uniform flow test.

D5: Wedge shock validation.

D6–8: Airfoil parametric + optimizer wiring.

D9–10: Run airfoil optimization, report.

D11–13: Reacting extension + duct injector case.

D14: Combustor MDO run (5–10 evals), final report.

## 9) Deliverables

- Codebase (solver + optimizer scripts).
- Configs (.geo, .yaml).
- Plots:  $C_p$  curves, contours, optimization history.
- Reports: Airfoil (Proj 1), Combustor (Proj 2).