Algorithms

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2.2 MERGESORT

- mergesort
- bottom-up mergesort
- sorting complexity
- comparators
 - stability

Complexity of sorting

Computational complexity. Framework to study efficiency of algorithms for solving a particular problem *X*.

Model of computation. Allowable operations.

Cost model. Operation count(s).

Upper bound. Cost guarantee provided by some algorithm for *X*.

Lower bound. Proven limit on cost guarantee of all algorithms for X.

Optimal algorithm. Algorithm with best possible cost guarantee for *X*.

lower bound ~ upper bound

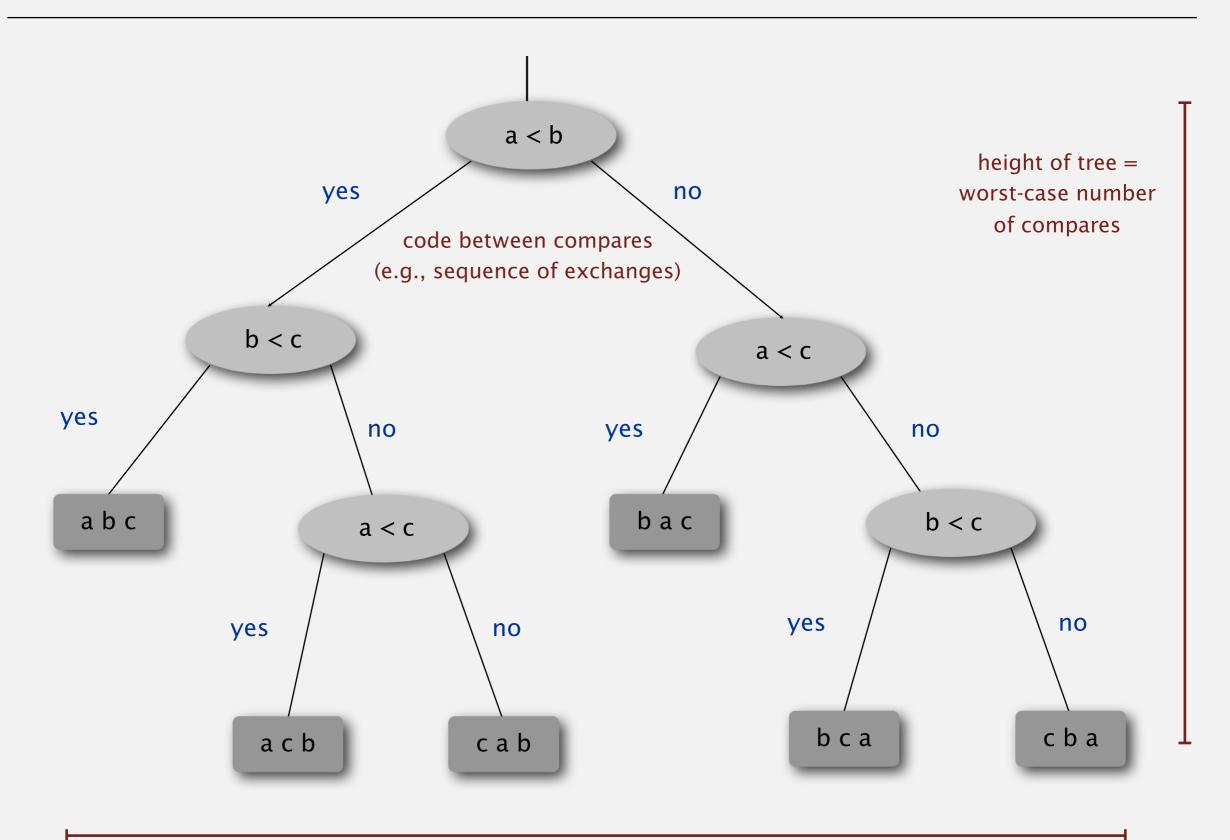
Example: sorting.

- Model of computation: decision tree.

 can access information
 only through compares

 (e.g., Java Comparable framework)
- Cost model: # compares.
- Upper bound: $\sim N \lg N$ from mergesort.
- Lower bound:
- Optimal algorithm:

Decision tree (for 3 distinct keys a, b, and c)

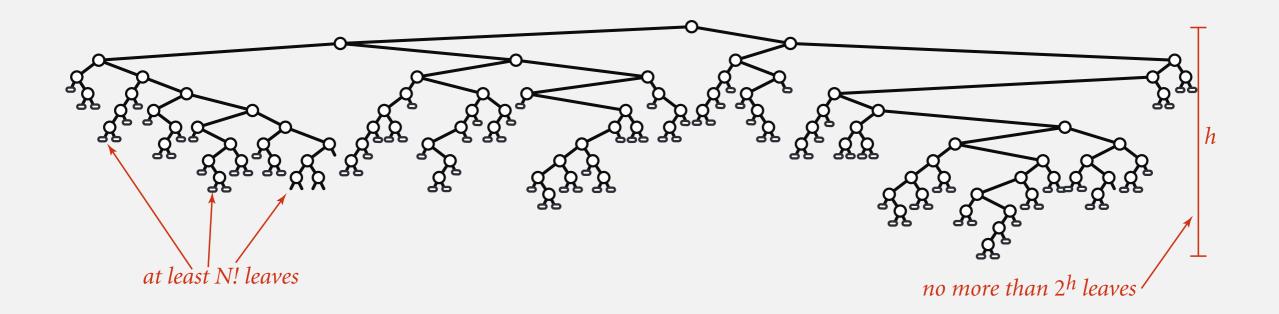


Compare-based lower bound for sorting

Proposition. Any compare-based sorting algorithm must use at least $lg(N!) \sim N lg N$ compares in the worst-case.

Pf.

- Assume array consists of N distinct values a_1 through a_N .
- Worst case dictated by height h of decision tree.
- Binary tree of height h has at most 2^h leaves.
- N! different orderings \Rightarrow at least N! leaves.

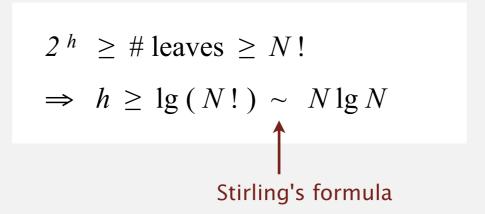


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Example: sorting.

- Model of computation: decision tree.
- Cost model: # compares.
- Upper bound: $\sim N \lg N$ from mergesort.
- Lower bound: $\sim N \lg N$.
- Optimal algorithm = mergesort.

First goal of algorithm design: optimal algorithms.

Complexity results in context

Compares? Mergesort is optimal with respect to number compares.

Space? Mergesort is not optimal with respect to space usage.



Lessons. Use theory as a guide.

- Ex. Design sorting algorithm that guarantees $\frac{1}{2}N \lg N$ compares?
- Ex. Design sorting algorithm that is both time- and space-optimal?

Complexity results in context (continued)

Lower bound may not hold if the algorithm can take advantage of:

The initial order of the input.

Ex: insert sort requires only a linear number of compares on partially-sorted arrays.

The distribution of key values.

Ex: 3-way quicksort requires only a linear number of compares on arrays with a constant number of distinct keys. [stay tuned]

The representation of the keys.

Ex: radix sort requires no key compares — it accesses the data via character/digit compares.