Algorithms

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http://algs4.cs.princeton.edu

2.4 PRIORITY QUEUES

- API and elementary implementations
- binary heaps
- heapsort
- event-driven simulation

Sorting with a binary heap

Q. What is this sorting algorithm?

```
public void sort(String[] a)
{
   int N = a.length;
   MaxPQ<String> pq = new MaxPQ<String>();
   for (int i = 0; i < N; i++)
        pq.insert(a[i]);
   for (int i = N-1; i >= 0; i--)
        a[i] = pq.delMax();
}
```

- Q. What are its properties?
- A. $N \log N$, extra array of length N, not stable.

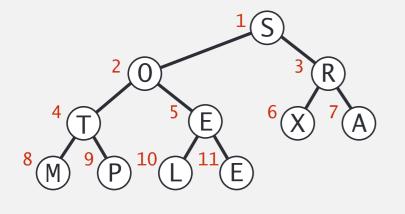
Heapsort intuition. A heap is an array; do sort in place.

Heapsort

Basic plan for in-place sort.

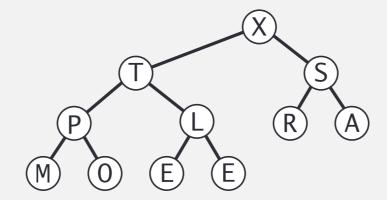
- View input array as a complete binary tree.
- Heap construction: build a max-heap with all N keys.
- Sortdown: repeatedly remove the maximum key.

keys in arbitrary order



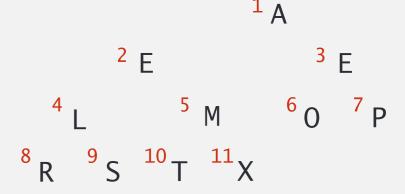
1 2 3 4 5 6 7 8 9 10 11 S O R T E X A M P L E

build max heap (in place)





sorted result (in place)



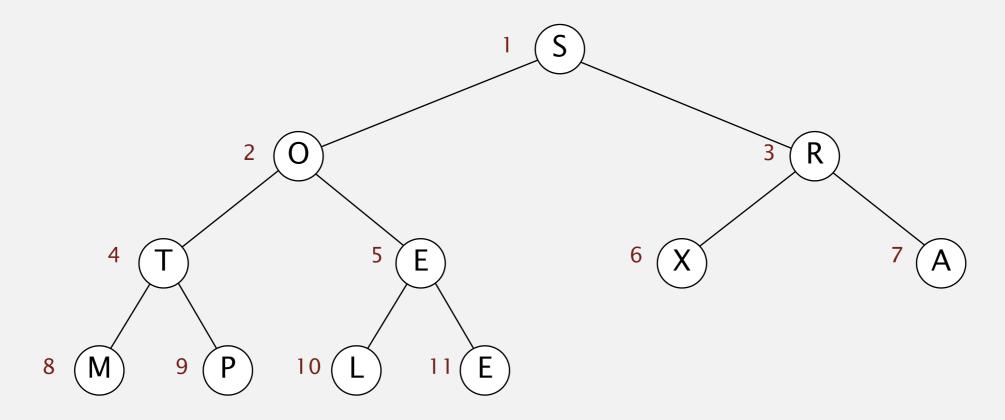


Heapsort demo

Heap construction. Build max heap using bottom-up method.

we assume array entries are indexed 1 to N

array in arbitrary order





S	0	R	Т	Ε	X	Α	М	Р	L	Ε
1	2	3	4	5	6	7	8	9	10	11

Heapsort demo

Sortdown. Repeatedly delete the largest remaining item.

