

Data Science Homework - 5.

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1. The given Points are

$A_1 (2, 10)$

$A_2 (2, 5)$

$A_3 (8, 4)$

$A_4 (5, 8)$

$B_2 (7, 5)$

$B_3 (6, 4)$

$C_1 (1, 2)$

$C_2 (4, 9)$

Here A_1, B_1, C_1 are assigned
as the initial centers of the cluster.

→ Euclidean distance gives you the distance
between two points.

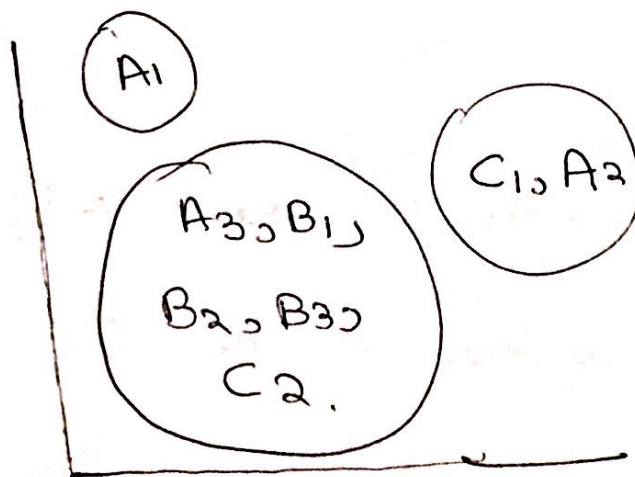
If (x_1, y_1) & (x_2, y_2) , The distance is

$$\sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$$

After a single iteration.

	A₁	A₂	C₁	B₁	B₂	B₃	C₂	C₃
A ₁	0	3.6	8.06					
A ₂	5	4.2	3.16					
A ₃	8.4	5	7.28					
B ₁	3.6	0	7.21					
B ₂	7.07	3.6	6.7					
B ₃	7.2	4.1	5.3					
C ₁	8.06	7.2	0					
C ₂	2.2	1.41	7.6					

↳ Picking the nearest centers from given values.



→ Let's check for the second iteration.
For the next iteration centers are updated by doing the

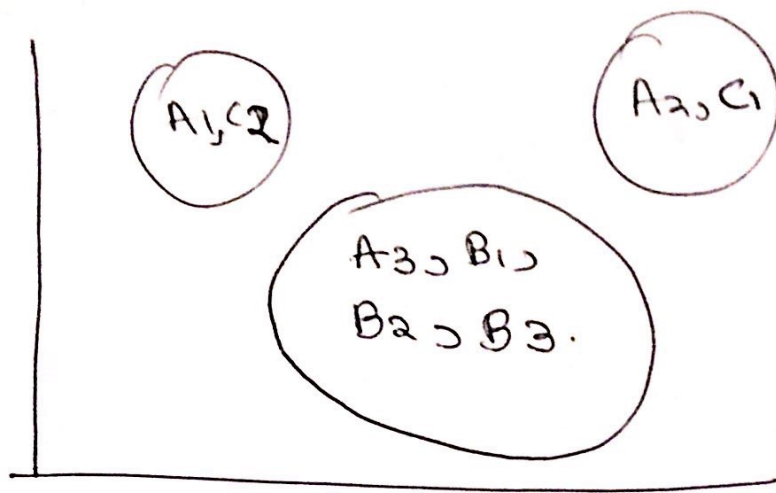
average of all the points in the given cluster.

$$C_1 = (2, 10)$$

$$C_2 = (6, 6)$$

$$C_3 = (1.5, 3.5)$$

<u>Second</u>	<u>Iteration⁰</u>		
	C_1	C_2	C_3
A_1	10	5.65	6.5
A_2	5	4.12	1.58
A_3	8.4	2.82	6.51
B_1	3.6	2.23	5.7
B_2	7.07	1.41	5.7
B_3	7.2	2	4.52
C_1	8.06	6.4	1.58
C_2	2.2	3.6	6.04



→ Again updating the centers.

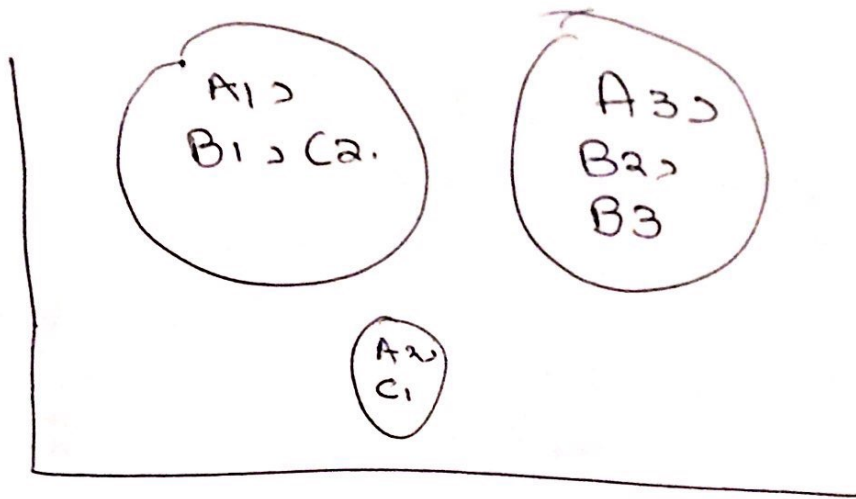
$$C_1 = (3, 9.5)$$

$$C_2 = (6.5, 5.25)$$

$$C_3 = (1.5, 3.5)$$

Third Iteration:

	C_1	C_2	C_3
A_1	$\boxed{1.11}$	6.5	6.5
A_2	4.6	4.5	$\boxed{1.58}$
A_3	7.4	$\boxed{1.92}$	6.51
B_1	$\boxed{2.2}$	3.13	5.7
B_2	6.02	$\boxed{0.2}$	5.7
B_3	6.26	$\boxed{1.34}$	4.52
C_1	7.7	6.3	$\boxed{1.58}$
C_2	$\boxed{1.11}$	4.5	6.04



→ Calculating Centers

$$C_1 = (3.66, 9)$$

$$C_2 = (7, 4.33)$$

$$C_3 = (1.5, 3.5)$$

Fourth Iteration

	C_1	C_2	C_3
A_1	1.93	7.52	6.5
A_2	4.33	5.04	11.58
A_3	6.62	4.05	6.5
B_1	11.67	4.7	5.7
B_2	5.2	0.67	5.7
B_3	5.52	10.05	4.52
C_1	7.4	6.43	11.58
C_2	6.34	5.5	6.04

// centers are same, & not any change.

→ Since the centers are not changed, it has reached the best possible cluster.

1a) Center 1 Center 2 Center 3
 A_1 A_3, B_1, B_2 C_1, A_2
 B_3, C_2

1b) Center 1 Center 2 Center 3
 A_1, B_1, C_2 A_3, B_2, B_3 A_2, C_1

2) 10.10) why does BIRCH encounter difficulty in finding clusters of arbitrary shape but OPTICS does not? Propose modifications to BIRCH to help it find clusters of arbitrary shape?

BIRCH uses the euclidean distance to find distance between the points, Due to this the shape is nearly spherical, the resulting cluster

is not in the arbitrary shape.
whereas OPTICS uses density of
the Points as the metric for distance
all the Points which are very close
enough or within a minimum density
measure form a cluster which can be
of any arbitrary shape, which is
based on the original position of
the Points.

As a modification to BIRCH, it
can be modified to use density measure
to form arbitrary shaped clusters by
clustering very low level BT trees, which
have very closely positioned Points. This
will then take density measure and not
distance measures so that form a CF tree
and will result in arbitrary shaped clusters.

3)

→ Partition based and hierarchical clustering uses distance as a measure for creating clusters of the given points.

→ Due to this distance measures they end up having spherical shaped clusters.

→ But in the case of density based clustering, takes use of the fact that the every cluster formed has a density different than other formed clusters.

→ Density clustering method takes the clusters as the dense regions of the data points

→ In this way they arbitrarily form arbitrary shaped cluster dense regions and are very suitable than other clustering methods in a way that they can separate those from less density regions in the data point space.

4) Basically, we are given the datapoints and need to build the clustering depending on the constraints and Kmeans or other clustering techniques.

→ Let's choose some random ATM's as centroids and for each point we assign it with the nearest centroid, satisfying the given constraints which we have enforced on the data points.

→ If a datapoint there is no centroid satisfying the constraint, then the datapoint is not assigned to any centroid, and the datapoint is then updated to the centroid list.

→ This process is repeated until any convergence is found.

→ The algorithm goes as follows

- 1) Define Constraints function which has
Constraints like → 10000 households per cluster
→ No obstacle objects
- 2) Randomly choose Centroid Datapoints &
assign it to all Datapoints
- 3) If a Datapoint has no nearest Centroid
with given requirements then add the
datapoint to Centroid list.
- 4) Repeat This untill Convergence.
- 5) Then the Points with no clusters
assigned ^{to} by ATM are ~~are~~ by dropping
all the Constraints.