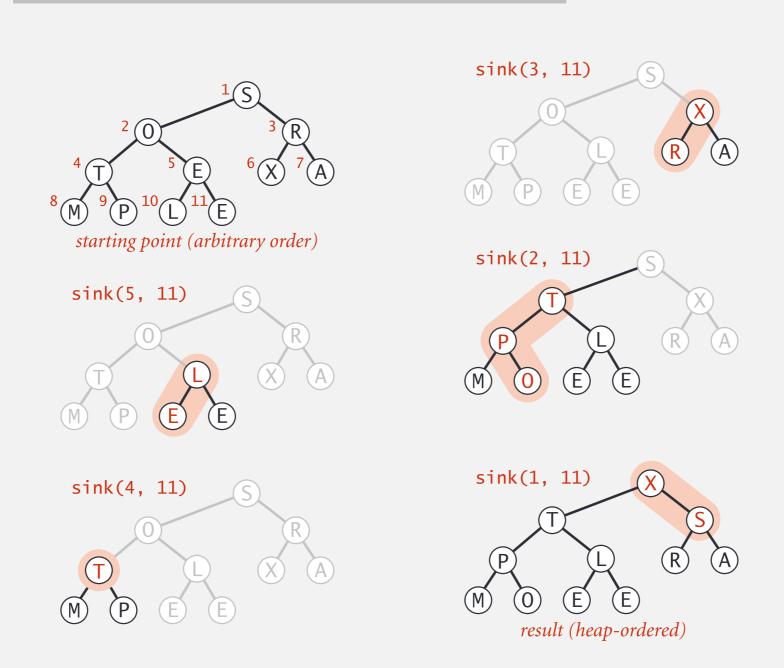
array in sorted order



Α	Ε	Ε	L	М	0	Р	R	S	Т	X
1	2	3	4	5	6	7	8	9	10	11

Heapsort: heap construction

First pass. Build heap using bottom-up method.

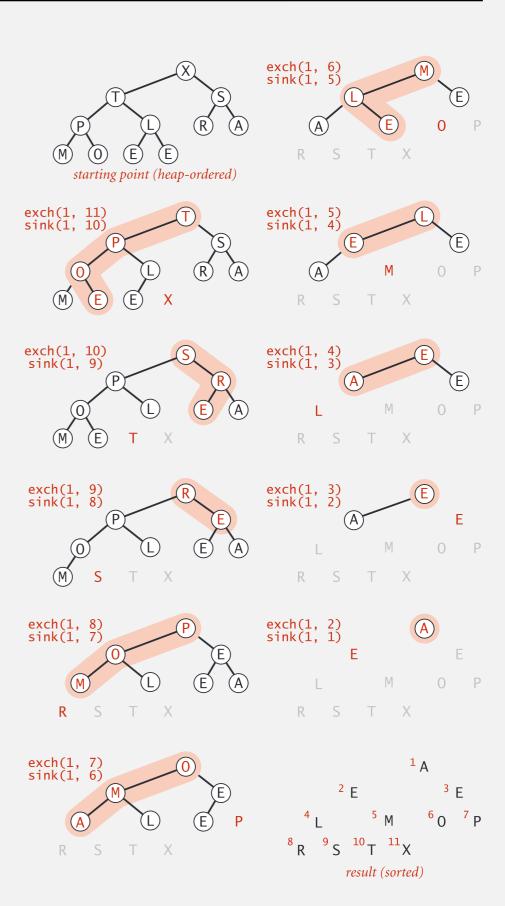


Heapsort: sortdown

Second pass.

- Remove the maximum, one at a time.
- Leave in array, instead of nulling out.

```
while (N > 1)
{
    exch(a, 1, N--);
    sink(a, 1, N);
}
```



Heapsort: Java implementation

```
public class Heap
   public static void sort(Comparable[] a)
      int N = a.length;
      for (int k = N/2; k >= 1; k--)
         sink(a, k, N);
      while (N > 1)
         exch(a, 1, N);
         sink(a, 1, --N);
                    but make static (and pass arguments)
   private static void sink(Comparable[] a, int k, int N)
   { /* as before */ }
   private static boolean less(Comparable[] a, int i, int j)
   { /* as before */ }
   private static void exch(Object[] a, int i, int j)
   { /* as before */
                                 but convert from 1-based
                                indexing to 0-base indexing
```

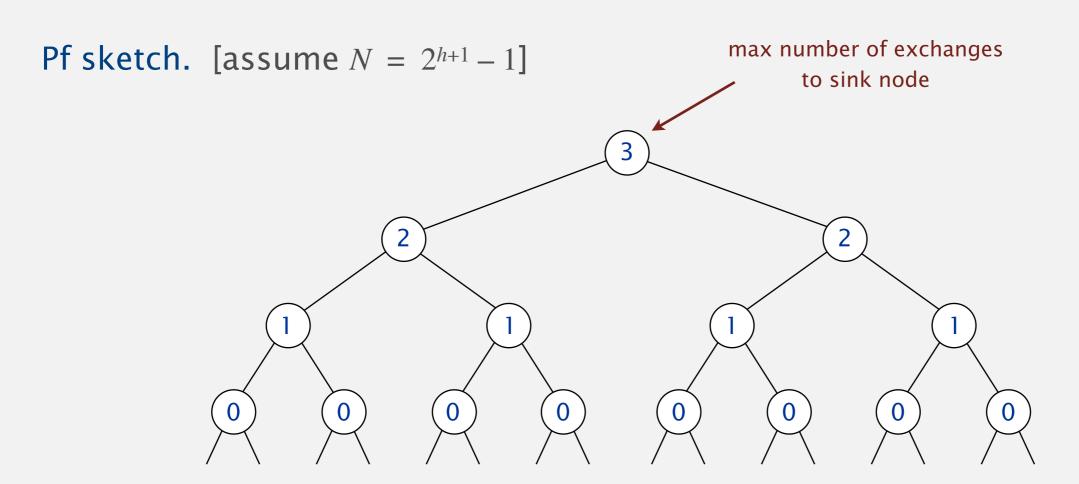
Heapsort: trace

```
a[i]
        k
                                               9 10 11
                                           8
   Ν
initial values
                    0
                                Ε
                                    X
        5
 11
 11
 11
 11
 11
        1
heap-ordered
                                    R
                                       Α
 10
        1
        1
   8
                                       Α
                                              S
        1
                    0
   6
        1
        1
                            Α
                                Ε
                            Α
                                M
   4
        1
   3
        1
        1
   1
                    Ε
                                M
sorted result
```

Heapsort trace (array contents just after each sink)

Heapsort: mathematical analysis

Proposition. Heap construction uses $\leq 2N$ compares and $\leq N$ exchanges.



binary heap of height h = 3

a tricky sum (see COS 340)
$$h+2(h-1)+4(h-2)+8(h-3)+\ldots+2^h(0) \leq 2^{h+1} = N$$

Heapsort: mathematical analysis

Proposition. Heap construction uses $\leq 2N$ compares and $\leq N$ exchanges.

Proposition. Heapsort uses $\leq 2 N \lg N$ compares and exchanges.

algorithm can be improved to ~ 1 N lg N

Significance. In-place sorting algorithm with $N \log N$ worst-case.

- Mergesort: no, linear extra space.
 ← in-place merge possible, not practical
- Quicksort: no, quadratic time in worst case. ← N log N worst-case quicksort possible, not practical
- Heapsort: yes!

Bottom line. Heapsort is optimal for both time and space, but:

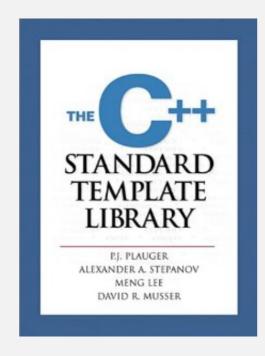
- Inner loop longer than quicksort's.
- Makes poor use of cache.
- Not stable.
 advanced tricks for improving

Introsort

Goal. As fast as quicksort in practice; $N \log N$ worst case, in place.

Introsort.

- Run quicksort.
- Cutoff to heapsort if stack depth exceeds 2 lg N.
- Cutoff to insertion sort for N = 16.



Introspective Sorting and Selection Algorithms

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Abstract

Quicksort is the preferred in-place sorting algorithm in many contexts, since its average computing time on uniformly distributed inputs is $\Theta(N \log N)$ and it is in fact faster than most other sorting algorithms on most inputs. Its drawback is that its worst-case time bound is $\Theta(N^2)$. Previous attempts to protect against the worst case by improving the way quicksort chooses pivot elements for partitioning have increased the average computing time too much—one might as well use heapsort, which has a $\Theta(N \log N)$ worst-case time bound but is on the average 2 to 5 times slower than quicksort. A similar dilemma exists with selection algorithms (for finding the i-th largest element) based on partitioning. This paper describes a simple solution to this dilemma: limit the depth of partitioning, and for subproblems that exceed the limit switch to another algorithm with a better worst-case bound. Using heapsort as the "stopper" yields a sorting algorithm that is just as fast as quicksort in the average case but also has an $\Theta(N \log N)$ worst case time bound. For selection, a hybrid of Hoare's FIND algorithm, which is linear on average but quadratic in the worst case, and the Blum-Floyd-Pratt-Rivest-Tarjan algorithm is as fast as Hoare's algorithm in practice, yet has a linear worst-case time bound. Also discussed are issues of implementing the new algorithms as generic algorithms and accurately measuring their performance in the framework of the C++ Standard Template Library.

In the wild. C++ STL, Microsoft .NET Framework.

Sorting algorithms: summary

	inplace?	stable?	best	average	worst	remarks
selection	~		½ N ²	½ N ²	½ N ²	N exchanges
insertion	~	✓	N	½ N ²	½ N ²	use for small N or partially ordered
shell	~		$N \log_3 N$?	$c N^{3/2}$	tight code; subquadratic
merge		✓	½ N lg N	N lg N	N lg N	$N \log N$ guarantee; stable
timsort		✓	N	N lg N	N lg N	improves mergesort when preexisting order
quick	~		$N \lg N$	2 <i>N</i> ln <i>N</i>	½ N ²	$N \log N$ probabilistic guarantee; fastest in practice
3-way quick	~		N	2 <i>N</i> ln <i>N</i>	½ N ²	improves quicksort when duplicate keys
heap	~		N	$2 N \lg N$	$2 N \lg N$	$N \log N$ guarantee; in-place
?	•	•	N	$N \lg N$	$N \lg N$	holy sorting grail